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Introduction

This manual documents the internals of the GNU compilers, including how to port them to new targets and some information about how to write front ends for new languages. It corresponds to the compilers (GCC) version 12.0.0. The use of the GNU compilers is documented in a separate manual. See Section “Introduction” in Using the GNU Compiler Collection (GCC).

This manual is mainly a reference manual rather than a tutorial. It discusses how to contribute to GCC (see Chapter 1 [Contributing], page 3), the characteristics of the machines supported by GCC as hosts and targets (see Chapter 2 [Portability], page 5), how GCC relates to the ABIs on such systems (see Chapter 3 [Interface], page 7), and the characteristics of the languages for which GCC front ends are written (see Chapter 5 [Languages], page 59). It then describes the GCC source tree structure and build system, some of the interfaces to GCC front ends, and how support for a target system is implemented in GCC.

Additional tutorial information is linked to from http://gcc.gnu.org/readings.html.
1 Contributing to GCC Development

If you would like to help pretest GCC releases to assure they work well, current development sources are available via Git (see http://gcc.gnu.org/git.html). Source and binary snapshots are also available for FTP; see http://gcc.gnu.org/snapshots.html.

If you would like to work on improvements to GCC, please read the advice at these URLs:

http://gcc.gnu.org/contribute.html
http://gcc.gnu.org/contributewhy.html

for information on how to make useful contributions and avoid duplication of effort. Suggested projects are listed at http://gcc.gnu.org/projects/.
Chapter 2: GCC and Portability

2 GCC and Portability

GCC itself aims to be portable to any machine where `int` is at least a 32-bit type. It aims to target machines with a flat (non-segmented) byte addressed data address space (the code address space can be separate). Target ABIs may have 8, 16, 32 or 64-bit `int` type. `char` can be wider than 8 bits.

GCC gets most of the information about the target machine from a machine description which gives an algebraic formula for each of the machine’s instructions. This is a very clean way to describe the target. But when the compiler needs information that is difficult to express in this fashion, ad-hoc parameters have been defined for machine descriptions. The purpose of portability is to reduce the total work needed on the compiler; it was not of interest for its own sake.

GCC does not contain machine dependent code, but it does contain code that depends on machine parameters such as endianness (whether the most significant byte has the highest or lowest address of the bytes in a word) and the availability of autoincrement addressing. In the RTL-generation pass, it is often necessary to have multiple strategies for generating code for a particular kind of syntax tree, strategies that are usable for different combinations of parameters. Often, not all possible cases have been addressed, but only the common ones or only the ones that have been encountered. As a result, a new target may require additional strategies. You will know if this happens because the compiler will call `abort`. Fortunately, the new strategies can be added in a machine-independent fashion, and will affect only the target machines that need them.
3 Interfacing to GCC Output

GCC is normally configured to use the same function calling convention normally in use on the target system. This is done with the machine-description macros described (see Chapter 18 [Target Macros], page 497).

However, returning of structure and union values is done differently on some target machines. As a result, functions compiled with PCC returning such types cannot be called from code compiled with GCC, and vice versa. This does not cause trouble often because few Unix library routines return structures or unions.

GCC code returns structures and unions that are 1, 2, 4 or 8 bytes long in the same registers used for int or double return values. (GCC typically allocates variables of such types in registers also.) Structures and unions of other sizes are returned by storing them into an address passed by the caller (usually in a register). The target hook TARGET_STRUCT_VALUE_RTX tells GCC where to pass this address.

By contrast, PCC on most target machines returns structures and unions of any size by copying the data into an area of static storage, and then returning the address of that storage as if it were a pointer value. The caller must copy the data from that memory area to the place where the value is wanted. This is slower than the method used by GCC, and fails to be reentrant.

On some target machines, such as RISC machines and the 80386, the standard system convention is to pass to the subroutine the address of where to return the value. On these machines, GCC has been configured to be compatible with the standard compiler, when this method is used. It may not be compatible for structures of 1, 2, 4 or 8 bytes.

GCC uses the system’s standard convention for passing arguments. On some machines, the first few arguments are passed in registers; in others, all are passed on the stack. It would be possible to use registers for argument passing on any machine, and this would probably result in a significant speedup. But the result would be complete incompatibility with code that follows the standard convention. So this change is practical only if you are switching to GCC as the sole C compiler for the system. We may implement register argument passing on certain machines once we have a complete GNU system so that we can compile the libraries with GCC.

On some machines (particularly the SPARC), certain types of arguments are passed “by invisible reference”. This means that the value is stored in memory, and the address of the memory location is passed to the subroutine.

If you use longjmp, beware of automatic variables. ISO C says that automatic variables that are not declared volatile have undefined values after a longjmp. And this is all GCC promises to do, because it is very difficult to restore register variables correctly, and one of GCC’s features is that it can put variables in registers without your asking it to.
4 The GCC low-level runtime library

GCC provides a low-level runtime library, ‘libgcc.a’ or ‘libgcc_s.so.1’ on some platforms. GCC generates calls to routines in this library automatically, whenever it needs to perform some operation that is too complicated to emit inline code for.

Most of the routines in libgcc handle arithmetic operations that the target processor cannot perform directly. This includes integer multiply and divide on some machines, and all floating-point and fixed-point operations on other machines. libgcc also includes routines for exception handling, and a handful of miscellaneous operations.

Some of these routines can be defined in mostly machine-independent C. Others must be hand-written in assembly language for each processor that needs them.

GCC will also generate calls to C library routines, such as memcpy and memset in some cases. The set of routines that GCC may possibly use is documented in Section “Other Builtins” in Using the GNU Compiler Collection (GCC).

These routines take arguments and return values of a specific machine mode, not a specific C type. See Section 14.6 [Machine Modes], page 275, for an explanation of this concept. For illustrative purposes, in this chapter the floating point type float is assumed to correspond to SFmode; double to DFmode; and long double to both TFmode and Xmode. Similarly, the integer types int and unsigned int correspond to SImode; long and unsigned long to DImode; and long long and unsigned long long to TImode.

4.1 Routines for integer arithmetic

The integer arithmetic routines are used on platforms that don’t provide hardware support for arithmetic operations on some modes.

4.1.1 Arithmetic functions

int __ashlsi3 (int a, int b)  
[Runtime Function]
long __ashldi3 (long a, int b)  
[Runtime Function]
long long __ashlti3 (long long a, int b)  
[Runtime Function]
These functions return the result of shifting a left by b bits.

int __ashrsi3 (int a, int b)  
[Runtime Function]
long __ashrdi3 (long a, int b)  
[Runtime Function]
long long __ashrti3 (long long a, int b)  
[Runtime Function]
These functions return the result of arithmetically shifting a right by b bits.

int __divsi3 (int a, int b)  
[Runtime Function]
long __divdi3 (long a, long b)  
[Runtime Function]
long long __divti3 (long long a, long long b)  
[Runtime Function]
These functions return the quotient of the signed division of a and b.

int __lshrsi3 (int a, int b)  
[Runtime Function]
long __lshrdi3 (long a, int b)  
[Runtime Function]
long long __lshrti3 (long long a, int b)  
[Runtime Function]
These functions return the result of logically shifting a right by b bits.
int __modsi3 (int a, int b)  [Runtime Function]
long __moddi3 (long a, long b)  [Runtime Function]
long long __modti3 (long long a, long long b)  [Runtime Function]
These functions return the remainder of the signed division of a and b.

int __mulsi3 (int a, int b)  [Runtime Function]
long __muldi3 (long a, long b)  [Runtime Function]
long long __multi3 (long long a, long long b)  [Runtime Function]
These functions return the product of a and b.

long __negdi2 (long a)  [Runtime Function]
long long __negti2 (long long a)  [Runtime Function]
These functions return the negation of a.

unsigned int __udivsi3 (unsigned int a, unsigned int b)  [Runtime Function]
unsigned long __udivdi3 (unsigned long a, unsigned long b)  [Runtime Function]
unsigned long long __udivti3 (unsigned long long a, unsigned long long b)  [Runtime Function]
These functions return the quotient of the unsigned division of a and b.

unsigned long __udivmoddi4 (unsigned long a, unsigned long b, unsigned long *c)  [Runtime Function]
unsigned long long __udivmodti4 (unsigned long long a, unsigned long long b, unsigned long long *c)  [Runtime Function]
These functions calculate both the quotient and remainder of the unsigned division of a and b. The return value is the quotient, and the remainder is placed in variable pointed to by c.

unsigned int __umodsi3 (unsigned int a, unsigned int b)  [Runtime Function]
unsigned long __umoddi3 (unsigned long a, unsigned long b)  [Runtime Function]
unsigned long long __umodti3 (unsigned long long a, unsigned long long b)  [Runtime Function]
These functions return the remainder of the unsigned division of a and b.

### 4.1.2 Comparison functions

The following functions implement integral comparisons. These functions implement a low-level compare, upon which the higher level comparison operators (such as less than and greater than or equal to) can be constructed. The returned values lie in the range zero to two, to allow the high-level operators to be implemented by testing the returned result using either signed or unsigned comparison.

int __cmpdi2 (long a, long b)  [Runtime Function]
int __cmpti2 (long long a, long long b)  [Runtime Function]
These functions perform a signed comparison of a and b. If a is less than b, they return 0; if a is greater than b, they return 2; and if a and b are equal they return 1.

int __ucmpdi2 (unsigned long a, unsigned long b)  [Runtime Function]
int __ucmpti2 (unsigned long long a, unsigned long long b)  [Runtime Function]
These functions perform an unsigned comparison of a and b. If a is less than b, they return 0; if a is greater than b, they return 2; and if a and b are equal they return 1.
4.1.3 Trapping arithmetic functions

The following functions implement trapping arithmetic. These functions call the libc function `abort` upon signed arithmetic overflow.

```c
int __absvsi2 (int a) [Runtime Function]
long __absvdi2 (long a) [Runtime Function]
These functions return the absolute value of `a`.

int __addvsi3 (int a, int b) [Runtime Function]
long __addvdi3 (long a, long b) [Runtime Function]
These functions return the sum of `a` and `b`; that is `a + b`.

int __mulvsi3 (int a, int b) [Runtime Function]
long __mulvdi3 (long a, long b) [Runtime Function]
The functions return the product of `a` and `b`; that is `a * b`.

int __negvsi2 (int a) [Runtime Function]
long __negvdi2 (long a) [Runtime Function]
These functions return the negation of `a`; that is `-a`.

int __subvsi3 (int a, int b) [Runtime Function]
long __subvdi3 (long a, long b) [Runtime Function]
These functions return the difference between `b` and `a`; that is `a - b`.

4.1.4 Bit operations

```c
int __clzsi2 (unsigned int a) [Runtime Function]
int __clzdi2 (unsigned long a) [Runtime Function]
int __clzti2 (unsigned long long a) [Runtime Function]
These functions return the number of leading 0-bits in `a`, starting at the most significant bit position. If `a` is zero, the result is undefined.

int __ctzsi2 (unsigned int a) [Runtime Function]
int __ctzdi2 (unsigned long a) [Runtime Function]
int __ctzti2 (unsigned long long a) [Runtime Function]
These functions return the number of trailing 0-bits in `a`, starting at the least significant bit position. If `a` is zero, the result is undefined.

int __ffsdi2 (unsigned long a) [Runtime Function]
int __ffsti2 (unsigned long long a) [Runtime Function]
These functions return the index of the least significant 1-bit in `a`, or the value zero if `a` is zero. The least significant bit is index one.

int __paritysi2 (unsigned int a) [Runtime Function]
int __paritydi2 (unsigned long a) [Runtime Function]
int __parityti2 (unsigned long long a) [Runtime Function]
These functions return the value zero if the number of bits set in `a` is even, and the value one otherwise.
int __popcountsi2 (unsigned int a) [Runtime Function]
int __popcountdi2 (unsigned long a) [Runtime Function]
int __popcountti2 (unsigned long long a) [Runtime Function]

These functions return the number of bits set in a.

int32_t __bswapsi2 (int32_t a) [Runtime Function]
int64_t __bswapdi2 (int64_t a) [Runtime Function]

These functions return the a byteswapped.

4.2 Routines for floating point emulation

The software floating point library is used on machines which do not have hardware support for floating point. It is also used whenever ‘-msoft-float’ is used to disable generation of floating point instructions. (Not all targets support this switch.)

For compatibility with other compilers, the floating point emulation routines can be renamed with the DECLARE.Library.RENAMES macro (see Section 18.12 [Library Calls], page 579). In this section, the default names are used.

Presently the library does not support XFmode, which is used for long double on some architectures.

4.2.1 Arithmetic functions

float __addsf3 (float a, float b) [Runtime Function]
double __adddf3 (double a, double b) [Runtime Function]
long double __addtf3 (long double a, long double b) [Runtime Function]
long double __addxf3 (long double a, long double b) [Runtime Function]

These functions return the sum of a and b.

float __subsf3 (float a, float b) [Runtime Function]
double __subdf3 (double a, double b) [Runtime Function]
long double __subtf3 (long double a, long double b) [Runtime Function]
long double __subxf3 (long double a, long double b) [Runtime Function]

These functions return the difference between b and a; that is, a − b.

float __mulsf3 (float a, float b) [Runtime Function]
double __muldf3 (double a, double b) [Runtime Function]
long double __multf3 (long double a, long double b) [Runtime Function]
long double __mulxf3 (long double a, long double b) [Runtime Function]

These functions return the product of a and b.

float __divsf3 (float a, float b) [Runtime Function]
double __divdf3 (double a, double b) [Runtime Function]
long double __divtf3 (long double a, long double b) [Runtime Function]
long double __divxf3 (long double a, long double b) [Runtime Function]

These functions return the quotient of a and b; that is, a/b.

float __negsf2 (float a) [Runtime Function]
double __negdf2 (double a) [Runtime Function]
long double __negtf2 (long double a) [Runtime Function]
long double __negxf2 (long double a)  [Runtime Function]

These functions return the negation of a. They simply flip the sign bit, so they can produce negative zero and negative NaN.

4.2.2 Conversion functions

double __extendsfdf2 (float a)  [Runtime Function]
long double __extendsstf2 (float a)  [Runtime Function]
long double __extendsxfxf2 (float a)  [Runtime Function]
long double __extenddftf2 (double a)  [Runtime Function]
long double __extenddfxf2 (double a)  [Runtime Function]

These functions extend a to the wider mode of their return type.

double __truncxfdf2 (long double a)  [Runtime Function]
double __trunctfdf2 (long double a)  [Runtime Function]
float __truncxfsf2 (long double a)  [Runtime Function]
float __trunctfsf2 (long double a)  [Runtime Function]
float __truncdfsf2 (double a)  [Runtime Function]

These functions truncate a to the narrower mode of their return type, rounding toward zero.

int __fixsfsi (float a)  [Runtime Function]
int __fixdfs (double a)  [Runtime Function]
int __fixtfsi (long double a)  [Runtime Function]
int __fixxfsi (long double a)  [Runtime Function]

These functions convert a to a signed integer, rounding toward zero.

long __fixsfdi (float a)  [Runtime Function]
long __fixdfdi (double a)  [Runtime Function]
long __fixtfdi (long double a)  [Runtime Function]
long __fixxfdi (long double a)  [Runtime Function]

These functions convert a to a signed long, rounding toward zero.

long long __fixsfti (float a)  [Runtime Function]
long long __fixdfsti (double a)  [Runtime Function]
long long __fixtftti (long double a)  [Runtime Function]
long long __fixxftti (long double a)  [Runtime Function]

These functions convert a to a signed long long, rounding toward zero.

unsigned int __fixunssfsi (float a)  [Runtime Function]
unsigned int __fixunsdfs (double a)  [Runtime Function]
unsigned int __fixunstfsi (long double a)  [Runtime Function]
unsigned int __fixunsxfsi (long double a)  [Runtime Function]

These functions convert a to an unsigned integer, rounding toward zero. Negative values all become zero.

unsigned long __fixunssfdi (float a)  [Runtime Function]
unsigned long __fixunsdfdi (double a)  [Runtime Function]
unsigned long __fixunstfdi (long double a)  [Runtime Function]
unsigned long __fixunsxfdi (long double a)  [Runtime Function]
These functions convert a to an unsigned long, rounding toward zero. Negative values all become zero.

unsigned long long __fixunssfti (float a)     [Runtime Function]
unsigned long long __fixunsdfti (double a)    [Runtime Function]
unsigned long long __fixunstfti (long double a) [Runtime Function]
unsigned long long __fixunsxfti (long double a) [Runtime Function]
These functions convert a to an unsigned long long, rounding toward zero. Negative values all become zero.

float __floatsisf (int i)                     [Runtime Function]
double __floatsidf (int i)                    [Runtime Function]
long double __floatsitf (int i)               [Runtime Function]
long double __floatsixf (int i)               [Runtime Function]
These functions convert i, a signed integer, to floating point.

float __floatdisf (long i)                    [Runtime Function]
double __floatdidf (long i)                   [Runtime Function]
long double __floatditf (long i)              [Runtime Function]
long double __floatdixf (long i)              [Runtime Function]
These functions convert i, a signed long, to floating point.

float __floattisf (long long i)               [Runtime Function]
double __floattidf (long long i)              [Runtime Function]
long double __floattitf (long long i)         [Runtime Function]
long double __floattixf (long long i)         [Runtime Function]
These functions convert i, a signed long long, to floating point.

float __floatunsisf (unsigned int i)              [Runtime Function]
double __floatunsidf (unsigned int i)           [Runtime Function]
long double __floatunsitf (unsigned int i)      [Runtime Function]
long double __floatunsixf (unsigned int i)      [Runtime Function]
These functions convert i, an unsigned integer, to floating point.

float __floatundisf (unsigned long i)           [Runtime Function]
double __floatundidf (unsigned long i)          [Runtime Function]
long double __floatunditf (unsigned long i)     [Runtime Function]
long double __floatundixf (unsigned long i)     [Runtime Function]
These functions convert i, an unsigned long, to floating point.

float __floatuntisf (unsigned long long i)      [Runtime Function]
double __floatuntidf (unsigned long long i)     [Runtime Function]
long double __floatuntitf (unsigned long long i) [Runtime Function]
long double __floatuntixf (unsigned long long i) [Runtime Function]
These functions convert i, an unsigned long long, to floating point.
4.2.3 Comparison functions

There are two sets of basic comparison functions.

- **int __cmpsf2 (float a, float b)** [Runtime Function]
- **int __cmpdf2 (double a, double b)** [Runtime Function]
- **int __cmptf2 (long double a, long double b)** [Runtime Function]

These functions calculate \( a <\leq > b \). That is, if \( a \) is less than \( b \), they return \(-1\); if \( a \) is greater than \( b \), they return \(1\); and if \( a \) and \( b \) are equal they return \(0\). If either argument is NaN they return \(1\), but you should not rely on this; if NaN is a possibility, use one of the higher-level comparison functions.

- **int __unordsf2 (float a, float b)** [Runtime Function]
- **int __unorddf2 (double a, double b)** [Runtime Function]
- **int __unordtf2 (long double a, long double b)** [Runtime Function]

These functions return a nonzero value if either argument is NaN, otherwise \(0\).

There is also a complete group of higher level functions which correspond directly to comparison operators. They implement the ISO C semantics for floating-point comparisons, taking NaN into account. Pay careful attention to the return values defined for each set.

Under the hood, all of these routines are implemented as

```c
if (__unordXf2 (a, b))
    return E;
return __cmpXf2 (a, b);
```

where \( E \) is a constant chosen to give the proper behavior for NaN. Thus, the meaning of the return value is different for each set. Do not rely on this implementation; only the semantics documented below are guaranteed.

- **int __eqsf2 (float a, float b)** [Runtime Function]
- **int __eqdf2 (double a, double b)** [Runtime Function]
- **int __eqtf2 (long double a, long double b)** [Runtime Function]

These functions return \(0\) if neither argument is NaN, and \(a\) and \(b\) are equal.

- **int __nesf2 (float a, float b)** [Runtime Function]
- **int __nedf2 (double a, double b)** [Runtime Function]
- **int __netf2 (long double a, long double b)** [Runtime Function]

These functions return a nonzero value if either argument is NaN, or if \(a\) and \(b\) are unequal.

- **int __gesf2 (float a, float b)** [Runtime Function]
- **int __gedf2 (double a, double b)** [Runtime Function]
- **int __getf2 (long double a, long double b)** [Runtime Function]

These functions return a value greater than or equal to zero if neither argument is NaN, and \(a\) is greater than or equal to \(b\).

- **int __ltsf2 (float a, float b)** [Runtime Function]
- **int __ltdf2 (double a, double b)** [Runtime Function]
- **int __lttf2 (long double a, long double b)** [Runtime Function]

These functions return a value less than zero if neither argument is NaN, and \(a\) is strictly less than \(b\).
int __lesf2 (float a, float b)       [Runtime Function]
int __ledf2 (double a, double b)    [Runtime Function]
int __letf2 (long double a, long double b) [Runtime Function]

These functions return a value less than or equal to zero if neither argument is NaN, and a is less than or equal to b.

int __gtsf2 (float a, float b)       [Runtime Function]
int __gtdf2 (double a, double b)    [Runtime Function]
int __gttf2 (long double a, long double b) [Runtime Function]

These functions return a value greater than zero if neither argument is NaN, and a is strictly greater than b.

4.2.4 Other floating-point functions

float __powisf2 (float a, int b)      [Runtime Function]
double __powidf2 (double a, int b)   [Runtime Function]
long double __powitf2 (long double a, int b) [Runtime Function]
long double __powixf2 (long double a, int b) [Runtime Function]

These functions convert raise a to the power b.

complex float __mulsc3 (float a, float b, float c, float d)      [Runtime Function]
complex double __muldc3 (double a, double b, double c, double d) [Runtime Function]
complex long double __multc3 (long double a, long double b, long double c, long double d) [Runtime Function]
complex long double __mulxc3 (long double a, long double b, long double c, long double d) [Runtime Function]

These functions return the product of $a + ib$ and $c + id$, following the rules of C99 Annex G.

complex float __divsc3 (float a, float b, float c, float d)      [Runtime Function]
complex double __divdc3 (double a, double b, double c, double d) [Runtime Function]
complex long double __divtc3 (long double a, long double b, long double c, long double d) [Runtime Function]
complex long double __divxc3 (long double a, long double b, long double c, long double d) [Runtime Function]

These functions return the quotient of $a + ib$ and $c + id$ (i.e., $(a + ib)/(c + id)$), following the rules of C99 Annex G.

4.3 Routines for decimal floating point emulation

The software decimal floating point library implements IEEE 754-2008 decimal floating point arithmetic and is only activated on selected targets.

The software decimal floating point library supports either DPD (Densely Packed Decimal) or BID (Binary Integer Decimal) encoding as selected at configure time.
4.3.1 Arithmetic functions

```c
_decimal32 __dpd_addsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal32 __bid_addsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal64 __dpd_adddd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal64 __bid_adddd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal128 __dpd_addtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
_decimal128 __bid_addtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
```

These functions return the sum of $a$ and $b$.

```c
_decimal32 __dpd_subsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal32 __bid_subsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal64 __dpd_subdd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal64 __bid_subdd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal128 __dpd_subtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
_decimal128 __bid_subtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
```

These functions return the difference between $b$ and $a$; that is, $a - b$.

```c
_decimal32 __dpd_mulsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal32 __bid_mulsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal64 __dpd_muldd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal64 __bid_muldd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal128 __dpd_multd3 (Decimal128 a, Decimal128 b) [Runtime Function]
_decimal128 __bid_multd3 (Decimal128 a, Decimal128 b) [Runtime Function]
```

These functions return the product of $a$ and $b$.

```c
_decimal32 __dpd_divsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal32 __bid_divsd3 (Decimal32 a, Decimal32 b) [Runtime Function]
_decimal64 __dpd_divdd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal64 __bid_divdd3 (Decimal64 a, Decimal64 b) [Runtime Function]
_decimal128 __dpd_divtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
_decimal128 __bid_divtd3 (Decimal128 a, Decimal128 b) [Runtime Function]
```

These functions return the quotient of $a$ and $b$; that is, $a/b$.

```c
_decimal32 __dpd_negsd2 (Decimal32 a) [Runtime Function]
_decimal32 __bid_negsd2 (Decimal32 a) [Runtime Function]
_decimal64 __dpd_negdd2 (Decimal64 a) [Runtime Function]
_decimal64 __bid_negdd2 (Decimal64 a) [Runtime Function]
_decimal128 __dpd_negtd2 (Decimal128 a) [Runtime Function]
_decimal128 __bid_negtd2 (Decimal128 a) [Runtime Function]
```

These functions return the negation of $a$. They simply flip the sign bit, so they can produce negative zero and negative NaN.

4.3.2 Conversion functions

```c
_decimal64 __dpd_extendsddd2 (Decimal32 a) [Runtime Function]
_decimal64 __bid_extendsddd2 (Decimal32 a) [Runtime Function]
_decimal128 __dpd_extendsdtd2 (Decimal32 a) [Runtime Function]
_decimal128 __bid_extendsdtd2 (Decimal32 a) [Runtime Function]
```
These functions convert the value \( a \) from one decimal floating type to another.

These functions convert the value of \( a \) from a binary floating type to a decimal floating type of a different size.
These functions convert the value of $a$ from a decimal floating type to a binary floating type of a different size.

`long double __bid_extendddtf (_Decimal64 a)`  [Runtime Function]

These functions convert the value of $a$ between decimal and binary floating types of the same size.

`int __dpd_fixsdsi (Decimal32 a)`  [Runtime Function]
`int __bid_fixsdsi (Decimal32 a)`  [Runtime Function]
`int __dpd_fixddsi (Decimal64 a)`  [Runtime Function]
`int __bid_fixddsi (Decimal64 a)`  [Runtime Function]
`int __dpd_fixtdsi (Decimal128 a)`  [Runtime Function]
`int __bid_fixtdsi (Decimal128 a)`  [Runtime Function]

These functions convert $a$ to a signed integer.

`long __dpd_fixsddi (Decimal32 a)`  [Runtime Function]
`long __bid_fixsddi (Decimal32 a)`  [Runtime Function]
`long __dpd_fixdddi (Decimal64 a)`  [Runtime Function]
`long __bid_fixdddi (Decimal64 a)`  [Runtime Function]
`long __dpd_fixtddi (Decimal128 a)`  [Runtime Function]
`long __bid_fixtddi (Decimal128 a)`  [Runtime Function]

These functions convert $a$ to a signed long.

`unsigned int __dpd_fixunssdsi (Decimal32 a)`  [Runtime Function]
`unsigned int __bid_fixunssdsi (Decimal32 a)`  [Runtime Function]
`unsigned int __dpd_fixunssdsi (Decimal64 a)`  [Runtime Function]
`unsigned int __bid_fixunssdsi (Decimal64 a)`  [Runtime Function]
`unsigned int __dpd_fixunstdsi (Decimal128 a)`  [Runtime Function]
`unsigned int __bid_fixunstdsi (Decimal128 a)`  [Runtime Function]

These functions convert $a$ to an unsigned integer. Negative values all become zero.
unsigned long __bid_fixunstddi (Decimal128 a) [Runtime Function]
These functions convert a to an unsigned long. Negative values all become zero.

_Decimal32 __dpd_floatsisd (int i) [Runtime Function]
_Decimal32 __bid_floatsisd (int i) [Runtime Function]
_Decimal64 __dpd_floatsidd (int i) [Runtime Function]
_Decimal64 __bid_floatsidd (int i) [Runtime Function]
_Decimal128 __dpd_floatsitd (int i) [Runtime Function]
_Decimal128 __bid_floatsitd (int i) [Runtime Function]
These functions convert i, a signed integer, to decimal floating point.

_Decimal32 __dpd_floatdisd (long i) [Runtime Function]
_Decimal32 __bid_floatdisd (long i) [Runtime Function]
_Decimal64 __dpd_floatdidd (long i) [Runtime Function]
_Decimal64 __bid_floatdidd (long i) [Runtime Function]
_Decimal128 __dpd_floatditd (long i) [Runtime Function]
_Decimal128 __bid_floatditd (long i) [Runtime Function]
These functions convert i, a signed long, to decimal floating point.

_Decimal32 __dpd_floatunssisd (unsigned int i) [Runtime Function]
_Decimal32 __bid_floatunssisd (unsigned int i) [Runtime Function]
_Decimal64 __dpd_floatunssidd (unsigned int i) [Runtime Function]
_Decimal64 __bid_floatunssidd (unsigned int i) [Runtime Function]
_Decimal128 __dpd_floatunssitd (unsigned int i) [Runtime Function]
_Decimal128 __bid_floatunssitd (unsigned int i) [Runtime Function]
These functions convert i, an unsigned integer, to decimal floating point.

_Decimal32 __dpd_floatunssdisd (unsigned long i) [Runtime Function]
_Decimal32 __bid_floatunssdisd (unsigned long i) [Runtime Function]
_Decimal64 __dpd_floatunssdidd (unsigned long i) [Runtime Function]
_Decimal64 __bid_floatunssdidd (unsigned long i) [Runtime Function]
_Decimal128 __dpd_floatunssditd (unsigned long i) [Runtime Function]
_Decimal128 __bid_floatunssditd (unsigned long i) [Runtime Function]
These functions convert i, an unsigned long, to decimal floating point.

4.3.3 Comparison functions

int __dpd_unordsd2 (Decimal32 a, Decimal32 b) [Runtime Function]
int __bid_unordsd2 (Decimal32 a, Decimal32 b) [Runtime Function]
int __dpd_unorrd2 (Decimal64 a, Decimal64 b) [Runtime Function]
int __bid_unorrd2 (Decimal64 a, Decimal64 b) [Runtime Function]
int __dpd_unordtd2 (Decimal128 a, Decimal128 b) [Runtime Function]
int __bid_unordtd2 (Decimal128 a, Decimal128 b) [Runtime Function]
These functions return a nonzero value if either argument is NaN, otherwise 0.

There is also a complete group of higher level functions which correspond directly to comparison operators. They implement the ISO C semantics for floating-point comparisons, taking NaN into account. Pay careful attention to the return values defined for each set. Under the hood, all of these routines are implemented as
if (__bid_unordXd2 (a, b))
    return E;
return __bid_cmpXd2 (a, b);

where E is a constant chosen to give the proper behavior for NaN. Thus, the meaning of the return value is different for each set. Do not rely on this implementation; only the semantics documented below are guaranteed.

int __dpd_eqsd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __bid_eqsd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __dpd_eqdd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __bid_eqdd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __dpd_eqtd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]
int __bid_eqtd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]

These functions return zero if neither argument is NaN, and a and b are equal.

int __dpd_nesd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __bid_nesd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __dpd_nedd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __bid_nedd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __dpd_netd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]
int __bid_netd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]

These functions return a nonzero value if either argument is NaN, or if a and b are unequal.

int __dpd_gesd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __bid_gesd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __dpd_gedd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __bid_gedd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __dpd_getd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]
int __bid_getd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]

These functions return a value greater than or equal to zero if neither argument is NaN, and a is greater than or equal to b.

int __dpd_ltsd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __bid_ltsd2 (_Decimal32 a, _Decimal32 b) [Runtime Function]
int __dpd_ltdd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __bid_ltdd2 (_Decimal64 a, _Decimal64 b) [Runtime Function]
int __dpd_lttdd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]
int __bid_lttdd2 (_Decimal128 a, _Decimal128 b) [Runtime Function]

These functions return a value less than zero if neither argument is NaN, and a is strictly less than b.
int __bid_letd2 (_Decimal128 a, _Decimal128 b)  
These functions return a value less than or equal to zero if neither argument is NaN, and a is less than or equal to b.

int __dpd_gtsd2 (_Decimal32 a, _Decimal32 b)  
int __bid_gtsd2 (_Decimal32 a, _Decimal32 b)  

int __dpd_gtdd2 (_Decimal64 a, _Decimal64 b)  
int __bid_gtdd2 (_Decimal64 a, _Decimal64 b)  

int __dpd_gttd2 (_Decimal128 a, _Decimal128 b)  
int __bid_gttd2 (_Decimal128 a, _Decimal128 b)  
These functions return a value greater than zero if neither argument is NaN, and a is strictly greater than b.

4.4 Routines for fixed-point fractional emulation

The software fixed-point library implements fixed-point fractional arithmetic, and is only activated on selected targets.

For ease of comprehension fract is an alias for the _Fract type, accum an alias for _Accum, and sat an alias for _Sat.

For illustrative purposes, in this section the fixed-point fractional type short fract is assumed to correspond to machine mode QQmode; unsigned short fract to UQQmode; fract to HQmode; unsigned fract to UHQmode; long fract to SQmode; unsigned long fract to USQmode; long long fract to DQmode; and unsigned long long fract to UDQmode. Similarly the fixed-point accumulator type short accum corresponds to HAmode; unsigned short accum to UHAmode; accum to SAmode; unsigned accum to USAmode; long accum to DAmode; unsigned long accum to DAmode; long long accum to TAmode; and unsigned long long accum to UTAmode.

4.4.1 Arithmetic functions

short fract __addqq3 (short fract a, short fract b)  
fract __addhq3 (fract a, fract b)  
long fract __addsq3 (long fract a, long fract b)  
long long fract __adddq3 (long long fract a, long long fract b)  
unsigned short fract __adduqq3 (unsigned short fract a, unsigned short fract b)  
unsigned fract __adduhq3 (unsigned fract a, unsigned fract b)  
unsigned long fract __addusq3 (unsigned long fract a, unsigned long fract b)  
unsigned long long fract __addudq3 (unsigned long long fract a, unsigned long long fract b)  
short accum __addha3 (short accum a, short accum b)  
accum __addsa3 (accum a, accum b)  
long accum __addda3 (long accum a, long accum b)  
long long accum __addta3 (long long accum a, long long accum b)
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unsigned short accum __adduha3 (unsigned short accum a, unsigned short accum b) [Runtime Function]

unsigned accum __addusa3 (unsigned accum a, unsigned accum b) [Runtime Function]

unsigned long accum __adduda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]

unsigned long long accum __adduta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the sum of \( a \) and \( b \).

short fract __ssaddqq3 (short fract a, short fract b) [Runtime Function]
fract __ssaddhq3 (fract a, fract b) [Runtime Function]
long fract __ssaddsq3 (long fract a, long fract b) [Runtime Function]
long long fract __ssadddq3 (long long fract a, long long fract b) [Runtime Function]
short accum __ssaddha3 (short accum a, short accum b) [Runtime Function]
accum __ssaddsa3 (accum a, accum b) [Runtime Function]
long accum __ssaddda3 (long accum a, long accum b) [Runtime Function]
long long accum __ssaddta3 (long long accum a, long long accum b) [Runtime Function]

These functions return the sum of \( a \) and \( b \) with signed saturation.

unsigned short fract __usadduqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __usadduhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __usaddusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __usaddudq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
unsigned short accum __usadduha3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __usaddusa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __usadduda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __usadduta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the sum of \( a \) and \( b \) with unsigned saturation.

short fract __subqq3 (short fract a, short fract b) [Runtime Function]
fract __subhq3 (fract a, fract b) [Runtime Function]
long fract __subsq3 (long fract a, long fract b) [Runtime Function]
long long fract __subdq3 (long long fract a, long long fract b) [Runtime Function]
unsigned short fract __subuqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __subuhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __subusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __subudq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
short accum __subha3 (short accum a, short accum b) [Runtime Function]
accum __subsa3 (accum a, accum b) [Runtime Function]
long accum __subda3 (long accum a, long accum b) [Runtime Function]
long long accum __subta3 (long long accum a, long long accum b) [Runtime Function]
unsigned short accum __subua3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __subsa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __subda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __subta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the difference of a and b; that is, a - b.

short fract __sssubqq3 (short fract a, short fract b) [Runtime Function]
fract __sssubhq3 (fract a, fract b) [Runtime Function]
long fract __sssubsq3 (long fract a, long fract b) [Runtime Function]
long long fract __sssubdq3 (long long fract a, long long fract b) [Runtime Function]
short accum __sssubha3 (short accum a, short accum b) [Runtime Function]
accum __sssubsa3 (accum a, accum b) [Runtime Function]
long accum __sssubda3 (long accum a, long accum b) [Runtime Function]
long long accum __sssubta3 (long long accum a, long long accum b) [Runtime Function]

These functions return the difference of a and b with signed saturation; that is, a - b.

unsigned short fract __ussubuqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __ussubuhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __ussubusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __ussubudq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
unsigned short accum __ussubua3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __ussubsa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __ussubda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __ussubta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]
These functions return the difference of \(a\) and \(b\) with unsigned saturation; that is, \(a - b\).

These functions return the product of \(a\) and \(b\) with signed saturation.
unsigned short fract __usmuluqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __usmuluhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __usmulusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __usmuludq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
unsigned short accum __usmuluha3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __usmulusa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __usmuluda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __usmuluta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the product of a and b with unsigned saturation.

short fract __divqq3 (short fract a, short fract b) [Runtime Function]
fract __divhq3 (fract a, fract b) [Runtime Function]
long fract __divsq3 (long fract a, long fract b) [Runtime Function]
long long fract __divdq3 (long long fract a, long long fract b) [Runtime Function]
short accum __divha3 (short accum a, short accum b) [Runtime Function]
accum __divsa3 (accum a, accum b) [Runtime Function]
long accum __divda3 (long accum a, long accum b) [Runtime Function]
long long accum __divta3 (long long accum a, long long accum b) [Runtime Function]

These functions return the quotient of the signed division of a and b.

unsigned short fract __udivuqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __udivuhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __udivusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __udivudq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
unsigned short accum __udivuha3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __udivusa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __udivuda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __udivuta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the quotient of the unsigned division of a and b.
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short fract __ssdivqq3 (short fract a, short fract b) [Runtime Function]
fract __ssdivhq3 (fract a, fract b) [Runtime Function]
long fract __ssdivsq3 (long fract a, long fract b) [Runtime Function]
long long fract __ssdivdq3 (long long fract a, long long fract b) [Runtime Function]
short accum __ssdivha3 (short accum a, short accum b) [Runtime Function]
accum __ssdivsa3 (accum a, accum b) [Runtime Function]
long accum __ssdivda3 (long accum a, long accum b) [Runtime Function]
long long accum __ssdivta3 (long long accum a, long long accum b) [Runtime Function]

These functions return the quotient of the signed division of a and b with signed saturation.

unsigned short fract __usdivuqq3 (unsigned short fract a, unsigned short fract b) [Runtime Function]
unsigned fract __usdivuhq3 (unsigned fract a, unsigned fract b) [Runtime Function]
unsigned long fract __usdivusq3 (unsigned long fract a, unsigned long fract b) [Runtime Function]
unsigned long long fract __usdivudq3 (unsigned long long fract a, unsigned long long fract b) [Runtime Function]
unsigned short accum __usdivuha3 (unsigned short accum a, unsigned short accum b) [Runtime Function]
unsigned accum __usdivusa3 (unsigned accum a, unsigned accum b) [Runtime Function]
unsigned long accum __usdivuda3 (unsigned long accum a, unsigned long accum b) [Runtime Function]
unsigned long long accum __usdivuta3 (unsigned long long accum a, unsigned long long accum b) [Runtime Function]

These functions return the quotient of the unsigned division of a and b with unsigned saturation.

short fract __negqq2 (short fract a) [Runtime Function]
fract __neghq2 (fract a) [Runtime Function]
long fract __negsq2 (long fract a) [Runtime Function]
long long fract __negdq2 (long long fract a) [Runtime Function]
unsigned short fract __neguqq2 (unsigned short fract a) [Runtime Function]
unsigned fract __neguhq2 (unsigned fract a) [Runtime Function]
unsigned long fract __negusq2 (unsigned long fract a) [Runtime Function]
unsigned long long fract __negudq2 (unsigned long long fract a) [Runtime Function]
short accum __negha2 (short accum a) [Runtime Function]
accum __negsa2 (accum a) [Runtime Function]
long accum __negda2 (long accum a) [Runtime Function]
long long accum __negta2 (long long accum a) [Runtime Function]
unsigned short accum __neguha2 (unsigned short accum a) [Runtime Function]
unsigned accum __negusa2 (unsigned accum a) [Runtime Function]
unsigned long accum __neguda2 (unsigned long accum a) [Runtime Function]
unsigned long long accum __neguta2 (unsigned long long accum a)

These functions return the negation of a.

short fract __ssnegqq2 (short fract a)
fract __ssneghq2 (fract a)
long fract __ssnegsq2 (long fract a)
long long fract __ssnegdq2 (long long fract a)
short accum __ssnegha2 (short accum a)
accum __ssnegsa2 (accum a)
long accum __ssnegda2 (long accum a)
long long accum __ssnegta2 (long long accum a)

These functions return the negation of a with signed saturation.

unsigned short fract __usneguqq2 (unsigned short fract a)
unsigned fract __usneguhq2 (unsigned fract a)
unsigned long fract __usnegusq2 (unsigned long fract a)
unsigned long long fract __usnegudq2 (unsigned long long fract a)
unsigned short accum __usneguha2 (unsigned short accum a)
unsigned accum __usnegusa2 (unsigned accum a)
unsigned long accum __usneguda2 (unsigned long accum a)
unsigned long long accum __usneguta2 (unsigned long long accum a)

These functions return the negation of a with unsigned saturation.
unsigned long long accum __ashluta3 (unsigned long long accum a, int b)
These functions return the result of shifting a left by b bits.

short fract __ashrqq3 (short fract a, int b)
fract __ashrhq3 (fract a, int b)
long long fract __ashrdq3 (long long fract a, int b)
short accum __ashrna3 (short accum a, int b)
accum __ashrva3 (accum a, int b)
long accum __ashrd3 (long accum a, int b)
long long accum __ashrt3 (long long accum a, int b)
These functions return the result of arithmetically shifting a right by b bits.

unsigned short fract __lshruqq3 (unsigned short fract a, int b)
unsigned fract __lshruhq3 (unsigned fract a, int b)
unsigned long fract __lshrusq3 (unsigned long fract a, int b)
unsigned long long fract __lshrudq3 (unsigned long long fract a, int b)
unsigned short accum __lshruha3 (unsigned short accum a, int b)
unsigned accum __lshrus3 (unsigned accum a, int b)
unsigned long accum __lshruda3 (unsigned long accum a, int b)
unsigned long long accum __lshruta3 (unsigned long long accum a, int b)
These functions return the result of logically shifting a right by b bits.

fract __ssashlhq3 (fract a, int b)
long fract __ssashlsq3 (long fract a, int b)
long long fract __ssashldq3 (long long fract a, int b)
short accum __ssaslh3 (short accum a, int b)
accum __ssashlsa3 (accum a, int b)
long accum __ssashlda3 (long accum a, int b)
long long accum __ssasht3 (long long accum a, int b)
These functions return the result of shifting a left by b bits with signed saturation.

unsigned short fract __usashluqq3 (unsigned short fract a, int b)
unsigned fract __usashluhq3 (unsigned fract a, int b)
unsigned long fract __usashlusq3 (unsigned long fract a, int b)
unsigned long long fract __usashludq3 (unsigned long long fract a, int b)
unsigned short accum __usashluha3 (unsigned short accum a, int b)
These functions return the result of shifting a left by b bits.
unsigned accum __usashlusa3 (unsigned accum a, int b) [Runtime Function]
unsigned long accum __usashluda3 (unsigned long accum a, int b)
unsigned long long accum __usashluta3 (unsigned long long accum a, int b)

These functions return the result of shifting a left by b bits with unsigned saturation.

4.4.2 Comparison functions

The following functions implement fixed-point comparisons. These functions implement a low-level compare, upon which the higher level comparison operators (such as less than and greater than or equal to) can be constructed. The returned values lie in the range zero to two, to allow the high-level operators to be implemented by testing the returned result using either signed or unsigned comparison.

int __cmpqq2 (short fract a, short fract b) [Runtime Function]
int __cmpqh2 (fract a, fract b) [Runtime Function]
int __cmphq2 (long fract a, long fract b) [Runtime Function]
int __cmpdq2 (long long fract a, long long fract b) [Runtime Function]
int __cmpuqq2 (unsigned short fract a, unsigned short fract b) [Runtime Function]
int __cmpuhq2 (unsigned fract a, unsigned fract b) [Runtime Function]
int __cmpusa2 (unsigned long fract a, unsigned long fract b) [Runtime Function]

These functions perform a signed or unsigned comparison of a and b (depending on the selected machine mode). If a is less than b, they return 0; if a is greater than b, they return 2; and if a and b are equal they return 1.

4.4.3 Conversion functions

fract __fractqqhq2 (short fract a) [Runtime Function]
long fract __fractqqsq2 (short fract a) [Runtime Function]
long long fract __fractqqdq2 (short fract a) [Runtime Function]
short accum __fractqqa2 (short fract a) [Runtime Function]
accum __fractqsa2 (short fract a) [Runtime Function]
long accum __fractqda2 (short fract a) [Runtime Function]
long long accum __fractqqta2 (short fract a) [Runtime Function]
unsigned short fract __fractqqu2q (short fract a) [Runtime Function]
unsigned fract __fractqquh2q (short fract a) [Runtime Function]
unsigned long fract __fractqqusq (short fract a) [Runtime Function]
unsigned long long fract __fractqqudq (short fract a) [Runtime Function]
unsigned short accum __fractqquha (short fract a) [Runtime Function]
unsigned accum __fractqquasa (short fract a) [Runtime Function]
unsigned long accum __fractqquda (short fract a) [Runtime Function]
unsigned long long accum __fractqquata (short fract a) [Runtime Function]
signed char __fractqquqi (short fract a) [Runtime Function]
short __fractqquhi (short fract a) [Runtime Function]
int __fractqqusi (short fract a) [Runtime Function]
long __fractqqudi (short fract a) [Runtime Function]
long long __fractqqudq (short fract a) [Runtime Function]
float __fractqqufsf (short fract a) [Runtime Function]
double __fractqqudfs (short fract a) [Runtime Function]
short fract __fractqquhh (short fract a) [Runtime Function]
long fract __fractqquh (long fract a) [Runtime Function]
long long fract __fractqquh (long fract a) [Runtime Function]
short accum __fractqquha (long fract a) [Runtime Function]
accum __fractqquha (long fract a) [Runtime Function]
long accum __fractqquda (long fract a) [Runtime Function]
unsigned short fract __fractqquha (long fract a) [Runtime Function]
unsigned accum __fractqquh (long fract a) [Runtime Function]
unsigned long accum __fractqquh (long fract a) [Runtime Function]
unsigned long long accum __fractqquh (long fract a) [Runtime Function]
signed char __fractqquhs (long fract a) [Runtime Function]
short __fractqquhs (long fract a) [Runtime Function]
int __fractqquhs (long fract a) [Runtime Function]
long __fractqquhs (long fract a) [Runtime Function]
long long __fractqquhs (long fract a) [Runtime Function]
short accum __fractqquha (long fract a) [Runtime Function]
accum __fractqquha (long fract a) [Runtime Function]
long accum __fractqquda (long fract a) [Runtime Function]
unsigned short fract __fractqquha (long fract a) [Runtime Function]
unsigned accum __fractqquh (long fract a) [Runtime Function]
unsigned long accum __fractqquh (long fract a) [Runtime Function]
unsigned long long accum __fractqquh (long fract a) [Runtime Function]
unsigned accum __fractsqusa (long fract a)
unsigned long accum __fractsquda (long fract a)
unsigned long long accum __fractsquta (long fract a)
signed char __fractsqqi (long fract a)
short __fractsqhi (long fract a)
int __fractsqsi (long fract a)
long __fractsqdi (long fract a)
long long __fractsqti (long fract a)
float __fractsqsf (long fract a)
double __fractsqdf (long fract a)
short fract __fractdqq2 (long long fract a)
fraction __fractdqhq2 (long long fract a)
long fract __fractdqsq2 (long long fract a)
short accum __fractdqha (long long fract a)
accum __fractdqsa (long long fract a)
long accum __fractdqua (long long fract a)
long long accum __fractdqtqa (long long fract a)
unsigned short fract __fractdquqq (long long fract a)
unsigned fract __fractdquhq (long long fract a)
unsigned long fract __fractdquqs (long long fract a)
unsigned long long fract __fractdqudq (long long fract a)
unsigned short accum __fractdquha (long long fract a)
unsigned accum __fractdqusa (long long fract a)
unsigned long accum __fractdquda (long long fract a)
unsigned long long accum __fractdquta (long long fract a)
signed char __fractdqqi (long long fract a)
short __fractdqqi (long long fract a)
int __fractdqqi (long long fract a)
long __fractdqqi (long long fract a)
long long __fractdqqi (long long fract a)
float __fractdqqi (long long fract a)
double __fractdqqi (long long fract a)
short fract __fractdqq2 (long long fract a)
fraction __fractdqq2 (long long fract a)
long fract __fractdqq2 (long long fract a)
short accum __fractdqq2 (long long fract a)
accum __fractdqq2 (long long fract a)
long accum __fractdqq2 (long long fract a)
long long accum __fractdqq2 (long long fract a)
unsigned short fract __fractdqq2 (long long fract a)
unsigned fract __fractdqq2 (long long fract a)
unsigned long fract __fractdqq2 (long long fract a)
unsigned long long fract __fractdqq2 (long long fract a)
unsigned short accum __fractdqq2 (long long fract a)
unsigned accum __fractdqq2 (long long fract a)
unsigned long accum __fracthauda (short accum a)  [Runtime Function]
unsigned long long accum __fracthauta (short accum a)  [Runtime Function]
signed char __fracthaqi (short accum a)  [Runtime Function]
short __fracthahi (short accum a)  [Runtime Function]
int __fracthasi (short accum a)  [Runtime Function]
long __fracthadi (short accum a)  [Runtime Function]
long long __fracthadi (short accum a)  [Runtime Function]
float __fracthasf (short accum a)  [Runtime Function]
double __fracthadf (short accum a)  [Runtime Function]
short fract __fractsaqq (accum a)  [Runtime Function]
fract __fractsahq (accum a)  [Runtime Function]
long fract __fractsaq (accum a)  [Runtime Function]
long long fract __fractsadq (accum a)  [Runtime Function]
short accum __fractsaha2 (accum a)  [Runtime Function]
long accum __fractsada2 (accum a)  [Runtime Function]
unsigned short fract __fractssauqq (accum a)  [Runtime Function]
unsigned fract __fractssahq (accum a)  [Runtime Function]
unsigned long fract __fractssausq (accum a)  [Runtime Function]
unsigned long long fract __fractssaudq (accum a)  [Runtime Function]
unsigned short accum __fractssauha (accum a)  [Runtime Function]
unsigned accum __fractssausa (accum a)  [Runtime Function]
unsigned long accum __fractssauda (accum a)  [Runtime Function]
unsigned long long accum __fractssauta (accum a)  [Runtime Function]
signed char __fractsaqi (accum a)  [Runtime Function]
short __fractssi (accum a)  [Runtime Function]
int __fractssasi (accum a)  [Runtime Function]
long __fractssadi (accum a)  [Runtime Function]
long long __fractssati (accum a)  [Runtime Function]
float __fractssasf (accum a)  [Runtime Function]
double __fractssadf (accum a)  [Runtime Function]
short fract __fractdaqq (long accum a)  [Runtime Function]
fract __fractdahq (long accum a)  [Runtime Function]
long fract __fractdasq (long accum a)  [Runtime Function]
long long fract __fractdadq (long accum a)  [Runtime Function]
short accum __fractdaha2 (long accum a)  [Runtime Function]
accum __fractdasa2 (long accum a)  [Runtime Function]
long long accum __fractdata2 (long accum a)  [Runtime Function]
unsigned short fract __fractdauuqq (long accum a)  [Runtime Function]
unsigned fract __fractdauhq (long accum a)  [Runtime Function]
unsigned long fract __fractdausq (long accum a)  [Runtime Function]
unsigned long long fract __fractdaudq (long accum a)  [Runtime Function]
unsigned short accum __fractdausha (long accum a)  [Runtime Function]
unsigned accum __fractdausa (long accum a)  [Runtime Function]
unsigned long accum __fractdauda (long accum a)  [Runtime Function]
unsigned long long accum __fractdauta (long accum a)  [Runtime Function]
signed char __fractdaqi (long accum a)  [Runtime Function]
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unsigned short fract __fractusquqq2 (unsigned long fract a)

unsigned fract __fractusquhq2 (unsigned long fract a)
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<thead>
<tr>
<th>Function Name</th>
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long fract __fractudasq (unsigned long accum a) [Runtime Function]
long long fract __fractudadq (unsigned long accum a) [Runtime Function]
short accum __fractudaha (unsigned long accum a) [Runtime Function]
accum __fractudasq (unsigned long accum a) [Runtime Function]
long accum __fractudada (unsigned long accum a) [Runtime Function]
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unsigned fract __fractudaubq (unsigned long accum a) [Runtime Function]
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double __fractutadf (unsigned long long accum a)
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fract __fractqihq (signed char a)
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fract __fracthihq (short a)
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accum __fracthsiqa (short a)
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unsigned fract __fracthiuuhq (short a)
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unsigned short accum __fracthiuha (short a)
unsigned accum __fracthiiusa (short a)
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fract __fractsihq (int a)
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long fract __fracttsfq (float a)
long long fract __fracttsfdq (float a)
short accum __fracttsfa (float a)
accum __fracttsfsa (float a)
long accum __fracttsfda (float a)
Chapter 4: The GCC low-level runtime library

These functions convert from fractional and signed non-fractionals to fractionals and signed non-fractionals, without saturation.

fract __satfractqhhq2 (short fract a)  
long fract __satfractqqsq2 (short fract a)  
long long fract __satfractqqdqq2 (short fract a)  
short accum __satfractqha (short fract a)  
accum __satfractqsa (short fract a)  
long accum __satfractqda (short fract a)  
long long accum __satfractqqta (short fract a)  
unsigned short fract __satfractqquqq (short fract a)  
unsigned fract __satfractqquhq (short fract a)  
unsigned long fract __satfractqquusq (short fract a)  
unsigned long long fract __satfractqqudq (short fract a)  

unsigned short accum __satfractqquha (short fract a)  
unsigned accum __satfractqqusa (short fract a)  
unsigned long accum __satfractqquda (short fract a)  
unsigned long long accum __satfractqquta (short fract a)  

short fract __satfracthqqq2 (fract a)  
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long long fract __satfracthqdq2 (fract a) [Runtime Function]
short accum __satfracthqha (fract a) [Runtime Function]
accum __satfracthqsa (fract a) [Runtime Function]
long accum __satfracthqda (fract a) [Runtime Function]
long long accum __satfracthqta (fract a) [Runtime Function]
unsigned short fract __satfracthqquqq (fract a) [Runtime Function]
unsigned fract __satfracthquhq (fract a) [Runtime Function]
unsigned long fract __satfracthqusq (fract a) [Runtime Function]
unsigned long long fract __satfracthqudq (fract a) [Runtime Function]
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fract __satfractsfhq (float a) [Runtime Function]
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The functions convert from fractional and signed non-fractionals to fractionals, with saturation.
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unsigned short __fractunsdhqi (unsigned short fract a) [Runtime Function]
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unsigned short __fractunstuhqhi (unsigned long fract a) [Runtime Function]
unsigned int __fractunstuhqsi (unsigned long fract a) [Runtime Function]
unsigned long long __fractunstuhqti (unsigned long fract a) [Runtime Function]
unsigned char __fractunstusqqi (unsigned long fract a) [Runtime Function]
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long accum __fractunshida (unsigned short a)
long long accum __fractunshita (unsigned short a)
unsigned short fract __fractunshiuqq (unsigned short a)
unsigned fract __fractunshiuuhq (unsigned short a)
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unsigned accum __fractunssiusa (unsigned long a)
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These functions convert from fractionals to unsigned non-fractionals; and from unsigned non-fractionals to fractionals, without saturation.
unsigned long long accum __satfractunsiuta (unsigned char a) [Runtime Function]
short fract __satfractunshiqq (unsigned short a) [Runtime Function]
fract __satfractunshihq (unsigned short a) [Runtime Function]
long fract __satfractunshiq (unsigned short a) [Runtime Function]
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unsigned long accum __satfractunshida (unsigned short a) [Runtime Function]
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fract __satfractunssihq (unsigned int a) [Runtime Function]
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long fract __satfractunssdisq (unsigned long a) [Runtime Function]
These functions convert from unsigned non-fractionals to fractionals, with saturation.

4.5 Language-independent routines for exception handling

document me!

_Unwind_DeleteException
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4.6 Miscellaneous runtime library routines

4.6.1 Cache control functions

void __clear_cache (char *beg, char *end)  
[Runtime Function]
This function clears the instruction cache between beg and end.

4.6.2 Split stack functions and variables

void * __splitstack_find (void *segment_arg, void *sp,  
size_t len, void **next_segment, void **next_sp, void **initial_sp)  
[Runtime Function]
When using `-fsplit-stack', this call may be used to iterate over the stack segments.
It may be called like this:

    void *next_segment = NULL;  
    void *next_sp = NULL;  
    void *initial_sp = NULL;  
    void *stack;  
    size_t stack_size;  
    while ((stack = __splitstack_find (next_segment, next_sp,  
        &stack_size, &next_segment,  
        &next_sp, &initial_sp))  
        != NULL)  
    
        {
            /* Stack segment starts at stack and is  
                stack_size bytes long. */  
        }
There is no way to iterate over the stack segments of a different thread. However, what is permitted is for one thread to call this with the `segment_arg` and `sp` arguments NULL, to pass `next_segment`, `next_sp`, and `initial_sp` to a different thread, and then to suspend one way or another. A different thread may run the subsequent `__splitstack_find` iterations. Of course, this will only work if the first thread is suspended while the second thread is calling `__splitstack_find`. If not, the second thread could be looking at the stack while it is changing, and anything could happen.

```c
__morestack_segments [Variable]
__morestack_current_segment [Variable]
__morestack_initial_sp [Variable]
```

Internal variables used by the ‘-fsplit-stack’ implementation.
5 Language Front Ends in GCC

The interface to front ends for languages in GCC, and in particular the tree structure (see Chapter 11 [OVERVIEW], page 165), was initially designed for C, and many aspects of it are still somewhat biased towards C and C-like languages. It is, however, reasonably well suited to other procedural languages, and front ends for many such languages have been written for GCC.

Writing a compiler as a front end for GCC, rather than compiling directly to assembler or generating C code which is then compiled by GCC, has several advantages:

- GCC front ends benefit from the support for many different target machines already present in GCC.
- GCC front ends benefit from all the optimizations in GCC. Some of these, such as alias analysis, may work better when GCC is compiling directly from source code than when it is compiling from generated C code.
- Better debugging information is generated when compiling directly from source code than when going via intermediate generated C code.

Because of the advantages of writing a compiler as a GCC front end, GCC front ends have also been created for languages very different from those for which GCC was designed, such as the declarative logic/functional language Mercury. For these reasons, it may also be useful to implement compilers created for specialized purposes (for example, as part of a research project) as GCC front ends.
6 Source Tree Structure and Build System

This chapter describes the structure of the GCC source tree, and how GCC is built. The user documentation for building and installing GCC is in a separate manual (http://gcc.gnu.org/install/), with which it is presumed that you are familiar.

6.1 Configure Terms and History

The configure and build process has a long and colorful history, and can be confusing to anyone who doesn’t know why things are the way they are. While there are other documents which describe the configuration process in detail, here are a few things that everyone working on GCC should know.

There are three system names that the build knows about: the machine you are building on (build), the machine that you are building for (host), and the machine that GCC will produce code for (target). When you configure GCC, you specify these with ‘--build=’, ‘--host=’, and ‘--target=’.

Specifying the host without specifying the build should be avoided, as configure may (and once did) assume that the host you specify is also the build, which may not be true.

If build, host, and target are all the same, this is called a native. If build and host are the same but target is different, this is called a cross. If build, host, and target are all different this is called a canadien (for obscure reasons dealing with Canada’s political party and the background of the person working on the build at that time). If host and target are the same, but build is different, you are using a cross-compiler to build a native for a different system. Some people call this a host-x-host, crossed native, or cross-built native. If build and target are the same, but host is different, you are using a cross compiler to build a cross compiler that produces code for the machine you’re building on. This is rare, so there is no common way of describing it. There is a proposal to call this a crossback.

If build and host are the same, the GCC you are building will also be used to build the target libraries (like libstdc++). If build and host are different, you must have already built and installed a cross compiler that will be used to build the target libraries (if you configured with ‘--target=foo-bar’, this compiler will be called foo-bar-gcc).

In the case of target libraries, the machine you’re building for is the machine you specified with ‘--target’. So, build is the machine you’re building on (no change there), host is the machine you’re building for (the target libraries are built for the target, so host is the target you specified), and target doesn’t apply (because you’re not building a compiler, you’re building libraries). The configure/make process will adjust these variables as needed. It also sets $with_cross_host to the original ‘--host’ value in case you need it.

The libiberty support library is built up to three times: once for the host, once for the target (even if they are the same), and once for the build if build and host are different. This allows it to be used by all programs which are generated in the course of the build process.

6.2 Top Level Source Directory

The top level source directory in a GCC distribution contains several files and directories that are shared with other software distributions such as that of GNU Binutils. It also contains several subdirectories that contain parts of GCC and its runtime libraries:
'boehm-gc'
The Boehm conservative garbage collector, optionally used as part of the ObjC runtime library when configured with `--enable-objc-gc`.

'config'
Autoconf macros and Makefile fragments used throughout the tree.

'contrib'
Contributed scripts that may be found useful in conjunction with GCC. One of these, `contrib/texi2pod.pl`, is used to generate man pages from Texinfo manuals as part of the GCC build process.

'fixincludes'
The support for fixing system headers to work with GCC. See `fixincludes/README` for more information. The headers fixed by this mechanism are installed in `/libsubdir/include-fixed`. Along with those headers, `README-fixinc` is also installed, as `/libsubdir/include-fixed/README`.

'gcc'
The main sources of GCC itself (except for runtime libraries), including optimizers, support for different target architectures, language front ends, and testsuites. See Section 6.3 [The ‘gcc’ Subdirectory], page 63, for details.

'gnattools'
Support tools for GNAT.

'include'
Headers for the `libiberty` library.

'intl'
GNU `libintl`, from GNU `gettext`, for systems which do not include it in `libc`.

'libada'
The Ada runtime library.

'libatomic'
The runtime support library for atomic operations (e.g. for `__sync` and `__atomic`).

'libcpp'
The C preprocessor library.

'libdecrnumber'
The Decimal Float support library.

'libffi'
The `libffi` library, used as part of the Go runtime library.

'libgcc'
The GCC runtime library.

'libfortran'
The Fortran runtime library.

'libgo'
The Go runtime library. The bulk of this library is mirrored from the master Go repository.

'libgomp'
The GNU Offloading and Multi Processing Runtime Library.

'libiberty'
The `libiberty` library, used for portability and for some generally useful data structures and algorithms. See Section “Introduction” in GNU `libiberty`, for more information about this library.

'libitm'
The runtime support library for transactional memory.
'libobjc' The Objective-C and Objective-C++ runtime library.

'libquadmath'
The runtime support library for quad-precision math operations.

'libphobos'
The D standard and runtime library. The bulk of this library is mirrored from the master D repositories.

'libssp'
The Stack protector runtime library.

'libstdc++-v3'
The C++ runtime library.

'lto-plugin'
Plugin used by the linker if link-time optimizations are enabled.

'maintainer-scripts'
Scripts used by the gccadmin account on gcc.gnu.org.

'zlib'
The zlib compression library, used for compressing and uncompressing GCC’s intermediate language in LTO object files.

The build system in the top level directory, including how recursion into subdirectories works and how building runtime libraries for multilibs is handled, is documented in a separate manual, included with GNU Binutils. See Section “GNU configure and build system” in The GNU configure and build system, for details.

6.3 The ‘gcc’ Subdirectory

The ‘gcc’ directory contains many files that are part of the C sources of GCC, other files used as part of the configuration and build process, and subdirectories including documentation and a testsuite. The files that are sources of GCC are documented in a separate chapter. See Chapter 9 [Passes and Files of the Compiler], page 131.

6.3.1 Subdirectories of ‘gcc’

The ‘gcc’ directory contains the following subdirectories:

'language'
Subdirectories for various languages. Directories containing a file ‘config-lang.in’ are language subdirectories. The contents of the subdirectories ‘c’ (for C), ‘cp’ (for C++), ‘objc’ (for Objective-C), ‘objcp’ (for Objective-C++), and ‘lto’ (for LTO) are documented in this manual (see Chapter 9 [Passes and Files of the Compiler], page 131); those for other languages are not. See Section 6.3.8 [Anatomy of a Language Front End], page 71, for details of the files in these directories.

'common'
Source files shared between the compiler drivers (such as gcc) and the compilers proper (such as ‘cc1’). If an architecture defines target hooks shared between those places, it also has a subdirectory in ‘common/config’. See Section 18.1 [Target Structure], page 497.
6.3.2 Configuration in the ‘gcc’ Directory

The ‘gcc’ directory is configured with an Autoconf-generated script ‘configure’. The ‘configure’ script is generated from ‘configure.ac’ and ‘aclocal.m4’. From the files ‘configure.ac’ and ‘acconfig.h’, Autoheader generates the file ‘config.in’. The file ‘cstamp-h.in’ is used as a timestamp.

6.3.2.1 Scripts Used by ‘configure’

‘configure’ uses some other scripts to help in its work:

- The standard GNU ‘config.sub’ and ‘config.guess’ files, kept in the top level directory, are used.
- The file ‘config.gcc’ is used to handle configuration specific to the particular target machine. The file ‘config.build’ is used to handle configuration specific to the particular build machine. The file ‘config.host’ is used to handle configuration specific to the particular host machine. (In general, these should only be used for features that cannot reasonably be tested in Autoconf feature tests.) See Section 6.3.2.2 [The ‘config.build’; ‘config.host’; and ‘config.gcc’ Files], page 65, for details of the contents of these files.
- Each language subdirectory has a file ‘language/config-lang.in’ that is used for front-end-specific configuration. See Section 6.3.8.2 [The Front End ‘config-lang.in’ File], page 73, for details of this file.
- A helper script ‘configure.frag’ is used as part of creating the output of ‘configure’. 
6.3.2.2 The ‘config.build’; ‘config.host’; and ‘config.gcc’ Files

The ‘config.build’ file contains specific rules for particular systems which GCC is built on. This should be used as rarely as possible, as the behavior of the build system can always be detected by autoconf.

The ‘config.host’ file contains specific rules for particular systems which GCC will run on. This is rarely needed.

The ‘config.gcc’ file contains specific rules for particular systems which GCC will generate code for. This is usually needed.

Each file has a list of the shell variables it sets, with descriptions, at the top of the file.

FIXME: document the contents of these files, and what variables should be set to control build, host and target configuration.

6.3.2.3 Files Created by configure

Here we spell out what files will be set up by ‘configure’ in the ‘gcc’ directory. Some other files are created as temporary files in the configuration process, and are not used in the subsequent build; these are not documented.

- ‘Makefile’ is constructed from ‘Makefile.in’, together with the host and target fragments (see Chapter 20 [Makefile Fragments], page 687) ‘t-target’ and ‘x-host’ from ‘config’, if any, and language Makefile fragments ‘language/Makelang.in’.
- ‘auto-host.h’ contains information about the host machine determined by ‘configure’. If the host machine is different from the build machine, then ‘auto-build.h’ is also created, containing such information about the build machine.
- ‘config.status’ is a script that may be run to recreate the current configuration.
- ‘configargs.h’ is a header containing details of the arguments passed to ‘configure’ to configure GCC, and of the thread model used.
- ‘cstamp-h’ is used as a timestamp.
- If a language ‘config-lang.in’ file (see Section 6.3.8.2 [The Front End ‘config-lang.in’ File], page 73) sets outputs, then the files listed in outputs there are also generated.

The following configuration headers are created from the Makefile, using ‘mkconfig.sh’, rather than directly by ‘configure’. ‘config.h’, ‘bconfig.h’ and ‘tconfig.h’ all contain the ‘xm-machine.h’ header, if any, appropriate to the host, build and target machines respectively, the configuration headers for the target, and some definitions; for the host and build machines, these include the autoconfigured headers generated by ‘configure’. The other configuration headers are determined by ‘config.gcc’. They also contain the typedefs for rtx, rtvec and tree.

- ‘config.h’, for use in programs that run on the host machine.
- ‘bconfig.h’, for use in programs that run on the build machine.
- ‘tconfig.h’, for use in programs and libraries for the target machine.
- ‘tm_p.h’, which includes the header ‘machine-protos.h’ that contains prototypes for functions in the target ‘machine.c’ file. The ‘machine-protos.h’ header is included after the ‘rtl.h’ and/or ‘tree.h’ would have been included. The ‘tm_p.h’ also includes the header ‘tm-preds.h’ which is generated by ‘genpreds’ program during the build to define the declarations and inline functions for the predicate functions.
6.3.3 Build System in the ‘gcc’ Directory

FIXME: describe the build system, including what is built in what stages. Also list the various source files that are used in the build process but aren’t source files of GCC itself and so aren’t documented below (see Chapter 9 [Passes], page 131).

6.3.4 Makefile Targets

These targets are available from the ‘gcc’ directory:

- **all**  
  This is the default target. Depending on what your build/host/target configuration is, it coordinates all the things that need to be built.

- **doc**  
  Produce info-formatted documentation and man pages. Essentially it calls ‘make man’ and ‘make info’.

- **dvi**  
  Produce DVI-formatted documentation.

- **pdf**  
  Produce PDF-formatted documentation.

- **html**  
  Produce HTML-formatted documentation.

- **man**  
  Generate man pages.

- **info**  
  Generate info-formatted pages.

- **mostlyclean**  
  Delete the files made while building the compiler.

- **clean**  
  That, and all the other files built by ‘make all’.

- **distclean**  
  That, and all the files created by configure.

- **maintainer-clean**  
  Distclean plus any file that can be generated from other files. Note that additional tools may be required beyond what is normally needed to build GCC.

- **srcextra**  
  Generates files in the source directory that are not version-controlled but should go into a release tarball.

- **srcinfo**  
  **srcman**  
  Copies the info-formatted and manpage documentation into the source directory usually for the purpose of generating a release tarball.

- **install**  
  Installs GCC.

- **uninstall**  
  Deletes installed files, though this is not supported.

- **check**  
  Run the testsuite. This creates a ‘testsuite’ subdirectory that has various ‘.sum’ and ‘.log’ files containing the results of the testing. You can run subsets with, for example, ‘make check-gcc’. You can specify specific tests by setting RUNTESTFLAGS to be the name of the ‘.exp’ file, optionally followed by (for some tests) an equals and a file wildcard, like:

  ```
  make check-gcc RUNTESTFLAGS="execute.exp=19980413-**"
  ```

  Note that running the testsuite may require additional tools be installed, such as Tcl or DejaGnu.
The toplevel tree from which you start GCC compilation is not the GCC directory, but rather a complex Makefile that coordinates the various steps of the build, including bootstrapping the compiler and using the new compiler to build target libraries.

When GCC is configured for a native configuration, the default action for `make` is to do a full three-stage bootstrap. This means that GCC is built three times—once with the native compiler, once with the native-built compiler it just built, and once with the compiler it built the second time. In theory, the last two should produce the same results, which `make compare` can check. Each stage is configured separately and compiled into a separate directory, to minimize problems due to ABI incompatibilities between the native compiler and GCC.

If you do a change, rebuilding will also start from the first stage and “bubble” up the change through the three stages. Each stage is taken from its build directory (if it had been built previously), rebuilt, and copied to its subdirectory. This will allow you to, for example, continue a bootstrap after fixing a bug which causes the stage2 build to crash. It does not provide as good coverage of the compiler as bootstrapping from scratch, but it ensures that the new code is syntactically correct (e.g., that you did not use GCC extensions by mistake), and avoids spurious bootstrap comparison failures\(^1\).

Other targets available from the top level include:

- `bootstrap-lean`
  
  Like `bootstrap`, except that the various stages are removed once they’re no longer needed. This saves disk space.

- `bootstrap2`
- `bootstrap2-lean`
  
  Performs only the first two stages of bootstrap. Unlike a three-stage bootstrap, this does not perform a comparison to test that the compiler is running properly. Note that the disk space required by a “lean” bootstrap is approximately independent of the number of stages.

- `stage\(N\)`-bubble (\(N = 1...4\), profile, feedback)
  
  Rebuild all the stages up to \(N\), with the appropriate flags, “bubbling” the changes as described above.

- `all-stage\(N\)` (\(N = 1...4\), profile, feedback)
  
  Assuming that stage \(N\) has already been built, rebuild it with the appropriate flags. This is rarely needed.

- `cleanstrap`
  
  Remove everything (`make clean`) and rebuilds (`make bootstrap`).

- `compare`
  
  Compares the results of stages 2 and 3. This ensures that the compiler is running properly, since it should produce the same object files regardless of how it itself was compiled.

- `profiledbootstrap`
  
  Builds a compiler with profiling feedback information. In this case, the second and third stages are named ‘profile’ and ‘feedback’, respectively. For more information, see the installation instructions.

---

\(^1\) Except if the compiler was buggy and miscompiled some of the files that were not modified. In this case, it’s best to use `make restrap`. 
restrap
Restart a bootstrap, so that everything that was not built with the system compiler is rebuilt.

stage$N$-start ($N = 1 \ldots 4$, profile, feedback)
For each package that is bootstrapped, rename directories so that, for example, ‘gcc’ points to the stage$N$ GCC, compiled with the stage$N-1$ GCC$^2$.
You will invoke this target if you need to test or debug the stage$N$ GCC. If you only need to execute GCC (but you need not run ‘make’ either to rebuild it or to run test suites), you should be able to work directly in the ‘stage$N$-gcc’ directory. This makes it easier to debug multiple stages in parallel.

stage
For each package that is bootstrapped, relocate its build directory to indicate its stage. For example, if the ‘gcc’ directory points to the stage2 GCC, after invoking this target it will be renamed to ‘stage2-gcc’.

If you wish to use non-default GCC flags when compiling the stage2 and stage3 compilers, set BOOT_CFLAGS on the command line when doing ‘make’.

Usually, the first stage only builds the languages that the compiler is written in: typically, C and maybe Ada. If you are debugging a miscompilation of a different stage2 front-end (for example, of the Fortran front-end), you may want to have front-ends for other languages in the first stage as well. To do so, set STAGE1_LANGUAGES on the command line when doing ‘make’.

For example, in the aforementioned scenario of debugging a Fortran front-end miscompilation caused by the stage1 compiler, you may need a command like

```
make stage2-bubble STAGE1_LANGUAGES=c,fortran
```

Alternatively, you can use per-language targets to build and test languages that are not enabled by default in stage1. For example, `make f951` will build a Fortran compiler even in the stage1 build directory.

6.3.5 Library Source Files and Headers under the ‘gcc’ Directory

FIXME: list here, with explanation, all the C source files and headers under the ‘gcc’ directory that aren’t built into the GCC executable but rather are part of runtime libraries and object files, such as ‘crtstuff.c’ and ‘unwind-dw2.c’. See Section 6.3.6 [Headers Installed by GCC], page 68, for more information about the ‘ginclude’ directory.

6.3.6 Headers Installed by GCC

In general, GCC expects the system C library to provide most of the headers to be used with it. However, GCC will fix those headers if necessary to make them work with GCC, and will install some headers required of freestanding implementations. These headers are installed in ‘libsubdir/include’. Headers for non-C runtime libraries are also installed by GCC; these are not documented here. (FIXME: document them somewhere.)

Several of the headers GCC installs are in the ‘ginclude’ directory. These headers, ‘iso646.h’, ‘stdarg.h’, ‘stdbool.h’, and ‘stddef.h’, are installed in ‘libsubdir/include’, unless the target Makefile fragment (see Section 20.1 [Target Fragment], page 687) overrides this by setting USER_H.

---

$^2$ Customarily, the system compiler is also termed the ‘stage0’ GCC.
In addition to these headers and those generated by fixing system headers to work with GCC, some other headers may also be installed in ‘libsubdir/include’. ‘config.gcc’ may set extra_headers; this specifies additional headers under ‘config’ to be installed on some systems.

GCC installs its own version of <float.h>, from ‘ginclude/float.h’. This is done to cope with command-line options that change the representation of floating point numbers.

GCC also installs its own version of <limits.h>; this is generated from ‘glimits.h’, together with ‘limitx.h’ and ‘limity.h’ if the system also has its own version of <limits.h>. (GCC provides its own header because it is required of ISO C freestanding implementations, but needs to include the system header from its own header as well because other standards such as POSIX specify additional values to be defined in <limits.h>.) The system’s <limits.h> header is used via ‘libsubdir/include/syslimits.h’, which is copied from ‘gsyslimits.h’ if it does not need fixing to work with GCC; if it needs fixing, ‘syslimits.h’ is the fixed copy.

GCC can also install <tgmath.h>. It will do this when ‘config.gcc’ sets use_gcc_tgmath to yes.

6.3.7 Building Documentation
The main GCC documentation is in the form of manuals in Texinfo format. These are installed in Info format; DVI versions may be generated by ‘make dvi’, PDF versions by ‘make pdf’, and HTML versions by ‘make html’. In addition, some man pages are generated from the Texinfo manuals, there are some other text files with miscellaneous documentation, and runtime libraries have their own documentation outside the ‘gcc’ directory. FIXME: document the documentation for runtime libraries somewhere.

6.3.7.1 Texinfo Manuals
The manuals for GCC as a whole, and the C and C++ front ends, are in files ‘doc/*.texi’. Other front ends have their own manuals in files ‘language/*.texi’. Common files ‘doc/include/*.texi’ are provided which may be included in multiple manuals; the following files are in ‘doc/include’:

‘fdl.texi’
The GNU Free Documentation License.

‘funding.texi’
The section “Funding Free Software”.

‘gcc-common.texi’
Common definitions for manuals.

‘gpl_v3.texi’
The GNU General Public License.

‘texinfo.tex’
A copy of ‘texinfo.tex’ known to work with the GCC manuals.

DVI-formatted manuals are generated by ‘make dvi’, which uses texi2dvi (via the Makefile macro $(TEXI2DVI)). PDF-formatted manuals are generated by ‘make pdf’, which uses texi2pdf (via the Makefile macro $(TEXI2PDF)). HTML formatted manuals are generated
by ‘make html’. Info manuals are generated by ‘make info’ (which is run as part of a boot-strap); this generates the manuals in the source directory, using makeinfo via the Makefile macro $(MAKEINFO), and they are included in release distributions.

Manuals are also provided on the GCC web site, in both HTML and PostScript forms. This is done via the script ‘maintainer-scripts/update_web_docs.git’. Each manual to be provided online must be listed in the definition of MANUALS in that file; a file ‘name.texi’ must only appear once in the source tree, and the output manual must have the same name as the source file. (However, other Texinfo files, included in manuals but not themselves the root files of manuals, may have names that appear more than once in the source tree.) The manual file ‘name.texi’ should only include other files in its own directory or in ‘doc/include’. HTML manuals will be generated by ‘makeinfo --html’, PostScript manuals by texi2dvi and dvips, and PDF manuals by texi2pdf. All Texinfo files that are parts of manuals must be version-controlled, even if they are generated files, for the generation of online manuals to work.

The installation manual, ‘doc/install.texi’, is also provided on the GCC web site. The HTML version is generated by the script ‘doc/install.texi2html’.

### 6.3.7.2 Man Page Generation

Because of user demand, in addition to full Texinfo manuals, man pages are provided which contain extracts from those manuals. These man pages are generated from the Texinfo manuals using ‘contrib/texi2pod.pl’ and pod2man. (The man page for g++, ‘cp/g++.1’, just contains a ‘.so’ reference to ‘gcc.1’, but all the other man pages are generated from Texinfo manuals.)

Because many systems may not have the necessary tools installed to generate the man pages, they are only generated if the ‘configure’ script detects that recent enough tools are installed, and the Makefiles allow generating man pages to fail without aborting the build. Man pages are also included in release distributions. They are generated in the source directory.

Magic comments in Texinfo files starting ‘@c man’ control what parts of a Texinfo file go into a man page. Only a subset of Texinfo is supported by ‘texi2pod.pl’, and it may be necessary to add support for more Texinfo features to this script when generating new man pages. To improve the man page output, some special Texinfo macros are provided in ‘doc/include/gcc-common.texi’ which ‘texi2pod.pl’ understands:

@gcctabopt

Use in the form ‘@table @gcctabopt’ for tables of options, where for printed output the effect of ‘@code’ is better than that of ‘@option’ but for man page output a different effect is wanted.

@gccoptlist

Use for summary lists of options in manuals.

@gol

Use at the end of each line inside ‘@gccoptlist’. This is necessary to avoid problems with differences in how the ‘@gccoptlist’ macro is handled by different Texinfo formatters.

FIXME: describe the ‘texi2pod.pl’ input language and magic comments in more detail.
6.3.7.3 Miscellaneous Documentation

In addition to the formal documentation that is installed by GCC, there are several other text files in the ‘gcc’ subdirectory with miscellaneous documentation:

‘ABOUT-GCC-NLS’
Notes on GCC’s Native Language Support. FIXME: this should be part of this manual rather than a separate file.

‘ABOUT-NLS’
Notes on the Free Translation Project.

‘COPYING’
‘COPYING3’
The GNU General Public License, Versions 2 and 3.

‘COPYING.LIB’
‘COPYING3.LIB’
The GNU Lesser General Public License, Versions 2.1 and 3.

‘*ChangeLog*’
‘*/ChangeLog*’
Change log files for various parts of GCC.

‘LANGUAGES’
Details of a few changes to the GCC front-end interface. FIXME: the information in this file should be part of general documentation of the front-end interface in this manual.

‘ONEWS’
Information about new features in old versions of GCC. (For recent versions, the information is on the GCC web site.)

‘README.Portability’
Information about portability issues when writing code in GCC. FIXME: why isn’t this part of this manual or of the GCC Coding Conventions?


6.3.8 Anatomy of a Language Front End

A front end for a language in GCC has the following parts:

- A directory ‘language’ under ‘gcc’ containing source files for that front end. See Section 6.3.8.1 [The Front End ‘language’ Directory], page 72, for details.
- A mention of the language in the list of supported languages in ‘gcc/doc/install.texi’.
- A mention of the name under which the language’s runtime library is recognized by ‘--enable-shared=package’ in the documentation of that option in ‘gcc/doc/install.texi’.
- A mention of any special prerequisites for building the front end in the documentation of prerequisites in ‘gcc/doc/install.texi’.
- Details of contributors to that front end in ‘gcc/doc/contrib.texi’. If the details are in that front end’s own manual then there should be a link to that manual’s list in ‘contrib.texi’.
• Information about support for that language in `gcc/doc/frontends.texi`.
• Information about standards for that language, and the front end’s support for them, in `gcc/doc/standards.texi`. This may be a link to such information in the front end’s own manual.
• Details of source file suffixes for that language and `-x lang` options supported, in `gcc/doc/invoke.texi`.
• Entries in `default_compilers` in `gcc.c` for source file suffixes for that language.
• Preferably testsuites, which may be under `gcc/testsuite` or runtime library directories. FIXME: document somewhere how to write testsuite harnesses.
• Probably a runtime library for the language, outside the `gcc` directory. FIXME: document this further.
• Details of the directories of any runtime libraries in `gcc/doc/sourcebuild.texi`.
• Check targets in `Makefile.def` for the top-level `Makefile` to check just the compiler or the compiler and runtime library for the language.

If the front end is added to the official GCC source repository, the following are also necessary:
• At least one Bugzilla component for bugs in that front end and runtime libraries. This category needs to be added to the Bugzilla database.
• Normally, one or more maintainers of that front end listed in `MAINTAINERS`.
• Mentions on the GCC web site in `index.html` and `frontends.html`, with any relevant links on `readings.html`. (Front ends that are not an official part of GCC may also be listed on `frontends.html`, with relevant links.)
• A news item on `index.html`, and possibly an announcement on the `gcc-announce@gcc.gnu.org` mailing list.
• The front end’s manuals should be mentioned in `maintainer-scripts/update_web_docs.git` (see Section 6.3.7.1 [Texinfo Manuals], page 69) and the online manuals should be linked to from `onlinedocs/index.html`.
• Any old releases or CVS repositories of the front end, before its inclusion in GCC, should be made available on the GCC web site at `https://gcc.gnu.org/pub/gcc/old-releases/`.
• The release and snapshot script `maintainer-scripts/gcc_release` should be updated to generate appropriate tarballs for this front end.
• If this front end includes its own version files that include the current date, `maintainer-scripts/update_version` should be updated accordingly.

6.3.8.1 The Front End ‘language’ Directory

A front end ‘language’ directory contains the source files of that front end (but not of any runtime libraries, which should be outside the ‘gcc’ directory). This includes documentation, and possibly some subsidiary programs built alongside the front end. Certain files are special and other parts of the compiler depend on their names:

‘config-lang.in’

This file is required in all language subdirectories. See Section 6.3.8.2 [The Front End ‘config-lang.in’ File], page 73, for details of its contents.
‘Make-lang.in’
This file is required in all language subdirectories. See Section 6.3.8.3 [The Front End ‘Make-lang.in’ File], page 74, for details of its contents.

‘lang.opt’
This file registers the set of switches that the front end accepts on the command line, and their ‘--help’ text. See Chapter 8 [Options], page 123.

‘lang-specs.h’
This file provides entries for default_compilers in ‘gcc.c’ which override the default of giving an error that a compiler for that language is not installed.

‘language-tree.def’
This file, which need not exist, defines any language-specific tree codes.

6.3.8.2 The Front End ‘config-lang.in’ File
Each language subdirectory contains a ‘config-lang.in’ file. This file is a shell script that may define some variables describing the language:

language
This definition must be present, and gives the name of the language for some purposes such as arguments to ‘--enable-languages’.

langRequires
If defined, this variable lists (space-separated) language front ends other than C that this front end requires to be enabled (with the names given being their language settings). For example, the Obj-C++ front end depends on the C++ and ObjC front ends, so sets ‘langRequires="objc c++"’.

subdirRequires
If defined, this variable lists (space-separated) front end directories other than C that this front end requires to be present. For example, the Objective-C++ front end uses source files from the C++ and Objective-C front ends, so sets ‘subdirRequires="cp objc"’.

targetLibs
If defined, this variable lists (space-separated) targets in the top level ‘Makefile’ to build the runtime libraries for this language, such as target-libobjc.

langDirs
If defined, this variable lists (space-separated) top level directories (parallel to ‘gcc’), apart from the runtime libraries, that should not be configured if this front end is not built.

buildByDefault
If defined to ‘no’, this language front end is not built unless enabled in an ‘--enable-languages’ argument. Otherwise, front ends are built by default, subject to any special logic in ‘configure.ac’ (as is present to disable the Ada front end if the Ada compiler is not already installed).

bootLanguage
If defined to ‘yes’, this front end is built in stage1 of the bootstrap. This is only relevant to front ends written in their own languages.
If defined, a space-separated list of compiler executables that will be run by the driver. The names here will each end with `\$(exeext)`.

If defined, a space-separated list of files that should be generated by `configure` substituting values in them. This mechanism can be used to create a file `language/Makefile` from `language/Makefile.in`, but this is deprecated, building everything from the single `gcc/Makefile` is preferred.

If defined, a space-separated list of files that should be scanned by `gengtype.c` to generate the garbage collection tables and routines for this language. This excludes the files that are common to all front ends. See Chapter 23 [Type Information], page 695.

### 6.3.8.3 The Front End ‘Make-lang.in’ File

Each language subdirectory contains a `Make-lang.in` file. It contains targets `lang.hook` (where `lang` is the setting of `language` in `config-lang.in`) for the following values of `hook`, and any other Makefile rules required to build those targets (which may if necessary use other Makefiles specified in `outputs` in `config-lang.in`, although this is deprecated). It also adds any testsuite targets that can use the standard rule in `gcc/Makefile.in` to the variable `lang_checks`.

- `all.cross`
- `start.encap`
- `rest.encap`
  
  FIXME: exactly what goes in each of these targets?

- `tags`
  Build an `etags` `TAGS` file in the language subdirectory in the source tree.

- `info`
  Build info documentation for the front end, in the build directory. This target is only called by `make bootstrap` if a suitable version of `makeinfo` is available, so does not need to check for this, and should fail if an error occurs.

- `dvi`
  Build DVI documentation for the front end, in the build directory. This should be done using `$(TEXI2DVI)`, with appropriate `-I` arguments pointing to directories of included files.

- `pdf`
  Build PDF documentation for the front end, in the build directory. This should be done using `$(TEXI2PDF)`, with appropriate `-I` arguments pointing to directories of included files.

- `html`
  Build HTML documentation for the front end, in the build directory.

- `man`
  Build generated man pages for the front end from Texinfo manuals (see Section 6.3.7.2 [Man Page Generation], page 70), in the build directory. This target is only called if the necessary tools are available, but should ignore errors so as not to stop the build if errors occur; man pages are optional and the tools involved may be installed in a broken way.

- `install-common`
  Install everything that is part of the front end, apart from the compiler executables listed in `compilers` in `config-lang.in`.
install-info
Install info documentation for the front end, if it is present in the source directory. This target should have dependencies on info files that should be installed.

install-man
Install man pages for the front end. This target should ignore errors.

install-plugin
Install headers needed for plugins.

srcextra
Copies its dependencies into the source directory. This generally should be used for generated files such as Bison output files which are not version-controlled, but should be included in any release tarballs. This target will be executed during a bootstrap if `--enable-generated-files-in-srcreldir` was specified as a `configure` option.

srcinfo
srcman
Copies its dependencies into the source directory. These targets will be executed during a bootstrap if `--enable-generated-files-in-srcreldir` was specified as a `configure` option.

uninstall
Uninstall files installed by installing the compiler. This is currently documented not to be supported, so the hook need not do anything.

mostlyclean
clean
distclean
maintainer-clean
The language parts of the standard GNU `*clean` targets. See Section “Standard Targets for Users” in GNU Coding Standards, for details of the standard targets. For GCC, `maintainer-clean` should delete all generated files in the source directory that are not version-controlled, but should not delete anything that is.

`Make-lang.in` must also define a variable `lang_OBJS` to a list of host object files that are used by that language.

6.3.9 Anatomy of a Target Back End
A back end for a target architecture in GCC has the following parts:

- A directory `machine` under `gcc/config`, containing a machine description `machine.md` file (see Chapter 17 [Machine Descriptions], page 349), header files `machine.h` and `machine-protos.h` and a source file `machine.c` (see Chapter 18 [Target Description Macros and Functions], page 497), possibly a target Makefile fragment `t-machine` (see Section 20.1 [The Target Makefile Fragment], page 687), and maybe some other files. The names of these files may be changed from the defaults given by explicit specifications in `config.gcc`.

- If necessary, a file `machine-modes.def` in the `machine` directory, containing additional machine modes to represent condition codes. See Section 18.15 [Condition Code], page 591, for further details.
• An optional `machine.opt` file in the `machine` directory, containing a list of target-specific options. You can also add other option files using the `extra_options` variable in `config.gcc`. See Chapter 8 [Options], page 123.

• Entries in `config.gcc` (see Section 6.3.2.2 [The `config.gcc` File], page 65) for the systems with this target architecture.

• Documentation in `gcc/doc/invoke.texi` for any command-line options supported by this target (see Section 18.3 [Run-time Target Specification], page 504). This means both entries in the summary table of options and details of the individual options.

• Documentation in `gcc/doc/extend.texi` for any target-specific attributes supported (see Section 18.24 [Defining target-specific uses of `__attribute__`], page 652), including where the same attribute is already supported on some targets, which are enumerated in the manual.

• Documentation in `gcc/doc/extend.texi` for any target-specific pragmas supported.

• Documentation in `gcc/doc/extend.texi` of any target-specific built-in functions supported.

• Documentation in `gcc/doc/extend.texi` of any target-specific format checking styles supported.

• Documentation in `gcc/doc/md.texi` of any target-specific constraint letters (see Section 17.8.5 [Constraints for Particular Machines], page 369).

• A note in `gcc/doc/contrib.texi` under the person or people who contributed the target support.

• Entries in `gcc/doc/install.texi` for all target triplets supported with this target architecture, giving details of any special notes about installation for this target, or saying that there are no special notes if there are none.

• Possibly other support outside the `gcc` directory for runtime libraries. FIXME: reference docs for this. The `libstdc++` porting manual needs to be installed as info for this to work, or to be a chapter of this manual.

The `machine.h` header is included very early in GCC’s standard sequence of header files, while `machine-protos.h` is included late in the sequence. Thus `machine-protos.h` can include declarations referencing types that are not defined when `machine.h` is included, specifically including those from `rtl.h` and `tree.h`. Since both RTL and tree types may not be available in every context where `machine-protos.h` is included, in this file you should guard declarations using these types inside appropriate `#ifdef RTX_CODE` or `#ifdef TREE_CODE` conditional code segments.

If the backend uses shared data structures that require GTY markers for garbage collection (see Chapter 23 [Type Information], page 695), you must declare those in `machine.h` rather than `machine-protos.h`. Any definitions required for building libgcc must also go in `machine.h`.

GCC uses the macro `IN_TARGET_CODE` to distinguish between machine-specific `.c` and `.cc` files and machine-independent `.c` and `.cc` files. Machine-specific files should use the directive:

```
#define IN_TARGET_CODE 1
```

before including `config.h`. 
If the back end is added to the official GCC source repository, the following are also necessary:

- An entry for the target architecture in ‘readings.html’ on the GCC web site, with any relevant links.
- Details of the properties of the back end and target architecture in ‘backends.html’ on the GCC web site.
- A news item about the contribution of support for that target architecture, in ‘index.html’ on the GCC web site.
- Normally, one or more maintainers of that target listed in ‘MAINTAINERS’. Some existing architectures may be unmaintained, but it would be unusual to add support for a target that does not have a maintainer when support is added.
- Target triplets covering all ‘config.gcc’ stanzas for the target, in the list in ‘contrib/config-list.mk’.
7 Testsuites

GCC contains several testsuites to help maintain compiler quality. Most of the runtime libraries and language front ends in GCC have testsuites. Currently only the C language testsuites are documented here; FIXME: document the others.

7.1 Idioms Used in Testsuite Code

In general, C testcases have a trailing ‘-n.c’, starting with ‘-1.c’, in case other testcases with similar names are added later. If the test is a test of some well-defined feature, it should have a name referring to that feature such as ‘feature-1.c’. If it does not test a well-defined feature but just happens to exercise a bug somewhere in the compiler, and a bug report has been filed for this bug in the GCC bug database, ‘prbug-number-1.c’ is the appropriate form of name. Otherwise (for miscellaneous bugs not filed in the GCC bug database), and previously more generally, test cases are named after the date on which they were added. This allows people to tell at a glance whether a test failure is because of a recently found bug that has not yet been fixed, or whether it may be a regression, but does not give any other information about the bug or where discussion of it may be found. Some other language testsuites follow similar conventions.

In the ‘gcc.dg’ testsuite, it is often necessary to test that an error is indeed a hard error and not just a warning—for example, where it is a constraint violation in the C standard, which must become an error with ‘-pedantic-errors’. The following idiom, where the first line shown is line line of the file and the line that generates the error, is used for this:

```c
/* { dg-bogus "warning" "warning in place of error" } */
/* { dg-error "regexp" "message" { target *-*-* } line } */
```

It may be necessary to check that an expression is an integer constant expression and has a certain value. To check that E has value V, an idiom similar to the following is used:

```c
char x[((E) == (V) ? 1 : -1)];
```

In ‘gcc.dg’ tests, __typeof__ is sometimes used to make assertions about the types of expressions. See, for example, ‘gcc.dg/c99-condexpr-1.c’. The more subtle uses depend on the exact rules for the types of conditional expressions in the C standard; see, for example, ‘gcc.dg/c99-intconst-1.c’.

It is useful to be able to test that optimizations are being made properly. This cannot be done in all cases, but it can be done where the optimization will lead to code being optimized away (for example, where flow analysis or alias analysis should show that certain code cannot be called) or to functions not being called because they have been expanded as built-in functions. Such tests go in ‘gcc.c-torture/execute’. Where code should be optimized away, a call to a nonexistent function such as link_failure () may be inserted; a definition

```c
#ifdef __OPTIMIZE__
void
link_failure (void)
{
    abort ();
}
#endif
```
will also be needed so that linking still succeeds when the test is run without optimization. When all calls to a built-in function should have been optimized and no calls to the non-built-in version of the function should remain, that function may be defined as static to call abort () (although redeclaring a function as static may not work on all targets).

All testcases must be portable. Target-specific testcases must have appropriate code to avoid causing failures on unsupported systems; unfortunately, the mechanisms for this differ by directory.

FIXME: discuss non-C testsuites here.

7.2 Directives used within DejaGnu tests

7.2.1 Syntax and Descriptions of test directives

Test directives appear within comments in a test source file and begin with dg-. Some of these are defined within DejaGnu and others are local to the GCC testsuite.

The order in which test directives appear in a test can be important: directives local to GCC sometimes override information used by the DejaGnu directives, which know nothing about the GCC directives, so the DejaGnu directives must precede GCC directives.

Several test directives include selectors (see Section 7.2.2 [Selectors], page 84) which are usually preceded by the keyword target or xfail.

7.2.1.1 Specify how to build the test

{ dg-do do-what-keyword [{ target/xfail selector }] }  
  do-what-keyword specifies how the test is compiled and whether it is executed. It is one of:
  
  preprocess  Compile with ‘-E’ to run only the preprocessor.
  compile    Compile with ‘-S’ to produce an assembly code file.
  assemble   Compile with ‘-c’ to produce a relocatable object file.
  link       Compile, assemble, and link to produce an executable file.
  run         Produce and run an executable file, which is expected to return an exit code of 0.

The default is compile. That can be overridden for a set of tests by redefining dg-do-what-default within the .exp file for those tests.

If the directive includes the optional ‘{ target selector }’ then the test is skipped unless the target system matches the selector.

If do-what-keyword is run and the directive includes the optional ‘{ xfail selector }’ and the selector is met then the test is expected to fail. The xfail clause is ignored for other values of do-what-keyword; those tests can use directive dg-xfail-if.
7.2.1.2 Specify additional compiler options

\{ dg-options options [[ target selector ]] \}

This DejaGnu directive provides a list of compiler options, to be used if the target system matches selector, that replace the default options used for this set of tests.

\{ dg-add-options feature ... \}

Add any compiler options that are needed to access certain features. This directive does nothing on targets that enable the features by default, or that don’t provide them at all. It must come after all dg-options directives. For supported values of feature see Section 7.2.4 [Add Options], page 107.

\{ dg-additional-options options [[ target selector ]] \}

This directive provides a list of compiler options, to be used if the target system matches selector, that are added to the default options used for this set of tests.

7.2.1.3 Modify the test timeout value

The normal timeout limit, in seconds, is found by searching the following in order:

- the value defined by an earlier dg-timeout directive in the test
- variable tool_timeout defined by the set of tests
- gcc,timeout set in the target board
- 300

\{ dg-timeout n [[target selector ]] \}

Set the time limit for the compilation and for the execution of the test to the specified number of seconds.

\{ dg-timeout-factor x [[ target selector ]] \}

Multiply the normal time limit for compilation and execution of the test by the specified floating-point factor.

7.2.1.4 Skip a test for some targets

\{ dg-skip-if comment { selector } [[ include-opts ] [[ exclude-opts ]]] \}

Arguments include-opts and exclude-opts are lists in which each element is a string of zero or more GCC options. Skip the test if all of the following conditions are met:

- the test system is included in selector
- for at least one of the option strings in include-opts, every option from that string is in the set of options with which the test would be compiled; use ‘*’ for an include-opts list that matches any options; that is the default if include-opts is not specified
- for each of the option strings in exclude-opts, at least one option from that string is not in the set of options with which the test would be compiled; use ‘’ for an empty exclude-opts list; that is the default if exclude-opts is not specified

For example, to skip a test if option -Os is present:
/* { dg-skip-if "" { *-*-* } { "-0s" } { "" } } */

To skip a test if both options -O2 and -g are present:
/* { dg-skip-if "" { *-*-* } { "-02 -g" } { "" } } */

To skip a test if either -O2 or -O3 is present:
/* { dg-skip-if "" { *-*-* } { "-02 "-03" } { "" } } */

To skip a test unless option -Os is present:
/* { dg-skip-if "" { *-*-* } { "*" } { "-0s" } } */

To skip a test if either -O2 or -O3 is used with -g but not if -fpic is also present:
/* { dg-skip-if "" { *-*-* } { "-02 -g" "-03 -g" } { "-fpic" } } */

{ dg-require-effective-target keyword [{ target selector }]
  Skip the test if the test target, including current multilib flags, is not covered by
  the effective-target keyword. If the directive includes the optional ‘{ selector }
  ’ then the effective-target test is only performed if the target system matches
  the selector. This directive must appear after any dg-do directive in the test
  and before any dg-additional-sources directive. See Section 7.2.3 [Effective-
  Target Keywords], page 86.

{ dg-require-support args }
  Skip the test if the target does not provide the required support. These di-
  rectives must appear after any dg-do directive in the test and before any dg-
  additional-sources directive. They require at least one argument, which can
  be an empty string if the specific procedure does not examine the argument. See
  Section 7.2.5 [Require Support], page 109, for a complete list of these directives.

7.2.1.5 Expect a test to fail for some targets

{ dg-xfail-if comment { selector } [{ include-opts } [{ exclude-opts }]] }
  Expect the test to fail if the conditions (which are the same as for dg-skip-if)
  are met. This does not affect the execute step.

{ dg-xfail-run-if comment { selector } [{ include-opts } [{ exclude-opts }]] }
  Expect the execute step of a test to fail if the conditions (which are the same
  as for dg-skip-if) are met.

7.2.1.6 Expect the compiler to crash

{ dg-ice comment [{ selector } [{ include-opts } [{ exclude-opts }]]]
  Expect the compiler to crash with an internal compiler error and return a
  nonzero exit status if the conditions (which are the same as for dg-skip-if)
  are met. Used for tests that test bugs that have not been fixed yet.

7.2.1.7 Expect the test executable to fail

{ dg-shouldfail comment [{ selector } [{ include-opts } [{ exclude-opts }]]]
  Expect the test executable to return a nonzero exit status if the conditions
  (which are the same as for dg-skip-if) are met.
7.2.1.8 Verify compiler messages

Where *line* is an accepted argument for these commands, a value of ‘0’ can be used if there is no line associated with the message.

```{ dg-error regexp [comment [{ target/xfail selector } [line]]] }
```

This DejaGnu directive appears on a source line that is expected to get an error message, or else specifies the source line associated with the message. If there is no message for that line or if the text of that message is not matched by `regexp` then the check fails and `comment` is included in the FAIL message. The check does not look for the string ‘error’ unless it is part of `regexp`.

```{ dg-warning regexp [comment [{ target/xfail selector } [line]]] }
```

This DejaGnu directive appears on a source line that is expected to get a warning message, or else specifies the source line associated with the message. If there is no message for that line or if the text of that message is not matched by `regexp` then the check fails and `comment` is included in the FAIL message. The check does not look for the string ‘warning’ unless it is part of `regexp`.

```{ dg-message regexp [comment [{ target/xfail selector } [line]]] }
```

The line is expected to get a message other than an error or warning. If there is no message for that line or if the text of that message is not matched by `regexp` then the check fails and `comment` is included in the FAIL message.

```{ dg-note regexp [comment [{ target/xfail selector } [line]]] }
```

The line is expected to get a ‘note’ message. If there is no message for that line or if the text of that message is not matched by `regexp` then the check fails and `comment` is included in the FAIL message. By default, any excess ‘note’ messages are pruned, meaning their appearance doesn’t trigger excess errors. However, if `dg-note` is used at least once in a testcase, they’re not pruned and instead must all be handled explicitly. Thus, if looking for just single instances of messages with ‘note: ’ prefixes without caring for all of them, use ‘dg-message "note: [...]"’ instead of ‘dg-note’, or use ‘dg-note’ together with ‘dg-prune-output "note: "’.

```{ dg-bogus regexp [comment [{ target/xfail selector } [line]]] }
```

This DejaGnu directive appears on a source line that should not get a message matching `regexp`, or else specifies the source line associated with the bogus message. It is usually used with ‘xfail’ to indicate that the message is a known problem for a particular set of targets.

```{ dg-line linenumvar }
```

This DejaGnu directive sets the variable `linenumvar` to the line number of the source line. The variable `linenumvar` can then be used in subsequent `dg-error`, `dg-warning`, `dg-message`, `dg-note` and `dg-bogus` directives. For example:

```
int a; /* { dg-line first_def_a } */
float a; /* { dg-error "conflicting types of" } */
/* { dg-message "previous declaration of" "{ target *-*-* } first_def_a } */
```

```{ dg-excess-errors comment [{ target/xfail selector } ] } }
```

This DejaGnu directive indicates that the test is expected to fail due to compiler messages that are not handled by ‘dg-error’, ‘dg-warning’, ‘dg-message’,
‘dg-note’ or ‘dg-bogus’. For this directive ‘xfail’ has the same effect as ‘target’.

{ dg-prune-output regexp }
Prune messages matching regexp from the test output.

7.2.1.9 Verify output of the test executable

{ dg-output regexp [{ target/xfail selector }] }
This DejaGnu directive compares regexp to the combined output that the test executable writes to ‘stdout’ and ‘stderr’.

7.2.1.10 Specify environment variables for a test

{ dg-set-compiler-env-var var_name "var_value" }
Specify that the environment variable var_name needs to be set to var_value before invoking the compiler on the test file.

{ dg-set-target-env-var var_name "var_value" }
Specify that the environment variable var_name needs to be set to var_value before execution of the program created by the test.

7.2.1.11 Specify additional files for a test

{ dg-additional-files "filelist" }
Specify additional files, other than source files, that must be copied to the system where the compiler runs.

{ dg-additional-sources "filelist" }
Specify additional source files to appear in the compile line following the main test file.

7.2.1.12 Add checks at the end of a test

{ dg-final { local-directive } }
This DejaGnu directive is placed within a comment anywhere in the source file and is processed after the test has been compiled and run. Multiple ‘dg-final’ commands are processed in the order in which they appear in the source file. See Section 7.2.6 [Final Actions], page 110, for a list of directives that can be used within dg-final.

7.2.2 Selecting targets to which a test applies
Several test directives include selectors to limit the targets for which a test is run or to declare that a test is expected to fail on particular targets.

A selector is:

• one or more target triplets, possibly including wildcard characters; use ‘*-*-*’ to match any target

• a single effective-target keyword (see Section 7.2.3 [Effective-Target Keywords], page 86)

• a list of compiler options that should be included or excluded (as described in more detail below)
• a logical expression

Depending on the context, the selector specifies whether a test is skipped and reported as unsupported or is expected to fail. A context that allows either ‘target’ or ‘xfail’ also allows ‘{ target selector1 xfail selector2 }’ to skip the test for targets that don’t match selector1 and the test to fail for targets that match selector2.

A selector expression appears within curly braces and uses a single logical operator: one of ‘!’, ‘&&’, or ‘||’. An operand is one of the following:

• another selector expression, in curly braces
• an effective-target keyword, such as lp64
• a single target triplet
• a list of target triplets within quotes or curly braces
• one of the following:

  `{ any-opts opt1 ... optn }`

  Each of opt1 to optn is a space-separated list of option globs. The selector expression evaluates to true if, for one of these strings, every glob in the string matches an option that was passed to the compiler. For example:

  `{ any-opts "-O3 -flto" "-O[2g]" }`

  is true if any of the following are true:

  • ‘-O2’ was passed to the compiler
  • ‘-Og’ was passed to the compiler
  • both ‘-O3’ and ‘-flto’ were passed to the compiler

  This kind of selector can only be used within dg-final directives. Use dg-skip-if, dg-xfail-if or dg-xfail-run-if to skip whole tests based on options, or to mark them as expected to fail with certain options.

  `{ no-opts opt1 ... optn }`

  As for any-opts above, each of opt1 to optn is a space-separated list of option globs. The selector expression evaluates to true if, for all of these strings, there is at least one glob that does not match an option that was passed to the compiler. It is shorthand for:

  `{ ! { any-opts opt1 ... optn } }`

  For example:

  `{ no-opts "-O3 -flto" "-O[2g]" }`

  is true if all of the following are true:

  • ‘-O2’ was not passed to the compiler
  • ‘-Og’ was not passed to the compiler
  • at least one of ‘-O3’ or ‘-flto’ was not passed to the compiler

  Like any-opts, this kind of selector can only be used within dg-final directives.

Here are some examples of full target selectors:

  `{ target { ! "hppa*-*-* ia64*-*-*" } }`
  `{ target { powerpc*-*-* & k lp64 } }`
  `{ xfail { lp64 || vect_no_align } }`
  `{ xfail { aarch64*-*-* & k { any-opts "-O2" } } }`
7.2.3 Keywords describing target attributes

Effective-target keywords identify sets of targets that support particular functionality. They are used to limit tests to be run only for particular targets, or to specify that particular sets of targets are expected to fail some tests.

Effective-target keywords are defined in `lib/target-supports.exp` in the GCC test-suite, with the exception of those that are documented as being local to a particular test directory.

The ‘effective target’ takes into account all of the compiler options with which the test will be compiled, including the multilib options. By convention, keywords ending in _nocache can also include options specified for the particular test in an earlier dg-options or dg-add-options directive.

7.2.3.1 Endianness

be Target uses big-endian memory order for multi-byte and multi-word data.
le Target uses little-endian memory order for multi-byte and multi-word data.

7.2.3.2 Data type sizes

ilp32 Target has 32-bit int, long, and pointers.
lp64 Target has 32-bit int, 64-bit long and pointers.
l1p64 Target has 32-bit int and long, 64-bit long long and pointers.

double64 Target has 64-bit double.
double64plus Target has double that is 64 bits or longer.

longdouble128 Target has 128-bit long double.

int32plus Target has int that is at 32 bits or longer.

int16 Target has int that is 16 bits or shorter.

longlong64 Target has 64-bit long long.

long_neq_int Target has int and long with different sizes.

short_eq_int Target has short and int with the same size.

ptr_eq_short Target has pointers (void *) and short with the same size.

int_eq_float Target has int and float with the same size.

ptr_eq_long Target has pointers (void *) and long with the same size.
large_double  
  Target supports double that is longer than float.

large_long_double  
  Target supports long double that is longer than double.

ptr32plus  
  Target has pointers that are 32 bits or longer.

double  
  Target supports double that is longer than float.

floatn  
  Target has the _Floatn type.

floatnx  
  Target has the _Floatnx type.

floatn_runtime  
  Target has the _Floatn type, including runtime support for any options added with dg-add-options.

floatnx_runtime  
  Target has the _Floatnx type, including runtime support for any options added with dg-add-options.

floatnx_runtime  
  Target has runtime support for any options added with dg-add-options for any _Floatn or _Floatnx type.

inf  
  Target supports floating point infinite (inf) for type double.

inff  
  Target supports floating point infinite (inf) for type float.

7.2.3.3 Fortran-specific attributes

fortran_integer_16  
  Target supports Fortran integer that is 16 bytes or longer.

fortran_real_10  
  Target supports Fortran real that is 10 bytes or longer.

fortran_real_16  
  Target supports Fortran real that is 16 bytes or longer.

fortran_large_int  
  Target supports Fortran integer kinds larger than integer(8).
fortran_large_real
Target supports Fortran real kinds larger than real(8).

7.2.3.4 Vector-specific attributes

vect_align_stack_vars
The target’s ABI allows stack variables to be aligned to the preferred vector alignment.

vect_avg_qi
Target supports both signed and unsigned averaging operations on vectors of bytes.

vect_mulhrs_hi
Target supports both signed and unsigned multiply-high-with-round-and-scale operations on vectors of half-words.

vect_sdiv_pow2_si
Target supports signed division by constant power-of-2 operations on vectors of 4-byte integers.

vect_condition
Target supports vector conditional operations.

vect_cond_mixed
Target supports vector conditional operations where comparison operands have different type from the value operands.

vect_double
Target supports hardware vectors of double.

vect_double_cond_arith
Target supports conditional addition, subtraction, multiplication, division, minimum and maximum on vectors of double, via the cond_ optabs.

vect_element_align_preferred
The target’s preferred vector alignment is the same as the element alignment.

vect_float
Target supports hardware vectors of float when ‘-funsafe-math-optimizations’ is in effect.

vect_float_strict
Target supports hardware vectors of float when ‘-funsafe-math-optimizations’ is not in effect. This implies vect_float.

vect_int
Target supports hardware vectors of int.

vect_long
Target supports hardware vectors of long.

vect_long_long
Target supports hardware vectors of long long.

vect_check_ptrs
Target supports the check_raw_ptrs and check_war_ptrs optabs on vectors.
vect_fully_masked
Target supports fully-masked (also known as fully-predicated) loops, so that vector loops can handle partial as well as full vectors.

vect_masked_load
Target supports vector masked loads.

vect_masked_store
Target supports vector masked stores.

vect_scatter_store
Target supports vector scatter stores.

vect_aligned_arrays
Target aligns arrays to vector alignment boundary.

vect_hw_misalign
Target supports a vector misalign access.

vect_no_align
Target does not support a vector alignment mechanism.

vect_peeling_profitable
Target might require to peel loops for alignment purposes.

vect_no_int_min_max
Target does not support a vector min and max instruction on int.

vect_no_int_add
Target does not support a vector add instruction on int.

vect_no_bitwise
Target does not support vector bitwise instructions.

vect_bool_cmp
Target supports comparison of bool vectors for at least one vector length.

vect_char_add
Target supports addition of char vectors for at least one vector length.

vect_char_mult
Target supports vector char multiplication.

vect_short_mult
Target supports vector short multiplication.

vect_int_mult
Target supports vector int multiplication.

vect_long_mult
Target supports 64 bit vector long multiplication.

vect_extract_even_odd
Target supports vector even/odd element extraction.

vect_extract_even_odd_wide
Target supports vector even/odd element extraction of vectors with elements SImode or larger.
vect_interleave
Target supports vector interleaving.

vect_strided
Target supports vector interleaving and extract even/odd.

vect_strided_wide
Target supports vector interleaving and extract even/odd for wide element types.

vect_perm
Target supports vector permutation.

vect_perm_byte
Target supports permutation of vectors with 8-bit elements.

vect_perm_short
Target supports permutation of vectors with 16-bit elements.

vect_perm3_byte
Target supports permutation of vectors with 8-bit elements, and for the default vector length it is possible to permute:

\{ a0, a1, a2, b0, b1, b2, ... \}

to:

\{ a0, a0, a0, b0, b0, b0, ... \}
\{ a1, a1, a1, b1, b1, b1, ... \}
\{ a2, a2, a2, b2, b2, b2, ... \}

using only two-vector permutes, regardless of how long the sequence is.

vect_perm3_int
Like vect_perm3_byte, but for 32-bit elements.

vect_perm3_short
Like vect_perm3_byte, but for 16-bit elements.

vect_shift
Target supports a hardware vector shift operation.

vect_unaligned_possible
Target prefers vectors to have an alignment greater than element alignment, but also allows unaligned vector accesses in some circumstances.

vect_variable_length
Target has variable-length vectors.

vect64
Target supports vectors of 64 bits.

vect32
Target supports vectors of 32 bits.

vect_widen_sum_hi_to_si
Target supports a vector widening summation of short operands into int results, or can promote (unpack) from short to int.

vect_widen_sum_qi_to_hi
Target supports a vector widening summation of char operands into short results, or can promote (unpack) from char to short.
\texttt{vect\_widen\_sum\_qi\_to\_si}
Target supports a vector widening summation of \texttt{char} operands into \texttt{int} results.

\texttt{vect\_widen\_mult\_qi\_to\_hi}
Target supports a vector widening multiplication of \texttt{char} operands into \texttt{short} results, or can promote (unpack) from \texttt{char} to \texttt{short} and perform non-widening multiplication of \texttt{short}.

\texttt{vect\_widen\_mult\_hi\_to\_si}
Target supports a vector widening multiplication of \texttt{short} operands into \texttt{int} results, or can promote (unpack) from \texttt{short} to \texttt{int} and perform non-widening multiplication of \texttt{int}.

\texttt{vect\_widen\_mult\_si\_to\_di\_pattern}
Target supports a vector widening multiplication of \texttt{int} operands into \texttt{long} results.

\texttt{vect\_sdot\_qi}
Target supports a vector dot-product of \texttt{signed char}.

\texttt{vect\_udot\_qi}
Target supports a vector dot-product of \texttt{unsigned char}.

\texttt{vect\_usdot\_qi}
Target supports a vector dot-product where one operand of the multiply is \texttt{signed char} and the other of \texttt{unsigned char}.

\texttt{vect\_sdot\_hi}
Target supports a vector dot-product of \texttt{signed short}.

\texttt{vect\_udot\_hi}
Target supports a vector dot-product of \texttt{unsigned short}.

\texttt{vect\_pack\_trunc}
Target supports a vector demotion (packing) of \texttt{short} to \texttt{char} and from \texttt{int} to \texttt{short} using modulo arithmetic.

\texttt{vect\_unpack}
Target supports a vector promotion (unpacking) of \texttt{char} to \texttt{short} and from \texttt{char} to \texttt{int}.

\texttt{vect\_int\_float\_cvt}
Target supports conversion from \texttt{signed int} to \texttt{float}.

\texttt{vect\_uint\_float\_cvt}
Target supports conversion from \texttt{unsigned int} to \texttt{float}.

\texttt{vect\_float\_int\_cvt}
Target supports conversion from \texttt{float} to \texttt{signed int}.

\texttt{vect\_float\_uint\_cvt}
Target supports conversion from \texttt{float} to \texttt{unsigned int}.

\texttt{vect\_int\_double\_cvt}
Target supports conversion from \texttt{signed int} to \texttt{double}.
vect_doubleint_cvt
  Target supports conversion from double to signed int.

vect_max_reduc
  Target supports max reduction for vectors.

vect_sizes_16B_8B
  Target supports 16- and 8-bytes vectors.

vect_sizes_32B_16B
  Target supports 32- and 16-bytes vectors.

vect_logical_reduc
  Target supports AND, IOR and XOR reduction on vectors.

vect_fold_extract_last
  Target supports the fold_extract_last optab.

vect_len_load_store
  Target supports the len_load and len_store optabs.

vect_partial_vectors_usage_1
  Target supports loop vectorization with partial vectors and vect-partial-
  vector-usage is set to 1.

vect_partial_vectors_usage_2
  Target supports loop vectorization with partial vectors and vect-partial-
  vector-usage is set to 2.

vect_partial_vectors
  Target supports loop vectorization with partial vectors and vect-partial-
  vector-usage is nonzero.

7.2.3.5 Thread Local Storage attributes

tls
  Target supports thread-local storage.

tls_native
  Target supports native (rather than emulated) thread-local storage.

tls_runtime
  Test system supports executing TLS executables.

7.2.3.6 Decimal floating point attributes

dfp
  Targets supports compiling decimal floating point extension to C.

dfp_nocache
  Including the options used to compile this particular test, the target supports
  compiling decimal floating point extension to C.

dfpert
  Test system can execute decimal floating point tests.

dfpert_nocache
  Including the options used to compile this particular test, the test system can
  execute decimal floating point tests.

hard_dfp
  Target generates decimal floating point instructions with current options.
### 7.2.3.7 ARM-specific attributes

- **arm32**  
  ARM target generates 32-bit code.

- **arm_little_endian**  
  ARM target that generates little-endian code.

- **arm_eabi**  
  ARM target adheres to the ABI for the ARM Architecture.

- **arm_fp_ok**  
  ARM target defines `__ARM_FP` using `-mfloat-abi=softfp` or equivalent options. Some multilibs may be incompatible with these options.

- **arm_fp_dp_ok**  
  ARM target defines `__ARM_FP` with double-precision support using `-mfloat-abi=softfp` or equivalent options. Some multilibs may be incompatible with these options.

- **arm_hf_eabi**  
  ARM target adheres to the VFP and Advanced SIMD Register Arguments variant of the ABI for the ARM Architecture (as selected with `-mfloat-abi=hard`).

- **arm_softfloat**  
  ARM target uses emulated floating point operations.

- **arm_hard_vfp_ok**  
  ARM target supports `-mfpu=vfp -mfloat-abi=hard`. Some multilibs may be incompatible with these options.

- **arm_iwmmxt_ok**  
  ARM target supports `-mcpu=iwmmxt`. Some multilibs may be incompatible with this option.

- **arm_neon**  
  ARM target supports generating NEON instructions.

- **arm_tune_string_ops_prefer_neon**  
  Test CPU tune supports inlining string operations with NEON instructions.

- **arm_neon_hw**  
  Test system supports executing NEON instructions.

- **arm_neonv2_hw**  
  Test system supports executing NEON v2 instructions.

- **arm_neon_ok**  
  ARM Target supports `-mfpu=neon -mfloat-abi=softfp` or compatible options. Some multilibs may be incompatible with these options.

- **arm_neon_ok_no_float_abi**  
  ARM Target supports NEON with `-mfpu=neon`, but without any `-mfloat-abi=` option. Some multilibs may be incompatible with this option.

- **arm_neonv2_ok**  
  ARM Target supports `-mfpu=neon-vfpv4 -mfloat-abi=softfp` or compatible options. Some multilibs may be incompatible with these options.
arm_fp16_ok
Target supports options to generate VFP half-precision floating-point instructions. Some multilibs may be incompatible with these options. This test is valid for ARM only.

arm_fp16_hw
Target supports executing VFP half-precision floating-point instructions. This test is valid for ARM only.

arm_neon_fp16_ok
ARM Target supports `-mfpu=neon-fp16` `-mfloat-abi=softfp` or compatible options, including `-mfp16-format=ieee` if necessary to obtain the `__fp16` type. Some multilibs may be incompatible with these options.

arm_neon_fp16_hw
Test system supports executing Neon half-precision float instructions. (Implies previous.)

arm_fp16_alternative_ok
ARM target supports the ARM FP16 alternative format. Some multilibs may be incompatible with the options needed.

arm_fp16_none_ok
ARM target supports specifying none as the ARM FP16 format.

arm_thumb1_ok
ARM target generates Thumb-1 code for `-mthumb`.

arm_thumb2_ok
ARM target generates Thumb-2 code for `-mthumb`.

arm_nothumb
ARM target that is not using Thumb.

arm_vfp_ok
ARM target supports `-mfpu=vfp` `-mfloat-abi=softfp`. Some multilibs may be incompatible with these options.

arm_vfp3_ok
ARM target supports `-mfpu=vfp3` `-mfloat-abi=softfp`. Some multilibs may be incompatible with these options.

arm_arch_v8a_hard_ok
The compiler is targeting arm*-v8-a* and can compile and assemble code using the options `-march=armv8-a` `-mfpu=neon-fp-armv8` `-mfloat-abi=hard`. This is not enough to guarantee that linking works.

arm_arch_v8a_hard_multilib
The compiler is targeting arm*-v8-a* and can build programs using the options `-march=armv8-a` `-mfpu=neon-fp-armv8` `-mfloat-abi=hard`. The target can also run the resulting binaries.

arm_v8_vfp_ok
ARM target supports `-mfpu=fp-armv8` `-mfloat-abi=softfp`. Some multilibs may be incompatible with these options.
arm_v8_neon_ok
ARM target supports -mfpu=neon-fp-armv8 -mfloat-abi=softfp. Some multilibs may be incompatible with these options.

arm_v8_1a_neon_ok
ARM target supports options to generate ARMv8.1-A Adv.SIMD instructions. Some multilibs may be incompatible with these options.

arm_v8_1a_neon_hw
ARM target supports executing ARMv8.1-A Adv.SIMD instructions. Some multilibs may be incompatible with the options needed. Implies arm_v8_1a_neon_ok.

arm_acq_rel
ARM target supports acquire-release instructions.

arm_v8_2a_fp16_scalar_ok
ARM target supports options to generate instructions for ARMv8.2-A and scalar instructions from the FP16 extension. Some multilibs may be incompatible with these options.

arm_v8_2a_fp16_scalar_hw
ARM target supports executing instructions for ARMv8.2-A and scalar instructions from the FP16 extension. Some multilibs may be incompatible with these options. Implies arm_v8_2a_fp16_neon_ok.

arm_v8_2a_fp16_neon_ok
ARM target supports options to generate instructions from ARMv8.2-A with the FP16 extension. Some multilibs may be incompatible with these options. Implies arm_v8_2a_fp16_neon_hw.

arm_v8_2a_fp16_neon_hw
ARM target supports executing instructions from ARMv8.2-A with the FP16 extension. Some multilibs may be incompatible with these options. Implies arm_v8_2a_fp16_neon_ok and arm_v8_2a_fp16_scalar_hw.

arm_v8_2a_dotprod_neon_ok
ARM target supports options to generate instructions from ARMv8.2-A with the Dot Product extension. Some multilibs may be incompatible with these options.

arm_v8_2a_dotprod_neon_hw
ARM target supports executing instructions from ARMv8.2-A with the Dot Product extension. Some multilibs may be incompatible with these options. Implies arm_v8_2a_dotprod_neon_ok.

arm_v8_2a_i8mm_neon_hw
ARM target supports executing instructions from ARMv8.2-A with the 8-bit Matrix Multiply extension. Some multilibs may be incompatible with these options. Implies arm_v8_2a_i8mm_ok.
arm_fp16fml_neon_ok
ARM target supports extensions to generate the VFML and VFMLS half-precision floating-point instructions available from ARMv8.2-A and onwards. Some multilibs may be incompatible with these options.

arm_v8_2a_bf16_neon_ok
ARM target supports options to generate instructions from ARMv8.2-A with the BFLOAT16 extension (bf16). Some multilibs may be incompatible with these options.

arm_v8_2a_i8mm_ok
ARM target supports options to generate instructions from ARMv8.2-A with the 8-Bit Integer Matrix Multiply extension (i8mm). Some multilibs may be incompatible with these options.

arm_v8_1m_mve_ok
ARM target supports options to generate instructions from ARMv8.1-M with the M-Profile Vector Extension (MVE). Some multilibs may be incompatible with these options.

arm_v8_1m_mve_fp_ok
ARM target supports options to generate instructions from ARMv8.1-M with the Half-precision floating-point instructions (HP), Floating-point Extension (FP) along with M-Profile Vector Extension (MVE). Some multilibs may be incompatible with these options.

arm_mve_hw
Test system supports executing MVE instructions.

arm_v8m_main_cde
ARM target supports options to generate instructions from ARMv8-M with the Custom Datapath Extension (CDE). Some multilibs may be incompatible with these options.

arm_v8m_main_cde_fp
ARM target supports options to generate instructions from ARMv8-M with the Custom Datapath Extension (CDE) and floating-point (VFP). Some multilibs may be incompatible with these options.

arm_v8_1m_main_cde_mve
ARM target supports options to generate instructions from ARMv8.1-M with the Custom Datapath Extension (CDE) and M-Profile Vector Extension (MVE). Some multilibs may be incompatible with these options.

arm_prefer_ldrd_strd
ARM target prefers LDRD and STRD instructions over LDM and STM instructions.

arm_thumb1_movt_ok
ARM target generates Thumb-1 code for -mthumb with MOVW and MOVT instructions available.

arm_thumb1_cbz_ok
ARM target generates Thumb-1 code for -mthumb with CBZ and CBNZ instructions available.
arm_divmod_simode
ARM target for which divmod transform is disabled, if it supports hardware div instruction.

arm_cmse_ok
ARM target supports ARMv8-M Security Extensions, enabled by the -mcmse option.

arm_cmse_hw
Test system supports executing CMSE instructions.

arm_coproc1_ok
ARM target supports the following coprocessor instructions: CDP, LDC, STC, MCR and MRC.

arm_coproc2_ok
ARM target supports all the coprocessor instructions also listed as supported in [arm_coproc1_ok], page 97 in addition to the following: CDP2, LDC2, LDC21, STC2, STC21, MCR2 and MRC2.

arm_coproc3_ok
ARM target supports all the coprocessor instructions also listed as supported in [arm_coproc2_ok], page 97 in addition the following: MCRR and MRRC.

arm_coproc4_ok
ARM target supports all the coprocessor instructions also listed as supported in [arm_coproc3_ok], page 97 in addition the following: MCRR2 and MRRC2.

arm_simd32_ok
ARM Target supports options suitable for accessing the SIMD32 intrinsics from arm_acle.h. Some multilibs may be incompatible with these options.

arm_sat_ok
ARM Target supports options suitable for accessing the saturation intrinsics from arm_acle.h. Some multilibs may be incompatible with these options.

arm_dsp_ok
ARM Target supports options suitable for accessing the DSP intrinsics from arm_acle.h. Some multilibs may be incompatible with these options.

arm_softfp_ok
ARM target supports the -mfloat-abi=softfp option.

arm_hard_ok
ARM target supports the -mfloat-abi=hard option.

arm_v8_1_lob_ok
ARM Target supports executing the Armv8.1-M Mainline Low Overhead Loop instructions DLS and LE. Some multilibs may be incompatible with these options.

arm_thumb2_no_arm_v8_1_lob
ARM target where Thumb-2 is used without options but does not support executing the Armv8.1-M Mainline Low Overhead Loop instructions DLS and LE.
ARM target generates Thumb-2 code for `-mthumb` but does not support executing the Armv8.1-M Mainline Low Overhead Loop instructions DLS and LE.

### 7.2.3.8 AArch64-specific attributes

- **aarch64_asm_<ext>_ok**
  AArch64 assembler supports the architecture extension `ext` via the `.arch_extension` pseudo-op.

- **aarch64_tiny**
  AArch64 target which generates instruction sequences for tiny memory model.

- **aarch64_small**
  AArch64 target which generates instruction sequences for small memory model.

- **aarch64_large**
  AArch64 target which generates instruction sequences for large memory model.

- **aarch64_little_endian**
  AArch64 target which generates instruction sequences for little endian.

- **aarch64_big_endian**
  AArch64 target which generates instruction sequences for big endian.

- **aarch64_small_fpic**
  Binutils installed on test system supports relocation types required by `-fpic` for AArch64 small memory model.

- **aarch64_sve_hw**
  AArch64 target that is able to generate and execute SVE code (regardless of whether it does so by default).

- **aarch64_sve128_hw**
- **aarch64_sve256_hw**
- **aarch64_sve512_hw**
- **aarch64_sve1024_hw**
- **aarch64_sve2048_hw**
  Like `aarch64_sve_hw`, but also test for an exact hardware vector length.

- **aarch64_fjcvtzs_hw**
  AArch64 target that is able to generate and execute armv8.3-a FJCVTZS instruction.

### 7.2.3.9 MIPS-specific attributes

- **mips64**
  MIPS target supports 64-bit instructions.

- **nomips16**
  MIPS target does not produce MIPS16 code.

- **mips16_attribute**
  MIPS target can generate MIPS16 code.

- **mips_loongson**
  MIPS target is a Loongson-2E or -2F target using an ABI that supports the Loongson vector modes.
mips_msa  
MIPS target supports `-mmsa`, MIPS SIMD Architecture (MSA).

mips_newabi_large_long_double  
MIPS target supports `long double` larger than `double` when using the new ABI.

mpaired_single  
MIPS target supports `-mpaired-single`.

7.2.3.10  **MSP430-specific attributes**

msp430_small  
MSP430 target has the small memory model enabled (`-msmall`).

msp430_large  
MSP430 target has the large memory model enabled (`-mlarge`).

7.2.3.11  **PowerPC-specific attributes**

dfp_hw  
PowerPC target supports executing hardware DFP instructions.

p8vector_hw  
PowerPC target supports executing VSX instructions (ISA 2.07).

powerpc64  
Test system supports executing 64-bit instructions.

powerpc_altivec  
PowerPC target supports AltiVec.

powerpc_altivec_ok  
PowerPC target supports `-maltivec`.

powerpc_eabi_ok  
PowerPC target supports `-meabi`.

powerpc_elfv2  
PowerPC target supports `-mabi=elfv2`.

powerpc_fprs  
PowerPC target supports floating-point registers.

powerpc_hard_double  
PowerPC target supports hardware double-precision floating-point.

powerpc_htm_ok  
PowerPC target supports `-mhtm`.

powerpc_p8vector_ok  
PowerPC target supports `-mpower8-vector`.

powerpc_popcntb_ok  
PowerPC target supports the `popcntb` instruction, indicating that this target supports `-mcpu=power5`.

powerpc_ppu_ok  
PowerPC target supports `-mcpu=cell`. 
powerpc_spe
   PowerPC target supports PowerPC SPE.

powerpc_spe_nocache
   Including the options used to compile this particular test, the PowerPC target
   supports PowerPC SPE.

powerpc_spu
   PowerPC target supports PowerPC SPU.

powerpc_vsx_ok
   PowerPC target supports -mvsx.

powerpc_405_nocache
   Including the options used to compile this particular test, the PowerPC target
   supports PowerPC 405.

ppc_recip_hw
   PowerPC target supports executing reciprocal estimate instructions.

vmx_hw
   PowerPC target supports executing AltiVec instructions.

vsx_hw
   PowerPC target supports executing VSX instructions (ISA 2.06).

has_arch_pwr5
   PowerPC target pre-defines macro _ARCH_PWR5 which means the -mcpu setting
   is Power5 or later.

has_arch_pwr6
   PowerPC target pre-defines macro _ARCH_PWR6 which means the -mcpu setting
   is Power6 or later.

has_arch_pwr7
   PowerPC target pre-defines macro _ARCH_PWR7 which means the -mcpu setting
   is Power7 or later.

has_arch_pwr8
   PowerPC target pre-defines macro _ARCH_PWR8 which means the -mcpu setting
   is Power8 or later.

has_arch_pwr9
   PowerPC target pre-defines macro _ARCH_PWR9 which means the -mcpu setting
   is Power9 or later.

7.2.3.12 Other hardware attributes

autoincdec
   Target supports autoincrement/decrement addressing.

avx
   Target supports compiling avx instructions.

avx_runtime
   Target supports the execution of avx instructions.

avx2
   Target supports compiling avx2 instructions.
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avx2_runtime
    Target supports the execution of avx2 instructions.

avxvnni
    Target supports the execution of avxvnni instructions.

avx512f
    Target supports compiling avx512f instructions.

avx512f_runtime
    Target supports the execution of avx512f instructions.

avx512vp2intersect
    Target supports the execution of avx512vp2intersect instructions.

amx_tile
    Target supports the execution of amx-tile instructions.

amx_int8
    Target supports the execution of amx-int8 instructions.

amx_bf16
    Target supports the execution of amx-bf16 instructions.

cell_hw
    Test system can execute AltiVec and Cell PPU instructions.

coldfire_fpu
    Target uses a ColdFire FPU.

divmod
    Target supporting hardware divmod insn or divmod libcall.

divmod_simode
    Target supporting hardware divmod insn or divmod libcall for SImode.

hard_float
    Target supports FPU instructions.

non_strict_align
    Target does not require strict alignment.

pie_copyreloc
    The x86-64 target linker supports PIE with copy reloc.

rdrand
    Target supports x86 rdrand instruction.

sqrt_insn
    Target has a square root instruction that the compiler can generate.

sse
    Target supports compiling sse instructions.

sse_runtime
    Target supports the execution of sse instructions.

sse2
    Target supports compiling sse2 instructions.

sse2_runtime
    Target supports the execution of sse2 instructions.

sync_char_short
    Target supports atomic operations on char and short.

sync_int_long
    Target supports atomic operations on int and long.
ultrasparc_hw
Test environment appears to run executables on a simulator that accepts only
EM_SPARC executables and chokes on EM_SPARC32PLUS or EM_SPARCV9 executa-
bles.

vect_cmdline_needed
Target requires a command line argument to enable a SIMD instruction set.

xorsign
Target supports the xorsign optab expansion.

7.2.3.13 Environment attributes

c
The language for the compiler under test is C.

c++
The language for the compiler under test is C++.

c99_runtime
Target provides a full C99 runtime.

correct_iso_cpp_string_wchar_protos
Target string.h and wchar.h headers provide C++ required overloads for
strchr etc. functions.

d_runtime
Target provides the D runtime.

d_runtime_has_std_library
Target provides the D standard library (Phobos).

dummy_wcsftime
Target uses a dummy wcsftime function that always returns zero.

fd_truncate
Target can truncate a file from a file descriptor, as used by
‘libgfortran/io/unix.c:fd_truncate’; i.e. ftruncate or chsize.

fenv
Target provides ‘fenv.h’ include file.

fenv_exceptions
Target supports ‘fenv.h’ with all the standard IEEE exceptions and floating-
point exceptions are raised by arithmetic operations.

fenv_exceptions_dfp
Target supports ‘fenv.h’ with all the standard IEEE exceptions and floating-
point exceptions are raised by arithmetic operations for decimal floating point.

fileio
Target offers such file I/O library functions as fopen, fclose, tmpnam, and
remove. This is a link-time requirement for the presence of the functions in
the library; even if they fail at runtime, the requirement is still regarded as
satisfied.

freestanding
Target is ‘freestanding’ as defined in section 4 of the C99 standard. Effectively,
it is a target which supports no extra headers or libraries other than
what is considered essential.
gettimeofday
   Target supports gettimeofday.

init_priority
   Target supports constructors with initialization priority arguments.

inttypes_types
   Target has the basic signed and unsigned types in inttypes.h. This is for
   tests that GCC’s notions of these types agree with those in the header, as some
   systems have only inttypes.h.

lax_strtofp
   Target might have errors of a few ULP in string to floating-point conversion
   functions and overflow is not always detected correctly by those functions.

mempcpy
   Target provides mempcpy function.

mmap
   Target supports mmap.

ewlib
   Target supports Newlib.

ewlib_nano_io
   GCC was configured with --enable-newlib-nano-formatted-io, which re-
   duces the code size of Newlib formatted I/O functions.

ewlib
   Target supports Newlib.

pow10
   Target provides pow10 function.

pthread
   Target can compile using pthread.h with no errors or warnings.

pthread_h
   Target has pthread.h.

run_expensive_tests
   Expensive testcases (usually those that consume excessive amounts of CPU
   time) should be run on this target. This can be enabled by setting the GCC_-
   TEST_RUN_EXPENSIVE environment variable to a non-empty string.

simulator
   Test system runs executables on a simulator (i.e. slowly) rather than hardware
   (i.e. fast).

signal
   Target has signal.h.

stabs
   Target supports the stabs debugging format.

stdint_types
   Target has the basic signed and unsigned C types in stdint.h. This will be
   obsolete when GCC ensures a working stdint.h for all targets.

stdint_types_mbig_endian
   Target accepts the option ‘-mbig_endian’ and stdint.h can be included with-
   out error when ‘-mbig_endian’ is passed.

stpcpy
   Target provides stpcpy function.

sysconf
   Target supports sysconf.
trampolines
    Target supports trampolines.

uclibc
    Target supports uClibc.

unwrapped
    Target does not use a status wrapper.

vxworks_kernel
    Target is a VxWorks kernel.

vxworks_rtp
    Target is a VxWorks RTP.

wchar
    Target supports wide characters.

7.2.3.14 Other attributes

R_flag_in_section
    Target supports the 'R' flag in .section directive in assembly inputs.

automatic_stack_alignment
    Target supports automatic stack alignment.

branch_cost
    Target supports `-branch-cost=N`.

cxa_atexit
    Target uses __cxa_atexit.

default_packed
    Target has packed layout of structure members by default.

exceptions
    Target supports exceptions.

exceptions_enabled
    Target supports exceptions and they are enabled in the current testing configuration.

fgraphite
    Target supports Graphite optimizations.

fixed_point
    Target supports fixed-point extension to C.

fopenacc
    Target supports OpenACC via `-fopenacc`.

fopenmp
    Target supports OpenMP via `-fopenmp`.

fpic
    Target supports `-fpic` and `-fPIC`.

freorder
    Target supports `-freorder-blocks-and-partition`.

fstack_protector
    Target supports `-fstack-protector`.

gas
    Target uses GNU as.
gc_sections
   Target supports '--gc-sections'.

gld
   Target uses GNU ld.

keeps_null_pointer_checks
   Target keeps null pointer checks, either due to the use of
   '-fno-delete-null-pointer-checks' or hardwired into the target.

llvm_binutils
   Target is using an LLVM assembler and/or linker, instead of GNU Binutils.
lra
   Target supports local register allocator (LRA).
lto
   Compiler has been configured to support link-time optimization (LTO).
lto_incremental
   Compiler and linker support link-time optimization relocatable linking with 'r'
   and '-flto' options.
naked_functions
   Target supports the naked function attribute.
named_sections
   Target supports named sections.
natural_alignment_32
   Target uses natural alignment (aligned to type size) for types of 32 bits or less.
target_natural_alignment_64
   Target uses natural alignment (aligned to type size) for types of 64 bits or less.
noinit
   Target supports the noinit variable attribute.
nonpic
   Target does not generate PIC by default.
o_flag_in_section
   Target supports the 'o' flag in .section directive in assembly inputs.
offload_gcn
   Target has been configured for OpenACC/OpenMP offloading on AMD GCN.
persistent
   Target supports the persistent variable attribute.
pie_enabled
   Target generates PIE by default.
pcc_bitfield_type_matters
   Target defines PCC_BITFIELD_TYPE_MATTERS.
pe_aligned_commons
   Target supports '-mpe-aligned-commons'.
pie
   Target supports '-pie', '-fpie' and '-fPIE'.
rdynamic
   Target supports '-rdynamic'.
**scalar_all_fma**
Target supports all four fused multiply-add optabs for both float and double. These optabs are: fma_optab, fms_optab, fnma_optab and fnms_optab.

**section_anchors**
Target supports section anchors.

**short Enums**
Target defaults to short enums.

**stack_size**
Target has limited stack size. The stack size limit can be obtained using the STACK_SIZE macro defined by [dg-add-options feature stack size], page 109.

**static**
Target supports ‘-static’.

**static_libgfortran**
Target supports statically linking ‘libgfortran’.

**string_merging**
Target supports merging string constants at link time.

**ucn**
Target supports compiling and assembling UCN.

**ucn_nocache**
Including the options used to compile this particular test, the target supports compiling and assembling UCN.

**unaligned_stack**
Target does not guarantee that its STACK_BOUNDARY is greater than or equal to the required vector alignment.

**vector_alignment_reachable**
Vector alignment is reachable for types of 32 bits or less.

**vector_alignment_reachable_for_64bit**
Vector alignment is reachable for types of 64 bits or less.

**wchar_t_char16_t_compatible**
Target supports wchar_t that is compatible with char16_t.

**wchar_t_char32_t_compatible**
Target supports wchar_t that is compatible with char32_t.

**comdat_group**
Target uses comdat groups.

**indirect_calls**
Target supports indirect calls, i.e. calls where the target is not constant.

**lgccjit**
Target supports -lgccjit, i.e. libgccjit.so can be linked into jit tests.

**__OPTIMIZE__**
Optimizations are enabled (__OPTIMIZE__) per the current compiler flags.
7.2.3.15 Local to tests in gcc.target/i386

3dnow  Target supports compiling 3dnow instructions.
aes    Target supports compiling aes instructions.
fma4   Target supports compiling fma4 instructions.
mfentry Target supports the -mfentry option that alters the position of profiling calls such that they precede the prologue.
ms_hook_prologue Target supports attribute ms_hook_prologue.
pclmul Target supports compiling pclmul instructions.
sse3   Target supports compiling sse3 instructions.
sse4   Target supports compiling sse4 instructions.
sse4a  Target supports compiling sse4a instructions.
ssse3  Target supports compiling ssse3 instructions.
vaes   Target supports compiling vaes instructions.
vpclmul Target supports compiling vpclmul instructions.
xop    Target supports compiling xop instructions.

7.2.3.16 Local to tests in gcc.test-framework

no Always returns 0.
yes Always returns 1.

7.2.4 Features for dg-add-options

The supported values of feature for directive dg-add-options are:

arm_fp __ARM_FP definition. Only ARM targets support this feature, and only then in certain modes; see the [arm_fp_ok effective target keyword], page 93.

arm_fp_dp __ARM_FP definition with double-precision support. Only ARM targets support this feature, and only then in certain modes; see the [arm_fp_dp_ok effective target keyword], page 93.

arm_neon NEON support. Only ARM targets support this feature, and only then in certain modes; see the [arm_neon_ok effective target keyword], page 93.

arm_fp16 VFP half-precision floating point support. This does not select the FP16 format; for that, use [arm_fp16_ieee], page 107 or [arm_fp16_alternative], page 108 instead. This feature is only supported by ARM targets and then only in certain modes; see the [arm_fp16_ok effective target keyword], page 94.

arm_fp16_ieee ARM IEEE 754-2008 format VFP half-precision floating point support. This feature is only supported by ARM targets and then only in certain modes; see the [arm_fp16_ok effective target keyword], page 94.
arm_fp16_alternative

ARM Alternative format VFP half-precision floating point support. This feature is only supported by ARM targets and then only in certain modes; see the [arm_fp16_ok effective target keyword], page 94.

arm_neon_fp16

NEON and half-precision floating point support. Only ARM targets support this feature, and only then in certain modes; see the [arm_neon_fp16_ok effective target keyword], page 94.

arm_vfp3

arm vfp3 floating point support; see the [arm_vfp3_ok effective target keyword], page 94.

arm_arch_v8a_hard

Add options for ARMv8-A and the hard-float variant of the AAPCS, if this is supported by the compiler; see the [arm_arch_v8a_hard_ok], page 94 effective target keyword.

arm_v8_1a_neon

Add options for ARMv8.1-A with Adv.SIMD support, if this is supported by the target; see the [arm_v8_1a_neon_ok], page 95 effective target keyword.

arm_v8_2a_fp16_scalar

Add options for ARMv8.2-A with scalar FP16 support, if this is supported by the target; see the [arm_v8_2a_fp16_scalar_ok], page 95 effective target keyword.

arm_v8_2a_fp16_neon

Add options for ARMv8.2-A with Adv.SIMD FP16 support, if this is supported by the target; see the [arm_v8_2a_fp16_neon_ok], page 95 effective target keyword.

arm_v8_2a_dotprod_neon

Add options for ARMv8.2-A with Adv.SIMD Dot Product support, if this is supported by the target; see the [arm_v8_2a_dotprod_neon_ok], page 95 effective target keyword.

arm_fp16fml_neon

Add options to enable generation of the VFMAL and VFMSL instructions, if this is supported by the target; see the [arm_fp16fml_neon_ok], page 96 effective target keyword.

arm_dsp

Add options for ARM DSP intrinsics support, if this is supported by the target; see the [arm_dsp_ok effective target keyword], page 97.

bind_pic_locally

Add the target-specific flags needed to enable functions to bind locally when using pic/PIC passes in the testsuite.

floatn

Add the target-specific flags needed to use the _Floatn type.

floatnx

Add the target-specific flags needed to use the _Floatnx type.

ieee

Add the target-specific flags needed to enable full IEEE compliance mode.
mips16_attribute

mips16 function attributes. Only MIPS targets support this feature, and only then in certain modes.

stack_size

Add the flags needed to define macro STACK_SIZE and set it to the stack size limit associated with the [stack_size effective target], page 106.

sqrt_insn

Add the target-specific flags needed to enable hardware square root instructions, if any.

tls

Add the target-specific flags needed to use thread-local storage.

7.2.5 Variants of dg-require-support

A few of the dg-require directives take arguments.

dg-require-iconv codeset

Skip the test if the target does not support iconv. codeset is the codeset to convert to.

dg-require-profiling profopt

Skip the test if the target does not support profiling with option profopt.

dg-require-stack-check check

Skip the test if the target does not support the -fstack-check option. If check is "", support for -fstack-check is checked, for -fstack-check="check" otherwise.

dg-require-stack-size size

Skip the test if the target does not support a stack size of size.

dg-require-visibility vis

Skip the test if the target does not support the visibility attribute. If vis is "", support for visibility("hidden") is checked, for visibility("vis") otherwise.

The original dg-require directives were defined before there was support for effective-target keywords. The directives that do not take arguments could be replaced with effective-target keywords.

dg-require-alias ""

Skip the test if the target does not support the ‘alias’ attribute.

dg-require-ascii-locale ""

Skip the test if the host does not support an ASCII locale.

dg-require-compat-dfp ""

Skip this test unless both compilers in a ‘compat’ testsuite support decimal floating point.

dg-require-cxa-atexit ""

Skip the test if the target does not support __cxa_atexit. This is equivalent to dg-require-effective-target cxa_atexit.
dg-require-dll ""
Skip the test if the target does not support DLL attributes.

dg-require-dot ""
Skip the test if the host does not have dot.

dg-require-fork ""
Skip the test if the target does not support fork.

dg-require-gc-sections ""
Skip the test if the target’s linker does not support the --gc-sections flags.
This is equivalent to dg-require-effective-target gc-sections.

dg-require-host-local ""
Skip the test if the host is remote, rather than the same as the build system. Some tests are incompatible with DejaGnu’s handling of remote hosts, which involves copying the source file to the host and compiling it with a relative path and "-o a.out".

dg-require-mkfifo ""
Skip the test if the target does not support mkfifo.

dg-require-named-sections ""
Skip the test if the target does not support named sections. This is equivalent to dg-require-effective-target named_sections.

dg-require-weak ""
Skip the test if the target does not support weak symbols.

dg-require-weak-override ""
Skip the test if the target does not support overriding weak symbols.

7.2.6 Commands for use in dg-final
The GCC testsuite defines the following directives to be used within dg-final.

7.2.6.1 Scan a particular file

scan-file filename regexp [{ target/xfail selector }]
Passes if regexp matches text in filename.

scan-file-not filename regexp [{ target/xfail selector }]
Passes if regexp does not match text in filename.

scan-module module regexp [{ target/xfail selector }]
Passes if regexp matches in Fortran module module.

dg-check-dot filename
Passes if filename is a valid `.dot` file (by running dot -Tpng on it, and verifying the exit code is 0).

7.2.6.2 Scan the assembly output

scan-assembler regex [{ target/xfail selector }]
Passes if regex matches text in the test’s assembler output.
scan-assembler-not regex [{ target/xfail selector }]
  Passes if regex does not match text in the test’s assembler output.

scan-assembler-times regex num [{ target/xfail selector }]
  Passes if regex is matched exactly num times in the test’s assembler output.

scan-assembler-dem regex [{ target/xfail selector }]
  Passes if regex matches text in the test’s demangled assembler output.

scan-assembler-dem-not regex [{ target/xfail selector }]
  Passes if regex does not match text in the test’s demangled assembler output.

scan-assembler-symbol-section functions section [{ target/xfail selector }]
  Passes if functions are all in section. The caller needs to allow for USER_LABEL_PREFIX and different section name conventions.

scan-symbol-section filename functions section [{ target/xfail selector }]
  Passes if functions are all in section in filename. The same caveats as for scan-assembler-symbol-section apply.

scan-hidden symbol [{ target/xfail selector }]
  Passes if symbol is defined as a hidden symbol in the test’s assembly output.

scan-not-hidden symbol [{ target/xfail selector }]
  Passes if symbol is not defined as a hidden symbol in the test’s assembly output.

check-function-bodies prefix terminator [options [{ target/xfail selector }]]
  Looks through the source file for comments that give the expected assembly output for selected functions. Each line of expected output starts with the prefix string prefix and the expected output for a function as a whole is followed by a line that starts with the string terminator. Specifying an empty terminator is equivalent to specifying ‘"*/"’.

  options, if specified, is a list of regular expressions, each of which matches a full command-line option. A non-empty list prevents the test from running unless all of the given options are present on the command line. This can help if a source file is compiled both with and without optimization, since it is rarely useful to check the full function body for unoptimized code.

  The first line of the expected output for a function fn has the form:

  prefix fn: [{ target/xfail selector }]

  Subsequent lines of the expected output also start with prefix. In both cases, whitespace after prefix is not significant.

  The test discards assembly directives such as .cfi_startproc and local label definitions such as .LFB0 from the compiler’s assembly output. It then matches the result against the expected output for a function as a single regular expression. This means that later lines can use backslashes to refer back to ‘(...)’ captures on earlier lines. For example:

  /* { dg-final { check-function-bodies "**" ""-DCHECK_ASM" } } */
  ...*/
  /*
  ** add_w0_s8_m:
  ** mov (z[0-9]+\.b), w0
checks whether the implementations of `add_w0_s8_m` and `add_b0_s8_m` match the regular expressions given. The test only runs when `'-DCHECK_ASM'` is passed on the command line.

It is possible to create non-capturing multi-line regular expression groups of the form `(a|b|...)` by putting the `(, ']' and `)` on separate lines (each still using `prefix`). For example:

```c
筼 *
筼 add_b0_s8_m:
筼 mov (z[0-9]+.b), b0
筼 add z1\b, p0/m, z1\b, \1
筼 ret
筼 *
筼 svint8_t add_b0_s8_m (...) { ... }

筼 checks whether `cmple_f16_tied` is implemented by the `fcmge` instruction followed by `ret` or by the `fcmlle` instruction followed by `ret`. The test is still a single regular expression.

A line containing just:

`prefix ...

stands for zero or more unmatched lines; the whitespace after `prefix` is again not significant.

### 7.2.6.3 Scan optimization dump files

These commands are available for `kind` of `tree, ltrans-tree, offload-tree, rtl, offload-rtl, ipa, and wpa-ipa`.

**scan-kind-dump regex suffix {{ target/xfail selector }}**

Passes if `regex` matches text in the dump file with suffix `suffix`.

**scan-kind-dump-not regex suffix {{ target/xfail selector }}**

Passes if `regex` does not match text in the dump file with suffix `suffix`.

**scan-kind-dump-times regex num suffix {{ target/xfail selector }}**

Passes if `regex` is found exactly `num` times in the dump file with suffix `suffix`.

**scan-kind-dump-dem regex suffix {{ target/xfail selector }}**

Passes if `regex` matches demangled text in the dump file with suffix `suffix`.
scan-kind-dump-dem-not regex suffix [{ target/xfail selector }]
Passes if regex does not match demangled text in the dump file with suffix suffix.

The suffix argument which describes the dump file to be scanned may contain a glob pattern that must expand to exactly one file name. This is useful if, e.g., different pass instances are executed depending on torture testing command-line flags, producing dump files whose names differ only in their pass instance number suffix. For example, to scan instances 1, 2, 3 of a tree pass “mypass” for occurrences of the string “code has been optimized”, use:

```c
/* { dg-options "-fdump-tree-mypass" } */
/* { dg-final { scan-tree-dump "code has been optimized" "mypass\[1-3\]" } } */
```

7.2.6.4 Check for output files

output-exists [{ target/xfail selector }]
Passes if compiler output file exists.

output-exists-not [{ target/xfail selector }]
Passes if compiler output file does not exist.

scan-symbol regexp [{ target/xfail selector }]
Passes if the pattern is present in the final executable.

scan-symbol-not regexp [{ target/xfail selector }]
Passes if the pattern is absent from the final executable.

7.2.6.5 Checks for gcov tests

run-gcov sourcefile
Check line counts in gcov tests.

run-gcov [branches] [calls] { opts sourcefile }
Check branch and/or call counts, in addition to line counts, in gcov tests.

run-gcov-pytest { sourcefile pytest_file }
Check output of gcov intermediate format with a pytest script.

7.2.6.6 Clean up generated test files

Usually the test-framework removes files that were generated during testing. If a testcase, for example, uses any dumping mechanism to inspect a passes dump file, the testsuite recognized the dump option passed to the tool and schedules a final cleanup to remove these files.

There are, however, following additional cleanup directives that can be used to annotate a testcase "manually".

cleanup-coverage-files
Removes coverage data files generated for this test.

cleanup-modules "list-of-extra-modules"
Removes Fortran module files generated for this test, excluding the module names listed in keep-modules. Cleaning up module files is usually done automatically by the testsuite by looking at the source files and removing the modules after the test has been executed.
module MoD1
dend module MoD1
module Mod2
dend module Mod2
module mod3
dend module mod3
module mod4
dend module mod4

! { dg-final { cleanup-modules "mod1 mod2" } } ! redundant
! { dg-final { keep-modules "mod3 mod4" } }

keep-modules "list-of-modules-not-to-delete"
Whitespace separated list of module names that should not be deleted by
cleanup-modules. If the list of modules is empty, all modules defined in this file
are kept.

module maybe_unneeded
dend module maybe_unneeded
module keep1
dend module keep1
module keep2
dend module keep2

! { dg-final { keep-modules "keep1 keep2" } } ! just keep these two
! { dg-final { keep-modules "" } } ! keep all

dg-keep-saved-temps "list-of-suffixes-not-to-delete"
Whitespace separated list of suffixes that should not be deleted automatically
in a testcase that uses '--save-temps'.

// { dg-options "--save-temps -fpch-preprocess -I." }
int main() { return 0; }

// { dg-keep-saved-temps ".s" } ! just keep assembler file
// { dg-keep-saved-temps ".s" ".i" } ! ... and .i
// { dg-keep-saved-temps ".ii" ".o" } ! or just .ii and .o

cleanup-profile-file
Removes profiling files generated for this test.

7.3 Ada Language Testsuites

The Ada testsuite includes executable tests from the ACATS testsuite, publicly available

These tests are integrated in the GCC testsuite in the 'ada/acats' directory, and enabled
automatically when running make check, assuming the Ada language has been enabled when
configuring GCC.

You can also run the Ada testsuite independently, using make check-ada, or run a subset
of the tests by specifying which chapter to run, e.g.:

$ make check-ada CHAPTERS="c3 c9"

The tests are organized by directory, each directory corresponding to a chapter of the
Ada Reference Manual. So for example, 'c9' corresponds to chapter 9, which deals with
tasking features of the language.

The tests are run using two sh scripts: 'run_acats' and 'run_all.sh'. To run the
tests using a simulator or a cross target, see the small customization section at the top of
'run_all.sh'.

These tests are run using the build tree: they can be run without doing a make install.
7.4 C Language Testsuites

GCC contains the following C language testsuites, in the ‘gcc/testsuite’ directory:

‘gcc.dg’ This contains tests of particular features of the C compiler, using the more modern ‘dg’ harness. Correctness tests for various compiler features should go here if possible.

Magic comments determine whether the file is preprocessed, compiled, linked or run. In these tests, error and warning message texts are compared against expected texts or regular expressions given in comments. These tests are run with the options ‘-ansi -pedantic’ unless other options are given in the test. Except as noted below they are not run with multiple optimization options.

‘gcc.dg/compat’

This subdirectory contains tests for binary compatibility using ‘lib/compat.exp’, which in turn uses the language-independent support (see Section 7.8 [Support for testing binary compatibility], page 118).

‘gcc.dg/cpp’

This subdirectory contains tests of the preprocessor.

‘gcc.dg/debug’

This subdirectory contains tests for debug formats. Tests in this subdirectory are run for each debug format that the compiler supports.

‘gcc.dg/format’

This subdirectory contains tests of the ‘-Wformat’ format checking. Tests in this directory are run with and without ‘-DWIDE’.

‘gcc.dg/noncompile’

This subdirectory contains tests of code that should not compile and does not need any special compilation options. They are run with multiple optimization options, since sometimes invalid code crashes the compiler with optimization.

‘gcc.dg/special’

FIXME: describe this.

‘gcc.c-torture’

This contains particular code fragments which have historically broken easily. These tests are run with multiple optimization options, so tests for features which only break at some optimization levels belong here. This also contains tests to check that certain optimizations occur. It might be worthwhile to separate the correctness tests cleanly from the code quality tests, but it hasn’t been done yet.

‘gcc.c-torture/compat’

FIXME: describe this.

This directory should probably not be used for new tests.

‘gcc.c-torture/compile’

This testsuite contains test cases that should compile, but do not need to link or run. These test cases are compiled with several different combinations of optimization options. All warnings are disabled for these test cases, so this
directory is not suitable if you wish to test for the presence or absence of compiler warnings. While special options can be set, and tests disabled on specific platforms, by the use of ‘.x’ files, mostly these test cases should not contain platform dependencies. FIXME: discuss how defines such as STACK_SIZE are used.

'gcc.c-torture/execute'
This testsuite contains test cases that should compile, link and run; otherwise the same comments as for 'gcc.c-torture/compile' apply.

'gcc.c-torture/execute/ieee'
This contains tests which are specific to IEEE floating point.

'gcc.c-torture/unsorted'
FIXME: describe this.
This directory should probably not be used for new tests.

'gcc.misc-tests'
This directory contains C tests that require special handling. Some of these tests have individual expect files, and others share special-purpose expect files:

'bprob*.c'
Test '-fbranch-probabilities' using 'gcc.misc-tests/bprob.exp', which in turn uses the generic, language-independent framework (see Section 7.7 [Support for testing profile-directed optimizations], page 118).

'gcov*.c'
Test gcov output using 'gcov.exp', which in turn uses the language-independent support (see Section 7.6 [Support for testing gcov], page 117).

'i386-pf-*.c'
Test i386-specific support for data prefetch using 'i386-prefetch.exp'.

'gcc.test-framework'
'dg-*.*'
Test the testsuite itself using 'gcc.test-framework/test-framework.exp'.

FIXME: merge in ‘testsuite/README.gcc’ and discuss the format of test cases and magic comments more.

### 7.5 Support for testing link-time optimizations

Tests for link-time optimizations usually require multiple source files that are compiled separately, perhaps with different sets of options. There are several special-purpose test directives used for these tests.

{ dg-lto-do do-what-keyword }

*do-what-keyword* specifies how the test is compiled and whether it is executed. It is one of:

assemble Compile with ‘-c’ to produce a relocatable object file.
link Compile, assemble, and link to produce an executable file.
run Produce and run an executable file, which is expected to return an exit code of 0.

The default is assemble. That can be overridden for a set of tests by redefining dg-do-what-default within the .exp file for those tests.

Unlike dg-do, dg-lto-do does not support an optional ‘target’ or ‘xfail’ list. Use dg-skip-if, dg-xfail-if, or dg-xfail-run-if.

{ dg-lto-options { { options } [{ options } ] } [{ target selector }]} 

This directive provides a list of one or more sets of compiler options to override LTO_OPTIONS. Each test will be compiled and run with each of these sets of options.

{ dg-extra-ld-options options [{ target selector }] } 

This directive adds options to the linker options used.

{ dg-suppress-ld-options options [{ target selector }] } 

This directive removes options from the set of linker options used.

7.6 Support for testing gcov

Language-independent support for testing gcov, and for checking that branch profiling produces expected values, is provided by the expect file ‘lib/gcov.exp’. gcov tests also rely on procedures in ‘lib/gcc-dg.exp’ to compile and run the test program. A typical gcov test contains the following DejaGnu commands within comments:

{ dg-options "--coverage" } 
{ dg-do run { target native } } 
{ dg-final { run-gcov sourcefile } } 

Checks of gcov output can include line counts, branch percentages, and call return percentages. All of these checks are requested via commands that appear in comments in the test’s source file. Commands to check line counts are processed by default. Commands to check branch percentages and call return percentages are processed if the run-gcov command has arguments branches or calls, respectively. For example, the following specifies checking both, as well as passing ‘-b’ to gcov:

{ dg-final { run-gcov branches calls { -b sourcefile } } } 

A line count command appears within a comment on the source line that is expected to get the specified count and has the form count(cnt). A test should only check line counts for lines that will get the same count for any architecture.

Commands to check branch percentages (branch) and call return percentages (returns) are very similar to each other. A beginning command appears on or before the first of a range of lines that will report the percentage, and the ending command follows that range of lines. The beginning command can include a list of percentages, all of which are expected to be found within the range. A range is terminated by the next command of the same kind. A command branch(end) or returns(end) marks the end of a range without starting a new one. For example:

```c
if (i > 10 && j > i && j < 20) /* branch(27 50 75) */ 
/* branch(27 50 75) */
    /* branch(end) */
    foo (i, j);
```
For a call return percentage, the value specified is the percentage of calls reported to return. For a branch percentage, the value is either the expected percentage or 100 minus that value, since the direction of a branch can differ depending on the target or the optimization level.

Not all branches and calls need to be checked. A test should not check for branches that might be optimized away or replaced with predicated instructions. Don’t check for calls inserted by the compiler or ones that might be inlined or optimized away.

A single test can check for combinations of line counts, branch percentages, and call return percentages. The command to check a line count must appear on the line that will report that count, but commands to check branch percentages and call return percentages can bracket the lines that report them.

7.7 Support for testing profile-directed optimizations

The file `profopt.exp` provides language-independent support for checking correct execution of a test built with profile-directed optimization. This testing requires that a test program be built and executed twice. The first time it is compiled to generate profile data, and the second time it is compiled to use the data that was generated during the first execution. The second execution is to verify that the test produces the expected results.

To check that the optimization actually generated better code, a test can be built and run a third time with normal optimizations to verify that the performance is better with the profile-directed optimizations. `profopt.exp` has the beginnings of this kind of support.

`profopt.exp` provides generic support for profile-directed optimizations. Each set of tests that uses it provides information about a specific optimization:

- `tool`: tool being tested, e.g., gcc
- `profile_option`: options used to generate profile data
- `feedback_option`: options used to optimize using that profile data
- `prof_ext`: suffix of profile data files
- `PROFOPT_OPTIONS`: list of options with which to run each test, similar to the lists for torture tests

```
{ dg-final-generate { local-directive } }
This directive is similar to dg-final, but the local-directive is run after the generation of profile data.

{ dg-final-use { local-directive } }
The local-directive is run after the profile data have been used.
```

7.8 Support for testing binary compatibility

The file `compat.exp` provides language-independent support for binary compatibility testing. It supports testing interoperability of two compilers that follow the same ABI, or of multiple sets of compiler options that should not affect binary compatibility. It is intended to be used for testsuites that complement ABI testsuites.
A test supported by this framework has three parts, each in a separate source file: a main program and two pieces that interact with each other to split up the functionality being tested.

\['testname\_main.suffix'\]
   Contains the main program, which calls a function in file \['testname\_x.suffix'\].

\['testname\_x.suffix'\]
   Contains at least one call to a function in \['testname\_y.suffix'\].

\['testname\_y.suffix'\]
   Shares data with, or gets arguments from, \['testname\_x.suffix'\].

Within each test, the main program and one functional piece are compiled by the GCC under test. The other piece can be compiled by an alternate compiler. If no alternate compiler is specified, then all three source files are all compiled by the GCC under test. You can specify pairs of sets of compiler options. The first element of such a pair specifies options used with the GCC under test, and the second element of the pair specifies options used with the alternate compiler. Each test is compiled with each pair of options.

\['compat.exp'\] defines default pairs of compiler options. These can be overridden by defining the environment variable \(\text{COMPAT\_OPTIONS}\) as:

\[
\text{COMPAT\_OPTIONS}="[\text{list} \{\text{tsti}\} \{\text{alti}\}] \ldots[\text{list} \{\text{tstn}\} \{\text{altn}\}]"
\]

where \(\text{tsti}\) and \(\text{alti}\) are lists of options, with \(\text{tsti}\) used by the compiler under test and \(\text{alti}\) used by the alternate compiler. For example, with \([\text{list} \{\text{-g -00}\} \{\text{-03}\}] [\text{list} \{\text{-fpic}\} \{\text{-fPIC -02}\}]\), the test is first built with \('-g -00'\) by the compiler under test and with \('-03'\) by the alternate compiler. The test is built a second time using \('-fpic'\) by the compiler under test and \('-fPIC -02'\) by the alternate compiler.

An alternate compiler is specified by defining an environment variable to be the full pathname of an installed compiler; for C define \(\text{ALT\_CC\_UNDER\_TEST}\), and for C++ define \(\text{ALT\_CXX\_UNDER\_TEST}\). These will be written to the \('site.exp'\) file used by DejaGnu. The default is to build each test with the compiler under test using the first of each pair of compiler options from \(\text{COMPAT\_OPTIONS}\). When \(\text{ALT\_CC\_UNDER\_TEST}\) or \(\text{ALT\_CXX\_UNDER\_TEST}\) is same, each test is built using the compiler under test but with combinations of the options from \(\text{COMPAT\_OPTIONS}\).

To run only the C++ compatibility suite using the compiler under test and another version of GCC using specific compiler options, do the following from \(\text{objdir/gcc}\):

\[
\text{rm site.exp} \\
\text{make -k} \\
\text{ALT\_CXX\_UNDER\_TEST}=${alt_prefix}/bin/g++ \\
\text{COMPAT\_OPTIONS}=\"lists as shown above\" \\
\text{check-c++} \\
\text{RUNTESTFLAGS}="compat.exp"
\]

A test that fails when the source files are compiled with different compilers, but passes when the files are compiled with the same compiler, demonstrates incompatibility of the generated code or runtime support. A test that fails for the alternate compiler but passes for the compiler under test probably tests for a bug that was fixed in the compiler under test but is present in the alternate compiler.

The binary compatibility tests support a small number of test framework commands that appear within comments in a test file.
dg-require-∗
These commands can be used in ‘testname_main.suffix’ to skip the test if
specific support is not available on the target.

dg-options
The specified options are used for compiling this particular source file, ap-
pended to the options from COMPAT_OPTIONS. When this command appears in
‘testname_main.suffix’ the options are also used to link the test program.

dg-xfail-if
This command can be used in a secondary source file to specify that compilation
is expected to fail for particular options on particular targets.

7.9 Support for torture testing using multiple options
Throughout the compiler testsuite there are several directories whose tests are run
multiple times, each with a different set of options. These are known as torture tests.
‘lib/torture-options.exp’ defines procedures to set up these lists:

torture-init
Initialize use of torture lists.

set-torture-options
Set lists of torture options to use for tests with and without loops. Optionally
combine a set of torture options with a set of other options, as is done with
Objective-C runtime options.

torture-finish
Finalize use of torture lists.

The ‘.exp’ file for a set of tests that use torture options must include calls to these three
procedures if:
• It calls gcc-dg-runtest and overrides DG_TORTURE_OPTIONS.
• It calls $tool-torture or $tool-torture-execute, where tool is c, fortran, or
objc.
• It calls dg-pch.

It is not necessary for a ‘.exp’ file that calls gcc-dg-runtest to call the torture procedures
if the tests should use the list in DG_TORTURE_OPTIONS defined in ‘gcc-dg.exp’.

Most uses of torture options can override the default lists by defining TORTURE_OPTIONS or add to the default list by defining ADDI-
TIONAL_TORTURE_OPTIONS. Define these in a ‘.dejagnurc’ file or add
them to the ‘site.exp’ file; for example

    set ADDITIONAL_TORTURE_OPTIONS [list \n        { -O2 -ftree-loop-linear } \n        { -O2 -fpeel-loops } ]

7.10 Support for testing GIMPLE passes
As of gcc 7, C functions can be tagged with __GIMPLE to indicate that the function body
will be GIMPLE, rather than C. The compiler requires the option ‘-fgimple’ to enable this
functionality. For example:
void __GIMPLE (startwith ("dse2")) foo ()
{
  int a;

  bb_2:
  if (a > 4)
    goto bb_3;
  else
    goto bb_4;

  bb_3:
  a_2 = 10;
  goto bb_5;

  bb_4:
  a_3 = 20;

  bb_5:
  a_1 = __PHI (bb_3: a_2, bb_4: a_3);
  a_4 = a_1 + 4;
  return;
}

The startwith argument indicates at which pass to begin.

Use the dump modifier -gimple (e.g. '-fdump-tree-all-gimple') to make tree dumps more closely follow the format accepted by the GIMPLE parser.

Example DejaGnu tests of GIMPLE can be seen in the source tree at 'gcc/testsuite/gcc.dg/gimplefe-*.c'.

The __GIMPLE parser is integrated with the C tokenizer and preprocessor, so it should be possible to use macros to build out test coverage.

### 7.11 Support for testing RTL passes

As of gcc 7, C functions can be tagged with __RTL to indicate that the function body will be RTL, rather than C. For example:

```c
double __RTL (startwith ("ira")) test (struct foo *f, const struct bar *b)
{
  (function "test"
   [...]snip; various directives go in here...]
  ) ; ; function "test"
}
```

The startwith argument indicates at which pass to begin.

The parser expects the RTL body to be in the format emitted by this dumping function:

```c
DEBUG_FUNCTION void
print_rtx_function (FILE *outfile, function *fn, bool compact);
```

when "compact" is true. So you can capture RTL in the correct format from the debugger using:

```
(gdb) print_rtx_function (stderr, cfun, true);
```

and copy and paste the output into the body of the C function.
Example DejaGnu tests of RTL can be seen in the source tree under 'gcc/testsuite/gcc.dg/rtl'.

The __RTL parser is not integrated with the C tokenizer or preprocessor, and works simply by reading the relevant lines within the braces. In particular, the RTL body must be on separate lines from the enclosing braces, and the preprocessor is not usable within it.
8 Option specification files

Most GCC command-line options are described by special option definition files, the names of which conventionally end in `.opt`. This chapter describes the format of these files.

8.1 Option file format

Option files are a simple list of records in which each field occupies its own line and in which the records themselves are separated by blank lines. Comments may appear on their own line anywhere within the file and are preceded by semicolons. Whitespace is allowed before the semicolon.

The files can contain the following types of record:

- A language definition record. These records have two fields: the string `Language` and the name of the language. Once a language has been declared in this way, it can be used as an option property. See Section 8.2 [Option properties], page 125.

- A target specific save record to save additional information. These records have two fields: the string `TargetSave`, and a declaration type to go in the `cl_target_option` structure.

- A variable record to define a variable used to store option information. These records have two fields: the string `Variable`, and a declaration of the type and name of the variable, optionally with an initializer (but without any trailing ';'). These records may be used for variables used for many options where declaring the initializer in a single option definition record, or duplicating it in many records, would be inappropriate, or for variables set in option handlers rather than referenced by `Var` properties.

- A variable record to define a variable used to store option information. These records have two fields: the string `TargetVariable`, and a declaration of the type and name of the variable, optionally with an initializer (but without any trailing ';'). `TargetVariable` is a combination of `Variable` and `TargetSave` records in that the variable is defined in the `gcc_options` structure, but these variables are also stored in the `cl_target_option` structure. The variables are saved in the target save code and restored in the target restore code.

- A variable record to record any additional files that the `options.h` file should include. This is useful to provide enumeration or structure definitions needed for target variables. These records have two fields: the string `HeaderInclude` and the name of the include file.

- A variable record to record any additional files that the `options.c` or `options-save.c` file should include. This is useful to provide inline functions needed for target variables and/or `ifdef` sequences to properly set up the initialization. These records have two fields: the string `SourceInclude` and the name of the include file.

- An enumeration record to define a set of strings that may be used as arguments to an option or options. These records have three fields: the string `Enum`, a space-separated list of properties and help text used to describe the set of strings in `--help` output. Properties use the same format as option properties; the following are valid:
Name(name)
This property is required; name must be a name (suitable for use in C identifiers) used to identify the set of strings in Enum option properties.

Type(type)
This property is required; type is the C type for variables set by options using this enumeration together with Var.

UnknownError(message)
The message message will be used as an error message if the argument is invalid; for enumerations without UnknownError, a generic error message is used. message should contain a single ‘%qs’ format, which will be used to format the invalid argument.

- An enumeration value record to define one of the strings in a set given in an ‘Enum’ record. These records have two fields: the string ‘EnumValue’ and a space-separated list of properties. Properties use the same format as option properties; the following are valid:

  Enum(name)
  This property is required; name says which ‘Enum’ record this ‘EnumValue’ record corresponds to.

  String(string)
  This property is required; string is the string option argument being described by this record.

  Value(value)
  This property is required; it says what value (representable as int) should be used for the given string.

  Canonical
  This property is optional. If present, it says the present string is the canonical one among all those with the given value. Other strings yielding that value will be mapped to this one so specs do not need to handle them.

  DriverOnly
  This property is optional. If present, the present string will only be accepted by the driver. This is used for cases such as ‘-march=native’ that are processed by the driver so that ‘gcc -v’ shows how the options chosen depended on the system on which the compiler was run.

- An option definition record. These records have the following fields:
  1. the name of the option, with the leading “-” removed
  2. a space-separated list of option properties (see Section 8.2 [Option properties], page 125)
  3. the help text to use for ‘--help’ (omitted if the second field contains the Undocumented property).

By default, all options beginning with “f”, “W” or “m” are implicitly assumed to take a “no-” form. This form should not be listed separately. If an option beginning with one of these letters does not have a “no-” form, you can use the RejectNegative property to reject it.
The help text is automatically line-wrapped before being displayed. Normally the name
of the option is printed on the left-hand side of the output and the help text is printed
on the right. However, if the help text contains a tab character, the text to the left
of the tab is used instead of the option’s name and the text to the right of the tab forms
the help text. This allows you to elaborate on what type of argument the option takes.

- A target mask record. These records have one field of the form ‘Mask(x)’. The options-
  processing script will automatically allocate a bit in target_flags (see Section 18.3
  [Run-time Target], page 504) for each mask name x and set the macro MASK_x to the
  appropriate bitmask. It will also declare a TARGET_x macro that has the value 1 when
  bit MASK_x is set and 0 otherwise.

They are primarily intended to declare target masks that are not associated with user
options, either because these masks represent internal switches or because the options
are not available on all configurations and yet the masks always need to be defined.

8.2 Option properties

The second field of an option record can specify any of the following properties. When an
option takes an argument, it is enclosed in parentheses following the option property name.
The parser that handles option files is quite simplistic, and will be tricked by any nested
parentheses within the argument text itself; in this case, the entire option argument can be
wrapped in curly braces within the parentheses to demarcate it, e.g.:

Condition({defined (USE_CYGWIN_LIBSTDCCXX_WRAPPERS)})

Common The option is available for all languages and targets.

Target The option is available for all languages but is target-specific.

Driver The option is handled by the compiler driver using code not shared with the
  compilers proper (‘cc1’ etc.).

language The option is available when compiling for the given language.

It is possible to specify several different languages for the same option. Each lan-
  guage must have been declared by an earlier Language record. See Section 8.1
  [Option file format], page 123.

RejectDriver

The option is only handled by the compilers proper (‘cc1’ etc.) and should not
be accepted by the driver.

RejectNegative

The option does not have a “no-” form. All options beginning with “f”, “W”
or “m” are assumed to have a “no-” form unless this property is used.

Negative(othername)

The option will turn off another option othername, which is the option name
with the leading “-” removed. This chain action will propagate through the
Negative property of the option to be turned off. The driver will prune op-
tions, removing those that are turned off by some later option. This pruning is
not done for options with Joined or JoinedOrMissing properties, unless the
options have both the RejectNegative property and the Negative property
mentions itself.
As a consequence, if you have a group of mutually-exclusive options, their Negative properties should form a circular chain. For example, if options `--a`, `--b` and `--c` are mutually exclusive, their respective Negative properties should be `Negative(b)`, `Negative(c)` and `Negative(a)`.

**Joined**

The option takes a mandatory argument. Joined indicates that the option and argument can be included in the same argv entry (as with `-mflush-func=name`, for example). Separate indicates that the option and argument can be separate argv entries (as with `-o`). An option is allowed to have both of these properties.

**JoinedOrMissing**

The option takes an optional argument. If the argument is given, it will be part of the same argv entry as the option itself.

This property cannot be used alongside Joined or Separate.

**MissingArgError(message)**

For an option marked Joined or Separate, the message message will be used as an error message if the mandatory argument is missing; for options without MissingArgError, a generic error message is used. message should contain a single `%qs` format, which will be used to format the name of the option passed.

**Args(n)**

For an option marked Separate, indicate that it takes n arguments. The default is 1.

**UInteger**

The option’s argument is a non-negative integer consisting of either decimal or hexadecimal digits interpreted as int. Hexadecimal integers may optionally start with the 0x or 0X prefix. The option parser validates and converts the argument before passing it to the relevant option handler. UInteger should also be used with options like `-falign-loops` where both `-falign-loops` and `-falign-loops=n` are supported to make sure the saved options are given a full integer. Positive values of the argument in excess of INT_MAX wrap around zero.

**Host_Wide_Int**

The option’s argument is a non-negative integer consisting of either decimal or hexadecimal digits interpreted as the widest integer type on the host. As with an UInteger argument, hexadecimal integers may optionally start with the 0x or 0X prefix. The option parser validates and converts the argument before passing it to the relevant option handler. Host_Wide_Int should be used with options that need to accept very large values. Positive values of the argument in excess of HOST_WIDE_INT_M1U are assigned HOST_WIDE_INT_M1U.

**IntegerRange(n, m)**

The option’s arguments are integers of type int. The option’s parser validates that the value of an option integer argument is within the closed range \([n, m]\).

**ByteSize**

A property applicable only to UInteger or Host_Wide_Int arguments. The option’s integer argument is interpreted as if in infinite precision using saturation arithmetic in the corresponding type. The argument may be followed by a `byte-size` suffix designating a multiple of bytes such as kB and KiB for
kilobyte and kibibyte, respectively, MB and MiB for megabyte and mebibyte, GB and GiB for gigabyte and gigibyte, and so on. **ByteSize** should be used for with options that take a very large argument representing a size in bytes, such as ‘-Wlarger-than’.

**ToLower**  
The option’s argument should be converted to lowercase as part of putting it in canonical form, and before comparing with the strings indicated by any **Enum** property.

**NoDriverArg**  
For an option marked **Separate**, the option only takes an argument in the compiler proper, not in the driver. This is for compatibility with existing options that are used both directly and via ‘-Wp,’; new options should not have this property.

**Var(var)**  
The state of this option should be stored in variable `var` (actually a macro for `global_options.x_var`). The way that the state is stored depends on the type of option:

- **WarnRemoved**  
The option is removed and every usage of such option will result in a warning. We use it option backward compatibility.

- **Var(var, set)**  
The option controls an integer variable `var` and is active when `var` equals `set`. The option parser will set `var` to `set` when the positive form of the option is used and `!set` when the “no-” form is used.

  `var` is declared in the same way as for the single-argument form described above.

  - If the option uses the `Mask` or `InverseMask` properties, `var` is the integer variable that contains the mask.
  - If the option is a normal on/off switch, `var` is an integer variable that is nonzero when the option is enabled. The options parser will set the variable to 1 when the positive form of the option is used and 0 when the “no-” form is used.
  - If the option takes an argument and has the `UInteger` property, `var` is an integer variable that stores the value of the argument.
  - If the option takes an argument and has the `Enum` property, `var` is a variable (type given in the `Type` property of the ‘Enum’ record whose `Name` property has the same argument as the `Enum` property of this option) that stores the value of the argument.
  - If the option has the `Defer` property, `var` is a pointer to a `VEC(cl_deferred_option,heap)` that stores the option for later processing. (`var` is declared with type `void *` and needs to be cast to `VEC(cl_deferred_option,heap)` before use.)
  - Otherwise, if the option takes an argument, `var` is a pointer to the argument string. The pointer will be null if the argument is optional and wasn’t given.

The option-processing script will usually zero-initialize `var`. You can modify this behavior using `Init`. 
**Init(value)**

The variable specified by the `Var` property should be statically initialized to `value`. If more than one option using the same variable specifies `Init`, all must specify the same initializer.

**Mask(name)**

The option is associated with a bit in the `target_flags` variable (see Section 18.3 [Run-time Target], page 504) and is active when that bit is set. You may also specify `Var` to select a variable other than `target_flags`.

The options-processing script will automatically allocate a unique bit for the option. If the option is attached to `target_flags`, the script will set the macro `MASK_name` to the appropriate bitmask. It will also declare a `TARGET_name` macro that has the value 1 when the option is active and 0 otherwise. If you use `Var` to attach the option to a different variable, the bitmask macro will be called `OPTION_MASK_name`.

**InverseMask(othername)**

**InverseMask(othername, thisname)**

The option is the inverse of another option that has the `Mask(othername)` property. If `thisname` is given, the options-processing script will declare a `TARGET_thisname` macro that is 1 when the option is active and 0 otherwise.

**Enum(name)**

The option’s argument is a string from the set of strings associated with the corresponding `Enum` record. The string is checked and converted to the integer specified in the corresponding `EnumValue` record before being passed to option handlers.

**Defer**

The option should be stored in a vector, specified with `Var`, for later processing.

**Alias(opt)**

**Alias(opt, arg)**

**Alias(opt, posarg, negarg)**

The option is an alias for `"-opt"` (or the negative form of that option, depending on `NegativeAlias`). In the first form, any argument passed to the alias is considered to be passed to `"-opt"`, and `"-opt"` is considered to be negated if the alias is used in negated form. In the second form, the alias may not be negated or have an argument, and `posarg` is considered to be passed as an argument to `"-opt"`. In the third form, the alias may not have an argument, if the alias is used in the positive form then `posarg` is considered to be passed to `"-opt"`, and if the alias is used in the negative form then `negarg` is considered to be passed to `"-opt"`.

Aliases should not specify `Var` or `Mask` or `UInteger`. Aliases should normally specify the same languages as the target of the alias; the flags on the target will be used to determine any diagnostic for use of an option for the wrong language, while those on the alias will be used to identify what command-line text is the option and what text is any argument to that option.

When an `Alias` definition is used for an option, driver specs do not need to handle it and no `OPT_` enumeration value is defined for it; only the canonical form of the option will be seen in those places.
NegativeAlias

For an option marked with `Alias(opt)`, the option is considered to be an alias for the positive form of ‘-opt’ if negated and for the negative form of ‘-opt’ if not negated. `NegativeAlias` may not be used with the forms of `Alias` taking more than one argument.

Ignore

This option is ignored apart from printing any warning specified using `Warn`. The option will not be seen by specs and no ‘OPT_’ enumeration value is defined for it.

SeparateAlias

For an option marked with `Joined, Separate and Alias`, the option only acts as an alias when passed a separate argument; with a joined argument it acts as a normal option, with an ‘OPT_’ enumeration value. This is for compatibility with the Java ‘-d’ option and should not be used for new options.

Warn(message)

If this option is used, output the warning `message`. `message` is a format string, either taking a single operand with a ‘%qs’ format which is the option name, or not taking any operands, which is passed to the ‘warning’ function. If an alias is marked `Warn`, the target of the alias must not also be marked `Warn`.

Warning

This is a warning option and should be shown as such in ‘--help’ output. This flag does not currently affect anything other than ‘--help’.

Optimization

This is an optimization option. It should be shown as such in ‘--help’ output, and any associated variable named using `Var` should be saved and restored when the optimization level is changed with `optimize` attributes.

PerFunction

This is an option that can be overridden on a per-function basis. `Optimization` implies `PerFunction`, but options that do not affect executable code generation may use this flag instead, so that the option is not taken into account in ways that might affect executable code generation.

Param

This is an option that is a parameter.

Undocumented

The option is deliberately missing documentation and should not be included in the ‘--help’ output.

Condition(cond)

The option should only be accepted if preprocessor condition `cond` is true. Note that any C declarations associated with the option will be present even if `cond` is false; `cond` simply controls whether the option is accepted and whether it is printed in the ‘--help’ output.

Save

Build the `cl_target_option` structure to hold a copy of the option, add the functions `cl_target_option_save` and `cl_target_option_restore` to save and restore the options.
SetByCombined
The option may also be set by a combined option such as ‘-ffast-math’. This causes the gcc_options struct to have a field frontend_set_name, where name is the name of the field holding the value of this option (without the leading x_). This gives the front end a way to indicate that the value has been set explicitly and should not be changed by the combined option. For example, some front ends use this to prevent ‘-ffast-math’ and ‘-fno-fast-math’ from changing the value of ‘-fmath-errno’ for languages that do not use errno.

EnabledBy(opt)
EnabledBy(opt || opt2)
EnabledBy(opt && opt2)
If not explicitly set, the option is set to the value of ‘-opt’; multiple options can be given, separated by ||. The third form using && specifies that the option is only set if both opt and opt2 are set. The options opt and opt2 must have the Common property; otherwise, use LangEnabledBy.

LangEnabledBy(language, opt)
LangEnabledBy(language, opt, posarg, negarg)
When compiling for the given language, the option is set to the value of ‘-opt’, if not explicitly set. opt can be also a list of || separated options. In the second form, if opt is used in the positive form then posarg is considered to be passed to the option, and if opt is used in the negative form then negarg is considered to be passed to the option. It is possible to specify several different languages. Each language must have been declared by an earlier Language record. See Section 8.1 [Option file format], page 123.

NoDWARFRecord
The option is omitted from the producer string written by ‘-grecord-gcc-switches’.

PchIgnore
Even if this is a target option, this option will not be recorded / compared to determine if a precompiled header file matches.

CPP(var)
The state of this option should be kept in sync with the preprocessor option var. If this property is set, then properties Var and Init must be set as well.

CppReason(CPP_W_Enum)
This warning option corresponds to cpplib.h warning reason code CPP_W_Enum. This should only be used for warning options of the C-family front-ends.
9 Passes and Files of the Compiler

This chapter is dedicated to giving an overview of the optimization and code generation passes of the compiler. In the process, it describes some of the language front end interface, though this description is no where near complete.

9.1 Parsing pass

The language front end is invoked only once, via `lang_hooks.parse_file`, to parse the entire input. The language front end may use any intermediate language representation deemed appropriate. The C front end uses GENERIC trees (see Chapter 11 [GENERIC], page 165), plus a double handful of language specific tree codes defined in `c-common.def`. The Fortran front end uses a completely different private representation.

At some point the front end must translate the representation used in the front end to a representation understood by the language-independent portions of the compiler. Current practice takes one of two forms. The C front end manually invokes the gimplifier (see Chapter 12 [GIMPLE], page 213) on each function, and uses the gimplifier callbacks to convert the language-specific tree nodes directly to GIMPLE before passing the function off to be compiled. The Fortran front end converts from a private representation to GENERIC, which is later lowered to GIMPLE when the function is compiled. Which route to choose probably depends on how well GENERIC (plus extensions) can be made to match up with the source language and necessary parsing data structures.

BUG: Gimplification must occur before nested function lowering, and nested function lowering must be done by the front end before passing the data off to cgraph.

TODO: Cgraph should control nested function lowering. It would only be invoked when it is certain that the outer-most function is used.

TODO: Cgraph needs a gimplify_function callback. It should be invoked when (1) it is certain that the function is used, (2) warning flags specified by the user require some amount of compilation in order to honor, (3) the language indicates that semantic analysis is not complete until gimplification occurs. Hum... this sounds overly complicated. Perhaps we should just have the front end gimplify always; in most cases it's only one function call.

The front end needs to pass all function definitions and top level declarations off to the middle-end so that they can be compiled and emitted to the object file. For a simple procedural language, it is usually most convenient to do this as each top level declaration or definition is seen. There is also a distinction to be made between generating functional code and generating complete debug information. The only thing that is absolutely required for functional code is that function and data definitions be passed to the middle-end. For complete debug information, function, data and type declarations should all be passed as well.

In any case, the front end needs each complete top-level function or data declaration, and each data definition should be passed to `rest_of_decl_compilation`. Each complete type definition should be passed to `rest_of_type_compilation`. Each function definition should be passed to `cgraph_finalize_function`.

TODO: I know rest_of_compilation currently has all sorts of RTL generation semantics. I plan to move all code generation bits (both Tree and RTL) to compile_function. Should we hide cgraph from the front ends and move back to rest_of_compilation as the official
interface? Possibly we should rename all three interfaces such that the names match in some meaningful way and that is more descriptive than "rest_of".

The middle-end will, at its option, emit the function and data definitions immediately or queue them for later processing.

**9.2 Gimplification pass**

*Gimplification* is a whimsical term for the process of converting the intermediate representation of a function into the GIMPLE language (see Chapter 12 [GIMPLE], page 213). The term stuck, and so words like “gimplification”, “gimplify”, “gimplifier” and the like are sprinkled throughout this section of code.

While a front end may certainly choose to generate GIMPLE directly if it chooses, this can be a moderately complex process unless the intermediate language used by the front end is already fairly simple. Usually it is easier to generate GENERIC trees plus extensions and let the language-independent gimplifier do most of the work.

The main entry point to this pass is *gimplify_function_tree* located in ‘gimplify.c’. From here we process the entire function gimplifying each statement in turn. The main workhorse for this pass is *gimplify_expr*. Approximately everything passes through here at least once, and it is from here that we invoke the lang_hooks.gimplify_expr callback.

The callback should examine the expression in question and return GS_UNHANDLED if the expression is not a language specific construct that requires attention. Otherwise it should alter the expression in some way to such that forward progress is made toward producing valid GIMPLE. If the callback is certain that the transformation is complete and the expression is valid GIMPLE, it should return GS_ALL_DONE. Otherwise it should return GS_OK, which will cause the expression to be processed again. If the callback encounters an error during the transformation (because the front end is relying on the gimplification process to finish semantic checks), it should return GS_ERROR.

**9.3 Pass manager**

The pass manager is located in ‘passes.c’, ‘tree-optimize.c’ and ‘tree-pass.h’. It processes passes as described in ‘passes.def’. Its job is to run all of the individual passes in the correct order, and take care of standard bookkeeping that applies to every pass.

The theory of operation is that each pass defines a structure that represents everything we need to know about that pass—when it should be run, how it should be run, what intermediate language form or on-the-side data structures it needs. We register the pass to be run in some particular order, and the pass manager arranges for everything to happen in the correct order.

The actuality doesn’t completely live up to the theory at present. Command-line switches and timevar_id_t enumerations must still be defined elsewhere. The pass manager validates constraints but does not attempt to (re-)generate data structures or lower intermediate language form based on the requirements of the next pass. Nevertheless, what is present is useful, and a far sight better than nothing at all.

Each pass should have a unique name. Each pass may have its own dump file (for GCC debugging purposes). Passes with a name starting with a star do not dump anything. Sometimes passes are supposed to share a dump file / option name. To still give these
unique names, you can use a prefix that is delimited by a space from the part that is used for the dump file / option name. E.g. When the pass name is "ud dce", the name used for dump file/options is "dce".

TODO: describe the global variables set up by the pass manager, and a brief description of how a new pass should use it. I need to look at what info RTL passes use first...

9.4 Inter-procedural optimization passes

The inter-procedural optimization (IPA) passes use call graph information to perform transformations across function boundaries. IPA is a critical part of link-time optimization (LTO) and whole-program (WHOPR) optimization, and these passes are structured with the needs of LTO and WHOPR in mind by dividing their operations into stages. For detailed discussion of the LTO/WHOPR IPA pass stages and interfaces, see Section 25.3 [IPA], page 716.

The following briefly describes the inter-procedural optimization (IPA) passes, which are split into small IPA passes, regular IPA passes, and late IPA passes, according to the LTO/WHOPR processing model.

9.4.1 Small IPA passes

A small IPA pass is a pass derived from simple_ipa_opt_pass. As described in Section 25.3 [IPA], page 716, it does everything at once and defines only the Execute stage. During this stage it accesses and modifies the function bodies. No generate_summary, read_summary, or write_summary hooks are defined.

- IPA free lang data
  This pass frees resources that are used by the front end but are not needed once it is done. It is located in ‘tree.c’ and is described by pass_ipa_free_lang_data.

- IPA function and variable visibility
  This is a local function pass handling visibilities of all symbols. This happens before LTO streaming, so ‘-fwhole-program’ should be ignored at this level. It is located in ‘ipa-visibility.c’ and is described by pass_ipa_function_and_variable_visibility.

- IPA remove symbols
  This pass performs reachability analysis and reclaims all unreachable nodes. It is located in ‘passes.c’ and is described by pass_ipa_remove_symbols.

- IPA OpenACC
  This is a pass group for OpenACC processing. It is located in ‘tree-ssa-loop.c’ and is described by pass_ipa_oacc.

- IPA points-to analysis
  This is a tree-based points-to analysis pass. The idea behind this analyzer is to generate set constraints from the program, then solve the resulting constraints in order to generate the points-to sets. It is located in ‘tree-ssa-structalias.c’ and is described by pass_ipa_pta.

- IPA OpenACC kernels
  This is a pass group for processing OpenACC kernels regions. It is a subpass of the IPA OpenACC pass group that runs on offloaded functions containing OpenACC kernels loops. It is located in ‘tree-ssa-loop.c’ and is described by pass_ipa_oacc_kernels.
• Target clone
  This is a pass for parsing functions with multiple target attributes. It is located in `multiple_target.c` and is described by pass_target_clone.

• IPA auto profile
  This pass uses AutoFDO profiling data to annotate the control flow graph. It is located in `auto-profile.c` and is described by pass_ipa_auto_profile.

• IPA tree profile
  This pass does profiling for all functions in the call graph. It calculates branch probabilities and basic block execution counts. It is located in `tree-profile.c` and is described by pass_ipa_tree_profile.

• IPA free function summary
  This pass is a small IPA pass when argument small_p is true. It releases inline function summaries and call summaries. It is located in `ipa-fnsummary.c` and is described by pass_ipa_free_free_fn_summary.

• IPA increase alignment
  This pass increases the alignment of global arrays to improve vectorization. It is located in `tree-vectorizer.c` and is described by pass_ipa_increase_alignment.

• IPA transactional memory
  This pass is for transactional memory support. It is located in `trans-mem.c` and is described by pass_ipa_tm.

• IPA lower emulated TLS
  This pass lowers thread-local storage (TLS) operations to emulation functions provided by libgcc. It is located in `tree-emutls.c` and is described by pass_ipa_lower_emutls.

9.4.2 Regular IPA passes
A regular IPA pass is a pass derived from ipa_opt_pass_d that is executed in WHOPR compilation. Regular IPA passes may have summary hooks implemented in any of the LGEN, WPA or LTRANS stages (see Section 25.3 [IPA], page 716).

• IPA whole program visibility
  This pass performs various optimizations involving symbol visibility with `-fwhole-program`, including symbol privatization, discovering local functions, and dismantling comdat groups. It is located in `ipa-visibility.c` and is described by pass_ipa_whole_program_visibility.

• IPA profile
  The IPA profile pass propagates profiling frequencies across the call graph. It is located in `ipa-profile.c` and is described by pass_ipa_profile.

• IPA identical code folding
  This is the inter-procedural identical code folding pass. The goal of this transformation is to discover functions and read-only variables that have exactly the same semantics. It is located in `ipa-icf.c` and is described by pass_ipa_icf.
• IPA devirtualization
  This pass performs speculative devirtualization based on the type inheritance graph. When a polymorphic call has only one likely target in the unit, it is turned into a speculative call. It is located in ‘ipa-devirt.c’ and is described by pass_ipa_devirt.

• IPA constant propagation
  The goal of this pass is to discover functions that are always invoked with some arguments with the same known constant values and to modify the functions accordingly. It can also do partial specialization and type-based devirtualization. It is located in ‘ipa-cp.c’ and is described by pass_ipa_cp.

• IPA scalar replacement of aggregates
  This pass can replace an aggregate parameter with a set of other parameters representing part of the original, turning those passed by reference into new ones which pass the value directly. It also removes unused function return values and unused function parameters. This pass is located in ‘ipa-sra.c’ and is described by pass_ipa_sra.

• IPA constructor/destructor merge
  This pass merges multiple constructors and destructors for static objects into single functions. It’s only run at LTO time unless the target doesn’t support constructors and destructors natively. The pass is located in ‘ipa.c’ and is described by pass_ipa_cdtor_merge.

• IPA function summary
  This pass provides function analysis for inter-procedural passes. It collects estimates of function body size, execution time, and frame size for each function. It also estimates information about function calls: call statement size, time and how often the parameters change for each call. It is located in ‘ipa-fnsummary.c’ and is described by pass_ipa_fn_summary.

• IPA inline
  The IPA inline pass handles function inlining with whole-program knowledge. Small functions that are candidates for inlining are ordered in increasing badness, bounded by unit growth parameters. Unreachable functions are removed from the call graph. Functions called once and not exported from the unit are inlined. This pass is located in ‘ipa-inline.c’ and is described by pass_ipa_inline.

• IPA pure/const analysis
  This pass marks functions as being either const (TREE_READONLY) or pure (DECL_PURE_P). The per-function information is produced by pure_const_generate_summary, then the global information is computed by performing a transitive closure over the call graph. It is located in ‘ipa-pure-const.c’ and is described by pass_ipa_pure_const.

• IPA free function summary
  This pass is a regular IPA pass when argument small_p is false. It releases inline function summaries and call summaries. It is located in ‘ipa-fnsummary.c’ and is described by pass_ipa_free_fn_summary.

• IPA reference
  This pass gathers information about how variables whose scope is confined to the compilation unit are used. It is located in ‘ipa-reference.c’ and is described by pass_ipa_reference.
• IPA single use

This pass checks whether variables are used by a single function. It is located in ‘ipa.c’ and is described by pass_ipa_single_use.

• IPA comdats

This pass looks for static symbols that are used exclusively within one comdat group, and moves them into that comdat group. It is located in ‘ipa-comdats.c’ and is described by pass_ipa_comdats.

9.4.3 Late IPA passes

Late IPA passes are simple IPA passes executed after the regular passes. In WHOPR mode the passes are executed after partitioning and thus see just parts of the compiled unit.

• Materialize all clones

Once all functions from compilation unit are in memory, produce all clones and update all calls. It is located in ‘ipa.c’ and is described by pass_materialize_all_clones.

• IPA points-to analysis

Points-to analysis; this is the same as the points-to-analysis pass run with the small IPA passes (see Section 9.4.1 [Small IPA passes], page 133).

• OpenMP simd clone

This is the OpenMP constructs’ SIMD clone pass. It creates the appropriate SIMD clones for functions tagged as elemental SIMD functions. It is located in ‘omp-simd-clone.c’ and is described by pass_omp_simd_clone.

9.5 Tree SSA passes

The following briefly describes the Tree optimization passes that are run after gimplification and what source files they are located in.

• Remove useless statements

This pass is an extremely simple sweep across the gimple code in which we identify obviously dead code and remove it. Here we do things like simplify if statements with constant conditions, remove exception handling constructs surrounding code that obviously cannot throw, remove lexical bindings that contain no variables, and other assorted simplistic cleanups. The idea is to get rid of the obvious stuff quickly rather than wait until later when it’s more work to get rid of it. This pass is located in ‘tree-cfg.c’ and described by pass_remove_useless_stmts.

• OpenMP lowering

If OpenMP generation (‘-fopenmp’) is enabled, this pass lowers OpenMP constructs into GIMPLE.

Lowering of OpenMP constructs involves creating replacement expressions for local variables that have been mapped using data sharing clauses, exposing the control flow of most synchronization directives and adding region markers to facilitate the creation of the control flow graph. The pass is located in ‘omp-low.c’ and is described by pass_lower_omp.
• OpenMP expansion
  If OpenMP generation (`-fopenmp`) is enabled, this pass expands parallel regions into their own functions to be invoked by the thread library. The pass is located in ‘omp-low.c’ and is described by `pass_expand_omp`.

• Lower control flow
  This pass flattens if statements (`COND_EXPR`) and moves lexical bindings (`BIND_EXPR`) out of line. After this pass, all if statements will have exactly two `goto` statements in its `then` and `else` arms. Lexical binding information for each statement will be found in `TREE_BLOCK` rather than being inferred from its position under a `BIND_EXPR`. This pass is found in ‘gimple-low.c’ and is described by `pass_lower_cf`.

• Lower exception handling control flow
  This pass decomposes high-level exception handling constructs (`TRY_FINALLY_EXPR` and `TRY_CATCH_EXPR`) into a form that explicitly represents the control flow involved. After this pass, `lookup_stmt_eh_region` will return a non-negative number for any statement that may have EH control flow semantics; examine `tree_can_throw_internal` or `tree_can_throw_external` for exact semantics. Exact control flow may be extracted from `foreach_reachable_handler`. The EH region nesting tree is defined in ‘except.h’ and built in ‘except.c’. The lowering pass itself is in ‘tree-eh.c’ and is described by `pass_lower_eh`.

• Build the control flow graph
  This pass decomposes a function into basic blocks and creates all of the edges that connect them. It is located in ‘tree-cfg.c’ and is described by `pass_build_cfg`.

• Find all referenced variables
  This pass walks the entire function and collects an array of all variables referenced in the function, `referenced_vars`. The index at which a variable is found in the array is used as a UID for the variable within this function. This data is needed by the SSA rewriting routines. The pass is located in ‘tree-dfa.c’ and is described by `pass_referenced_vars`.

• Enter static single assignment form
  This pass rewrites the function such that it is in SSA form. After this pass, all `is_gimple_reg` variables will be referenced by `SSA_NAME`, and all occurrences of other variables will be annotated with `VDEFS` and `VUSES`; PHI nodes will have been inserted as necessary for each basic block. This pass is located in ‘tree-ssa.c’ and is described by `pass_build_ssa`.

• Warn for uninitialized variables
  This pass scans the function for uses of `SSA_NAME`s that are fed by default definition. For non-parameter variables, such uses are uninitialized. The pass is run twice, before and after optimization (if turned on). In the first pass we only warn for uses that are positively uninitialized; in the second pass we warn for uses that are possibly uninitialized. The pass is located in ‘tree-ssa.c’ and is defined by `pass_early_warn_uninitialized` and `pass_late_warn_uninitialized`.

• Dead code elimination
  This pass scans the function for statements without side effects whose result is unused. It does not do memory life analysis, so any value that is stored in memory is considered
used. The pass is run multiple times throughout the optimization process. It is located in `tree-ssa-dce.c` and is described by `pass_dce`.

- **Dominator optimizations**
  This pass performs trivial dominator-based copy and constant propagation, expression simplification, and jump threading. It is run multiple times throughout the optimization process. It is located in `tree-ssa-dom.c` and is described by `pass_dominator`.

- **Forward propagation of single-use variables**
  This pass attempts to remove redundant computation by substituting variables that are used once into the expression that uses them and seeing if the result can be simplified. It is located in `tree-ssa-forwprop.c` and is described by `pass_forwprop`.

- **Copy Renaming**
  This pass attempts to change the name of compiler temporaries involved in copy operations such that SSA-normal can coalesce the copy away. When compiler temporaries are copies of user variables, it also renames the compiler temporary to the user variable resulting in better use of user symbols. It is located in `tree-ssa-copyrename.c` and is described by `pass_copyrename`.

- **PHI node optimizations**
  This pass recognizes forms of PHI inputs that can be represented as conditional expressions and rewrites them into straight line code. It is located in `tree-ssa-phiopt.c` and is described by `pass_phiopt`.

- **May-alias optimization**
  This pass performs a flow sensitive SSA-based points-to analysis. The resulting may-alias, must-alias, and escape analysis information is used to promote variables from in-memory addressable objects to non-aliased variables that can be renamed into SSA form. We also update the VDEF/VUSE memory tags for non-renameable aggregates so that we get fewer false kills. The pass is located in `tree-ssa-alias.c` and is described by `pass_may_alias`.
  Interprocedural points-to information is located in `tree-ssa-structalias.c` and described by `pass_ipa_pta`.

- **Profiling**
  This pass instruments the function in order to collect runtime block and value profiling data. Such data may be fed back into the compiler on a subsequent run so as to allow optimization based on expected execution frequencies. The pass is located in `tree-profile.c` and is described by `pass_ipa_tree_profile`.

- **Static profile estimation**
  This pass implements series of heuristics to guess propabilities of branches. The resulting predictions are turned into edge profile by propagating branches across the control flow graphs. The pass is located in `tree-profile.c` and is described by `pass_profile`.

- **Lower complex arithmetic**
  This pass rewrites complex arithmetic operations into their component scalar arithmetic operations. The pass is located in `tree-complex.c` and is described by `pass_lower_complex`.
• Scalar replacement of aggregates
  This pass rewrites suitable non-aliased local aggregate variables into a set of scalar
  variables. The resulting scalar variables are rewritten into SSA form, which allows
  subsequent optimization passes to do a significantly better job with them. The pass is
  located in ‘tree-sra.c’ and is described by pass_sra.
• Dead store elimination
  This pass eliminates stores to memory that are subsequently overwritten by another
  store, without any intervening loads. The pass is located in ‘tree-ssa-dse.c’ and is
  described by pass_dse.
• Tail recursion elimination
  This pass transforms tail recursion into a loop. It is located in ‘tree-tailcall.c’ and
  is described by pass_tail_recursion.
• Forward store motion
  This pass sinks stores and assignments down the flowgraph closer to their use point.
  The pass is located in ‘tree-ssa-sink.c’ and is described by pass_sink_code.
• Partial redundancy elimination
  This pass eliminates partially redundant computations, as well as performing load
  motion. The pass is located in ‘tree-ssa-pre.c’ and is described by pass_pre.
  Just before partial redundancy elimination, if ‘-funsafe-math-optimizations’ is on,
  GCC tries to convert divisions to multiplications by the reciprocal. The pass is located
  in ‘tree-ssa-math-opts.c’ and is described by pass_cse_reciprocal.
• Full redundancy elimination
  This is a simpler form of PRE that only eliminates redundancies that occur on all
  paths. It is located in ‘tree-ssa-pre.c’ and described by pass_fre.
• Loop optimization
  The main driver of the pass is placed in ‘tree-ssa-loop.c’ and described by pass_-
  loop.
  The optimizations performed by this pass are:
  Loop invariant motion. This pass moves only invariants that would be hard to handle
  on RTL level (function calls, operations that expand to nontrivial sequences of insns).
  With ‘-funswitch-loops’ it also moves operands of conditions that are invariant out
  of the loop, so that we can use just trivial invariantness analysis in loop unswitching.
  The pass also includes store motion. The pass is implemented in ‘tree-ssa-loop-im.c’.
  Canonical induction variable creation. This pass creates a simple counter for number
  of iterations of the loop and replaces the exit condition of the loop using it, in case
  when a complicated analysis is necessary to determine the number of iterations. Later
  optimizations then may determine the number easily. The pass is implemented in
  ‘tree-ssa-loop-ivcanon.c’.
  Induction variable optimizations. This pass performs standard induction variable op-
  timizations, including strength reduction, induction variable merging and induction
  variable elimination. The pass is implemented in ‘tree-ssa-loop-ivopts.c’.
  Loop unswitching. This pass moves the conditional jumps that are invariant out of
  the loops. To achieve this, a duplicate of the loop is created for each possible outcome
  of conditional jump(s). The pass is implemented in ‘tree-ssa-loop-unswitch.c’.
Loop splitting. If a loop contains a conditional statement that is always true for one part of the iteration space and false for the other this pass splits the loop into two, one dealing with one side the other only with the other, thereby removing one inner-loop conditional. The pass is implemented in ‘tree-ssa-loop-split.c’.

The optimizations also use various utility functions contained in ‘tree-ssa-loop-manip.c’, ‘cfgloop.c’, ‘cfgloopenal.c’ and ‘cfgloopmanip.c’.

Vectorization. This pass transforms loops to operate on vector types instead of scalar types. Data parallelism across loop iterations is exploited to group data elements from consecutive iterations into a vector and operate on them in parallel. Depending on available target support the loop is conceptually unrolled by a factor $VF$ (vectorization factor), which is the number of elements operated upon in parallel in each iteration, and the $VF$ copies of each scalar operation are fused to form a vector operation. Additional loop transformations such as peeling and versioning may take place to align the number of iterations, and to align the memory accesses in the loop. The pass is implemented in ‘tree-vectorizer.c’ (the main driver), ‘tree-vec-loop.c’ and ‘tree-vec-loop-manip.c’ (loop specific parts and general loop utilities), ‘tree-vec-slp’ (loop-aware SLP functionality), ‘tree-vec-stmts.c’, ‘tree-vec-data-refs.c’ and ‘tree-vec-slp-patterns.c’ containing the SLP pattern matcher. Analysis of data references is in ‘tree-data-ref.c’.

SLP Vectorization. This pass performs vectorization of straight-line code. The pass is implemented in ‘tree-vectorizer.c’ (the main driver), ‘tree-vec-slp.c’, ‘tree-vec-stmts.c’ and ‘tree-vec-data-refs.c’.

Autoparallelization. This pass splits the loop iteration space to run into several threads. The pass is implemented in ‘tree-parloops.c’.

Graphite is a loop transformation framework based on the polyhedral model. Graphite stands for Gimple Represented as Polyhedra. The internals of this infrastructure are documented in [http://gcc.gnu.org/wiki/Graphite](http://gcc.gnu.org/wiki/Graphite). The passes working on this representation are implemented in the various ‘graphite-*’ files.

- Tree level if-conversion for vectorizer
  This pass applies if-conversion to simple loops to help vectorizer. We identify if convertible loops, if-convert statements and merge basic blocks in one big block. The idea is to present loop in such form so that vectorizer can have one to one mapping between statements and available vector operations. This pass is located in ‘tree-if-conv.c’ and is described by pass_if_conversion.

- Conditional constant propagation
  This pass relaxes a lattice of values in order to identify those that must be constant even in the presence of conditional branches. The pass is located in ‘tree-ssa-ccp.c’ and is described by pass_ccp.

  A related pass that works on memory loads and stores, and not just register values, is located in ‘tree-ssa-cp.c’ and described by pass_store_ccp.

- Conditional copy propagation
  This is similar to constant propagation but the lattice of values is the “copy-of” relation. It eliminates redundant copies from the code. The pass is located in ‘tree-ssa-copy.c’ and described by pass_copy_prop.
A related pass that works on memory copies, and not just register copies, is located in ‘tree-ssa-copy.c’ and described by pass_store_copy_prop.

- **Value range propagation**
  
  This transformation is similar to constant propagation but instead of propagating single constant values, it propagates known value ranges. The implementation is based on Patterson’s range propagation algorithm (Accurate Static Branch Prediction by Value Range Propagation, J. R. C. Patterson, PLDI ’95). In contrast to Patterson’s algorithm, this implementation does not propagate branch probabilities nor it uses more than a single range per SSA name. This means that the current implementation cannot be used for branch prediction (though adapting it would not be difficult). The pass is located in ‘tree-vrp.c’ and is described by pass_vrp.

- **Folding built-in functions**
  
  This pass simplifies built-in functions, as applicable, with constant arguments or with inferable string lengths. It is located in ‘tree-ssa-ccp.c’ and is described by pass_fold_builtins.

- **Split critical edges**
  
  This pass identifies critical edges and inserts empty basic blocks such that the edge is no longer critical. The pass is located in ‘tree-cfg.c’ and is described by pass_split_crit_edges.

- **Control dependence dead code elimination**
  
  This pass is a stronger form of dead code elimination that can eliminate unnecessary control flow statements. It is located in ‘tree-ssa-dce.c’ and is described by pass_cd_dce.

- **Tail call elimination**
  
  This pass identifies function calls that may be rewritten into jumps. No code transformation is actually applied here, but the data and control flow problem is solved. The code transformation requires target support, and so is delayed until RTL. In the meantime CALL_EXPR_TAILCALL is set indicating the possibility. The pass is located in ‘tree-tailcall.c’ and is described by pass_tail_calls. The RTL transformation is handled by fixup_tail_calls in ‘calls.c’.

- **Warn for function return without value**
  
  For non-void functions, this pass locates return statements that do not specify a value and issues a warning. Such a statement may have been injected by falling off the end of the function. This pass is run last so that we have as much time as possible to prove that the statement is not reachable. It is located in ‘tree-cfg.c’ and is described by pass_warn_function_return.

- **Leave static single assignment form**
  
  This pass rewrites the function such that it is in normal form. At the same time, we eliminate as many single-use temporaries as possible, so the intermediate language is no longer GIMPLE, but GENERIC. The pass is located in ‘tree-outof-ssa.c’ and is described by pass_del_ssa.

- **Merge PHI nodes that feed into one another**
This is part of the CFG cleanup passes. It attempts to join PHI nodes from a forwarder CFG block into another block with PHI nodes. The pass is located in ‘tree-cfgcleanup.c’ and is described by pass_merge_phi.

- Return value optimization

If a function always returns the same local variable, and that local variable is an aggregate type, then the variable is replaced with the return value for the function (i.e., the function’s DECL_RESULT). This is equivalent to the C++ named return value optimization applied to GIMPLE. The pass is located in ‘tree-nrv.c’ and is described by pass_nrv.

- Return slot optimization

If a function returns a memory object and is called as var = foo(), this pass tries to change the call so that the address of var is sent to the caller to avoid an extra memory copy. This pass is located in tree-nrv.c and is described by pass_return_slot.

- Optimize calls to __builtin_object_size

This is a propagation pass similar to CCP that tries to remove calls to __builtin_object_size when the size of the object can be computed at compile-time. This pass is located in ‘tree-object-size.c’ and is described by pass_object_sizes.

- Loop invariant motion

This pass removes expensive loop-invariant computations out of loops. The pass is located in ‘tree-ssa-loop.c’ and described by pass_lim.

- Loop nest optimizations

This is a family of loop transformations that works on loop nests. It includes loop interchange, scaling, skewing and reversal and they are all geared to the optimization of data locality in array traversals and the removal of dependencies that hamper optimizations such as loop parallelization and vectorization. The pass is located in ‘tree-loop-linear.c’ and described by pass_linear_transform.

- Removal of empty loops

This pass removes loops with no code in them. The pass is located in ‘tree-ssa-loop-ivcanon.c’ and described by pass_empty_loop.

- Unrolling of small loops

This pass completely unrolls loops with few iterations. The pass is located in ‘tree-ssa-loop-ivcanon.c’ and described by pass_complete_unroll.

- Predictive commoning

This pass makes the code reuse the computations from the previous iterations of the loops, especially loads and stores to memory. It does so by storing the values of these computations to a bank of temporary variables that are rotated at the end of loop. To avoid the need for this rotation, the loop is then unrolled and the copies of the loop body are rewritten to use the appropriate version of the temporary variable. This pass is located in ‘tree-predcom.c’ and described by pass_predcom.

- Array prefetching

This pass issues prefetch instructions for array references inside loops. The pass is located in ‘tree-ssa-loop-prefetch.c’ and described by pass_loop_prefetch.
• Reassociation
This pass rewrites arithmetic expressions to enable optimizations that operate on them, like redundancy elimination and vectorization. The pass is located in ‘tree-ssa-reassoc.c’ and described by pass_reassoc.

• Optimization of stdarg functions
This pass tries to avoid the saving of register arguments into the stack on entry to stdarg functions. If the function doesn’t use any va_start macros, no registers need to be saved. If va_start macros are used, the va_list variables don’t escape the function, it is only necessary to save registers that will be used in va_arg macros. For instance, if va_arg is only used with integral types in the function, floating point registers don’t need to be saved. This pass is located in tree-stdarg.c and described by pass_stdarg.

9.6 RTL passes
The following briefly describes the RTL generation and optimization passes that are run after the Tree optimization passes.

• RTL generation
The source files for RTL generation include ‘stmt.c’, ‘calls.c’, ‘expr.c’, ‘explow.c’, ‘expmed.c’, ‘function.c’, ‘optabs.c’ and ‘emit-rtl.c’. Also, the file ‘insn-emit.c’, generated from the machine description by the program genemit, is used in this pass. The header file ‘expr.h’ is used for communication within this pass.

The header files ‘insn-flags.h’ and ‘insn-codes.h’, generated from the machine description by the programs genflags and gencodes, tell this pass which standard names are available for use and which patterns correspond to them.

• Generation of exception landing pads
This pass generates the glue that handles communication between the exception handling library routines and the exception handlers within the function. Entry points in the function that are invoked by the exception handling library are called landing pads. The code for this pass is located in ‘except.c’.

• Control flow graph cleanup
This pass removes unreachable code, simplifies jumps to next, jumps to jump, jumps across jumps, etc. The pass is run multiple times. For historical reasons, it is occasionally referred to as the “jump optimization pass”. The bulk of the code for this pass is in ‘cfgcleanup.c’, and there are support routines in ‘cfgrtl.c’ and ‘jump.c’.

• Forward propagation of single-def values
This pass attempts to remove redundant computation by substituting variables that come from a single definition, and seeing if the result can be simplified. It performs copy propagation and addressing mode selection. The pass is run twice, with values being propagated into loops only on the second run. The code is located in ‘fwprop.c’.

• Common subexpression elimination
This pass removes redundant computation within basic blocks, and optimizes addressing modes based on cost. The pass is run twice. The code for this pass is located in ‘cse.c’.
• Global common subexpression elimination
This pass performs two different types of GCSE depending on whether you are optimizing for size or not (LCM based GCSE tends to increase code size for a gain in speed, while Morel-Renvoise based GCSE does not). When optimizing for size, GCSE is done using Morel-Renvoise Partial Redundancy Elimination, with the exception that it does not try to move invariants out of loops—that is left to the loop optimization pass. If MR PRE GCSE is done, code hoisting (aka unification) is also done, as well as load motion. If you are optimizing for speed, LCM (lazy code motion) based GCSE is done. LCM is based on the work of Knoop, Ruthing, and Steffen. LCM based GCSE also does loop invariant code motion. We also perform load and store motion when optimizing for speed. Regardless of which type of GCSE is used, the GCSE pass also performs global constant and copy propagation. The source file for this pass is ‘gcse.c’, and the LCM routines are in ‘lcm.c’.

• Loop optimization
This pass performs several loop related optimizations. The source files ‘cfgloopanal.c’ and ‘cfgloopmanip.c’ contain generic loop analysis and manipulation code. Initialization and finalization of loop structures is handled by ‘loop-init.c’. A loop invariant motion pass is implemented in ‘loop-invariant.c’. Basic block level optimizations—unrolling, and peeling loops—are implemented in ‘loop-unroll.c’. Replacing of the exit condition of loops by special machine-dependent instructions is handled by ‘loop-doloop.c’.

• Jump bypassing
This pass is an aggressive form of GCSE that transforms the control flow graph of a function by propagating constants into conditional branch instructions. The source file for this pass is ‘gcse.c’.

• If conversion
This pass attempts to replace conditional branches and surrounding assignments with arithmetic, boolean value producing comparison instructions, and conditional move instructions. In the very last invocation after reload/LRA, it will generate predicated instructions when supported by the target. The code is located in ‘ifcvt.c’.

• Web construction
This pass splits independent uses of each pseudo-register. This can improve effect of the other transformation, such as CSE or register allocation. The code for this pass is located in ‘web.c’.

• Instruction combination
This pass attempts to combine groups of two or three instructions that are related by data flow into single instructions. It combines the RTL expressions for the instructions by substitution, simplifies the result using algebra, and then attempts to match the result against the machine description. The code is located in ‘combine.c’.

• Mode switching optimization
This pass looks for instructions that require the processor to be in a specific “mode” and minimizes the number of mode changes required to satisfy all users. What these modes are, and what they apply to are completely target-specific. The code for this pass is located in ‘mode-switching.c’.
• Modulo scheduling
This pass looks at innermost loops and reorders their instructions by overlapping different iterations. Modulo scheduling is performed immediately before instruction scheduling. The code for this pass is located in ‘modulo-sched.c’.

• Instruction scheduling
This pass looks for instructions whose output will not be available by the time that it is used in subsequent instructions. Memory loads and floating point instructions often have this behavior on RISC machines. It re-orders instructions within a basic block to try to separate the definition and use of items that otherwise would cause pipeline stalls. This pass is performed twice, before and after register allocation. The code for this pass is located in ‘haifa-sched.c’, ‘sched-deps.c’, ‘sched-ebb.c’, ‘sched-rgn.c’ and ‘sched-vis.c’.

• Register allocation
These passes make sure that all occurrences of pseudo registers are eliminated, either by allocating them to a hard register, replacing them by an equivalent expression (e.g. a constant) or by placing them on the stack. This is done in several subpasses:
  • The integrated register allocator (IRA). It is called integrated because coalescing, register live range splitting, and hard register preferencing are done on-the-fly during coloring. It also has better integration with the reload/LRA pass. Pseudo-registers spilled by the allocator or the reload/LRA have still a chance to get hard-registers if the reload/LRA evicts some pseudo-registers from hard-registers. The allocator helps to choose better pseudos for spilling based on their live ranges and to coalesce stack slots allocated for the spilled pseudo-registers. IRA is a regional register allocator which is transformed into Chaitin-Briggs allocator if there is one region. By default, IRA chooses regions using register pressure but the user can force it to use one region or regions corresponding to all loops.
  Source files of the allocator are ‘ira.c’, ‘ira-build.c’, ‘ira-costs.c’, ‘ira-conflicts.c’, ‘ira-color.c’, ‘ira-emit.c’, ‘ira-lives’, plus header files ‘ira.h’ and ‘ira-int.h’ used for the communication between the allocator and the rest of the compiler.
  • Reloading. This pass renumbers pseudo registers with the hardware registers numbers they were allocated. Pseudo registers that did not get hard registers are replaced with stack slots. Then it finds instructions that are invalid because a value has failed to end up in a register, or has ended up in a register of the wrong kind. It fixes up these instructions by reloading the problematical values temporarily into registers. Additional instructions are generated to do the copying.
  The reload pass also optionally eliminates the frame pointer and inserts instructions to save and restore call-clobbered registers around calls.
  Source files are ‘reload.c’ and ‘reload1.c’, plus the header ‘reload.h’ used for communication between them.
  • This pass is a modern replacement of the reload pass. Source files are ‘lra.c’, ‘lra-assign.c’, ‘lra-coalesce.c’, ‘lra-constraints.c’, ‘lra-eliminations.c’, ‘lra-lives.c’, ‘lra-remat.c’, ‘lra-spills.c’, the header ‘lra-int.h’ used for communication between them, and the header ‘lra.h’ used for communication between LRA and the rest of compiler.
Unlike the reload pass, intermediate LRA decisions are reflected in RTL as much as possible. This reduces the number of target-dependent macros and hooks, leaving instruction constraints as the primary source of control.

LRA is run on targets for which TARGET_LRA_P returns true.

- Basic block reordering
  This pass implements profile guided code positioning. If profile information is not available, various types of static analysis are performed to make the predictions normally coming from the profile feedback (IE execution frequency, branch probability, etc). It is implemented in the file `bb-reorder.c`, and the various prediction routines are in `predict.c`.

- Variable tracking
  This pass computes where the variables are stored at each position in code and generates notes describing the variable locations to RTL code. The location lists are then generated according to these notes to debug information if the debugging information format supports location lists. The code is located in `var-tracking.c`.

- Delayed branch scheduling
  This optional pass attempts to find instructions that can go into the delay slots of other instructions, usually jumps and calls. The code for this pass is located in `reorg.c`.

- Branch shortening
  On many RISC machines, branch instructions have a limited range. Thus, longer sequences of instructions must be used for long branches. In this pass, the compiler figures out what how far each instruction will be from each other instruction, and therefore whether the usual instructions, or the longer sequences, must be used for each branch. The code for this pass is located in `final.c`.

- Register-to-stack conversion
  Conversion from usage of some hard registers to usage of a register stack may be done at this point. Currently, this is supported only for the floating-point registers of the Intel 80387 coprocessor. The code for this pass is located in `reg-stack.c`.

- Final
  This pass outputs the assembler code for the function. The source files are `final.c` plus `insn-output.c`; the latter is generated automatically from the machine description by the tool `genoutput`. The header file `conditions.h` is used for communication between these files.

- Debugging information output
  This is run after final because it must output the stack slot offsets for pseudo registers that did not get hard registers. Source files are `dbxout.c` for DBX symbol table format, `dwarfout.c` for DWARF symbol table format, files `dwarf2out.c` and `dwarf2asm.c` for DWARF2 symbol table format, and `vmsdbgout.c` for VMS debug symbol table format.

### 9.7 Optimization info

This section describes dump infrastructure which is common to both pass dumps as well as optimization dumps. The goal for this infrastructure is to provide both gcc developers and users detailed information about various compiler transformations and optimizations.
9.7.1 Dump setup
A dump manager class is defined in ‘dumpfile.h’. Various passes register dumping pass-specific information via dump_register in ‘passes.c’. During the registration, an optimization pass can select its optimization group (see Section 9.7.2 [Optimization groups], page 147). After that optimization information corresponding to the entire group (presumably from multiple passes) can be output via command-line switches. Note that if a pass does not fit into any of the pre-defined groups, it can select OPTGROUP_NONE.

Note that in general, a pass need not know its dump output file name, whether certain flags are enabled, etc. However, for legacy reasons, passes could also call dump_begin which returns a stream in case the particular pass has optimization dumps enabled. A pass could call dump_end when the dump has ended. These methods should go away once all the passes are converted to use the new dump infrastructure.

The recommended way to setup the dump output is via dump_start and dump_end.

9.7.2 Optimization groups
The optimization passes are grouped into several categories. Currently defined categories in ‘dumpfile.h’ are

OPTGROUP_IPA
IPA optimization passes. Enabled by ‘-ipa’

OPTGROUP_LOOP
Loop optimization passes. Enabled by ‘-loop’.

OPTGROUP_INLINE
Inlining passes. Enabled by ‘-inline’.

OPTGROUP_OMP
OMP (Offloading and Multi Processing) passes. Enabled by ‘-omp’.

OPTGROUP_VEC
Vectorization passes. Enabled by ‘-vec’.

OPTGROUP_OTHER
All other optimization passes which do not fall into one of the above.

OPTGROUP_ALL
All optimization passes. Enabled by ‘-optall’.

By using groups a user could selectively enable optimization information only for a group of passes. By default, the optimization information for all the passes is dumped.

9.7.3 Dump files and streams
There are two separate output streams available for outputting optimization information from passes. Note that both these streams accept stderr and stdout as valid streams and thus it is possible to dump output to standard output or error. This is specially handy for outputting all available information in a single file by redirecting stderr.

pstream This stream is for pass-specific dump output. For example, ‘-fdump-tree-vect=foo.v’ dumps tree vectorization pass output into the given file name ‘foo.v’. If the file name is not provided, the default file
name is based on the source file and pass number. Note that one could also
use special file names **stdout** and **stderr** for dumping to standard output and
standard error respectively.

**alt_stream**
This stream is used for printing optimization specific output in response to the
`-fopt-info`. Again a file name can be given. If the file name is not given, it
defaults to **stderr**.

### 9.7.4 Dump output verbosity

The dump verbosity has the following options

- **optimized**
  Print information when an optimization is successfully applied. It is up to a
  pass to decide which information is relevant. For example, the vectorizer passes
  print the source location of loops which got successfully vectorized.

- **missed**
  Print information about missed optimizations. Individual passes control which
  information to include in the output. For example,
  
  ```
gcc -O2 -ftree-vectorize -fopt-info-vec-missed
  ```
  will print information about missed optimization opportunities from vectoriza-
  tion passes on stderr.

- **note**
  Print verbose information about optimizations, such as certain transformations,
  more detailed messages about decisions etc.

- **all**
  Print detailed optimization information. This includes **optimized**, **missed**, and
  **note**.

### 9.7.5 Dump types

**dump_printf**
This is a generic method for doing formatted output. It takes an additional
argument **dump_kind** which signifies the type of dump. This method outputs
information only when the dumps are enabled for this particular **dump_kind**.
Note that the caller doesn’t need to know if the particular dump is enabled
or not, or even the file name. The caller only needs to decide which dump
output information is relevant, and under what conditions. This determines
the associated flags.

Consider the following example from `loop-unroll.c` where an informative
message about a loop (along with its location) is printed when any of the
following flags is enabled

- optimization messages
- RTL dumps
- detailed dumps

```c
int report_flags = MSG_OPTIMIZED_LOCATIONS | TDF_RTL | TDFDETAILS;

dump_printf_loc (report_flags, insn,
    "loop turned into non-loop; it never loops.\n");
```
dump_basic_block
Output basic block.

dump_generic_expr
Output generic expression.

dump_gimple_stmt
Output gimple statement.
Note that the above methods also have variants prefixed with _loc, such as
dump_printf_loc, which are similar except they also output the source location
information. The _loc variants take a const dump_location_t &. This class
can be constructed from a gimple * or from a rtx_insn *, and so callers can
pass a gimple * or a rtx_insn * as the _loc argument. The dump_location_t
constructor will extract the source location from the statement or instruction,
along with the profile count, and the location in GCC’s own source code (or
the plugin) from which the dump call was emitted. Only the source location
is currently used. There is also a dump_user_location_t class, capturing the
source location and profile count, but not the dump emission location, so that
locations in the user’s code can be passed around. This can also be constructed
from a gimple * and from a rtx_insn *, and it too can be passed as the _loc
argument.

9.7.6 Dump examples
 gcc -O3 -fopt-info-missed=missed.all
 outputs missed optimization report from all the passes into ‘missed.all’.

As another example,
 gcc -O3 -fopt-info-inline-optimized-missed=inline.txt
 will output information about missed optimizations as well as optimized locations from
all the inlining passes into ‘inline.txt’.

If the filename is provided, then the dumps from all the applicable optimizations are
concatenated into the ‘filename’. Otherwise the dump is output onto ‘stderr’. If options
is omitted, it defaults to ‘optimized-optall’, which means dump all information about
successful optimizations from all the passes. In the following example, the optimization
information is output on to ‘stderr’.
 gcc -O3 -fopt-info
 Note that ‘-fopt-info-vec-missed’ behaves the same as ‘-fopt-info-missed-vec’.
The order of the optimization group names and message types listed after ‘-fopt-info’
does not matter.

As another example, consider
 gcc -fopt-info-vec-missed=vec.miss -fopt-info-loop-optimized=loop.opt

Here the two output file names ‘vec.miss’ and ‘loop.opt’ are in conflict since only one
output file is allowed. In this case, only the first option takes effect and the subsequent
options are ignored. Thus only the ‘vec.miss’ is produced which contains dumps from the
vectorizer about missed opportunities.
10 Sizes and offsets as runtime invariants

GCC allows the size of a hardware register to be a runtime invariant rather than a compile-time constant. This in turn means that various sizes and offsets must also be runtime invariants rather than compile-time constants, such as:

- the size of a general `machine_mode` (see Section 14.6 [Machine Modes], page 275);
- the size of a spill slot;
- the offset of something within a stack frame;
- the number of elements in a vector;
- the size and offset of a `mem` rtx (see Section 14.8 [Regs and Memory], page 286); and
- the byte offset in a `subreg` rtx (see Section 14.8 [Regs and Memory], page 286).

The motivating example is the Arm SVE ISA, whose vector registers can be any multiple of 128 bits between 128 and 2048 inclusive. The compiler normally produces code that works for all SVE register sizes, with the actual size only being known at runtime.

GCC’s main representation of such runtime invariants is the `poly_int` class. This chapter describes what `poly_int` does, lists the available operations, and gives some general usage guidelines.

10.1 Overview of `poly_int`

We define indeterminates `x1, \ldots, xn` whose values are only known at runtime and use polynomials of the form:

\[ c_0 + c_1 \times x_1 + \ldots + c_n \times x_n \]

...
poly_uint16
   a 'poly_int' with unsigned short coefficients.

poly_int64
   a 'poly_int' with HOST_WIDE_INT coefficients.

poly_uint64
   a 'poly_int' with unsigned HOST_WIDE_INT coefficients.

poly_offset_int
   a 'poly_int' with offset_int coefficients.

poly_wide_int
   a 'poly_int' with wide_int coefficients.

poly_widest_int
   a 'poly_int' with widest_int coefficients.

Since the main purpose of poly_int is to represent sizes and offsets, the last two typedefs are only rarely used.

10.2 Consequences of using poly_int

The two main consequences of using polynomial sizes and offsets are that:

- there is no total ordering between the values at compile time, and
- some operations might yield results that cannot be expressed as a poly_int.

For example, if x is a runtime invariant, we cannot tell at compile time whether:

\[ 3 + 4x \leq 1 + 5x \]

since the condition is false when \( x \leq 1 \) and true when \( x \geq 2 \).

Similarly, poly_int cannot represent the result of:

\[(3 + 4x) \times (1 + 5x)\]

since it cannot (and in practice does not need to) store powers greater than one. It also cannot represent the result of:

\[(3 + 4x) \div (1 + 5x)\]

The following sections describe how we deal with these restrictions.

As described earlier, a poly_int<1, T> has no indeterminates and so degenerates to a compile-time constant of type T. It would be possible in that case to do all normal arithmetic on the T, and to compare the T using the normal C++ operators. We deliberately prevent target-independent code from doing this, since the compiler needs to support other poly_int<n, T> as well, regardless of the current target’s NUM_POLY_INT_COEFS.

However, it would be very artificial to force target-specific code to follow these restrictions if the target has no runtime indeterminates. There is therefore an implicit conversion from poly_int<1, T> to T when compiling target-specific translation units.
10.3 Comparisons involving poly_int

In general we need to compare sizes and offsets in two situations: those in which the values need to be ordered, and those in which the values can be unordered. More loosely, the distinction is often between values that have a definite link (usually because they refer to the same underlying register or memory location) and values that have no definite link. An example of the former is the relationship between the inner and outer sizes of a subreg, where we must know at compile time whether the subreg is paradoxical, partial, or complete. An example of the latter is alias analysis: we might want to check whether two arbitrary memory references overlap.

Referring back to the examples in the previous section, it makes sense to ask whether a memory reference of size ‘$3 + 4x$’ overlaps one of size ‘$1 + 5x$’, but it does not make sense to have a subreg in which the outer mode has ‘$3 + 4x$’ bytes and the inner mode has ‘$1 + 5x$’ bytes (or vice versa). Such subregs are always invalid and should trigger an internal compiler error if formed.

The underlying operators are the same in both cases, but the distinction affects how they are used.

10.3.1 Comparison functions for poly_int

poly_int provides the following routines for checking whether a particular condition “may be” (might be) true:

\[
\text{maybe_lt} \quad \text{maybe_le} \quad \text{maybe_eq} \quad \text{maybe_ge} \quad \text{maybe_gt} \\
\text{maybe_ne}
\]

The functions have their natural meaning:

‘maybe_lt(a, b)’
Return true if a might be less than b.

‘maybe_le(a, b)’
Return true if a might be less than or equal to b.

‘maybe_eq(a, b)’
Return true if a might be equal to b.

‘maybe_ne(a, b)’
Return true if a might not be equal to b.

‘maybe_ge(a, b)’
Return true if a might be greater than or equal to b.

‘maybe_gt(a, b)’
Return true if a might be greater than b.

For readability, poly_int also provides “known” inverses of these functions:

\[
\text{known_lt} \; (a, b) = \neg \text{maybe_ge} \; (a, b) \\
\text{known_le} \; (a, b) = \neg \text{maybe_gt} \; (a, b) \\
\text{known_eq} \; (a, b) = \neg \text{maybe_ne} \; (a, b) \\
\text{known_ge} \; (a, b) = \neg \text{maybe_lt} \; (a, b) \\
\text{known_gt} \; (a, b) = \neg \text{maybe_le} \; (a, b) \\
\text{known_ne} \; (a, b) = \neg \text{maybe_eq} \; (a, b)
\]
Properties of the poly_int comparisons

All “maybe” relations except maybe_ne are transitive, so for example:

maybe_lt (a, b) && maybe_lt (b, c) implies maybe_lt (a, c)

for all a, b and c. maybe_lt, maybe_gt and maybe_ne are irreflexive, so for example:

!maybe_lt (a, a)

is true for all a. maybe_le, maybe_eq and maybe_ge are reflexive, so for example:

maybe_le (a, a)

is true for all a. maybe_eq and maybe_ne are symmetric, so:

maybe_eq (a, b) == maybe_eq (b, a)
maybe_ne (a, b) == maybe_ne (b, a)

for all a and b. In addition:

maybe_le (a, b) == maybe_lt (a, b) || maybe_eq (a, b)
maybe_ge (a, b) == maybe_gt (a, b) || maybe_eq (a, b)
maybe_lt (a, b) == maybe_gt (b, a)
maybe_le (a, b) == maybe_ge (b, a)

However:

maybe_le (a, b) && maybe_le (b, a) does not imply !maybe_ne (a, b) [== known_eq (a, b)]
maybe_ge (a, b) && maybe_ge (b, a) does not imply !maybe_ne (a, b) [== known_eq (a, b)]

One example is again ‘a == 3 + 4x’ and ‘b == 1 + 5x’, where ‘maybe_le (a, b)’, ‘maybe_ge (a, b)’ and ‘maybe_ne (a, b)’ all hold. maybe_le and maybe_ge are therefore not antisymmetric and do not form a partial order.

From the above, it follows that:

• All “known” relations except known_ne are transitive.
• known_lt, known_ne and known_gt are irreflexive.
• known_le, known_eq and known_ge are reflexive.

Also:

known_lt (a, b) == known_gt (b, a)
known_le (a, b) == known_ge (b, a)
known_lt (a, b) implies !known_le (b, a) [asymmetry]
known_ge (a, b) implies !known_related (b, a)
known_le (a, b) && known_le (b, a) == known_eq (a, b) [== !maybe_ne (a, b)]
known_ge (a, b) && known_ge (b, a) == known_eq (a, b) [== !maybe_ne (a, b)]

known_le and known_ge are therefore antisymmetric and are partial orders. However:

known_le (a, b) does not imply known_lt (a, b) || known_eq (a, b)
known_ge (a, b) does not imply known_gt (a, b) || known_eq (a, b)

For example, ‘known_le (4, 4 + 4x)’ holds because the runtime indeterminate x is a nonnegative integer, but neither known_lt (4, 4 + 4x) nor known_eq (4, 4 + 4x) hold.

Comparing potentially-unordered poly_ints

In cases where there is no definite link between two poly_ints, we can usually make a conservatively-correct assumption. For example, the conservative assumption for alias analysis is that two references might alias.

One way of checking whether [begin1, end1) might overlap [begin2, end2) using the poly_int comparisons is:
maybe_gt (end1, begin2) && maybe_gt (end2, begin1)

and another (equivalent) way is:

!(known_le (end1, begin2) || known_le (end2, begin1))

However, in this particular example, it is better to use the range helper functions instead. See Section 10.3.6 [Range checks on poly_ints], page 156.

10.3.4 Comparing ordered poly_ints

In cases where there is a definite link between two poly_ints, such as the outer and inner sizes of subregs, we usually require the sizes to be ordered by the known_le partial order. poly_int provides the following utility functions for ordered values:

'ordered_p (a, b)'
Return true if a and b are ordered by the known_le partial order.

'ordered_min (a, b)'
Assert that a and b are ordered by known_le and return the minimum of the two. When using this function, please add a comment explaining why the values are known to be ordered.

'ordered_max (a, b)'
Assert that a and b are ordered by known_le and return the maximum of the two. When using this function, please add a comment explaining why the values are known to be ordered.

For example, if a subreg has an outer mode of size outer and an inner mode of size inner:

- the subreg is complete if known_eq (inner, outer)
- otherwise, the subreg is paradoxical if known_le (inner, outer)
- otherwise, the subreg is partial if known_le (outer, inner)
- otherwise, the subreg is ill-formed

Thus the subreg is only valid if 'ordered_p (outer, inner)' is true. If this condition is already known to be true then:

- the subreg is complete if known_eq (inner, outer)
- the subreg is paradoxical if maybe_lt (inner, outer)
- the subreg is partial if maybe_lt (outer, inner)

with the three conditions being mutually exclusive.

Code that checks whether a subreg is valid would therefore generally check whether ordered_p holds (in addition to whatever other checks are required for subreg validity). Code that is dealing with existing subregs can assert that ordered_p holds and use either of the classifications above.

10.3.5 Checking for a poly_int marker value

It is sometimes useful to have a special “marker value” that is not meant to be taken literally. For example, some code uses a size of -1 to represent an unknown size, rather than having to carry around a separate boolean to say whether the size is known.

The best way of checking whether something is a marker value is known_eq. Conversely the best way of checking whether something is not a marker value is maybe_ne.
Thus in the size example just mentioned, \texttt{known_eq (size, -1)} would check for an unknown size and \texttt{maybe_ne (size, -1)} would check for a known size.

### 10.3.6 Range checks on poly_ints

As well as the core comparisons (see Section 10.3.1 [Comparison functions for poly_int], page 153), \texttt{poly_int} provides utilities for various kinds of range check. In each case the range is represented by a start position and a size rather than a start position and an end position; this is because the former is used much more often than the latter in GCC. Also, the sizes can be -1 (or all ones for unsigned sizes) to indicate a range with a known start position but an unknown size. All other sizes must be nonnegative. A range of size 0 does not contain anything or overlap anything.

\texttt{known_size_p (size)}

Return true if \texttt{size} represents a known range size, false if it is -1 or all ones (for signed and unsigned types respectively).

\texttt{ranges_maybe_overlap_p (pos1, size1, pos2, size2)}

Return true if the range described by \texttt{pos1} and \texttt{size1} might overlap the range described by \texttt{pos2} and \texttt{size2} (in other words, return true if we cannot prove that the ranges are disjoint).

\texttt{ranges_known_overlap_p (pos1, size1, pos2, size2)}

Return true if the range described by \texttt{pos1} and \texttt{size1} is known to overlap the range described by \texttt{pos2} and \texttt{size2}.

\texttt{known_subrange_p (pos1, size1, pos2, size2)}

Return true if the range described by \texttt{pos1} and \texttt{size1} is known to be contained in the range described by \texttt{pos2} and \texttt{size2}.

\texttt{maybe_in_range_p (value, pos, size)}

Return true if \texttt{value} might be in the range described by \texttt{pos} and \texttt{size} (in other words, return true if we cannot prove that \texttt{value} is outside that range).

\texttt{known_in_range_p (value, pos, size)}

Return true if \texttt{value} is known to be in the range described by \texttt{pos} and \texttt{size}.

\texttt{endpoint_representable_p (pos, size)}

Return true if the range described by \texttt{pos} and \texttt{size} is open-ended or if the endpoint (\texttt{pos + size}) is representable in the same type as \texttt{pos} and \texttt{size}. The function returns false if adding \texttt{size} to \texttt{pos} makes conceptual sense but could overflow.

There is also a \texttt{poly_int} version of the \texttt{IN_RANGE_P} macro:

\texttt{coeffs_in_range_p (x, lower, upper)}

Return true if every coefficient of \texttt{x} is in the inclusive range [\texttt{lower}, \texttt{upper}]. This function can be useful when testing whether an operation would cause the values of coefficients to overflow.

Note that the function does not indicate whether \texttt{x} itself is in the given range. \texttt{x} can be either a constant or a \texttt{poly_int}.
10.3.7 Sorting poly_ints

poly_int provides the following routine for sorting:

'compare_sizes_for_sort (a, b)'

Compare a and b in reverse lexicographical order (that is, compare the highest-indexed coefficients first). This can be useful when sorting data structures, since it has the effect of separating constant and non-constant values. If all values are nonnegative, the constant values come first.

Note that the values do not necessarily end up in numerical order. For example, ‘1 + 1x’ would come after ‘100’ in the sort order, but may well be less than ‘100’ at run time.

10.4 Arithmetic on poly_ints

Addition, subtraction, negation and bit inversion all work normally for poly_ints. Multiplication by a constant multiplier and left shifting by a constant shift amount also work normally. General multiplication of two poly_ints is not supported and is not useful in practice.

Other operations are only conditionally supported: the operation might succeed or might fail, depending on the inputs.

This section describes both types of operation.

10.4.1 Using poly_int with C++ arithmetic operators

The following C++ expressions are supported, where p1 and p2 are poly_ints and where c1 and c2 are scalars:

- p1
- p1

p1 + p2
p1 + c2
c1 + p2

p1 - p2
p1 - c2
c1 - p2

c1 * p2
p1 * c2

p1 << c2

p1 += p2
p1 += c2

p1 -= p2
p1 -= c2

p1 *= c2
p1 <<= c2

These arithmetic operations handle integer ranks in a similar way to C++. The main difference is that every coefficient narrower than HOST_WIDE_INT promotes to HOST_WIDE_INT, whereas in C++ everything narrower than int promotes to int. For example:
poly_uint16 + int -> poly_int64
unsigned int + poly_uint16 -> poly_int64
poly_int64 + int -> poly_int64
poly_int32 + poly_uint64 -> poly_uint64
uint64 + poly_int64 -> poly_uint64
poly_offset_int + int32 -> poly_offset_int
offset_int + poly_uint16 -> poly_offset_int

In the first two examples, both coefficients are narrower than HOST_WIDE_INT, so the result has coefficients of type HOST_WIDE_INT. In the other examples, the coefficient with the highest rank “wins”.

If one of the operands is wide_int or poly_wide_int, the rules are the same as for wide_int arithmetic.

10.4.2 wi arithmetic on poly_ints
As well as the C++ operators, poly_int supports the following wi routines:

   wi::neg (p1, &overflow)
   wi::add (p1, p2)
   wi::add (p1, c2)
   wi::add (c1, p1)
   wi::add (p1, p2, sign, &overflow)
   wi::sub (p1, p2)
   wi::sub (p1, c2)
   wi::sub (c1, p1)
   wi::sub (p1, p2, sign, &overflow)
   wi::mul (p1, c2)
   wi::mul (c1, p1)
   wi::mul (p1, c2, sign, &overflow)
   wi::lshift (p1, c2)

These routines just check whether overflow occurs on any individual coefficient; it is not possible to know at compile time whether the final runtime value would overflow.

10.4.3 Division of poly_ints
Division of poly_ints is possible for certain inputs. The functions for division return true if the operation is possible and in most cases return the results by pointer. The routines are:

'multiple_p (a, b)'
'multiple_p (a, b, &quotient)'
   Return true if a is an exact multiple of b, storing the result in quotient if so.
   There are overloads for various combinations of polynomial and constant a, b
   and quotient.

'constant_multiple_p (a, b)'
'constant_multiple_p (a, b, &quotient)'
   Like multiple_p, but also test whether the multiple is a compile-time constant.
can_div_trunc_p (a, b, &quotient)
can_div_trunc_p (a, b, &quotient, &remainder)

Return true if we can calculate \( \text{trunc} \left( \frac{a}{b} \right) \) at compile time, storing the result in \( \text{quotient} \) and \( \text{remainder} \) if so.

can_div_away_from_zero_p (a, b, &quotient)

Return true if we can calculate \( \frac{a}{b} \) at compile time, rounding away from zero. Store the result in \( \text{quotient} \) if so.

Note that this is true if and only if can_div_trunc_p is true. The only difference is in the rounding of the result.

There is also an asserting form of division:

exact_div (a, b)

Assert that \( a \) is a multiple of \( b \) and return \( \frac{a}{b} \). The result is a poly_int if \( a \) is a poly_int.

10.4.4 Other poly_int arithmetic

There are tentative routines for other operations besides division:

can_ior_p (a, b, &result)

Return true if we can calculate \( a \mid b \) at compile time, storing the result in \( \text{result} \) if so.

Also, ANDs with a value \( (1 << y) - 1 \) or its inverse can be treated as alignment operations. See Section 10.5 [Alignment of poly_ints], page 159.

In addition, the following miscellaneous routines are available:

coeff_gcd (a)

Return the greatest common divisor of all nonzero coefficients in \( a \), or zero if \( a \) is known to be zero.

common_multiple (a, b)

Return a value that is a multiple of both \( a \) and \( b \), where one value is a poly_int and the other is a scalar. The result will be the least common multiple for some indeterminate values but not necessarily for all.

force_common_multiple (a, b)

Return a value that is a multiple of both poly_int \( a \) and poly_int \( b \), asserting that such a value exists. The result will be the least common multiple for some indeterminate values but not necessarily for all.

When using this routine, please add a comment explaining why the assertion is known to hold.

Please add any other operations that you find to be useful.

10.5 Alignment of poly_ints

poly_int provides various routines for aligning values and for querying misalignments. In each case the alignment must be a power of 2.
Return true if we can align \texttt{value} up or down to the nearest multiple of \texttt{align} at compile time. The answer is the same for both directions.

Return true if \texttt{can_align_p}; if so, set \texttt{aligned} to the greatest aligned value that is less than or equal to \texttt{value}.

Return true if \texttt{can_align_p}; if so, set \texttt{aligned} to the lowest aligned value that is greater than or equal to \texttt{value}.

Return true if we can align \texttt{a} and \texttt{b} down to the nearest \texttt{align} boundary at compile time and if the two results are equal.

Return true if we can align \texttt{a} and \texttt{b} up to the nearest \texttt{align} boundary at compile time and if the two results are equal.

Return a result that is no greater than \texttt{value} and that is aligned to \texttt{align}. The result will the closest aligned value for some indeterminate values but not necessarily for all.

For example, suppose we are allocating an object of \texttt{size} bytes in a downward-growing stack whose current limit is given by \texttt{limit}. If the object requires \texttt{align} bytes of alignment, the new stack limit is given by:

\begin{verbatim}
aligned_lower_bound (limit - size, align)
\end{verbatim}

Likewise return a result that is no less than \texttt{value} and that is aligned to \texttt{align}. This is the routine that would be used for upward-growing stacks in the scenario just described.

Return true if we can calculate the misalignment of \texttt{value} with respect to \texttt{align} at compile time, storing the result in \texttt{misalign} if so.

Return the minimum alignment that \texttt{value} is known to have (in other words, the largest alignment that can be guaranteed whatever the values of the indeterminates turn out to be). Return 0 if \texttt{value} is known to be 0.

Assert that \texttt{value} can be aligned down to \texttt{align} at compile time and return the result. When using this routine, please add a comment explaining why the assertion is known to hold.

Likewise, but aligning up.

Divide the result of \texttt{force_align_down} by \texttt{align}. Again, please add a comment explaining why the assertion in \texttt{force_align_down} is known to hold.
force_align_up_and_div (value, align)
Likewise for force_align_up.

force_get_misalignment (value, align)
Assert that we can calculate the misalignment of value with respect to align at compile time and return the misalignment. When using this function, please add a comment explaining why the assertion is known to hold.

10.6 Computing bounds on poly_ints
poly_int also provides routines for calculating lower and upper bounds:

constant_lower_bound (a)
Assert that a is nonnegative and return the smallest value it can have.

constant_lower_bound_with_limit (a, b)
Return the least value a can have, given that the context in which a appears guarantees that the answer is no less than b. In other words, the caller is asserting that a is greater than or equal to b even if known_ge (a, b) doesn’t hold.

constant_upper_bound_with_limit (a, b)
Return the greatest value a can have, given that the context in which a appears guarantees that the answer is no greater than b. In other words, the caller is asserting that a is less than or equal to b even if known_le (a, b) doesn’t hold.

lower_bound (a, b)
Return a value that is always less than or equal to both a and b. It will be the greatest such value for some indeterminate values but necessarily for all.

upper_bound (a, b)
Return a value that is always greater than or equal to both a and b. It will be the least such value for some indeterminate values but necessarily for all.

10.7 Converting poly_ints
A poly_int<n, T> can be constructed from up to n individual T coefficients, with the remaining coefficients being implicitly zero. In particular, this means that every poly_int<n, T> can be constructed from a single scalar T, or something compatible with T.

Also, a poly_int<n, T> can be constructed from a poly_int<n, U> if T can be constructed from U.

The following functions provide other forms of conversion, or test whether such a conversion would succeed.

value.is_constant ()
Return true if poly_int value is a compile-time constant.

value.is_constant (&c1)
Return true if poly_int value is a compile-time constant, storing it in c1 if so. c1 must be able to hold all constant values of value without loss of precision.
'value.to_constant ()'
Assert that value is a compile-time constant and return its value. When using this function, please add a comment explaining why the condition is known to hold (for example, because an earlier phase of analysis rejected non-constants).

'value.to_shwi (&p2)'
Return true if 'poly_int<N, T>' value can be represented without loss of precision as a 'poly_int<N, HOST_WIDE_INT>', storing it in that form in p2 if so.

'value.to_uhwi (&p2)'
Return true if 'poly_int<N, T>' value can be represented without loss of precision as a 'poly_int<N, unsigned HOST_WIDE_INT>', storing it in that form in p2 if so.

'value.force_shwi ()'
Forcibly convert each coefficient of 'poly_int<N, T>' value to HOST_WIDE_INT, truncating any that are out of range. Return the result as a 'poly_int<N, HOST_WIDE_INT>'.

'value.force_uhwi ()'
Forcibly convert each coefficient of 'poly_int<N, T>' value to unsigned HOST_WIDE_INT, truncating any that are out of range. Return the result as a 'poly_int<N, unsigned HOST_WIDE_INT>'.

'wi::shwi (value, precision)'
Return a poly_int with the same value as value, but with the coefficients converted from HOST_WIDE_INT to wide_int. precision specifies the precision of the wide_int coefficients; if this is wider than a HOST_WIDE_INT, the coefficients of value will be sign-extended to fit.

'wi::uhwi (value, precision)'
Like wi::shwi, except that value has coefficients of type unsigned HOST_WIDE_INT. If precision is wider than a HOST_WIDE_INT, the coefficients of value will be zero-extended to fit.

'wi::sext (value, precision)'
Return a poly_int of the same type as value, sign-extending every coefficient from the low precision bits. This in effect applies wi::sext to each coefficient individually.

'wi::zext (value, precision)'
Like wi::sext, but for zero extension.

'poly_wide_int::from (value, precision, sign)'
Convert value to a poly_wide_int in which each coefficient has precision bits. Extend the coefficients according to sign if the coefficients have fewer bits.

'poly_offset_int::from (value, sign)'
Convert value to a poly_offset_int, extending its coefficients according to sign if they have fewer bits than offset_int.

'poly_widest_int::from (value, sign)'
Convert value to a poly_widest_int, extending its coefficients according to sign if they have fewer bits than widest_int.
10.8 Miscellaneous poly_int routines

`print_dec (value, file, sign)`
`print_dec (value, file)`

Print value to file as a decimal value, interpreting the coefficients according to sign. The final argument is optional if value has an inherent sign; for example, poly_int64 values print as signed by default and poly_uint64 values print as unsigned by default.

This is a simply a poly_int version of a wide-int routine.

10.9 Guidelines for using poly_int

One of the main design goals of poly_int was to make it easy to write target-independent code that handles variable-sized registers even when the current target has fixed-sized registers. There are two aspects to this:

- The set of poly_int operations should be complete enough that the question in most cases becomes “Can we do this operation on these particular poly_int values? If not, bail out” rather than “Are these poly_int values constant? If so, do the operation, otherwise bail out”.

- If target-independent code compiles and runs correctly on a target with one value of NUM_POLY_INT_COEFFS, and if the code does not use asserting functions like to_constant, it is reasonable to assume that the code also works on targets with other values of NUM_POLY_INT_COEFFS. There is no need to check this during everyday development.

So the general principle is: if target-independent code is dealing with a poly_int value, it is better to operate on it as a poly_int if at all possible, choosing conservatively-correct behavior if a particular operation fails. For example, the following code handles an index pos into a sequence of vectors that each have nunits elements:

```c
/* Calculate which vector contains the result, and which lane of that vector we need. */
if (!can_div_trunc_p (pos, nunits, &vec_entry, &vec_index))
{
  if (dump_enabled_p ())
    dump_printf_loc (MSG_MISSED_OPTIMIZATION, vect_location,
                     "Cannot determine which vector holds the"
                     " final result.\n");
  return false;
}
```

However, there are some contexts in which operating on a poly_int is not possible or does not make sense. One example is when handling static initializers, since no current target supports the concept of a variable-length static initializer. In these situations, a reasonable fallback is:

```c
if (poly_value.is_constant (&const_value))
{
  ...
  /* Operate on const_value. */
  ...
}
else
```
poly_int also provides some asserting functions like to_constant. Please only use these functions if there is a good theoretical reason to believe that the assertion cannot fire. For example, if some work is divided into an analysis phase and an implementation phase, the analysis phase might reject inputs that are not is_constant, in which case the implementation phase can reasonably use to_constant on the remaining inputs. The assertions should not be used to discover whether a condition ever occurs “in the field”; in other words, they should not be used to restrict code to constants at first, with the intention of only implementing a poly_int version if a user hits the assertion.

If a particular asserting function like to_constant is needed more than once for the same reason, it is probably worth adding a helper function or macro for that situation, so that the justification only needs to be given once. For example:

```c
/* Return the size of an element in a vector of size SIZE, given that
the vector has NELTS elements. The return value is in the same units
as SIZE (either bits or bytes).

to_constant () is safe in this situation because vector elements are
always constant-sized scalars. */
#define vector_element_size(SIZE, NELTS) \
(exact_div (SIZE, NELTS).to_constant ()
```

Target-specific code in ‘config/cpu’ only needs to handle non-constant poly_ints if NUM_POLY_INT_COEFFS is greater than one. For other targets, poly_int degenerates to a compile-time constant and is often interchangeable with a normal scalar integer. There are two main exceptions:

- Sometimes an explicit cast to an integer type might be needed, such as to resolve ambiguities in a ?: expression, or when passing values through ... to things like print functions.
- Target macros are included in target-independent code and so do not have access to the implicit conversion to a scalar integer. If this becomes a problem for a particular target macro, the possible solutions, in order of preference, are:
  - Convert the target macro to a target hook (for all targets).
  - Put the target’s implementation of the target macro in its ‘cpu.c’ file and call it from the target macro in the ‘cpu.h’ file.
  - Add to_constant () calls where necessary. The previous option is preferable because it will help with any future conversion of the macro to a hook.
Chapter 11: GENERIC

11 GENERIC

The purpose of GENERIC is simply to provide a language-independent way of representing an entire function in trees. To this end, it was necessary to add a few new tree codes to the back end, but almost everything was already there. If you can express it with the codes in gcc/tree.def, it's GENERIC.

Early on, there was a great deal of debate about how to think about statements in a tree IL. In GENERIC, a statement is defined as any expression whose value, if any, is ignored. A statement will always have TREE_SIDE_EFFECTS set (or it will be discarded), but a non-statement expression may also have side effects. A CALL_EXPR, for instance.

It would be possible for some local optimizations to work on the GENERIC form of a function; indeed, the adapted tree inliner works fine on GENERIC, but the current compiler performs inlining after lowering to GIMPLE (a restricted form described in the next section). Indeed, currently the frontends perform this lowering before handing off to tree_rest_of_compilation, but this seems inelegant.

11.1 Deficiencies

There are many places in which this document is incomplet and incorrect. It is, as of yet, only preliminary documentation.

11.2 Overview

The central data structure used by the internal representation is the tree. These nodes, while all of the C type tree, are of many varieties. A tree is a pointer type, but the object to which it points may be of a variety of types. From this point forward, we will refer to trees in ordinary type, rather than in this font, except when talking about the actual C type tree.

You can tell what kind of node a particular tree is by using the TREE_CODE macro. Many, many macros take trees as input and return trees as output. However, most macros require a certain kind of tree node as input. In other words, there is a type-system for trees, but it is not reflected in the C type-system.

For safety, it is useful to configure GCC with ‘--enable-checking’. Although this results in a significant performance penalty (since all tree types are checked at run-time), and is therefore inappropriate in a release version, it is extremely helpful during the development process.

Many macros behave as predicates. Many, although not all, of these predicates end in ‘_P’. Do not rely on the result type of these macros being of any particular type. You may, however, rely on the fact that the type can be compared to 0, so that statements like

\[
\text{if (TEST_P (t) \&\& !TEST_P (y))}
\]

\[
\text{x = 1;}
\]

and

\[
\text{int i = (TEST_P (t) != 0);}
\]

are legal. Macros that return int values now may be changed to return tree values, or other pointers in the future. Even those that continue to return int may return multiple nonzero codes where previously they returned only zero and one. Therefore, you should not write code like
if (TEST_P (t) == 1)
as this code is not guaranteed to work correctly in the future.

You should not take the address of values returned by the macros or functions described
here. In particular, no guarantee is given that the values are lvalues.

In general, the names of macros are all in uppercase, while the names of functions are
entirely in lowercase. There are rare exceptions to this rule. You should assume that any
macro or function whose name is made up entirely of uppercase letters may evaluate its
arguments more than once. You may assume that a macro or function whose name is made
up entirely of lowercase letters will evaluate its arguments only once.

The error_mark_node is a special tree. Its tree code is ERROR_MARK, but since there is
only ever one node with that code, the usual practice is to compare the tree against error_-
mark_node. (This test is just a test for pointer equality.) If an error has occurred during
front-end processing the flag errorcount will be set. If the front end has encountered code
it cannot handle, it will issue a message to the user and set sorrycount. When these
flags are set, any macro or function which normally returns a tree of a particular kind may
instead return the error_mark_node. Thus, if you intend to do any processing of erroneous
code, you must be prepared to deal with the error_mark_node.

Occasionally, a particular tree slot (like an operand to an expression, or a particular field
in a declaration) will be referred to as “reserved for the back end”. These slots are used to
store RTL when the tree is converted to RTL for use by the GCC back end. However, if
that process is not taking place (e.g., if the front end is being hooked up to an intelligent
editor), then those slots may be used by the back end presently in use.

If you encounter situations that do not match this documentation, such as tree nodes of
types not mentioned here, or macros documented to return entities of a particular kind that
instead return entities of some different kind, you have found a bug, either in the front end
or in the documentation. Please report these bugs as you would any other bug.

11.2.1 Trees

All GENERIC trees have two fields in common. First, TREE_CHAIN is a pointer that can be
used as a singly-linked list to other trees. The other is TREE_TYPE. Many trees store the
type of an expression or declaration in this field.

These are some other functions for handling trees:

tree_size

Return the number of bytes a tree takes.

build0
build1
build2
build3
build4
build5
build6

These functions build a tree and supply values to put in each parameter. The
basic signature is `code, type, [operands]`. code is the TREE_CODE, and type
is a tree representing the TREE_TYPE. These are followed by the operands, each
of which is also a tree.
11.2.2 Identifiers

An IDENTIFIER_NODE represents a slightly more general concept than the standard C or C++ concept of identifier. In particular, an IDENTIFIER_NODE may contain a ‘$’, or other extraordinary characters.

There are never two distinct IDENTIFIER_NODEs representing the same identifier. Therefore, you may use pointer equality to compare IDENTIFIER_NODEs, rather than using a routine like strcmp. Use get_identifier to obtain the unique IDENTIFIER_NODE for a supplied string.

You can use the following macros to access identifiers:

IDENTIFIER_POINTER
The string represented by the identifier, represented as a char*. This string is always NUL-terminated, and contains no embedded NUL characters.

IDENTIFIER_LENGTH
The length of the string returned by IDENTIFIER_POINTER, not including the trailing NUL. This value of IDENTIFIER_LENGTH (x) is always the same as strlen (IDENTIFIER_POINTER (x)).

IDENTIFIER_OPNAME_P
This predicate holds if the identifier represents the name of an overloaded operator. In this case, you should not depend on the contents of either the IDENTIFIER_POINTER or the IDENTIFIER_LENGTH.

IDENTIFIER_TYPENAME_P
This predicate holds if the identifier represents the name of a user-defined conversion operator. In this case, the TREE_TYPE of the IDENTIFIER_NODE holds the type to which the conversion operator converts.

11.2.3 Containers

Two common container data structures can be represented directly with tree nodes. A TREE_LIST is a singly linked list containing two trees per node. These are the TREE_PURPOSE and TREE_VALUE of each node. (Often, the TREE_PURPOSE contains some kind of tag, or additional information, while the TREE_VALUE contains the majority of the payload. In other cases, the TREE_PURPOSE is simply NULL_TREE, while in still others both the TREE_PURPOSE and TREE_VALUE are of equal stature.) Given one TREE_LIST node, the next node is found by following the TREE_CHAIN. If the TREE_CHAIN is NULL_TREE, then you have reached the end of the list.

A TREE_VEC is a simple vector. The TREE_VEC_LENGTH is an integer (not a tree) giving the number of nodes in the vector. The nodes themselves are accessed using the TREE_VEC_ELT macro, which takes two arguments. The first is the TREE_VEC in question; the second is an integer indicating which element in the vector is desired. The elements are indexed from zero.

11.3 Types

All types have corresponding tree nodes. However, you should not assume that there is exactly one tree node corresponding to each type. There are often multiple nodes corresponding to the same type.
For the most part, different kinds of types have different tree codes. (For example, pointer types use a \texttt{POINTER\_TYPE} code while arrays use an \texttt{ARRAY\_TYPE} code.) However, pointers to member functions use the \texttt{RECORD\_TYPE} code. Therefore, when writing a \texttt{switch} statement that depends on the code associated with a particular type, you should take care to handle pointers to member functions under the \texttt{RECORD\_TYPE} case label.

The following functions and macros deal with cv-qualification of types:

\textbf{\texttt{TYPE\_MAIN\_VARIANT}}

This macro returns the unqualified version of a type. It may be applied to an unqualified type, but it is not always the identity function in that case.

A few other macros and functions are usable with all types:

\textbf{\texttt{TYPE\_SIZE}}

The number of bits required to represent the type, represented as an \texttt{INTEGER\_CST}. For an incomplete type, \texttt{TYPE\_SIZE} will be \texttt{NULL\_TREE}.

\textbf{\texttt{TYPE\_ALIGN}}

The alignment of the type, in bits, represented as an \texttt{int}.

\textbf{\texttt{TYPE\_NAME}}

This macro returns a declaration (in the form of a \texttt{TYPE\_DECL}) for the type. (Note this macro does \textit{not} return an \texttt{IDENTIFIER\_NODE}, as you might expect, given its name!) You can look at the \texttt{DECL\_NAME} of the \texttt{TYPE\_DECL} to obtain the actual name of the type. The \texttt{TYPE\_NAME} will be \texttt{NULL\_TREE} for a type that is not a built-in type, the result of a typedef, or a named class type.

\textbf{\texttt{TYPE\_CANONICAL}}

This macro returns the “canonical” type for the given type node. Canonical types are used to improve performance in the C++ and Objective-C++ front ends by allowing efficient comparison between two type nodes in \texttt{same\_type\_p}: if the \texttt{TYPE\_CANONICAL} values of the types are equal, the types are equivalent; otherwise, the types are not equivalent. The notion of equivalence for canonical types is the same as the notion of type equivalence in the language itself. For instance,

When \texttt{TYPE\_CANONICAL} is \texttt{NULL\_TREE}, there is no canonical type for the given type node. In this case, comparison between this type and any other type requires the compiler to perform a deep, “structural” comparison to see if the two type nodes have the same form and properties.

The canonical type for a node is always the most fundamental type in the equivalence class of types. For instance, \texttt{int} is its own canonical type. A typedef \texttt{I} of \texttt{int} will have \texttt{int} as its canonical type. Similarly, \texttt{I*} and a typedef \texttt{IP} (defined to \texttt{I*}) will have \texttt{int*} as their canonical type. When building a new type node, be sure to set \texttt{TYPE\_CANONICAL} to the appropriate canonical type. If the new type is a compound type (built from other types), and any of those other types require structural equality, use \texttt{SET\_TYPE\_STRUCTURAL\_EQUALITY} to ensure that the new type also requires structural equality. Finally, if for some reason you cannot guarantee that \texttt{TYPE\_CANONICAL} will point to the canonical type, use \texttt{SET\_TYPE\_STRUCTURAL\_EQUALITY} to make sure that the new type—and any type constructed based on it—requires structural equality. If you suspect
that the canonical type system is miscomparing types, pass --param verify-canonical-types=1 to the compiler or configure with --enable-checking to force the compiler to verify its canonical-type comparisons against the structural comparisons; the compiler will then print any warnings if the canonical types miscompare.

**TYPE_STRUCTURAL_EQUALITY_P**

This predicate holds when the node requires structural equality checks, e.g., when TYPE_CANONICAL is NULL_TREE.

**SET_TYPE_STRUCTURAL_EQUALITY**

This macro states that the type node it is given requires structural equality checks, e.g., it sets TYPE_CANONICAL to NULL_TREE.

**same_type_p**

This predicate takes two types as input, and holds if they are the same type. For example, if one type is a typedef for the other, or both are typedefs for the same type. This predicate also holds if the two trees given as input are simply copies of one another; i.e., there is no difference between them at the source level, but, for whatever reason, a duplicate has been made in the representation. You should never use == (pointer equality) to compare types; always use same_type_p instead.

Detailed below are the various kinds of types, and the macros that can be used to access them. Although other kinds of types are used elsewhere in G++, the types described here are the only ones that you will encounter while examining the intermediate representation.

**VOID_TYPE**

Used to represent the void type.

**INTEGER_TYPE**

Used to represent the various integral types, including char, short, int, long, and long long. This code is not used for enumeration types, nor for the bool type. The TYPE_PRECISION is the number of bits used in the representation, represented as an unsigned int. (Note that in the general case this is not the same value as TYPE_SIZE; suppose that there were a 24-bit integer type, but that alignment requirements for the ABI required 32-bit alignment. Then, TYPE_SIZE would be an INTEGER_CST for 32, while TYPE_PRECISION would be 24.) The integer type is unsigned if TYPE_UNSIGNED holds; otherwise, it is signed.

The TYPE_MIN_VALUE is an INTEGER_CST for the smallest integer that may be represented by this type. Similarly, the TYPE_MAX_VALUE is an INTEGER_CST for the largest integer that may be represented by this type.

**REAL_TYPE**

Used to represent the float, double, and long double types. The number of bits in the floating-point representation is given by TYPE_PRECISION, as in the INTEGER_TYPE case.

**FIXED_POINT_TYPE**

Used to represent the short _Fract, _Fract, long _Fract, _Fract, long long _Fract, short _Accum, _Accum, _Accum, long _Accum, and long long _Accum types. The num-
ber of bits in the fixed-point representation is given by \texttt{TYPE\_PRECISION}, as in the \texttt{INTEGER\_TYPE} case. There may be padding bits, fractional bits and integral bits. The number of fractional bits is given by \texttt{TYPE\_FBIT}, and the number of integral bits is given by \texttt{TYPE\_IBIT}. The fixed-point type is unsigned if \texttt{TYPE\_UNSIGNED} holds; otherwise, it is signed. The fixed-point type is saturating if \texttt{TYPE\_SATURATING} holds; otherwise, it is not saturating.

\textbf{COMPLEX\_TYPE}

Used to represent GCC built-in \texttt{__complex__} data types. The \texttt{TREE\_TYPE} is the type of the real and imaginary parts.

\textbf{ENUMERAL\_TYPE}

Used to represent an enumeration type. The \texttt{TYPE\_PRECISION} gives (as an \texttt{int}), the number of bits used to represent the type. If there are no negative enumeration constants, \texttt{TYPE\_UNSIGNED} will hold. The minimum and maximum enumeration constants may be obtained with \texttt{TYPE\_MIN\_VALUE} and \texttt{TYPE\_MAX\_VALUE}, respectively; each of these macros returns an \texttt{INTEGER\_CST}.

The actual enumeration constants themselves may be obtained by looking at the \texttt{TYPE\_VALUES}. This macro will return a \texttt{TREE\_LIST}, containing the constants. The \texttt{TREE\_PURPOSE} of each node will be an \texttt{IDENTIFIER\_NODE} giving the name of the constant; the \texttt{TREE\_VALUE} will be an \texttt{INTEGER\_CST} giving the value assigned to that constant. These constants will appear in the order in which they were declared. The \texttt{TREE\_TYPE} of each of these constants will be the type of enumeration type itself.

\textbf{OPAQUE\_TYPE}

Used for things that have a \texttt{MODE\_OPAQUE} mode class in the backend. Opaque types have a size and precision, and can be held in memory or registers. They are used when we do not want the compiler to make assumptions about the availability of other operations as would happen with integer types.

\textbf{BOOLEAN\_TYPE}

Used to represent the \texttt{bool} type.

\textbf{POINTER\_TYPE}

Used to represent pointer types, and pointer to data member types. The \texttt{TREE\_TYPE} gives the type to which this type points.

\textbf{REFERENCE\_TYPE}

Used to represent reference types. The \texttt{TREE\_TYPE} gives the type to which this type refers.

\textbf{FUNCTION\_TYPE}

Used to represent the type of non-member functions and of static member functions. The \texttt{TREE\_TYPE} gives the return type of the function. The \texttt{TYPE\_ARG\_TYPES} are a \texttt{TREE\_LIST} of the argument types. The \texttt{TREE\_VALUE} of each node in this list is the type of the corresponding argument; the \texttt{TREE\_PURPOSE} is an expression for the default argument value, if any. If the last node in the list is \texttt{void\_list\_node} (a \texttt{TREE\_LIST} node whose \texttt{TREE\_VALUE} is the \texttt{void\_type\_node}), then functions of this type do not take variable arguments. Otherwise, they do take a variable number of arguments.
Note that in C (but not in C++) a function declared like `void f()` is an unpro-totyped function taking a variable number of arguments; the `TYPE_ARG_TYPES` of such a function will be `NULL`.

**METHOD_TYPE**

Used to represent the type of a non-static member function. Like a `FUNCTION_TYPE`, the return type is given by the `TREE_TYPE`. The type of `*this`, i.e., the class of which functions of this type are a member, is given by the `TYPE_METHOD_BASETYPE`. The `TYPE_ARG_TYPES` is the parameter list, as for a `FUNCTION_TYPE`, and includes the `this` argument.

**ARRAY_TYPE**

Used to represent array types. The `TREE_TYPE` gives the type of the elements in the array. If the array-bound is present in the type, the `TYPE_DOMAIN` is an `INTEGER_TYPE` whose `TYPE_MIN_VALUE` and `TYPE_MAX_VALUE` will be the lower and upper bounds of the array, respectively. The `TYPE_MIN_VALUE` will always be an `INTEGER_CST` for zero, while the `TYPE_MAX_VALUE` will be one less than the number of elements in the array, i.e., the highest value which may be used to index an element in the array.

**RECORD_TYPE**

Used to represent `struct` and `class` types, as well as pointers to member functions and similar constructs in other languages. `TYPE_FIELDS` contains the items contained in this type, each of which can be a `FIELD_DECL`, `VAR_DECL`, `CONST_DECL`, or `TYPE_DECL`. You may not make any assumptions about the ordering of the fields in the type or whether one or more of them overlap.

**UNION_TYPE**

Used to represent `union` types. Similar to `RECORD_TYPE` except that all `FIELD_DECL` nodes in `TYPE_FIELD` start at bit position zero.

**QUAL_UNION_TYPE**

Used to represent part of a variant record in Ada. Similar to `UNION_TYPE` except that each `FIELD_DECL` has a `DECL_QUALIFIER` field, which contains a boolean expression that indicates whether the field is present in the object. The type will only have one field, so each field’s `DECL_QUALIFIER` is only evaluated if none of the expressions in the previous fields in `TYPE_FIELDS` are nonzero. Normally these expressions will reference a field in the outer object using a `PLACEHOLDER_EXPR`.

**LANG_TYPE**

This node is used to represent a language-specific type. The front end must handle it.

**OFFSET_TYPE**

This node is used to represent a pointer-to-data member. For a data member `X::m` the `TYPE_OFFSET_BASETYPE` is `X` and the `TREE_TYPE` is the type of `m`.

There are variables whose values represent some of the basic types. These include:

**void_type_node**

A node for `void`. 
integer_type_node
   A node for int.

unsigned_type_node.
   A node for unsigned int.

char_type_node.
   A node for char.

It may sometimes be useful to compare one of these variables with a type in hand, using`same_type_p`.

11.4 Declarations

This section covers the various kinds of declarations that appear in the internal representation, except for declarations of functions (represented by `FUNCTION_DECL` nodes), which are described in Section 11.8 [Functions], page 197.

11.4.1 Working with declarations

Some macros can be used with any kind of declaration. These include:

DECL_NAME
   This macro returns an IDENTIFIER_NODE giving the name of the entity.

TREE_TYPE
   This macro returns the type of the entity declared.

EXPR_FILENAME
   This macro returns the name of the file in which the entity was declared, as a char*. For an entity declared implicitly by the compiler (like `__builtin_memcpy`), this will be the string "<internal>".

EXPR_LINENO
   This macro returns the line number at which the entity was declared, as an int.

DECL_ARTIFICIAL
   This predicate holds if the declaration was implicitly generated by the compiler. For example, this predicate will hold of an implicitly declared member function, or of the `TYPE_DECL` implicitly generated for a class type. Recall that in C++ code like:
   ```
   struct S { };  
   ```
   is roughly equivalent to C code like:
   ```
   struct S { };  
   typedef struct S S;  
   ```
   The implicitly generated `typedef` declaration is represented by a `TYPE_DECL` for which `DECL_ARTIFICIAL` holds.

The various kinds of declarations include:

LABEL_DECL
   These nodes are used to represent labels in function bodies. For more information, see Section 11.8 [Functions], page 197. These nodes only appear in block scopes.
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CONST_DECL
These nodes are used to represent enumeration constants. The value of the constant is given by DECL_INITIAL which will be an INTEGER_CST with the same type as the TREE_TYPE of the CONSTDECL, i.e., an ENUMERAL_TYPE.

RESULT_DECL
These nodes represent the value returned by a function. When a value is assigned to a RESULT_DECL, that indicates that the value should be returned, via bitwise copy, by the function. You can use DECL_SIZE and DECL_ALIGN on a RESULT_DECL, just as with a VAR_DECL.

TYPE_DECL
These nodes represent typedef declarations. The TREE_TYPE is the type declared to have the name given by DECL_NAME. In some cases, there is no associated name.

VAR_DECL
These nodes represent variables with namespace or block scope, as well as static data members. The DECL_SIZE and DECL_ALIGN are analogous to TYPE_SIZE and TYPE_ALIGN. For a declaration, you should always use the DECL_SIZE and DECL_ALIGN rather than the TYPE_SIZE and TYPE_ALIGN given by the TREE_TYPE, since special attributes may have been applied to the variable to give it a particular size and alignment. You may use the predicates DECL_THIS_STATIC or DECL_THIS_EXTERN to test whether the storage class specifiers static or extern were used to declare a variable.

If this variable is initialized (but does not require a constructor), the DECL_INITIAL will be an expression for the initializer. The initializer should be evaluated, and a bitwise copy into the variable performed. If the DECL_INITIAL is the error_mark_node, there is an initializer, but it is given by an explicit statement later in the code; no bitwise copy is required.

GCC provides an extension that allows either automatic variables, or global variables, to be placed in particular registers. This extension is being used for a particular VAR_DECL if DECL_REGISTER holds for the VAR_DECL, and if DECL_ASSEMBLER_NAME is not equal to DECL_NAME. In that case, DECL_ASSEMBLER_NAME is the name of the register into which the variable will be placed.

PARM_DECL
Used to represent a parameter to a function. Treat these nodes similarly to VAR_DECL nodes. These nodes only appear in the DECL_ARGUMENTS for a FUNCTION_DECL.

The DECL_ARG_TYPE for a PARM_DECL is the type that will actually be used when a value is passed to this function. It may be a wider type than the TREE_TYPE of the parameter; for example, the ordinary type might be short while the DECL_ARG_TYPE is int.

DEBUG_EXPR_DECL
Used to represent an anonymous debug-information temporary created to hold an expression as it is optimized away, so that its value can be referenced in debug bind statements.
FIELD_DECL
These nodes represent non-static data members. The DECL_SIZE and DECLAlign behave as for VAR_DECL nodes. The position of the field within the parent record is specified by a combination of three attributes. DECL_FIELD_OFFSET is the position, counting in bytes, of the DECL_OFFSET_ALIGN-bit sized word containing the bit of the field closest to the beginning of the structure. DECL_FIELD_BIT_OFFSET is the bit offset of the first bit of the field within this word; this may be nonzero even for fields that are not bit-fields, since DECL_OFFSET_ALIGN may be greater than the natural alignment of the field’s type.
If DECL_C_BIT_FIELD holds, this field is a bit-field. In a bit-field, DECL_BIT_FIELD_TYPE also contains the type that was originally specified for it, while DECL_TYPE may be a modified type with lesser precision, according to the size of the bit field.

NAMESPACE_DECLS
Namespaces provide a name hierarchy for other declarations. They appear in the DECL_CONTEXT of other _DECL nodes.

11.4.2 Internal structure
DECL nodes are represented internally as a hierarchy of structures.

11.4.2.1 Current structure hierarchy
struct tree_decl_minimal
This is the minimal structure to inherit from in order for common DECL macros to work. The fields it contains are a unique ID, source location, context, and name.

struct tree_decl_common
This structure inherits from struct tree_decl_minimal. It contains fields that most DECL nodes need, such as a field to store alignment, machine mode, size, and attributes.

struct tree_field_decl
This structure inherits from struct tree_decl_common. It is used to represent FIELD_DECL.

struct tree_label_decl
This structure inherits from struct tree_decl_common. It is used to represent LABEL_DECL.

struct tree_translation_unit_decl
This structure inherits from struct tree_decl_common. It is used to represent TRANSLATION_UNIT_DECL.

struct tree_decl_with_rtl
This structure inherits from struct tree_decl_common. It contains a field to store the low-level RTL associated with a DECL node.

struct tree_result_decl
This structure inherits from struct tree_decl_with_rtl. It is used to represent RESULT_DECL.
struct tree_const_decl
This structure inherits from struct tree_decl_with_rtl. It is used to represent CONST_DECL.

struct tree_parm_decl
This structure inherits from struct tree_decl_with_rtl. It is used to represent PARM_DECL.

struct tree_decl_with_vis
This structure inherits from struct tree_decl_with_rtl. It contains fields necessary to store visibility information, as well as a section name and assembler name.

struct tree_var_decl
This structure inherits from struct tree_decl_with_vis. It is used to represent VAR_DECL.

struct tree_function_decl
This structure inherits from struct tree_decl_with_vis. It is used to represent FUNCTION_DECL.

11.4.2.2 Adding new DECL node types
Adding a new DECL tree consists of the following steps

Add a new tree code for the DECL node
For language specific DECL nodes, there is a ‘.def’ file in each frontend directory where the tree code should be added. For DECL nodes that are part of the middle-end, the code should be added to ‘tree.def’.

Create a new structure type for the DECL node
These structures should inherit from one of the existing structures in the language hierarchy by using that structure as the first member.

```
struct tree_foo_decl
{
    struct tree_decl_with_vis common;
}
```

Would create a structure name tree_foo_decl that inherits from struct tree_decl_with_vis.

For language specific DECL nodes, this new structure type should go in the appropriate ‘.h’ file. For DECL nodes that are part of the middle-end, the structure type should go in ‘tree.h’.

Add a member to the tree structure enumerator for the node
For garbage collection and dynamic checking purposes, each DECL node structure type is required to have a unique enumerator value specified with it. For language specific DECL nodes, this new enumerator value should go in the appropriate ‘.def’ file. For DECL nodes that are part of the middle-end, the enumerator values are specified in ‘treestruct.def’.
Update union `tree_node`
In order to make your new structure type usable, it must be added to `union tree_node`. For language specific `DECL` nodes, a new entry should be added to the appropriate `.h` file of the form

```c
struct tree_foo_decl GTY ((tag ("TS_VAR_DECL"))) foo_decl;
```

For `DECL` nodes that are part of the middle-end, the additional member goes directly into `union tree_node` in `tree.h`.

Update dynamic checking info
In order to be able to check whether accessing a named portion of `union tree_node` is legal, and whether a certain `DECL` node contains one of the enumerated `DECL` node structures in the hierarchy, a simple lookup table is used. This lookup table needs to be kept up to date with the tree structure hierarchy, or else checking and containment macros will fail inappropriately.

For language specific `DECL` nodes, there is an `init_ts` function in an appropriate `.c` file, which initializes the lookup table. Code setting up the table for new `DECL` nodes should be added there. For each `DECL` tree code and enumerator value representing a member of the inheritance hierarchy, the table should contain 1 if that tree code inherits (directly or indirectly) from that member.

Thus, a `FOO_DECL` node derived from `struct decl_with rtl`, and enumerator value `TS_FOO_DECL`, would be set up as follows

```c
tree_contains Struct[FOO_DECL][TS_FOO_DECL] = 1;
```

For `DECL` nodes that are part of the middle-end, the setup code goes into `tree.c`.

Add macros to access any new fields and flags
Each added field or flag should have a macro that is used to access it, that performs appropriate checking to ensure only the right type of `DECL` nodes access the field.

These macros generally take the following form

```c
#define FOO_DECL_FIELDNAME(NODE) FOO_DECL_CHECK(NODE)->foo_decl.fieldname
```

However, if the structure is simply a base class for further structures, something like the following should be used

```c
#define BASE_STRUCT_CHECK(T) CONTAINS_STRUCT_CHECK(T, TS_BASE_STRUCT)
#define BASE_STRUCT_FIELDNAME(NODE) 
(BASE_STRUCT_CHECK(NODE))->base_struct.fieldname
```

Reading them from the generated `all-tree.def` file (which in turn includes all the `tree.def` files), `gencheck.c` is used during GCC’s build to generate the `_CHECK` macros for all tree codes.

11.5 Attributes in trees
Attributes, as specified using the `__attribute__` keyword, are represented internally as a `TREE_LIST`. The `TREE_PURPOSE` is the name of the attribute, as an `IDENTIFIER_NODE`. The `TREE_VALUE` is a `TREE_LIST` of the arguments of the attribute, if any, or `NULL_TREE` if there
are no arguments; the arguments are stored as the TREE_VALUE of successive entries in the list, and may be identifiers or expressions. The TREE_CHAIN of the attribute is the next attribute in a list of attributes applying to the same declaration or type, or NULL_TREE if there are no further attributes in the list.

Attributes may be attached to declarations and to types; these attributes may be accessed with the following macros. All attributes are stored in this way, and many also cause other changes to the declaration or type or to other internal compiler data structures.

```
tree DECL_ATTRIBUTES (tree decl) [Tree Macro]
    This macro returns the attributes on the declaration decl.
```

```
tree TYPE_ATTRIBUTES (tree type) [Tree Macro]
    This macro returns the attributes on the type type.
```

### 11.6 Expressions

The internal representation for expressions is for the most part quite straightforward. However, there are a few facts that one must bear in mind. In particular, the expression “tree” is actually a directed acyclic graph. (For example there may be many references to the integer constant zero throughout the source program; many of these will be represented by the same expression node.) You should not rely on certain kinds of node being shared, nor should you rely on certain kinds of nodes being unshared.

The following macros can be used with all expression nodes:

**TREE_TYPE**

Returns the type of the expression. This value may not be precisely the same type that would be given the expression in the original program.

In what follows, some nodes that one might expect to always have type `bool` are documented to have either integral or boolean type. At some point in the future, the C front end may also make use of this same intermediate representation, and at this point these nodes will certainly have integral type. The previous sentence is not meant to imply that the C++ front end does not or will not give these nodes integral type.

Below, we list the various kinds of expression nodes. Except where noted otherwise, the operands to an expression are accessed using the `TREE_OPERAND` macro. For example, to access the first operand to a binary plus expression `expr`, use:

```
TREE_OPERAND (expr, 0)
```

As this example indicates, the operands are zero-indexed.

#### 11.6.1 Constant expressions

The table below begins with constants, moves on to unary expressions, then proceeds to binary expressions, and concludes with various other kinds of expressions:

**INTEGER_CST**

These nodes represent integer constants. Note that the type of these constants is obtained with `TREE_TYPE`; they are not always of type `int`. In particular, `char` constants are represented with `INTEGER_CST` nodes. The value of the integer constant `e` is represented in an array of `HOST_WIDE_INT`. There are enough
elements in the array to represent the value without taking extra elements for redundant 0s or -1. The number of elements used to represent $e$ is available via TREE_INT_CST_NUNITS. Element $i$ can be extracted by using TREE_INT_CST_ELT ($e$, $i$). TREE_INT_CST_LOW is a shorthand for TREE_INT_CST_ELT ($e$, 0).

The functions tree_fits_shwi_p and tree_fits_uhwi_p can be used to tell if the value is small enough to fit in a signed HOST_WIDE_INT or an unsigned HOST_WIDE_INT respectively. The value can then be extracted using tree_to_shwi and tree_to_uhwi.

REAL_CST

FIXME: Talk about how to obtain representations of this constant, do comparisons, and so forth.

FIXED_CST

These nodes represent fixed-point constants. The type of these constants is obtained with TREE_TYPE. TREE_FIXED_CST_PTR points to a struct fixed_value; TREE_FIXED_CST returns the structure itself. struct fixed_value contains data with the size of two HOST_BITS_PER_WIDE_INT and mode as the associated fixed-point machine mode for data.

COMPLEX_CST

These nodes are used to represent complex number constants, that is a __complex__ whose parts are constant nodes. The TREE_REALPART and TREE_IMAGPART return the real and the imaginary parts respectively.

VECTOR_CST

These nodes are used to represent vector constants. Each vector constant $v$ is treated as a specific instance of an arbitrary-length sequence that itself contains 'VECTOR_CST_NPATTERNS ($v$)' interleaved patterns. Each pattern has the form:

\{
base0, base1, base1 + step, base1 + step * 2, ...
\}

The first three elements in each pattern are enough to determine the values of the other elements. However, if all steps are zero, only the first two elements are needed. If in addition each base1 is equal to the corresponding base0, only the first element in each pattern is needed. The number of encoded elements per pattern is given by 'VECTOR_CST_NELTS_PER_PATTERN ($v$)'.

For example, the constant:

\{ 0, 1, 2, 6, 3, 8, 4, 10, 5, 12, 6, 14, 7, 16, 8, 18 \}

is interpreted as an interleaving of the sequences:

\{ 0, 2, 3, 4, 5, 6, 7, 8 \}
\{ 1, 6, 8, 10, 12, 14, 16, 18 \}

where the sequences are represented by the following patterns:

base0 == 0, base1 == 2, step == 1
base0 == 1, base1 == 6, step == 2

In this case:

VECTOR_CST_NPATTERNS ($v$) == 2
VECTOR_CST_NELTS_PER_PATTERN ($v$) == 3

The vector is therefore encoded using the first 6 elements (\{ 0, 1, 2, 6, 3, 8 \}), with the remaining 10 elements being implicit extensions of them.
Sometimes this scheme can create two possible encodings of the same vector. For example \{ 0, 1 \} could be seen as two patterns with one element each or one pattern with two elements (\emph{base0} and \emph{base1}). The canonical encoding is always the one with the fewest patterns or (if both encodings have the same number of patterns) the one with the fewest encoded elements.

\texttt{\texttt{vector_cst_encoding_nelts \( \langle v \rangle \)}} gives the total number of encoded elements in \( v \), which is 6 in the example above. \texttt{VECTOR_CST_ENCODED_ELTS \( \langle v \rangle \)}} gives a pointer to the elements encoded in \( v \) and \texttt{VECTOR_CST_ENCODED_ELT \( \langle v, i \rangle \)}} accesses the value of encoded element \( i \).

\texttt{\texttt{VECTOR_CST_DUPLICATE_P \( \langle v \rangle \)}} is true if \( v \) simply contains repeated instances of \texttt{\texttt{VECTOR_CST_NPATTERNS \( \langle v \rangle \)}} values. This is a shorthand for testing \texttt{\texttt{VECTOR_CST_NELTS_PER_PATTERN \( \langle v \rangle \)} == 1}'.

\texttt{\texttt{VECTOR_CST_STEPED_P \( \langle v \rangle \)}} is true if at least one pattern in \( v \) has a nonzero step. This is a shorthand for testing \texttt{\texttt{VECTOR_CST_NELTS_PER_PATTERN \( \langle v \rangle \)} == 3}'.

The utility function \texttt{vector_cst_elt} gives the value of an arbitrary index as a \texttt{tree}. \texttt{vector_cst_int_elt} gives the same value as a \texttt{wide_int}.

**STRING_CST**

These nodes represent string-constants. The \texttt{\texttt{TREE_STRING_LENGTH \( \langle v \rangle \)}} returns the length of the string, as an \texttt{int}. The \texttt{\texttt{TREE_STRING_POINTER \( \langle v \rangle \)}} is a \texttt{char*} containing the string itself. The string may not be NUL-terminated, and it may contain embedded NUL characters. Therefore, the \texttt{\texttt{TREE_STRING_LENGTH \( \langle v \rangle \)}} includes the trailing NUL if it is present.

For wide string constants, the \texttt{\texttt{TREE_STRING_LENGTH \( \langle v \rangle \)}} is the number of bytes in the string, and the \texttt{\texttt{TREE_STRING_POINTER \( \langle v \rangle \)}} points to an array of the bytes of the string, as represented on the target system (that is, as integers in the target endianness). Wide and non-wide string constants are distinguished only by the \texttt{\texttt{TREE_TYPE \( \langle v \rangle \)}} of the \texttt{STRING_CST}.

\texttt{\texttt{FIXME: The formats of string constants are not well-defined when the target system bytes are not the same width as host system bytes.}}

**POLY_INT_CST**

These nodes represent invariants that depend on some target-specific runtime parameters. They consist of \texttt{\texttt{NUM_POLY_INT_COEFFS \( \langle v \rangle \)}} coefficients, with the first coefficient being the constant term and the others being multipliers that are applied to the runtime parameters.

\texttt{POLY_INT_CST_ELT \( \langle x, i \rangle \)}} references coefficient number \( i \) of \texttt{POLY_INT_CST \( \langle x \rangle \)}} node \( x \). Each coefficient is an \texttt{INTEGER_CST}.

### 11.6.2 References to storage

**ARRAY_REF**

These nodes represent array accesses. The first operand is the array; the second is the index. To calculate the address of the memory accessed, you must scale the index by the size of the type of the array elements. The type of these expressions must be the type of a component of the array. The third and
fourth operands are used after simplification to represent the lower bound and component size but should not be used directly; call `array_ref_low_bound` and `array_ref_element_size` instead.

**ARRAY_RANGE_REF**

These nodes represent access to a range (or “slice”) of an array. The operands are the same as that for `ARRAY_REF` and have the same meanings. The type of these expressions must be an array whose component type is the same as that of the first operand. The range of that array type determines the amount of data these expressions access.

**TARGET_MEM_REF**

These nodes represent memory accesses whose address directly map to an addressing mode of the target architecture. The first argument is `TMR_SYMBOL` and must be a `VAR_DECL` of an object with a fixed address. The second argument is `TMR_BASE` and the third one is `TMR_INDEX`. The fourth argument is `TMR_STEP` and must be an `INTEGER_CST`. The fifth argument is `TMR_OFFSET` and must be an `INTEGER_CST`. Any of the arguments may be NULL if the appropriate component does not appear in the address. Address of the `TARGET_MEM_REF` is determined in the following way.

\[ &TMR_SYMBOL + TMR_BASE + TMR_INDEX \times TMR_STEP + TMR_OFFSET \]

The sixth argument is the reference to the original memory access, which is preserved for the purposes of the RTL alias analysis. The seventh argument is a tag representing the results of tree level alias analysis.

**ADDR_EXPR**

These nodes are used to represent the address of an object. (These expressions will always have pointer or reference type.) The operand may be another expression, or it may be a declaration.

As an extension, GCC allows users to take the address of a label. In this case, the operand of the `ADDR_EXPR` will be a `LABEL_DECL`. The type of such an expression is `void*`.

If the object addressed is not an lvalue, a temporary is created, and the address of the temporary is used.

**INDIRECT_REF**

These nodes are used to represent the object pointed to by a pointer. The operand is the pointer being dereferenced; it will always have pointer or reference type.

**MEM_REF**

These nodes are used to represent the object pointed to by a pointer offset by a constant. The first operand is the pointer being dereferenced; it will always have pointer or reference type. The second operand is a pointer constant. Its type is specifying the type to be used for type-based alias analysis.

**COMPONENT_REF**

These nodes represent non-static data member accesses. The first operand is the object (rather than a pointer to it); the second operand is the `FIELD_DECL` for the data member. The third operand represents the byte offset of the field, but should not be used directly; call `component_ref_field_offset` instead.
11.6.3 Unary and Binary Expressions

**NEGATE_EXPR**

These nodes represent unary negation of the single operand, for both integer and floating-point types. The type of negation can be determined by looking at the type of the expression.

The behavior of this operation on signed arithmetic overflow is controlled by the `flag_wrapv` and `flag_trapv` variables.

**ABS_EXPR**

These nodes represent the absolute value of the single operand, for both integer and floating-point types. This is typically used to implement the `abs`, `labs` and `llabs` builtins for integer types, and the `fabs`, `fabsf` and `fabsl` builtins for floating point types. The type of abs operation can be determined by looking at the type of the expression.

This node is not used for complex types. To represent the modulus or complex abs of a complex value, use the `BUILT_IN_CABS`, `BUILT_IN_CABSF` or `BUILT_IN_CABSL` builtins, as used to implement the C99 `cabs`, `cabsf` and `cabsl` built-in functions.

**ABSU_EXPR**

These nodes represent the absolute value of the single operand in equivalent unsigned type such that `ABSU_EXPR` of `TYPE_MIN` is well defined.

**BIT_NOT_EXPR**

These nodes represent bitwise complement, and will always have integral type. The only operand is the value to be complemented.

**TRUTH_NOT_EXPR**

These nodes represent logical negation, and will always have integral (or boolean) type. The operand is the value being negated. The type of the operand and that of the result are always of `BOOLEAN_TYPE` or `INTEGER_TYPE`.

**PREDECREMENT_EXPR**

**PREINCREMENT_EXPR**

**POSTDECREMENT_EXPR**

**POSTINCREMENT_EXPR**

These nodes represent increment and decrement expressions. The value of the single operand is computed, and the operand incremented or decremented. In the case of `PREDECREMENT_EXPR` and `PREINCREMENT_EXPR`, the value of the expression is the value resulting after the increment or decrement; in the case of `POSTDECREMENT_EXPR` and `POSTINCREMENT_EXPR` is the value before the increment or decrement occurs. The type of the operand, like that of the result, will be either integral, boolean, or floating-point.

**FIX_TRUNC_EXPR**

These nodes represent conversion of a floating-point value to an integer. The single operand will have a floating-point type, while the complete expression will have an integral (or boolean) type. The operand is rounded towards zero.
FLOAT_EXPR
These nodes represent conversion of an integral (or boolean) value to a floating-point value. The single operand will have integral type, while the complete expression will have a floating-point type.

FIXME: How is the operand supposed to be rounded? Is this dependent on `-mieee`?

COMPLEX_EXPR
These nodes are used to represent complex numbers constructed from two expressions of the same (integer or real) type. The first operand is the real part and the second operand is the imaginary part.

CONJ_EXPR
These nodes represent the conjugate of their operand.

REALPART_EXPR
IMAGPART_EXPR
These nodes represent respectively the real and the imaginary parts of complex numbers (their sole argument).

NON_LVALUE_EXPR
These nodes indicate that their one and only operand is not an lvalue. A back end can treat these identically to the single operand.

NOP_EXPR
These nodes are used to represent conversions that do not require any code-generation. For example, conversion of a char* to an int* does not require any code be generated; such a conversion is represented by a NOP_EXPR. The single operand is the expression to be converted. The conversion from a pointer to a reference is also represented with a NOP_EXPR.

CONVERT_EXPR
These nodes are similar to NOP_EXPRs, but are used in those situations where code may need to be generated. For example, if an int* is converted to an int code may need to be generated on some platforms. These nodes are never used for C++-specific conversions, like conversions between pointers to different classes in an inheritance hierarchy. Any adjustments that need to be made in such cases are always indicated explicitly. Similarly, a user-defined conversion is never represented by a CONVERT_EXPR; instead, the function calls are made explicit.

FIXED_CONVERT_EXPR
These nodes are used to represent conversions that involve fixed-point values. For example, from a fixed-point value to another fixed-point value, from an integer to a fixed-point value, from a fixed-point value to an integer, from a floating-point value to a fixed-point value, or from a fixed-point value to a floating-point value.

LSHIFT_EXPR
RSHIFT_EXPR
These nodes represent left and right shifts, respectively. The first operand is the value to shift; it will always be of integral type. The second operand is
an expression for the number of bits by which to shift. Right shift should be
treated as arithmetic, i.e., the high-order bits should be zero-filled when the
expression has unsigned type and filled with the sign bit when the expression
has signed type. Note that the result is undefined if the second operand is
larger than or equal to the first operand’s type size. Unlike most nodes, these
can have a vector as first operand and a scalar as second operand.

BIT_IOR_EXPR
BIT_XOR_EXPR
BIT_AND_EXPR
These nodes represent bitwise inclusive or, bitwise exclusive or, and bitwise
and, respectively. Both operands will always have integral type.

TRUTH_ANDIF_EXPR
TRUTH_ORIF_EXPR
These nodes represent logical “and” and logical “or”, respectively. These oper-
ators are not strict; i.e., the second operand is evaluated only if the value of the
expression is not determined by evaluation of the first operand. The type of the
operands and that of the result are always of BOOLEAN_TYPE or INTEGER_TYPE.

TRUTH_AND_EXPR
TRUTH_OR_EXPR
TRUTH_XOR_EXPR
These nodes represent logical and, logical or, and logical exclusive or. They are
strict; both arguments are always evaluated. There are no corresponding oper-
ators in C or C++, but the front end will sometimes generate these expressions
anyhow, if it can tell that strictness does not matter. The type of the operands
and that of the result are always of BOOLEAN_TYPE or INTEGER_TYPE.

POINTER_PLUS_EXPR
This node represents pointer arithmetic. The first operand is always a
pointer/reference type. The second operand is always an unsigned integer
type compatible with sizetype. This and POINTER_DIFF_EXPR are the only
binary arithmetic operators that can operate on pointer types.

POINTER_DIFF_EXPR
This node represents pointer subtraction. The two operands always have
pointer/reference type. It returns a signed integer of the same precision as the
pointers. The behavior is undefined if the difference of the two pointers, seen
as infinite precision non-negative integers, does not fit in the result type. The
result does not depend on the pointer type, it is not divided by the size of the
pointed-to type.

PLUS_EXPR
MINUS_EXPR
MULT_EXPR
These nodes represent various binary arithmetic operations. Respectively, these
operations are addition, subtraction (of the second operand from the first) and
multiplication. Their operands may have either integral or floating type, but
there will never be case in which one operand is of floating type and the other
is of integral type.
The behavior of these operations on signed arithmetic overflow is controlled by the `flag_wrapv` and `flag_trapv` variables.

**MULT_HIGHPART_EXPR**
This node represents the “high-part” of a widening multiplication. For an integral type with \( b \) bits of precision, the result is the most significant \( b \) bits of the full \( 2^b \) product.

**RDIV_EXPR**
This node represents a floating point division operation.

**TRUNC_DIV_EXPR**
**FLOOR_DIV_EXPR**
**CEIL_DIV_EXPR**
**ROUND_DIV_EXPR**
These nodes represent integer division operations that return an integer result. **TRUNC_DIV_EXPR** rounds towards zero, **FLOOR_DIV_EXPR** rounds towards negative infinity, **CEIL_DIV_EXPR** rounds towards positive infinity and **ROUND_DIV_EXPR** rounds to the closest integer. Integer division in C and C++ is truncating, i.e. **TRUNC_DIV_EXPR**.

The behavior of these operations on signed arithmetic overflow, when dividing the minimum signed integer by minus one, is controlled by the `flag_wrapv` and `flag_trapv` variables.

**TRUNC_MOD_EXPR**
**FLOOR_MOD_EXPR**
**CEIL_MOD_EXPR**
**ROUND_MOD_EXPR**
These nodes represent the integer remainder or modulus operation. The integer modulus of two operands \( a \) and \( b \) is defined as \( a - (a/b)\times b \) where the division calculated using the corresponding division operator. Hence for **TRUNC_MOD_EXPR** this definition assumes division using truncation towards zero, i.e. **TRUNC_DIV_EXPR**. Integer remainder in C and C++ uses truncating division, i.e. **TRUNC_MOD_EXPR**.

**EXACT_DIV_EXPR**
The **EXACT_DIV_EXPR** code is used to represent integer divisions where the numerator is known to be an exact multiple of the denominator. This allows the backend to choose between the faster of **TRUNC_DIV_EXPR**, **CEIL_DIV_EXPR** and **FLOOR_DIV_EXPR** for the current target.

**LT_EXPR**
**LE_EXPR**
**GT_EXPR**
**GE_EXPR**
**LTGT_EXPR**
**EQ_EXPR**
**NE_EXPR**
These nodes represent the less than, less than or equal to, greater than, greater than or equal to, less or greater than, equal, and not equal comparison operators. The first and second operands will either be both of integral type, both of
floating type or both of vector type, except for LTGT_EXPR where they will only be both of floating type. The result type of these expressions will always be of integral, boolean or signed integral vector type. These operations return the result type's zero value for false, the result type's one value for true, and a vector whose elements are zero (false) or minus one (true) for vectors.

For floating point comparisons, if we honor IEEE NaNs and either operand is NaN, then NE_EXPR always returns true and the remaining operators always return false. On some targets, comparisons against an IEEE NaN, other than equality and inequality, may generate a floating-point exception.

ORDERED_EXPR
UNORDERED_EXPR

These nodes represent non-trapping ordered and unordered comparison operators. These operations take two floating point operands and determine whether they are ordered or unordered relative to each other. If either operand is an IEEE NaN, their comparison is defined to be unordered, otherwise the comparison is defined to be ordered. The result type of these expressions will always be of integral or boolean type. These operations return the result type's zero value for false, and the result type's one value for true.

UNLT_EXPR
UNLE_EXPR
UNGT_EXPR
UNGE_EXPR
UNEQ_EXPR

These nodes represent the unordered comparison operators. These operations take two floating point operands and determine whether the operands are unordered or are less than, less than or equal to, greater than, greater than or equal to, or equal respectively. For example, UNLT_EXPR returns true if either operand is an IEEE NaN or the first operand is less than the second. All these operations are guaranteed not to generate a floating point exception. The result type of these expressions will always be of integral or boolean type. These operations return the result type's zero value for false, and the result type's one value for true.

MODIFY_EXPR

These nodes represent assignment. The left-hand side is the first operand; the right-hand side is the second operand. The left-hand side will be a VAR_DECL, INDIRECT_REF, COMPONENT_REF, or other lvalue. These nodes are used to represent not only assignment with '=' but also compound assignments (like '+='), by reduction to '=' assignment. In other words, the representation for 'i += 3' looks just like that for 'i = i + 3'.

INIT_EXPR

These nodes are just like MODIFY_EXPR, but are used only when a variable is initialized, rather than assigned to subsequently. This means that we can assume that the target of the initialization is not used in computing its own value; any reference to the lhs in computing the rhs is undefined.
COMPOUND_EXPR
These nodes represent comma-expressions. The first operand is an expression whose value is computed and thrown away prior to the evaluation of the second operand. The value of the entire expression is the value of the second operand.

COND_EXPR
These nodes represent ?: expressions. The first operand is of boolean or integral type. If it evaluates to a nonzero value, the second operand should be evaluated, and returned as the value of the expression. Otherwise, the third operand is evaluated, and returned as the value of the expression.

The second operand must have the same type as the entire expression, unless it unconditionally throws an exception or calls a noreturn function, in which case it should have void type. The same constraints apply to the third operand.

This allows array bounds checks to be represented conveniently as \((i >= 0 && i < 10) ? i : \text{abort()}\).

As a GNU extension, the C language front-ends allow the second operand of the ?: operator may be omitted in the source. For example, \(x ? : 3\) is equivalent to \(x ? x : 3\), assuming that \(x\) is an expression without side effects. In the tree representation, however, the second operand is always present, possibly protected by SAVE_EXPR if the first argument does cause side effects.

CALL_EXPR
These nodes are used to represent calls to functions, including non-static member functions. CALL_EXPRs are implemented as expression nodes with a variable number of operands. Rather than using TREE_OPERAND to extract them, it is preferable to use the specialized accessor macros and functions that operate specifically on CALL_EXPR nodes.

CALL_EXPR_FN returns a pointer to the function to call; it is always an expression whose type is a POINTER_TYPE.

The number of arguments to the call is returned by call_expr_nargs, while the arguments themselves can be accessed with the CALL_EXPR_ARG macro. The arguments are zero-indexed and numbered left-to-right. You can iterate over the arguments using FOR_EACH_CALL_EXPR_ARG, as in:

```c
  tree call, arg;
  call_expr_arg_iterator iter;
  FOR_EACH_CALL_EXPR_ARG (arg, iter, call)
    /* arg is bound to successive arguments of call. */
    ...
```

For non-static member functions, there will be an operand corresponding to the this pointer. There will always be expressions corresponding to all of the arguments, even if the function is declared with default arguments and some arguments are not explicitly provided at the call sites.

CALL_EXPRs also have a CALL_EXPR_STATIC_CHAIN operand that is used to implement nested functions. This operand is otherwise null.

CLEANUP_POINT_EXPR
These nodes represent full-expressions. The single operand is an expression to evaluate. Any destructor calls engendered by the creation of temporaries
during the evaluation of that expression should be performed immediately after the expression is evaluated.

**CONSTRUCTOR**
These nodes represent the brace-enclosed initializers for a structure or an array. They contain a sequence of component values made out of a vector of constructor_elt, which is a (INDEX, VALUE) pair.

If the TREE_TYPE of the CONSTRUCTOR is a RECORD_TYPE, UNION_TYPE or QUAL_UNION_TYPE then the INDEX of each node in the sequence will be a FIELD_DECL and the VALUE will be the expression used to initialize that field.

If the TREE_TYPE of the CONSTRUCTOR is an ARRAY_TYPE, then the INDEX of each node in the sequence will be an INTEGER_CST or a RANGE_EXPR of two INTEGER_CSTs. A single INTEGER_CST indicates which element of the array is being assigned to. A RANGE_EXPR indicates an inclusive range of elements to initialize. In both cases the VALUE is the corresponding initializer. It is re-evaluated for each element of a RANGE_EXPR. If the INDEX is NULL_TREE, then the initializer is for the next available array element.

In the front end, you should not depend on the fields appearing in any particular order. However, in the middle end, fields must appear in declaration order. You should not assume that all fields will be represented. Unrepresented fields will be cleared (zeroed), unless the CONSTRUCTOR_NO.Clearing flag is set, in which case their value becomes undefined.

**COMPOUND_LITERAL_EXPR**
These nodes represent ISO C99 compound literals. The COMPOUND_LITERAL_EXPR DECL_EXPR is a DECL_EXPR containing an anonymous VAR_DECL for the unnamed object represented by the compound literal; the DECL_INITIAL of that VAR_DECL is a CONSTRUCTOR representing the brace-enclosed list of initializers in the compound literal. That anonymous VAR_DECL can also be accessed directly by the COMPOUND_LITERAL_EXPR DECL macro.

**SAVE_EXPR**
A SAVE_EXPR represents an expression (possibly involving side effects) that is used more than once. The side effects should occur only the first time the expression is evaluated. Subsequent uses should just reuse the computed value. The first operand to the SAVE_EXPR is the expression to evaluate. The side effects should be executed where the SAVE_EXPR is first encountered in a depth-first preorder traversal of the expression tree.

**TARGET_EXPR**
A TARGET_EXPR represents a temporary object. The first operand is a VAR_DECL for the temporary variable. The second operand is the initializer for the temporary. The initializer is evaluated and, if non-void, copied (bitwise) into the temporary. If the initializer is void, that means that it will perform the initialization itself.

Often, a TARGET_EXPR occurs on the right-hand side of an assignment, or as the second operand to a comma-expression which is itself the right-hand side of an assignment, etc. In this case, we say that the TARGET_EXPR is “normal”;

otherwise, we say it is “orphaned”. For a normal TARGET_EXPR the temporary variable should be treated as an alias for the left-hand side of the assignment, rather than as a new temporary variable.

The third operand to the TARGET_EXPR, if present, is a cleanup-expression (i.e., destructor call) for the temporary. If this expression is orphaned, then this expression must be executed when the statement containing this expression is complete. These cleanups must always be executed in the order opposite to that in which they were encountered. Note that if a temporary is created on one branch of a conditional operator (i.e., in the second or third operand to a COND_EXPR), the cleanup must be run only if that branch is actually executed.

VA_ARG_EXPR
This node is used to implement support for the C/C++ variable argument-list mechanism. It represents expressions like va_arg(ap, type). Its TREE_TYPE yields the tree representation for type and its sole argument yields the representation for ap.

ANNOTATE_EXPR
This node is used to attach markers to an expression. The first operand is the annotated expression, the second is an INTEGER_CST with a value from enum annot_expr_kind, the third is an INTEGER_CST.

11.6.4 Vectors

VEC_DUPLICATE_EXPR
This node has a single operand and represents a vector in which every element is equal to that operand.

VEC_SERIES_EXPR
This node represents a vector formed from a scalar base and step, given as the first and second operands respectively. Element i of the result is equal to ‘base + i*step’.

This node is restricted to integral types, in order to avoid specifying the rounding behavior for floating-point types.

VEC_LSHIFT_EXPR
VEC_RSHIFT_EXPR
These nodes represent whole vector left and right shifts, respectively. The first operand is the vector to shift; it will always be of vector type. The second operand is an expression for the number of bits by which to shift. Note that the result is undefined if the second operand is larger than or equal to the first operand’s type size.

VEC_WIDEN_MULT_HI_EXPR
VEC_WIDEN_MULT_LO_EXPR
These nodes represent widening vector multiplication of the high and low parts of the two input vectors, respectively. Their operands are vectors that contain the same number of elements (N) of the same integral type. The result is a vector that contains half as many elements, of an integral type whose size is twice as wide. In the case of VEC_WIDEN_MULT_HI_EXPR the high N/2 elements
of the two vector are multiplied to produce the vector of $\frac{N}{2}$ products. In the case of \texttt{VEC\_WIDEN\_MULT\_LO\_EXPR} the low $\frac{N}{2}$ elements of the two vector are multiplied to produce the vector of $\frac{N}{2}$ products.

\texttt{VEC\_WIDEN\_PLUS\_HI\_EXPR}  
\texttt{VEC\_WIDEN\_PLUS\_LO\_EXPR}  
These nodes represent widening vector addition of the high and low parts of the two input vectors, respectively. Their operands are vectors that contain the same number of elements ($N$) of the same integral type. The result is a vector that contains half as many elements, of an integral type whose size is twice as wide. In the case of \texttt{VEC\_WIDEN\_PLUS\_HI\_EXPR} the high $\frac{N}{2}$ elements of the two vectors are added to produce the vector of $\frac{N}{2}$ products. In the case of \texttt{VEC\_WIDEN\_PLUS\_LO\_EXPR} the low $\frac{N}{2}$ elements of the two vectors are added to produce the vector of $\frac{N}{2}$ products.

\texttt{VEC\_WIDEN\_MINUS\_HI\_EXPR}  
\texttt{VEC\_WIDEN\_MINUS\_LO\_EXPR}  
These nodes represent widening vector subtraction of the high and low parts of the two input vectors, respectively. Their operands are vectors that contain the same number of elements ($N$) of the same integral type. The high/low elements of the second vector are subtracted from the high/low elements of the first. The result is a vector that contains half as many elements, of an integral type whose size is twice as wide. In the case of \texttt{VEC\_WIDEN\_MINUS\_HI\_EXPR} the high $\frac{N}{2}$ elements of the second vector are subtracted from the high $\frac{N}{2}$ of the first to produce the vector of $\frac{N}{2}$ products. In the case of \texttt{VEC\_WIDEN\_MINUS\_LO\_EXPR} the low $\frac{N}{2}$ elements of the second vector are subtracted from the low $\frac{N}{2}$ of the first to produce the vector of $\frac{N}{2}$ products.

\texttt{VEC\_UNPACK\_HI\_EXPR}  
\texttt{VEC\_UNPACK\_LO\_EXPR}  
These nodes represent unpacking of the high and low parts of the input vector, respectively. The single operand is a vector that contains $N$ elements of the same integral or floating point type. The result is a vector that contains half as many elements, of an integral or floating point type whose size is twice as wide. In the case of \texttt{VEC\_UNPACK\_HI\_EXPR} the high $\frac{N}{2}$ elements of the vector are extracted and widened (promoted). In the case of \texttt{VEC\_UNPACK\_LO\_EXPR} the low $\frac{N}{2}$ elements of the vector are extracted and widened (promoted).

\texttt{VEC\_UNPACK\_FLOAT\_HI\_EXPR}  
\texttt{VEC\_UNPACK\_FLOAT\_LO\_EXPR}  
These nodes represent unpacking of the high and low parts of the input vector, where the values are converted from fixed point to floating point. The single operand is a vector that contains $N$ elements of the same integral type. The result is a vector that contains half as many elements of a floating point type whose size is twice as wide. In the case of \texttt{VEC\_UNPACK\_FLOAT\_HI\_EXPR} the high $\frac{N}{2}$ elements of the vector are extracted, converted and widened. In the case of \texttt{VEC\_UNPACK\_FLOAT\_LO\_EXPR} the low $\frac{N}{2}$ elements of the vector are extracted, converted and widened.
VEC_UNPACK_FIX_TRUNC_HI_EXPR

These nodes represent unpacking of the high and low parts of the input vector, where the values are truncated from floating point to fixed point. The single operand is a vector that contains \( N \) elements of the same floating point type. The result is a vector that contains half as many elements of an integral type whose size is twice as wide. In the case of VEC_UNPACK_FIX_TRUNC_HI_EXPR the high \( N/2 \) elements of the vector are extracted and converted with truncation. In the case of VEC_UNPACK_FIX_TRUNC_LO_EXPR the low \( N/2 \) elements of the vector are extracted and converted with truncation.

VEC_UNPACK_FIX_TRUNC_LO_EXPR

VEC_PACK_TRUNC_EXPR

This node represents packing of truncated elements of the two input vectors into the output vector. Input operands are vectors that contain the same number of elements of the same integral or floating point type. The result is a vector that contains twice as many elements of an integral or floating point type whose size is half as wide. The elements of the two vectors are demoted and merged (concatenated) to form the output vector.

VEC_PACK_SAT_EXPR

This node represents packing of elements of the two input vectors into the output vector using saturation. Input operands are vectors that contain the same number of elements of the same integral type. The result is a vector that contains twice as many elements of an integral type whose size is half as wide. The elements of the two vectors are demoted and merged (concatenated) to form the output vector.

VEC_PACK_FIX_TRUNC_EXPR

This node represents packing of elements of the two input vectors into the output vector, where the values are converted from floating point to fixed point. Input operands are vectors that contain the same number of elements of a floating point type. The result is a vector that contains twice as many elements of an integral type whose size is half as wide. The elements of the two vectors are merged (concatenated) to form the output vector.

VEC_PACK_FLOAT_EXPR

This node represents packing of elements of the two input vectors into the output vector, where the values are converted from fixed point to floating point. Input operands are vectors that contain the same number of elements of an integral type. The result is a vector that contains twice as many elements of floating point type whose size is half as wide. The elements of the two vectors are merged (concatenated) to form the output vector.

VEC_COND_EXPR

These nodes represent `?:` expressions. The three operands must be vectors of the same size and number of elements. The second and third operands must have the same type as the entire expression. The first operand is of signed integral vector type. If an element of the first operand evaluates to a zero value, the corresponding element of the result is taken from the third operand. If it evaluates to a minus one value, it is taken from the second operand. It
should never evaluate to any other value currently, but optimizations should not rely on that property. In contrast with a COND_EXPR, all operands are always evaluated.

**SAD_EXPR** This node represents the Sum of Absolute Differences operation. The three operands must be vectors of integral types. The first and second operand must have the same type. The size of the vector element of the third operand must be at least twice of the size of the vector element of the first and second one. The SAD is calculated between the first and second operands, added to the third operand, and returned.

### 11.7 Statements

Most statements in GIMPLE are assignment statements, represented by GIMPLE_ASSIGN. No other C expressions can appear at statement level; a reference to a volatile object is converted into a GIMPLE_ASSIGN.

There are also several varieties of complex statements.

#### 11.7.1 Basic Statements

**ASM_EXPR**

Used to represent an inline assembly statement. For an inline assembly statement like:

```c
asm ("mov x, y");
```

The ASM_STRING macro will return a STRING_CST node for "mov x, y". If the original statement made use of the extended-assembly syntax, then ASM_OUTPUTS, ASM_INPUTS, and ASM_CLOBBERS will be the outputs, inputs, and clobbers for the statement, represented as STRING_CST nodes. The extended-assembly syntax looks like:

```c
asm ("fsinx %1,%0" : ="f" (result) : "f" (angle));
```

The first string is the ASM_STRING, containing the instruction template. The next two strings are the output and inputs, respectively; this statement has no clobbers. As this example indicates, “plain” assembly statements are merely a special case of extended assembly statements; they have no cv-qualifiers, outputs, inputs, or clobbers. All of the strings will be NUL-terminated, and will contain no embedded NUL-characters.

If the assembly statement is declared volatile, or if the statement was not an extended assembly statement, and is therefore implicitly volatile, then the predicate ASM_VOLATILE_P will hold of the ASM_EXPR.

**DECL_EXPR**

Used to represent a local declaration. The DECL_EXPR_DECL macro can be used to obtain the entity declared. This declaration may be a LABEL_DECL, indicating that the label declared is a local label. (As an extension, GCC allows the declaration of labels with scope.) In C, this declaration may be a FUNCTION_DECL, indicating the use of the GCC nested function extension. For more information, see Section 11.8 [Functions], page 197.
LABEL_EXPR
Used to represent a label. The LABEL_DECL declared by this statement can be obtained with the LABEL_EXPR_LABEL macro. The IDENTIFIER_NODE giving the name of the label can be obtained from the LABEL_DECL with DECL_NAME.

GOTO_EXPR
Used to represent a goto statement. The GOTO_DESTINATION will usually be a LABEL_DECL. However, if the “computed goto” extension has been used, the GOTO_DESTINATION will be an arbitrary expression indicating the destination. This expression will always have pointer type.

RETURN_EXPR
Used to represent a return statement. Operand 0 represents the value to return. It should either be the RESULT_DECL for the containing function, or a MODIFY_EXPR or INIT_EXPR setting the function’s RESULT_DECL. It will be NULL_TREE if the statement was just

    return;

LOOP_EXPR
These nodes represent “infinite” loops. The LOOP_EXPR_BODY represents the body of the loop. It should be executed forever, unless an EXIT_EXPR is encountered.

EXIT_EXPR
These nodes represent conditional exits from the nearest enclosing LOOP_EXPR. The single operand is the condition; if it is nonzero, then the loop should be exited. An EXIT_EXPR will only appear within a LOOP_EXPR.

SWITCH_EXPR
Used to represent a switch statement. The SWITCH_COND is the expression on which the switch is occurring. The SWITCH_BODY is the body of the switch statement. SWITCH_ALL_CASES_P is true if the switch includes a default label or the case label ranges cover all possible values of the condition expression.
Note that TREE_TYPE for a SWITCH_EXPR represents the original type of switch expression as given in the source, before any compiler conversions, instead of the type of the switch expression itself (which is not meaningful).

CASE_LABEL_EXPR
Used to represent a case label, range of case labels, or a default label. If CASE_LOW is NULL_TREE, then this is a default label. Otherwise, if CASE_HIGH is NULL_TREE, then this is an ordinary case label. In this case, CASE_LOW is an expression giving the value of the label. Both CASE_LOW and CASE_HIGH are INTEGER_CST nodes. These values will have the same type as the condition expression in the switch statement.
Otherwise, if both CASE_LOW and CASE_HIGH are defined, the statement is a range of case labels. Such statements originate with the extension that allows users to write things of the form:

    case 2 . . . 5:

The first value will be CASE_LOW, while the second will be CASE_HIGH.
DEBUG_BEGIN_STMT

Marks the beginning of a source statement, for purposes of debug information generation.

11.7.2 Blocks

Block scopes and the variables they declare in GENERIC are expressed using the BIND_EXPR code, which in previous versions of GCC was primarily used for the C statement-expression extension.

Variables in a block are collected into BIND_EXPR_VARS in declaration order through their TREE_CHAIN field. Any runtime initialization is moved out of DECL_INITIAL and into a statement in the controlled block. When simplifying from C or C++, this initialization replaces the DECL_STMT. These variables will never require cleanups. The scope of these variables is just the body.

Variable-length arrays (VLAs) complicate this process, as their size often refers to variables initialized earlier in the block and their initialization involves an explicit stack allocation. To handle this, we add an indirection and replace them with a pointer to stack space allocated by means of alloca. In most cases, we also arrange for this space to be reclaimed when the enclosing BIND_EXPR is exited, the exception to this being when there is an explicit call to alloca in the source code, in which case the stack is left depressed on exit of the BIND_EXPR.

A C++ program will usually contain more BIND_EXPRs than there are syntactic blocks in the source code, since several C++ constructs have implicit scopes associated with them. On the other hand, although the C++ front end uses pseudo-scopes to handle cleanups for objects with destructors, these don’t translate into the GIMPLE form; multiple declarations at the same level use the same BIND_EXPR.

11.7.3 Statement Sequences

Multiple statements at the same nesting level are collected into a STATEMENT_LIST. Statement lists are modified and traversed using the interface in ‘tree-iterator.h’.

11.7.4 Empty Statements

Whenever possible, statements with no effect are discarded. But if they are nested within another construct which cannot be discarded for some reason, they are instead replaced with an empty statement, generated by build_empty_stmt. Initially, all empty statements were shared, after the pattern of the Java front end, but this caused a lot of trouble in practice.

An empty statement is represented as (void)0.

11.7.5 Jumps

Other jumps are expressed by either GOTO_EXPR or RETURN_EXPR.

The operand of a GOTO_EXPR must be either a label or a variable containing the address to jump to.

The operand of a RETURN_EXPR is either NULL_TREE, RESULT_DECL, or a MODIFY_EXPR which sets the return value. It would be nice to move the MODIFY_EXPR into a separate statement, but the special return semantics in expand_return make that difficult. It may still happen in the future, perhaps by moving most of that logic into expand_assignment.
11.7.6 Cleanups

Destructors for local C++ objects and similar dynamic cleanups are represented in GIMPLE by a `TRY_FINALLY_EXPR`. `TRY_FINALLY_EXPR` has two operands, both of which are a sequence of statements to execute. The first sequence is executed. When it completes the second sequence is executed.

The first sequence may complete in the following ways:
1. Execute the last statement in the sequence and fall off the end.
2. Execute a goto statement (`GOTO_EXPR`) to an ordinary label outside the sequence.
3. Execute a return statement (`RETURN_EXPR`).
4. Throw an exception. This is currently not explicitly represented in GIMPLE.

The second sequence is not executed if the first sequence completes by calling `setjmp` or `exit` or any other function that does not return. The second sequence is also not executed if the first sequence completes via a non-local goto or a computed goto (in general the compiler does not know whether such a goto statement exits the first sequence or not, so we assume that it doesn’t).

After the second sequence is executed, if it completes normally by falling off the end, execution continues wherever the first sequence would have continued, by falling off the end, or doing a goto, etc.

If the second sequence is an `EH_ELSE_EXPR` selector, then the sequence in its first operand is used when the first sequence completes normally, and that in its second operand is used for exceptional cleanups, i.e., when an exception propagates out of the first sequence.

`TRY_FINALLY_EXPR` complicates the flow graph, since the cleanup needs to appear on every edge out of the controlled block; this reduces the freedom to move code across these edges. Therefore, the EH lowering pass which runs before most of the optimization passes eliminates these expressions by explicitly adding the cleanup to each edge. Rethrowing the exception is represented using `RESX_EXPR`.

11.7.7 OpenMP

All the statements starting with `OMP_` represent directives and clauses used by the OpenMP API [https://www.openmp.org](https://www.openmp.org).

`OMP_PARALLEL`

Represents `#pragma omp parallel [clause1 ... clauseN]`. It has four operands:

Operand `OMP_PARALLEL_BODY` is valid while in GENERIC and High GIMPLE forms. It contains the body of code to be executed by all the threads. During GIMPLE lowering, this operand becomes `NULL` and the body is emitted linearly after `OMP_PARALLEL`.

Operand `OMP_PARALLEL_CLAUSES` is the list of clauses associated with the directive.

Operand `OMP_PARALLEL_FN` is created by `pass_lower_omp`, it contains the `FUNCTION_DECL` for the function that will contain the body of the parallel region.
Operand `OMP_PARALLEL_DATA_ARG` is also created by `pass_lower_omp`. If there are shared variables to be communicated to the children threads, this operand will contain the `VAR_DECL` that contains all the shared values and variables.

**OMP_FOR**

Represents `#pragma omp for [clause1 ... clauseN]`. It has six operands:
- Operand `OMP_FOR_BODY` contains the loop body.
- Operand `OMP_FOR_CLAUSES` is the list of clauses associated with the directive.
- Operand `OMP_FOR_INIT` is the loop initialization code of the form `VAR = N1`.
- Operand `OMP_FOR_COND` is the loop conditional expression of the form `VAR {<,>,<=,=>} N2`.
- Operand `OMP_FOR_INCR` is the loop index increment of the form `VAR {+=,-=} INCR`.
- Operand `OMP_FOR_PRE_BODY` contains side effect code from operands `OMP_FOR_INIT`, `OMP_FOR_COND` and `OMP_FOR_INCR`. These side effects are part of the `OMP_FOR` block but must be evaluated before the start of loop body.

The loop index variable `VAR` must be a signed integer variable, which is implicitly private to each thread. Bounds `N1` and `N2` and the increment expression `INCR` are required to be loop invariant integer expressions that are evaluated without any synchronization. The evaluation order, frequency of evaluation and side effects are unspecified by the standard.

**OMP_SECTIONS**

Represents `#pragma omp sections [clause1 ... clauseN]`.
- Operand `OMP_SECTIONS_BODY` contains the sections body, which in turn contains a set of `OMP_SECTION` nodes for each of the concurrent sections delimited by `#pragma omp section`.
- Operand `OMP_SECTIONS_CLAUSES` is the list of clauses associated with the directive.

**OMP_SECTION**

Section delimiter for `OMP_SECTIONS`.

**OMP_SINGLE**

Represents `#pragma omp single`.
- Operand `OMP_SINGLE_BODY` contains the body of code to be executed by a single thread.
- Operand `OMP_SINGLE_CLAUSES` is the list of clauses associated with the directive.

**OMP_MASTER**

Represents `#pragma omp master`.
- Operand `OMP_MASTER_BODY` contains the body of code to be executed by the master thread.

**OMP_ORDERED**

Represents `#pragma omp ordered`.
Operand **OMP_ORDERED_BODY** contains the body of code to be executed in the sequential order dictated by the loop index variable.

**OMP_CRITICAL**
Represents `#pragma omp critical [name]`.
Operand **OMP_CRITICAL_BODY** is the critical section.
Operand **OMP_CRITICAL_NAME** is an optional identifier to label the critical section.

**OMP_RETURN**
This does not represent any OpenMP directive, it is an artificial marker to indicate the end of the body of an OpenMP. It is used by the flow graph (`tree-cfg.c`) and OpenMP region building code (`omp-low.c`).

**OMP_CONTINUE**
Similarly, this instruction does not represent an OpenMP directive, it is used by **OMP_FOR** (and similar codes) as well as **OMP_SECTIONS** to mark the place where the code needs to loop to the next iteration, or the next section, respectively.
In some cases, **OMP_CONTINUE** is placed right before **OMP_RETURN**. But if there are cleanups that need to occur right after the looping body, it will be emitted between **OMP_CONTINUE** and **OMP_RETURN**.

**OMP_ATOMIC**
Represents `#pragma omp atomic`.
Operand 0 is the address at which the atomic operation is to be performed.
Operand 1 is the expression to evaluate. The gimplifier tries three alternative code generation strategies. Whenever possible, an atomic update built-in is used. If that fails, a compare-and-swap loop is attempted. If that also fails, a regular critical section around the expression is used.

**OMP_CLAUSE**
Represents clauses associated with one of the **OMP_** directives. Clauses are represented by separate subcodes defined in ‘tree.h’. Clauses codes can be one of: **OMP_CLAUSE_PRIVATE**, **OMP_CLAUSE_SHARED**, **OMP_CLAUSE_FIRSTPRIVATE**, **OMP_CLAUSE_LASTPRIVATE**, **OMP_CLAUSE_COPYIN**, **OMP_CLAUSE_COPYPRIVATE**, **OMP_CLAUSE_IF**, **OMP_CLAUSE_NUM_THREADS**, **OMP_CLAUSE_SCHEDULE**, **OMP_CLAUSE_NOWAIT**, **OMP_CLAUSE_ORDERED**, **OMP_CLAUSE_REDUCTION**, **OMP_CLAUSE_COLLAPSE**, **OMP_CLAUSE_UNTIED**, **OMP_CLAUSE_FINAL**, and **OMP_CLAUSE_MERGEABLE**. Each code represents the corresponding OpenMP clause.
Clauses associated with the same directive are chained together via **OMP_CLAUSE_CHAIN**. Those clauses that accept a list of variables are restricted to exactly one, accessed with **OMP_CLAUSE_VAR**. Therefore, multiple variables under the same clause C need to be represented as multiple C clauses chained together. This facilitates adding new clauses during compilation.

### 11.7.8 OpenACC
All the statements starting with **OACC_** represent directives and clauses used by the OpenACC API [https://www.openacc.org](https://www.openacc.org).
OACC_CACHE
   Represents #pragma acc cache (var ...).

OACC_DATA
   Represents #pragma acc data [clause1 ... clauseN].

OACC_DECLARE
   Represents #pragma acc declare [clause1 ... clauseN].

OACC_ENTER_DATA
   Represents #pragma acc enter data [clause1 ... clauseN].

OACC_EXIT_DATA
   Represents #pragma acc exit data [clause1 ... clauseN].

OACC_HOST_DATA
   Represents #pragma acc host_data [clause1 ... clauseN].

OACC_KERNELS
   Represents #pragma acc kernels [clause1 ... clauseN].

OACC_LOOP
   Represents #pragma acc loop [clause1 ... clauseN].
   See the description of the OMP_FOR code.

OACC_PARALLEL
   Represents #pragma acc parallel [clause1 ... clauseN].

OACC_SERIAL
   Represents #pragma acc serial [clause1 ... clauseN].

OACC_UPDATE
   Represents #pragma acc update [clause1 ... clauseN].

11.8 Functions
A function is represented by a FUNCTION_DECL node. It stores the basic pieces of the function
such as body, parameters, and return type as well as information on the surrounding context,
visibility, and linkage.

11.8.1 Function Basics
A function has four core parts: the name, the parameters, the result, and the body. The
following macros and functions access these parts of a FUNCTION_DECL as well as other basic
features:

DECL_NAME
   This macro returns the unqualified name of the function, as an IDENTIFIER_NODE. For an instantiation of a function template, the DECL_NAME is the unqualified name of the template, not something like f<int>. The value of DECL_NAME is undefined when used on a constructor, destructor, overloaded operator, or type-conversion operator, or any function that is implicitly generated by the compiler. See below for macros that can be used to distinguish these cases.
DECL_ASSEMBLER_NAME

This macro returns the mangled name of the function, also an IDENTIFIER_NODE. This name does not contain leading underscores on systems that prefix all identifiers with underscores. The mangled name is computed in the same way on all platforms; if special processing is required to deal with the object file format used on a particular platform, it is the responsibility of the back end to perform those modifications. (Of course, the back end should not modify DECL_ASSEMBLER_NAME itself.)

Using DECL_ASSEMBLER_NAME will cause additional memory to be allocated (for the mangled name of the entity) so it should be used only when emitting assembly code. It should not be used within the optimizers to determine whether or not two declarations are the same, even though some of the existing optimizers do use it in that way. These uses will be removed over time.

DECL_ARGUMENTS

This macro returns the PARM_DECL for the first argument to the function. Subsequent PARM_DECL nodes can be obtained by following the TREE_CHAIN links.

DECL_RESULT

This macro returns the RESULT_DECL for the function.

DECL_SAVED_TREE

This macro returns the complete body of the function.

TREE_TYPE

This macro returns the FUNCTION_TYPE or METHOD_TYPE for the function.

DECL_INITIAL

A function that has a definition in the current translation unit will have a non-NULL DECL_INITIAL. However, back ends should not make use of the particular value given by DECL_INITIAL.

It should contain a tree of BLOCK nodes that mirrors the scopes that variables are bound in the function. Each block contains a list of decls declared in a basic block, a pointer to a chain of blocks at the next lower scope level, then a pointer to the next block at the same level and a backpointer to the parent BLOCK or FUNCTION_DECL. So given a function as follows:

```c
void foo()
{
  int a;
  {
    int b;
  }
  int c;
}
```

you would get the following:

```c
tree foo = FUNCTION_DECL;
tree decl_a = VAR_DECL;
tree decl_b = VAR_DECL;
tree decl_c = VAR_DECL;
tree block_a = BLOCK;
tree block_b = BLOCK;
tree block_c = BLOCK;
```
BLOCK_VARS(block_a) = decl_a;
BLOCK_SUBBLOCKS(block_a) = block_b;
BLOCK_CHAIN(block_a) = block_c;
BLOCK_SUPERCONTEXT(block_a) = foo;
BLOCK_VARS(block_b) = decl_b;
BLOCK_SUPERCONTEXT(block_b) = block_a;
BLOCK_VARS(block_c) = decl_c;
BLOCK_SUPERCONTEXT(block_c) = foo;
DECL_INITIALIZER(foo) = block_a;

11.8.2 Function Properties

To determine the scope of a function, you can use the DECL_CONTEXT macro. This macro will return the class (either a RECORD_TYPE or a UNION_TYPE) or namespace (a NAMESPACE_DECL) of which the function is a member. For a virtual function, this macro returns the class in which the function was actually defined, not the base class in which the virtual declaration occurred.

In C, the DECL_CONTEXT for a function maybe another function. This representation indicates that the GNU nested function extension is in use. For details on the semantics of nested functions, see the GCC Manual. The nested function can refer to local variables in its containing function. Such references are not explicitly marked in the tree structure; back ends must look at the DECL_CONTEXT for the referenced VAR_DECL. If the DECL_CONTEXT for the referenced VAR_DECL is not the same as the function currently being processed, and neither DECL_EXTERNAL nor TREE_STATIC hold, then the reference is to a local variable in a containing function, and the back end must take appropriate action.

DECL_EXTERNAL
This predicate holds if the function is undefined.

TREE_PUBLIC
This predicate holds if the function has external linkage.

TREE_STATIC
This predicate holds if the function has been defined.

TREE_THIS_VOLATILE
This predicate holds if the function does not return normally.

TREE_READONLY
This predicate holds if the function can only read its arguments.

DECL_PURE_P
This predicate holds if the function can only read its arguments, but may also read global memory.

DECL_VIRTUAL_P
This predicate holds if the function is virtual.

DECL_ARTIFICIAL
This macro holds if the function was implicitly generated by the compiler, rather than explicitly declared. In addition to implicitly generated class member functions, this macro holds for the special functions created to implement static initialization and destruction, to compute run-time type information, and so forth.
DECL_FUNCTION_SPECIFIC_TARGET

This macro returns a tree node that holds the target options that are to be used to compile this particular function or NULL_TREE if the function is to be compiled with the target options specified on the command line.

DECL_FUNCTION_SPECIFIC_Optimization

This macro returns a tree node that holds the optimization options that are to be used to compile this particular function or NULL_TREE if the function is to be compiled with the optimization options specified on the command line.

11.9 Language-dependent trees

Front ends may wish to keep some state associated with various GENERIC trees while parsing. To support this, trees provide a set of flags that may be used by the front end. They are accessed using TREE_LANG_FLAG_n where ‘n’ is currently 0 through 6.

If necessary, a front end can use some language-dependent tree codes in its GENERIC representation, so long as it provides a hook for converting them to GIMPLE and doesn’t expect them to work with any (hypothetical) optimizers that run before the conversion to GIMPLE. The intermediate representation used while parsing C and C++ looks very little like GENERIC, but the C and C++ gimplifier hooks are perfectly happy to take it as input and spit out GIMPLE.

11.10 C and C++ Trees

This section documents the internal representation used by GCC to represent C and C++ source programs. When presented with a C or C++ source program, GCC parses the program, performs semantic analysis (including the generation of error messages), and then produces the internal representation described here. This representation contains a complete representation for the entire translation unit provided as input to the front end. This representation is then typically processed by a code-generator in order to produce machine code, but could also be used in the creation of source browsers, intelligent editors, automatic documentation generators, interpreters, and any other programs needing the ability to process C or C++ code.

This section explains the internal representation. In particular, it documents the internal representation for C and C++ source constructs, and the macros, functions, and variables that can be used to access these constructs. The C++ representation is largely a superset of the representation used in the C front end. There is only one construct used in C that does not appear in the C++ front end and that is the GNU “nested function” extension. Many of the macros documented here do not apply in C because the corresponding language constructs do not appear in C.

The C and C++ front ends generate a mix of GENERIC trees and ones specific to C and C++. These language-specific trees are higher-level constructs than the ones in GENERIC to make the parser’s job easier. This section describes those trees that aren’t part of GENERIC as well as aspects of GENERIC trees that are treated in a language-specific manner.

If you are developing a “back end”, be it a code-generator or some other tool, that uses this representation, you may occasionally find that you need to ask questions not easily answered by the functions and macros available here. If that situation occurs, it is quite
likely that GCC already supports the functionality you desire, but that the interface is simply not documented here. In that case, you should ask the GCC maintainers (via mail to gcc@gcc.gnu.org) about documenting the functionality you require. Similarly, if you find yourself writing functions that do not deal directly with your back end, but instead might be useful to other people using the GCC front end, you should submit your patches for inclusion in GCC.

11.10.1 Types for C++

In C++, an array type is not qualified; rather the type of the array elements is qualified. This situation is reflected in the intermediate representation. The macros described here will always examine the qualification of the underlying element type when applied to an array type. (If the element type is itself an array, then the recursion continues until a non-array type is found, and the qualification of this type is examined.) So, for example, CP_TYPE_CONST_P will hold of the type const int () [7], denoting an array of seven ints.

The following functions and macros deal with cv-qualification of types:

cp_type_quads
This function returns the set of type qualifiers applied to this type. This value is TYPE_UNQUALIFIED if no qualifiers have been applied. The TYPE_QUAL_CONST bit is set if the type is const-qualified. The TYPE_QUAL_VOLATILE bit is set if the type is volatile-qualified. The TYPE_QUAL_RESTRICT bit is set if the type is restrict-qualified.

CP_TYPE_CONST_P
This macro holds if the type is const-qualified.

CP_TYPE_VOLATILE_P
This macro holds if the type is volatile-qualified.

CP_TYPE_RESTRICT_P
This macro holds if the type is restrict-qualified.

CP_TYPE_CONST_NON_VOLATILE_P
This predicate holds for a type that is const-qualified, but not volatile-qualified; other cv-qualifiers are ignored as well: only the const-ness is tested.

A few other macros and functions are usable with all types:

TYPE_SIZE
The number of bits required to represent the type, represented as an INTEGER_CST. For an incomplete type, TYPE_SIZE will be NULL_TREE.

TYPE_ALIGN
The alignment of the type, in bits, represented as an int.

TYPE_NAME
This macro returns a declaration (in the form of a TYPE_DECL) for the type. (Note this macro does not return an IDENTIFIER_NODE, as you might expect, given its name!) You can look at the DECL_NAME of the TYPE_DECL to obtain the actual name of the type. The TYPE_NAME will be NULL_TREE for a type that is not a built-in type, the result of a typedef, or a named class type.
This predicate holds if the type is an integral type. Notice that in C++, enumerations are not integral types.

This predicate holds if the type is an integral type (in the C++ sense) or a floating point type.

This predicate holds for a class-type.

This predicate holds for a built-in type.

This predicate holds if the type is a pointer to data member.

This predicate holds if the type is a pointer type, and the pointee is not a data member.

This predicate holds for a pointer to function type.

This predicate holds for a pointer to object type. Note however that it does not hold for the generic pointer to object type void *. You may use TYPE_PTROBJ_P to test for a pointer to object type as well as void *.

The table below describes types specific to C and C++ as well as language-dependent info about GENERIC types.

Used to represent pointer types, and pointer to data member types. If TREE_TYPE is a pointer to data member type, then TYPE_PTRDATA MEM_P will hold. For a pointer to data member type of the form 'T X::*', TYPE_PTRMEM_CLASS_TYPE will be the type X, while TYPE_PTRMEM_POINTED_TO_TYPE will be the type T.

Used to represent struct and class types in C and C++. If TYPE_PTRMEMFUNC_P holds, then this type is a pointer-to-member type. In that case, the TYPE_PTRMEMFUNC_FN_TYPE is a POINTER_TYPE pointing to a METHOD_TYPE. The METHOD_TYPE is the type of a function pointed to by the pointer-to-member function. If TYPE_PTRMEMFUNC_P does not hold, this type is a class type. For more information, see Section 11.10.3 [Classes], page 204.

This node is used to represent a type the knowledge of which is insufficient for a sound processing.

Used to represent a construct of the form typename T::A. The TYPE_CONTEXT is T; the TYPE_NAME is an IDENTIFIER_NODE for A. If the type is specified via a template-id, then TYPENAME_TYPE_FULLNAME yields a TEMPLATE_ID_EXPR.
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TREE_TYPE is non-NULL if the node is implicitly generated in support for the implicit typename extension; in which case the TREE_TYPE is a type node for the base-class.

TYPEOF_TYPE
Used to represent the __typeof__ extension. The TYPE_FIELDS is the expression the type of which is being represented.

11.10.2 Namespaces
The root of the entire intermediate representation is the variable global_namespace. This is the namespace specified with :: in C++ source code. All other namespaces, types, variables, functions, and so forth can be found starting with this namespace.

However, except for the fact that it is distinguished as the root of the representation, the global namespace is no different from any other namespace. Thus, in what follows, we describe namespaces generally, rather than the global namespace in particular.

A namespace is represented by a NAMESPACE_DECL node.

The following macros and functions can be used on a NAMESPACE_DECL:

DECL_NAME
This macro is used to obtain the IDENTIFIER_NODE corresponding to the unqualified name of the name of the namespace (see Section 11.2.2 [Identifiers], page 167). The name of the global namespace is ‘::’, even though in C++ the global namespace is unnamed. However, you should use comparison with global_namespace, rather than DECL_NAME to determine whether or not a namespace is the global one. An unnamed namespace will have a DECL_NAME equal to anonymous_namespace_name. Within a single translation unit, all unnamed namespaces will have the same name.

DECL_CONTEXT
This macro returns the enclosing namespace. The DECL_CONTEXT for the global_namespace is NULL_TREE.

DECL_NAMESPACE_ALIAS
If this declaration is for a namespace alias, then DECL_NAMESPACE_ALIAS is the namespace for which this one is an alias.

Do not attempt to use cp_namespace_decls for a namespace which is an alias. Instead, follow DECL_NAMESPACE_ALIAS links until you reach an ordinary, non-alias, namespace, and call cp_namespace_decls there.

DECL_NAMESPACE_STD_P
This predicate holds if the namespace is the special ::std namespace.

cp_namespace_decls
This function will return the declarations contained in the namespace, including types, overloaded functions, other namespaces, and so forth. If there are no declarations, this function will return NULL_TREE. The declarations are connected through their TREE_CHAIN fields.

Although most entries on this list will be declarations, TREE_LIST nodes may also appear. In this case, the TREE_VALUE will be an OVERLOAD. The value of the
TREE_PURPOSE is unspecified; back ends should ignore this value. As with the
other kinds of declarations returned by cp_namespace_decls, the TREE_CHAIN
will point to the next declaration in this list.

For more information on the kinds of declarations that can occur on this list,
See Section 11.4 [Declarations], page 172. Some declarations will not appear on
this list. In particular, no FIELD_DECL, LABEL_DECL, or PARM_DECL nodes will
appear here.

This function cannot be used with namespaces that have DECL_NAMESPACE_
ALIAS set.

11.10.3 Classes

Besides namespaces, the other high-level scoping construct in C++ is the class. (Throughout
this manual the term class is used to mean the types referred to in the ANSI/ISO
C++ Standard as classes; these include types defined with the class, struct, and union
keywords.)

A class type is represented by either a RECORD_TYPE or a UNION_TYPE. A class declared
with the union tag is represented by a UNION_TYPE, while classes declared with either the
struct or the class tag are represented by RECORD_TYPES. You can use the CLASSTYPE_
DECLARED_CLASS macro to discern whether or not a particular type is a class as opposed
to a struct. This macro will be true only for classes declared with the class tag.

Almost all members are available on the TYPE_FIELDS list. Given one member, the next
can be found by following the TREE_CHAIN. You should not depend in any way on the
order in which fields appear on this list. All nodes on this list will be ‘DECL’ nodes. A
FIELD_DECL is used to represent a non-static data member, a VAR_DECL is used to represent
a static data member, and a TYPE_DECL is used to represent a type. Note that the CONST_
DECL for an enumeration constant will appear on this list, if the enumeration type was
declared in the class. (Of course, the TYPE_DECL for the enumeration type will appear here
as well.) There are no entries for base classes on this list. In particular, there is no FIELD_
DECL for the “base-class portion” of an object. If a function member is overloaded, each
of the overloaded functions appears; no OVERLOAD nodes appear on the TYPE_FIELDS list.
Implicitly declared functions (including default constructors, copy constructors, assignment
operators, and destructors) will appear on this list as well.

The TYPE_VFIELD is a compiler-generated field used to point to virtual function tables.
It may or may not appear on the TYPE_FIELDS list. However, back ends should handle the
TYPE_VFIELD just like all the entries on the TYPE_FIELDS list.

Every class has an associated binfo, which can be obtained with TYPE_BINFO. Binfos
are used to represent base-classes. The binfo given by TYPE_BINFO is the degenerate case,
whereby every class is considered to be its own base-class. The base binfos for a particular
binfo are held in a vector, whose length is obtained with BINFO_N_BASE_BINfos. The base
binfos themselves are obtained with BINFO_BASE_BINFO and BINFO_BASE_ITERATE. To add
a new binfo, use BINFO_BASE_APPEND. The vector of base binfos can be obtained with
BINFO_BASE_BINfos, but normally you do not need to use that. The class type associated
with a binfo is given by BINFO_TYPE. It is not always the case that BINFO_TYPE (TYPE_
BINFO (x)), because of typedefs and qualified types. Neither is it the case that TYPE_BINFO
(BINFO_TYPE (y)) is the same binfo as y. The reason is that if y is a binfo representing a
base-class B of a derived class D, then BINFO_TYPE (y) will be B, and TYPE_BINFO (BINFO_TYPE (y)) will be B as its own base-class, rather than as a base-class of D.

The access to a base type can be found with BINFO_BASE_ACCESS. This will produce access_public_node, access_private_node or access_protected_node. If bases are always public, BINFO_BASE_ACCESS may be NULL.

BINFO_VIRTUAL_P is used to specify whether the binfo is inherited virtually or not. The other flags, BINFO_FLAG_0 to BINFO_FLAG_6, can be used for language specific use.

The following macros can be used on a tree node representing a class-type.

LOCAL_CLASS_P
This predicate holds if the class is local class i.e. declared inside a function body.

TYPE_POLYMORPHIC_P
This predicate holds if the class has at least one virtual function (declared or inherited).

TYPE_HAS_DEFAULT_CONSTRUCTOR
This predicate holds whenever its argument represents a class-type with default constructor.

CLASSTYPE_HAS_MUTABLE
TYPE_HAS_MUTABLE_P
These predicates hold for a class-type having a mutable data member.

CLASSTYPE_NON_POD_P
This predicate holds only for class-types that are not PODs.

TYPE_HAS_NEW_OPERATOR
This predicate holds for a class-type that defines operator new.

TYPE_HAS_ARRAY_NEW_OPERATOR
This predicate holds for a class-type for which operator new[] is defined.

TYPE_OVERLOADS_CALL_EXPR
This predicate holds for class-type for which the function call operator() is overloaded.

TYPE_OVERLOADSARRAY_REF
This predicate holds for a class-type that overloads operator[].

TYPE_OVERLOADS_ARROW
This predicate holds for a class-type for which operator-> is overloaded.

11.10.4 Functions for C++
A function is represented by a FUNCTION_DECL node. A set of overloaded functions is sometimes represented by an OVERLOAD node.

An OVERLOAD node is not a declaration, so none of the ‘DECL_’ macros should be used on an OVERLOAD. An OVERLOAD node is similar to a TREE_LIST. Use OVL_CURRENT to get the function associated with an OVERLOAD node; use OVL_NEXT to get the next OVERLOAD node in the list of overloaded functions. The macros OVL_CURRENT and OVL_NEXT are actually
polymorphic; you can use them to work with FUNCTION_DECL nodes as well as with overloads. In the case of a FUNCTION_DECL, OVL_CURRENT will always return the function itself, and OVL_NEXT will always be NULL_TREE.

To determine the scope of a function, you can use the DECL_CONTEXT macro. This macro will return the class (either a RECORD_TYPE or a UNION_TYPE) or namespace (a NAMESPACE_DECL) of which the function is a member. For a virtual function, this macro returns the class in which the function was actually defined, not the base class in which the virtual declaration occurred.

If a friend function is defined in a class scope, the DECL_FRIEND_CONTEXT macro can be used to determine the class in which it was defined. For example, in

```c
class C { friend void f() {});
```

the DECL_CONTEXT for f will be the global_namespace, but the DECL_FRIEND_CONTEXT will be the RECORD_TYPE for C.

The following macros and functions can be used on a FUNCTION_DECL:

DECL_MAIN_P
- This predicate holds for a function that is the program entry point ::code.

DECL_LOCAL_FUNCTION_P
- This predicate holds if the function was declared at block scope, even though it has a global scope.

DECL_ANTICIPATED
- This predicate holds if the function is a built-in function but its prototype is not yet explicitly declared.

DECL_EXTERN_C_FUNCTION_P
- This predicate holds if the function is declared as an `extern "C"` function.

DECL_LINKONCE_P
- This macro holds if multiple copies of this function may be emitted in various translation units. It is the responsibility of the linker to merge the various copies. Template instantiations are the most common example of functions for which DECL_LINKONCE_P holds; G++ instantiates needed templates in all translation units which require them, and then relies on the linker to remove duplicate instantiations.

FIXME: This macro is not yet implemented.

DECL_FUNCTION_MEMBER_P
- This macro holds if the function is a member of a class, rather than a member of a namespace.

DECL_STATIC_FUNCTION_P
- This predicate holds if the function a static member function.

DECL_NONSTATIC_MEMBER_FUNCTION_P
- This macro holds for a non-static member function.

DECL_CONST_MEMFUNC_P
- This predicate holds for a const-member function.
DECL_VOLATILE_MEMFUNC_P
This predicate holds for a volatile-member function.

DECL_CONSTRUCTOR_P
This macro holds if the function is a constructor.

DECL_NONCONVERTING_P
This predicate holds if the constructor is a non-converting constructor.

DECL_COMPLETE_CONSTRUCTOR_P
This predicate holds for a function which is a constructor for an object of a complete type.

DECL_BASE_CONSTRUCTOR_P
This predicate holds for a function which is a constructor for a base class sub-object.

DECL_COPY_CONSTRUCTOR_P
This predicate holds for a function which is a copy-constructor.

DECL_DESTRUCTOR_P
This macro holds if the function is a destructor.

DECL_COMPLETE_DESTRUCTOR_P
This predicate holds if the function is the destructor for an object a complete type.

DECL_OVERLOADED_OPERATOR_P
This macro holds if the function is an overloaded operator.

DECL_CONV_FN_P
This macro holds if the function is a type-conversion operator.

DECL_GLOBAL_CTOR_P
This predicate holds if the function is a file-scope initialization function.

DECL_GLOBAL_DTOR_P
This predicate holds if the function is a file-scope finalization function.

DECL_THUNK_P
This predicate holds if the function is a thunk.

These functions represent stub code that adjusts the this pointer and then jumps to another function. When the jumped-to function returns, control is transferred directly to the caller, without returning to the thunk. The first parameter to the thunk is always the this pointer; the thunk should add THUNK_DELTA to this value. (The THUNK_DELTA is an int, not an INTEGER_CST.)

Then, if THUNK_VCALL_OFFSET (an INTEGER_CST) is nonzero the adjusted this pointer must be adjusted again. The complete calculation is given by the following pseudo-code:

```c
this += THUNK_DELTA
if (THUNK_VCALL_OFFSET)
    this += (*((ptrdiff_t **) this)[THUNK_VCALL_OFFSET])
```

Finally, the thunk should jump to the location given by DECL_INITIAL; this will always be an expression for the address of a function.
DECL_NON_THUNK_FUNCTION_P
This predicate holds if the function is not a thunk function.

GLOBAL_INIT_PRIORITY
If either DECL_GLOBAL_CTOR_P or DECL_GLOBAL_DTOR_P holds, then this gives the initialization priority for the function. The linker will arrange that all functions for which DECL_GLOBAL_CTOR_P holds are run in increasing order of priority before main is called. When the program exits, all functions for which DECL_GLOBAL_DTOR_P holds are run in the reverse order.

TYPE_RAISES_EXCEPTIONS
This macro returns the list of exceptions that a (member-)function can raise. The returned list, if non NULL, is comprised of nodes whose TREE_VALUE represents a type.

TYPE_NOTHROW_P
This predicate holds when the exception-specification of its arguments is of the form ‘()’.

DECL_ARRAY_DELETE_OPERATOR_P
This predicate holds if the function an overloaded operator delete[].

11.10.5 Statements for C and C++
A function that has a definition in the current translation unit has a non-NULL DECL_INITIAL. However, back ends should not make use of the particular value given by DECL_INITIAL.

The DECL_SAVED_TREE gives the complete body of the function.

There are tree nodes corresponding to all of the source-level statement constructs, used within the C and C++ frontends. These are enumerated here, together with a list of the various macros that can be used to obtain information about them. There are a few macros that can be used with all statements:

STMT_IS_FULL_EXPR_P
In C++, statements normally constitute “full expressions”; temporaries created during a statement are destroyed when the statement is complete. However, G++ sometimes represents expressions by statements; these statements will not have STMT_IS_FULL_EXPR_P set. Temporaries created during such statements should be destroyed when the innermost enclosing statement with STMT_IS_FULL_EXPR_P set is exited.

Here is the list of the various statement nodes, and the macros used to access them. This documentation describes the use of these nodes in non-template functions (including instantiations of template functions). In template functions, the same nodes are used, but sometimes in slightly different ways.

Many of the statements have substatements. For example, a while loop has a body, which is itself a statement. If the substatement is NULL_TREE, it is considered equivalent to a statement consisting of a single ;, i.e., an expression statement in which the expression has been omitted. A substatement may in fact be a list of statements, connected via their TREE_CHAINs. So, you should always process the statement tree by looping over substatements, like this:
void processStmt (stmt) {
    tree stmt;
    while (stmt) {
        switch (TREE_CODE (stmt)) {
        case IF_STMT:
            process_stmt (THEN_CLAUSE (stmt));
            /* More processing here. */
            break;
        ...
        }
        stmt = TREE_CHAIN (stmt);
    }
}

In other words, while the then clause of an if statement in C++ can be only one statement (although that one statement may be a compound statement), the intermediate representation sometimes uses several statements chained together.

**BREAK_STMT**

Used to represent a break statement. There are no additional fields.

**CLEANUP_STMT**

Used to represent an action that should take place upon exit from the enclosing scope. Typically, these actions are calls to destructors for local objects, but back ends cannot rely on this fact. If these nodes are in fact representing such destructors, CLEANUP_DECL will be the VAR_DECL destroyed. Otherwise, CLEANUP_DECL will be NULL_TREE. In any case, the CLEANUP_EXPR is the expression to execute. The cleanups executed on exit from a scope should be run in the reverse order of the order in which the associated CLEANUP_STMTs were encountered.

**CONTINUE_STMT**

Used to represent a continue statement. There are no additional fields.

**CTOR_STMT**

Used to mark the beginning (if CTOR_BEGIN_P holds) or end (if CTOR_END_P holds) of the main body of a constructor. See also SUBOBJECT for more information on how to use these nodes.

**DO_STMT**

Used to represent a do loop. The body of the loop is given by DO_BODY while the termination condition for the loop is given by DO_COND. The condition for a do-statement is always an expression.

**EMPTY_CLASS_EXPR**

Used to represent a temporary object of a class with no data whose address is never taken. (All such objects are interchangeable.) The TREE_TYPE represents the type of the object.
EXPR_STMT
Used to represent an expression statement. Use EXPR_STMT_EXPR to obtain the expression.

FOR_STMT
Used to represent a for statement. The FOR_INIT_STMT is the initialization statement for the loop. The FOR_COND is the termination condition. The FOR_EXPR is the expression executed right before the FOR_COND on each loop iteration; often, this expression increments a counter. The body of the loop is given by FOR_BODY. FOR_SCOPE holds the scope of the for statement (used in the C++ front end only). Note that FOR_INIT_STMT and FOR_BODY return statements, while FOR_COND and FOR_EXPR return expressions.

HANDLER
Used to represent a C++ catch block. The HANDLER_TYPE is the type of exception that will be caught by this handler; it is equal (by pointer equality) to NULL if this handler is for all types. HANDLER_PARMS is the DECL_STMT for the catch parameter, and HANDLER_BODY is the code for the block itself.

IF_STMT
Used to represent an if statement. The IF_COND is the expression. If the condition is a TREE_LIST, then the TREE_PURPOSE is a statement (usually a DECL_STMT). Each time the condition is evaluated, the statement should be executed. Then, the TREE_VALUE should be used as the conditional expression itself. This representation is used to handle C++ code like this:

```cpp
if (int i = 7) ...
```

where there is a new local variable (or variables) declared within the condition. The THEN_CLAUSE represents the statement given by the then condition, while the ELSE_CLAUSE represents the statement given by the else condition. C++ distinguishes between this and COND_EXPR for handling templates.

SUBOBJECT
In a constructor, these nodes are used to mark the point at which a subobject of this is fully constructed. If, after this point, an exception is thrown before a CTOR_STMT with CTOR_END_P set is encountered, the SUBOBJECT_CLEANUP must be executed. The cleanups must be executed in the reverse order in which they appear.

SWITCH_STMT
Used to represent a switch statement. The SWITCH_STMT_COND is the expression on which the switch is occurring. See the documentation for an IF_STMT for more information on the representation used for the condition. The SWITCH_STMT_BODY is the body of the switch statement. The SWITCH_STMT_TYPE is the original type of switch expression as given in the source, before any compiler conversions. The SWITCH_STMT_SCOPE is the statement scope (used in the C++ front end only).

There are also two boolean flags used with SWITCH_STMT. SWITCH_STMT_ALL_CASES_P is true if the switch includes a default label or the case label ranges
cover all possible values of the condition expression. \texttt{SWITCH_STMT\_NO\_BREAK\_P} is true if there are no \texttt{break} statements in the switch.

\textbf{TRY\_BLOCK}

Used to represent a \texttt{try} block. The body of the try block is given by \texttt{TRY\_STMTS}. Each of the catch blocks is a \texttt{HANDLER} node. The first handler is given by \texttt{TRY\_HANDLERS}. Subsequent handlers are obtained by following the \texttt{TREE\_CHAIN} link from one handler to the next. The body of the handler is given by \texttt{HANDLER\_BODY}.

If \texttt{CLEANUP\_P} holds of the \texttt{TRY\_BLOCK}, then the \texttt{TRY\_HANDLERS} will not be a \texttt{HANDLER} node. Instead, it will be an expression that should be executed if an exception is thrown in the try block. It must rethrow the exception after executing that code. And, if an exception is thrown while the expression is executing, \texttt{terminate} must be called.

\textbf{USING\_STMT}

Used to represent a \texttt{using} directive. The namespace is given by \texttt{USING\_STMT\_NAMESPACE}, which will be a \texttt{NAMESPACE\_DECL}. This node is needed inside template functions, to implement using directives during instantiation.

\textbf{WHILE\_STMT}

Used to represent a \texttt{while} loop. The \texttt{WHILE\_COND} is the termination condition for the loop. See the documentation for an \texttt{IF\_STMT} for more information on the representation used for the condition.

The \texttt{WHILE\_BODY} is the body of the loop.

\section*{11.10.6 C++ Expressions}

This section describes expressions specific to the C and C++ front ends.

\textbf{TYPEID\_EXPR}

Used to represent a \texttt{typeid} expression.

\textbf{NEW\_EXPR}

\textbf{VEC\_NEW\_EXPR}

Used to represent a call to \texttt{new} and \texttt{new[]} respectively.

\textbf{DELETE\_EXPR}

\textbf{VEC\_DELETE\_EXPR}

Used to represent a call to \texttt{delete} and \texttt{delete[]} respectively.

\textbf{MEMBER\_REF}

Represents a reference to a member of a class.

\textbf{THROW\_EXPR}

Represents an instance of \texttt{throw} in the program. Operand 0, which is the expression to throw, may be \texttt{NULL\_TREE}.

\textbf{AGGR\_INIT\_EXPR}

An \texttt{AGGR\_INIT\_EXPR} represents the initialization as the return value of a function call, or as the result of a constructor. An \texttt{AGGR\_INIT\_EXPR} will only appear as a full-expression, or as the second operand of a \texttt{TARGET\_EXPR}. \texttt{AGGR\_INIT\_EXPRs} have a representation similar to that of \texttt{CALL\_EXPRs}. You can use the
AGGR_INIT_EXPR_FN and AGGR_INIT_EXPR_ARG macros to access the function
to call and the arguments to pass.
If AGGR_INIT_VIA_CTOR_P holds of the AGGR_INIT_EXPR, then the initialization
is via a constructor call. The address of the AGGR_INIT_EXPR_SLOT operand,
which is always a VAR_DECL, is taken, and this value replaces the first argument
in the argument list.
In either case, the expression is void.
Chapter 12: GIMPLE

12 GIMPLE

GIMPLE is a three-address representation derived from GENERIC by breaking down GENERIC expressions into tuples of no more than 3 operands (with some exceptions like function calls). GIMPLE was heavily influenced by the SIMPLE IL used by the McCAT compiler project at McGill University, though we have made some different choices. For one thing, SIMPLE doesn’t support goto.

Temporaries are introduced to hold intermediate values needed to compute complex expressions. Additionally, all the control structures used in GENERIC are lowered into conditional jumps, lexical scopes are removed and exception regions are converted into an on the side exception region tree.

The compiler pass which converts GENERIC into GIMPLE is referred to as the ‘gimplifier’. The gimplifier works recursively, generating GIMPLE tuples out of the original GENERIC expressions.

One of the early implementation strategies used for the GIMPLE representation was to use the same internal data structures used by front ends to represent parse trees. This simplified implementation because we could leverage existing functionality and interfaces. However, GIMPLE is a much more restrictive representation than abstract syntax trees (AST), therefore it does not require the full structural complexity provided by the main tree data structure.

The GENERIC representation of a function is stored in the DECL_SAVED_TREE field of the associated FUNCTION_DECL tree node. It is converted to GIMPLE by a call to gimplify_function_tree.

If a front end wants to include language-specific tree codes in the tree representation which it provides to the back end, it must provide a definition of LANG_HOOKS_GIMPLIFY_EXPR which knows how to convert the front end trees to GIMPLE. Usually such a hook will involve much of the same code for expanding front end trees to RTL. This function can return fully lowered GIMPLE, or it can return GENERIC trees and let the main gimplifier lower them the rest of the way; this is often simpler. GIMPLE that is not fully lowered is known as ‘High GIMPLE’ and consists of the IL before the pass pass_lower_cf. High GIMPLE contains some container statements like lexical scopes (represented by GIMPLE_BIND) and nested expressions (e.g., GIMPLE_TRY), while “Low GIMPLE” exposes all of the implicit jumps for control and exception expressions directly in the IL and EH region trees.

The C and C++ front ends currently convert directly from front end trees to GIMPLE, and hand that off to the back end rather than first converting to GENERIC. Their gimplifier hooks know about all the _STMT nodes and how to convert them to GENERIC forms. There was some work done on a genericization pass which would run first, but the existence of STMT_EXPR meant that in order to convert all of the C statements into GENERIC equivalents would involve walking the entire tree anyway, so it was simpler to lower all the way. This might change in the future if someone writes an optimization pass which would work better with higher-level trees, but currently the optimizers all expect GIMPLE.

You can request to dump a C-like representation of the GIMPLE form with the flag ‘-fdump-tree-gimple’.
12.1 Tuple representation

GIMPLE instructions are tuples of variable size divided in two groups: a header describing the instruction and its locations, and a variable length body with all the operands. Tuples are organized into a hierarchy with 3 main classes of tuples.

12.1.1 gimple (gsbase)

This is the root of the hierarchy, it holds basic information needed by most GIMPLE statements. There are some fields that may not be relevant to every GIMPLE statement, but those were moved into the base structure to take advantage of holes left by other fields (thus making the structure more compact). The structure takes 4 words (32 bytes) on 64 bit hosts:

<table>
<thead>
<tr>
<th>Field</th>
<th>Size (bits)</th>
</tr>
</thead>
<tbody>
<tr>
<td>code</td>
<td>8</td>
</tr>
<tr>
<td>subcode</td>
<td>16</td>
</tr>
<tr>
<td>no_warning</td>
<td>1</td>
</tr>
<tr>
<td>visited</td>
<td>1</td>
</tr>
<tr>
<td>nontemporal_move</td>
<td>1</td>
</tr>
<tr>
<td>plf</td>
<td>2</td>
</tr>
<tr>
<td>modified</td>
<td>1</td>
</tr>
<tr>
<td>has_volatile_ops</td>
<td>1</td>
</tr>
<tr>
<td>references_memory_p</td>
<td>1</td>
</tr>
<tr>
<td>uid</td>
<td>32</td>
</tr>
<tr>
<td>location</td>
<td>32</td>
</tr>
<tr>
<td>num_ops</td>
<td>32</td>
</tr>
<tr>
<td>bb</td>
<td>64</td>
</tr>
<tr>
<td>block</td>
<td>63</td>
</tr>
</tbody>
</table>

Total size 32 bytes

- **code** Main identifier for a GIMPLE instruction.
- **subcode** Used to distinguish different variants of the same basic instruction or provide flags applicable to a given code. The subcode flags field has different uses depending on the code of the instruction, but mostly it distinguishes instructions of the same family. The most prominent use of this field is in assignments, where subcode indicates the operation done on the RHS of the assignment. For example, \( a = b + c \) is encoded as GIMPLE_ASSIGN <PLUS_EXPR, a, b, c>.
- **no_warning** Bitflag to indicate whether a warning has already been issued on this statement.
- **visited** General purpose “visited” marker. Set and cleared by each pass when needed.
- **nontemporal_move** Bitflag used in assignments that represent non-temporal moves. Although this bitflag is only used in assignments, it was moved into the base to take advantage of the bit holes left by the previous fields.
- **plf** Pass Local Flags. This 2-bit mask can be used as general purpose markers by any pass. Passes are responsible for clearing and setting these two flags accordingly.
- **modified** Bitflag to indicate whether the statement has been modified. Used mainly by the operand scanner to determine when to re-scan a statement for operands.
• **has_volatile_ops** Bitflag to indicate whether this statement contains operands that have been marked volatile.

• **references_memory_p** Bitflag to indicate whether this statement contains memory references (i.e., its operands are either global variables, or pointer dereferences or anything that must reside in memory).

• **uid** This is an unsigned integer used by passes that want to assign IDs to every statement. These IDs must be assigned and used by each pass.

• **location** This is a `location_t` identifier to specify source code location for this statement. It is inherited from the front end.

• **num_ops** Number of operands that this statement has. This specifies the size of the operand vector embedded in the tuple. Only used in some tuples, but it is declared in the base tuple to take advantage of the 32-bit hole left by the previous fields.

• **bb** Basic block holding the instruction.

• **block** Lexical block holding this statement. Also used for debug information generation.

### 12.1.2 gimple_statement_with_ops

This tuple is actually split in two: `gimple_statement_with_ops_base` and `gimple_statement_with_ops`. This is needed to accommodate the way the operand vector is allocated. The operand vector is defined to be an array of 1 element. So, to allocate a dynamic number of operands, the memory allocator (`gimple_alloc`) simply allocates enough memory to hold the structure itself plus $N - 1$ operands which run “off the end” of the structure. For example, to allocate space for a tuple with 3 operands, `gimple_alloc` reserves `sizeof (struct gimple_statement_with_ops) + 2 * sizeof (tree)` bytes.

On the other hand, several fields in this tuple need to be shared with the `gimple_statement_with_memory_ops` tuple. So, these common fields are placed in `gimple_statement_with_ops_base` which is then inherited from the other two tuples.

`gsbase` 256
`def_ops` 64
`use_ops` 64
`op` `num_ops` * 64
Total 48 + 8 * `num_ops` bytes

• **gsbase** Inherited from `struct gimple`.
• **def_ops** Array of pointers into the operand array indicating all the slots that contain a variable written-to by the statement. This array is also used for immediate use chaining. Note that it would be possible to not rely on this array, but the changes required to implement this are pretty invasive.

• **use_ops** Similar to `def_ops` but for variables read by the statement.

• **op** Array of trees with `num_ops` slots.

### 12.1.3 gimple_statement_with_memory_ops

This tuple is essentially identical to `gimple_statement_with_ops`, except that it contains 4 additional fields to hold vectors related memory stores and loads. Similar to the pre-
vious case, the structure is split in two to accommodate for the operand vector (\texttt{gimple_statement_with_memory_ops_base} and \texttt{gimple_statement_with_memory_ops}).

Field Size (bits)
gsbase 256
def_ops 64
use_ops 64
vdef_ops 64
vuse_ops 64
stores 64
loads 64
op num_ops * 64
Total size $80 + 8 \times \text{num}_\text{ops}$ bytes

- vdef_ops Similar to def_ops but for VDEF operators. There is one entry per memory symbol written by this statement. This is used to maintain the memory SSA use-def and def-def chains.
- vuse_ops Similar to use_ops but for VUSE operators. There is one entry per memory symbol loaded by this statement. This is used to maintain the memory SSA use-def chains.
- stores Bitset with all the UIDs for the symbols written-to by the statement. This is different than vdef_ops in that all the affected symbols are mentioned in this set. If memory partitioning is enabled, the vdef_ops vector will refer to memory partitions. Furthermore, no SSA information is stored in this set.
- loads Similar to stores, but for memory loads. (Note that there is some amount of redundancy here, it should be possible to reduce memory utilization further by removing these sets).

All the other tuples are defined in terms of these three basic ones. Each tuple will add some fields.

12.2 Class hierarchy of GIMPLE statements

The following diagram shows the C++ inheritance hierarchy of statement kinds, along with their relationships to GSS_ values (layouts) and GIMPLE_ values (codes):

```
gimple
| layout: GSS_BASE
| used for 4 codes: GIMPLE_ERROR_MARK
| GIMPLE_NOP
| GIMPLE_OMP_SECTIONS_SWITCH
| GIMPLE_PREDICT
|
+ gimple_statement_with_ops_base
| (no GSS layout)
|
| + gimple_statement_with_ops
| layout: GSS_WITH_OPS
| + gcond
| code: GIMPLE_COND
|
| + gdebug
```
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- code: GIMPLE_DEBUG
- + ggoto
  - code: GIMPLE_GOTO
- + glabel
  - code: GIMPLE_LABEL
- + gswitch
  - code: GIMPLE_SWITCH
- + gimple_statement_with_memory_ops_base
  - layout: GSS_WITH_MEM_OPS_BASE
- + gimple_statement_with_memory_ops
  - layout: GSS_WITH_MEM_OPS
  - + gassign
    - code GIMPLE_ASSIGN
  - + greturn
    - code GIMPLE_RETURN
- + gcall
  - layout: GSS_CALL, code: GIMPLE_CALL
- + gasm
  - layout: GSS_ASM, code: GIMPLE_ASM
- + gtransaction
  - layout: GSS_TRANSACTION, code: GIMPLE_TRANSACTION
- + gimple_statement_omp
  - layout: GSS_OMP. Used for code GIMPLE_OMP_SECTION
  - + gomp_critical
    - layout: GSS_OMP_CRITICAL, code: GIMPLE_OMP_CRITICAL
  - + gomp_for
    - layout: GSS_OMP_FOR, code: GIMPLE_OMP_FOR
  - + gomp_parallel_layout
    - layout: GSS_OMP_PARALLEL_LAYOUT
  - + gimple_statement_omp_taskreg
    - | + gomp_parallel
      - | code: GIMPLE_OMP_PARALLEL
    - | + gomp_task
      - | code: GIMPLE_OMP_TASK
  - + gimple_statement_omp_target
    - code: GIMPLE_OMP_TARGET
  - + gomp_sections
    - layout: GSS_OMP_SECTIONS, code: GIMPLE_OMP_SECTIONS
12.3 GIMPLE instruction set

The following table briefly describes the GIMPLE instruction set.

<table>
<thead>
<tr>
<th>Instruction</th>
<th>High GIMPLE</th>
<th>Low GIMPLE</th>
</tr>
</thead>
<tbody>
<tr>
<td>GIMPLE_ASM</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_ASSIGN</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_BIND</td>
<td></td>
<td></td>
</tr>
<tr>
<td>GIMPLE_CALL</td>
<td>x</td>
<td></td>
</tr>
<tr>
<td>GIMPLE_CATCH</td>
<td></td>
<td></td>
</tr>
<tr>
<td>GIMPLE_COND</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_DEBUG</td>
<td></td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_EH_FILTER</td>
<td>x</td>
<td></td>
</tr>
<tr>
<td>GIMPLE_GOTO</td>
<td></td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_LABEL</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_NOP</td>
<td></td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_ATOMIC_LOAD</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_ATOMIC_STORE</td>
<td></td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_CONTINUE</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_CRITICAL</td>
<td></td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_FOR</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_MASTER</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_ORDERED</td>
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<td>x</td>
</tr>
<tr>
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<td></td>
<td>x</td>
</tr>
<tr>
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<td>x</td>
</tr>
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</tr>
<tr>
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<td>x</td>
</tr>
<tr>
<td>GIMPLE_OMP_SECTIONS_SWITCH</td>
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</tr>
<tr>
<td>GIMPLE_OMP_SINGLE</td>
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<tr>
<td>GIMPLE_PHI</td>
<td></td>
<td>x</td>
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<tr>
<td>GIMPLE_RESX</td>
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<tr>
<td>GIMPLE_RETURN</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_SWITCH</td>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>GIMPLE_TRY</td>
<td>x</td>
<td></td>
</tr>
</tbody>
</table>

12.4 Exception Handling

Other exception handling constructs are represented using GIMPLE_TRY_CATCH. GIMPLE_TRY_CATCH has two operands. The first operand is a sequence of statements to execute. If executing these statements does not throw an exception, then the second operand is ignored. Otherwise, if an exception is thrown, then the second operand of the GIMPLE_TRY_CATCH is checked. The second operand may have the following forms:

1. A sequence of statements to execute. When an exception occurs, these statements are executed, and then the exception is rethrown.

2. A sequence of GIMPLE_CATCH statements. Each GIMPLE_CATCH has a list of applicable exception types and handler code. If the thrown exception matches one of the caught types, the associated handler code is executed. If the handler code falls off the bottom, execution continues after the original GIMPLE_TRY_CATCH.
3. A \texttt{GIMPLE\_EH\_FILTER} statement. This has a list of permitted exception types, and code to handle a match failure. If the thrown exception does not match one of the allowed types, the associated match failure code is executed. If the thrown exception does match, it continues unwinding the stack looking for the next handler.

Currently throwing an exception is not directly represented in GIMPLE, since it is implemented by calling a function. At some point in the future we will want to add some way to express that the call will throw an exception of a known type.

Just before running the optimizers, the compiler lowers the high-level EH constructs above into a set of ‘\texttt{goto}’s, magic labels, and EH regions. Continuing to unwind at the end of a cleanup is represented with a \texttt{GIMPLE\_RESX}.

12.5 Temporaries

When simplification encounters a subexpression that is too complex, it creates a new temporary variable to hold the value of the subexpression, and adds a new statement to initialize it before the current statement. These special temporaries are known as ‘expression temporaries’, and are allocated using \texttt{get\_formal\_tmp\_var}. The compiler tries to always evaluate identical expressions into the same temporary, to simplify elimination of redundant calculations.

We can only use expression temporaries when we know that it will not be reevaluated before its value is used, and that it will not be otherwise modified\footnote{These restrictions are derived from those in Morgan 4.8.}. Other temporaries can be allocated using \texttt{get\_initialized\_tmp\_var} or \texttt{create\_tmp\_var}.

Currently, an expression like \texttt{a = b + 5} is not reduced any further. We tried converting it to something like

\begin{verbatim}
T1 = b + 5;
a = T1;
\end{verbatim}

but this bloated the representation for minimal benefit. However, a variable which must live in memory cannot appear in an expression; its value is explicitly loaded into a temporary first. Similarly, storing the value of an expression to a memory variable goes through a temporary.

12.6 Operands

In general, expressions in GIMPLE consist of an operation and the appropriate number of simple operands; these operands must either be a GIMPLE rvalue (\texttt{is\_gimple\_val}), i.e. a constant or a register variable. More complex operands are factored out into temporaries, so that

\begin{verbatim}
a = b + c + d
\end{verbatim}

becomes

\begin{verbatim}
T1 = b + c;
a = T1 + d;
\end{verbatim}

The same rule holds for arguments to a \texttt{GIMPLE\_CALL}.

The target of an assignment is usually a variable, but can also be a \texttt{MEM\_REF} or a compound lvalue as described below.
12.6.1 Compound Expressions
The left-hand side of a C comma expression is simply moved into a separate statement.

12.6.2 Compound Lvalues
Currently compound lvalues involving array and structure field references are not broken down; an expression like `a.b[2] = 42` is not reduced any further (though complex array subscripts are). This restriction is a workaround for limitations in later optimizers; if we were to convert this to

```c
T1 = &a.b;
T1[2] = 42;
```

alias analysis would not remember that the reference to `T1[2]` came by way of `a.b`, so it would think that the assignment could alias another member of `a`; this broke `struct-alias-1.c`. Future optimizer improvements may make this limitation unnecessary.

12.6.3 Conditional Expressions
A C `?:` expression is converted into an `if` statement with each branch assigning to the same temporary. So,

```c
a = b ? c : d;
```

becomes

```c
if (b == 1)
T1 = c;
else
T1 = d;
a = T1;
```

The GIMPLE level if-conversion pass re-introduces `?:` expression, if appropriate. It is used to vectorize loops with conditions using vector conditional operations.

Note that in GIMPLE, `if` statements are represented using `GIMPLE_COND`, as described below.

12.6.4 Logical Operators
Except when they appear in the condition operand of a `GIMPLE_COND`, logical ‘and’ and ‘or’ operators are simplified as follows: `a = b && c` becomes

```c
T1 = (bool)b;
if (T1 == true)
T1 = (bool)c;
a = T1;
```

Note that `T1` in this example cannot be an expression temporary, because it has two different assignments.

12.6.5 Manipulating operands
All gimple operands are of type `tree`. But only certain types of trees are allowed to be used as operand tuples. Basic validation is controlled by the function `get_gimple_rhs_class`, which given a tree code, returns an `enum` with the following values of type `enum gimple_rhs_class`

- `GIMPLE_INVALID_RHS` The tree cannot be used as a GIMPLE operand.
- `GIMPLE_TERNARY_RHS` The tree is a valid GIMPLE ternary operation.
• **GIMPLE_BINARY_RHS** The tree is a valid GIMPLE binary operation.
• **GIMPLE_UNARY_RHS** The tree is a valid GIMPLE unary operation.
• **GIMPLE_SINGLE_RHS** The tree is a single object, that cannot be split into simpler operands (for instance, **SSA_NAME**, **VAR_DECL**, **COMPONENT_REF**, etc).

This operand class also acts as an escape hatch for tree nodes that may be flattened out into the operand vector, but would need more than two slots on the RHS. For instance, a **COND_EXPR** expression of the form \((a \text{ op } b) ? x : y\) could be flattened out on the operand vector using 4 slots, but it would also require additional processing to distinguish \(c = a \text{ op } b\) from \(c = a \text{ op } b ? x : y\). Something similar occurs with **ASSERT_EXPR**. In time, these special case tree expressions should be flattened into the operand vector.

For tree nodes in the categories **GIMPLE_TERNARY_RHS**, **GIMPLE_BINARY_RHS** and **GIMPLE_UNARY_RHS**, they cannot be stored inside tuples directly. They first need to be flattened and separated into individual components. For instance, given the GENERIC expression

\[
a = b + c
\]

its tree representation is:

\[
\text{MODIFY_EXPR } <\text{VAR_DECL } <a>, \text{PLUS_EXPR } <\text{VAR_DECL } <b>, \text{VAR_DECL } <c>>>
\]

In this case, the GIMPLE form for this statement is logically identical to its GENERIC form but in GIMPLE, the **PLUS_EXPR** on the RHS of the assignment is not represented as a tree, instead the two operands are taken out of the **PLUS_EXPR** sub-tree and flattened into the GIMPLE tuple as follows:

\[
\text{GIMPLE_ASSIGN } <\text{PLUS_EXPR}, \text{VAR_DECL } <a>, \text{VAR_DECL } <b>, \text{VAR_DECL } <c>>
\]

### 12.6.6 Operand vector allocation

The operand vector is stored at the bottom of the three tuple structures that accept operands. This means, that depending on the code of a given statement, its operand vector will be at different offsets from the base of the structure. To access tuple operands use the following accessors

```c
unsigned gimple_num_ops (gimple g)  
{GIMPLE function}
Returns the number of operands in statement G.

tree gimple_op (gimple g, unsigned i)  
{GIMPLE function}
Returns operand I from statement G.

tree * gimple_ops (gimple g)  
{GIMPLE function}
Returns a pointer into the operand vector for statement G. This is computed using an internal table called gimple_ops_offset[]. This table is indexed by the gimple code of G.

When the compiler is built, this table is filled-in using the sizes of the structures used by each statement code defined in gimple.def. Since the operand vector is at the bottom of the structure, for a gimple code C the offset is computed as sizeof (struct-of C) - sizeof (tree).

This mechanism adds one memory indirection to every access when using gimple_op(), if this becomes a bottleneck, a pass can choose to memoize the result from gimple_ops() and use that to access the operands.
```
12.6.7 Operand validation

When adding a new operand to a gimple statement, the operand will be validated according to what each tuple accepts in its operand vector. These predicates are called by the `gimple_name_set_...()` function. Each tuple will use one of the following predicates (Note, this list is not exhaustive):

- **bool is_gimple_val (tree t)**
  Returns true if `t` is a "GIMPLE value", which are all the non-addressable stack variables (variables for which `is_gimple_reg` returns true) and constants (expressions for which `is_gimple_min_invariant` returns true).

- **bool is_gimple_addressable (tree t)**
  Returns true if `t` is a symbol or memory reference whose address can be taken.

- **bool is_gimple_asm_val (tree t)**
  Similar to `is_gimple_val` but it also accepts hard registers.

- **bool is_gimple_call_addr (tree t)**
  Return true if `t` is a valid expression to use as the function called by a `GIMPLE_CALL`.

- **bool is_gimple_mem_ref_addr (tree t)**
  Return true if `t` is a valid expression to use as first operand of a `MEM_REF` expression.

- **bool is_gimple_constant (tree t)**
  Return true if `t` is a valid gimple constant.

- **bool is_gimple_min_invariant (tree t)**
  Return true if `t` is a valid minimal invariant. This is different from constants, in that the specific value of `t` may not be known at compile time, but it is known that it doesn’t change (e.g., the address of a function local variable).

- **bool is_gimple_ip_invariant (tree t)**
  Return true if `t` is an interprocedural invariant. This means that `t` is a valid invariant in all functions (e.g. it can be an address of a global variable but not of a local one).

- **bool is_gimple_ip_invariant_address (tree t)**
  Return true if `t` is an `ADDR_EXPR` that does not change once the program is running (and which is valid in all functions).

12.6.8 Statement validation

- **bool is_gimple_assign (gimple g)**
  Return true if the code of `g` is `GIMPLE_ASSIGN`.

- **bool is_gimple_call (gimple g)**
  Return true if the code of `g` is `GIMPLE_CALL`.

- **bool is_gimple_debug (gimple g)**
  Return true if the code of `g` is `GIMPLE_DEBUG`.

- **bool gimple_assign_cast_p (const gimple g)**
  Return true if `g` is a `GIMPLE_ASSIGN` that performs a type cast operation.
bool gimple_debug_bind_p (gimple g)  
Return true if g is a GIMPLE_DEBUG that binds the value of an expression to a variable.

bool is_gimple_omp (gimple g)  
Return true if g is any of the OpenMP codes.

bool gimple_debug_begin_stmt_p (gimple g)  
Return true if g is a GIMPLE_DEBUG that marks the beginning of a source statement.

bool gimple_debug_inline_entry_p (gimple g)  
Return true if g is a GIMPLE_DEBUG that marks the entry point of an inlined function.

bool gimple_debug_nonbind_marker_p (gimple g)  
Return true if g is a GIMPLE_DEBUG that marks a program location, without any variable binding.

12.7 Manipulating GIMPLE statements

This section documents all the functions available to handle each of the GIMPLE instructions.

12.7.1 Common accessors

The following are common accessors for gimple statements.

enum gimple_code gimple_code (gimple g)  
Return the code for statement G.

basic_block gimple_bb (gimple g)  
Return the basic block to which statement G belongs to.

tree gimple_block (gimple g)  
Return the lexical scope block holding statement G.

enum tree_code gimple_expr_code (gimple stmt)  
Return the tree code for the expression computed by STMT. This is only meaningful for GIMPLE_CALL, GIMPLE_ASSIGN and GIMPLE_COND. If STMT is GIMPLE_CALL, it will return CALL_EXPR. For GIMPLE_COND, it returns the code of the comparison predicate. For GIMPLE_ASSIGN it returns the code of the operation performed by the RHS of the assignment.

void gimple_set_block (gimple g, tree block)  
Set the lexical scope block of G to BLOCK.

location_t gimple_locus (gimple g)  
Return locus information for statement G.

void gimple_set_locus (gimple g, location_t locus)  
Set locus information for statement G.

bool gimple_locus_empty_p (gimple g)  
Return true if G does not have locus information.
bool gimple_no_warning_p (gimple stmt)  
    Return true if no warnings should be emitted for statement STMT.

void gimple_set_visited (gimple stmt, bool visited_p)  
    Set the visited status on statement STMT to VISITED_P.

bool gimple_visited_p (gimple stmt)  
    Return the visited status on statement STMT.

void gimple_set_plf (gimple stmt, enum plf_mask plf, bool val_p)  
    Set pass local flag PLF on statement STMT to VAL_P.

unsigned int gimple_plf (gimple stmt, enum plf_mask plf)  
    Return the value of pass local flag PLF on statement STMT.

bool gimple_has_ops (gimple g)  
    Return true if statement G has register or memory operands.

bool gimple_has_mem_ops (gimple g)  
    Return true if statement G has memory operands.

unsigned gimple_num_ops (gimple g)  
    Return the number of operands for statement G.

tree * gimple_ops (gimple g)  
    Return the array of operands for statement G.

tree gimple_op (gimple g, unsigned i)  
    Return operand I for statement G.

tree * gimple_op_ptr (gimple g, unsigned i)  
    Return a pointer to operand I for statement G.

void gimple_set_op (gimple g, unsigned i, tree op)  
    Set operand I of statement G to OP.

bitmap gimple_addresses_taken (gimple stmt)  
    Return the set of symbols that have had their address taken by STMT.

struct def_optype_d * gimple_def_ops (gimple g)  
    Return the set of DEF operands for statement G.

void gimple_set_def_ops (gimple g, struct def_optype_d *def)  
    Set DEF to be the set of DEF operands for statement G.

struct use_optype_d * gimple_use_ops (gimple g)  
    Return the set of USE operands for statement G.

void gimple_set_use_ops (gimple g, struct use_optype_d *use)  
    Set USE to be the set of USE operands for statement G.
struct voptype_d * gimple_vuse_ops (gimple g)  
Return the set of VUSE operands for statement G.

void gimple_set_vuse_ops (gimple g, struct voptype_d *ops)  
Set OPS to be the set of VUSE operands for statement G.

struct voptype_d * gimple_vdef_ops (gimple g)  
Return the set of VDEF operands for statement G.

void gimple_set_vdef_ops (gimple g, struct voptype_d *ops)  
Set OPS to be the set of VDEF operands for statement G.

bitmap gimple_loaded_syms (gimple g)  
Return the set of symbols loaded by statement G. Each element of the set is the DECL_UID of the corresponding symbol.

bitmap gimple_stored_syms (gimple g)  
Return the set of symbols stored by statement G. Each element of the set is the DECL_UID of the corresponding symbol.

bool gimple_modified_p (gimple g)  
Return true if statement G has operands and the modified field has been set.

bool gimple_has_volatile_ops (gimple stmt)  
Return true if statement STMT contains volatile operands.

void gimple_set_has_volatile_ops (gimple stmt, bool volatilep)  
Return true if statement STMT contains volatile operands.

void update_stmt (gimple s)  
Mark statement S as modified, and update it.

void update_stmt_if_modified (gimple s)  
Update statement S if it has been marked modified.

gimple gimple_copy (gimple stmt)  
Return a deep copy of statement STMT.

12.8 Tuple specific accessors

12.8.1 GIMPLE_ASM

gasm *gimple_build_asm_vec (const char *string, vec<tree, va_gc> *inputs, vec<tree, va_gc> *outputs, vec<tree, va_gc> *clobbers, vec<tree, va_gc> *labels)  
Build a GIMPLE_ASM statement. This statement is used for building in-line assembly constructs. STRING is the assembly code. INPUTS, OUTPUTS, CLOBBERS and LABELS are the inputs, outputs, clobbered registers and labels.

unsigned gimple_asm_ninputs (const gasm *g)  
Return the number of input operands for GIMPLE_ASM G.
unsigned gimple_asm_noutputs (const gasm *g)  
Return the number of output operands for GIMPLE_ASM G.

unsigned gimple_asm_nclobbers (const gasm *g)  
Return the number of clobber operands for GIMPLE_ASM G.

tree gimple_asm_input_op (const gasm *g, unsigned index)  
Return input operand INDEX of GIMPLE_ASM G.

void gimple_asm_set_input_op (gasm *g, unsigned index, tree in_op)  
Set IN_OP to be input operand INDEX in GIMPLE_ASM G.

tree gimple_asm_output_op (const gasm *g, unsigned index)  
Return output operand INDEX of GIMPLE_ASM G.

void gimple_asm_set_output_op (gasm *g, unsigned index, tree out_op)  
Set OUT_OP to be output operand INDEX in GIMPLE_ASM G.

tree gimple_asm_clobber_op (const gasm *g, unsigned index)  
Return clobber operand INDEX of GIMPLE_ASM G.

void gimple_asm_set_clobber_op (gasm *g, unsigned index, tree clobber_op)  
Set CLOBBER_OP to be clobber operand INDEX in GIMPLE_ASM G.

const char * gimple_asm_string (const gasm *g)  
Return the string representing the assembly instruction in GIMPLE_ASM G.

bool gimple_asm_volatile_p (const gasm *g)  
Return true if G is an asm statement marked volatile.

void gimple_asm_set_volatile (gasm *g, bool volatile_p)  
Mark asm statement G as volatile or non-volatile based on VOLATILE_P.

12.8.2 GIMPLE_ASSIGN

gassign *gimble_build_assign (tree lhs, tree rhs)  
Build a GIMPLE_ASSIGN statement. The left-hand side is an lvalue passed in lhs. The right-hand side can be either a unary or binary tree expression. The expression tree rhs will be flattened and its operands assigned to the corresponding operand slots in the new statement. This function is useful when you already have a tree expression that you want to convert into a tuple. However, try to avoid building expression trees for the sole purpose of calling this function. If you already have the operands in separate trees, it is better to use gimple_build_assign with enum tree_code argument and separate arguments for each operand.
**gassign ** `gimple_build_assign` *(tree lhs, enum tree_code subcode, tree op1, tree op2, tree op3)*  
This function is similar to two operand `gimple_build_assign`, but is used to build a `GIMPLE_ASSIGN` statement when the operands of the right-hand side of the assignment are already split into different operands.

The left-hand side is an lvalue passed in lhs. Subcode is the `tree_code` for the right-hand side of the assignment. Op1, op2 and op3 are the operands.

**gassign ** `gimple_build_assign` *(tree lhs, enum tree_code subcode, tree op1, tree op2)*  
Like the above 5 operand `gimple_build_assign`, but with the last argument NULL - this overload should not be used for `GIMPLE_TERNARY_RHS` assignments.

**gassign ** `gimple_build_assign` *(tree lhs, enum tree_code subcode, tree op1)*  
Like the above 4 operand `gimple_build_assign`, but with the last argument NULL - this overload should be used only for `GIMPLE_UNARY_RHS` and `GIMPLE_SINGLE_RHS` assignments.

**gimple gimplify_assign** *(tree dst, tree src, gimple *seq*)  
Build a new `GIMPLE_ASSIGN` tuple and append it to the end of *SEQ_P*.

DST/SRC are the destination and source respectively. You can pass ungimplified trees in DST or SRC, in which case they will be converted to a gimple operand if necessary.

This function returns the newly created `GIMPLE_ASSIGN` tuple.

**enum tree_code gimple_assign_rhs_code** *(gimple g)*  
Return the code of the expression computed on the RHS of assignment statement G.

**enum gimple_rhs_class gimple_assign_rhs_class** *(gimple g)*  
Return the gimple rhs class of the code for the expression computed on the rhs of assignment statement G. This will never return `GIMPLE_INVALID_RHS`.

**tree gimple_assign_lhs** *(gimple g)*  
Return the LHS of assignment statement G.

**tree * gimple_assign_lhs_ptr** *(gimple g)*  
Return a pointer to the LHS of assignment statement G.

**tree gimple_assign_rhs1** *(gimple g)*  
Return the first operand on the RHS of assignment statement G.

**tree * gimple_assign_rhs1_ptr** *(gimple g)*  
Return the address of the first operand on the RHS of assignment statement G.

**tree gimple_assign_rhs2** *(gimple g)*  
Return the second operand on the RHS of assignment statement G.
tree * gimple_assign_rhs2_ptr (gimple g)  
[GINMPLE function]  
Return the address of the second operand on the RHS of assignment statement G.

tree gimple_assign_rhs3 (gimple g)  
[GINMPLE function]  
Return the third operand on the RHS of assignment statement G.

tree * gimple_assign_rhs3_ptr (gimple g)  
[GINMPLE function]  
Return the address of the third operand on the RHS of assignment statement G.

void gimple_assign_set_lhs (gimple g, tree lhs)  
[GINMPLE function]  
Set LHS to be the LHS operand of assignment statement G.

void gimple_assign_set_rhs1 (gimple g, tree rhs)  
[GINMPLE function]  
Set RHS to be the first operand on the RHS of assignment statement G.

void gimple_assign_set_rhs2 (gimple g, tree rhs)  
[GINMPLE function]  
Set RHS to be the second operand on the RHS of assignment statement G.

void gimple_assign_set_rhs3 (gimple g, tree rhs)  
[GINMPLE function]  
Set RHS to be the third operand on the RHS of assignment statement G.

bool gimple_assign_cast_p (const gimple s)  
[GINMPLE function]  
Return true if S is a type-cast assignment.

12.8.3 GIMPLE_BIND

gbind *gimple_build_bind (tree vars, gimple_seq body)  
[GINMPLE function]  
Build a GIMPLE_BIND statement with a list of variables in VARS and a body of statements in sequence BODY.

tree gimple_bind_vars (const gbind *g)  
[GINMPLE function]  
Return the variables declared in the GIMPLE_BIND statement G.

void gimple_bind_set_vars (gbind *g, tree vars)  
[GINMPLE function]  
Set VARS to be the set of variables declared in the GIMPLE_BIND statement G.

void gimple_bind_append_vars (gbind *g, tree vars)  
[GINMPLE function]  
Append VARS to the set of variables declared in the GIMPLE_BIND statement G.

gimple_seq gimple_bind_body (gbind *g)  
[GINMPLE function]  
Return the GIMPLE sequence contained in the GIMPLE_BIND statement G.

void gimple_bind_set_body (gbind *g, gimple_seq seq)  
[GINMPLE function]  
Set SEQ to be sequence contained in the GIMPLE_BIND statement G.

void gimple_bind_add_stmt (gbind *gs, gimple stmt)  
[GINMPLE function]  
Append a statement to the end of a GIMPLE_BIND’s body.

void gimple_bind_add_seq (gbind *gs, gimple_seq seq)  
[GINMPLE function]  
Append a sequence of statements to the end of a GIMPLE_BIND’s body.
tree gimple_bind_block (const gbind *g)  
Return the TREE_BLOCK node associated with GIMPLE_BIND statement G. This is analogous to the BIND_EXPR_BLOCK field in trees.

void gimple_bind_set_block (gbind *g, tree block)  
Set BLOCK to be the TREE_BLOCK node associated with GIMPLE_BIND statement G.

12.8.4 GIMPLE_CALL

gcall *gimple_build_call (tree fn, unsigned nargs, ...)  
Build a GIMPLE_CALL statement to function FN. The argument FN must be either a FUNCTION_DECL or a gimple call address as determined by is_gimple_call_addr. NARGS are the number of arguments. The rest of the arguments follow the argument NARGS, and must be trees that are valid as rvalues in gimple (i.e., each operand is validated with is_gimple_operand).

gcall *gimple_build_call_from_tree (tree call_expr, tree fnptrtype)  
Build a GIMPLE_CALL from a CALL_EXPR node. The arguments and the function are taken from the expression directly. The type of the GIMPLE_CALL is set from the second parameter passed by a caller. This routine assumes that call_expr is already in GIMPLE form. That is, its operands are GIMPLE values and the function call needs no further simplification. All the call flags in call_expr are copied over to the new GIMPLE_CALL.

gcall *gimple_build_call_vec (tree fn, vec<tree> args)  
Identical to gimple_build_call but the arguments are stored in a vec<tree>.

tree gimple_call_lhs (gimple g)  
Return the LHS of call statement G.

tree * gimple_call_lhs_ptr (gimple g)  
Return a pointer to the LHS of call statement G.

void gimple_call_set_lhs (gimple g, tree lhs)  
Set LHS to be the LHS operand of call statement G.

tree gimple_call_fn (gimple g)  
Return the tree node representing the function called by call statement G.

void gimple_call_set_fn (gcall *g, tree fn)  
Set FN to be the function called by call statement G. This has to be a gimple value specifying the address of the called function.

tree gimple_call_fndecl (gimple g)  
If a given GIMPLE_CALL’s callee is a FUNCTION_DECL, return it. Otherwise return NULL. This function is analogous to get_callee_fndecl in GENERIC.

tree gimple_call_set_fndecl (gimple g, tree fndecl)  
Set the called function to FNDECL.
tree gimple_call_return_type (const gcall *g)  
  Return the type returned by call statement \texttt{G}.

gimple_call_chain (gimple g)  
  Return the static chain for call statement \texttt{G}.

gimple_call_set_chain (gcall *g, tree chain)  
  Set \texttt{CHAIN} to be the static chain for call statement \texttt{G}.

unsigned gimple_call_num_args (gimple g)  
  Return the number of arguments used by call statement \texttt{G}.

tree gimple_call_arg (gimple g, unsigned index)  
  Return the argument at position \texttt{INDEX} for call statement \texttt{G}. The first argument is 0.

tree * gimple_call_arg_ptr (gimple g, unsigned index)  
  Return a pointer to the argument at position \texttt{INDEX} for call statement \texttt{G}.

void gimple_call_set_arg (gimple g, unsigned index, tree arg)  
  Set \texttt{ARG} to be the argument at position \texttt{INDEX} for call statement \texttt{G}.

void gimple_call_set_tail (gcall *s)  
  Mark call statement \texttt{S} as being a tail call (i.e., a call just before the exit of a function). These calls are candidate for tail call optimization.

bool gimple_call_tail_p (gcall *s)  
  Return true if GIMPLE_CALL \texttt{S} is marked as a tail call.

bool gimple_call_noreturn_p (gimple s)  
  Return true if \texttt{S} is a noreturn call.

gimple gimple_call_copy_skip_args (gcall *stmt, bitmap args_to_skip)  
  Build a GIMPLE_CALL identical to \texttt{STMT} but skipping the arguments in the positions marked by the set \texttt{ARGS_TO_SKIP}.

12.8.5 GIMPLE_CATCH

gcatch *gimple_build_catch (tree types, gimple_seq handler)  
  Build a GIMPLE_CATCH statement. \texttt{TYPES} are the tree types this catch handles. \texttt{HANDLER} is a sequence of statements with the code for the handler.

tree gimple_catch_types (const gcatch *g)  
  Return the types handled by GIMPLE_CATCH statement \texttt{G}.

tree * gimple_catch_types_ptr (gcatch *g)  
  Return a pointer to the types handled by GIMPLE_CATCH statement \texttt{G}.

gimple_seq gimple_catch_handler (gcatch *g)  
  Return the GIMPLE sequence representing the body of the handler of GIMPLE_CATCH statement \texttt{G}. 

void gimple_catch_set_types (gcatch *g, tree t) [GIMPLE function]
    Set T to be the set of types handled by GIMPLE_CATCH G.

void gimple_catch_set_handler (gcatch *g, gimple_seq handler) [GIMPLE function]
    Set HANDLER to be the body of GIMPLE_CATCH G.

12.8.6 GIMPLE_COND

gcond *gimple_build_cond (enum tree_code pred_code, tree lhs, tree rhs, tree t_label, tree f_label) [GIMPLE function]
    Build a GIMPLE_COND statement. A GIMPLE_COND statement compares LHS and RHS and if the condition in PRED_CODE is true, jump to the label in t_label, otherwise jump to the label in f_label. PRED_CODE are relational operator tree codes like EQ_EXPR, LT_EXPR, LE_EXPR, NE_EXPR, etc.

gcond *gimple_build_cond_from_tree (tree cond, tree t_label, tree f_label) [GIMPLE function]
    Build a GIMPLE_COND statement from the conditional expression tree COND. T_LABEL and F_LABEL are as in gimple_build_condition.

enum tree_code gimple_cond_code (gimple g) [GIMPLE function]
    Return the code of the predicate computed by conditional statement G.

void gimple_cond_set_code (gcond *g, enum tree_code code) [GIMPLE function]
    Set CODE to be the predicate code for the conditional statement G.

tree gimple_cond_lhs (gimple g) [GIMPLE function]
    Return the LHS of the predicate computed by conditional statement G.

void gimple_cond_set_lhs (gcond *g, tree lhs) [GIMPLE function]
    Set LHS to be the LHS operand of the predicate computed by conditional statement G.

tree gimple_cond_rhs (gimple g) [GIMPLE function]
    Return the RHS operand of the predicate computed by conditional G.

void gimple_cond_set_rhs (gcond *g, tree rhs) [GIMPLE function]
    Set RHS to be the RHS operand of the predicate computed by conditional statement G.

tree gimple_cond_true_label (const gcond *g) [GIMPLE function]
    Return the label used by conditional statement G when its predicate evaluates to true.

void gimple_cond_set_true_label (gcond *g, tree label) [GIMPLE function]
    Set LABEL to be the label used by conditional statement G when its predicate evaluates to true.

void gimple_cond_set_false_label (gcond *g, tree label) [GIMPLE function]
    Set LABEL to be the label used by conditional statement G when its predicate evaluates to false.

tree gimple_cond_false_label (const gcond *g) [GIMPLE function]
    Return the label used by conditional statement G when its predicate evaluates to false.
void gimple_cond_make_false (gcond *g)  
   Set the conditional COND_STMT to be of the form 'if (1 == 0)'.

void gimple_cond_make_true (gcond *g)  
   Set the conditional COND_STMT to be of the form 'if (1 == 1)'.

12.8.7 GIMPLE_DEBUG

gdebug *gimple_build_debug_bind (tree var, tree value,  
gimple stmt)  
Build a GIMPLE_DEBUG statement with GIMPLE_DEBUG_BIND subcode. The effect of  
this statement is to tell debug information generation machinery that the value of  
user variable var is given by value at that point, and to remain with that value until  
var runs out of scope, a dynamically-subsequent debug bind statement overrides the  
binding, or conflicting values reach a control flow merge point. Even if components of  
the value expression change afterwards, the variable is supposed to retain the same  
value, though not necessarily the same location.

It is expected that var be most often a tree for automatic user variables (VAR_DECL  
or PARM_DECL) that satisfy the requirements for gimple registers, but it may also be  
a tree for a scalarized component of a user variable (ARRAY_REF, COMPONENT_REF), or  
a debug temporary (DEBUG_EXPR_DECL).

As for value, it can be an arbitrary tree expression, but it is recommended that it be  
in a suitable form for a gimple assignment RHS. It is not expected that user variables  
that could appear as var ever appear in value, because in the latter we’d have their  
SSA_NAMESs instead, but even if they were not in SSA form, user variables appearing in  
value are to be regarded as part of the executable code space, whereas those in  
var are to be regarded as part of the source code space. There is no way to refer to  
the value bound to a user variable within a value expression.

If value is GIMPLE_DEBUG_BIND_NOVALUE, debug information generation machinery is  
informed that the variable var is unbound, i.e., that its value is indeterminate, which  
sometimes means it is really unavailable, and other times that the compiler could not  
keep track of it.

Block and location information for the newly-created stmt are taken from stmt, if  
given.

tree gimple_debug_bind_get_var (gimple stmt)  
Return the user variable var that is bound at stmt.

tree gimple_debug_bind_get_value (gimple stmt)  
Return the value expression that is bound to a user variable at stmt.

tree * gimple_debug_bind_get_value_ptr (gimple stmt)  
Return a pointer to the value expression that is bound to a user variable at stmt.

void gimple_debug_bind_set_var (gimple stmt, tree var)  
Modify the user variable bound at stmt to var.

void gimple_debug_bind_set_value (gimple stmt, tree var)  
Modify the value bound to the user variable bound at stmt to value.
void gimple_debug_bind_reset_value (gimple stmt) [GIMPLE function]
   Modify the value bound to the user variable bound at stmt so that the variable
   becomes unbound.

bool gimple_debug_bind_has_value_p (gimple stmt) [GIMPLE function]
   Return TRUE if stmt binds a user variable to a value, and FALSE if it unbinds the
   variable.

gimple gimple_build_debug_begin_stmt (tree block, location_t location) [GIMPLE function]
   Build a GIMPLE_DEBUG statement with GIMPLE_DEBUG_BEGIN_STMT subcode. The
   effect of this statement is to tell debug information generation machinery that the
   user statement at the given location and block starts at the point at which the
   statement is inserted. The intent is that side effects (e.g. variable bindings) of all
   prior user statements are observable, and that none of the side effects of subsequent
   user statements are.

gimple gimple_build_debug_inline_entry (tree block, location_t location) [GIMPLE function]
   Build a GIMPLE_DEBUG statement with GIMPLE_DEBUG_INLINE_ENTRY subcode. The
   effect of this statement is to tell debug information generation machinery that a
   function call at location underwent inline substitution, that block is the enclosing
   lexical block created for the substitution, and that at the point of the program in
   which the stmt is inserted, all parameters for the inlined function are bound to the
   respective arguments, and none of the side effects of its stmts are observable.

12.8.8 GIMPLE_EH_FILTER

geh_filter *gimple_build_eh_filter (tree types, gimple_seq failure) [GIMPLE function]
   Build a GIMPLE_EH_FILTER statement. TYPES are the filter’s types. FAILURE is a
   sequence with the filter’s failure action.

tree gimple_eh_filter_types (gimple g) [GIMPLE function]
   Return the types handled by GIMPLE_EH_FILTER statement G.

tree * gimple_eh_filter_types_ptr (gimple g) [GIMPLE function]
   Return a pointer to the types handled by GIMPLE_EH_FILTER statement G.

gimple_seq gimple_eh_filter_failure (gimple g) [GIMPLE function]
   Return the sequence of statement to execute when GIMPLE_EH_FILTER statement fails.

void gimple_eh_filter_set_types (geh_filter *g, tree types) [GIMPLE function]
   Set TYPES to be the set of types handled by GIMPLE_EH_FILTER G.

void gimple_eh_filter_set_failure (geh_filter *g, gimple_seq failure) [GIMPLE function]
   Set FAILURE to be the sequence of statements to execute on failure for GIMPLE_EH_-
   FILTER G.
tree gimple_eh_must_not_throw_fndecl (geh_mnt *eh_mnt_stmt)
    Get the function decl to be called by the MUST_NOT_THROW region.

void gimple_eh_must_not_throw_set_fndecl (geh_mnt *eh_mnt_stmt, tree decl)
    Set the function decl to be called by GS to DECL.

12.8.9 GIMPLE_LABEL

glabel *gimple_build_label (tree label)
    Build a GIMPLE_LABEL statement with corresponding to the tree label, LABEL.

tree gimple_label_label (const glabel *g)
    Return the LABEL_DECL node used by GIMPLE_LABEL statement G.

void gimple_label_set_label (glabel *g, tree label)
    Set LABEL to be the LABEL_DECL node used by GIMPLE_LABEL statement G.

12.8.10 GIMPLE_GOTO

ggoto *gimple_build_goto (tree dest)
    Build a GIMPLE_GOTO statement to label DEST.

tree gimple_goto_dest (gimple g)
    Return the destination of the unconditional jump G.

void gimple_goto_set_dest (ggoto *g, tree dest)
    Set DEST to be the destination of the unconditional jump G.

12.8.11 GIMPLE_NOP

gimple gimple_build_nop (void)
    Build a GIMPLE_NOP statement.

bool gimple_nop_p (gimple g)
    Returns TRUE if statement G is a GIMPLE_NOP.

12.8.12 GIMPLE_OMP_ATOMIC_LOAD

gomp_atomic_load *gimple_build_omp_atomic_load (tree lhs, tree rhs)
    Build a GIMPLE_OMP_ATOMIC_LOAD statement. LHS is the left-hand side of the assignment. RHS is the right-hand side of the assignment.

void gimple_omp_atomic_load_set_lhs (gomp_atomic_load *g, tree lhs)
    Set the LHS of an atomic load.

tree gimple_omp_atomic_load_lhs (const gomp_atomic_load *g)
    Get the LHS of an atomic load.
void gimple_omp_atomic_load_set_rhs ( gomp_atomic_load *g, tree rhs)
   Set the RHS of an atomic set.

tree gimple_omp_atomic_load_rhs ( const gomp_atomic_load *g)
   Get the RHS of an atomic set.

12.8.13 GIMPLE_OMP_ATOMIC_STORE

gomp_atomic_store *gimple_build_omp_atomic_store ( tree val)
   Build a GIMPLE_OMP_ATOMIC_STORE statement. VAL is the value to be stored.

void gimple_omp_atomic_store_set_val ( gomp_atomic_store *g, tree val)
   Set the value being stored in an atomic store.

tree gimple_omp_atomic_store_val ( const gomp_atomic_store *g)
   Return the value being stored in an atomic store.

12.8.14 GIMPLE_OMP_CONTINUE

gomp_continue *gimple_build_omp_continue ( tree control_def, tree control_use)
   Build a GIMPLE_OMP_CONTINUE statement. CONTROL_DEF is the definition of the control variable.
   CONTROL_USE is the use of the control variable.

tree gimple_omp_continue_control_def ( const gomp_continue *s)
   Return the definition of the control variable on a GIMPLE_OMP_CONTINUE in S.

tree gimple_omp_continue_control_def_ptr ( gomp_continue *s)
   Same as above, but return the pointer.

tree gimple_omp_continue_set_control_def ( gomp_continue *s)
   Set the control variable definition for a GIMPLE_OMP_CONTINUE statement in S.

tree gimple_omp_continue_control_use ( const gomp_continue *s)
   Return the use of the control variable on a GIMPLE_OMP_CONTINUE in S.

tree gimple_omp_continue_control_use_ptr ( gomp_continue *s)
   Same as above, but return the pointer.

tree gimple_omp_continue_set_control_use ( gomp_continue *s)
   Set the control variable use for a GIMPLE_OMP_CONTINUE statement in S.
12.8.15 GIMPLE_OMP_CRITICAL

`gomp_critical *gimple_build_omp_critical (gimple_seq body, tree name)`  
Build a GIMPLE_OMP_CRITICAL statement. **BODY** is the sequence of statements for which only one thread can execute. **NAME** is an optional identifier for this critical block.

`tree gimple_omp_critical_name (const gomp_critical *g)`  
Return the name associated with OMP_CRITICAL statement G.

`tree * gimple_omp_critical_name_ptr (gomp_critical *g)`  
Return a pointer to the name associated with OMP critical statement G.

`void gimple_omp_critical_set_name (gomp_critical *g, tree name)`  
Set **NAME** to be the name associated with OMP critical statement G.

12.8.16 GIMPLE_OMP_FOR

`gomp_for *gimple_build_omp_for (gimple_seq body, tree clauses, tree index, tree initial, tree final, tree incr, gimple_seq pre_body, enum tree_code omp_for_cond)`  
Build a GIMPLE_OMP_FOR statement. **BODY** is sequence of statements inside the for loop. **CLAUSES**, are any of the loop construct’s clauses. **PRE_BODY** is the sequence of statements that are loop invariant. **INDEX** is the index variable. **INITIAL** is the initial value of INDEX. **FINAL** is final value of INDEX. **OMP_FOR_COND** is the predicate used to compare INDEX and FINAL. **INCR** is the increment expression.

`tree gimple_omp_for_clauses (gimple g)`  
Return the clauses associated with OMP_FOR G.

`tree * gimple_omp_for_clauses_ptr (gimple g)`  
Return a pointer to the OMP_FOR G.

`void gimple_omp_for_set_clauses (gimple g, tree clauses)`  
Set **CLAUSES** to be the list of clauses associated with OMP_FOR G.

`tree gimple_omp_for_index (gimple g)`  
Return the index variable for OMP_FOR G.

`tree * gimple_omp_for_index_ptr (gimple g)`  
Return a pointer to the index variable for OMP_FOR G.

`void gimple_omp_for_set_index (gimple g, tree index)`  
Set **INDEX** to be the index variable for OMP_FOR G.

`tree gimple_omp_for_initial (gimple g)`  
Return the initial value for OMP_FOR G.

`tree * gimple_omp_for_initial_ptr (gimple g)`  
Return a pointer to the initial value for OMP_FOR G.
void gimple_omp_for_set_initial (gimple g, tree initial)  
Set INITIAL to be the initial value for OMP_FOR G.

tree gimple_omp_for_final (gimple g)  
Return the final value for OMP_FOR G.

tree * gimple_omp_for_final_ptr (gimple g)  
return a pointer to the final value for OMP_FOR G.

void gimple_omp_for_set_final (gimple g, tree final)  
Set FINAL to be the final value for OMP_FOR G.

tree gimple_omp_for_incr (gimple g)  
Return the increment value for OMP_FOR G.

tree * gimple_omp_for_incr_ptr (gimple g)  
Return a pointer to the increment value for OMP_FOR G.

void gimple_omp_for_set_incr (gimple g, tree incr)  
Set INCR to be the increment value for OMP_FOR G.

gimple_seq gimple_omp_for_pre_body (gimple g)  
Return the sequence of statements to execute before the OMP_FOR statement G starts.

void gimple_omp_for_set_pre_body (gimple g, gimple_seq pre_body)  
Set PRE_BODY to be the sequence of statements to execute before the OMP_FOR statement G starts.

void gimple_omp_for_set_cond (gimple g, enum tree_code cond)  
Set COND to be the condition code for OMP_FOR G.

type tree_code gimple_omp_for_cond (gimple g)  
Return the condition code associated with OMP_FOR G.

12.8.17 GIMPLE_OMP_MASTER

gimple gimple_build_omp_master (gimple_seq body)  
Build a GIMPLE_OMP_MASTER statement. BODY is the sequence of statements to be executed by just the master.

12.8.18 GIMPLE_OMP_ORDERED

gimple gimple_build_omp_ordered (gimple_seq body)  
Build a GIMPLE_OMP_ORDERED statement.

BODY is the sequence of statements inside a loop that will executed in sequence.
12.8.19 GIMPLE_OMP_PARALLEL

gomp_parallel *gimple_build_omp_parallel ( gimple_seq body, tree clauses, tree child_fn, tree data_arg) [GIMPLE function]
Build a GIMPLE_OMP_PARALLEL statement.

BODY is sequence of statements which are executed in parallel. CLAUSES, are the OMP parallel construct’s clauses. CHILD_FN is the function created for the parallel threads to execute. DATA_ARG are the shared data argument(s).

bool gimple_omp_parallel_combined_p (gimple g) [GIMPLE function]
Return true if OMP parallel statement G has the GF_OMP_PARALLEL_COMBINED flag set.

void gimple_omp_parallel_set_combined_p (gimple g) [GIMPLE function]
Set the GF_OMP_PARALLEL_COMBINED field in OMP parallel statement G.

gimple_seq gimple_omp_body (gimple g) [GIMPLE function]
Return the body for the OMP statement G.

void gimple_omp_set_body (gimple g, gimple_seq body) [GIMPLE function]
Set BODY to be the body for the OMP statement G.

tree gimple_omp_parallel_clauses (gimple g) [GIMPLE function]
Return the clauses associated with OMP_PARALLEL G.

tree * gimple_omp_parallel_clauses_ptr (gomp_parallel *g) [GIMPLE function]
Return a pointer to the clauses associated with OMP_PARALLEL G.

void gimple_omp_parallel_set_clauses (gomp_parallel *g, tree clauses) [GIMPLE function]
Set CLAUSES to be the list of clauses associated with OMP_PARALLEL G.

tree gimple_omp_parallel_child_fn (const gomp_parallel *g) [GIMPLE function]
Return the child function used to hold the body of OMP_PARALLEL G.

tree * gimple_omp_parallel_child_fn_ptr (gomp_parallel *g) [GIMPLE function]
Return a pointer to the child function used to hold the body of OMP_PARALLEL G.

void gimple_omp_parallel_set_child_fn (gomp_parallel *g, tree child_fn) [GIMPLE function]
Set CHILD_FN to be the child function for OMP_PARALLEL G.

tree gimple_omp_parallel_data_arg (const gomp_parallel *g) [GIMPLE function]
Return the artificial argument used to send variables and values from the parent to the children threads in OMP_PARALLEL G.

tree * gimple_omp_parallel_data_arg_ptr (gomp_parallel *g) [GIMPLE function]
Return a pointer to the data argument for OMP_PARALLEL G.
void gimple_omp_parallel_set_data_arg ( gomp_parallel *g, tree data_arg )
    Set DATA_ARG to be the data argument for OMP_PARALLEL G.

12.8.20 GIMPLE_OMP_RETURN

gimple gimple_build_omp_return ( bool wait_p )
    Build a GIMPLE_OMP_RETURN statement. WAIT_P is true if this is a non-waiting return.

void gimple_omp_return_set_nowait ( gimple s )
    Set the nowait flag on GIMPLE_OMP_RETURN statement S.

bool gimple_omp_return_nowait_p ( gimple g )
    Return true if OMP return statement G has the GF_OMP_RETURN_NOWAIT flag set.

12.8.21 GIMPLE_OMP_SECTION

gimple gimple_build_omp_section ( gimple_seq body )
    Build a GIMPLE_OMP_SECTION statement for a sections statement.
    BODY is the sequence of statements in the section.

bool gimple_omp_section_last_p ( gimple g )
    Return true if OMP section statement G has the GF_OMP_SECTION_LAST flag set.

void gimple_omp_section_set_last ( gimple g )
    Set the GF_OMP_SECTION_LAST flag on G.

12.8.22 GIMPLE_OMP_SECTIONS

gomp_sections *gimple_build_omp_sections ( gimple_seq body, tree clauses )
    Build a GIMPLE_OMP_SECTIONS statement. BODY is a sequence of section statements.
    CLAUSES are any of the OMP sections construct’s clauses: private, firstprivate, lastprivate, reduction, and nowait.

gimple gimple_build_omp_sections_switch ( void )
    Build a GIMPLE_OMP_SECTIONS_SWITCH statement.

tree gimple_omp_sections_control ( gimple g )
    Return the control variable associated with the GIMPLE_OMP_SECTIONS in G.

tree * gimple_omp_sections_control_ptr ( gimple g )
    Return a pointer to the clauses associated with the GIMPLE_OMP_SECTIONS in G.

void gimple_omp_sections_set_control ( gimple g, tree control )
    Set CONTROL to be the set of clauses associated with the GIMPLE_OMP_SECTIONS in G.

tree gimple_omp_sections_clauses ( gimple g )
    Return the clauses associated with OMP_SECTIONS G.
tree * gimple_omp_sections_clauses_ptr (gimple g)  
Return a pointer to the clauses associated with OMP_SECTIONS G.

void gimple_omp_sections_set_clauses (gimple g, tree clauses)  
Set CLAUSES to be the set of clauses associated with OMP_SECTIONS G.

12.8.23 GIMPLE_OMP_SINGLE

gomp_single *gimple_build_omp_single (gimple_seq body, tree clauses)  
Build a GIMPLE_OMP_SINGLE statement. BODY is the sequence of statements that will be executed once. CLAUSES are any of the OMP single construct’s clauses: private, firstprivate, copyprivate, nowait.

tree gimple_omp_single_clauses (gimple g)  
Return the clauses associated with OMP_SINGLE G.

tree * gimple_omp_single_clauses_ptr (gimple g)  
Return a pointer to the clauses associated with OMP_SINGLE G.

void gimple_omp_single_set_clauses (gomp_single *g, tree clauses)  
Set CLAUSES to be the clauses associated with OMP_SINGLE G.

12.8.24 GIMPLE_PHI

unsigned gimple_phi_capacity (gimple g)  
Return the maximum number of arguments supported by GIMPLE_PHI G.

unsigned gimple_phi_num_args (gimple g)  
Return the number of arguments in GIMPLE_PHI G. This must always be exactly the number of incoming edges for the basic block holding G.

tree gimple_phi_result (gimple g)  
Return the SSA name created by GIMPLE_PHI G.

tree * gimple_phi_result_ptr (gimple g)  
Return a pointer to the SSA name created by GIMPLE_PHI G.

void gimple_phi_set_result (gphi *g, tree result)  
Set RESULT to be the SSA name created by GIMPLE_PHI G.

struct phi_arg_d * gimple_phi_arg (gimple g, index)  
Return the PHI argument corresponding to incoming edge INDEX for GIMPLE_PHI G.

void gimple_phi_set_arg (gphi *g, index, struct phi_arg_d * phiarg)  
Set PHIARG to be the argument corresponding to incoming edge INDEX for GIMPLE_PHI G.
12.8.25 GIMPLE_RESX

gresx *gimple_build_resx (int region)  
  [GIMPLE function] Build a GIMPLE_RESX statement which is a statement. This statement is a placeholder for _Unwind_Resume before we know if a function call or a branch is needed. REGION is the exception region from which control is flowing.

int gimple_resx_region (const gresx *g)  
  [GIMPLE function] Return the region number for GIMPLE_RESX G.

void gimple_resx_set_region (gresx *g, int region)  
  [GIMPLE function] Set REGION to be the region number for GIMPLE_RESX G.

12.8.26 GIMPLE_RETURN

greturn *gimple_build_return (tree retval)  
  [GIMPLE function] Build a GIMPLE_RETURN statement whose return value is retval.

tree gimple_return_retval (const greturn *g)  
  [GIMPLE function] Return the return value for GIMPLE_RETURN G.

void gimple_return_set_retval (greturn *g, tree retval)  
  [GIMPLE function] Set RETVAL to be the return value for GIMPLE_RETURN G.

12.8.27 GIMPLE_SWITCH

gswitch *gimple_build_switch (tree index, tree default_label, vec<tree> *args)  
  [GIMPLE function] Build a GIMPLE_SWITCH statement. INDEX is the index variable to switch on, and DEFAULT_LABEL represents the default label. ARGS is a vector of CASE_LABEL_EXPR trees that contain the non-default case labels. Each label is a tree of code CASE_LABEL_EXPR.

unsigned gimple_switch_num_labels (const gswitch *g)  
  [GIMPLE function] Return the number of labels associated with the switch statement G.

void gimple_switch_set_num_labels (gswitch *g, unsigned nlabels)  
  [GIMPLE function] Set NLABELS to be the number of labels for the switch statement G.

tree gimple_switch_index (const gswitch *g)  
  [GIMPLE function] Return the index variable used by the switch statement G.

void gimple_switch_set_index (gswitch *g, tree index)  
  [GIMPLE function] Set INDEX to be the index variable for switch statement G.

tree gimple_switch_label (const gswitch *g, unsigned index)  
  [GIMPLE function] Return the label numbered INDEX. The default label is 0, followed by any labels in a switch statement.
void gimple_switch_set_label (gswitch *g, unsigned index,  
  tree label)  
  Set the label number INDEX to LABEL. 0 is always the default label.

tree gimple_switch_default_label ( const gswitch *g)  
  Return the default label for a switch statement.

void gimple_switch_set_default_label (gswitch *g, tree  
  label)  
  Set the default label for a switch statement.

12.8.28 GIMPLE_TRY

gtry *gimple_build_try (gimple_seq eval, gimple_seq  
  cleanup, unsigned int kind)  
  Build a GIMPLE_TRY statement. EVAL is a sequence with the expression to evaluate.  
  CLEANUP is a sequence of statements to run at clean-up time. KIND is the enumeration  
  value GIMPLE_TRY_CATCH if this statement denotes a try/catch construct or GIMPLE_  
  TRY_FINALLY if this statement denotes a try/finally construct.

enum gimple_try_flags gimple_try_kind (gimple g)  
  Return the kind of try block represented by GIMPLE_TRY G. This is either GIMPLE_  
  TRY_CATCH or GIMPLE_TRY_FINALLY.

bool gimple_try_catch_is_cleanup (gimple g)  
  Return the GIMPLE_TRY_CATCH_IS_CLEANUP flag.

gimple_seq gimple_try_eval (gimple g)  
  Return the sequence of statements used as the body for GIMPLE_TRY G.

gimple_seq gimple_try_cleanup (gimple g)  
  Return the sequence of statements used as the cleanup body for GIMPLE_TRY G.

void gimple_try_set_catch_is_cleanup (gimple g, bool  
  catch_is_cleanup)  
  Set the GIMPLE_TRY_CATCH_IS_CLEANUP flag.

void gimple_try_set_eval (gtry *g, gimple_seq eval)  
  Set EVAL to be the sequence of statements to use as the body for GIMPLE_TRY G.

void gimple_try_set_cleanup (gtry *g, gimple_seq cleanup)  
  Set CLEANUP to be the sequence of statements to use as the cleanup body for GIMPLE_  
  TRY G.

12.8.29 GIMPLE_WITH_CLEANUP_EXPR

gimple gimple_build_wce (gimple_seq cleanup)  
  Build a GIMPLE_WITH_CLEANUP_EXPR statement. CLEANUP is the clean-up expression.

gimple_seq gimple_wce_cleanup (gimple g)  
  Return the cleanup sequence for cleanup statement G.
void gimple_wce_set_cleanup (gimple g, gimple_seq cleanup)  [GIMPLE function]
    Set CLEANUP to be the cleanup sequence for G.

bool gimple_wce_cleanup_eh_only (gimple g)  [GIMPLE function]
    Return the CLEANUP_EH_ONLY flag for a WCE tuple.

void gimple_wce_set_cleanup_eh_only (gimple g, bool eh_only_p)  [GIMPLE function]
    Set the CLEANUP_EH_ONLY flag for a WCE tuple.

12.9 GIMPLE sequences

GIMPLE sequences are the tuple equivalent of STATEMENT_LIST’s used in GENERIC. They are used to chain statements together, and when used in conjunction with sequence iterators, provide a framework for iterating through statements.

GIMPLE sequences are of type struct gimple_sequence, but are more commonly passed by reference to functions dealing with sequences. The type for a sequence pointer is gimple_seq which is the same as struct gimple_sequence *. When declaring a local sequence, you can define a local variable of type struct gimple_sequence. When declaring a sequence allocated on the garbage collected heap, use the function gimple_seq_alloc documented below.

There are convenience functions for iterating through sequences in the section entitled Sequence Iterators.

Below is a list of functions to manipulate and query sequences.

void gimple_seq_add_stmt (gimple_seq *seq, gimple g)  [GIMPLE function]
    Link a gimple statement to the end of the sequence *SEQ if G is not NULL. If *SEQ is NULL, allocate a sequence before linking.

void gimple_seq_add_seq (gimple_seq *dest, gimple_seq src)  [GIMPLE function]
    Append sequence SRC to the end of sequence *DEST if SRC is not NULL. If *DEST is NULL, allocate a new sequence before appending.

gimple_seq gimple_seq_deep_copy (gimple_seq src)  [GIMPLE function]
    Perform a deep copy of sequence SRC and return the result.

gimple_seq gimple_seq_reverse (gimple_seq seq)  [GIMPLE function]
    Reverse the order of the statements in the sequence SEQ. Return SEQ.

gimple gimple_seq_first (gimple_seq s)  [GIMPLE function]
    Return the first statement in sequence S.

gimple gimple_seq_last (gimple_seq s)  [GIMPLE function]
    Return the last statement in sequence S.

void gimple_seq_set_last (gimple_seq s, gimple last)  [GIMPLE function]
    Set the last statement in sequence S to the statement in LAST.

void gimple_seq_set_first (gimple_seq s, gimple first)  [GIMPLE function]
    Set the first statement in sequence S to the statement in FIRST.
void gimple_seq_init (gimple_seq s) [GIMPLE function]
    Initialize sequence S to an empty sequence.

gimple_seq gimple_seq_alloc (void) [GIMPLE function]
    Allocate a new sequence in the garbage collected store and return it.

void gimple_seq_copy (gimple_seq dest, gimple_seq src) [GIMPLE function]
    Copy the sequence SRC into the sequence DEST.

bool gimple_seq_empty_p (gimple_seq s) [GIMPLE function]
    Return true if the sequence S is empty.

gimple_seq bb_seq (basic_block bb) [GIMPLE function]
    Returns the sequence of statements in BB.

void set_bb_seq (basic_block bb, gimple_seq seq) [GIMPLE function]
    Sets the sequence of statements in BB to SEQ.

bool gimple_seq_singleton_p (gimple_seq seq) [GIMPLE function]
    Determine whether SEQ contains exactly one statement.

12.10 Sequence iterators

Sequence iterators are convenience constructs for iterating through statements in a sequence. Given a sequence SEQ, here is a typical use of gimple sequence iterators:

    gimple_stmt_iterator gsi;
    for (gsi = gsi_start (seq); !gsi_end_p (gsi); gsi_next (&gsi))
        {
            gimple g = gsi_stmt (gsi);
            /* Do something with gimple statement G. */
        }

Backward iterations are possible:

    for (gsi = gsi_last (seq); !gsi_end_p (gsi); gsi_prev (&gsi))

Forward and backward iterations on basic blocks are possible with gsi_start_bb and gsi_last_bb.

In the documentation below we sometimes refer to enum gsi_iterator_update. The valid options for this enumeration are:

* GSI_NEW_STMT Only valid when a single statement is added. Move the iterator to it.
* GSI_SAME_STMT Leave the iterator at the same statement.
* GSI_CONTINUE_LINKING Move iterator to whatever position is suitable for linking other statements in the same direction.

Below is a list of the functions used to manipulate and use statement iterators.

gimple_stmt_iterator gsi_start (gimple_seq seq) [GIMPLE function]
    Return a new iterator pointing to the sequence SEQ's first statement. If SEQ is empty, the iterator's basic block is NULL. Use gsi_start_bb instead when the iterator needs to always have the correct basic block set.
gimple_stmt_iterator gsi_start_bb (basic_block bb)  
   Return a new iterator pointing to the first statement in basic block BB.

gimple_stmt_iterator gsi_last (gimple_seq seq)  
   Return a new iterator initially pointing to the last statement of sequence SEQ. If
   SEQ is empty, the iterator’s basic block is NULL. Use gsi_last_bb instead when the
   iterator needs to always have the correct basic block set.

gimple_stmt_iterator gsi_last_bb (basic_block bb)  
   Return a new iterator pointing to the last statement in basic block BB.

bool gsi_end_p (gimple_stmt_iterator i)  
   Return TRUE if at the end of I.

bool gsi_one_before_end_p (gimple_stmt_iterator i)  
   Return TRUE if we’re one statement before the end of I.

void gsi_next (gimple_stmt_iterator *i)  
   Advance the iterator to the next gimple statement.

void gsi_prev (gimple_stmt_iterator *i)  
   Advance the iterator to the previous gimple statement.

gimple gsi_stmt (gimple_stmt_iterator i)  
   Return the current stmt.

gimple_stmt_iterator gsi_after_labels (basic_block bb)  
   Return a block statement iterator that points to the first non-label statement in block
   BB.

gimple * gsi_stmt_ptr (gimple_stmt_iterator *i)  
   Return a pointer to the current stmt.

basic_block gsi_bb (gimple_stmt_iterator i)  
   Return the basic block associated with this iterator.

gimple_seq gsi_seq (gimple_stmt_iterator i)  
   Return the sequence associated with this iterator.

void gsi_remove (gimple_stmt_iterator *i, bool remove_eh_info)  
   Remove the current stmt from the sequence. The iterator is updated to point to the
   next statement. When REMOVE_EH_INFO is true we remove the statement pointed to
   by iterator I from the EH tables. Otherwise we do not modify the EH tables. Generally,
   REMOVE_EH_INFO should be true when the statement is going to be removed from the
   IL and not reinserted elsewhere.

void gsi_link_seq_before (gimple_stmt_iterator *i,  
   gimple_seq seq, enum gsi_iterator_update_mode)  
   Links the sequence of statements SEQ before the statement pointed by iterator I. MODE
   indicates what to do with the iterator after insertion (see enum gsi_iterator_update
   above).
void gsi_link_before (gimple_stmt_iterator *i, gimple g,         [GIMPLE function]
    enum gsi_iterator_update mode)
    Links statement G before the statement pointed-to by iterator I. Updates iterator I
    according to MODE.

void gsi_link_seq_after (gimple_stmt_iterator *i,         [GIMPLE function]
    gimple_seq seq, enum gsi_iterator_update mode)
    Links sequence SEQ after the statement pointed-to by iterator I. MODE is as in gsi_
    insert_after.

void gsi_link_after (gimple_stmt_iterator *i, gimple g, enum         [GIMPLE function]
    gsi_iterator_update mode)
    Links statement G after the statement pointed-to by iterator I. MODE is as in gsi_
    insert_after.

gimple_seq gsi_split_seq_after (gimple_stmt_iterator i)         [GIMPLE function]
    Move all statements in the sequence after I to a new sequence. Return this new
    sequence.

gimple_seq gsi_split_seq_before (gimple_stmt_iterator *i)         [GIMPLE function]
    Move all statements in the sequence before I to a new sequence. Return this new
    sequence.

void gsi_replace (gimple_stmt_iterator *i, gimple stmt, bool         [GIMPLE function]
    update_eh_info)
    Replace the statement pointed-to by I to_STMT. If UPDATE_EH_INFO is true, the exception
    handling information of the original statement is moved to the new statement.

void gsi_insert_before (gimple_stmt_iterator *i, gimple stmt, enum         [GIMPLE function]
    gsi_iterator_update mode)
    Insert statement_STMT before the statement pointed-to by iterator I, update_STMT’s
    basic block and scan it for new operands. MODE specifies how to update iterator I
    after insertion (see enum gsi_iterator_update).

void gsi_insert_seq_before (gimple_stmt_iterator *i,         [GIMPLE function]
    gimple_seq seq, enum gsi_iterator_update mode)
    Like gsi_insert_before, but for all the statements in SEQ.

void gsi_insert_after (gimple_stmt_iterator *i, gimple stmt, enum         [GIMPLE function]
    gsi_iterator_update mode)
    Insert statement_STMT after the statement pointed-to by iterator I, update_STMT’s
    basic block and scan it for new operands. MODE specifies how to update iterator I
    after insertion (see enum gsi_iterator_update).

void gsi_insert_seq_after (gimple_stmt_iterator *i,         [GIMPLE function]
    gimple_seq seq, enum gsi_iterator_update mode)
    Like gsi_insert_after, but for all the statements in SEQ.

gimple_stmt_iterator gsi_for_stmt (gimple stmt)         [GIMPLE function]
    Finds iterator for_STMT.
void gsi_move_after (gimple_stmt_iterator *from,  
gimple_stmt_iterator *to)  
Move the statement at FROM so it comes right after the statement at TO.

void gsi_move_before (gimple_stmt_iterator *from,  
gimple_stmt_iterator *to)  
Move the statement at FROM so it comes right before the statement at TO.

void gsi_move_to_bb_end (gimple_stmt_iterator *from,  
 basic_block bb)  
Move the statement at FROM to the end of basic block BB.

void gsi_insert_on_edge (edge e, gimple stmt)  
Add STMT to the pending list of edge E. No actual insertion is made until a call to 
gsi_commit_edge_inserts() is made.

void gsi_insert_seq_on_edge (edge e, gimple_seq seq)  
Add the sequence of statements in SEQ to the pending list of edge E. No actual 
insertion is made until a call to gsi_commit_edge_inserts() is made.

basic_block gsi_insert_on_edge_immediate (edge e,  
gimple stmt)  
Similar to gsi_insert_on_edge+gsi_commit_edge_inserts. If a new block has to 
be created, it is returned.

void gsi_commit_one_edge_insert (edge e, basic_block  
*new_bb)  
Commit insertions pending at edge E. If a new block is created, set NEW_BB to this 
block, otherwise set it to NULL.

void gsi_commit_edge_inserts (void)  
This routine will commit all pending edge insertions, creating any new basic blocks 
which are necessary.

12.11 Adding a new GIMPLE statement code

The first step in adding a new GIMPLE statement code, is modifying the file gimple.def, 
which contains all the GIMPLE codes. Then you must add a corresponding gimple subclass 
located in gimple.h. This in turn, will require you to add a corresponding GTY tag in 
gsstruct.def, and code to handle this tag in gss_for_code which is located in gimple.c.

In order for the garbage collector to know the size of the structure you created in 
gimple.h, you need to add a case to handle your new GIMPLE statement in gimple_size 
which is located in gimple.c.

You will probably want to create a function to build the new gimple statement in 
gimple.c. The function should be called gimple_build_new-tuple-name, and should return 
the new tuple as a pointer to the appropriate gimple subclass.

If your new statement requires accessors for any members or operands it may have, 
put simple inline accessors in gimple.h and any non-trivial accessors in gimple.c with a 
corresponding prototype in gimple.h.
You should add the new statement subclass to the class hierarchy diagram in gimple.texi.

### 12.12 Statement and operand traversals

There are two functions available for walking statements and sequences: `walk_gimple_stmt` and `walk_gimple_seq`, accordingly, and a third function for walking the operands in a statement: `walk_gimple_op`.

```c
#include <gimple.h>

/* GIMPLE function */
tree walk_gimple_stmt (gimplestmt_iterator *gsi,
                        walk_stmt_fn callbackStmt, walk_tree_fn callbackOp,
                        struct walk_stmt_info *wi)

This function is used to walk the current statement in GSI, optionally using traversal state stored in WI. If WI is NULL, no state is kept during the traversal.

The callback `CALLBACK_STMT` is called. If `CALLBACK_STMT` returns true, it means that the callback function has handled all the operands of the statement and it is not necessary to walk its operands.

If `CALLBACK_STMT` is NULL or it returns false, `CALLBACK_OP` is called on each operand of the statement via `walk_gimple_op`. If `walk_gimple_op` returns non-NULL for any operand, the remaining operands are not scanned.

The return value is that returned by the last call to `walk_gimple_op`, or `NULLTREE` if no `CALLBACK_OP` is specified.

```c
#include <gimple.h>

/* GIMPLE function */
tree walk_gimple_op (gimplestmt stmt, walk_tree_fn callbackOp,
                        struct walk_stmt_info *wi)

Use this function to walk the operands of statement `stmt`. Every operand is walked via `walk_tree` with optional state information in WI.

`CALLBACK_OP` is called on each operand of `stmt` via `walk_tree`. Additional parameters to `walk_tree` must be stored in WI. For each operand `OP`, `walk_tree` is called as:

```c
walk_tree (&OP, CALLBACK_OP, WI, PSET)
```

If `CALLBACK_OP` returns non-NULL for an operand, the remaining operands are not scanned. The return value is that returned by the last call to `walk_tree`, or `NULLTREE` if no `CALLBACK_OP` is specified.

```c
#include <gimple.h>

/* GIMPLE function */
tree walk_gimple_seq (gimple_seq seq, walk_stmt_fn callbackStmt,
                        walk_tree_fn callbackOp, struct walk_stmt_info *wi)

This function walks all the statements in the sequence `seq` calling `walk_gimple_stmt` on each one. WI is as in `walk_gimple_stmt`. If `walk_gimple_stmt` returns non-NULL, the walk is stopped and the value returned. Otherwise, all the statements are walked and `NULL_TREE` returned.
13 Analysis and Optimization of GIMPLE tuples

GCC uses three main intermediate languages to represent the program during compilation: GENERIC, GIMPLE and RTL. GENERIC is a language-independent representation generated by each front end. It is used to serve as an interface between the parser and optimizer. GENERIC is a common representation that is able to represent programs written in all the languages supported by GCC.

GIMPLE and RTL are used to optimize the program. GIMPLE is used for target and language independent optimizations (e.g., inlining, constant propagation, tail call elimination, redundancy elimination, etc). Much like GENERIC, GIMPLE is a language independent, tree based representation. However, it differs from GENERIC in that the GIMPLE grammar is more restrictive: expressions contain no more than 3 operands (except function calls), it has no control flow structures and expressions with side effects are only allowed on the right hand side of assignments. See the chapter describing GENERIC and GIMPLE for more details.

This chapter describes the data structures and functions used in the GIMPLE optimizers (also known as “tree optimizers” or “middle end”). In particular, it focuses on all the macros, data structures, functions and programming constructs needed to implement optimization passes for GIMPLE.

13.1 Annotations

The optimizers need to associate attributes with variables during the optimization process. For instance, we need to know whether a variable has aliases. All these attributes are stored in data structures called annotations which are then linked to the field ann in struct tree_common.

13.2 SSA Operands

Almost every GIMPLE statement will contain a reference to a variable or memory location. Since statements come in different shapes and sizes, their operands are going to be located at various spots inside the statement’s tree. To facilitate access to the statement’s operands, they are organized into lists associated inside each statement’s annotation. Each element in an operand list is a pointer to a VAR_DECL, PARM_DECL or SSA_NAME tree node. This provides a very convenient way of examining and replacing operands.

Data flow analysis and optimization is done on all tree nodes representing variables. Any node for which SSA_VAR_P returns nonzero is considered when scanning statement operands. However, not all SSA_VAR_P variables are processed in the same way. For the purposes of optimization, we need to distinguish between references to local scalar variables and references to globals, statics, structures, arrays, aliased variables, etc. The reason is simple, the compiler can gather complete data flow information for a local scalar. On the other hand, a global variable may be modified by a function call, it may not be possible to keep track of all the elements of an array or the fields of a structure, etc.

The operand scanner gathers two kinds of operands: real and virtual. An operand for which is_gimple_reg returns true is considered real, otherwise it is a virtual operand. We also distinguish between uses and definitions. An operand is used if its value is loaded by the statement (e.g., the operand at the RHS of an assignment). If the statement assigns a
new value to the operand, the operand is considered a definition (e.g., the operand at the LHS of an assignment).

Virtual and real operands also have very different data flow properties. Real operands are unambiguous references to the full object that they represent. For instance, given

```c
{  
  int a, b;  
  a = b  
}
```

Since `a` and `b` are non-aliased locals, the statement `a = b` will have one real definition and one real use because variable `a` is completely modified with the contents of variable `b`. Real definition are also known as *killing definitions*. Similarly, the use of `b` reads all its bits.

In contrast, virtual operands are used with variables that can have a partial or ambiguous reference. This includes structures, arrays, globals, and aliased variables. In these cases, we have two types of definitions. For globals, structures, and arrays, we can determine from a statement whether a variable of these types has a killing definition. If the variable does, then the statement is marked as having a *must definition* of that variable. However, if a statement is only defining a part of the variable (i.e. a field in a structure), or if we know that a statement might define the variable but we cannot say for sure, then we mark that statement as having a *may definition*. For instance, given

```c
{  
  int a, b, *p;  
  if (...)  
    p = &a;  
  else  
    p = &b;  
  *p = 5;  
  return *p;  
}
```

The assignment `*p = 5` may be a definition of `a` or `b`. If we cannot determine statically where `p` is pointing to at the time of the store operation, we create virtual definitions to mark that statement as a potential definition site for `a` and `b`. Memory loads are similarly marked with virtual use operands. Virtual operands are shown in tree dumps right before the statement that contains them. To request a tree dump with virtual operands, use the `-vops` option to `-fdump-tree`:

```c
{  
  int a, b, *p;  
  if (...)  
    p = &a;  
  else  
    p = &b;  
  # a = VDEF <a>  
  # b = VDEF <b>  
  *p = 5;  
  # VUSE <a>  
  # VUSE <b>  
  return *p;  
}
```
Notice that \texttt{VDEF} operands have two copies of the referenced variable. This indicates that this is not a killing definition of that variable. In this case we refer to it as a \textit{may definition} or \textit{aliased store}. The presence of the second copy of the variable in the \texttt{VDEF} operand will become important when the function is converted into SSA form. This will be used to link all the non-killing definitions to prevent optimizations from making incorrect assumptions about them.

Operands are updated as soon as the statement is finished via a call to \texttt{update_stmt}. If statement elements are changed via \texttt{SET_USE} or \texttt{SET_DEF}, then no further action is required (i.e., those macros take care of updating the statement). If changes are made by manipulating the statement's tree directly, then a call must be made to \texttt{update_stmt} when complete. Calling one of the \texttt{bsi_insert} routines or \texttt{bsi_replace} performs an implicit call to \texttt{update_stmt}.

\subsection{Operand Iterators And Access Routines}

Operands are collected by \texttt{tree-ssa-operands.c}. They are stored inside each statement's annotation and can be accessed through either the operand iterators or an access routine.

The following access routines are available for examining operands:

1. \texttt{SINGLE\_SSA\_{USE,DEF,TREE}\_OPERAND}: These accessors will return NULL unless there is exactly one operand matching the specified flags. If there is exactly one operand, the operand is returned as either a \texttt{tree}, \texttt{def_operand_p}, or \texttt{use_operand_p}.

   \begin{verbatim}
   tree t = SINGLE_SSA_TREE_OPERAND (stmt, flags);
   use_operand_p u = SINGLE_SSA_USE_OPERAND (stmt, SSA_ALL_VIRTUAL_USES);
   def_operand_p d = SINGLE_SSA_DEF_OPERAND (stmt, SSA_OP_ALL_DEFS);
   \end{verbatim}

2. \texttt{ZERO\_SSA\_OPERANDS}: This macro returns true if there are no operands matching the specified flags.

   \begin{verbatim}
   if (ZERO_SSA_OPERANDS (stmt, SSA_OP_ALL_VIRTUALS))
       return;
   \end{verbatim}

3. \texttt{NUM\_SSA\_OPERANDS}: This macro Returns the number of operands matching 'flags'. This actually executes a loop to perform the count, so only use this if it is really needed.

   \begin{verbatim}
   int count = NUM_SSA_OPERANDS (stmt, flags)
   \end{verbatim}

If you wish to iterate over some or all operands, use the \texttt{FOR\_EACH\_SSA\_{USE,DEF,TREE}\_OPERAND} iterator. For example, to print all the operands for a statement:

\begin{verbatim}
void print_ops (tree stmt)
{
    ssa_op_iter;
    tree var;

    FOR_EACH_SSA_TREE_OPERAND (var, stmt, iter, SSA_OP_ALL_OPERANDS)
    print_generic_expr (stderr, var, TDF_SLIM);
}
\end{verbatim}

How to choose the appropriate iterator:

1. Determine whether you are need to see the operand pointers, or just the trees, and choose the appropriate macro:

   \begin{center}
   \begin{tabular}{ll}
   \textbf{Need} & \textbf{Macro} \\
   \hline
   use_operand_p & \texttt{FOR\_EACH\_SSA\_USE\_OPERAND} \\
   \end{tabular}
   \end{center}
2. You need to declare a variable of the type you are interested in, and an ssa_op_iter structure which serves as the loop controlling variable.

3. Determine which operands you wish to use, and specify the flags of those you are interested in. They are documented in ‘tree-ssa-operands.h’:

```c
#define SSA_OP_USE 0x01 /* Real USE operands. */
#define SSA_OP_DEF 0x02 /* Real DEF operands. */
#define SSA_OP_VUSE 0x04 /* VUSE operands. */
#define SSA_OP_VDEF 0x08 /* VDEF operands. */
```

/* These are commonly grouped operand flags. */
#define SSA_OP_VIRTUAL_USES (SSA_OP_VUSE)
#define SSA_OP_VIRTUAL_DEFS (SSA_OP_VDEF)
#define SSA_OP_ALL_VIRTUALS (SSA_OP_VIRTUAL_USES | SSA_OP_VIRTUAL_DEFS)
#define SSA_OP_ALL_USES (SSA_OP_VIRTUAL_USES | SSA_OP_USE)
#define SSA_OP_ALL_DEFS (SSA_OP_VIRTUAL_DEFS | SSA_OP_DEF)
#define SSA_OP_ALL_OPERANDS (SSA_OP_ALL_USES | SSA_OP_ALL_DEFS)

So if you want to look at the use pointers for all the USE and VUSE operands, you would do something like:

```c
use_operand_p use_p;
ssa_op_iter iter;
FOR_EACH_SSA_USE_OPERAND (use_p, stmt, iter, (SSA_OP_USE | SSA_OP_VUSE))
{
    process_use_ptr (use_p);
}
```

The TREE macro is basically the same as the USE and DEF macros, only with the use or def dereferenced via USE_FROM_PTR (use_p) and DEF_FROM_PTR (def_p). Since we aren’t using operand pointers, use and defs flags can be mixed.

```c
tree var;
ssa_op_iter iter;
FOR_EACH_SSA_TREE_OPERAND (var, stmt, iter, SSA_OP_VUSE)
{
    print_generic_expr (stderr, var, TDF_SLIM);
}
```

VDEFs are broken into two flags, one for the DEF portion (SSA_OP_VDEF) and one for the USE portion (SSA_OP_VUSE).

There are many examples in the code, in addition to the documentation in ‘tree-ssa-operands.h’ and ‘ssa-iterators.h’.

There are also a couple of variants on the stmt iterators regarding PHI nodes.

FOR_EACH_PHI_ARG Works exactly like FOR_EACH_SSA_USE_OPERAND, except it works over PHI arguments instead of statement operands.

```c
/* Look at every virtual PHI use. */
FOR_EACH_PHI_ARG (use_p, phi_stmt, iter, SSA_OP_VIRTUAL_USES)
{
    my_code;
}
/* Look at every real PHI use. */
```
FOR EACH PHI_ARG (use_p, phi_stmt, iter, SSA_OP_USES)
  my_code;
/* Look at every PHI use. */
FOR EACH PHI_ARG (use_p, phi_stmt, iter, SSA_OP_ALL_USES)
  my_code;
FOR EACH PHI OR_STMT_{USE,DEF} works exactly like FOR EACH SSA_{USE,DEF}_OPERAND, except it will function on either a statement or a PHI node. These should be used when it is appropriate but they are not quite as efficient as the individual FOR EACH PHI and FOR EACH SSA routines.
FOR EACH PHI OR_STMT_USE (use_operand_p, stmt, iter, flags)
{
  my_code;
}
FOR EACH PHI OR_STMT_DEF (def_operand_p, phi, iter, flags)
{
  my_code;
}

13.2.2 Immediate Uses
Immediate use information is now always available. Using the immediate use iterators, you may examine every use of any SSA_NAME. For instance, to change each use of ssa_var to ssa_var2 and call fold_stmt on each stmt after that is done:

use_operand_p imm_use_p;
imm_use_iterator iterator;
tree ssa_var, stmt;
FOR EACH IMM_USE_STMT (stmt, iterator, ssa_var)
{
  FOR EACH IMM_USE_ON_STMT (imm_use_p, iterator)
    SET_USE (imm_use_p, ssa_var_2);
    fold_stmt (stmt);
}

There are 2 iterators which can be used. FOR EACH IMM_USE_FAST is used when the immediate uses are not changed, i.e., you are looking at the uses, but not setting them.

If they do get changed, then care must be taken that things are not changed under the iterators, so use the FOR EACH IMM_USE_STMT and FOR EACH IMM_USE_ON_STMT iterators. They attempt to preserve the sanity of the use list by moving all the uses for a statement into a controlled position, and then iterating over those uses. Then the optimization can manipulate the stmt when all the uses have been processed. This is a little slower than the FAST version since it adds a placeholder element and must sort through the list a bit for each statement. This placeholder element must be also be removed if the loop is terminated early; a destructor takes care of that when leaving the FOR EACH IMM_USE_STMT scope.

There are checks in verify_ssa which verify that the immediate use list is up to date, as well as checking that an optimization didn’t break from the loop without using this macro. It is safe to simply ‘break’; from a FOR EACH IMM_USE_FAST traverse.

Some useful functions and macros:
1. has_zero_uses (ssa_var) : Returns true if there are no uses of ssa_var.
2. has_single_use (ssa_var) : Returns true if there is only a single use of ssa_var.
3. single_imm_use (ssa_var, use_operand_p *ptr, tree *stmt) : Returns true if there is only a single use of ssa_var, and also returns the use pointer and statement it occurs in, in the second and third parameters.
4. num_imm_uses (ssa_var) : Returns the number of immediate uses of ssa_var. It is better not to use this if possible since it simply utilizes a loop to count the uses.
5. PHI_ARG_INDEX_FROM_USE (use_p) : Given a use within a PHI node, return the index number for the use. An assert is triggered if the use isn’t located in a PHI node.
6. USE_STMT (use_p) : Return the statement a use occurs in.

Note that uses are not put into an immediate use list until their statement is actually inserted into the instruction stream via a bsi_* routine.

It is also still possible to utilize lazy updating of statements, but this should be used only when absolutely required. Both alias analysis and the dominator optimizations currently do this.

When lazy updating is being used, the immediate use information is out of date and cannot be used reliably. Lazy updating is achieved by simply marking statements modified via calls to gimple_set_modified instead of update_stmt. When lazy updating is no longer required, all the modified statements must have update_stmt called in order to bring them up to date. This must be done before the optimization is finished, or verify_ssa will trigger an abort.

This is done with a simple loop over the instruction stream:

```c
block_stmt_iterator bsi;
basic_block bb;
FOR_EACH_BB (bb)
{
    for (bsi = bsi_start (bb); !bsi_end_p (bsi); bsi_next (&bsi))
        update_stmt_if_modified (bsi_stmt (bsi));
}
```

13.3 Static Single Assignment

Most of the tree optimizers rely on the data flow information provided by the Static Single Assignment (SSA) form. We implement the SSA form as described in R. Cytron, J. Ferrante, B. Rosen, M. Wegman, and K. Zadeck. Efficiently Computing Static Single Assignment Form and the Control Dependence Graph. ACM Transactions on Programming Languages and Systems, 13(4):451-490, October 1991.

The SSA form is based on the premise that program variables are assigned in exactly one location in the program. Multiple assignments to the same variable create new versions of that variable. Naturally, actual programs are seldom in SSA form initially because variables tend to be assigned multiple times. The compiler modifies the program representation so that every time a variable is assigned in the code, a new version of the variable is created. Different versions of the same variable are distinguished by subscripting the variable name with its version number. Variables used in the right-hand side of expressions are renamed so that their version number matches that of the most recent assignment.

We represent variable versions using SSA_NAME nodes. The renaming process in ‘tree-ssa.c’ wraps every real and virtual operand with an SSA_NAME node which contains
the version number and the statement that created the SSA_NAME. Only definitions and virtual definitions may create new SSA_NAME nodes.

Sometimes, flow of control makes it impossible to determine the most recent version of a variable. In these cases, the compiler inserts an artificial definition for that variable called PHI function or PHI node. This new definition merges all the incoming versions of the variable to create a new name for it. For instance,

```c
if (...)  
a_1 = 5;
else if (...)  
a_2 = 2;
else  
a_3 = 13;
```

```c
# a_4 = PHI <a_1, a_2, a_3>
return a_4;
```

Since it is not possible to determine which of the three branches will be taken at runtime, we don’t know which of a_1, a_2 or a_3 to use at the return statement. So, the SSA renamer creates a new version a_4 which is assigned the result of “merging” a_1, a_2 and a_3. Hence, PHI nodes mean “one of these operands. I don’t know which”.

The following functions can be used to examine PHI nodes

- `gimple_phi_result (phi)`  
  Returns the SSA_NAME created by PHI node phi (i.e., phi’s LHS).

- `gimple_phi_num_args (phi)`  
  Returns the number of arguments in phi. This number is exactly the number of incoming edges to the basic block holding phi.

- `gimple_phi_arg (phi, i)`  
  Returns ith argument of phi.

- `gimple_phi_arg_edge (phi, i)`  
  Returns the incoming edge for the ith argument of phi.

- `gimple_phi_arg_def (phi, i)`  
  Returns the SSA_NAME for the ith argument of phi.

### 13.3.1 Preserving the SSA form

Some optimization passes make changes to the function that invalidate the SSA property. This can happen when a pass has added new symbols or changed the program so that variables that were previously aliased aren’t anymore. Whenever something like this happens, the affected symbols must be renamed into SSA form again. Transformations that emit new code or replicate existing statements will also need to update the SSA form.

Since GCC implements two different SSA forms for register and virtual variables, keeping the SSA form up to date depends on whether you are updating register or virtual names. In both cases, the general idea behind incremental SSA updates is similar: when new SSA names are created, they typically are meant to replace other existing names in the program.

For instance, given the following code:
1 L0:
2 x_1 = PHI (0, x_5)
3 if (x_1 < 10)
4  if (x_1 > 7)
5   y_2 = 0
6  else
7   y_3 = x_1 + x_7
8 endif
9 x_5 = x_1 + 1
10 goto L0;
11 endif

Suppose that we insert new names x_10 and x_11 (lines 4 and 8).

1 L0:
2 x_1 = PHI (0, x_5)
3 if (x_1 < 10)
4  x_10 = ...
5  if (x_1 > 7)
6   y_2 = 0
7  else
8   x_11 = ...
9   y_3 = x_1 + x_7
10 endif
11 x_5 = x_1 + 1
12 goto L0;
13 endif

We want to replace all the uses of x_1 with the new definitions of x_10 and x_11. Note that the only uses that should be replaced are those at lines 5, 9 and 11. Also, the use of x_7 at line 9 should not be replaced (this is why we cannot just mark symbol x for renaming).

Additionally, we may need to insert a PHI node at line 11 because that is a merge point for x_10 and x_11. So the use of x_1 at line 11 will be replaced with the new PHI node. The insertion of PHI nodes is optional. They are not strictly necessary to preserve the SSA form, and depending on what the caller inserted, they may not even be useful for the optimizers.

Updating the SSA form is a two step process. First, the pass has to identify which names need to be updated and/or which symbols need to be renamed into SSA form for the first time. When new names are introduced to replace existing names in the program, the mapping between the old and the new names are registered by calling register_new_name_mapping (note that if your pass creates new code by duplicating basic blocks, the call to tree_duplicate_bb will set up the necessary mappings automatically).

After the replacement mappings have been registered and new symbols marked for renaming, a call to update_ssa makes the registered changes. This can be done with an explicit call or by creating TODO flags in the tree_opt_pass structure for your pass. There are several TODO flags that control the behavior of update_ssa:

- TODO_update_ssa. Update the SSA form inserting PHI nodes for newly exposed symbols and virtual names marked for updating. When updating real names, only insert PHI nodes for a real name O_j in blocks reached by all the new and old definitions for O_j. If the iterated dominance frontier for O_j is not pruned, we may end up inserting PHI nodes in blocks that have one or more edges with no incoming definition for O_j. This would lead to uninitialized warnings for O_j’s symbol.
• **TODO_update_ssa_no_phi.** Update the SSA form without inserting any new PHI nodes at all. This is used by passes that have either inserted all the PHI nodes themselves or passes that need only to patch use-def and def-def chains for virtuals (e.g., DCE).

• **TODO_update_ssa_full_phi.** Insert PHI nodes everywhere they are needed. No pruning of the IDF is done. This is used by passes that need the PHI nodes for $O_j$ even if it means that some arguments will come from the default definition of $O_j$’s symbol (e.g., *pass_linear_transform*).

WARNING: If you need to use this flag, chances are that your pass may be doing something wrong. Inserting PHI nodes for an old name where not all edges carry a new replacement may lead to silent codegen errors or spurious uninitialized warnings.

• **TODO_update_ssa_only_virtuals.** Passes that update the SSA form on their own may want to delegate the updating of virtual names to the generic updater. Since FUD chains are easier to maintain, this simplifies the work they need to do. NOTE: If this flag is used, any OLD->NEW mappings for real names are explicitly destroyed and only the symbols marked for renaming are processed.

### 13.3.2 Examining SSA_NAME nodes

The following macros can be used to examine SSA_NAME nodes

```c
[Macro] SSA_NAME_DEF_STMT (var)

Returns the statement $s$ that creates the SSA_NAME var. If $s$ is an empty statement (i.e., IS_EMPTY_STMT ($s$) returns true), it means that the first reference to this variable is a USE or a VUSE.
```

```c
[Macro] SSA_NAME_VERSION (var)

Returns the version number of the SSA_NAME object var.
```

### 13.3.3 Walking the dominator tree

```c
void walk_dominator_tree (walk_data, bb)

This function walks the dominator tree for the current CFG calling a set of callback functions defined in struct dom_walk_data in ‘domwalk.h’. The callback functions you need to define give you hooks to execute custom code at various points during traversal:

1. Once to initialize any local data needed while processing $bb$ and its children. This local data is pushed into an internal stack which is automatically pushed and popped as the walker traverses the dominator tree.
2. Once before traversing all the statements in the $bb$.
3. Once for every statement inside $bb$.
4. Once after traversing all the statements and before recursing into $bb$’s dominator children.
5. It then recurses into all the dominator children of $bb$.
6. After recursing into all the dominator children of $bb$ it can, optionally, traverse every statement in $bb$ again (i.e., repeating steps 2 and 3).
7. Once after walking the statements in $bb$ and $bb$’s dominator children. At this stage, the block local data stack is popped.
```
13.4 Alias analysis

Alias analysis in GIMPLE SSA form consists of two pieces. First the virtual SSA web ties conflicting memory accesses and provides a SSA use-def chain and SSA immediate-use chains for walking possibly dependent memory accesses. Second an alias-oracle can be queried to disambiguate explicit and implicit memory references.

1. Memory SSA form.

All statements that may use memory have exactly one accompanied use of a virtual SSA name that represents the state of memory at the given point in the IL.

All statements that may define memory have exactly one accompanied definition of a virtual SSA name using the previous state of memory and defining the new state of memory after the given point in the IL.

```c
int i;
int foo (void)
{
    # .MEM_3 = VDEF <.MEM_2(D)>
    i = 1;
    # VUSE <.MEM_3>
    return i;
}
```

The virtual SSA names in this case are .MEM_2(D) and .MEM_3. The store to the global variable i defines .MEM_3 invalidating .MEM_2(D). The load from i uses that new state .MEM_3.

The virtual SSA web serves as constraints to SSA optimizers preventing illegitimate code-motion and optimization. It also provides a way to walk related memory statements.

2. Points-to and escape analysis.

Points-to analysis builds a set of constraints from the GIMPLE SSA IL representing all pointer operations and facts we do or do not know about pointers. Solving this set of constraints yields a conservatively correct solution for each pointer variable in the program (though we are only interested in SSA name pointers) as to what it may possibly point to.

This points-to solution for a given SSA name pointer is stored in the pt_solution sub-structure of the SSA_NAME_PTR_INFO record. The following accessor functions are available:

- pt_solution_includes
- pt_solutions_intersect

Points-to analysis also computes the solution for two special set of pointers, ESCAPED and CALLUSED. Those represent all memory that has escaped the scope of analysis or that is used by pure or nested const calls.

3. Type-based alias analysis

Type-based alias analysis is frontend dependent though generic support is provided by the middle-end in alias.c. TBAA code is used by both tree optimizers and RTL optimizers.

Every language that wishes to perform language-specific alias analysis should define a function that computes, given a tree node, an alias set for the node. Nodes in different
alias sets are not allowed to alias. For an example, see the C front-end function c_get_alias_set.

4. Tree alias-oracle
The tree alias-oracle provides means to disambiguate two memory references and memory references against statements. The following queries are available:

- `refs_may_alias_p`
- `ref_maybe_used_by_stmt_p`
- `stmt_may_clobber_ref_p`

In addition to those two kind of statement walkers are available walking statements related to a reference ref. `walk_non_aliased_vuses` walks over dominating memory defining statements and calls back if the statement does not clobber ref providing the non-aliased VUSE. The walk stops at the first clobbering statement or if asked to. `walk_aliased_vdefs` walks over dominating memory defining statements and calls back on each statement clobbering ref providing its aliasing VDEF. The walk stops if asked to.

13.5 Memory model
The memory model used by the middle-end models that of the C/C++ languages. The middle-end has the notion of an effective type of a memory region which is used for type-based alias analysis.

The following is a refinement of ISO C99 6.5/6, clarifying the block copy case to follow common sense and extending the concept of a dynamic effective type to objects with a declared type as required for C++.

The effective type of an object for an access to its stored value is the declared type of the object or the effective type determined by a previous store to it. If a value is stored into an object through an lvalue having a type that is not a character type, then the type of the lvalue becomes the effective type of the object for that access and for subsequent accesses that do not modify the stored value. If a value is copied into an object using memcpy or memmove, or is copied as an array of character type, then the effective type of the modified object for that access and for subsequent accesses that do not modify the value is undetermined. For all other accesses to an object, the effective type of the object is simply the type of the lvalue used for the access.
14 RTL Representation

The last part of the compiler work is done on a low-level intermediate representation called Register Transfer Language. In this language, the instructions to be output are described, pretty much one by one, in an algebraic form that describes what the instruction does.

RTL is inspired by Lisp lists. It has both an internal form, made up of structures that point at other structures, and a textual form that is used in the machine description and in printed debugging dumps. The textual form uses nested parentheses to indicate the pointers in the internal form.

14.1 RTL Object Types

RTL uses five kinds of objects: expressions, integers, wide integers, strings and vectors. Expressions are the most important ones. An RTL expression (“RTX”, for short) is a C structure, but it is usually referred to with a pointer; a type that is given the typedef name rtx.

An integer is simply an int; their written form uses decimal digits. A wide integer is an integral object whose type is HOST_WIDE_INT; their written form uses decimal digits.

A string is a sequence of characters. In core it is represented as a char * in usual C fashion, and it is written in C syntax as well. However, strings in RTL may never be null. If you write an empty string in a machine description, it is represented in core as a null pointer rather than as a pointer to a null character. In certain contexts, these null pointers instead of strings are valid. Within RTL code, strings are most commonly found inside symbol_ref expressions, but they appear in other contexts in the RTL expressions that make up machine descriptions.

In a machine description, strings are normally written with double quotes, as you would in C. However, strings in machine descriptions may extend over many lines, which is invalid C, and adjacent string constants are not concatenated as they are in C. Any string constant may be surrounded with a single set of parentheses. Sometimes this makes the machine description easier to read.

There is also a special syntax for strings, which can be useful when C code is embedded in a machine description. Wherever a string can appear, it is also valid to write a C-style brace block. The entire brace block, including the outermost pair of braces, is considered to be the string constant. Double quote characters inside the braces are not special. Therefore, if you write string constants in the C code, you need not escape each quote character with a backslash.

A vector contains an arbitrary number of pointers to expressions. The number of elements in the vector is explicitly present in the vector. The written form of a vector consists of square brackets (’[...’]’) surrounding the elements, in sequence and with whitespace separating them. Vectors of length zero are not created; null pointers are used instead.

Expressions are classified by expression codes (also called RTX codes). The expression code is a name defined in ‘rtl.def’, which is also (in uppercase) a C enumeration constant. The possible expression codes and their meanings are machine-independent. The code of an RTX can be extracted with the macro GET_CODE (x) and altered with PUT_CODE (x, newcode).
The expression code determines how many operands the expression contains, and what kinds of objects they are. In RTL, unlike Lisp, you cannot tell by looking at an operand what kind of object it is. Instead, you must know from its context—from the expression code of the containing expression. For example, in an expression of code `subreg`, the first operand is to be regarded as an expression and the second operand as a polynomial integer. In an expression of code `plus`, there are two operands, both of which are to be regarded as expressions. In a `symbol_ref` expression, there is one operand, which is to be regarded as a string.

Expressions are written as parentheses containing the name of the expression type, its flags and machine mode if any, and then the operands of the expression (separated by spaces).

Expression code names in the ‘md’ file are written in lowercase, but when they appear in C code they are written in uppercase. In this manual, they are shown as follows: `const_int`.

In a few contexts a null pointer is valid where an expression is normally wanted. The written form of this is `(nil)`.

### 14.2 RTL Classes and Formats

The various expression codes are divided into several classes, which are represented by single characters. You can determine the class of an RTX code with the macro `GET_RTX_CLASS (code)`. Currently, ‘rtl.def’ defines these classes:

- **RTX_OBJ**
  - An RTX code that represents an actual object, such as a register (`REG`) or a memory location (`MEM`, `SYMBOL_REF`). `LO_SUM` is also included; instead, `SUBREG` and `STRICT_LOW_PART` are not in this class, but in class `RTX_EXTRA`.

- **RTX_CONST_OBJ**
  - An RTX code that represents a constant object. `HIGH` is also included in this class.

- **RTX_COMPARE**
  - An RTX code for a non-symmetric comparison, such as `GEU` or `LT`.

- **RTX_COMM_COMPARE**
  - An RTX code for a symmetric (commutative) comparison, such as `EQ` or `ORDERED`.

- **RTX_UNARY**
  - An RTX code for a unary arithmetic operation, such as `NEG`, `NOT`, or `ABS`. This category also includes value extension (sign or zero) and conversions between integer and floating point.

- **RTX_COMM_ARITH**
  - An RTX code for a commutative binary operation, such as `PLUS` or `AND`. `NE` and `EQ` are comparisons, so they have class `RTX_COMM_COMPARE`.

- **RTX_BIN_ARITH**
  - An RTX code for a non-commutative binary operation, such as `MINUS`, `DIV`, or `ASHIFTRT`.
RTX_BITFIELD_OPS
An RTX code for a bit-field operation. Currently only ZERO_EXTRACT and SIGN_EXTRACT. These have three inputs and are lvalues (so they can be used for insertion as well). See Section 14.11 [Bit-Fields], page 297.

RTX_TERNARY
An RTX code for other three input operations. Currently only IF_THEN_ELSE, VEC_MERGE, SIGN_EXTRACT, ZERO_EXTRACT, and FMA.

RTX_INSN
An RTX code for an entire instruction: INSN, JUMP_INSN, and CALL_INSN. See Section 14.19 [Insns], page 308.

RTX_MATCH
An RTX code for something that matches in insns, such as MATCH_DUP. These only occur in machine descriptions.

RTX_AUTOINC
An RTX code for an auto-increment addressing mode, such as POST_INC. ‘XEXP (x, 0)’ gives the auto-modified register.

RTX_EXTRA
All other RTX codes. This category includes the remaining codes used only in machine descriptions (DEFINE_*, etc.). It also includes all the codes describing side effects (SET, USE, Clobber, etc.) and the non-insns that may appear on an insn chain, such as NOTE, BARRIER, and CODE_LABEL. SUBREG is also part of this class.

For each expression code, ‘rtl.def’ specifies the number of contained objects and their kinds using a sequence of characters called the format of the expression code. For example, the format of subreg is ‘ep’.

These are the most commonly used format characters:

- e An expression (actually a pointer to an expression).
- i An integer.
- w A wide integer.
- s A string.
- E A vector of expressions.

A few other format characters are used occasionally:

- u ‘u’ is equivalent to ‘e’ except that it is printed differently in debugging dumps. It is used for pointers to insns.
- n ‘n’ is equivalent to ‘i’ except that it is printed differently in debugging dumps. It is used for the line number or code number of a note insn.
- S ‘S’ indicates a string which is optional. In the RTL objects in core, ‘S’ is equivalent to ‘s’, but when the object is read, from an ‘md’ file, the string value of this operand may be omitted. An omitted string is taken to be the null string.
‘\(V\)’ indicates a vector which is optional. In the RTL objects in core, ‘\(V\)’ is equivalent to ‘\(E\)’, but when the object is read from an ‘\(md\)’ file, the vector value of this operand may be omitted. An omitted vector is effectively the same as a vector of no elements.

‘\(B\)’ indicates a pointer to basic block structure.

‘\(p\)’ A polynomial integer. At present this is used only for SUBREG_BYTE.

‘\(0\)’ means a slot whose contents do not fit any normal category. ‘\(0\)’ slots are not printed at all in dumps, and are often used in special ways by small parts of the compiler.

There are macros to get the number of operands and the format of an expression code:

\[
\text{GET_RTX_LENGTH (code)}
\]
Number of operands of an RTX of code code.

\[
\text{GET_RTX_FORMAT (code)}
\]
The format of an RTX of code code, as a C string.

Some classes of RTX codes always have the same format. For example, it is safe to assume that all comparison operations have format ee.

RTX_UNARY
All codes of this class have format e.

RTX_BIN_ARITH
RTX_COMM_ARITH
RTX_COMM_COMPARE
RTX_COMPARE
All codes of these classes have format ee.

RTX_BITFIELD_OPS
RTX_TERNARY
All codes of these classes have format eee.

RTX_INSN
All codes of this class have formats that begin with iuueiee. See Section 14.19 [Insns], page 308. Note that not all RTL objects linked onto an insn chain are of class RTX_INSN.

RTX_CONST_OBJ
RTX_OBJ
RTX_MATCH
RTX_EXTRA
You can make no assumptions about the format of these codes.

### 14.3 Access to Operands

Operands of expressions are accessed using the macros XEXP, XINT, XWINT and XSTR. Each of these macros takes two arguments: an expression-pointer (RTX) and an operand number (counting from zero). Thus,

\[
\text{XEXP (x, 2)}
\]
accesses operand 2 of expression x, as an expression.
\texttt{XINT (x, 2)}

accesses the same operand as an integer. \texttt{XSTR}, used in the same fashion, would access it as a string.

Any operand can be accessed as an integer, as an expression or as a string. You must choose the correct method of access for the kind of value actually stored in the operand. You would do this based on the expression code of the containing expression. That is also how you would know how many operands there are.

For example, if \( x \) is an \texttt{int\_list} expression, you know that it has two operands which can be correctly accessed as \texttt{XINT (x, 0)} and \texttt{XEXP (x, 1)}. Incorrect accesses like \texttt{XEXP (x, 0)} and \texttt{XINT (x, 1)} would compile, but would trigger an internal compiler error when rtl checking is enabled. Nothing stops you from writing \texttt{XEXP (x, 28)} either, but this will access memory past the end of the expression with unpredictable results.

Access to operands which are vectors is more complicated. You can use the macro \texttt{XVEC} to get the vector-pointer itself, or the macros \texttt{XVECEXP} and \texttt{XVECLEN} to access the elements and length of a vector.

\begin{verbatim}
XVEC (exp, idx)
  Access the vector-pointer which is operand number \( idx \) in \( exp \).

XVECLEN (exp, idx)
  Access the length (number of elements) in the vector which is in operand number \( idx \) in \( exp \). This value is an \texttt{int}.

XVECEXP (exp, idx, eltnum)
  Access element number \( eltnum \) in the vector which is in operand number \( idx \) in \( exp \). This value is an RTX.

  It is up to you to make sure that \( eltnum \) is not negative and is less than \texttt{XVECLEN (exp, idx)}.
\end{verbatim}

All the macros defined in this section expand into lvalues and therefore can be used to assign the operands, lengths and vector elements as well as to access them.

### 14.4 Access to Special Operands

Some RTL nodes have special annotations associated with them.

\begin{verbatim}
MEM

MEM_ALIAS_SET (x)
  If 0, \( x \) is not in any alias set, and may alias anything. Otherwise, \( x \) can only alias MEMs in a conflicting alias set. This value is set in a language-dependent manner in the front-end, and should not be altered in the back-end. In some front-ends, these numbers may correspond in some way to types, or other language-level entities, but they need not, and the back-end makes no such assumptions. These set numbers are tested with \texttt{alias\_sets\_conflict\_p}.

MEM_EXPR (x)
  If this register is known to hold the value of some user-level declaration, this is that tree node. It may also be a \texttt{COMPONENT\_REF},
\end{verbatim}
in which case this is some field reference, and \texttt{TREE_OPERAND (x, 0)} contains the declaration, or another \texttt{COMPONENT_REF}, or null if there is no compile-time object associated with the reference.

\texttt{MEM_OFFSET_KNOWN_P (x)}

True if the offset of the memory reference from \texttt{MEM_EXPR} is known. ‘\texttt{MEM_OFFSET (x)}’ provides the offset if so.

\texttt{MEM_OFFSET (x)}

The offset from the start of \texttt{MEM_EXPR}. The value is only valid if ‘\texttt{MEM_OFFSET_KNOWN_P (x)}’ is true.

\texttt{MEM_SIZE_KNOWN_P (x)}

True if the size of the memory reference is known. ‘\texttt{MEM_SIZE (x)}’ provides its size if so.

\texttt{MEM_SIZE (x)}

The size in bytes of the memory reference. This is mostly relevant for BLKmode references as otherwise the size is implied by the mode. The value is only valid if ‘\texttt{MEM_SIZE_KNOWN_P (x)}’ is true.

\texttt{MEM_ALIGN (x)}

The known alignment in bits of the memory reference.

\texttt{MEM_ADDR_SPACE (x)}

The address space of the memory reference. This will commonly be zero for the generic address space.

\texttt{REG}

\texttt{ORIGINAL_REGNO (x)}

This field holds the number the register “originally” had; for a pseudo register turned into a hard reg this will hold the old pseudo register number.

\texttt{REG_EXPR (x)}

If this register is known to hold the value of some user-level declaration, this is that tree node.

\texttt{REG_OFFSET (x)}

If this register is known to hold the value of some user-level declaration, this is the offset into that logical storage.

\texttt{SYMBOL_REF}

\texttt{SYMBOL_REFDECL (x)}

If the \texttt{symbol_ref} x was created for a \texttt{VAR_DECL} or a \texttt{FUNCTION_DECL}, that tree is recorded here. If this value is null, then x was created by back end code generation routines, and there is no associated front end symbol table entry. \texttt{SYMBOL_REFDECL} may also point to a tree of class ‘\texttt{c}’, that is, some sort of constant. In this case, the \texttt{symbol_ref} is an entry in the per-file constant pool; again, there is no associated front end symbol table entry.
SYMBOL_REF_CONSTANT (x)
If ‘CONSTANT_POOL_ADDRESS_P (x)’ is true, this is the constant pool entry for x. It is null otherwise.

SYMBOL_REF_DATA (x)
A field of opaque type used to store SYMBOL_REF_DECL or SYMBOL_REF_CONSTANT.

SYMBOL_REF_FLAGS (x)
In a symbol_ref, this is used to communicate various predicates about the symbol. Some of these are common enough to be computed by common code, some are specific to the target. The common bits are:

SYMBOL_FLAG_FUNCTION
Set if the symbol refers to a function.

SYMBOL_FLAG_LOCAL
Set if the symbol is local to this “module”. See TARGET_BINDS_LOCAL_P.

SYMBOL_FLAG_EXTERNAL
Set if this symbol is not defined in this translation unit. Note that this is not the inverse of SYMBOL_FLAG_LOCAL.

SYMBOL_FLAG_SMALL
Set if the symbol is located in the small data section. See TARGET_IN_SMALL_DATA_P.

SYMBOL_REF_TLS_MODEL (x)
This is a multi-bit field accessor that returns the tls_model to be used for a thread-local storage symbol. It returns zero for non-thread-local symbols.

SYMBOL_FLAG_HAS_BLOCK_INFO
Set if the symbol has SYMBOL_REF_BLOCK and SYMBOL_REF_BLOCK_OFFSET fields.

SYMBOL_FLAG_ANCHOR
Set if the symbol is used as a section anchor. “Section anchors” are symbols that have a known position within an object_block and that can be used to access nearby members of that block. They are used to implement ‘-fsection-anchors’.
If this flag is set, then SYMBOL_FLAG_HAS_BLOCK_INFO will be too.

Bits beginning with SYMBOL_FLAG_MACH_DEP are available for the target’s use.

SYMBOL_REF_BLOCK (x)
If ‘SYMBOL_REF_HAS_BLOCK_INFO_P (x)’, this is the ‘object_block’ structure to which the symbol belongs, or NULL if it has not been assigned a block.
SYMBOL_REF_BLOCK_OFFSET (x)
If ‘SYMBOL_REF_HAS_BLOCK_INFO_P (x)’, this is the offset of x from the first object in ‘SYMBOL_REF_BLOCK (x)’. The value is negative if x has not yet been assigned to a block, or it has not been given an offset within that block.

14.5 Flags in an RTL Expression

RTL expressions contain several flags (one-bit bit-fields) that are used in certain types of expression. Most often they are accessed with the following macros, which expand into lvalues.

CROSSING_JUMP_P (x)
Nonzero in a jump_insn if it crosses between hot and cold sections, which could potentially be very far apart in the executable. The presence of this flag indicates to other optimizations that this branching instruction should not be “collapsed” into a simpler branching construct. It is used when the optimization to partition basic blocks into hot and cold sections is turned on.

CONSTANT_POOL_ADDRESS_P (x)
Nonzero in a symbol_ref if it refers to part of the current function’s constant pool. For most targets these addresses are in a .rodata section entirely separate from the function, but for some targets the addresses are close to the beginning of the function. In either case GCC assumes these addresses can be addressed directly, perhaps with the help of base registers. Stored in the unchanging field and printed as ‘/u’.

INSN_ANNULLED_BRANCH_P (x)
In a jump_insn, call_insn, or insn indicates that the branch is an annulling one. See the discussion under sequence below. Stored in the unchanging field and printed as ‘/u’.

INSN_DELETED_P (x)
In an insn, call_insn, jump_insn, code_label, jump_table_data, barrier, or note, nonzero if the insn has been deleted. Stored in the volatil field and printed as ‘/v’.

INSN_FROM_TARGET_P (x)
In an insn or jump_insn or call_insn in a delay slot of a branch, indicates that the insn is from the target of the branch. If the branch insn has INSN_ANNULLED_BRANCH_P set, this insn will only be executed if the branch is taken. For annulled branches with INSN_FROM_TARGET_P clear, the insn will be executed only if the branch is not taken. When INSN_ANNULLED_BRANCH_P is not set, this insn will always be executed. Stored in the in_struct field and printed as ‘/s’.

LABEL_PRESERVE_P (x)
In a code_label or note, indicates that the label is referenced by code or data not visible to the RTL of a given function. Labels referenced by a non-local goto will have this bit set. Stored in the in_struct field and printed as ‘/s’.

LABEL_REF_NONLOCAL_P (x)
In label_ref and reg_label expressions, nonzero if this is a reference to a non-local label. Stored in the volatil field and printed as ‘/v’.
MEM_KEEP_ALIAS_SET_P (x)
In mem expressions, 1 if we should keep the alias set for this mem unchanged
when we access a component. Set to 1, for example, when we are already in
a non-addressable component of an aggregate. Stored in the jump field and
printed as ‘/j’.

MEM_VOLATILE_P (x)
In mem, asm_operands, and asm_input expressions, nonzero for volatile memory
references. Stored in the volatil field and printed as ‘/v’.

MEM_NOTRAP_P (x)
In mem, nonzero for memory references that will not trap. Stored in the call
field and printed as ‘/c’.

MEM_POINTER (x)
Nonzero in a mem if the memory reference holds a pointer. Stored in the frame_related
field and printed as ‘/f’.

MEM_READONLY_P (x)
Nonzero in a mem, if the memory is statically allocated and read-only.
Read-only in this context means never modified during the lifetime of the pro-
gram, not necessarily in ROM or in write-disabled pages. A common example
of the later is a shared library’s global offset table. This table is initialized by
the runtime loader, so the memory is technically writable, but after control is
transferred from the runtime loader to the application, this memory will never
be subsequently modified.
Stored in the unchanging field and printed as ‘/u’.

PREFETCH_SCHEDULE_BARRIER_P (x)
In a prefetch, indicates that the prefetch is a scheduling barrier. No other
INSNs will be moved over it. Stored in the volatil field and printed as ‘/v’.

REG_FUNCTION_VALUE_P (x)
Nonzero in a reg if it is the place in which this function’s value is going to be
returned. (This happens only in a hard register.) Stored in the return_val
field and printed as ‘/i’.

REG_POINTER (x)
Nonzero in a reg if the register holds a pointer. Stored in the frame_related
field and printed as ‘/f’.

REG_USERVAR_P (x)
In a reg, nonzero if it corresponds to a variable present in the user’s source
code. Zero for temporaries generated internally by the compiler. Stored in the volatil field and printed as ‘/v’.
The same hard register may be used also for collecting the values of functions
called by this one, but REG_FUNCTION_VALUE_P is zero in this kind of use.

RTL_CONST_CALL_P (x)
In a call_insn indicates that the insn represents a call to a const function.
Stored in the unchanging field and printed as ‘/u’.
RTL_PURE_CALL_P (x)
In a call_insn indicates that the insn represents a call to a pure function. Stored in the return_val field and printed as '/i'.

RTL_CONST_OR_PURE_CALL_P (x)
In a call_insn, true if RTL_CONST_CALL_P or RTL_PURE_CALL_P is true.

RTL_LOOPING_CONST_OR_PURE_CALL_P (x)
In a call_insn indicates that the insn represents a possibly infinite looping call to a const or pure function. Stored in the call field and printed as '/c'. Only true if one of RTL_CONST_CALL_P or RTL_PURE_CALL_P is true.

RTL_FRAME_RELATED_P (x)
Nonzero in an insn, call_insn, jump_insn, barrier, or set which is part of a function prologue and sets the stack pointer, sets the frame pointer, or saves a register. This flag should also be set on an instruction that sets up a temporary register to use in place of the frame pointer. Stored in the frame_related field and printed as '/f'.

In particular, on RISC targets where there are limits on the sizes of immediate constants, it is sometimes impossible to reach the register save area directly from the stack pointer. In that case, a temporary register is used that is near enough to the register save area, and the Canonical Frame Address, i.e., DWARF2's logical frame pointer, register must (temporarily) be changed to be this temporary register. So, the instruction that sets this temporary register must be marked as RTX_FRAME_RELATED_P.

If the marked instruction is overly complex (defined in terms of what dwarf2out_frame_debug_expr can handle), you will also have to create a REG_FRAME_RELATED_EXPR note and attach it to the instruction. This note should contain a simple expression of the computation performed by this instruction, i.e., one that dwarf2out_frame_debug_expr can handle.

This flag is required for exception handling support on targets with RTL prologues.

SCHED_GROUP_P (x)
During instruction scheduling, in an insn, call_insn, jump_insn or jump_table_data, indicates that the previous insn must be scheduled together with this insn. This is used to ensure that certain groups of instructions will not be split up by the instruction scheduling pass, for example, use insns before a call_insn may not be separated from the call_insn. Stored in the in_struct field and printed as '/s'.

SET_IS_RETURN_P (x)
For a set, nonzero if it is for a return. Stored in the jump field and printed as '/j'.

SIBLING_CALL_P (x)
For a call_insn, nonzero if the insn is a sibling call. Stored in the jump field and printed as '/j'.
STRING_POOL_ADDRESS_P (x)

For a symbol_ref expression, nonzero if it addresses this function's string constant pool. Stored in the frame_related field and printed as ‘/f’.

SUBREG_PROMOTED_UNSIGNED_P (x)

Returns a value greater than zero for a subreg that has SUBREG_PROMOTED_VAR_P nonzero if the object being referenced is kept zero-extended, zero if it is kept sign-extended, and less than zero if it is extended some other way via the ptr_extend instruction. Stored in the unchanging field and volatil field, printed as ‘/u’ and ‘/v’. This macro may only be used to get the value it may not be used to change the value. Use SUBREG_PROMOTED_UNSIGNED_SET to change the value.

SUBREG_PROMOTED_UNSIGNED_SET (x)

Set the unchanging and volatil fields in a subreg to reflect zero, sign, or other extension. If volatil is zero, then unchanging as nonzero means zero extension and as zero means sign extension. If volatil is nonzero then some other type of extension was done via the ptr_extend instruction.

SUBREG_PROMOTED_VAR_P (x)

Nonzero in a subreg if it was made when accessing an object that was promoted to a wider mode in accord with the PROMOTED_MODE machine description macro (see Section 18.5 [Storage Layout], page 508). In this case, the mode of the subreg is the declared mode of the object and the mode of SUBREG_REG is the mode of the register that holds the object. Promoted variables are always either sign- or zero-extended to the wider mode on every assignment. Stored in the in_struct field and printed as ‘/s’.

SYMBOL_REF_USED (x)

In a symbol_ref, indicates that x has been used. This is normally only used to ensure that x is only declared external once. Stored in the used field.

SYMBOL_REF_WEAK (x)

In a symbol_ref, indicates that x has been declared weak. Stored in the return_val field and printed as ‘/i’.

SYMBOL_REF_FLAG (x)

In a symbol_ref, this is used as a flag for machine-specific purposes. Stored in the volatil field and printed as ‘/v’.

Most uses of SYMBOL_REF_FLAG are historic and may be subsumed by SYMBOL_REF_FLAGS. Certainly use of SYMBOL_REF_FLAGS is mandatory if the target requires more than one bit of storage.

These are the fields to which the above macros refer:

call

In a mem, 1 means that the memory reference will not trap.
In a call, 1 means that this pure or const call may possibly infinite loop.
In an RTL dump, this flag is represented as ‘/c’.
frame_related
In an insn or set expression, 1 means that it is part of a function prologue and sets the stack pointer, sets the frame pointer, saves a register, or sets up a temporary register to use in place of the frame pointer.
In reg expressions, 1 means that the register holds a pointer.
In mem expressions, 1 means that the memory reference holds a pointer.
In symbol_ref expressions, 1 means that the reference addresses this function’s string constant pool.
In an RTL dump, this flag is represented as ‘/f’.

in_struct
In reg expressions, it is 1 if the register has its entire life contained within the test expression of some loop.
In subreg expressions, 1 means that the subreg is accessing an object that has had its mode promoted from a wider mode.
In label_ref expressions, 1 means that the referenced label is outside the innermost loop containing the insn in which the label_ref was found.
In code_label expressions, it is 1 if the label may never be deleted. This is used for labels which are the target of non-local gotos. Such a label that would have been deleted is replaced with a note of type NOTE_INSN_DELETED_LABEL.
In an insn during dead-code elimination, 1 means that the insn is dead code.
In an insn or jump_insn during reorg for an insn in the delay slot of a branch, 1 means that this insn is from the target of the branch.
In an insn during instruction scheduling, 1 means that this insn must be scheduled as part of a group together with the previous insn.
In an RTL dump, this flag is represented as ‘/s’.

return_val
In reg expressions, 1 means the register contains the value to be returned by the current function. On machines that pass parameters in registers, the same register number may be used for parameters as well, but this flag is not set on such uses.
In symbol_ref expressions, 1 means the referenced symbol is weak.
In call expressions, 1 means the call is pure.
In an RTL dump, this flag is represented as ‘/i’.

jump
In a mem expression, 1 means we should keep the alias set for this mem unchanged when we access a component.
In a set, 1 means it is for a return.
In a call_insn, 1 means it is a sibling call.
In a jump_insn, 1 means it is a crossing jump.
In an RTL dump, this flag is represented as ‘/j’.

unchanging
In reg and mem expressions, 1 means that the value of the expression never changes.
In subreg expressions, it is 1 if the subreg references an unsigned object whose mode has been promoted to a wider mode.

In an insn or jump_insn in the delay slot of a branch instruction, 1 means an annulling branch should be used.

In a symbol_ref expression, 1 means that this symbol addresses something in the per-function constant pool.

In a call_insn 1 means that this instruction is a call to a const function.

In an RTL dump, this flag is represented as ‘/u’.

used

This flag is used directly (without an access macro) at the end of RTL generation for a function, to count the number of times an expression appears in insns. Expressions that appear more than once are copied, according to the rules for shared structure (see Section 14.22 [Sharing], page 326).

For a reg, it is used directly (without an access macro) by the leaf register renumbering code to ensure that each register is only renumbered once.

In a symbol_ref, it indicates that an external declaration for the symbol has already been written.

volatil

In a mem, asm_operands, or asm_input expression, it is 1 if the memory reference is volatile. Volatile memory references may not be deleted, reordered or combined.

In a symbol_ref expression, it is used for machine-specific purposes.

In a reg expression, it is 1 if the value is a user-level variable. 0 indicates an internal compiler temporary.

In an insn, 1 means the insn has been deleted.

In label_ref and reg_label expressions, 1 means a reference to a non-local label.

In prefetch expressions, 1 means that the containing insn is a scheduling barrier.

In an RTL dump, this flag is represented as ‘/v’.

14.6 Machine Modes

A machine mode describes a size of data object and the representation used for it. In the C code, machine modes are represented by an enumeration type, machine_mode, defined in machmode.def. Each RTL expression has room for a machine mode and so do certain kinds of tree expressions (declarations and types, to be precise).

In debugging dumps and machine descriptions, the machine mode of an RTL expression is written after the expression code with a colon to separate them. The letters ‘mode’ which appear at the end of each machine mode name are omitted. For example, (reg:SI 38) is a reg expression with machine mode SImode. If the mode is VOIDmode, it is not written at all.

Here is a table of machine modes. The term “byte” below refers to an object of BITS_PER_UNIT bits (see Section 18.5 [Storage Layout], page 508).

BInode “Bit” mode represents a single bit, for predicate registers.
<table>
<thead>
<tr>
<th>Mode</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>QImode</td>
<td>“Quarter-Integer” mode represents a single byte treated as an integer.</td>
</tr>
<tr>
<td>HImode</td>
<td>“Half-Integer” mode represents a two-byte integer.</td>
</tr>
<tr>
<td>PSImode</td>
<td>“Partial Single Integer” mode represents an integer which occupies four bytes but which doesn’t really use all four. On some machines, this is the right mode to use for pointers.</td>
</tr>
<tr>
<td>SImode</td>
<td>“Single Integer” mode represents a four-byte integer.</td>
</tr>
<tr>
<td>PDImode</td>
<td>“Partial Double Integer” mode represents an integer which occupies eight bytes but which doesn’t really use all eight. On some machines, this is the right mode to use for certain pointers.</td>
</tr>
<tr>
<td>DImode</td>
<td>“Double Integer” mode represents an eight-byte integer.</td>
</tr>
<tr>
<td>TImode</td>
<td>“Tetra Integer” (?) mode represents a sixteen-byte integer.</td>
</tr>
<tr>
<td>OImode</td>
<td>“Octa Integer” (?) mode represents a thirty-two-byte integer.</td>
</tr>
<tr>
<td>XImode</td>
<td>“Hexadeca Integer” (?) mode represents a sixty-four-byte integer.</td>
</tr>
<tr>
<td>QFmode</td>
<td>“Quarter-Floating” mode represents a quarter-precision (single byte) floating point number.</td>
</tr>
<tr>
<td>HFmode</td>
<td>“Half-Floating” mode represents a half-precision (two byte) floating point number.</td>
</tr>
<tr>
<td>TQFmode</td>
<td>“Three-Quarter-Floating” (?) mode represents a three-quarter-precision (three byte) floating point number.</td>
</tr>
<tr>
<td>SFmode</td>
<td>“Single Floating” mode represents a four byte floating point number. In the common case, of a processor with IEEE arithmetic and 8-bit bytes, this is a single-precision IEEE floating point number; it can also be used for double-precision (on processors with 16-bit bytes) and single-precision VAX and IBM types.</td>
</tr>
<tr>
<td>DFmode</td>
<td>“Double Floating” mode represents an eight byte floating point number. In the common case, of a processor with IEEE arithmetic and 8-bit bytes, this is a double-precision IEEE floating point number.</td>
</tr>
<tr>
<td>XFmode</td>
<td>“Extended Floating” mode represents an IEEE extended floating point number. This mode only has 80 meaningful bits (ten bytes). Some processors require such numbers to be padded to twelve bytes, others to sixteen; this mode is used for either.</td>
</tr>
<tr>
<td>SDmode</td>
<td>“Single Decimal Floating” mode represents a four byte decimal floating point number (as distinct from conventional binary floating point).</td>
</tr>
<tr>
<td>DDmode</td>
<td>“Double Decimal Floating” mode represents an eight byte decimal floating point number.</td>
</tr>
<tr>
<td>TDmode</td>
<td>“Tetra Decimal Floating” mode represents a sixteen byte decimal floating point number all 128 of whose bits are meaningful.</td>
</tr>
<tr>
<td>TFmode</td>
<td>“Tetra Floating” mode represents a sixteen byte floating point number all 128 of whose bits are meaningful. One common use is the IEEE quad-precision format.</td>
</tr>
</tbody>
</table>
QQmode  “Quarter-Fractional” mode represents a single byte treated as a signed fractional number. The default format is “s.7”.

HQmode  “Half-Fractional” mode represents a two-byte signed fractional number. The default format is “s.15”.

SQmode  “Single Fractional” mode represents a four-byte signed fractional number. The default format is “s.31”.

DQmode  “Double Fractional” mode represents an eight-byte signed fractional number. The default format is “s.63”.

TQmode  “Tetra Fractional” mode represents a sixteen-byte signed fractional number. The default format is “s.127”.

UQQmode “Unsigned Quarter-Fractional” mode represents a single byte treated as an unsigned fractional number. The default format is “.8”.

UHQmode “Unsigned Half-Fractional” mode represents a two-byte unsigned fractional number. The default format is “.16”.

USQmode “Unsigned Single Fractional” mode represents a four-byte unsigned fractional number. The default format is “.32”.

UDQmode “Unsigned Double Fractional” mode represents an eight-byte unsigned fractional number. The default format is “.64”.

UTQmode “Unsigned Tetra Fractional” mode represents a sixteen-byte unsigned fractional number. The default format is “.128”.

HAmode  “Half-Accumulator” mode represents a two-byte signed accumulator. The default format is “s8.7”.

SAmode  “Single Accumulator” mode represents a four-byte signed accumulator. The default format is “s16.15”.

DAmode  “Double Accumulator” mode represents an eight-byte signed accumulator. The default format is “s32.31”.

TAmode  “Tetra Accumulator” mode represents a sixteen-byte signed accumulator. The default format is “s64.63”.

UHAmode “Unsigned Half-Accumulator” mode represents a two-byte unsigned accumulator. The default format is “.8”.

USAmode “Unsigned Single Accumulator” mode represents a four-byte unsigned accumulator. The default format is “.16”.

UDAmode “Unsigned Double Accumulator” mode represents an eight-byte unsigned accumulator. The default format is “.32”.

UTAmode “Unsigned Tetra Accumulator” mode represents a sixteen-byte unsigned accumulator. The default format is “.64”.

CCmode  “Condition Code” mode represents the value of a condition code, which is a machine-specific set of bits used to represent the result of a comparison operation. Other machine-specific modes may also be used for the condition code. (see Section 18.15 [Condition Code], page 591).
BLKmode  “Block” mode represents values that are aggregates to which none of the other modes apply. In RTL, only memory references can have this mode, and only if they appear in string-move or vector instructions. On machines which have no such instructions, BLKmode will not appear in RTL.

VOIDmode  Void mode means the absence of a mode or an unspecified mode. For example, RTL expressions of code const_int have mode VOIDmode because they can be taken to have whatever mode the context requires. In debugging dumps of RTL, VOIDmode is expressed by the absence of any mode.

QCmode, HCmode, SCmode, DCmode, XCmode, TCmode  These modes stand for a complex number represented as a pair of floating point values. The floating point values are in QFmode, HFmode, SFmode, DFmode, XFmode, and TFmode, respectively.

CQImode, CHImode, CSImode, CDImode, CTImode, COImode, CPSImode  These modes stand for a complex number represented as a pair of integer values. The integer values are in QImode, HImode, SImode, DImode, TImode, OImode, and PSImode, respectively.

BND32mode BND64mode  These modes stand for bounds for pointer of 32 and 64 bit size respectively. Mode size is double pointer mode size.

The machine description defines Pmode as a C macro which expands into the machine mode used for addresses. Normally this is the mode whose size is BITS_PER_WORD, SImode on 32-bit machines.

The only modes which a machine description must support are QImode, and the modes corresponding to BITS_PER_WORD, FLOAT_TYPE_SIZE and DOUBLE_TYPE_SIZE. The compiler will attempt to use DImode for 8-byte structures and unions, but this can be prevented by overriding the definition of MAX_FIXED_MODE_SIZE. Alternatively, you can have the compiler use TImode for 16-byte structures and unions. Likewise, you can arrange for the C type short int to avoid using HImode.

Very few explicit references to machine modes remain in the compiler and these few references will soon be removed. Instead, the machine modes are divided into mode classes. These are represented by the enumeration type enum mode_class defined in ‘machmode.h’. The possible mode classes are:

MODE_INT  Integer modes. By default these are BImode, QImode, HImode, SImode, DImode, TImode, and OImode.

MODE_PARTIAL_INT  The “partial integer” modes, PQImode, PHImode, PSImode and PDImode.

MODE_FLOAT  Floating point modes. By default these are QFmode, HFmode, TQFmode, SFmode, DFmode, XFmode and TFmode.

MODE_DECIMAL_FLOAT  Decimal floating point modes. By default these are SDmode, DDmode and TDmode.
MODE_FRACT
Signed fractional modes. By default these are QQmode, HQmode, SQmode, DQmode and TQmode.

MODE_UFRACT
Unsigned fractional modes. By default these are UQQmode, UHQmode, USQmode, UDQmode and UTQmode.

MODE_ACCUM
Signed accumulator modes. By default these are HAmode, SAmode, DAmode and TAmode.

MODE_UACCUM
Unsigned accumulator modes. By default these are UHAmode, USAmode, UDAmode and UTAmode.

MODE_COMPLEX_INT
Complex integer modes. (These are not currently implemented).

MODE_COMPLEX_FLOAT
Complex floating point modes. By default these are QCmode, HCmode, SCmode, DCmode, XCmode, and TCmode.

MODE_CC
Modes representing condition code values. These are CCmode plus any CC_MODE modes listed in the 'machine-modes.def'. See Section 17.12 [Jump Patterns], page 450, also see Section 18.15 [Condition Code], page 591.

MODE_POINTER_BOUNDS
Pointer bounds modes. Used to represent values of pointer bounds type. Operations in these modes may be executed as NOPs depending on hardware features and environment setup.

MODE_OPAQUE
This is a mode class for modes that don’t want to provide operations other than register moves, memory moves, loads, stores, and unspecs. They have a size and precision and that’s all.

MODE_RANDOM
This is a catchall mode class for modes which don’t fit into the above classes. Currently VOIDmode and BLKmode are in MODE_RANDOM.

machmode.h also defines various wrapper classes that combine a machine_mode with a static assertion that a particular condition holds. The classes are:

scalar_int_mode
A mode that has class MODE_INT or MODE_PARTIAL_INT.

scalar_float_mode
A mode that has class MODE_FLOAT or MODE_DECIMAL_FLOAT.

scalar_mode
A mode that holds a single numerical value. In practice this means that the mode is a scalar_int_mode, is a scalar_float_mode, or has class MODE_FRACT, MODE_UFRACT, MODE_ACCUM, MODE_UACCUM or MODE_POINTER_BOUNDS.
complex_mode
A mode that has class MODE_COMPLEX_INT or MODE_COMPLEX_FLOAT.

fixed_size_mode
A mode whose size is known at compile time.

Named modes use the most constrained of the available wrapper classes, if one exists, otherwise they use machine_mode. For example, QImode is a scalar_int_mode, SFmode is a scalar_float_mode and BLKmode is a plain machine_mode. It is possible to refer to any mode as a raw machine_mode by adding the E_ prefix, where E stands for “enumeration”. For example, the raw machine_mode names of the modes just mentioned are E_QImode, E_SFmode and E_BLKmode respectively.

The wrapper classes implicitly convert to machine_mode and to any wrapper class that represents a more general condition; for example scalar_int_mode and scalar_float_mode both convert to scalar_mode and all three convert to fixed_size_mode. The classes act like machine_modes that accept only certain named modes.

’machmode.h’ also defines a template class opt_mode<T> that holds a T or nothing, where T can be either machine_mode or one of the wrapper classes above. The main operations on an opt_mode<T> x are as follows:

‘x.exists ()’
Return true if x holds a mode rather than nothing.

‘x.exists (&y)’
Return true if x holds a mode rather than nothing, storing the mode in y if so. y must be assignment-compatible with T.

‘x.require ()’
Assert that x holds a mode rather than nothing and return that mode.

‘x = y’
Set x to y, where y is a T or implicitly converts to a T.

The default constructor sets an opt_mode<T> to nothing. There is also a constructor that takes an initial value of type T.

It is possible to use the ‘is-a.h’ accessors on a machine_mode or machine mode wrapper x:

‘is_a <T> (x)’
Return true if x meets the conditions for wrapper class T.

‘is_a <T> (x, &y)’
Return true if x meets the conditions for wrapper class T, storing it in y if so. y must be assignment-compatible with T.

‘as_a <T> (x)’
Assert that x meets the conditions for wrapper class T and return it as a T.

‘dyn_cast <T> (x)’
Return an opt_mode<T> that holds x if x meets the conditions for wrapper class T and that holds nothing otherwise.

The purpose of these wrapper classes is to give stronger static type checking. For example, if a function takes a scalar_int_mode, a caller that has a general machine_mode must either check or assert that the code is indeed a scalar integer first, using one of the functions above.
The wrapper classes are normal C++ classes, with user-defined constructors. Sometimes it is useful to have a POD version of the same type, particularly if the type appears in a
union. The template class pod_mode<T> provides a POD version of wrapper class T. It is assignment-compatible with T and implicitly converts to both machine_mode and T.

Here are some C macros that relate to machine modes:

GET_MODE (x)
Returns the machine mode of the RTX x.

PUT_MODE (x, newmode)
Alters the machine mode of the RTX x to be newmode.

NUM_MACHINE_MODES
Stands for the number of machine modes available on the target machine. This is one greater than the largest numeric value of any machine mode.

GET_MODE_NAME (m)
Returns the name of mode m as a string.

GET_MODE_CLASS (m)
Returns the mode class of mode m.

GET_MODE_WIDER_MODE (m)
Returns the next wider natural mode. For example, the expression GET_MODE_WIDER_MODE (QImode) returns HImode.

GET_MODE_SIZE (m)
Returns the size in bytes of a datum of mode m.

GET_MODE_BITSIZE (m)
Returns the size in bits of a datum of mode m.

GET_MODE_IBIT (m)
Returns the number of integral bits of a datum of fixed-point mode m.

GET_MODE_FBIT (m)
Returns the number of fractional bits of a datum of fixed-point mode m.

GET_MODE_MASK (m)
Returns a bitmask containing 1 for all bits in a word that fit within mode m. This macro can only be used for modes whose bitsize is less than or equal to HOST_BITS_PER_INT.

GET_MODE_ALIGNMENT (m)
Returns the required alignment, in bits, for an object of mode m.

GET_MODE_UNIT_SIZE (m)
Returns the size in bytes of the subunits of a datum of mode m. This is the same as GET_MODE_SIZE except in the case of complex modes. For them, the unit size is the size of the real or imaginary part.

GET_MODE_NUNITS (m)
Returns the number of units contained in a mode, i.e., GET_MODE_SIZE divided by GET_MODE_UNIT_SIZE.
GET_CLASS_NARROWEST_MODE (c)

Returns the narrowest mode in mode class c.

The following 3 variables are defined on every target. They can be used to allocate buffers that are guaranteed to be large enough to hold any value that can be represented on the target. The first two can be overridden by defining them in the target’s mode.def file, however, the value must be a constant that can determined very early in the compilation process. The third symbol cannot be overridden.

BITS_PER_UNIT
The number of bits in an addressable storage unit (byte). If you do not define this, the default is 8.

MAX_BITSIZE_MODE_ANY_INT
The maximum bitsize of any mode that is used in integer math. This should be overridden by the target if it uses large integers as containers for larger vectors but otherwise never uses the contents to compute integer values.

MAX_BITSIZE_MODE_ANY_MODE
The bitsize of the largest mode on the target. The default value is the largest mode size given in the mode definition file, which is always correct for targets whose modes have a fixed size. Targets that might increase the size of a mode beyond this default should define MAX_BITSIZE_MODE_ANY_MODE to the actual upper limit in ‘machine-modes.def’.

The global variables byte_mode and word_mode contain modes whose classes are MODE_INT and whose bitsizes are either BITS_PER_UNIT or BITS_PER_WORD, respectively. On 32-bit machines, these are QImode and SImode, respectively.

14.7 Constant Expression Types

The simplest RTL expressions are those that represent constant values.

(const_int i)

This type of expression represents the integer value i. i is customarily accessed with the macro INTVAL as in INTVAL (exp), which is equivalent to XWINT (exp, 0).

Constants generated for modes with fewer bits than in HOST_WIDE_INT must be sign extended to full width (e.g., with gen_int_mode). For constants for modes with more bits than in HOST_WIDE_INT the implied high order bits of that constant are copies of the top bit. Note however that values are neither inherently signed nor inherently unsigned; where necessary, signedness is determined by the rtl operation instead.

There is only one expression object for the integer value zero; it is the value of the variable const0_rtx. Likewise, the only expression for integer value one is found in const1_rtx, the only expression for integer value two is found in const2_rtx, and the only expression for integer value negative one is found in constm1_rtx. Any attempt to create an expression of code const_int and value zero, one, two or negative one will return const0_rtx, const1_rtx, const2_rtx or constm1_rtx as appropriate.
Similarly, there is only one object for the integer whose value is STORE_FLAG_VALUE. It is found in const_true_rtx. If STORE_FLAG_VALUE is one, const_true_rtx and const1_rtx will point to the same object. If STORE_FLAG_VALUE is -1, const_true_rtx and constm1_rtx will point to the same object.

(const_double:m i0 i1 ...)

This represents either a floating-point constant of mode m or (on older ports that do not define TARGET_SUPPORTS_WIDE_INT) an integer constant too large to fit into HOST_BITS_PER_WIDE_INT bits but small enough to fit within twice that number of bits. In the latter case, m will be VOIDmode. For integral values constants for modes with more bits than twice the number in HOST_WIDE_INT the implied high order bits of that constant are copies of the top bit of CONST_DOUBLE_HIGH. Note however that integral values are neither inherently signed nor inherently unsigned; where necessary, signedness is determined by the rtl operation instead.

On more modern ports, CONST_DOUBLE only represents floating point values. New ports define TARGET_SUPPORTS_WIDE_INT to make this designation.

If m is VOIDmode, the bits of the value are stored in i0 and i1. i0 is customarily accessed with the macro CONST_DOUBLE_LOW and i1 with CONST_DOUBLE_HIGH.

If the constant is floating point (regardless of its precision), then the number of integers used to store the value depends on the size of REAL_VALUE_TYPE (see Section 18.22 [Floating Point], page 649). The integers represent a floating point number, but not precisely in the target machine’s or host machine’s floating point format. To convert them to the precise bit pattern used by the target machine, use the macro REAL_VALUE_TO_TARGET_DOUBLE and friends (see Section 18.20.2 [Data Output], page 618).

The host dependency for the number of integers used to store a double value makes it problematic for machine descriptions to use expressions of code const_double and therefore a syntactic alias has been provided:

  (const_double_zero:m)

standing for:

  (const_double:m 0 0 ...)

for matching the floating-point value zero, possibly the only useful one.

(const_wide_int:m numits elt0 ...)

This contains an array of HOST_WIDE_INTs that is large enough to hold any constant that can be represented on the target. This form of rtl is only used on targets that define TARGET_SUPPORTS_WIDE_INT to be nonzero and then CONST_DOUBLEs are only used to hold floating-point values. If the target leaves TARGET_SUPPORTS_WIDE_INT defined as 0, CONST_WIDE_INTs are not used and CONST_DOUBLEs are as they were before.

The values are stored in a compressed format. The higher-order 0s or -1s are not represented if they are just the logical sign extension of the number that is represented.

CONST_WIDE_INT_VEC (code)

Returns the entire array of HOST_WIDE_INTs that are used to store the value. This macro should be rarely used.
CONST_WIDE_INT_NUMITS (code)
The number of HOST_WIDE_INTs used to represent the number. Note that this
generally is smaller than the number of HOST_WIDE_INTs implied by the mode
size.

CONST_WIDE_INT_ELT (code, i)
Returns the ith element of the array. Element 0 is contains the low order bits
of the constant.

(const_fixed:m ...)
Represents a fixed-point constant of mode m. The operand is a data structure
of type struct fixed_value and is accessed with the macro CONST_FIXED_ VALUE. The high part of data is accessed with CONST_FIXED_VALUE_HIGH; the
low part is accessed with CONST_FIXED_VALUE_LOW.

(const_poly_int:m [c0 c1 ...])
Represents a poly_int-style polynomial integer with coefficients c0, c1, ....
The coefficients are wide_int-based integers rather than rtxes. CONST_POLY_ INT_COEFFS gives the values of individual coefficients (which is mostly only
useful in low-level routines) and const_poly_int_value gives the full poly_ int value.

(const_vector:m [x0 x1 ...])
Represents a vector constant. The values in square brackets are elements of
the vector, which are always const_int, const_wide_int, const_double or
const_fixed expressions.

Each vector constant v is treated as a specific instance of an arbitrary-length
sequence that itself contains 'CONST_VECTOR_NPATTERNS (v)' interleaved pat-
terns. Each pattern has the form:
{ base0, base1, base1 + step, base1 + step * 2, ... }
The first three elements in each pattern are enough to determine the values of
the other elements. However, if all steps are zero, only the first two elements are
needed. If in addition each base1 is equal to the corresponding base0, only the
first element in each pattern is needed. The number of determining elements
per pattern is given by 'CONST_VECTOR_NELTS_PER_PATTERN (v)'.

For example, the constant:
{ 0, 1, 2, 6, 3, 8, 4, 10, 5, 12, 6, 14, 7, 16, 8, 18 }
is interpreted as an interleaving of the sequences:
{ 0, 2, 3, 4, 5, 6, 7, 8 }
{ 1, 6, 8, 10, 12, 14, 16, 18 }
where the sequences are represented by the following patterns:
base0 == 0, base1 == 2, step == 1
base0 == 1, base1 == 6, step == 2

In this case:
CONST_VECTOR_NPATTERNS (v) == 2
CONST_VECTOR_NELTS_PER_PATTERN (v) == 3
Thus the first 6 elements ('{ 0, 1, 2, 6, 3, 8 }') are enough to determine the
whole sequence; we refer to them as the “encoded” elements. They are the
only elements present in the square brackets for variable-length `const_vectors`
(i.e. for `const_vectors` whose mode `m` has a variable number of elements).
However, as a convenience to code that needs to handle both `const_vectors`
and `parallels`, all elements are present in the square brackets for fixed-length
`const_vectors`; the encoding scheme simply reduces the amount of work in-
volved in processing constants that follow a regular pattern.
Sometimes this scheme can create two possible encodings of the same vector.
For example `{ 0, 1 }` could be seen as two patterns with one element each or
one pattern with two elements (`base0` and `base1`). The canonical encoding is
always the one with the fewest patterns or (if both encodings have the same
number of patterns) the one with the fewest encoded elements.

`const_vector_encoding_nelts (v)` gives the total number of encoded
elements in `v`, which is 6 in the example above. `CONST_VECTOR_ENCODED_ELTI (v, i)`
accesses the value of encoded element `i`.

`CONST_VECTOR_DUPLICATE_P (v)` is true if `v` simply contains repeated in-
stances of `CONST_VECTOR_NPATTERNS (v)` values. This is a shorthand for test-
ing `CONST_VECTOR_NELTS_PER_PATTERN (v) == 1`.

`CONST_VECTOR_STEPPED_P (v)` is true if at least one pattern in `v` has a nonzero
step. This is a shorthand for testing `CONST_VECTOR_NELTS_PER_PATTERN (v) == 3`.

`CONST_VECTOR_NUNITS (v)` gives the total number of elements in `v`; it is a
shorthand for getting the number of units in `GET_MODE (v)`.
The utility function `const_vector_elt` gives the value of an arbitrary element
as an `rtx`. `const_vector_int_elt` gives the same value as a `wide_int`.

(const_string str)
Represents a constant string with value `str`. Currently this is used only for insn
attributes (see Section 17.19 [Insn Attributes], page 467) since constant strings
in C are placed in memory.

(symbol_ref:mode symbol)
Represents the value of an assembler label for data. `symbol` is a string that
describes the name of the assembler label. If it starts with a `*`, the label is
the rest of `symbol` not including the `*`. Otherwise, the label is `symbol`, usually
prefixed with `__`.
The `symbol_ref` contains a mode, which is usually `Pmode`. Usually that is the
only mode for which a symbol is directly valid.

(label_ref:mode label)
Represents the value of an assembler label for code. It contains one operand,
an expression, which must be a `code_label` or a `note` of type `NOTE_INSN_`
DELETED_LABEL that appears in the instruction sequence to identify the place
where the label should go.
The reason for using a distinct expression type for code label references is so
that jump optimization can distinguish them.
The `label_ref` contains a mode, which is usually `Pmode`. Usually that is the
only mode for which a label is directly valid.
(const:m exp)
Represents a constant that is the result of an assembly-time arithmetic computation. The operand, exp, contains only const_int, symbol_ref, label_ref or unspec expressions, combined with plus and minus. Any such unspecs are target-specific and typically represent some form of relocation operator. m should be a valid address mode.

(high:m exp)
Represents the high-order bits of exp. The number of bits is machine-dependent and is normally the number of bits specified in an instruction that initializes the high order bits of a register. It is used with lo_sum to represent the typical two-instruction sequence used in RISC machines to reference large immediate values and/or link-time constants such as global memory addresses. In the latter case, m is Pmode and exp is usually a constant expression involving symbol_ref.

The macro CONST0_RTX (mode) refers to an expression with value 0 in mode mode. If mode mode is of mode class MODE_INT, it returns const0_rtx. If mode mode is of mode class MODE_FLOAT, it returns a CONST_DOUBLE expression in mode mode. Otherwise, it returns a CONST_VECTOR expression in mode mode. Similarly, the macro CONST1_RTX (mode) refers to an expression with value 1 in mode mode and similarly for CONST2_RTX. The CONST1_RTX and CONST2_RTX macros are undefined for vector modes.

14.8 Registers and Memory
Here are the RTL expression types for describing access to machine registers and to main memory.

(reg:m n) For small values of the integer n (those that are less than FIRST_PSEUDO_REGISTER), this stands for a reference to machine register number n: a hard register. For larger values of n, it stands for a temporary value or pseudo register. The compiler’s strategy is to generate code assuming an unlimited number of such pseudo registers, and later convert them into hard registers or into memory references.

m is the machine mode of the reference. It is necessary because machines can generally refer to each register in more than one mode. For example, a register may contain a full word but there may be instructions to refer to it as a half word or as a single byte, as well as instructions to refer to it as a floating point number of various precisions.

Even for a register that the machine can access in only one mode, the mode must always be specified.

The symbol FIRST_PSEUDO_REGISTER is defined by the machine description, since the number of hard registers on the machine is an invariant characteristic of the machine. Note, however, that not all of the machine registers must be general registers. All the machine registers that can be used for storage of data are given hard register numbers, even those that can be used only in certain instructions or can hold only certain types of data.

A hard register may be accessed in various modes throughout one function, but each pseudo register is given a natural mode and is accessed only in that
mode. When it is necessary to describe an access to a pseudo register using a nonnatural mode, a `subreg` expression is used.

A `reg` expression with a machine mode that specifies more than one word of data may actually stand for several consecutive registers. If in addition the register number specifies a hardware register, then it actually represents several consecutive hardware registers starting with the specified one.

Each pseudo register number used in a function’s RTL code is represented by a unique `reg` expression.

Some pseudo register numbers, those within the range of `FIRST_VIRTUAL_REGISTER` to `LAST_VIRTUAL_REGISTER` only appear during the RTL generation phase and are eliminated before the optimization phases. These represent locations in the stack frame that cannot be determined until RTL generation for the function has been completed. The following virtual register numbers are defined:

**VIRTUAL_INCOMING_ARGS_REGNUM**

This points to the first word of the incoming arguments passed on the stack. Normally these arguments are placed there by the caller, but the callee may have pushed some arguments that were previously passed in registers.

When RTL generation is complete, this virtual register is replaced by the sum of the register given by `ARG_POINTER_REGNUM` and the value of `FIRST_PARM_OFFSET`.

**VIRTUAL_STACK_VARS_REGNUM**

If `FRAME_GROWS_DOWNWARD` is defined to a nonzero value, this points to immediately above the first variable on the stack. Otherwise, it points to the first variable on the stack.

`VIRTUAL_STACK_VARS_REGNUM` is replaced with the sum of the register given by `FRAME_POINTER_REGNUM` and the value `TARGET_STARTING_FRAME_OFFSET`.

**VIRTUAL_STACK_DYNAMIC_REGNUM**

This points to the location of dynamically allocated memory on the stack immediately after the stack pointer has been adjusted by the amount of memory desired.

This virtual register is replaced by the sum of the register given by `STACK_POINTER_REGNUM` and the value `STACK_DYNAMIC_OFFSET`.

**VIRTUAL_OUTGOING_ARGS_REGNUM**

This points to the location in the stack at which outgoing arguments should be written when the stack is pre-pushed (arguments pushed using push insns should always use `STACK_POINTER_REGNUM`).

This virtual register is replaced by the sum of the register given by `STACK_POINTER_REGNUM` and the value `STACK_POINTER_OFFSET`. 
(subreg:m1 reg:m2 bytenum)

subreg expressions are used to refer to a register in a machine mode other than its natural one, or to refer to one register of a multi-part reg that actually refers to several registers.

Each pseudo register has a natural mode. If it is necessary to operate on it in a different mode, the register must be enclosed in a subreg.

There are currently three supported types for the first operand of a subreg:

- **pseudo registers** This is the most common case. Most subregs have pseudo regs as their first operand.

- **mem subregs** of mem were common in earlier versions of GCC and are still supported. During the reload pass these are replaced by plain mems. On machines that do not do instruction scheduling, use of subregs of mem are still used, but this is no longer recommended. Such subregs are considered to be register_operands rather than memory_operands before and during reload. Because of this, the scheduling passes cannot properly schedule instructions with subregs of mem, so for machines that do scheduling, subregs of mem should never be used. To support this, the combine and recog passes have explicit code to inhibit the creation of subregs of mem when INSN_SCHEDULING is defined.

The use of subregs of mem after the reload pass is an area that is not well understood and should be avoided. There is still some code in the compiler to support this, but this code has possibly rotted. This use of subregs is discouraged and will most likely not be supported in the future.

- **hard registers** It is seldom necessary to wrap hard registers in subregs; such registers would normally reduce to a single reg rtx. This use of subregs is discouraged and may not be supported in the future.

subregs of subregs are not supported. Using simplify_gen_subreg is the recommended way to avoid this problem.

subregs come in two distinct flavors, each having its own usage and rules:

**Paradoxical subregs**

When \( m1 \) is strictly wider than \( m2 \), the subreg expression is called paradoxical. The canonical test for this class of subreg is:

\[
\text{paradoxical_subreg_p (}m1, m2\text{)}
\]

Paradoxical subregs can be used as both lvalues and rvalues. When used as an lvalue, the low-order bits of the source value are stored in reg and the high-order bits are discarded. When used as an rvalue, the low-order bits of the subreg are taken from reg while the high-order bits may or may not be defined.

The high-order bits of rvalues are defined in the following circumstances:

- **subregs of mem** When \( m2 \) is smaller than a word, the macro LOAD_EXTEND_OP, can control how the high-order bits are defined.
• subreg of regs The upper bits are defined when SUBREG_PROMOTED_VAR_P is true. SUBREG_PROMOTED_UNSIGNED_P describes what the upper bits hold. Such subregs usually represent local variables, register variables and parameter pseudo variables that have been promoted to a wider mode.

bytenum is always zero for a paradoxical subreg, even on big-endian targets.

For example, the paradoxical subreg:

(set (subreg:SI (reg:HI x) 0) y)

stores the lower 2 bytes of y in x and discards the upper 2 bytes. A subsequent:

(set z (subreg:SI (reg:HI x) 0))

would set the lower two bytes of z to y and set the upper two bytes to an unknown value assuming SUBREG_PROMOTED_VAR_P is false.

Normal subregs

When \( m1 \) is at least as narrow as \( m2 \) the subreg expression is called normal.

Normal subregs restrict consideration to certain bits of reg. For this purpose, reg is divided into individually-addressable blocks in which each block has:

\[
\text{REGMODE_NATURAL_SIZE (m2)}
\]

bytes. Usually the value is \text{UNITS_PER_WORD}; that is, most targets usually treat each word of a register as being independently addressable.

There are two types of normal subreg. If \( m1 \) is known to be no bigger than a block, the subreg refers to the least-significant part (or lowpart) of one block of reg. If \( m1 \) is known to be larger than a block, the subreg refers to two or more complete blocks.

When used as an lvalue, subreg is a block-based accessor. Storing to a subreg modifies all the blocks of reg that overlap the subreg, but it leaves the other blocks of reg alone.

When storing to a normal subreg that is smaller than a block, the other bits of the referenced block are usually left in an undefined state. This laxity makes it easier to generate efficient code for such instructions. To represent an instruction that preserves all the bits outside of those in the subreg, use strict_low_part or zero_extract around the subreg.

bytenum must identify the offset of the first byte of the subreg from the start of reg, assuming that reg is laid out in memory order. The memory order of bytes is defined by two target macros, WORDS_BIG_ENDIAN and BYTES_BIG_ENDIAN:

• WORDS_BIG_ENDIAN, if set to 1, says that byte number zero is part of the most significant word; otherwise, it is part of the least significant word.
• **BYTES_BIG_ENDIAN**, if set to 1, says that byte number zero is the most significant byte within a word; otherwise, it is the least significant byte within a word.

On a few targets, **FLOAT_WORDS_BIG_ENDIAN** disagrees with **WORDS_BIG_ENDIAN**. However, most parts of the compiler treat floating point values as if they had the same endianness as integer values. This works because they handle them solely as a collection of integer values, with no particular numerical value. Only real.c and the runtime libraries care about **FLOAT_WORDS_BIG_ENDIAN**.

Thus,

\[(\text{subreg:HI (reg:SI } x) 2)\]

on a **BYTES_BIG_ENDIAN**, \(\text{`UNITS_PER_WORD == 4' target is the same as}\)

\[(\text{subreg:HI (reg:SI } x) 0)\]

on a little-endian, \(\text{`UNITS_PER_WORD == 4' target. Both subregs access the lower two bytes of register x.}\)

Note that the byte offset is a polynomial integer; it may not be a compile-time constant on targets with variable-sized modes. However, the restrictions above mean that there are only a certain set of acceptable offsets for a given combination of \(m_1\) and \(m_2\). The compiler can always tell which blocks a valid subreg occupies, and whether the subreg is a lowpart of a block.

**A MODE_PARTIAL_INT** mode behaves as if it were as wide as the corresponding **MODE_INT** mode, except that it has a number of undefined bits, which are determined by the precision of the mode.

For example, on a little-endian target which defines **PSImode** to have a precision of 20 bits:

\[(\text{subreg:PSI (reg:SI 0) 0})\]

accesses the low 20 bits of \(\text{`(reg:SI 0)'}.\)

Continuing with a **PSImode** precision of 20 bits, if we assume \(\text{`REGMODE_NATURAL_SIZE (DIMode) <= 4', then the following two subregs:}\)

\[(\text{subreg:PSI (reg:DI 0) 0})\]
\[(\text{subreg:PSI (reg:DI 0) 4})\]

represent accesses to the low 20 bits of the two halves of \(\text{`(reg:DI 0)'}.\)

If \(\text{`REGMODE_NATURAL_SIZE (PSImode) <= 2'}\) then these two subregs:

\[(\text{subreg:HI (reg:PSI 0) 0})\]
\[(\text{subreg:HI (reg:PSI 0) 2})\]

represent independent 2-byte accesses that together span the whole of \(\text{`(reg:PSI 0)'}.\) Storing to the first subreg does not affect the value of the second, and vice versa, so the assignment:

\[(\text{set (subreg:HI (reg:PSI 0) 0) (reg:HI 4)})\]

sets the low 16 bits of \(\text{`(reg:PSI 0)' to `(reg:HI 4)', and the high 4 defined bits of `(reg:PSI 0)’ retain their original value. The behavior here is the same as for normal subregs, when there are no MODE_PARTIAL_INT modes involved.
The rules above apply to both pseudo regs and hard regs. If the semantics are not correct for particular combinations of \( m1, m2 \) and hard reg, the target-specific code must ensure that those combinations are never used. For example:

\[ \text{TARGET\_CAN\_CHANGE\_MODE\_CLASS} (m2, m1, \text{class}) \]

must be false for every class class that includes reg.

GCC must be able to determine at compile time whether a subreg is paradoxical, whether it occupies a whole number of blocks, or whether it is a lowpart of a block. This means that certain combinations of variable-sized mode are not permitted. For example, if \( m2 \) holds \( n \) SI values, where \( n \) is greater than zero, it is not possible to form a DI subreg of it; such a subreg would be paradoxical when \( n \) is 1 but not when \( n \) is greater than 1.

The first operand of a subreg expression is customarily accessed with the SUBREG_REG macro and the second operand is customarily accessed with the SUBREG_BYTE macro.

It has been several years since a platform in which \( \text{BYTES\_BIG\__ENDIAN} \) not equal to \( \text{WORDS\_BIG\__ENDIAN} \) has been tested. Anyone wishing to support such a platform in the future may be confronted with code rot.

(\( \text{scratch:m} \))

This represents a scratch register that will be required for the execution of a single instruction and not used subsequently. It is converted into a reg by either the local register allocator or the reload pass.

\( \text{scratch} \) is usually present inside a clobber operation (see Section 14.15 [Side Effects], page 300).

On some machines, the condition code register is given a register number and a reg is used. Other machines store condition codes in general registers; in such cases a pseudo register should be used.

Some machines, such as the SPARC and RS/6000, have two sets of arithmetic instructions, one that sets and one that does not set the condition code. This is best handled by normally generating the instruction that does not set the condition code, and making a pattern that both performs the arithmetic and sets the condition code register. For examples, search for ‘addcc’ and ‘andcc’ in ‘sparc.md’.

(\( \text{pc} \))

This represents the machine’s program counter. It has no operands and may not have a machine mode. (\( \text{pc} \)) may be validly used only in certain specific contexts in jump instructions.

There is only one expression object of code \( \text{pc} \); it is the value of the variable \( \text{pc\_rtx} \). Any attempt to create an expression of code \( \text{pc} \) will return \( \text{pc\_rtx} \).

All instructions that do not jump alter the program counter implicitly by incrementing it, but there is no need to mention this in the RTL.

(\( \text{mem:m addr alias} \))

This RTX represents a reference to main memory at an address represented by the expression \( \text{addr} \). \( m \) specifies how large a unit of memory is accessed. \( \text{alias} \) specifies an alias set for the reference. In general two items are in different alias sets if they cannot reference the same memory address.
The construct `(mem:BLK (scratch))` is considered to alias all other memories. Thus it may be used as a memory barrier in epilogue stack deallocation patterns.

`(concat rtx rtx)`
This RTX represents the concatenation of two other RTXs. This is used for complex values. It should only appear in the RTL attached to declarations and during RTL generation. It should not appear in the ordinary insn chain.

`(concatn [rtx ...])`
This RTX represents the concatenation of all the rtx to make a single value. Like `concat`, this should only appear in declarations, and not in the insn chain.

### 14.9 RTL Expressions for Arithmetic

Unless otherwise specified, all the operands of arithmetic expressions must be valid for mode `m`. An operand is valid for mode `m` if it has mode `m`, or if it is a `const_int` or `const_double` and `m` is a mode of class `MODE_INT`.

For commutative binary operations, constants should be placed in the second operand.

`(plus:m x y)`
`(ss_plus:m x y)`
`(us_plus:m x y)`
These three expressions all represent the sum of the values represented by `x` and `y` carried out in machine mode `m`. They differ in their behavior on overflow of integer modes. `plus` wraps round modulo the width of `m`; `ss_plus` saturates at the maximum signed value representable in `m`; `us_plus` saturates at the maximum unsigned value.

`(lo_sum:m x y)`
This expression represents the sum of `x` and the low-order bits of `y`. It is used with `high` (see Section 14.7 [Constants], page 282) to represent the typical two-instruction sequence used in RISC machines to reference large immediate values and/or link-time constants such as global memory addresses. In the latter case, `m` is `Pmode` and `y` is usually a constant expression involving `symbol_ref`. The number of low order bits is machine-dependent but is normally the number of bits in mode `m` minus the number of bits set by `high`.

`(minus:m x y)`
`(ss_minus:m x y)`
`(us_minus:m x y)`
These three expressions represent the result of subtracting `y` from `x`, carried out in mode `M`. Behavior on overflow is the same as for the three variants of `plus` (see above).

`(compare:m x y)`
Represents the result of subtracting `y` from `x` for purposes of comparison. The result is computed without overflow, as if with infinite precision. Of course, machines cannot really subtract with infinite precision. However, they can pretend to do so when only the sign of the result will be used, which is the case when the result is stored in the condition code. And that is the only
way this kind of expression may validly be used: as a value to be stored in the condition codes, in a register. See Section 14.10 [Comparisons], page 296.

The mode $m$ is not related to the modes of $x$ and $y$, but instead is the mode of the condition code value. It is some mode in class MODE_CC, often CCmode. See Section 18.15 [Condition Code], page 591. If $m$ is CCmode, the operation returns sufficient information (in an unspecified format) so that any comparison operator can be applied to the result of the COMPARE operation. For other modes in class MODE_CC, the operation only returns a subset of this information.

Normally, $x$ and $y$ must have the same mode. Otherwise, compare is valid only if the mode of $x$ is in class MODE_INT and $y$ is a const_int or const_double with mode VOIDmode. The mode of $x$ determines what mode the comparison is to be done in; thus it must not be VOIDmode.

If one of the operands is a constant, it should be placed in the second operand and the comparison code adjusted as appropriate.

A compare specifying two VOIDmode constants is not valid since there is no way to know in what mode the comparison is to be performed; the comparison must either be folded during the compilation or the first operand must be loaded into a register while its mode is still known.

\[
\begin{align*}
\text{(neg}: & m \ x) \\
\text{(ss_neg}: & m \ x) \\
\text{(us_neg}: & m \ x)
\end{align*}
\]

These two expressions represent the negation (subtraction from zero) of the value represented by $x$, carried out in mode $m$. They differ in the behavior on overflow of integer modes. In the case of neg, the negation of the operand may be a number not representable in mode $m$, in which case it is truncated to $m$. ss_neg and us_neg ensure that an out-of-bounds result saturates to the maximum or minimum signed or unsigned value.

\[
\begin{align*}
\text{(mult}: & m \ x \ y) \\
\text{(ss_mult}: & m \ x \ y) \\
\text{(us_mult}: & m \ x \ y)
\end{align*}
\]

Represents the signed product of the values represented by $x$ and $y$ carried out in machine mode $m$. ss_mult and us_mult ensure that an out-of-bounds result saturates to the maximum or minimum signed or unsigned value.

Some machines support a multiplication that generates a product wider than the operands. Write the pattern for this as

\[
\text{(mult}: m \ (\text{sign_extend}: m \ x) \ (\text{sign_extend}: m \ y))
\]

where $m$ is wider than the modes of $x$ and $y$, which need not be the same.

For unsigned widening multiplication, use the same idiom, but with zero_extend instead of sign_extend.

\[
\begin{align*}
\text{(fma}: & m \ x \ y \ z)
\end{align*}
\]

Represents the fma, fmaf, and fmal builtin functions, which compute `$x \times y + z$’ without doing an intermediate rounding step.
\((\text{div}:m \ x \ y)\)

\((\text{ss\_div}:m \ x \ y)\)

Represents the quotient in signed division of \(x\) by \(y\), carried out in machine mode \(m\). If \(m\) is a floating point mode, it represents the exact quotient; otherwise, the integerized quotient. \(\text{ss\_div}\) ensures that an out-of-bounds result saturates to the maximum or minimum signed value.

Some machines have division instructions in which the operands and quotient widths are not all the same; you should represent such instructions using \(\text{truncate}\) and \(\text{sign\_extend}\) as in,

\((\text{truncate}:m1 \ (\text{div}:m2 \ x \ (\text{sign\_extend}:m2 \ y)))\)

\((\text{udiv}:m \ x \ y)\)

\((\text{us\_div}:m \ x \ y)\)

Like \(\text{div}\) but represents unsigned division. \(\text{us\_div}\) ensures that an out-of-bounds result saturates to the maximum or minimum unsigned value.

\((\text{mod}:m \ x \ y)\)

\((\text{umod}:m \ x \ y)\)

Like \(\text{div}\) and \(\text{udiv}\) but represent the remainder instead of the quotient.

\((\text{smin}:m \ x \ y)\)

\((\text{smax}:m \ x \ y)\)

Represents the smaller (for \(\text{smin}\)) or larger (for \(\text{smax}\)) of \(x\) and \(y\), interpreted as signed values in mode \(m\). When used with floating point, if both operands are zeros, or if either operand is NaN, then it is unspecified which of the two operands is returned as the result.

\((\text{umin}:m \ x \ y)\)

\((\text{umax}:m \ x \ y)\)

Like \(\text{smin}\) and \(\text{smax}\), but the values are interpreted as unsigned integers.

\((\text{not}:m \ x)\)

Represents the bitwise complement of the value represented by \(x\), carried out in mode \(m\), which must be a fixed-point machine mode.

\((\text{and}:m \ x \ y)\)

Represents the bitwise logical-and of the values represented by \(x\) and \(y\), carried out in machine mode \(m\), which must be a fixed-point machine mode.

\((\text{ior}:m \ x \ y)\)

Represents the bitwise inclusive-or of the values represented by \(x\) and \(y\), carried out in machine mode \(m\), which must be a fixed-point mode.

\((\text{xor}:m \ x \ y)\)

Represents the bitwise exclusive-or of the values represented by \(x\) and \(y\), carried out in machine mode \(m\), which must be a fixed-point mode.

\((\text{ashift}:m \ x \ c)\)

\((\text{ss\_ashift}:m \ x \ c)\)

\((\text{us\_ashift}:m \ x \ c)\)

These three expressions represent the result of arithmetically shifting \(x\) left by \(c\) places. They differ in their behavior on overflow of integer modes. An \(\text{ashift}\) operation is a plain shift with no special behavior in case of a change in the
sign bit; \texttt{ss\_ashift} and \texttt{us\_ashift} saturates to the minimum or maximum representable value if any of the bits shifted out differs from the final sign bit. \( x \) have mode \( m \), a fixed-point machine mode. \( c \) be a fixed-point mode or be a constant with mode \texttt{VOIDmode}; which mode is determined by the mode called for in the machine description entry for the left-shift instruction. For example, on the VAX, the mode of \( c \) is \texttt{QIpmode} regardless of \( m \).

\[(\text{lshiftrt}: m \times c)\]  
\[(\text{ashiftrt}: m \times c)\]

Like \texttt{ashift} but for right shift. Unlike the case for left shift, these two operations are distinct.

\[(\text{rotate}: m \times c)\]  
\[(\text{rotatert}: m \times c)\]

Similar but represent left and right rotate. If \( c \) is a constant, use \texttt{rotate}.

\[(\text{abs}: m \times x)\]

\[(\text{ss\_abs}: m \times x)\]

Represents the absolute value of \( x \), computed in mode \( m \). \texttt{ss\_abs} ensures that an out-of-bounds result saturates to the maximum signed value.

\[(\text{sqrt}: m \times x)\]

Represents the square root of \( x \), computed in mode \( m \). Most often \( m \) will be a floating point mode.

\[(\text{ffs}: m \times x)\]

Represents one plus the index of the least significant 1-bit in \( x \), represented as an integer of mode \( m \). (The value is zero if \( x \) is zero.) The mode of \( x \) must be \( m \) or \texttt{VOIDmode}.

\[(\text{clrsb}: m \times x)\]

Represents the number of redundant leading sign bits in \( x \), represented as an integer of mode \( m \), starting at the most significant bit position. This is one less than the number of leading sign bits (either 0 or 1), with no special cases. The mode of \( x \) must be \( m \) or \texttt{VOIDmode}.

\[(\text{clz}: m \times x)\]

Represents the number of leading 0-bits in \( x \), represented as an integer of mode \( m \), starting at the most significant bit position. If \( x \) is zero, the value is determined by \texttt{CLZ\_DEFINED\_VALUE\_AT\_ZERO} (see Section 18.31 [Misc], page 661). Note that this is one of the few expressions that is not invariant under widening. The mode of \( x \) must be \( m \) or \texttt{VOIDmode}.

\[(\text{ctz}: m \times x)\]

Represents the number of trailing 0-bits in \( x \), represented as an integer of mode \( m \), starting at the least significant bit position. If \( x \) is zero, the value is determined by \texttt{CTZ\_DEFINED\_VALUE\_AT\_ZERO} (see Section 18.31 [Misc], page 661). Except for this case, \texttt{ctz(x)} is equivalent to \texttt{ffs(x)} - 1. The mode of \( x \) must be \( m \) or \texttt{VOIDmode}.

\[(\text{popcount}: m \times x)\]

Represents the number of 1-bits in \( x \), represented as an integer of mode \( m \). The mode of \( x \) must be \( m \) or \texttt{VOIDmode}. 
(parity: m x)

Represents the number of 1-bits modulo 2 in x, represented as an integer of mode m. The mode of x must be m or VOIDmode.

(bswap: m x)

Represents the value x with the order of bytes reversed, carried out in mode m, which must be a fixed-point machine mode. The mode of x must be m or VOIDmode.

14.10 Comparison Operations

Comparison operators test a relation on two operands and are considered to represent a machine-dependent nonzero value described by, but not necessarily equal to, STORE_FLAG_VALUE (see Section 18.31 [Misc], page 661) if the relation holds, or zero if it does not, for comparison operators whose results have a ‘MODE_INT’ mode, FLOAT_STORE_FLAG_VALUE (see Section 18.31 [Misc], page 661) if the relation holds, or zero if it does not, for comparison operators that return floating-point values, and a vector of either VECTOR_STORE_FLAG_VALUE (see Section 18.31 [Misc], page 661) if the relation holds, or of zeros if it does not, for comparison operators that return vector results. The mode of the comparison operation is independent of the mode of the data being compared. If the comparison operation is being tested (e.g., the first operand of an if_then_else), the mode must be VOIDmode.

A comparison operation compares two data objects. The mode of the comparison is determined by the operands; they must both be valid for a common machine mode. A comparison with both operands constant would be invalid as the machine mode could not be deduced from it, but such a comparison should never exist in RTL due to constant folding.

Usually only one style of comparisons is supported on a particular machine, but the combine pass will try to merge operations to produce code like (eq x y), in case it exists in the context of the particular insn involved.

Inequality comparisons come in two flavors, signed and unsigned. Thus, there are distinct expression codes gt and gtu for signed and unsigned greater-than. These can produce different results for the same pair of integer values: for example, 1 is signed greater-than −1 but not unsigned greater-than, because −1 when regarded as unsigned is actually 0xffffffff which is greater than 1.

The signed comparisons are also used for floating point values. Floating point comparisons are distinguished by the machine modes of the operands.

(eq: m x y)

STORE_FLAG_VALUE if the values represented by x and y are equal, otherwise 0.

(ne: m x y)

STORE_FLAG_VALUE if the values represented by x and y are not equal, otherwise 0.

(gt: m x y)

STORE_FLAG_VALUE if the x is greater than y. If they are fixed-point, the comparison is done in a signed sense.

(gtu: m x y)

Like gt but does unsigned comparison, on fixed-point numbers only.
Like `gt` and `gtu` but test for “less than”.

Like `gt` and `gtu` but test for “greater than or equal”.

Like `gt` and `gtu` but test for “less than or equal”.

This is not a comparison operation but is listed here because it is always used in conjunction with a comparison operation. To be precise, `cond` is a comparison expression. This expression represents a choice, according to `cond`, between the value represented by `then` and the one represented by `else`.

On most machines, `if_then_else` expressions are valid only to express conditional jumps.

Similar to `if_then_else`, but more general. Each of `test1`, `test2`, ... is performed in turn. The result of this expression is the value corresponding to the first nonzero test, or `default` if none of the tests are nonzero expressions.

This is currently not valid for instruction patterns and is supported only for insn attributes. See Section 17.19 [Insn Attributes], page 467.

### 14.11 Bit-Fields

Special expression codes exist to represent bit-field instructions.

This represents a reference to a sign-extended bit-field contained or starting in `loc` (a memory or register reference). The bit-field is `size` bits wide and starts at bit `pos`. The compilation option `BITS_BIG_ENDIAN` says which end of the memory unit `pos` counts from.

If `loc` is in memory, its mode must be a single-byte integer mode. If `loc` is in a register, the mode to use is specified by the operand of the `insv` or `extv` pattern (see Section 17.9 [Standard Names], page 405) and is usually a full-word integer mode, which is the default if none is specified.

The mode of `pos` is machine-specific and is also specified in the `insv` or `extv` pattern.

The mode `m` is the same as the mode that would be used for `loc` if it were a register.

A `sign_extract` cannot appear as an lvalue, or part thereof, in RTL.

Like `sign_extract` but refers to an unsigned or zero-extended bit-field. The same sequence of bits are extracted, but they are filled to an entire word with zeros instead of by sign-extension.
Unlike `sign_extract`, this type of expressions can be lvalues in RTL; they may appear on the left side of an assignment, indicating insertion of a value into the specified bit-field.

### 14.12 Vector Operations

All normal RTL expressions can be used with vector modes; they are interpreted as operating on each part of the vector independently. Additionally, there are a few new expressions to describe specific vector operations.

- **(vec_merge: m vec1 vec2 items)**
  This describes a merge operation between two vectors. The result is a vector of mode `m`; its elements are selected from either `vec1` or `vec2`. Which elements are selected is described by `items`, which is a bit mask represented by a `const_int`; a zero bit indicates the corresponding element in the result vector is taken from `vec2` while a set bit indicates it is taken from `vec1`.

- **(vec_select: m vec1 selection)**
  This describes an operation that selects parts of a vector. `vec1` is the source vector, and `selection` is a parallel that contains a `const_int` (or another expression, if the selection can be made at runtime) for each of the subparts of the result vector, giving the number of the source subpart that should be stored into it. The result mode `m` is either the submode for a single element of `vec1` (if only one subpart is selected), or another vector mode with that element submode (if multiple subparts are selected).

- **(vec_concat: m x1 x2)**
  Describes a vector concat operation. The result is a concatenation of the vectors or scalars `x1` and `x2`; its length is the sum of the lengths of the two inputs.

- **(vec_duplicate: m x)**
  This operation converts a scalar into a vector or a small vector into a larger one by duplicating the input values. The output vector mode must have the same submodes as the input vector mode or the scalar modes, and the number of output parts must be an integer multiple of the number of input parts.

- **(vec_series: m base step)**
  This operation creates a vector in which element `i` is equal to `base + i*step`. `m` must be a vector integer mode.

### 14.13 Conversions

All conversions between machine modes must be represented by explicit conversion operations. For example, an expression which is the sum of a byte and a full word cannot be written as `(plus:SI (reg:QI 34) (reg:SI 80))` because the plus operation requires two operands of the same machine mode. Therefore, the byte-sized operand is enclosed in a conversion operation, as in

```
(plus:SI (sign_extend:SI (reg:QI 34)) (reg:SI 80))
```

The conversion operation is not a mere placeholder, because there may be more than one way of converting from a given starting mode to the desired final mode. The conversion operation code says how to do it.
For all conversion operations, \( x \) must not be VOID mode because the mode in which to do the conversion would not be known. The conversion must either be done at compile-time or \( x \) must be placed into a register.

\[
\text{(sign\_extend:}\ m\ x) \quad \text{Represents the result of sign-extending the value } x \text{ to machine mode } m.\ m \text{ must be a fixed-point mode and } x \text{ a fixed-point value of a mode narrower than } m. \\
\text{(zero\_extend:}\ m\ x) \quad \text{Represents the result of zero-extending the value } x \text{ to machine mode } m.\ m \text{ must be a fixed-point mode and } x \text{ a fixed-point value of a mode narrower than } m. \\
\text{(float\_extend:}\ m\ x) \quad \text{Represents the result of extending the value } x \text{ to machine mode } m.\ m \text{ must be a floating point mode and } x \text{ a floating point value of a mode narrower than } m. \\
\text{(truncate:}\ m\ x) \quad \text{Represents the result of truncating the value } x \text{ to machine mode } m.\ m \text{ must be a fixed-point mode and } x \text{ a fixed-point value of a mode wider than } m. \\
\text{(ss\_truncate:}\ m\ x) \quad \text{Represents the result of truncating the value } x \text{ to machine mode } m,\ \text{using signed saturation in the case of overflow. Both } m \text{ and the mode of } x \text{ must be fixed-point modes.} \\
\text{(us\_truncate:}\ m\ x) \quad \text{Represents the result of truncating the value } x \text{ to machine mode } m,\ \text{using unsigned saturation in the case of overflow. Both } m \text{ and the mode of } x \text{ must be fixed-point modes.} \\
\text{(float\_truncate:}\ m\ x) \quad \text{Represents the result of truncating the value } x \text{ to machine mode } m.\ m \text{ must be a floating point mode and } x \text{ a floating point value of a mode wider than } m. \\
\text{(float:}\ m\ x) \quad \text{Represents the result of converting fixed point value } x,\ \text{regarded as signed, to floating point mode } m. \\
\text{(unsigned\_float:}\ m\ x) \quad \text{Represents the result of converting fixed point value } x,\ \text{regarded as unsigned, to floating point mode } m. \\
\text{(fix:}\ m\ x) \quad \text{When } m \text{ is a floating-point mode, represents the result of converting floating point value } x\ \text{(valid for mode } m)\ \text{to an integer, still represented in floating point mode } m,\ \text{by rounding towards zero.} \\
\text{When } m \text{ is a fixed-point mode, represents the result of converting floating point value } x \text{ to mode } m,\ \text{regarded as signed. How rounding is done is not specified, so this operation may be used validly in compiling C code only for integer-valued operands.}
\]
\(\text{unsigned\_fix}\,: m \, x\)

Represents the result of converting floating point value \(x\) to fixed point mode \(m\), regarded as unsigned. How rounding is done is not specified.

\(\text{fract\_convert}\,: m \, x\)

Represents the result of converting fixed-point value \(x\) to fixed-point mode \(m\), signed integer value \(x\) to fixed-point mode \(m\), floating-point value \(x\) to fixed-point mode \(m\), fixed-point value \(x\) to integer mode \(m\) regarded as signed, or fixed-point value \(x\) to floating-point mode \(m\). When overflows or underflows happen, the results are undefined.

\(\text{sat\_fract}\,: m \, x\)

Represents the result of converting fixed-point value \(x\) to fixed-point mode \(m\), signed integer value \(x\) to fixed-point mode \(m\), or floating-point value \(x\) to fixed-point mode \(m\). When overflows or underflows happen, the results are saturated to the maximum or the minimum.

\(\text{unsigned\_fract\_convert}\,: m \, x\)

Represents the result of converting fixed-point value \(x\) to integer mode \(m\) regarded as unsigned, or unsigned integer value \(x\) to fixed-point mode \(m\). When overflows or underflows happen, the results are undefined.

\(\text{unsigned\_sat\_fract}\,: m \, x\)

Represents the result of converting unsigned integer value \(x\) to fixed-point mode \(m\). When overflows or underflows happen, the results are saturated to the maximum or the minimum.

14.14 Declarations

Declaration expression codes do not represent arithmetic operations but rather state assertions about their operands.

\(\text{strict\_low\_part}\,(\text{subreg}\,: m\,(\text{reg}\,: n\, r)\, 0))\)

This expression code is used in only one context: as the destination operand of a set expression. In addition, the operand of this expression must be a non-paradoxical subreg expression.

The presence of \text{strict\_low\_part} says that the part of the register which is meaningful in mode \(n\), but is not part of mode \(m\), is not to be altered. Normally, an assignment to such a subreg is allowed to have undefined effects on the rest of the register when \(m\) is smaller than \texttt{REGMODE\_NATURAL\_SIZE (n')}.

14.15 Side Effect Expressions

The expression codes described so far represent values, not actions. But machine instructions never produce values; they are meaningful only for their side effects on the state of the machine. Special expression codes are used to represent side effects.

The body of an instruction is always one of these side effect codes; the codes described above, which represent values, appear only as the operands of these.
\( (\text{set } lval \ x) \)

Represents the action of storing the value of \( x \) into the place represented by \( lval \). \( lval \) must be an expression representing a place that can be stored in: \( \text{reg} \) (or \( \text{subreg}, \text{strict_low_part} \) or \( \text{zero_extract} \)), \( \text{mem}, \text{pc}, \) or \( \text{parallel} \).

If \( lval \) is a \( \text{reg}, \text{subreg} \) or \( \text{mem} \), it has a machine mode; then \( x \) must be valid for that mode.

If \( lval \) is a \( \text{reg} \) whose machine mode is less than the full width of the register, then it means that the part of the register specified by the machine mode is given the specified value and the rest of the register receives an undefined value. Likewise, if \( lval \) is a \( \text{subreg} \) whose machine mode is narrower than the mode of the register, the rest of the register can be changed in an undefined way.

If \( lval \) is a \( \text{strict_low_part} \) of a \( \text{subreg} \), then the part of the register specified by the machine mode of the \( \text{subreg} \) is given the value \( x \) and the rest of the register is not changed.

If \( lval \) is a \( \text{zero_extract} \), then the referenced part of the bit-field (a memory or register reference) specified by the \( \text{zero_extract} \) is given the value \( x \) and the rest of the bit-field is not changed. Note that \( \text{sign_extract} \) cannot appear in \( lval \).

If \( lval \) is a \( \text{parallel} \), it is used to represent the case of a function returning a structure in multiple registers. Each element of the \( \text{parallel} \) is an \( \text{expr_list} \) whose first operand is a \( \text{reg} \) and whose second operand is a \( \text{const_int} \) representing the offset (in bytes) into the structure at which the data in that register corresponds. The first element may be null to indicate that the structure is also passed partly in memory.

If \( lval \) is \( (\text{pc}) \), we have a jump instruction, and the possibilities for \( x \) are very limited. It may be a \( \text{label_ref} \) expression (unconditional jump). It may be an \( \text{if_then_else} \) (conditional jump), in which case either the second or the third operand must be \( (\text{pc}) \) (for the case which does not jump) and the other of the two must be a \( \text{label_ref} \) (for the case which does jump). \( x \) may also be a \( \text{mem} \) or \( (\text{plus:SI (pc)} \ y) \), where \( y \) may be a \( \text{reg} \) or a \( \text{mem} \); these unusual patterns are used to represent jumps through branch tables.

If \( lval \) is not \( (\text{pc}) \), the mode of \( lval \) must not be \( \text{VOIDmode} \) and the mode of \( x \) must be valid for the mode of \( lval \).

\( lval \) is customarily accessed with the \( \text{SET_DEST} \) macro and \( x \) with the \( \text{SET_SRC} \) macro.

\( (\text{return}) \)

As the sole expression in a pattern, represents a return from the current function, on machines where this can be done with one instruction, such as VAXen. On machines where a multi-instruction “epilogue” must be executed in order to return from the function, returning is done by jumping to a label which precedes the epilogue, and the \( \text{return} \) expression code is never used.

Inside an \( \text{if_then_else} \) expression, represents the value to be placed in \( \text{pc} \) to return to the caller.

Note that an insn pattern of \( (\text{return}) \) is logically equivalent to \( (\text{set (pc) (return)}) \), but the latter form is never used.
(simple_return)
Like (return), but truly represents only a function return, while (return) may represent an insn that also performs other functions of the function epilogue. Like (return), this may also occur in conditional jumps.

(call function nargs)
Represents a function call. function is a mem expression whose address is the address of the function to be called. nargs is an expression which can be used for two purposes: on some machines it represents the number of bytes of stack argument; on others, it represents the number of argument registers.

Each machine has a standard machine mode which function must have. The machine description defines macro FUNCTION_MODE to expand into the requisite mode name. The purpose of this mode is to specify what kind of addressing is allowed, on machines where the allowed kinds of addressing depend on the machine mode being addressed.

(clobber x)
Represents the storing or possible storing of an unpredictable, undescribed value into x, which must be a reg, scratch, parallel or mem expression.

One place this is used is in string instructions that store standard values into particular hard registers. It may not be worth the trouble to describe the values that are stored, but it is essential to inform the compiler that the registers will be altered, lest it attempt to keep data in them across the string instruction.

If x is (mem:BLK (const_int 0)) or (mem:BLK (scratch)), it means that all memory locations must be presumed clobbered. If x is a parallel, it has the same meaning as a parallel in a set expression.

Note that the machine description classifies certain hard registers as “call-clobbered”. All function call instructions are assumed by default to clobber these registers, so there is no need to use clobber expressions to indicate this fact. Also, each function call is assumed to have the potential to alter any memory location, unless the function is declared const.

If the last group of expressions in a parallel are each a clobber expression whose arguments are reg or match_scratch (see Section 17.4 [RTL Template], page 351) expressions, the combiner phase can add the appropriate clobber expressions to an insn it has constructed when doing so will cause a pattern to be matched.

This feature can be used, for example, on a machine that whose multiply and add instructions don’t use an MQ register but which has an add-accumulate instruction that does clobber the MQ register. Similarly, a combined instruction might require a temporary register while the constituent instructions might not.

When a clobber expression for a register appears inside a parallel with other side effects, the register allocator guarantees that the register is unoccupied both before and after that insn if it is a hard register clobber. For pseudo-register clobber, the register allocator and the reload pass do not assign the same hard register to the clobber and the input operands if there is an insn alternative containing the ‘&’ constraint (see Section 17.8.4 [Modifiers], page 368) for the clobber and the hard register is in register classes of the clobber in the
alternative. You can clobber either a specific hard register, a pseudo register, or a \texttt{scratch} expression; in the latter two cases, GCC will allocate a hard register that is available there for use as a temporary.

For instructions that require a temporary register, you should use \texttt{scratch} instead of a pseudo-register because this will allow the combiner phase to add the \texttt{clobber} when required. You do this by coding \texttt{(clobber (match\_scratch . . .))}. If you do clobber a pseudo register, use one which appears nowhere else—generate a new one each time. Otherwise, you may confuse CSE.

There is one other known use for clobbering a pseudo register in a \texttt{parallel}: when one of the input operands of the insn is also clobbered by the insn. In this case, using the same pseudo register in the clobber and elsewhere in the insn produces the expected results.

\texttt{(use x)} Represents the use of the value of \texttt{x}. It indicates that the value in \texttt{x} at this point in the program is needed, even though it may not be apparent why this is so. Therefore, the compiler will not attempt to delete previous instructions whose only effect is to store a value in \texttt{x}. \texttt{x} must be a \texttt{reg} expression.

In some situations, it may be tempting to add a \texttt{use} of a register in a \texttt{parallel} to describe a situation where the value of a special register will modify the behavior of the instruction. A hypothetical example might be a pattern for an addition that can either wrap around or use saturating addition depending on the value of a special control register:

\begin{verbatim}
(parallel [(set (reg:SI 2) (unspec:SI [(reg:SI 3) (reg:SI 4)] 0))
          (use (reg:SI 1))])
\end{verbatim}

This will not work, several of the optimizers only look at expressions locally; it is very likely that if you have multiple insns with identical inputs to the \texttt{unspec}, they will be optimized away even if register 1 changes in between.

This means that \texttt{use} can only be used to describe that the register is live. You should think twice before adding \texttt{use} statements, more often you will want to use \texttt{unspec} instead. The \texttt{use} RTX is most commonly useful to describe that a fixed register is implicitly used in an insn. It is also safe to use in patterns where the compiler knows for other reasons that the result of the whole pattern is variable, such as ‘\texttt{cpymem}’ or ‘\texttt{call}’ patterns.

During the reload phase, an insn that has a \texttt{use} as pattern can carry a \texttt{reg\_equal} note. These \texttt{use} insns will be deleted before the reload phase exits.

During the delayed branch scheduling phase, \texttt{x} may be an insn. This indicates that \texttt{x} previously was located at this place in the code and its data dependencies need to be taken into account. These \texttt{use} insns will be deleted before the delayed branch scheduling phase exits.

\texttt{(parallel \[x0 x1 \ldots\]})

Represents several side effects performed in parallel. The square brackets stand for a vector; the operand of \texttt{parallel} is a vector of expressions. \texttt{x0}, \texttt{x1} and so on are individual side effect expressions—expressions of code \texttt{set}, \texttt{call}, \texttt{return}, \texttt{simple\_return}, \texttt{clobber} or \texttt{use}. 
“In parallel” means that first all the values used in the individual side-effects are computed, and second all the actual side-effects are performed. For example,

```
(parallel [(set (reg:SI 1) (mem:SI (reg:SI 1)))
          (set (mem:SI (reg:SI 1)) (reg:SI 1))])
```

says unambiguously that the values of hard register 1 and the memory location addressed by it are interchanged. In both places where (reg:SI 1) appears as a memory address it refers to the value in register 1 before the execution of the insn.

It follows that it is incorrect to use parallel and expect the result of one set to be available for the next one. For example, people sometimes attempt to represent a jump-if-zero instruction this way:

```
(parallel [(set (reg:CC CC_REG) (reg:SI 34))
          (set (pc) (if_then_else
                     (eq (reg:CC CC_REG) (const_int 0))
                     (label_ref ...) (pc))))
```

But this is incorrect, because it says that the jump condition depends on the condition code value before this instruction, not on the new value that is set by this instruction.

Peephole optimization, which takes place together with final assembly code output, can produce insns whose patterns consist of a parallel whose elements are the operands needed to output the resulting assembler code—often reg, mem or constant expressions. This would not be well-formed RTL at any other stage in compilation, but it is OK then because no further optimization remains to be done.

```
(cond_exec [cond expr])
```

Represents a conditionally executed expression. The expr is executed only if the cond is nonzero. The cond expression must not have side-effects, but the expr may very well have side-effects.

```
(sequence [insns ...])
```

Represents a sequence of insns. If a sequence appears in the chain of insns, then each of the insns that appears in the sequence must be suitable for appearing in the chain of insns, i.e. must satisfy the INSN_P predicate.

After delay-slot scheduling is completed, an insn and all the insns that reside in its delay slots are grouped together into a sequence. The insn requiring the delay slot is the first insn in the vector; subsequent insns are to be placed in the delay slot.

INSN_ANNULLED_BRANCH_P is set on an insn in a delay slot to indicate that a branch insn should be used that will conditionally annul the effect of the insns in the delay slots. In such a case, INSN_FROM_TARGET_P indicates that the insn is from the target of the branch and should be executed only if the branch is taken; otherwise the insn should be executed only if the branch is not taken. See Section 17.19.8 [Delay Slots], page 476.

Some back ends also use sequence objects for purposes other than delay-slot groups. This is not supported in the common parts of the compiler, which treat such sequences as delay-slot groups.
DWARF2 Call Frame Address (CFA) adjustments are sometimes also expressed using sequence objects as the value of a RTX_FRAME_RELATED_P note. This only happens if the CFA adjustments cannot be easily derived from the pattern of the instruction to which the note is attached. In such cases, the value of the note is used instead of best-guessing the semantics of the instruction. The back end can attach notes containing a sequence of set patterns that express the effect of the parent instruction.

These expression codes appear in place of a side effect, as the body of an insn, though strictly speaking they do not always describe side effects as such:

(asm_input s)
Represents literal assembler code as described by the string s.

(unspec [operands ...] index)
(unspec_volatile [operands ...] index)
Represents a machine-specific operation on operands. index selects between multiple machine-specific operations. unspec_volatile is used for volatile operations and operations that may trap; unspec is used for other operations. These codes may appear inside a pattern of an insn, inside a parallel, or inside an expression.

(addr_vec:m [lr0 lr1 ...])
Represents a table of jump addresses. The vector elements lr0, etc., are label_ref expressions. The mode m specifies how much space is given to each address; normally m would be Pmode.

(addr_diff_vec:m base [lr0 lr1 ...] min max flags)
Represents a table of jump addresses expressed as offsets from base. The vector elements lr0, etc., are label_ref expressions and so is base. The mode m specifies how much space is given to each address-difference. min and max are set up by branch shortening and hold a label with a minimum and a maximum address, respectively. flags indicates the relative position of base, min and max to the containing insn and of min and max to base. See rtl.def for details.

(prefetch:m addr rw locality)
Represents prefetch of memory at address addr. Operand rw is 1 if the prefetch is for data to be written, 0 otherwise; targets that do not support write prefecches should treat this as a normal prefetch. Operand locality specifies the amount of temporal locality; 0 if there is none or 1, 2, or 3 for increasing levels of temporal locality; targets that do not support locality hints should ignore this.
This insn is used to minimize cache-miss latency by moving data into a cache before it is accessed. It should use only non-faulting data prefetch instructions.

### 14.16 Embedded Side-Effects on Addresses

Six special side-effect expression codes appear as memory addresses.

(pre_dec:m x)
Represents the side effect of decrementing x by a standard amount and represents also the value that x has after being decremented. x must be a reg or
mem, but most machines allow only a reg. m must be the machine mode for pointers on the machine in use. The amount x is decremented by is the length in bytes of the machine mode of the containing memory reference of which this expression serves as the address. Here is an example of its use:

(mem:DF (pre_dec:SI (reg:SI 39)))

This says to decrement pseudo register 39 by the length of a DFmode value and use the result to address a DFmode value.

(pre_inc:m x)
Similar, but specifies incrementing x instead of decrementing it.

(post_dec:m x)
Represents the same side effect as pre_dec but a different value. The value represented here is the value x has before being decremented.

(post_inc:m x)
Similar, but specifies incrementing x instead of decrementing it.

(post_modify:m x y)
Represents the side effect of setting x to y and represents x before x is modified. x must be a reg or mem, but most machines allow only a reg. m must be the machine mode for pointers on the machine in use.

The expression y must be one of three forms: (plus:m x z), (minus:m x z), or (plus:m x i), where z is an index register and i is a constant.

Here is an example of its use:


This says to modify pseudo register 42 by adding the contents of pseudo register 48 to it, after the use of what ever 42 points to.

(pre_modify:m x expr)
Similar except side effects happen before the use.

These embedded side effect expressions must be used with care. Instruction patterns may not use them. Until the ‘flow’ pass of the compiler, they may occur only to represent pushes onto the stack. The ‘flow’ pass finds cases where registers are incremented or decremented in one instruction and used as an address shortly before or after; these cases are then transformed to use pre- or post-increment or -decrement.

If a register used as the operand of these expressions is used in another address in an insn, the original value of the register is used. Uses of the register outside of an address are not permitted within the same insn as a use in an embedded side effect expression because such insns behave differently on different machines and hence must be treated as ambiguous and disallowed.

An instruction that can be represented with an embedded side effect could also be represented using parallel containing an additional set to describe how the address register is altered. This is not done because machines that allow these operations at all typically allow them wherever a memory address is called for. Describing them as additional parallel stores would require doubling the number of entries in the machine description.
14.17 Assembler Instructions as Expressions

The RTX code `asm_operands` represents a value produced by a user-specified assembler instruction. It is used to represent an `asm` statement with arguments. An `asm` statement with a single output operand, like this:

```c
asm ("foo %1,%2,%0" : "a" (outputvar) : "g" (x + y), "di" (*z));
```

is represented using a single `asm_operands` RTX which represents the value that is stored in `outputvar`:

```c
(set rtx-for-outputvar
 (asm_operands "foo %1,%2,%0" "a" 0
 [rtx-for-addition-result rtx-for-*z]
 [(asm_input:m1 "g")
 (asm_input:m2 "di")]))
```

Here the operands of the `asm_operands` RTX are the assembler template string, the output-operand’s constraint, the index-number of the output operand among the output operands specified, a vector of input operand RTX’s, and a vector of input-operand modes and constraints. The mode `m1` is the mode of the sum `x+y`; `m2` is that of `*z`.

When an `asm` statement has multiple output values, its insn has several such `set` RTX’s inside of a `parallel`. Each `set` contains an `asm_operands`; all of these share the same assembler template and vectors, but each contains the constraint for the respective output operand. They are also distinguished by the output-operand index number, which is 0, 1, ... for successive output operands.

14.18 Variable Location Debug Information in RTL

Variable tracking relies on `MEM_EXPR` and `REG_EXPR` annotations to determine what user variables memory and register references refer to.

Variable tracking at assignments uses these notes only when they refer to variables that live at fixed locations (e.g., addressable variables, global non-automatic variables). For variables whose location may vary, it relies on the following types of notes.

```c
(var_location:mode var exp stat)
```

Binds variable `var`, a tree, to value `exp`, an RTL expression. It appears only in `NOTE_INSN_VAR_LOCATION` and `DEBUG_INSN` s, with slightly different meanings. `mode`, if present, represents the mode of `exp`, which is useful if it is a modeless expression. `stat` is only meaningful in notes, indicating whether the variable is known to be initialized or uninitialized.

```c
(debug_expr:mode decl)
```

Stands for the value bound to the `DEBUG_EXPR_DECL` `decl`, that points back to it, within value expressions in `VAR_LOCATION` nodes.

```c
(debug_implicit_ptr:mode decl)
```

Stands for the location of a `decl` that is no longer addressable.

```c
(entry_value:mode decl)
```

Stands for the value a `decl` had at the entry point of the containing function.

```c
(debug_parameter_ref:mode decl)
```

Refers to a parameter that was completely optimized out.
(debug_marker: mode)

Marks a program location. With VOIDmode, it stands for the beginning of a
statement, a recommended inspection point logically after all prior side effects,
and before any subsequent side effects. With BLKmode, it indicates an inline
entry point: the lexical block encoded in the INSN_LOCATION is the enclosing
block that encloses the inlined function.

14.19 Insns

The RTL representation of the code for a function is a doubly-linked chain of objects called
insns. Insns are expressions with special codes that are used for no other purpose. Some
insns are actual instructions; others represent dispatch tables for switch statements; others
represent labels to jump to or various sorts of declarative information.

In addition to its own specific data, each insn must have a unique id-number that dis-
tinguishes it from all other insns in the current function (after delayed branch scheduling,
copies of an insn with the same id-number may be present in multiple places in a function,
but these copies will always be identical and will only appear inside a sequence), and chain
pointers to the preceding and following insns. These three fields occupy the same position
in every insn, independent of the expression code of the insn. They could be accessed with
XEXP and XINT, but instead three special macros are always used:

INSN_UID (i)
Accesses the unique id of insn i.

PREV_INSN (i)
Accesses the chain pointer to the insn preceding i. If i is the first insn, this is
a null pointer.

NEXT_INSN (i)
Accesses the chain pointer to the insn following i. If i is the last insn, this is a
null pointer.

The first insn in the chain is obtained by calling get_insns; the last insn is the result
of calling get_last_insn. Within the chain delimited by these insns, the NEXT_INSN and
PREV_INSN pointers must always correspond: if insn is not the first insn,

NEXT_INSN (PREV_INSN (insn)) == insn

is always true and if insn is not the last insn,

PREV_INSN (NEXT_INSN (insn)) == insn

is always true.

After delay slot scheduling, some of the insns in the chain might be sequence expressions,
which contain a vector of insns. The value of NEXT_INSN in all but the last of these insns
is the next insn in the vector; the value of NEXT_INSN of the last insn in the vector is the
same as the value of NEXT_INSN for the sequence in which it is contained. Similar rules
apply for PREV_INSN.

This means that the above invariants are not necessarily true for insns inside sequence
expressions. Specifically, if insn is the first insn in a sequence, NEXT_INSN (PREV_INSN
(insn)) is the insn containing the sequence expression, as is the value of PREV_INSN
(NEXT_INSN (insn)) if insn is the last insn in the sequence expression. You can use these
expressions to find the containing sequence expression.
Every insn has one of the following expression codes:

**insn**  
The expression code **insn** is used for instructions that do not jump and do not do function calls. **sequence** expressions are always contained in insns with code **insn** even if one of those insns should jump or do function calls.

Insns with code **insn** have four additional fields beyond the three mandatory ones listed above. These four are described in a table below.

**jump_insn**  
The expression code **jump_insn** is used for instructions that may jump (or, more generally, may contain **label_ref** expressions to which **pc** can be set in that instruction). If there is an instruction to return from the current function, it is recorded as a **jump_insn**.

**jump_insn** insns have the same extra fields as **insn** insns, accessed in the same way and in addition contain a field **JUMP_LABEL** which is defined once jump optimization has completed.

For simple conditional and unconditional jumps, this field contains the **code_label** to which this insn will (possibly conditionally) branch. In a more complex jump, **JUMP_LABEL** records one of the labels that the insn refers to; other jump target labels are recorded as **REG_LABEL_TARGET** notes. The exception is **addr_vec** and **addr_diff_vec**, where **JUMP_LABEL** is **NULL_RTX** and the only way to find the labels is to scan the entire body of the insn.

Return insns count as jumps, but their **JUMP_LABEL** is **RETURN** or **SIMPLE_RETURN**.

**call_insn**  
The expression code **call_insn** is used for instructions that may do function calls. It is important to distinguish these instructions because they imply that certain registers and memory locations may be altered unpredictably.

**call_insn** insns have the same extra fields as **insn** insns, accessed in the same way and in addition contain a field **CALL_INSN_FUNCTION_USAGE** which contains a list (chain of **expr_list** expressions) containing **use**, **clobber** and sometimes **set** expressions that denote hard registers and **mems** used or clobbered by the called function.

A **mem** generally points to a stack slot in which arguments passed to the libcall by reference (see Section 18.9.7 [Register Arguments], page 554) are stored. If the argument is caller-copied (see Section 18.9.7 [Register Arguments], page 554), the stack slot will be mentioned in **clobber** and **use** entries; if it’s callee-copied, only a **use** will appear, and the **mem** may point to addresses that are not stack slots.

Registers occurring inside a **clobber** in this list augment registers specified in **CALL_USED_REGISTERS** (see Section 18.7.1 [Register Basics], page 523).

If the list contains a **set** involving two registers, it indicates that the function returns one of its arguments. Such a **set** may look like a no-op if the same register holds the argument and the return value.
code_label

A code_label insn represents a label that a jump insn can jump to. It contains two special fields of data in addition to the three standard ones. CODE_LABEL_NUMBER is used to hold the label number, a number that identifies this label uniquely among all the labels in the compilation (not just in the current function). Ultimately, the label is represented in the assembler output as an assembler label, usually of the form ‘Ln’ where n is the label number.

When a code_label appears in an RTL expression, it normally appears within a label_ref which represents the address of the label, as a number.

Besides as a code_label, a label can also be represented as a note of type NOTE_INSN_DELETED_LABEL.

The field LABEL_NUSES is only defined once the jump optimization phase is completed. It contains the number of times this label is referenced in the current function.

The field LABEL_KIND differentiates four different types of labels: LABEL_NORMAL, LABEL_STATIC_ENTRY, LABEL_GLOBAL_ENTRY, and LABEL_WEAK_ENTRY. The only labels that do not have type LABEL_NORMAL are alternate entry points to the current function. These may be static (visible only in the containing translation unit), global (exposed to all translation units), or weak (global, but can be overridden by another symbol with the same name).

Much of the compiler treats all four kinds of label identically. Some of it needs to know whether or not a label is an alternate entry point; for this purpose, the macro LABEL_ALT_ENTRY_P is provided. It is equivalent to testing whether ‘LABEL_KIND (label) == LABEL_NORMAL’. The only place that cares about the distinction between static, global, and weak alternate entry points, besides the front-end code that creates them, is the function output_alternate_entry_point, in ‘final.c’.

To set the kind of a label, use the SET_LABEL_KIND macro.

jump_table_data

A jump_table_data insn is a placeholder for the jump-table data of a casesi or tablejump insn. They are placed after a tablejump_p insn. A jump_table_data insn is not part of a basic block, but it is associated with the basic block that ends with the tablejump_p insn. The PATTERN of a jump_table_data is always either an addr_vec or an addr_diff_vec, and a jump_table_data insn is always preceded by a code_label. The tablejump_p insn refers to that code_label via its JUMP_LABEL.

barrier

Barriers are placed in the instruction stream when control cannot flow past them. They are placed after unconditional jump instructions to indicate that the jumps are unconditional and after calls to volatile functions, which do not return (e.g., exit). They contain no information beyond the three standard fields.

note

Note insns are used to represent additional debugging and declarative information. They contain two nonstandard fields, an integer which is accessed with the macro NOTE_LINE_NUMBER and a string accessed with NOTE_SOURCE_FILE.
If \texttt{NOTE\_LINE\_NUMBER} is positive, the note represents the position of a source line and \texttt{NOTE\_SOURCE\_FILE} is the source file name that the line came from. These notes control generation of line number data in the assembler output.

Otherwise, \texttt{NOTE\_LINE\_NUMBER} is not really a line number but a code with one of the following values (and \texttt{NOTE\_SOURCE\_FILE} must contain a null pointer):

\textbf{NOTE\_INSN\_DELETED}

Such a note is completely ignorable. Some passes of the compiler delete insns by altering them into notes of this kind.

\textbf{NOTE\_INSN\_DELETED\_LABEL}

This marks what used to be a \texttt{code\_label}, but was not used for other purposes than taking its address and was transformed to mark that no code jumps to it.

\textbf{NOTE\_INSN\_BLOCK\_BEG}

\textbf{NOTE\_INSN\_BLOCK\_END}

These types of notes indicate the position of the beginning and end of a level of scoping of variable names. They control the output of debugging information.

\textbf{NOTE\_INSN\_EH\_REGION\_BEG}

\textbf{NOTE\_INSN\_EH\_REGION\_END}

These types of notes indicate the position of the beginning and end of a level of scoping for exception handling. \texttt{NOTE\_EH\_HANDLER} identifies which region is associated with these notes.

\textbf{NOTE\_INSN\_FUNCTION\_BEG}

Appears at the start of the function body, after the function prologue.

\textbf{NOTE\_INSN\_VAR\_LOCATION}

This note is used to generate variable location debugging information. It indicates that the user variable in its \texttt{VAR\_LOCATION} operand is at the location given in the RTL expression, or holds a value that can be computed by evaluating the RTL expression from that static point in the program up to the next such note for the same user variable.

\textbf{NOTE\_INSN\_BEGIN\__STMT}

This note is used to generate \texttt{is\_stmt} markers in line number debugging information. It indicates the beginning of a user statement.

\textbf{NOTE\_INSN\_INLINE\_ENTRY}

This note is used to generate \texttt{entry\_pc} for inlined subroutines in debugging information. It indicates an inspection point at which all arguments for the inlined function have been bound, and before its first statement.

These codes are printed symbolically when they appear in debugging dumps.
debug_insn

The expression code `debug_insn` is used for pseudo-instructions that hold debugging information for variable tracking at assignments (see `-fvar-tracking-assignments` option). They are the RTL representation of `GIMPLE_DEBUG` statements (Section 12.8.7 [GIMPLE_DEBUG], page 233), with a `VAR_LOCATION` operand that binds a user variable tree to an RTL representation of the value in the corresponding statement. A `DEBUG_EXPR` in it stands for the value bound to the corresponding `DEBUG_EXPR_DECL`.

`GIMPLE_DEBUG_BEGIN_STMT` and `GIMPLE_DEBUG_INLINE_ENTRY` are expanded to RTL as a `DEBUG_INSN` with a `DEBUG_MARKER PATTERN`; the difference is the RTL mode: the former's `DEBUG_MARKER` is `VOIDmode`, whereas the latter is `BLKmode`; information about the inlined function can be taken from the lexical block encoded in the `INSN_LOCATION`. These `DEBUG_INSN`s, that do not carry `VAR_LOCATION` information, just `DEBUG_MARKER`s, can be detected by testing `DEBUG_MARKER_INSN_P`, whereas those that do can be recognized as `DEBUG_BIND_INSN_P`.

Throughout optimization passes, `DEBUG_INSN`s are not reordered with respect to each other, particularly during scheduling. Binding information is kept in pseudo-instruction form, so that, unlike notes, it gets the same treatment and adjustments that regular instructions would. It is the variable tracking pass that turns these pseudo-instructions into `NOTE_INSN_VAR_LOCATION`, `NOTE_INSN_BEGIN_STMT` and `NOTE_INSN_INLINE_ENTRY` notes, analyzing control flow, value equivalences and changes to registers and memory referenced in value expressions, propagating the values of debug temporaries and determining expressions that can be used to compute the value of each user variable at as many points (ranges, actually) in the program as possible.

Unlike `NOTE_INSN_VAR_LOCATION`, the value expression in an `INSN_VAR_LOCATION` denotes a value at that specific point in the program, rather than an expression that can be evaluated at any later point before an overriding `VAR_LOCATION` is encountered. E.g., if a user variable is bound to a `REG` and then a subsequent insn modifies the `REG`, the note location would keep mapping the user variable to the register across the insn, whereas the insn location would keep the variable bound to the value, so that the variable tracking pass would emit another location note for the variable at the point in which the register is modified.

The machine mode of an insn is normally `VOIDmode`, but some phases use the mode for various purposes.

The common subexpression elimination pass sets the mode of an insn to `QImode` when it is the first insn in a block that has already been processed.

The second Haifa scheduling pass, for targets that can multiple issue, sets the mode of an insn to `TImode` when it is believed that the instruction begins an issue group. That is, when the instruction cannot issue simultaneously with the previous. This may be relied on by later passes, in particular machine-dependent reorg.

Here is a table of the extra fields of `insn`, `jump_insn` and `call_insn` insns:
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PATTERN (i)
An expression for the side effect performed by this insn. This must be one of the following codes: set, call, use, clobber, return, simple_return, asm_input, asm_output, addr_vec, addr_diff_vec, trap_if, unspec, unspec_volatile, parallel, cond_exec, or sequence. If it is a parallel, each element of the parallel must be one of these codes, except that parallel expressions cannot be nested and addr_vec and addr_diff_vec are not permitted inside a parallel expression.

INSN_CODE (i)
An integer that says which pattern in the machine description matches this insn, or –1 if the matching has not yet been attempted.
Such matching is never attempted and this field remains –1 on an insn whose pattern consists of a single use, clobber, asm_input, addr_vec or addr_diff_vec expression.
Matching is also never attempted on insns that result from an asm statement. These contain at least one asm_operands expression. The function asm_noperands returns a non-negative value for such insns.
In the debugging output, this field is printed as a number followed by a symbolic representation that locates the pattern in the ‘md’ file as some small positive or negative offset from a named pattern.

REG_NOTES (i)
A list (chain of expr_list, insn_list and int_list expressions) giving miscellaneous information about the insn. It is often information pertaining to the registers used in this insn.
The REG_NOTES field of an insn is a chain that includes expr_list and int_list expressions as well as insn_list expressions. There are several kinds of register notes, which are distinguished by the machine mode, which in a register note is really understood as being an enum reg_note. The first operand op of the note is data whose meaning depends on the kind of note.
The macro REG_NOTE_KIND (x) returns the kind of register note. Its counterpart, the macro PUT_REG_NOTE_KIND (x, newkind) sets the register note type of x to be newkind.
Register notes are of three classes: They may say something about an input to an insn, they may say something about an output of an insn, or they may create a linkage between two insns.
These register notes annotate inputs to an insn:
REG_DEAD The value in op dies in this insn; that is to say, altering the value immediately after this insn would not affect the future behavior of the program.
It does not follow that the register op has no useful value after this insn since op is not necessarily modified by this insn. Rather, no subsequent instruction uses the contents of op.
REG_UNUSED The register op being set by this insn will not be used in a subsequent insn. This differs from a REG_DEAD note, which indicates that the value in an input
will not be used subsequently. These two notes are independent; both may be
present for the same register.

REG_INC
The register \textit{op} is incremented (or decremented; at this level there is no dis-
tinction) by an embedded side effect inside this insn. This means it appears in
a \texttt{post\_inc}, \texttt{pre\_inc}, \texttt{post\_dec} or \texttt{pre\_dec} expression.

REG_NONNEG
The register \textit{op} is known to have a nonnegative value when this insn is reached.
This is used by special looping instructions that terminate when the register
goes negative.
The \texttt{REG\_NONNEG} note is added only to ‘\texttt{doloop\_end}’ insns, if its pattern uses a\texttt{ge} condition.

REG_LABEL_OPERAND
This insn uses \textit{op}, a \texttt{code\_label} or a \texttt{note} of type \texttt{NOTE\_INSN\_DELETED\_LABEL},
but is not a \texttt{jump\_insn}, or it is a \texttt{jump\_insn} that refers to the operand as an
ordinary operand. The label may still eventually be a jump target, but if so in
an indirect jump in a subsequent insn. The presence of this note allows jump
optimization to be aware that \textit{op} is, in fact, being used, and flow optimization
to build an accurate flow graph.

REG_LABEL_TARGET
This insn is a \texttt{jump\_insn} but not an \texttt{addr\_vec} or \texttt{addr\_diff\_vec}. It uses \textit{op},
a \texttt{code\_label} as a direct or indirect jump target. Its purpose is similar to
that of \texttt{REG\_LABEL\_OPERAND}. This note is only present if the insn has multiple
targets; the last label in the insn (in the highest numbered insn-field) goes
into the \texttt{JUMP\_LABEL} field and does not have a \texttt{REG\_LABEL\_TARGET} note. See
Section 14.19 [Insns], page 308.

REG_SETJMP
Appears attached to each \texttt{CALL\_INSN} to \texttt{setjmp} or a related function.

The following notes describe attributes of outputs of an insn:

REG_EQUIV
REG_EQUAL
This note is only valid on an insn that sets only one register and indicates that
that register will be equal to \textit{op} at run time; the scope of this equivalence differs
between the two types of notes. The value which the insn explicitly copies into
the register may look different from \textit{op}, but they will be equal at run time. If
the output of the single \texttt{set} is a \texttt{strict\_low\_part} or \texttt{zero\_extract} expression,
the note refers to the register that is contained in its first operand.
For \texttt{REG\_EQUIV}, the register is equivalent to \textit{op} throughout the entire function,
and could validly be replaced in all its occurrences by \textit{op}. (“Validly” here refers
to the data flow of the program; simple replacement may make some insns
invalid.) For example, when a constant is loaded into a register that is never
assigned any other value, this kind of note is used.
When a parameter is copied into a pseudo-register at entry to a function, a note
of this kind records that the register is equivalent to the stack slot where the
parameter was passed. Although in this case the register may be set by other insns, it is still valid to replace the register by the stack slot throughout the function.

A **REG_EQUIV** note is also used on an instruction which copies a register parameter into a pseudo-register at entry to a function, if there is a stack slot where that parameter could be stored. Although other insns may set the pseudo-register, it is valid for the compiler to replace the pseudo-register by stack slot throughout the function, provided the compiler ensures that the stack slot is properly initialized by making the replacement in the initial copy instruction as well. This is used on machines for which the calling convention allocates stack space for register parameters. See **REG_PARM_STACK_SPACE** in Section 18.9.6 [Stack Arguments], page 552.

In the case of **REG_EQUAL**, the register that is set by this insn will be equal to *op* at run time at the end of this insn but not necessarily elsewhere in the function. In this case, *op* is typically an arithmetic expression. For example, when a sequence of insns such as a library call is used to perform an arithmetic operation, this kind of note is attached to the insn that produces or copies the final value.

These two notes are used in different ways by the compiler passes. **REG_EQUAL** is used by passes prior to register allocation (such as common subexpression elimination and loop optimization) to tell them how to think of that value. **REG_EQUIV** notes are used by register allocation to indicate that there is an available substitute expression (either a constant or a **mem** expression for the location of a parameter on the stack) that may be used in place of a register if insufficient registers are available.

Except for stack homes for parameters, which are indicated by a **REG_EQUIV** note and are not useful to the early optimization passes and pseudo registers that are equivalent to a memory location throughout their entire life, which is not detected until later in the compilation, all equivalences are initially indicated by an attached **REG_EQUAL** note. In the early stages of register allocation, a **REG_EQUAL** note is changed into a **REG_EQUIV** note if *op* is a constant and the insn represents the only set of its destination register.

Thus, compiler passes prior to register allocation need only check for **REG_EQUAL** notes and passes subsequent to register allocation need only check for **REG_EQUIV** notes.

These notes describe linkages between insns. They occur in pairs: one insn has one of a pair of notes that points to a second insn, which has the inverse note pointing back to the first insn.

**REG_DEP_TRUE**

This indicates a true dependence (a read after write dependence).

**REG_DEP_OUTPUT**

This indicates an output dependence (a write after write dependence).

**REG_DEP_ANTI**

This indicates an anti dependence (a write after read dependence).
These notes describe information gathered from gcov profile data. They are stored in the REG_NOTES field of an insn.

**REG_BR_PROB**
This is used to specify the ratio of branches to non-branches of a branch insn according to the profile data. The note is represented as an int_list expression whose integer value is an encoding of profile_probability type. profile_probability provide member function from_reg_br_prob_note and to_reg_br_prob_note to extract and store the probability into the RTL encoding.

**REG_BR_PRED**
These notes are found in JUMP insns after delayed branch scheduling has taken place. They indicate both the direction and the likelihood of the JUMP. The format is a bitmask of ATTR_FLAG_* values.

**REG_FRAME_RELATED_EXPR**
This is used on an RTX_FRAME_RELATED_P insn wherein the attached expression is used in place of the actual insn pattern. This is done in cases where the pattern is either complex or misleading.

The note **REG_CALL_NOCF_CHECK** is used in conjunction with the ‘-fcf-protection=branch’ option. The note is set if a nocf_check attribute is specified for a function type or a pointer to function type. The note is stored in the REG_NOTES field of an insn.

**REG_CALL_NOCF_CHECK**
Users have control through the nocf_check attribute to identify which calls to a function should be skipped from control-flow instrumentation when the option ‘-fcf-protection=branch’ is specified. The compiler puts a REG_CALL_NOCF_CHECK note on each CALL_INSN instruction that has a function type marked with a nocf_check attribute.

For convenience, the machine mode in an insn_list or expr_list is printed using these symbolic codes in debugging dumps.

The only difference between the expression codes insn_list and expr_list is that the first operand of an insn_list is assumed to be an insn and is printed in debugging dumps as the insn’s unique id; the first operand of an expr_list is printed in the ordinary way as an expression.

### 14.20 RTL Representation of Function-Call Insns

Insns that call subroutines have the RTL expression code call_insn. These insns must satisfy special rules, and their bodies must use a special RTL expression code, call.

A call expression has two operands, as follows:

(call (mem:fm addr) nbytes)

Here nbytes is an operand that represents the number of bytes of argument data being passed to the subroutine, fm is a machine mode (which must equal as the definition of the FUNCTION_MODE macro in the machine description) and addr represents the address of the subroutine.

For a subroutine that returns no value, the call expression as shown above is the entire body of the insn, except that the insn might also contain use or clobber expressions.
For a subroutine that returns a value whose mode is not \texttt{BLKmode}, the value is returned in a hard register. If this register’s number is \texttt{r}, then the body of the call insn looks like this:

\begin{verbatim}
(set (reg:m r)
    (call (mem:fm addr) nbytes))
\end{verbatim}

This RTL expression makes it clear (to the optimizer passes) that the appropriate register receives a useful value in this insn.

When a subroutine returns a \texttt{BLKmode} value, it is handled by passing to the subroutine the address of a place to store the value. So the call insn itself does not “return” any value, and it has the same RTL form as a call that returns nothing.

On some machines, the call instruction itself clobbers some register, for example to contain the return address. \texttt{call_insn} insns on these machines should have a body which is a \texttt{parallel} that contains both the call expression and \texttt{clobber} expressions that indicate which registers are destroyed. Similarly, if the call instruction requires some register other than the stack pointer that is not explicitly mentioned in its RTL, a \texttt{use} subexpression should mention that register.

Functions that are called are assumed to modify all registers listed in the configuration macro \texttt{CALL_USED_REGISTERS} (see Section 18.7.1 [Register Basics], page 523) and, with the exception of \texttt{const} functions and library calls, to modify all of memory.

Insns containing just \texttt{use} expressions directly precede the \texttt{call_insn} insn to indicate which registers contain inputs to the function. Similarly, if registers other than those in \texttt{CALL_USED_REGISTERS} are clobbered by the called function, insns containing a single \texttt{clobber} follow immediately after the call to indicate which registers.

### 14.21 On-the-Side SSA Form for RTL

The patterns of an individual RTL instruction describe which registers are inputs to that instruction and which registers are outputs from that instruction. However, it is often useful to know where the definition of a register input comes from and where the result of a register output is used. One way of obtaining this information is to use the RTL SSA form, which provides a Static Single Assignment representation of the RTL instructions.

The RTL SSA code is located in the `rtl-ssa` subdirectory of the GCC source tree. This section only gives a brief overview of it; please see the comments in the source code for more details.

#### 14.21.1 Using RTL SSA in a pass

A pass that wants to use the RTL SSA form should start with the following:

\begin{verbatim}
#define INCLUDE_ALGORITHM
#define INCLUDE_FUNCTIONAL
#include "config.h"
#include "system.h"
#include "coretypes.h"
#include "backend.h"
#include "rtl.h"
#include "df.h"
#include "rtl-ssa.h"
\end{verbatim}

All the RTL SSA code is contained in the \texttt{rtl-ssa} namespace, so most passes will then want to do:
using namespace rtl_ssa;

However, this is purely a matter of taste, and the examples in the rest of this section do not require it.

The RTL SSA representation is an optional on-the-side feature that applies on top of the normal RTL instructions. It is currently local to individual RTL passes and is not maintained across passes.

However, in order to allow the RTL SSA information to be preserved across passes in future, ‘crtl->ssa’ points to the current function’s SSA form (if any). Passes that want to use the RTL SSA form should first do:

crtl->ssa = new rtl_ssa::function_info (fn);

where fn is the function that the pass is processing. (Passes that are using namespace rtl_ssa do not need the ‘rtl_ssa::’.)

Once the pass has finished with the SSA form, it should do the following:

free_dominance_info (CDI_DOMINATORS);
if (crtl->ssa->perform_pending_updates ())
  cleanup_cfg (0);

delete crtl->ssa;
crtl->ssa = nullptr;

The free_dominance_info call is necessary because dominance information is not currently maintained between RTL passes. The next two lines commit any changes to the RTL instructions that were queued for later; see the comment above the declaration of perform_pending_updates for details. The final two lines discard the RTL SSA form and free the associated memory.

### 14.21.2 RTL SSA Instructions

RTL SSA instructions are represented by an rtl_ssa::insn_info. These instructions are chained together in a single list that follows a reverse postorder (RPO) traversal of the function. This means that if any path through the function can execute an instruction \( I_1 \) and then later execute an instruction \( I_2 \) for the first time, \( I_1 \) appears before \( I_2 \) in the list\(^1\).

Two RTL SSA instructions can be compared to find which instruction occurs earlier than the other in the RPO. One way to do this is to use the C++ comparison operators, such as:

\*insn1 < \*insn2

Another way is to use the compare_with function:

insn1->compare_with (insn2)

This expression is greater than zero if insn1 comes after insn2 in the RPO, less than zero if insn1 comes before insn2 in the RPO, or zero if insn1 and insn2 are the same. This order is maintained even if instructions are added to the function or moved around.

The main purpose of rtl_ssa::insn_info is to hold SSA information about an instruction. However, it also caches certain properties of the instruction, such as whether it is an inline assembly instruction, whether it has volatile accesses, and so on.

---

\(^1\) Note that this order is different from the order of the underlying RTL instructions, which follow machine code order instead.
14.21.3 RTL SSA Basic Blocks

RTL SSA instructions (see Section 14.21.2 [RTL SSA Instructions], page 318) are organized into basic blocks, with each block being represented by an rtl_ssa:bb_info. There is a one-to-one mapping between these rtl_ssa:bb_info structures and the underlying CFG basic_block structures (see Section 15.1 [Basic Blocks], page 329).

If a CFG basic block \( bb \) contains an RTL instruction \( insn \), the RTL SSA representation of \( bb \) also contains an RTL SSA representation of \( insn \). Within RTL SSA, these instructions are referred to as “real” instructions. These real instructions fall into two groups: debug instructions and nondebug instructions. Only nondebug instructions should affect code generation decisions.

In addition, each RTL SSA basic block has two “artificial” instructions: a “head” instruction that comes before all the real instructions and an “end” instruction that comes after all real instructions. These instructions exist to represent things that are conceptually defined or used at the start and end of a basic block. The instructions always exist, even if they do not currently do anything.

Like instructions, these blocks are chained together in a reverse postorder. This list includes the entry block (which always comes first) and the exit block (which always comes last).

RTL SSA basic blocks are chained together into “extended basic blocks” (EBBs), represented by an rtl_ssa::ebb_info. Extended basic blocks contain one or more basic blocks. They have the property that if a block \( bby \) comes immediately after a block \( bbx \) in an EBB, then \( bby \) can only be reached by \( bbx \); in other words, \( bbx \) is the sole predecessor of \( bby \).

Each extended basic block starts with an artificial “phi node” instruction. This instruction defines all phi nodes for the EBB (see Section 14.21.6 [RTL SSA Phi Nodes], page 320). (Individual blocks in an EBB do not need phi nodes because their live values can only come from one source.)

The contents of a function are therefore represented using a four-level hierarchy:

- functions (rtl_ssa::function_info), which contain ...
- extended basic blocks (rtl_ssa::ebb_info), which contain ...
- basic blocks (rtl_ssa::bb_info), which contain ...
- instructions (rtl_ssa::insn_info)

In dumps, a basic block is identified as \( bb_n \), where \( n \) is the index of the associated CFG basic_block structure. An EBB is in turn identified by the index of its first block. For example, an EBB that contains ‘bb10’, bb5, bb6 and bb9 is identified as ebb10.

14.21.4 RTL SSA Resources

The RTL SSA form tracks two types of “resource”: registers and memory. Each hard and pseudo register is a separate resource. Memory is a single unified resource, like it is in GIMPLE (see Chapter 12 [GIMPLE], page 213).

Each resource has a unique identifier. The unique identifier for a register is simply its register number. The unique identifier for memory is a special register number called MEM_REGNO.

\(^2\) Note that this excludes non-instruction things like notes and barriers that also appear in the chain of RTL instructions.
Since resource numbers so closely match register numbers, it is sometimes convenient to refer to them simply as register numbers, or “regnos” for short. However, the RTL SSA form also provides an abstraction of resources in the form of `rtl_ssa::resource_info`. This is a lightweight class that records both the regno of a resource and the `machine_mode` that the resource has (see Section 14.6 [Machine Modes], page 275). It has functions for testing whether a resource is a register or memory. In principle it could be extended to other kinds of resource in future.

### 14.21.5 RTL SSA Register and Memory Accesses

In the RTL SSA form, most reads or writes of a resource are represented as a `rtl_ssa::access_info`. These `rtl_ssa::access_info`s are organized into the following class hierarchy:

```plaintext
rtl_ssa::access_info
  |          
  +-- rtl_ssa::use_info
  |          
  +-- rtl_ssa::def_info
     |          
     +-- rtl_ssa::clobber_info
     |          
     +-- rtl_ssa::set_info
        |          
        +-- rtl_ssa::phi_info
```

A `rtl_ssa::use_info` represents a read or use of a resource and a `rtl_ssa::def_info` represents a write or definition of a resource. As in the main RTL representation, there are two basic types of definition: clobbers and sets. The difference is that a clobber leaves the register with an unspecified value that cannot be used or relied on by later instructions, while a set leaves the register with a known value that later instructions could use if they wanted to. A `rtl_ssa::clobber_info` represents a clobber and a `rtl_ssa::set_info` represent a set.

Each `rtl_ssa::use_info` records which single `rtl_ssa::set_info` provides the value of the resource; this is null if the resource is completely undefined at the point of use. Each `rtl_ssa::set_info` in turn records all the `rtl_ssa::use_info`s that use its value.

If a value of a resource can come from multiple sources, a `rtl_ssa::phi_info` brings those multiple sources together into a single definition (see Section 14.21.6 [RTL SSA Phi Nodes], page 320).

### 14.21.6 RTL SSA Phi Nodes

If a resource is live on entry to an extended basic block and if the resource’s value can come from multiple sources, the extended basic block has a “phi node” that collects together these multiple sources. The phi node conceptually has one input for each incoming edge of the extended basic block, with the input specifying the value of the resource on that edge. For example, suppose a function contains the following RTL:

```plaintext
;; Basic block bb3
...
(set (reg:SI R1) (const_int 0)) ;; A
```

The exceptions are call clobbers, which are generally represented separately. See the comment above `rtl_ssa::insn_info` for details.
(set (pc) (label_ref bb5))

;;; Basic block bb4
...
(set (reg:SI R1) (const_int 1)) ;; B
;;; Fall through

;;; Basic block bb5
;;; preds: bb3, bb4
;;; live in: R1 ...
(code_label bb5)
...
(set (reg:SI R2)
    (plus:SI (reg:SI R1) ...)) ;; C

The value of R1 on entry to block 5 can come from either A or B. The extended basic block that contains block 5 would therefore have a phi node with two inputs: the first input would have the value of R1 defined by A and the second input would have the value of R1 defined by B. This phi node would then provide the value of R1 for C (assuming that R1 does not change again between the start of block 5 and C).

Since RTL is not a "native" SSA representation, these phi nodes simply collect together definitions that already exist. Each input to a phi node for a resource R is itself a definition of resource R (or is null if the resource is completely undefined for a particular incoming edge). This is in contrast to a native SSA representation like GIMPLE, where the phi inputs can be arbitrary expressions. As a result, RTL SSA phi nodes never involve "hidden" moves: all moves are instead explicit.

Phi nodes are represented as a rtl_ssa::phi_node. Each input to a phi node is represented as an rtl_ssa::use_info.

14.21.7 RTL SSA Access Lists

All the definitions of a resource are chained together in reverse postorder. In general, this list can contain an arbitrary mix of both sets (rtl_ssa::set_info) and clobbers (rtl_ssa::clobber_info). However, it is often useful to skip over all intervening clobbers of a resource in order to find the next set. The list is constructed in such a way that this can be done in amortized constant time.

All uses (rtl_ssa::use_info) of a given set are also chained together into a list. This list of uses is divided into three parts:
1. uses by "real" nondebug instructions (see [real RTL SSA insns], page 319)
2. uses by real debug instructions
3. uses by phi nodes (see Section 14.21.6 [RTL SSA Phi Nodes], page 320)

The first and second parts individually follow reverse postorder. The third part has no particular order.

The last use by a real nondebug instruction always comes earlier in the reverse postorder than the next definition of the resource (if any). This means that the accesses follow a linear sequence of the form:
• first definition of resource R
  • first use by a real nondebug instruction of the first definition of resource R
  • ...
last use by a real nondebug instruction of the first definition of resource R

second definition of resource R
  
  first use by a real nondebug instruction of the second definition of resource R
  
  . . .
  
  last use by a real nondebug instruction of the second definition of resource R
  
  . . .

last definition of resource R
  
  first use by a real nondebug instruction of the last definition of resource R
  
  . . .
  
  last use by a real nondebug instruction of the last definition of resource R

(Note that clobbers never have uses; only sets do.)

This linear view is easy to achieve when there is only a single definition of a resource, which is commonly true for pseudo registers. However, things are more complex if code has a structure like the following:

```c
// ebb2, bb2
R = va; // A
if (…) {
  // ebb2, bb3
  use1 (R); // B
  …
  R = vc; // C
} else {
  // ebb4, bb4
  use2 (R); // D
}
```

The list of accesses would begin as follows:

- definition of R by A
  - use of A’s definition of R by B
  - definition of R by C

The next access to R is in D, but the value of R that D uses comes from A rather than C.

This is resolved by adding a phi node for `ebb4`. All inputs to this phi node have the same value, which in the example above is A’s definition of R. In other circumstances, it would not be necessary to create a phi node when all inputs are equal, so these phi nodes are referred to as “degenerate” phi nodes.

The full list of accesses to R is therefore:

- definition of R by A
  - use of A’s definition of R by B
  - definition of R by C
  - definition of R by ebb4’s phi instruction, with the input coming from A
    - use of the ebb4’s R phi definition of R by B
Note that A’s definition is also used by ebb4’s phi node, but this use belongs to the third part of the use list described above and so does not form part of the linear sequence.

It is possible to “look through” any degenerate phi to the ultimate definition using the function `look_through_degenerate_phi`. Note that the input to a degenerate phi is never itself provided by a degenerate phi.

At present, the SSA form takes this principle one step further and guarantees that, for any given resource res, one of the following is true:

- The resource has a single definition `def`, which is not a phi node. Excluding uses of undefined registers, all uses of res by real nondebug instructions use the value provided by `def`.
- Excluding uses of undefined registers, all uses of res use values provided by definitions that occur earlier in the same extended basic block. These definitions might come from phi nodes or from real instructions.

### 14.21.8 Using the RTL SSA framework to change instructions

There are various routines that help to change a single RTL instruction or a group of RTL instructions while keeping the RTL SSA form up-to-date. This section first describes the process for changing a single instruction, then goes on to describe the differences when changing multiple instructions.

#### 14.21.8.1 Changing One RTL SSA Instruction

Before making a change, passes should first use a statement like the following:

```c++
auto attempt = crtl->ssa->new_change_attempt();
```

Here, `attempt` is an RAII object that should remain in scope for the entire change attempt. It automatically frees temporary memory related to the changes when it goes out of scope.

Next, the pass should create an `rtl_ssa::insn_change` object for the instruction that it wants to change. This object specifies several things:

- what the instruction’s new list of uses should be (`new_uses`). By default this is the same as the instruction’s current list of uses.
- what the instruction’s new list of definitions should be (`new_defs`). By default this is the same as the instruction’s current list of definitions.
- where the instruction should be located (`move_range`). This is a range of instructions after which the instruction could be placed, represented as an `rtl_ssa::insn_range`. By default the instruction must remain at its current position.

If a pass was attempting to change all these properties of an instruction `insn`, it might do something like this:

```c++
rtl_ssa::insn_change change (insn);
change.new_defs = ...;
change.new_uses = ...;
change.move_range = ...;
```

This `rtl_ssa::insn_change` only describes something that the pass might do; at this stage, nothing has actually changed.

As noted above, the default `move_range` requires the instruction to remain where it is. At the other extreme, it is possible to allow the instruction to move anywhere within its
extended basic block, provided that all the new uses and definitions can be performed at
the new location. The way to do this is:

    change.move_range = insn->ebb ()->insn_range ();

In either case, the next step is to make sure that move range is consistent with the new
uses and definitions. The way to do this is:

    if (!rtl_ssa::restrict_movement (change))
      return false;

This function tries to limit move_range to a range of instructions at which new_uses
and new_defs can be correctly performed. It returns true on success or false if no suitable
location exists.

The pass should also tentatively change the pattern of the instruction to whatever form
the pass wants the instruction to have. This should use the facilities provided by ‘recog.c’.
For example:

    rtl_insn *rtl = insn->rtl ();
    insn_change_watermark watermark;
    validate_change (rtl, &PATTERN (rtl), new_pat, 1);

will tentatively replace insn’s pattern with new_pat.

These changes and the construction of the rtl_ssa::insn_change can happen in either
order or be interleaved.

After the tentative changes to the instruction are complete, the pass should check whether
the new pattern matches a target instruction or satisfies the requirements of an inline asm:

    if (!rtl_ssa::recog (change))
      return false;

This step might change the instruction pattern further in order to make it match. It
might also add new definitions or restrict the range of the move. For example, if the new
pattern did not match in its original form, but could be made to match by adding a clobber
of the flags register, rtl_ssa::recog will check whether the flags register is free at an
appropriate point. If so, it will add a clobber of the flags register to new_defs and restrict
move_range to the locations at which the flags register can be safely clobbered.

Even if the proposed new instruction is valid according to rtl_ssa::recog, the change
might not be worthwhile. For example, when optimizing for speed, the new instruction
might turn out to be slower than the original one. When optimizing for size, the new
instruction might turn out to be bigger than the original one.

Passes should check for this case using change_is_worthwhile. For example:

    if (!rtl_ssa::change_is_worthwhile (change))
      return false;

If the change passes this test too then the pass can perform the change using:

    confirm_change_group ();
    crtl->ssa->change_insn (change);

Putting all this together, the change has the following form:

    auto attempt = crtl->ssa->new_change_attempt ();

    rtl_ssa::insn_change change (insn);
    change.new_defs = ...;
    change.new_uses = ...;
    change.move_range = ...;
if (!rtl_ssa::restrict_movement (change))
    return false;

insn_change_watermark watermark;
// Use validate_change etc. to change INSN’s pattern.
...
if (!rtl_ssa::recog (change)
    || !rtl_ssa::change_is_worthwhile (change))
    return false;

confirm_change_group ();
crtl->ssa->change_insn (change);

14.21.8.2 Changing Multiple RTL SSA Instructions

The process for changing multiple instructions is similar to the process for changing single instructions (see Section 14.21.8.1 [Changing One RTL SSA Instruction], page 323). The pass should again start the change attempt with:

    auto attempt = crtl->ssa->new_change_attempt ();

    and keep attempt in scope for the duration of the change attempt. It should then construct an rtl_ssa::insn_change for each change that it wants to make.

After this, it should combine the changes into a sequence of rtl_ssa::insn_change pointers. This sequence must be in reverse postorder; the instructions will remain strictly in the order that the sequence specifies.

For example, if a pass is changing exactly two instructions, it might do:

    rtl_ssa::insn_change *changes[] = { &change1, change2 };

    where change1’s instruction must come before change2’s. Alternatively, if the pass is changing a variable number of instructions, it might build up the sequence in a vec<rtl_ssa::insn_change >.

By default, rtl_ssa::restrict_movement assumes that all instructions other than the one passed to it will remain in their current positions and will retain their current uses and definitions. When changing multiple instructions, it is usually more effective to ignore the other instructions that are changing. The sequencing described above ensures that the changing instructions remain in the correct order with respect to each other. The way to do this is:

    if (!rtl_ssa::restrict_movement (change, insn_is_changing (changes)))
        return false;

Similarly, when rtl_ssa::restrict_movement is detecting whether a register can be clobbered, it by default assumes that all other instructions will remain in their current positions and retain their current form. It is again more effective to ignore changing instructions (which might, for example, no longer need to clobber the flags register). The way to do this is:

    if (!rtl_ssa::recog (change, insn_is_changing (changes)))
        return false;

When changing multiple instructions, the important question is usually not whether each individual change is worthwhile, but whether the changes as a whole are worthwhile. The way to test this is:

    if (!rtl_ssa::changes_are_worthwhile (changes))
        return false;
The process for changing single instructions makes sure that one `rtl_ssa::insn_change` in isolation is valid. But when changing multiple instructions, it is also necessary to test whether the sequence as a whole is valid. For example, it might be impossible to satisfy all of the `move_ranges` at once.

Therefore, once the pass has a sequence of changes that are individually correct, it should use:

```c
if (!crtl->ssa->verify_insn_changes (changes))
    return false;
```
to check whether the sequence as a whole is valid. If all checks pass, the final step is:

```c
confirm_change_group ();
crtl->ssa->change_insns (changes);
```

Putting all this together, the process for a two-instruction change is:

```c
auto attempt = crtl->ssa->new_change_attempt ();

rtl_ssa::insn_change change (insn1);
change1.new_defs = ...;
change1.new_uses = ...;
change1.move_range = ...;

rtl_ssa::insn_change change (insn2);
change2.new_defs = ...;
change2.new_uses = ...;
change2.move_range = ...;

rtl_ssa::insn_change *changes[] = { &change1, change2 };

auto is_changing = insn_is_changing (changes);
if (!rtl_ssa::restrict_movement (change1, is_changing)
     || !rtl_ssa::restrict_movement (change2, is_changing))
    return false;

insn_change_watermark watermark;
// Use validate_change etc. to change INSN1’s and INSN2’s patterns.
...
if (!rtl_ssa::recog (change1, is_changing)
    || !rtl_ssa::recog (change2, is_changing)
    || !rtl_ssa::changes_are_worthwhile (changes)
    || !crtl->ssa->verify_insn_changes (changes))
    return false;

confirm_change_group ();
crtl->ssa->change_insns (changes);
```

### 14.22 Structure Sharing Assumptions

The compiler assumes that certain kinds of RTL expressions are unique; there do not exist two distinct objects representing the same value. In other cases, it makes an opposite assumption: that no RTL expression object of a certain kind appears in more than one place in the containing structure.

These assumptions refer to a single function; except for the RTL objects that describe global variables and external functions, and a few standard objects such as small integer constants, no RTL objects are common to two functions.
• Each pseudo-register has only a single `reg` object to represent it, and therefore only a single machine mode.
• For any symbolic label, there is only one `symbol_ref` object referring to it.
• All `const_int` expressions with equal values are shared.
• All `const_poly_int` expressions with equal modes and values are shared.
• There is only one `pc` expression.
• There is only one `const_double` expression with value 0 for each floating point mode. Likewise for values 1 and 2.
• There is only one `const_vector` expression with value 0 for each vector mode, be it an integer or a double constant vector.
• No `label_ref` or `scratch` appears in more than one place in the RTL structure; in other words, it is safe to do a tree-walk of all the insns in the function and assume that each time a `label_ref` or `scratch` is seen it is distinct from all others that are seen.
• Only one `mem` object is normally created for each static variable or stack slot, so these objects are frequently shared in all the places they appear. However, separate but equal objects for these variables are occasionally made.
• When a single `asm` statement has multiple output operands, a distinct `asm_operands` expression is made for each output operand. However, these all share the vector which contains the sequence of input operands. This sharing is used later on to test whether two `asm_operands` expressions come from the same statement, so all optimizations must carefully preserve the sharing if they copy the vector at all.
• No RTL object appears in more than one place in the RTL structure except as described above. Many passes of the compiler rely on this by assuming that they can modify RTL objects in place without unwanted side-effects on other insns.
• During initial RTL generation, shared structure is freely introduced. After all the RTL for a function has been generated, all shared structure is copied by `unshare_all_rtl` in `emit-rtl.c`, after which the above rules are guaranteed to be followed.
• During the combiner pass, shared structure within an insn can exist temporarily. However, the shared structure is copied before the combiner is finished with the insn. This is done by calling `copy_rtx_if_shared`, which is a subroutine of `unshare_all_rtl`.

### 14.23 Reading RTL

To read an RTL object from a file, call `read_rtx`. It takes one argument, a stdio stream, and returns a single RTL object. This routine is defined in `read-rtl.c`. It is not available in the compiler itself, only the various programs that generate the compiler back end from the machine description.

People frequently have the idea of using RTL stored as text in a file as an interface between a language front end and the bulk of GCC. This idea is not feasible.

GCC was designed to use RTL internally only. Correct RTL for a given program is very dependent on the particular target machine. And the RTL does not contain all the information about the program.

The proper way to interface GCC to a new language front end is with the “tree” data structure, described in the files `tree.h` and `tree.def`. The documentation for this structure (see Chapter 11 [GENERIC], page 165) is incomplete.
15 Control Flow Graph

A control flow graph (CFG) is a data structure built on top of the intermediate code representation (the RTL or GIMPLE instruction stream) abstracting the control flow behavior of a function that is being compiled. The CFG is a directed graph where the vertices represent basic blocks and edges represent possible transfer of control flow from one basic block to another. The data structures used to represent the control flow graph are defined in ‘basic-block.h’.

In GCC, the representation of control flow is maintained throughout the compilation process, from constructing the CFG early in pass_build_cfg to pass_free_cfg (see ‘passes.def’). The CFG takes various different modes and may undergo extensive manipulations, but the graph is always valid between its construction and its release. This way, transfer of information such as data flow, a measured profile, or the loop tree, can be propagated through the passes pipeline, and even from GIMPLE to RTL.

Often the CFG may be better viewed as integral part of instruction chain, than structure built on the top of it. Updating the compiler’s intermediate representation for instructions cannot be easily done without proper maintenance of the CFG simultaneously.

15.1 Basic Blocks

A basic block is a straight-line sequence of code with only one entry point and only one exit. In GCC, basic blocks are represented using the basic_block data type.

Special basic blocks represent possible entry and exit points of a function. These blocks are called ENTRY_BLOCK_PTR and EXIT_BLOCK_PTR. These blocks do not contain any code.

The BASIC_BLOCK array contains all basic blocks in an unspecified order. Each basic_block structure has a field that holds a unique integer identifier index that is the index of the block in the BASIC_BLOCK array. The total number of basic blocks in the function is n_basic_blocks. Both the basic block indices and the total number of basic blocks may vary during the compilation process, as passes reorder, create, duplicate, and destroy basic blocks. The index for any block should never be greater than last_basic_block. The indices 0 and 1 are special codes reserved for ENTRY_BLOCK and EXIT_BLOCK, the indices of ENTRY_BLOCK_PTR and EXIT_BLOCK_PTR.

Two pointer members of the basic_block structure are the pointers next_bb and prev_bb. These are used to keep doubly linked chain of basic blocks in the same order as the underlying instruction stream. The chain of basic blocks is updated transparently by the provided API for manipulating the CFG. The macro FOR_EACH_BB can be used to visit all the basic blocks in lexicographical order, except ENTRY_BLOCK and EXIT_BLOCK. The macro FOR_ALL_BB also visits all basic blocks in lexicographical order, including ENTRY_BLOCK and EXIT_BLOCK.

The functions post_order_compute and inverted_post_order_compute can be used to compute topological orders of the CFG. The orders are stored as vectors of basic block indices. The BASIC_BLOCK array can be used to iterate each basic block by index. Dominator traversals are also possible using walk_dominator_tree. Given two basic blocks A and B, block A dominates block B if A is always executed before B.

Each basic_block also contains pointers to the first instruction (the head) and the last instruction (the tail) or end of the instruction stream contained in a basic block. In fact,
since the basic_block data type is used to represent blocks in both major intermediate representations of GCC (GIMPLE and RTL), there are pointers to the head and end of a basic block for both representations, stored in intermediate representation specific data in the il field of struct basic_block_def.

For RTL, these pointers are BB_HEAD and BB_END.

In the RTL representation of a function, the instruction stream contains not only the “real” instructions, but also notes or insn notes (to distinguish them from reg notes). Any function that moves or duplicates the basic blocks needs to take care of updating of these notes. Many of these notes expect that the instruction stream consists of linear regions, so updating can sometimes be tedious. All types of insn notes are defined in ‘insn-notes.def’.

In the RTL function representation, the instructions contained in a basic block always follow a NOTE_INSN_BASIC_BLOCK, but zero or more CODE_LABEL nodes can precede the block note. A basic block ends with a control flow instruction or with the last instruction before the next CODE_LABEL or NOTE_INSN_BASIC_BLOCK. By definition, a CODE_LABEL cannot appear in the middle of the instruction stream of a basic block.

In addition to notes, the jump table vectors are also represented as “pseudo-instructions” inside the insn stream. These vectors never appear in the basic block and should always be placed just after the table jump instructions referencing them. After removing the table jump it is often difficult to eliminate the code computing the address and referencing the vector, so cleaning up these vectors is postponed until after liveness analysis. Thus the jump table vectors may appear in the insn stream unreferenced and without any purpose. Before any edge is made fall-thru, the existence of such construct in the way needs to be checked by calling can_fallthru function.

For the GIMPLE representation, the PHI nodes and statements contained in a basic block are in a gimple_seq pointed to by the basic block intermediate language specific pointers. Abstract containers and iterators are used to access the PHI nodes and statements in a basic blocks. These iterators are called GIMPLE statement iterators (GSIs). Grep for ‘gsi’ in the various ‘gimple-*’ and ‘tree-*’ files. There is a gimple_stmt_iterator type for iterating over all kinds of statement, and a gphi_iterator subclass for iterating over PHI nodes. The following snippet will pretty-print all PHI nodes the statements of the current function in the GIMPLE representation.

```c
for (p1 = gsi_start_phis (bb); !gsi_end_p (p1); gsi_next (&p1))
{
  gphi *phi = p1.phi ();
  print_gimple_stmt (dump_file, phi, 0, TDF_SLIM);
}
for (si = gsi_start_bb (bb); !gsi_end_p (si); gsi_next (&si))
{
  gimple stmt = gsi_stmt (si);
  print_gimple_stmt (dump_file, stmt, 0, TDF_SLIM);
}
```
15.2 Edges

Edges represent possible control flow transfers from the end of some basic block A to the head of another basic block B. We say that A is a predecessor of B, and B is a successor of A. Edges are represented in GCC with the edge data type. Each edge acts as a link between two basic blocks: The src member of an edge points to the predecessor basic block of the dest basic block. The members preds and succs of the basic_block data type point to type-safe vectors of edges to the predecessors and successors of the block.

When walking the edges in an edge vector, edge iterators should be used. Edge iterators are constructed using the edge_iterator data structure and several methods are available to operate on them:

- **ei_start** This function initializes an edge_iterator that points to the first edge in a vector of edges.
- **ei_last** This function initializes an edge_iterator that points to the last edge in a vector of edges.
- **ei_end_p** This predicate is true if an edge_iterator represents the last edge in an edge vector.
- **ei_one_before_end_p** This predicate is true if an edge_iterator represents the second last edge in an edge vector.
- **ei_next** This function takes a pointer to an edge_iterator and makes it point to the next edge in the sequence.
- **ei_prev** This function takes a pointer to an edge_iterator and makes it point to the previous edge in the sequence.
- **ei_edge** This function returns the edge currently pointed to by an edge_iterator.
- **ei_safe_edge** This function returns the edge currently pointed to by an edge_iterator, but returns NULL if the iterator is pointing at the end of the sequence. This function has been provided for existing code makes the assumption that a NULL edge indicates the end of the sequence.

The convenience macro FOR_EACH_EDGE can be used to visit all of the edges in a sequence of predecessor or successor edges. It must not be used when an element might be removed during the traversal, otherwise elements will be missed. Here is an example of how to use the macro:

```c
edge e;
edge_iterator ei;

FOR_EACH_EDGE (e, ei, bb->succs)
{
    if (e->flags & EDGE_FALLTHRU)
        break;
}
```

There are various reasons why control flow may transfer from one block to another. One possibility is that some instruction, for example a CODE_LABEL, in a linearized instruction
stream just always starts a new basic block. In this case a *fall-thru* edge links the basic block to the first following basic block. But there are several other reasons why edges may be created. The *flags* field of the *edge* data type is used to store information about the type of edge we are dealing with. Each edge is of one of the following types:

**jump**
No type flags are set for edges corresponding to jump instructions. These edges are used for unconditional or conditional jumps and in RTL also for table jumps. They are the easiest to manipulate as they may be freely redirected when the flow graph is not in SSA form.

**fall-thru**
Fall-thru edges are present in case where the basic block may continue execution to the following one without branching. These edges have the *EDGE_FALLTHRU* flag set. Unlike other types of edges, these edges must come into the basic block immediately following in the instruction stream. The function *force_nonfallthru* is available to insert an unconditional jump in the case that redirection is needed. Note that this may require creation of a new basic block.

**exception handling**
Exception handling edges represent possible control transfers from a trapping instruction to an exception handler. The definition of “trapping” varies. In C++, only function calls can throw, but for Ada exceptions like division by zero or segmentation fault are defined and thus each instruction possibly throwing this kind of exception needs to be handled as control flow instruction. Exception edges have the *EDGE_ABNORMAL* and *EDGE_EH* flags set.

When updating the instruction stream it is easy to change possibly trapping instruction to non-trapping, by simply removing the exception edge. The opposite conversion is difficult, but should not happen anyway. The edges can be eliminated via *purge_dead_edges* call.

In the RTL representation, the destination of an exception edge is specified by *REG_EH_REGION* note attached to the insn. In case of a trapping call the *EDGE_ABNORMAL_CALL* flag is set too. In the *GIMPLE* representation, this extra flag is not set.

In the RTL representation, the predicate *may_trap_p* may be used to check whether instruction still may trap or not. For the tree representation, the *tree_could_trap_p* predicate is available, but this predicate only checks for possible memory traps, as in dereferencing an invalid pointer location.

**sibling calls**
Sibling calls or tail calls terminate the function in a non-standard way and thus an edge to the exit must be present. *EDGE_SIBCALL* and *EDGE_ABNORMAL* are set in such case. These edges only exist in the RTL representation.

**computed jumps**
Computed jumps contain edges to all labels in the function referenced from the code. All those edges have *EDGE_ABNORMAL* flag set. The edges used to represent computed jumps often cause compile time performance problems, since functions consisting of many taken labels and many computed jumps may have very dense flow graphs, so these edges need to be handled with special
care. During the earlier stages of the compilation process, GCC tries to avoid such dense flow graphs by factoring computed jumps. For example, given the following series of jumps,

```c
goto *x;
[ ... ]

goto *x;
[ ... ]

goto *x;
[ ... ]
```

factoring the computed jumps results in the following code sequence which has a much simpler flow graph:

```c
goto y;
[ ... ]

goto y;
[ ... ]

goto y;
[ ... ]
```

```
y:
goto *x;
```

However, the classic problem with this transformation is that it has a runtime cost in there resulting code: An extra jump. Therefore, the computed jumps are un-factored in the later passes of the compiler (in the pass called `pass_duplicate_computed_gotos`). Be aware of that when you work on passes in that area. There have been numerous examples already where the compile time for code with unfactored computed jumps caused some serious headaches.

### nonlocal goto handlers

GCC allows nested functions to return into caller using a `goto` to a label passed to as an argument to the callee. The labels passed to nested functions contain special code to cleanup after function call. Such sections of code are referred to as “nonlocal goto receivers”. If a function contains such nonlocal goto receivers, an edge from the call to the label is created with the `EDGE_ABNORMAL` and `EDGE_ABNORMAL_CALL` flags set.

### function entry points

By definition, execution of function starts at basic block 0, so there is always an edge from the `ENTRY_BLOCK_PTR` to basic block 0. There is no GIMPLE representation for alternate entry points at this moment. In RTL, alternate entry points are specified by `CODE_LABEL` with `LABEL_ALTERNATE_NAME` defined. This feature is currently used for multiple entry point prologues and is limited to post-reload passes only. This can be used by back-ends to emit alternate prologues for functions called from different contexts. In future full support for multiple entry functions defined by Fortran 90 needs to be implemented.

### function exits

In the pre-reload representation a function terminates after the last instruction in the insn chain and no explicit return instructions are used. This corresponds
to the fall-thru edge into exit block. After reload, optimal RTL epilogues are used that use explicit (conditional) return instructions that are represented by edges with no flags set.

15.3 Profile information

In many cases a compiler must make a choice whether to trade speed in one part of code for speed in another, or to trade code size for code speed. In such cases it is useful to know information about how often some given block will be executed. That is the purpose for maintaining profile within the flow graph. GCC can handle profile information obtained through profile feedback, but it can also estimate branch probabilities based on statics and heuristics.

The feedback based profile is produced by compiling the program with instrumentation, executing it on a train run and reading the numbers of executions of basic blocks and edges back to the compiler while re-compiling the program to produce the final executable. This method provides very accurate information about where a program spends most of its time on the train run. Whether it matches the average run of course depends on the choice of train data set, but several studies have shown that the behavior of a program usually changes just marginally over different data sets.

When profile feedback is not available, the compiler may be asked to attempt to predict the behavior of each branch in the program using a set of heuristics (see \texttt{predict.def} for details) and compute estimated frequencies of each basic block by propagating the probabilities over the graph.

Each basic block contains two integer fields to represent profile information: \texttt{frequency} and \texttt{count}. The \texttt{frequency} is an estimation how often is basic block executed within a function. It is represented as an integer scaled in the range from 0 to \texttt{BB_FREQ_BASE}. The most frequently executed basic block in function is initially set to \texttt{BB_FREQ_BASE} and the rest of frequencies are scaled accordingly. During optimization, the frequency of the most frequent basic block can both decrease (for instance by loop unrolling) or grow (for instance by cross-jumping optimization), so scaling sometimes has to be performed multiple times.

The \texttt{count} contains hard-counted numbers of execution measured during training runs and is nonzero only when profile feedback is available. This value is represented as the host’s widest integer (typically a 64 bit integer) of the special type \texttt{gcov_type}.

Most optimization passes can use only the frequency information of a basic block, but a few passes may want to know hard execution counts. The frequencies should always match the counts after scaling, however during updating of the profile information numerical error may accumulate into quite large errors.

Each edge also contains a branch probability field: an integer in the range from 0 to \texttt{REG_BR_PROB_BASE}. It represents probability of passing control from the end of the src basic block to the dest basic block, i.e. the probability that control will flow along this edge. The \texttt{EDGE_FREQUENCY} macro is available to compute how frequently a given edge is taken. There is a \texttt{count} field for each edge as well, representing same information as for a basic block.

The basic block frequencies are not represented in the instruction stream, but in the RTL representation the edge frequencies are represented for conditional jumps (via the \texttt{REG_BR_}
The probability that control flow arrives via a given edge to its destination basic block is called reverse probability and is not directly represented, but it may be easily computed from frequencies of basic blocks.

Updating profile information is a delicate task that can unfortunately not be easily integrated with the CFG manipulation API. Many of the functions and hooks to modify the CFG, such as \texttt{redirect_edge_and_branch}, do not have enough information to easily update the profile, so updating it is in the majority of cases left up to the caller. It is difficult to uncover bugs in the profile updating code, because they manifest themselves only by producing worse code, and checking profile consistency is not possible because of numeric error accumulation. Hence special attention needs to be given to this issue in each pass that modifies the CFG.

It is important to point out that \texttt{REG_BR_PROB_BASE} and \texttt{BB_FREQ_BASE} are both set low enough to be possible to compute second power of any frequency or probability in the flow graph, it is not possible to even square the \texttt{count} field, as modern CPUs are fast enough to execute $2^{32}$ operations quickly.

\section*{15.4 Maintaining the CFG}

An important task of each compiler pass is to keep both the control flow graph and all profile information up-to-date. Reconstruction of the control flow graph after each pass is not an option, since it may be very expensive and lost profile information cannot be reconstructed at all.

GCC has two major intermediate representations, and both use the \texttt{basic_block} and \texttt{edge} data types to represent control flow. Both representations share as much of the CFG maintenance code as possible. For each representation, a set of hooks is defined so that each representation can provide its own implementation of CFG manipulation routines when necessary. These hooks are defined in ‘\texttt{cfghooks.h}’. There are hooks for almost all common CFG manipulations, including block splitting and merging, edge redirection and creating and deleting basic blocks. These hooks should provide everything you need to maintain and manipulate the CFG in both the RTL and \texttt{GIMPLE} representation.

At the moment, the basic block boundaries are maintained transparently when modifying instructions, so there rarely is a need to move them manually (such as in case someone wants to output instruction outside basic block explicitly).

In the RTL representation, each instruction has a \texttt{BLOCK_FOR_INSN} value that represents pointer to the basic block that contains the instruction. In the \texttt{GIMPLE} representation, the function \texttt{gimple_bb} returns a pointer to the basic block containing the queried statement.

When changes need to be applied to a function in its \texttt{GIMPLE} representation, \texttt{GIMPLE statement iterators} should be used. These iterators provide an integrated abstraction of the flow graph and the instruction stream. Block statement iterators are constructed using the \texttt{gimple_stmt_iterator} data structure and several modifiers are available, including the following:

\texttt{gsi_start}

This function initializes a \texttt{gimple_stmt_iterator} that points to the first non-empty statement in a basic block.
gsi_last  This function initializes a `gimple_stmt_iterator` that points to the last statement in a basic block.

gsi_end_p  This predicate is true if a `gimple_stmt_iterator` represents the end of a basic block.

gsi_next  This function takes a `gimple_stmt_iterator` and makes it point to its successor.

gsi_prev  This function takes a `gimple_stmt_iterator` and makes it point to its predecessor.

gsi_insert_after  This function inserts a statement after the `gimple_stmt_iterator` passed in. The final parameter determines whether the statement iterator is updated to point to the newly inserted statement, or left pointing to the original statement.

gsi_insert_before  This function inserts a statement before the `gimple_stmt_iterator` passed in. The final parameter determines whether the statement iterator is updated to point to the newly inserted statement, or left pointing to the original statement.

gsi_remove  This function removes the `gimple_stmt_iterator` passed in and rechains the remaining statements in a basic block, if any.

In the RTL representation, the macros `BB_HEAD` and `BB_END` may be used to get the head and end `rtx` of a basic block. No abstract iterators are defined for traversing the insn chain, but you can just use `NEXT_INSN` and `PREV_INSN` instead. See Section 14.19 [Insns], page 308.

Usually a code manipulating pass simplifies the instruction stream and the flow of control, possibly eliminating some edges. This may for example happen when a conditional jump is replaced with an unconditional jump. Updating of edges is not transparent and each optimization pass is required to do so manually. However only few cases occur in practice. The pass may call `purge_dead_edges` on a given basic block to remove superfluous edges, if any.

Another common scenario is redirection of branch instructions, but this is best modeled as redirection of edges in the control flow graph and thus use of `redirect_edge_and_branch` is preferred over more low level functions, such as `redirect_jump` that operate on RTL chain only. The CFG hooks defined in `cfghooks.h` should provide the complete API required for manipulating and maintaining the CFG.

It is also possible that a pass has to insert control flow instruction into the middle of a basic block, thus creating an entry point in the middle of the basic block, which is impossible by definition: The block must be split to make sure it only has one entry point, i.e. the head of the basic block. The CFG hook `split_block` may be used when an instruction in the middle of a basic block has to become the target of a jump or branch instruction.

For a global optimizer, a common operation is to split edges in the flow graph and insert instructions on them. In the RTL representation, this can be easily done using the `insert_insn_on_edge` function that emits an instruction “on the edge”, caching it for a later `commit_edge_insertions` call that will take care of moving the inserted instructions.
off the edge into the instruction stream contained in a basic block. This includes the 
creation of new basic blocks where needed. In the GIMPLE representation, the equivalent 
functions are gsi_insert_on_edge which inserts a block statement iterator on an edge, 
and gsi_commit_edge_inserts which flushes the instruction to actual instruction stream. 

While debugging the optimization pass, the verify_flow_info function may be useful 
to find bugs in the control flow graph updating code.

15.5 Liveness information

Liveness information is useful to determine whether some register is “live” at given point 
of program, i.e. that it contains a value that may be used at a later point in the program. 
This information is used, for instance, during register allocation, as the pseudo registers 
only need to be assigned to a unique hard register or to a stack slot if they are live. The 
hard registers and stack slots may be freely reused for other values when a register is dead. 

Liveness information is available in the back end starting with pass_df_initialize and 
ending with pass_df_finish. Three flavors of live analysis are available: With LR, it is 
possible to determine at any point P in the function if the register may be used on some 
path from P to the end of the function. With UR, it is possible to determine if there is a path 
from the beginning of the function to P that defines the variable. LIVE is the intersection 
of the LR and UR and a variable is live at P if there is both an assignment that reaches it 
from the beginning of the function and a use that can be reached on some path from P to 
the end of the function.

In general LIVE is the most useful of the three. The macros DF_[LR, UR, LIVE]_[IN, OUT] 
can be used to access this information. The macros take a basic block number and return a 
bitmap that is indexed by the register number. This information is only guaranteed to be 
up to date after calls are made to df_analyze. See the file df-core.c for details on using 
the dataflow.

The liveness information is stored partly in the RTL instruction stream and partly in the 
flow graph. Local information is stored in the instruction stream: Each instruction may 
contain REG_DEAD notes representing that the value of a given register is no longer needed, 
or REG_UNUSED notes representing that the value computed by the instruction is never used. 
The second is useful for instructions computing multiple values at once.
16 Analysis and Representation of Loops

GCC provides extensive infrastructure for work with natural loops, i.e., strongly connected components of CFG with only one entry block. This chapter describes representation of loops in GCC, both on GIMPLE and in RTL, as well as the interfaces to loop-related analyses (induction variable analysis and number of iterations analysis).

16.1 Loop representation

This chapter describes the representation of loops in GCC, and functions that can be used to build, modify and analyze this representation. Most of the interfaces and data structures are declared in `<cfgloop.h>`. Loop structures are analyzed and this information disposed or updated at the discretion of individual passes. Still most of the generic CFG manipulation routines are aware of loop structures and try to keep them up-to-date. By this means an increasing part of the compilation pipeline is setup to maintain loop structure across passes to allow attaching meta information to individual loops for consumption by later passes.

In general, a natural loop has one entry block (header) and possibly several back edges (latches) leading to the header from the inside of the loop. Loops with several latches may appear if several loops share a single header, or if there is a branching in the middle of the loop. The representation of loops in GCC however allows only loops with a single latch. During loop analysis, headers of such loops are split and forwarder blocks are created in order to disambiguate their structures. Heuristic based on profile information and structure of the induction variables in the loops is used to determine whether the latches correspond to sub-loops or to control flow in a single loop. This means that the analysis sometimes changes the CFG, and if you run it in the middle of an optimization pass, you must be able to deal with the new blocks. You may avoid CFG changes by passing LOOPS_MAY_HAVE_MULTIPLE_LATCHES flag to the loop discovery, note however that most other loop manipulation functions will not work correctly for loops with multiple latch edges (the functions that only query membership of blocks to loops and subloop relationships, or enumerate and test loop exits, can be expected to work).

Body of the loop is the set of blocks that are dominated by its header, and reachable from its latch against the direction of edges in CFG. The loops are organized in a containment hierarchy (tree) such that all the loops immediately contained inside loop L are the children of L in the tree. This tree is represented by the `struct loops` structure. The root of this tree is a fake loop that contains all blocks in the function. Each of the loops is represented in a `struct loop` structure. Each loop is assigned an index (num field of the `struct loop` structure), and the pointer to the loop is stored in the corresponding field of the `larray` vector in the `loops` structure. The indices do not have to be continuous, there may be empty (NULL) entries in the `larray` created by deleting loops. Also, there is no guarantee on the relative order of a loop and its subloops in the numbering. The index of a loop never changes.

The entries of the `larray` field should not be accessed directly. The function `get_loop` returns the loop description for a loop with the given index. `number_of_loops` function returns number of loops in the function. To traverse all loops, use a range-based for loop with class `loops_list` instance. The `flags` argument passed to the constructor function of class `loops_list` is used to determine the direction of traversal and the set of loops visited. Each loop is guaranteed to be visited exactly once, regardless of the changes to the loop
tree, and the loops may be removed during the traversal. The newly created loops are never traversed, if they need to be visited, this must be done separately after their creation.

Each basic block contains the reference to the innermost loop it belongs to (\texttt{loop_father}). For this reason, it is only possible to have one \texttt{struct loops} structure initialized at the same time for each CFG. The global variable \texttt{current_loops} contains the \texttt{struct loops} structure. Many of the loop manipulation functions assume that dominance information is up-to-date.

The loops are analyzed through \texttt{loop_optimizer_init} function. The argument of this function is a set of flags represented in an integer bitmask. These flags specify what other properties of the loop structures should be calculated/enforced and preserved later:

- \texttt{LOOPS_MAY_HAVE_MULTIPLE_LATCHES}: If this flag is set, no changes to CFG will be performed in the loop analysis, in particular, loops with multiple latch edges will not be disambiguated. If a loop has multiple latches, its latch block is set to NULL. Most of the loop manipulation functions will not work for loops in this shape. No other flags that require CFG changes can be passed to \texttt{loop_optimizer_init}.

- \texttt{LOOPS_HAVE_PREHEADERS}: Forwarder blocks are created in such a way that each loop has only one entry edge, and additionally, the source block of this entry edge has only one successor. This creates a natural place where the code can be moved out of the loop, and ensures that the entry edge of the loop leads from its immediate super-loop.

- \texttt{LOOPS_HAVE_SIMPLE_LATCHES}: Forwarder blocks are created to force the latch block of each loop to have only one successor. This ensures that the latch of the loop does not belong to any of its sub-loops, and makes manipulation with the loops significantly easier. Most of the loop manipulation functions assume that the loops are in this shape.

- \texttt{LOOPS_HAVE_MARKED_IRREDUCIBLE_REGIONS}: Basic blocks and edges in the strongly connected components that are not natural loops (have more than one entry block) are marked with \texttt{BB_IRREDUCIBLE_LOOP} and \texttt{EDGE_IRREDUCIBLE_LOOP} flags. The flag is not set for blocks and edges that belong to natural loops that are in such an irreducible region (but it is set for the entry and exit edges of such a loop, if they lead to/from this region).

- \texttt{LOOPS_HAVE_RECORDED_EXITS}: The lists of exits are recorded and updated for each loop. This makes some functions (e.g., \texttt{get_loop_exit_edges}) more efficient. Some functions (e.g., \texttt{single_exit}) can be used only if the lists of exits are recorded.

These properties may also be computed/enforced later, using functions \texttt{create_preheaders}, \texttt{force_single_succ_latches}, \texttt{mark_irreducible_loops} and \texttt{record_loop_exits}. The properties can be queried using \texttt{loops_state_satisfies_p}.

The memory occupied by the loops structures should be freed with \texttt{loop_optimizer_finalize} function. When loop structures are setup to be preserved across passes this function reduces the information to be kept up-to-date to a minimum (only \texttt{LOOPS_MAY_HAVE_MULTIPLE_LATCHES} set).

The CFG manipulation functions in general do not update loop structures. Specialized versions that additionally do so are provided for the most common tasks. On GIMPLE, \texttt{cleanup_tree_cfg_loop} function can be used to cleanup CFG while updating the loops structures if \texttt{current_loops} is set.
At the moment loop structure is preserved from the start of GIMPLE loop optimizations until the end of RTL loop optimizations. During this time a loop can be tracked by its struct loop and number.

16.2 Loop querying

The functions to query the information about loops are declared in ‘cfgloop.h’. Some of the information can be taken directly from the structures. loop_father field of each basic block contains the innermost loop to that the block belongs. The most useful fields of loop structure (that are kept up-to-date at all times) are:

- **header, latch**: Header and latch basic blocks of the loop.
- **num_nodes**: Number of basic blocks in the loop (including the basic blocks of the sub-loops).
- **outer, inner, next**: The super-loop, the first sub-loop, and the sibling of the loop in the loops tree.

There are other fields in the loop structures, many of them used only by some of the passes, or not updated during CFG changes; in general, they should not be accessed directly.

The most important functions to query loop structures are:

- **loop_depth**: The depth of the loop in the loops tree, i.e., the number of super-loops of the loop.
- **flow_loops_dump**: Dumps the information about loops to a file.
- **verify_loop_structure**: Checks consistency of the loop structures.
- **loop_latch_edge**: Returns the latch edge of a loop.
- **loop_preheader_edge**: If loops have preheaders, returns the preheader edge of a loop.
- **flow_loop_nested_p**: Tests whether loop is a sub-loop of another loop.
- **flow_bb_inside_loop_p**: Tests whether a basic block belongs to a loop (including its sub-loops).
- **find_common_loop**: Finds the common super-loop of two loops.
- **superloop_at_depth**: Returns the super-loop of a loop with the given depth.
- **tree_num_loop_insns, num_loop_insns**: Estimates the number of insns in the loop, on GIMPLE and on RTL.
- **loop_exit_edge_p**: Tests whether edge is an exit from a loop.
- **mark_loop_exit_edges**: Marks all exit edges of all loops with EDGE_LOOP_EXIT flag.
- **get_loop_body, get_loop_body_in_dom_order, get_loop_body_in_bfs_order**: Enumerates the basic blocks in the loop in depth-first search order in reversed CFG, ordered by dominance relation, and breadth-first search order, respectively.
- **single_exit**: Returns the single exit edge of the loop, or NULL if the loop has more than one exit. You can only use this function if LOOPS_HAVE_MARKED_SINGLE_EXITS property is used.
- **get_loop_exit_edges**: Enumerates the exit edges of a loop.
- **just_once_each_iteration_p**: Returns true if the basic block is executed exactly once during each iteration of a loop (that is, it does not belong to a sub-loop, and it dominates the latch of the loop).
16.3 Loop manipulation

The loops tree can be manipulated using the following functions:

- `flow_loop_tree_node_add`: Adds a node to the tree.
- `flow_loop_tree_node_remove`: Removes a node from the tree.
- `add_bb_to_loop`: Adds a basic block to a loop.
- `remove_bb_from_loops`: Removes a basic block from loops.

Most low-level CFG functions update loops automatically. The following functions handle some more complicated cases of CFG manipulations:

- `remove_path`: Removes an edge and all blocks it dominates.
- `split_loop_exit_edge`: Splits exit edge of the loop, ensuring that PHI node arguments remain in the loop (this ensures that loop-closed SSA form is preserved). Only useful on GIMPLE.

Finally, there are some higher-level loop transformations implemented. While some of them are written so that they should work on non-innermost loops, they are mostly untested in that case, and at the moment, they are only reliable for the innermost loops:

- `create_iv`: Creates a new induction variable. Only works on GIMPLE. `standard_iv_increment_position` can be used to find a suitable place for the iv increment.
- `duplicate_loop_to_header_edge`, `tree_duplicate_loop_to_header_edge`: These functions (on RTL and on GIMPLE) duplicate the body of the loop prescribed number of times on one of the edges entering loop header, thus performing either loop unrolling or loop peeling. `can_duplicate_loop_p` (`can_unroll_loop_p` on GIMPLE) must be true for the duplicated loop.
- `loop_version`: This function creates a copy of a loop, and a branch before them that selects one of them depending on the prescribed condition. This is useful for optimizations that need to verify some assumptions in runtime (one of the copies of the loop is usually left unchanged, while the other one is transformed in some way).
- `tree_unroll_loop`: Unrolls the loop, including peeling the extra iterations to make the number of iterations divisible by unroll factor, updating the exit condition, and removing the exits that now cannot be taken. Works only on GIMPLE.

16.4 Loop-closed SSA form

Throughout the loop optimizations on tree level, one extra condition is enforced on the SSA form: No SSA name is used outside of the loop in that it is defined. The SSA form satisfying this condition is called “loop-closed SSA form” – LCSSA. To enforce LCSSA, PHI nodes must be created at the exits of the loops for the SSA names that are used outside of them. Only the real operands (not virtual SSA names) are held in LCSSA, in order to save memory.

There are various benefits of LCSSA:

- Many optimizations (value range analysis, final value replacement) are interested in the values that are defined in the loop and used outside of it, i.e., exactly those for that we create new PHI nodes.
• In induction variable analysis, it is not necessary to specify the loop in that the analysis should be performed – the scalar evolution analysis always returns the results with respect to the loop in that the SSA name is defined.

• It makes updating of SSA form during loop transformations simpler. Without LCSSA, operations like loop unrolling may force creation of PHI nodes arbitrarily far from the loop, while in LCSSA, the SSA form can be updated locally. However, since we only keep real operands in LCSSA, we cannot use this advantage (we could have local updating of real operands, but it is not much more efficient than to use generic SSA form updating for it as well; the amount of changes to SSA is the same).

However, it also means LCSSA must be updated. This is usually straightforward, unless you create a new value in loop and use it outside, or unless you manipulate loop exit edges (functions are provided to make these manipulations simple). rewrite_into_loop_closed_ssa is used to rewrite SSA form to LCSSA, and verify_loop_closed_ssa to check that the invariant of LCSSA is preserved.

16.5 Scalar evolutions

Scalar evolutions (SCEV) are used to represent results of induction variable analysis on GIMPLE. They enable us to represent variables with complicated behavior in a simple and consistent way (we only use it to express values of polynomial induction variables, but it is possible to extend it). The interfaces to SCEV analysis are declared in ‘tree-scalar-evolution.h’. To use scalar evolutions analysis, scev_initialize must be used. To stop using SCEV, scev_finalize should be used. SCEV analysis caches results in order to save time and memory. This cache however is made invalid by most of the loop transformations, including removal of code. If such a transformation is performed, scev_reset must be called to clean the caches.

Given an SSA name, its behavior in loops can be analyzed using the analyze_scalar_evolution function. The returned SCEV however does not have to be fully analyzed and it may contain references to other SSA names defined in the loop. To resolve these (potentially recursive) references, instantiate_parameters or resolve_mixers functions must be used. instantiate_parameters is useful when you use the results of SCEV only for some analysis, and when you work with whole nest of loops at once. It will try replacing all SSA names by their SCEV in all loops, including the super-loops of the current loop, thus providing a complete information about the behavior of the variable in the loop nest. resolve_mixers is useful if you work with only one loop at a time, and if you possibly need to create code based on the value of the induction variable. It will only resolve the SSA names defined in the current loop, leaving the SSA names defined outside unchanged, even if their evolution in the outer loops is known.

The SCEV is a normal tree expression, except for the fact that it may contain several special tree nodes. One of them is SCEV_NOT_KNOWN, used for SSA names whose value cannot be expressed. The other one is POLYNOMIAL_CHREC. Polynomial chrec has three arguments – base, step and loop (both base and step may contain further polynomial chrecs). Type of the expression and of base and step must be the same. A variable has evolution POLYNOMIAL_CHREC(base, step, loop) if it is (in the specified loop) equivalent to x_1 in the following example

while (...)
Note that this includes the language restrictions on the operations. For example, if we compile C code and \( x \) has signed type, then the overflow in addition would cause undefined behavior, and we may assume that this does not happen. Hence, the value with this SCEV cannot overflow (which restricts the number of iterations of such a loop).

In many cases, one wants to restrict the attention just to affine induction variables. In this case, the extra expressive power of SCEV is not useful, and may complicate the optimizations. In this case, `simple_iv` function may be used to analyze a value – the result is a loop-invariant base and step.

### 16.6 IV analysis on RTL

The induction variable on RTL is simple and only allows analysis of affine induction variables, and only in one loop at once. The interface is declared in `cfgloop.h`. Before analyzing induction variables in a loop \( L \), `iv_analysis_loop_init` function must be called on \( L \). After the analysis (possibly calling `iv_analysis_loop_init` for several loops) is finished, `iv_analysis_done` should be called. The following functions can be used to access the results of the analysis:

- **`iv_analyze`**: Analyses a single register used in the given insn. If no use of the register in this insn is found, the following insns are scanned, so that this function can be called on the insn returned by `get_condition`.
- **`iv_analyze_result`**: Analyses result of the assignment in the given insn.
- **`iv_analyze_expr`**: Analyses a more complicated expression. All its operands are analyzed by `iv_analyze`, and hence they must be used in the specified insn or one of the following insns.

The description of the induction variable is provided in `struct rtx_iv`. In order to handle subregs, the representation is a bit complicated; if the value of the `extend` field is not `UNKNOWN`, the value of the induction variable in the \( i \)-th iteration is

\[
\text{delta + mult} \times \text{extend}_{\text{extend_mode}}(\text{subreg}_{\text{mode}}(\text{base} + i \times \text{step})),
\]

with the following exception: if `first_special` is true, then the value in the first iteration (when \( i \) is zero) is `delta + mult \times \text{base}`. However, if `extend` is equal to `UNKNOWN`, then `first_special` must be false, `delta 0`, `mult 1` and the value in the \( i \)-th iteration is

\[
\text{subreg}_{\text{mode}}(\text{base} + i \times \text{step})
\]

The function `get_iv_value` can be used to perform these calculations.

### 16.7 Number of iterations analysis

Both on GIMPLE and on RTL, there are functions available to determine the number of iterations of a loop, with a similar interface. The number of iterations of a loop in GCC is defined as the number of executions of the loop latch. In many cases, it is not possible to determine the number of iterations unconditionally – the determined number is correct only if some assumptions are satisfied. The analysis tries to verify these conditions using the information contained in the program; if it fails, the conditions are returned together with the result. The following information and conditions are provided by the analysis:
• **assumptions**: If this condition is false, the rest of the information is invalid.

• **noloop_assumptions** on RTL, **may_be_zero** on GIMPLE: If this condition is true, the loop exits in the first iteration.

• **infinite**: If this condition is true, the loop is infinite. This condition is only available on RTL. On GIMPLE, conditions for finiteness of the loop are included in **assumptions**.

• **niter_expr** on RTL, **niter** on GIMPLE: The expression that gives number of iterations. The number of iterations is defined as the number of executions of the loop latch.

Both on GIMPLE and on RTL, it necessary for the induction variable analysis framework to be initialized (SCEV on GIMPLE, loop-iv on RTL). On GIMPLE, the results are stored to **struct tree_niter_desc** structure. Number of iterations before the loop is exited through a given exit can be determined using **number_of_iterations_exit** function. On RTL, the results are returned in **struct niter_desc** structure. The corresponding function is named **check_simple_exit**. There are also functions that pass through all the exits of a loop and try to find one with easy to determine number of iterations – **find_loop_niter** on GIMPLE and **find_simple_exit** on RTL. Finally, there are functions that provide the same information, but additionally cache it, so that repeated calls to number of iterations are not so costly – **number_of_latch_executions** on GIMPLE and **get_simple_loop_desc** on RTL.

Note that some of these functions may behave slightly differently than others – some of them return only the expression for the number of iterations, and fail if there are some assumptions. The function **number_of_latch_executions** works only for single-exit loops. The function **number_of_cond_exit_executions** can be used to determine number of executions of the exit condition of a single-exit loop (i.e., the **number_of_latch_executions** increased by one).

On GIMPLE, below constraint flags affect semantics of some APIs of number of iterations analyzer:

• **LOOP_C_INFINITE**: If this constraint flag is set, the loop is known to be infinite. APIs like **number_of_iterations_exit** can return false directly without doing any analysis.

• **LOOP_C_FINITE**: If this constraint flag is set, the loop is known to be finite, in other words, loop’s number of iterations can be computed with **assumptions** be true.

Generally, the constraint flags are set/cleared by consumers which are loop optimizers. It’s also the consumers’ responsibility to set/clear constraints correctly. Failing to do that might result in hard to track down bugs in scev/niter consumers. One typical use case is vectorizer: it drives number of iterations analyzer by setting **LOOP_C_FINITE** and vectorizes possibly infinite loop by versioning loop with analysis result. In return, constraints set by consumers can also help number of iterations analyzer in following optimizers. For example, **niter** of a loop versioned under **assumptions** is valid unconditionally.

Other constraints may be added in the future, for example, a constraint indicating that loops’ latch must roll thus **may_be_zero** would be false unconditionally.
16.8 Data Dependency Analysis

The code for the data dependence analysis can be found in `tree-data-ref.c` and its interface and data structures are described in `tree-data-ref.h`. The function that computes the data dependences for all the array and pointer references for a given loop is `compute_data_dependences_for_loop`. This function is currently used by the linear loop transform and the vectorization passes. Before calling this function, one has to allocate two vectors: a first vector will contain the set of data references that are contained in the analyzed loop body, and the second vector will contain the dependence relations between the data references. Thus if the vector of data references is of size $n$, the vector containing the dependence relations will contain $n \times n$ elements. However if the analyzed loop contains side effects, such as calls that potentially can interfere with the data references in the current analyzed loop, the analysis stops while scanning the loop body for data references, and inserts a single `chrec_dont_know` in the dependence relation array.

The data references are discovered in a particular order during the scanning of the loop body: the loop body is analyzed in execution order, and the data references of each statement are pushed at the end of the data reference array. Two data references syntactically occur in the program in the same order as in the array of data references. This syntactic order is important in some classical data dependence tests, and mapping this order to the elements of this array avoids costly queries to the loop body representation.

Three types of data references are currently handled: ARRAY_REF, INDIRECT_REF and COMPONENT_REF. The data structure for the data reference is `data_reference`, where `data_reference_p` is a name of a pointer to the data reference structure. The structure contains the following elements:

- **base_object_info**: Provides information about the base object of the data reference and its access functions. These access functions represent the evolution of the data reference in the loop relative to its base, in keeping with the classical meaning of the data reference access function for the support of arrays. For example, for a reference `a.b[i][j]`, the base object is `a.b` and the access functions, one for each array subscript, are: `{i_init, + i_step}_1, {j_init, +, j_step}_2`.

- **first_location_in_loop**: Provides information about the first location accessed by the data reference in the loop and about the access function used to represent evolution relative to this location. This data is used to support pointers, and is not used for arrays (for which we have base objects). Pointer accesses are represented as a one-dimensional access that starts from the first location accessed in the loop. For example:

```c
for1 i
    for2 j
        *((int *)p + i + j) = a[i][j];
```

The access function of the pointer access is `{0, + 4B}_for2` relative to `p + i`. The access functions of the array are `{i_init, + i_step}_for1` and `{j_init, +, j_step}_for2` relative to `a`.

Usually, the object the pointer refers to is either unknown, or we cannot prove that the access is confined to the boundaries of a certain object.

Two data references can be compared only if at least one of these two representations has all its fields filled for both data references.
The current strategy for data dependence tests is as follows: If both \(a\) and \(b\) are represented as arrays, compare \(a.base\_object\) and \(b.base\_object\); if they are equal, apply dependence tests (use access functions based on base\_objects). Else if both \(a\) and \(b\) are represented as pointers, compare \(a.first\_location\) and \(b.first\_location\); if they are equal, apply dependence tests (use access functions based on first location). However, if \(a\) and \(b\) are represented differently, only try to prove that the bases are definitely different.

- Aliasing information.
- Alignment information.

The structure describing the relation between two data references is \texttt{data\_dependence\_relation}\ and the shorter name for a pointer to such a structure is \texttt{ddr\_p}. This structure contains:

- a pointer to each data reference,
- a tree node \texttt{are\_dependent} that is set to \texttt{chrec\_known} if the analysis has proved that there is no dependence between these two data references, \texttt{chrec\_dont\_know} if the analysis was not able to determine any useful result and potentially there could exist a dependence between these data references, and \texttt{are\_dependent} is set to \texttt{NULL\_TREE} if there exist a dependence relation between the data references, and the description of this dependence relation is given in the \texttt{subscripts}, \texttt{dir\_vectors}, and \texttt{dist\_vectors} arrays,
- a boolean that determines whether the dependence relation can be represented by a classical distance vector,
- an array \texttt{subscripts} that contains a description of each subscript of the data references. Given two array accesses a subscript is the tuple composed of the access functions for a given dimension. For example, given \(A[f1][f2][f3]\) and \(B[g1][g2][g3]\), there are three subscripts: \((f1, g1)\), \((f2, g2)\), \((f3, g3)\).
- two arrays \texttt{dir\_vectors} and \texttt{dist\_vectors} that contain classical representations of the data dependences under the form of direction and distance dependence vectors,
- an array of loops \texttt{loop\_nest} that contains the loops to which the distance and direction vectors refer to.

Several functions for pretty printing the information extracted by the data dependence analysis are available: \texttt{dump\_ddrs} prints with a maximum verbosity the details of a data dependence relations array, \texttt{dump\_dist\_dir\_vectors} prints only the classical distance and direction vectors for a data dependence relations array, and \texttt{dump\_data\_references} prints the details of the data references contained in a data reference array.
17 Machine Descriptions

A machine description has two parts: a file of instruction patterns (‘.md’ file) and a C header file of macro definitions.

The ‘.md’ file for a target machine contains a pattern for each instruction that the target machine supports (or at least each instruction that is worth telling the compiler about). It may also contain comments. A semicolon causes the rest of the line to be a comment, unless the semicolon is inside a quoted string.

See the next chapter for information on the C header file.

17.1 Overview of How the Machine Description is Used

There are three main conversions that happen in the compiler:

1. The front end reads the source code and builds a parse tree.
2. The parse tree is used to generate an RTL insn list based on named instruction patterns.
3. The insn list is matched against the RTL templates to produce assembler code.

For the generate pass, only the names of the insns matter, from either a named define_insn or a define_expand. The compiler will choose the pattern with the right name and apply the operands according to the documentation later in this chapter, without regard for the RTL template or operand constraints. Note that the names the compiler looks for are hard-coded in the compiler—it will ignore unnamed patterns and patterns with names it doesn’t know about, but if you don’t provide a named pattern it needs, it will abort.

If a define_insn is used, the template given is inserted into the insn list. If a define_expand is used, one of three things happens, based on the condition logic. The condition logic may manually create new insns for the insn list, say via emit_insn(), and invoke DONE. For certain named patterns, it may invoke FAIL to tell the compiler to use an alternate way of performing that task. If it invokes neither DONE nor FAIL, the template given in the pattern is inserted, as if the define_expand were a define_insn.

Once the insn list is generated, various optimization passes convert, replace, and rearrange the insns in the insn list. This is where the define_split and define_peephole patterns get used, for example.

Finally, the insn list’s RTL is matched up with the RTL templates in the define_insn patterns, and those patterns are used to emit the final assembly code. For this purpose, each named define_insn acts like it’s unnamed, since the names are ignored.

17.2 Everything about Instruction Patterns

A define_insn expression is used to define instruction patterns to which insns may be matched. A define_insn expression contains an incomplete RTL expression, with pieces to be filled in later, operand constraints that restrict how the pieces can be filled in, and an output template or C code to generate the assembler output.

A define_insn is an RTL expression containing four or five operands:

1. An optional name n. When a name is present, the compiler automatically generates a C++ function ‘gen_n’ that takes the operands of the instruction as arguments and
returns the instruction’s rtx pattern. The compiler also assigns the instruction a unique code ‘CODE_FOR_n’, with all such codes belonging to an enum called insn_code.

These names serve one of two purposes. The first is to indicate that the instruction performs a certain standard job for the RTL-generation pass of the compiler, such as a move, an addition, or a conditional jump. The second is to help the target generate certain target-specific operations, such as when implementing target-specific intrinsic functions.

It is better to prefix target-specific names with the name of the target, to avoid any clash with current or future standard names.

The absence of a name is indicated by writing an empty string where the name should go. Nameless instruction patterns are never used for generating RTL code, but they may permit several simpler insns to be combined later on.

For the purpose of debugging the compiler, you may also specify a name beginning with the ‘*’ character. Such a name is used only for identifying the instruction in RTL dumps; it is equivalent to having a nameless pattern for all other purposes. Names beginning with the ‘*’ character are not required to be unique.

The name may also have the form ‘@n’. This has the same effect as a name ‘n’, but in addition tells the compiler to generate further helper functions; see Section 17.23.5 [Parameterized Names], page 494 for details.

2. The RTL template: This is a vector of incomplete RTL expressions which describe the semantics of the instruction (see Section 17.4 [RTL Template], page 351). It is incomplete because it may contain match_operand, match_operator, and match_dup expressions that stand for operands of the instruction.

If the vector has multiple elements, the RTL template is treated as a parallel expression.

3. The condition: This is a string which contains a C expression. When the compiler attempts to match RTL against a pattern, the condition is evaluated. If the condition evaluates to true, the match is permitted. The condition may be an empty string, which is treated as always true.

For a named pattern, the condition may not depend on the data in the insn being matched, but only the target-machine-type flags. The compiler needs to test these conditions during initialization in order to learn exactly which named instructions are available in a particular run.

For nameless patterns, the condition is applied only when matching an individual insn, and only after the insn has matched the pattern’s recognition template. The insn’s operands may be found in the vector operands.

An instruction condition cannot become more restrictive as compilation progresses. If the condition accepts a particular RTL instruction at one stage of compilation, it must continue to accept that instruction until the final pass. For example, ‘!reload_completed’ and ‘can_create_pseudo_p ()’ are both invalid instruction conditions, because they are true during the earlier RTL passes and false during the later ones. For the same reason, if a condition accepts an instruction before register allocation, it cannot later try to control register allocation by excluding certain register or value combinations.
Although a condition cannot become more restrictive as compilation progresses, the condition for a nameless pattern can become more permissive. For example, a nameless instruction can require \texttt{reload\_completed} to be true, in which case it only matches after register allocation.

4. The \textit{output template} or \textit{output statement}: This is either a string, or a fragment of C code which returns a string.

When simple substitution isn’t general enough, you can specify a piece of C code to compute the output. See Section 17.6 [Output Statement], page 356.

5. The \textit{insn attributes}: This is an optional vector containing the values of attributes for insns matching this pattern (see Section 17.19 [Insn Attributes], page 467).

### 17.3 Example of \texttt{define_insn}

Here is an example of an instruction pattern, taken from the machine description for the 68000/68020.

```c
(define_insn "tstsi"
  [(set (cc0)
       (match_operand:SI 0 "general\_operand" "rm"))]
  ""
  "*

  { if (TARGET_68020 || ! ADDRESS\_REG\_P (operands[0]))
    return "tstl %0";
    return "cmpl #0,%0";
  }"
)
```

This can also be written using braced strings:

```c
(define_insn "tstsi"
  [(set (cc0)
       (match_operand:SI 0 "general\_operand" "rm"))]
  ""
  { if (TARGET_68020 || ! ADDRESS\_REG\_P (operands[0]))
    return "tstl %0";
    return "cmpl #0,%0";
  }"
)
```

This describes an instruction which sets the condition codes based on the value of a general operand. It has no condition, so any insn with an RTL description of the form shown may be matched to this pattern. The name \texttt{tstsi} means “test a SImode value” and tells the RTL generation pass that, when it is necessary to test such a value, an insn to do so can be constructed using this pattern.

The output control string is a piece of C code which chooses which output template to return based on the kind of operand and the specific type of CPU for which code is being generated.

\texttt{"rm"} is an operand constraint. Its meaning is explained below.

### 17.4 RTL Template

The RTL template is used to define which insns match the particular pattern and how to find their operands. For named patterns, the RTL template also says how to construct an insn from specified operands.
Construction involves substituting specified operands into a copy of the template. Matching involves determining the values that serve as the operands in the insn being matched. Both of these activities are controlled by special expression types that direct matching and substitution of the operands.

\( \text{match\_operand:} m \ n \ \text{predicate constraint} \)

This expression is a placeholder for operand number \( n \) of the insn. When constructing an insn, operand number \( n \) will be substituted at this point. When matching an insn, whatever appears at this position in the insn will be taken as operand number \( n \); but it must satisfy \textit{predicate} or this instruction pattern will not match at all.

Operand numbers must be chosen consecutively counting from zero in each instruction pattern. There may be only one \texttt{match\_operand} expression in the pattern for each operand number. Usually operands are numbered in the order of appearance in \texttt{match\_operand} expressions. In the case of a \texttt{define\_expand}, any operand numbers used only in \texttt{match\_dup} expressions have higher values than all other operand numbers.

\texttt{predicate} is a string that is the name of a function that accepts two arguments, an expression and a machine mode. See Section 17.7 [Predicates], page 358. During matching, the function will be called with the putative operand as the expression and \( m \) as the mode argument (if \( m \) is not specified, \texttt{VOIDmode} will be used, which normally causes \texttt{predicate} to accept any mode). If it returns zero, this instruction pattern fails to match. \texttt{predicate} may be an empty string; then it means no test is to be done on the operand, so anything which occurs in this position is valid.

Most of the time, \texttt{predicate} will reject modes other than \( m \)—but not always. For example, the predicate \texttt{address\_operand} uses \( m \) as the mode of memory ref that the address should be valid for. Many predicates accept \texttt{const\_int} nodes even though their mode is \texttt{VOIDmode}.

\texttt{constraint} controls reloading and the choice of the best register class to use for a value, as explained later (see Section 17.8 [Constraints], page 362). If the constraint would be an empty string, it can be omitted.

People are often unclear on the difference between the constraint and the predicate. The predicate helps decide whether a given insn matches the pattern. The constraint plays no role in this decision; instead, it controls various decisions in the case of an insn which does match.

\( \text{match\_scratch:} m \ n \ \text{constraint} \)

This expression is also a placeholder for operand number \( n \) and indicates that operand must be a \texttt{scratch} or \texttt{reg} expression.

When matching patterns, this is equivalent to

\( \text{match\_operand:} m \ n \ \text{"scratch\_operand" constraint} \)

but, when generating RTL, it produces a \( \texttt{scratch:m} \) expression.

If the last few expressions in a \texttt{parallel} are \texttt{clobber} expressions whose operands are either a hard register or \texttt{match\_scratch}, the combiner can add or delete them when necessary. See Section 14.15 [Side Effects], page 300.
(match_dup n)
This expression is also a placeholder for operand number n. It is used when the
operand needs to appear more than once in the insn.
In construction, match_dup acts just like match_operand: the operand is sub-
stituted into the insn being constructed. But in matching, match_dup behaves
differently. It assumes that operand number n has already been determined by
a match_operand appearing earlier in the recognition template, and it matches
only an identical-looking expression.
Note that match_dup should not be used to tell the compiler that a particular
register is being used for two operands (example: add that adds one register to
another; the second register is both an input operand and the output operand).
Use a matching constraint (see Section 17.8.1 [Simple Constraints], page 362)
for those. match_dup is for the cases where one operand is used in two places
in the template, such as an instruction that computes both a quotient and a
remainder, where the opcode takes two input operands but the RTL template
has to refer to each of those twice; once for the quotient pattern and once for
the remainder pattern.

(match_operator: m n predicate [operands...])
This pattern is a kind of placeholder for a variable RTL expression code.
When constructing an insn, it stands for an RTL expression whose expression
code is taken from that of operand n, and whose operands are constructed from
the patterns operands.
When matching an expression, it matches an expression if the function predi-
cate returns nonzero on that expression and the patterns operands match the
operands of the expression.
Suppose that the function commutative_operator is defined as follows, to
match any expression whose operator is one of the commutative arithmetic
operators of RTL and whose mode is mode:

```c
int commutative_integer_operator (x, mode)
  rtx x;
  machine_mode mode;
{
  enum rtx_code code = GET_CODE (x);
  if (GET_MODE (x) != mode)
    return 0;
  return (GET_RTX_CLASS (code) == RTX_COMM_ARITH
     || code == EQ || code == NE);
}
```
Then the following pattern will match any RTL expression consisting of a com-
mutative operator applied to two general operands:

```c
(match_operator: SI 3 "commutative_operator"
 [(match_operand: SI 1 "general_operand" "g")
  (match_operand: SI 2 "general_operand" "g")])
```
Here the vector [operands...] contains two patterns because the expressions
to be matched all contain two operands.
When this pattern does match, the two operands of the commutative operator
are recorded as operands 1 and 2 of the insn. (This is done by the two instances
of `match_operand`.) Operand 3 of the insn will be the entire commutative expression: use `GET_CODE (operands[3])` to see which commutative operator was used.

The machine mode `m` of `match_operator` works like that of `match_operand`: it is passed as the second argument to the predicate function, and that function is solely responsible for deciding whether the expression to be matched “has” that mode.

When constructing an insn, argument 3 of the gen-function will specify the operation (i.e. the expression code) for the expression to be made. It should be an RTL expression, whose expression code is copied into a new expression whose operands are arguments 1 and 2 of the gen-function. The subexpressions of argument 3 are not used; only its expression code matters.

When `match_operator` is used in a pattern for matching an insn, it usually best if the operand number of the `match_operator` is higher than that of the actual operands of the insn. This improves register allocation because the register allocator often looks at operands 1 and 2 of insns to see if it can do register tying.

There is no way to specify constraints in `match_operator`. The operand of the insn which corresponds to the `match_operator` never has any constraints because it is never reloaded as a whole. However, if parts of its operands are matched by `match_operand` patterns, those parts may have constraints of their own.

**(match_op_dup: m n [operands ...])**

Like `match_dup`, except that it applies to operators instead of operands. When constructing an insn, operand number `n` will be substituted at this point. But in matching, `match_op_dup` behaves differently. It assumes that operand number `n` has already been determined by a `match_operator` appearing earlier in the recognition template, and it matches only an identical-looking expression.

**(match_parallel n predicate [subpat ...])**

This pattern is a placeholder for an insn that consists of a parallel expression with a variable number of elements. This expression should only appear at the top level of an insn pattern.

When constructing an insn, operand number `n` will be substituted at this point. When matching an insn, it matches if the body of the insn is a parallel expression with at least as many elements as the vector of `subpat` expressions in the `match_parallel`, if each `subpat` matches the corresponding element of the parallel, and the function `predicate` returns nonzero on the parallel that is the body of the insn. It is the responsibility of the predicate to validate elements of the parallel beyond those listed in the `match_parallel`.

A typical use of `match_parallel` is to match load and store multiple expressions, which can contain a variable number of elements in a parallel. For example,

```plaintext
(define_insn ""
  [(match_parallel 0 "load_multiple_operation"
      [(set (match_operand:SI 1 "gpc_reg_operand" "=r"))])
```
This example comes from ‘a29k.md’. The function `load_multiple_operation` is defined in ‘a29k.c’ and checks that subsequent elements in the `parallel` are the same as the `set` in the pattern, except that they are referencing subsequent registers and memory locations.

An insn that matches this pattern might look like:

```asm
(parallel
  (set (reg:SI 20) (mem:SI (reg:SI 100)))
  (use (reg:SI 179))
  (clobber (reg:SI 179))
  (set (reg:SI 21)
       (mem:SI (plus:SI (reg:SI 100) (const_int 4))))
  (set (reg:SI 22)
       (mem:SI (plus:SI (reg:SI 100) (const_int 8))))))
```

Like `match_op_dup`, but for `match_parallel` instead of `match_operator`.

### 17.5 Output Templates and Operand Substitution

The `output template` is a string which specifies how to output the assembler code for an instruction pattern. Most of the template is a fixed string which is output literally. The character ‘%’ is used to specify where to substitute an operand; it can also be used to identify places where different variants of the assembler require different syntax.

In the simplest case, a ‘%’ followed by a digit `n` says to output operand `n` at that point in the string.

‘%’ followed by a letter and a digit says to output an operand in an alternate fashion. Four letters have standard, built-in meanings described below. The machine description macro `PRINT_OPERAND` can define additional letters with nonstandard meanings.

- ‘%`cdigit`’ can be used to substitute an operand that is a constant value without the syntax that normally indicates an immediate operand.
- ‘%`ndigit`’ is like ‘%`cdigit`’ except that the value of the constant is negated before printing.
- ‘%`adigit`’ can be used to substitute an operand as if it were a memory reference, with the actual operand treated as the address. This may be useful when outputting a “load address” instruction, because often the assembler syntax for such an instruction requires you to write the operand as if it were a memory reference.
- ‘%`ldigit`’ is used to substitute a `label_ref` into a jump instruction.
- ‘%’ outputs a number which is unique to each instruction in the entire compilation. This is useful for making local labels to be referred to more than once in a single template that generates multiple assembler instructions.
- ‘%’ followed by a punctuation character specifies a substitution that does not use an operand. Only one case is standard: ‘%’ outputs a ‘%’ into the assembler code. Other
nonstandard cases can be defined in the PRINT_OPERAND macro. You must also define which punctuation characters are valid with the PRINT_OPERAND_PUNCT_VALID_P macro.

The template may generate multiple assembler instructions. Write the text for the instructions, with \; between them.

When the RTL contains two operands which are required by constraint to match each other, the output template must refer only to the lower-numbered operand. Matching operands are not always identical, and the rest of the compiler arranges to put the proper RTL expression for printing into the lower-numbered operand.

One use of nonstandard letters or punctuation following \% is to distinguish between different assembler languages for the same machine; for example, Motorola syntax versus MIT syntax for the 68000. Motorola syntax requires periods in most opcode names, while MIT syntax does not. For example, the opcode `movel` in MIT syntax is `move.1` in Motorola syntax. The same file of patterns is used for both kinds of output syntax, but the character sequence `\%` is used in each place where Motorola syntax wants a period. The PRINT_OPERAND macro for Motorola syntax defines the sequence to output a period; the macro for MIT syntax defines it to do nothing.

As a special case, a template consisting of the single character # instructs the compiler to first split the insn, and then output the resulting instructions separately. This helps eliminate redundancy in the output templates. If you have a define_insn that needs to emit multiple assembler instructions, and there is a matching define_split already defined, then you can simply use # as the output template instead of writing an output template that emits the multiple assembler instructions.

Note that # only has an effect while generating assembly code; it does not affect whether a split occurs earlier. An associated define_split must exist and it must be suitable for use after register allocation.

If the macro ASSEMBLER_DIALECT is defined, you can use construct of the form `{option0|option1|option2}` in the templates. These describe multiple variants of assembler language syntax. See Section 18.20.7 [Instruction Output], page 634.

### 17.6 C Statements for Assembler Output

Often a single fixed template string cannot produce correct and efficient assembler code for all the cases that are recognized by a single instruction pattern. For example, the opcodes may depend on the kinds of operands; or some unfortunate combinations of operands may require extra machine instructions.

If the output control string starts with a ‘@’, then it is actually a series of templates, each on a separate line. (Blank lines and leading spaces and tabs are ignored.) The templates correspond to the pattern’s constraint alternatives (see Section 17.8.2 [Multi-Alternative], page 367). For example, if a target machine has a two-address add instruction ‘addr’ to add into a register and another ‘addm’ to add a register to memory, you might write this pattern:

```c
(define_insn "addsi3"
  [(set (match_operand:SI 0 "general_operand" "+r,m")
       (plus:SI (match_operand:SI 1 "general_operand" "+0,0")
                 (match_operand:SI 2 "general_operand" "+g,r")))]
   ;;
   "$@"
```
If the output control string starts with a ‘*’, then it is not an output template but rather a 
piece of C program that should compute a template. It should execute a return statement 
to return the template-string you want. Most such templates use C string literals, which 
require doublequote characters to delimit them. To include these doublequote characters in 
the string, prefix each one with \\.

If the output control string is written as a brace block instead of a double-quoted string, 
it is automatically assumed to be C code. In that case, it is not necessary to put in a leading 
asterisk, or to escape the doublequotes surrounding C string literals.

The operands may be found in the array operands, whose C data type is rtx [].

It is very common to select different ways of generating assembler code based on whether 
an immediate operand is within a certain range. Be careful when doing this, because the 
result of INTVAL is an integer on the host machine. If the host machine has more bits in an 
int than the target machine has in the mode in which the constant will be used, then some 
of the bits you get from INTVAL will be superfluous. For proper results, you must carefully 
disregard the values of those bits.

It is possible to output an assembler instruction and then go on to output or compute 
more of them, using the subroutine output_asm_insn. This receives two arguments: a 
template-string and a vector of operands. The vector may be operands, or it may be 
another array of rtx that you declare locally and initialize yourself.

When an insn pattern has multiple alternatives in its constraints, often the appearance 
of the assembler code is determined mostly by which alternative was matched. When this 
is so, the C code can test the variable which_alternative, which is the ordinal number of 
the alternative that was actually satisfied (0 for the first, 1 for the second alternative, etc.).

For example, suppose there are two opcodes for storing zero, ‘clrreg’ for registers and 
‘clrmem’ for memory locations. Here is how a pattern could use which_alternative to 
choose between them:

```c
(define_insn ""
  [(set (match_operand:SI 0 "general_operand" "+r,m")
        (const_int 0))]
  ""
  { return (which_alternative == 0
    ? "clrreg %0" : "clrmem %0");
  })
```

The example above, where the assembler code to generate was solely determined by the 
alternative, could also have been specified as follows, having the output control string start 
with a ‘@’:

```c
(define_insn ""
  [(set (match_operand:SI 0 "general_operand" "+r,m")
        (const_int 0))]
  "@" 
  clrreg %0 
  clrmem %0")
```

If you just need a little bit of C code in one (or a few) alternatives, you can use ‘*’ inside 
of a ‘@’ multi-alternative template:
17.7 Predicates

A predicate determines whether a `match_operand` or `match_operator` expression matches, and therefore whether the surrounding instruction pattern will be used for that combination of operands. GCC has a number of machine-independent predicates, and you can define machine-specific predicates as needed. By convention, predicates used with `match_operand` have names that end in `_'operand`, and those used with `match_operator` have names that end in `_'operator`.

All predicates are boolean functions (in the mathematical sense) of two arguments: the RTL expression that is being considered at that position in the instruction pattern, and the machine mode that the `match_operand` or `match_operator` specifies. In this section, the first argument is called `op` and the second argument `mode`. Predicates can be called from C as ordinary two-argument functions; this can be useful in output templates or other machine-specific code.

Operand predicates can allow operands that are not actually acceptable to the hardware, as long as the constraints give reload the ability to fix them up (see Section 17.8 [Constraints], page 362). However, GCC will usually generate better code if the predicates specify the requirements of the machine instructions as closely as possible. Reload cannot fix up operands that must be constants ("immediate operands"); you must use a predicate that allows only constants, or else enforce the requirement in the extra condition.

Most predicates handle their `mode` argument in a uniform manner. If `mode` is `VOIDmode` (unspecified), then `op` can have any mode. If `mode` is anything else, then `op` must have the same mode, unless `op` is a `CONST_INT` or integer `CONST_DOUBLE`. These RTL expressions always have `VOIDmode`, so it would be counterproductive to check that their mode matches. Instead, predicates that accept `CONST_INT` and/or integer `CONST_DOUBLE` check that the value stored in the constant will fit in the requested mode.

Predicates with this behavior are called normal. `genrecog` can optimize the instruction recognizer based on knowledge of how normal predicates treat modes. It can also diagnose certain kinds of common errors in the use of normal predicates; for instance, it is almost always an error to use a normal predicate without specifying a mode.

Predicates that do something different with their `mode` argument are called special. The generic predicates `address_operand` and `pmode_register_operand` are special predicates. `genrecog` does not do any optimizations or diagnosis when special predicates are used.

17.7.1 Machine-Independent Predicates

These are the generic predicates available to all back ends. They are defined in `recog.c`. The first category of predicates allow only constant, or immediate, operands.
immediate_operand

This predicate allows any sort of constant that fits in mode. It is an appropriate choice for instructions that take operands that must be constant.

const_int_operand

This predicate allows any CONST_INT expression that fits in mode. It is an appropriate choice for an immediate operand that does not allow a symbol or label.

const_double_operand

This predicate accepts any CONST_DOUBLE expression that has exactly mode. If mode is VOIDmode, it will also accept CONST_INT. It is intended for immediate floating point constants.

The second category of predicates allow only some kind of machine register.

register_operand

This predicate allows any REG or SUBREG expression that is valid for mode. It is often suitable for arithmetic instruction operands on a RISC machine.

pmode_register_operand

This is a slight variant on register_operand which works around a limitation in the machine-description reader.

(match_operand n "pmode_register_operand" constraint)

means exactly what

(match_operand: P n "register_operand" constraint)

would mean, if the machine-description reader accepted ‘:P’ mode suffixes. Unfortunately, it cannot, because Pmode is an alias for some other mode, and might vary with machine-specific options. See Section 18.31 [Misc], page 661.

scratch_operand

This predicate allows hard registers and SCRATCH expressions, but not pseudo-registers. It is used internally by match_scratch; it should not be used directly.

The third category of predicates allow only some kind of memory reference.

memory_operand

This predicate allows any valid reference to a quantity of mode mode in memory, as determined by the weak form of GO_IF_LEGITIMATE_ADDRESS (see Section 18.13 [Addressing Modes], page 580).

address_operand

This predicate is a little unusual; it allows any operand that is a valid expression for the address of a quantity of mode mode, again determined by the weak form of GO_IF_LEGITIMATE_ADDRESS. To first order, if ‘(mem: mode (exp))’ is acceptable to memory_operand, then exp is acceptable to address_operand. Note that exp does not necessarily have the mode mode.
indirect_operand  
This is a stricter form of memory_operand which allows only memory references with a general_operand as the address expression. New uses of this predicate are discouraged, because general_operand is very permissive, so it’s hard to tell what an indirect_operand does or does not allow. If a target has different requirements for memory operands for different instructions, it is better to define target-specific predicates which enforce the hardware’s requirements explicitly.

push_operand  
This predicate allows a memory reference suitable for pushing a value onto the stack. This will be a MEM which refers to stack_pointer_rtx, with a side effect in its address expression (see Section 14.16 [Incdec], page 305); which one is determined by the STACK_PUSH_CODE macro (see Section 18.9.1 [Frame Layout], page 540).

pop_operand  
This predicate allows a memory reference suitable for popping a value off the stack. Again, this will be a MEM referring to stack_pointer_rtx, with a side effect in its address expression. However, this time STACK_POP_CODE is expected.

The fourth category of predicates allow some combination of the above operands.

nonmemory_operand  
This predicate allows any immediate or register operand valid for mode.

nonimmediate_operand  
This predicate allows any register or memory operand valid for mode.

general_operand  
This predicate allows any immediate, register, or memory operand valid for mode.

Finally, there are two generic operator predicates.

comparison_operator  
This predicate matches any expression which performs an arithmetic comparison in mode; that is, COMPARISON_P is true for the expression code.

ordered_comparison_operator  
This predicate matches any expression which performs an arithmetic comparison in mode and whose expression code is valid for integer modes; that is, the expression code will be one of eq, ne, lt, ltu, le, leu, gt, gtu, ge, geu.

17.7.2 Defining Machine-Specific Predicates
Many machines have requirements for their operands that cannot be expressed precisely using the generic predicates. You can define additional predicates using define_predicate and define_special_predicate expressions. These expressions have three operands:

- The name of the predicate, as it will be referred to in match_operand or match_operator expressions.
- An RTL expression which evaluates to true if the predicate allows the operand op, false if it does not. This expression can only use the following RTL codes:
**MATCH_OPERAND**

When written inside a predicate expression, a **MATCH_OPERAND** expression evaluates to true if the predicate it names would allow op. The operand number and constraint are ignored. Due to limitations in `genrecog`, you can only refer to generic predicates and predicates that have already been defined.

**MATCH_CODE**

This expression evaluates to true if op or a specified subexpression of op has one of a given list of RTX codes.

The first operand of this expression is a string constant containing a comma-separated list of RTX code names (in lower case). These are the codes for which the **MATCH_CODE** will be true.

The second operand is a string constant which indicates what subexpression of op to examine. If it is absent or the empty string, op itself is examined. Otherwise, the string constant must be a sequence of digits and/or lowercase letters. Each character indicates a subexpression to extract from the current expression; for the first character this is op, for the second and subsequent characters it is the result of the previous character.

A digit n extracts `XEXP (e, n)`; a letter l extracts `XVECEXP (e, 0, n)` where n is the alphabetic ordinal of l (0 for 'a', 1 for 'b', and so on). The **MATCH_CODE** then examines the RTX code of the subexpression extracted by the complete string. It is not possible to extract components of an `rtvec` that is not at position 0 within its RTX object.

**MATCH_TEST**

This expression has one operand, a string constant containing a C expression. The predicate’s arguments, op and mode, are available with those names in the C expression. The **MATCH_TEST** evaluates to true if the C expression evaluates to a nonzero value. **MATCH_TEST** expressions must not have side effects.

**AND**

**IOR**

**NOT**

**IF_THEN_ELSE**

The basic ‘**MATCH_**’ expressions can be combined using these logical operators, which have the semantics of the C operators ‘&&’, ‘||’, ‘!’ and ‘?’ respectively. As in Common Lisp, you may give an **AND** or **IOR** expression an arbitrary number of arguments; this has exactly the same effect as writing a chain of two-argument **AND** or **IOR** expressions.

- An optional block of C code, which should execute ‘**return true**’ if the predicate is found to match and ‘**return false**’ if it does not. It must not have any side effects. The predicate arguments, op and mode, are available with those names.

If a code block is present in a predicate definition, then the RTL expression must evaluate to true and the code block must execute ‘**return true**’ for the predicate to allow the operand. The RTL expression is evaluated first; do not re-check anything in the code block that was checked in the RTL expression.
The program `genrecog` scans `define_predicate` and `define_special_predicate` expressions to determine which RTX codes are possibly allowed. You should always make this explicit in the RTL predicate expression, using `MATCH_OPERAND` and `MATCH_CODE`.

Here is an example of a simple predicate definition, from the IA64 machine description:

```c
;; True if op is a SYMBOL_REF which refers to the sdata section.
(define_predicate "small_addr_symbolic_operand"
  (and (match_code "symbol_ref")
       (match_test "SYMBOL_REF_SMALL_ADDR_P (op)")
     )))
```

And here is another, showing the use of the C block.

```c
;; True if op is a register operand that is (or could be) a GR reg.
(define Predicate "gr_register_operand"
  (match_operand 0 "register_operand")
  
  { unsigned int regno;
    if (GET_CODE (op) == SUBREG)
      op = SUBREG_REG (op);
    regno = REGNO (op);
    return (regno >= FIRST_PSEUDO_REGISTER || GENERAL_REGNO_P (regno));
  }
```

Predicates written with `define_predicate` automatically include a test that `mode` is `VOIDmode`, or `op` has the same mode as `mode`, or `op` is a `CONST_INT` or `CONST_DOUBLE`. They do not check specifically for integer `CONST_DOUBLE`, nor do they test that the value of either kind of constant fits in the requested mode. This is because target-specific predicates that take constants usually have to do more stringent value checks anyway. If you need the exact same treatment of `CONST_INT` or `CONST_DOUBLE` that the generic predicates provide, use a `MATCH_OPERAND` subexpression to call `const_int_operand`, `const_double_operand`, or `immediate_operand`.

Predicates written with `define_special_predicate` do not get any automatic mode checks, and are treated as having special mode handling by `genrecog`.

The program `genpreds` is responsible for generating code to test predicates. It also writes a header file containing function declarations for all machine-specific predicates. It is not necessary to declare these predicates in ‘`cpu-protos.h`’.

### 17.8 Operand Constraints

Each `match_operand` in an instruction pattern can specify constraints for the operands allowed. The constraints allow you to fine-tune matching within the set of operands allowed by the predicate.

Constraints can say whether an operand may be in a register, and which kinds of register; whether the operand can be a memory reference, and which kinds of address; whether the operand may be an immediate constant, and which possible values it may have. Constraints can also require two operands to match. Side-effects aren’t allowed in operands of inline `asm`, unless ‘<’ or ‘>’ constraints are used, because there is no guarantee that the side effects will happen exactly once in an instruction that can update the addressing register.

#### 17.8.1 Simple Constraints

The simplest kind of constraint is a string full of letters, each of which describes one kind of operand that is permitted. Here are the letters that are allowed:
Whitespace characters are ignored and can be inserted at any position except the first. This enables each alternative for different operands to be visually aligned in the machine description even if they have different number of constraints and modifiers.

`m` A memory operand is allowed, with any kind of address that the machine supports in general. Note that the letter used for the general memory constraint can be re-defined by a back end using the `TARGET_MEM_CONSTRAINT` macro.

`o` A memory operand is allowed, but only if the address is *offsettable*. This means that adding a small integer (actually, the width in bytes of the operand, as determined by its machine mode) may be added to the address and the result is also a valid memory address.

For example, an address which is constant is offsettable; so is an address that is the sum of a register and a constant (as long as a slightly larger constant is also within the range of address-offsets supported by the machine); but an autoincrement or autodecrement address is not offsettable. More complicated indirect/indexed addresses may or may not be offsettable depending on the other addressing modes that the machine supports.

Note that in an output operand which can be matched by another operand, the constraint letter `o` is valid only when accompanied by both `<` (if the target machine has predecrement addressing) and `>` (if the target machine has prein increment addressing).

`V` A memory operand that is not offsettable. In other words, anything that would fit the `m` constraint but not the `o` constraint.

`<` A memory operand with autodecrement addressing (either predecrement or postdecrement) is allowed. In inline `asm` this constraint is only allowed if the operand is used exactly once in an instruction that can handle the side effects. Not using an operand with `<` in constraint string in the inline `asm` pattern at all or using it in multiple instructions isn’t valid, because the side effects wouldn’t be performed or would be performed more than once. Furthermore, on some targets the operand with `<` in constraint string must be accompanied by special instruction suffixes like `%U0` instruction suffix on PowerPC or `%P0` on IA-64.

`>` A memory operand with autoincrement addressing (either preincrement or postincrement) is allowed. In inline `asm` the same restrictions as for `<` apply.

`r` A register operand is allowed provided that it is in a general register.

`i` An immediate integer operand (one with constant value) is allowed. This includes symbolic constants whose values will be known only at assembly time or later.

`n` An immediate integer operand with a known numeric value is allowed. Many systems cannot support assembly-time constants for operands less than a word wide. Constraints for these operands should use `n` rather than `i`.
Other letters in the range ‘I’ through ‘P’ may be defined in a machine-dependent fashion to permit immediate integer operands with explicit integer values in specified ranges. For example, on the 68000, ‘I’ is defined to stand for the range of values 1 to 8. This is the range permitted as a shift count in the shift instructions.

‘E’
An immediate floating operand (expression code `const_double`) is allowed, but only if the target floating point format is the same as that of the host machine (on which the compiler is running).

‘F’
An immediate floating operand (expression code `const_double` or `const_vector`) is allowed.

‘G’, ‘H’
‘G’ and ‘H’ may be defined in a machine-dependent fashion to permit immediate floating operands in particular ranges of values.

‘s’
An immediate integer operand whose value is not an explicit integer is allowed. This might appear strange; if an insn allows a constant operand with a value not known at compile time, it certainly must allow any known value. So why use ‘s’ instead of ‘i’? Sometimes it allows better code to be generated. For example, on the 68000 in a fullword instruction it is possible to use an immediate operand; but if the immediate value is between $-128$ and $127$, better code results from loading the value into a register and using the register. This is because the load into the register can be done with a `moveq` instruction. We arrange for this to happen by defining the letter ‘K’ to mean “any integer outside the range $-128$ to $127$”, and then specifying ‘Ks’ in the operand constraints.

‘g’
Any register, memory or immediate integer operand is allowed, except for registers that are not general registers.

‘X’
Any operand whatsoever is allowed, even if it does not satisfy `general_operand`. This is normally used in the constraint of a `match_scratch` when certain alternatives will not actually require a scratch register.

‘0’, ‘1’, ‘2’, . . . ‘9’
An operand that matches the specified operand number is allowed. If a digit is used together with letters within the same alternative, the digit should come last.

This number is allowed to be more than a single digit. If multiple digits are encountered consecutively, they are interpreted as a single decimal integer. There is scant chance for ambiguity, since to-date it has never been desirable that ‘10’ be interpreted as matching either operand 1 or operand 0. Should this be desired, one can use multiple alternatives instead.

This is called a `matching constraint` and what it really means is that the assembler has only a single operand that fills two roles considered separate in the RTL insn. For example, an add insn has two input operands and one output operand in the RTL, but on most CISC machines an add instruction really has only two operands, one of them an input-output operand:
Matching constraints are used in these circumstances. More precisely, the two operands that match must include one input-only operand and one output-only operand. Moreover, the digit must be a smaller number than the number of the operand that uses it in the constraint.

For operands to match in a particular case usually means that they are identical-looking RTL expressions. But in a few special cases specific kinds of dissimilarity are allowed. For example, \(*x\) as an input operand will match \(*x++\) as an output operand. For proper results in such cases, the output template should always use the output-operand’s number when printing the operand.

An operand that is a valid memory address is allowed. This is for “load address” and “push address” instructions.

‘p’ in the constraint must be accompanied by \texttt{address_operand} as the predicate in the \texttt{match_operand}. This predicate interprets the mode specified in the \texttt{match_operand} as the mode of the memory reference for which the address would be valid.

Other letters can be defined in machine-dependent fashion to stand for particular classes of registers or other arbitrary operand types. ‘d’, ‘a’ and ‘f’ are defined on the 68000/68020 to stand for data, address and floating point registers.

In order to have valid assembler code, each operand must satisfy its constraint. But a failure to do so does not prevent the pattern from applying to an insn. Instead, it directs the compiler to modify the code so that the constraint will be satisfied. Usually this is done by copying an operand into a register.

Contrast, therefore, the two instruction patterns that follow:

\begin{verbatim}
(define_insn ""
  [(set (match_operand:SI 0 "general_operand" ":=r")
       (plus:SI (match_dup 0)
          (match_operand:SI 1 "general_operand" ":0")))]
"
"...")
\end{verbatim}

which has two operands, one of which must appear in two places, and

\begin{verbatim}
(define_insn ""
  [(set (match_operand:SI 0 "general_operand" ":=r")
       (plus:SI (match_operand:SI 1 "general_operand" ":0")
         (match_operand:SI 2 "general_operand" "r")))]
"
"...")
\end{verbatim}

which has three operands, two of which are required by a constraint to be identical. If we are considering an insn of the form

\begin{verbatim}
(insn n prev next
  (set (reg:SI 3)
    (plus:SI (reg:SI 6) (reg:SI 109))))
...)
\end{verbatim}

the first pattern would not apply at all, because this insn does not contain two identical subexpressions in the right place. The pattern would say, “That does not look like an
add instruction; try other patterns". The second pattern would say, “Yes, that’s an add instruction, but there is something wrong with it”. It would direct the reload pass of the compiler to generate additional insns to make the constraint true. The results might look like this:

\[
\text{insn } n2 \text{ prev } n \text{ (set (reg:SI 3) (reg:SI 6)) }...
\]

\[
\text{insn } n \text{ next } n2 \text{ (set (reg:SI 3) (plus:SI (reg:SI 3) (reg:SI 109))) }...
\]

It is up to you to make sure that each operand, in each pattern, has constraints that can handle any RTL expression that could be present for that operand. (When multiple alternatives are in use, each pattern must, for each possible combination of operand expressions, have at least one alternative which can handle that combination of operands.) The constraints don’t need to allow any possible operand—when this is the case, they do not constrain—but they must at least point the way to reloading any possible operand so that it will fit.

- If the constraint accepts whatever operands the predicate permits, there is no problem: reloading is never necessary for this operand.

  For example, an operand whose constraints permit everything except registers is safe provided its predicate rejects registers.

  An operand whose predicate accepts only constant values is safe provided its constraints include the letter ‘i’. If any possible constant value is accepted, then nothing less than ‘i’ will do; if the predicate is more selective, then the constraints may also be more selective.

- Any operand expression can be reloaded by copying it into a register. So if an operand’s constraints allow some kind of register, it is certain to be safe. It need not permit all classes of registers; the compiler knows how to copy a register into another register of the proper class in order to make an instruction valid.

- A nonoffsettable memory reference can be reloaded by copying the address into a register. So if the constraint uses the letter ‘o’, all memory references are taken care of.

- A constant operand can be reloaded by allocating space in memory to hold it as preinitialized data. Then the memory reference can be used in place of the constant. So if the constraint uses the letters ‘o’ or ‘m’, constant operands are not a problem.

- If the constraint permits a constant and a pseudo register used in an insn was not allocated to a hard register and is equivalent to a constant, the register will be replaced with the constant. If the predicate does not permit a constant and the insn is re-recognized for some reason, the compiler will crash. Thus the predicate must always recognize any objects allowed by the constraint.

If the operand’s predicate can recognize registers, but the constraint does not permit them, it can make the compiler crash. When this operand happens to be a register, the reload pass will be stymied, because it does not know how to copy a register temporarily into memory.
If the predicate accepts a unary operator, the constraint applies to the operand. For example, the MIPS processor at ISA level 3 supports an instruction which adds two registers in SImode to produce a DImode result, but only if the registers are correctly sign extended. This predicate for the input operands accepts a sign_extend of an SImode register. Write the constraint to indicate the type of register that is required for the operand of the sign_extend.

17.8.2 Multiple Alternative Constraints

Sometimes a single instruction has multiple alternative sets of possible operands. For example, on the 68000, a logical-or instruction can combine register or an immediate value into memory, or it can combine any kind of operand into a register; but it cannot combine one memory location into another.

These constraints are represented as multiple alternatives. An alternative can be described by a series of letters for each operand. The overall constraint for an operand is made from the letters for this operand from the first alternative, a comma, the letters for this operand from the second alternative, a comma, and so on until the last alternative. All operands for a single instruction must have the same number of alternatives. Here is how it is done for fullword logical-or on the 68000:

```
(define_insn "iorsi3"
  [(set (match_operand:SI 0 "general_operand" "=m,d")
      (ior:SI (match_operand:SI 1 "general_operand" "%0,0")
      (match_operand:SI 2 "general_operand" "dKs,dmKs")))
  ...
]
```

The first alternative has ‘m’ (memory) for operand 0, ‘0’ for operand 1 (meaning it must match operand 0), and ‘dKs’ for operand 2. The second alternative has ‘d’ (data register) for operand 0, ‘0’ for operand 1, and ‘dmKs’ for operand 2. The ‘=’ and ‘%’ in the constraints apply to all the alternatives; their meaning is explained in the next section (see Section 17.8.3 [Class Preferences], page 368).

If all the operands fit any one alternative, the instruction is valid. Otherwise, for each alternative, the compiler counts how many instructions must be added to copy the operands so that that alternative applies. The alternative requiring the least copying is chosen. If two alternatives need the same amount of copying, the one that comes first is chosen. These choices can be altered with the ‘?’ and ‘!’ characters:

- `?` Disparage slightly the alternative that the ‘?’ appears in, as a choice when no alternative applies exactly. The compiler regards this alternative as one unit more costly for each ‘?’ that appears in it.
- `!` Disparage severely the alternative that the ‘!’ appears in. This alternative can still be used if it fits without reloading, but if reloading is needed, some other alternative will be used.
- `^` This constraint is analogous to ‘?’ but it disparages slightly the alternative only if the operand with the ‘^’ needs a reload.
- `$` This constraint is analogous to ‘!’ but it disparages severely the alternative only if the operand with the ‘$’ needs a reload.

When an insn pattern has multiple alternatives in its constraints, often the appearance of the assembler code is determined mostly by which alternative was matched. When this
is so, the C code for writing the assembler code can use the variable \texttt{which\_alternative},
which is the ordinal number of the alternative that was actually satisfied (0 for the first, 1
for the second alternative, etc.). See Section 17.6 [Output Statement], page 356.

17.8.3 Register Class Preferences

The operand constraints have another function: they enable the compiler to decide which
kind of hardware register a pseudo register is best allocated to. The compiler examines the
constraints that apply to the insns that use the pseudo register, looking for the machine-
dependent letters such as ‘d’ and ‘a’ that specify classes of registers. The pseudo register
is put in whichever class gets the most “votes”. The constraint letters ‘g’ and ‘r’ also vote:
they vote in favor of a general register. The machine description says which registers are
considered general.

Of course, on some machines all registers are equivalent, and no register classes are
defined. Then none of this complexity is relevant.

17.8.4 Constraint Modifier Characters

Here are constraint modifier characters.

\begin{itemize}
\item \texttt{=} Means that this operand is written to by this instruction: the previous value is
discarded and replaced by new data.
\item \texttt{+} Means that this operand is both read and written by the instruction.
\end{itemize}

When the compiler fixes up the operands to satisfy the constraints, it needs to
know which operands are read by the instruction and which are written by it.
‘=’ identifies an operand which is only written; ‘+’ identifies an operand that is
both read and written; all other operands are assumed to only be read.

If you specify ‘=’ or ‘+’ in a constraint, you put it in the first character of the
constraint string.

\begin{itemize}
\item \texttt{&} Means (in a particular alternative) that this operand is an \textit{earlyclobber} operand,
which is written before the instruction is finished using the input operands.
Therefore, this operand may not lie in a register that is read by the instruction
or as part of any memory address.
\end{itemize}

‘&’ applies only to the alternative in which it is written. In constraints with
multiple alternatives, sometimes one alternative requires ‘&’ while others do not. See, for example, the \texttt{movdf} insn of the 68000.

An operand which is read by the instruction can be tied to an earlyclobber
operand if its only use as an input occurs before the early result is written.
Adding alternatives of this form often allows GCC to produce better code when
only some of the read operands can be affected by the earlyclobber. See, for
example, the \texttt{mulsi3} insn of the ARM.

Furthermore, if the \textit{earlyclobber} operand is also a read/write operand, then
that operand is written only after it’s used.
‘&’ does not obviate the need to write ‘=’ or ‘+’. As \textit{earlyclobber} operands
are always written, a read-only \textit{earlyclobber} operand is ill-formed and will be
rejected by the compiler.
Declares the instruction to be commutative for this operand and the following operand. This means that the compiler may interchange the two operands if that is the cheapest way to make all operands fit the constraints. ‘%’ applies to all alternatives and must appear as the first character in the constraint. Only read-only operands can use ‘%’.

This is often used in patterns for addition instructions that really have only two operands: the result must go in one of the arguments. Here for example, is how the 68000 halfword-add instruction is defined:

```lisp
(define_insn "addhi3"
[(set (match_operand:HI 0 "general_operand" "=m,r")
 (plus:HI (match_operand:HI 1 "general_operand" "%0,0")
 (match_operand:HI 2 "general_operand" "di,g")))]
...)
```

GCC can only handle one commutative pair in an asm; if you use more, the compiler may fail. Note that you need not use the modifier if the two alternatives are strictly identical; this would only waste time in the reload pass. The modifier is not operational after register allocation, so the result of `define_peephole2` and `define_splits` performed after reload cannot rely on ‘%’ to make the intended insn match.

‘#’

Says that all following characters, up to the next comma, are to be ignored as a constraint. They are significant only for choosing register preferences.

‘*’

Says that the following character should be ignored when choosing register preferences. ‘*’ has no effect on the meaning of the constraint as a constraint, and no effect on reloading. For LRA ‘*’ additionally disparages slightly the alternative if the following character matches the operand.

Here is an example: the 68000 has an instruction to sign-extend a halfword in a data register, and can also sign-extend a value by copying it into an address register. While either kind of register is acceptable, the constraints on an address-register destination are less strict, so it is best if register allocation makes an address register its goal. Therefore, ‘*’ is used so that the ‘d’ constraint letter (for data register) is ignored when computing register preferences.

```lisp
(define_insn "extendhisi2"
[(set (match_operand:SI 0 "general_operand" "=*d,a")
 (sign_extend:SI
 (match_operand:HI 1 "general_operand" "0,g")))]
...)
```

17.8.5 Constraints for Particular Machines

Whenever possible, you should use the general-purpose constraint letters in `asm` arguments, since they will convey meaning more readily to people reading your code. Failing that, use the constraint letters that usually have very similar meanings across architectures. The most commonly used constraints are ‘m’ and ‘r’ (for memory and general-purpose registers respectively; see Section 17.8.1 [Simple Constraints], page 362), and ‘I’, usually the letter indicating the most common immediate-constant format.

Each architecture defines additional constraints. These constraints are used by the compiler itself for instruction generation, as well as for `asm` statements; therefore, some of the
constraints are not particularly useful for \texttt{asm}. Here is a summary of some of the machine-dependent constraints available on some particular machines; it includes both constraints that are useful for \texttt{asm} and constraints that aren’t. The compiler source file mentioned in the table heading for each architecture is the definitive reference for the meanings of that architecture’s constraints.

\textit{AArch64 family—`config/aarch64/constraints.md’}

\begin{itemize}
  \item \texttt{k}  The stack pointer register (SP)
  \item \texttt{w}  Floating point register, Advanced SIMD vector register or SVE vector register
  \item \texttt{x}  Like \texttt{w}, but restricted to registers 0 to 15 inclusive.
  \item \texttt{y}  Like \texttt{w}, but restricted to registers 0 to 7 inclusive.
  \item \texttt{Up1}  One of the low eight SVE predicate registers (P0 to P7)
  \item \texttt{Upa}  Any of the SVE predicate registers (P0 to P15)
  \item \texttt{I}  Integer constant that is valid as an immediate operand in an \texttt{ADD} instruction
  \item \texttt{J}  Integer constant that is valid as an immediate operand in a \texttt{SUB} instruction (once negated)
  \item \texttt{K}  Integer constant that can be used with a 32-bit logical instruction
  \item \texttt{L}  Integer constant that can be used with a 64-bit logical instruction
  \item \texttt{M}  Integer constant that is valid as an immediate operand in a 32-bit \texttt{MOV} pseudo instruction. The \texttt{MOV} may be assembled to one of several different machine instructions depending on the value
  \item \texttt{N}  Integer constant that is valid as an immediate operand in a 64-bit \texttt{MOV} pseudo instruction
  \item \texttt{S}  An absolute symbolic address or a label reference
  \item \texttt{Y}  Floating point constant zero
  \item \texttt{Z}  Integer constant zero
  \item \texttt{Ush}  The high part (bits 12 and upwards) of the pc-relative address of a symbol within 4GB of the instruction
  \item \texttt{Q}  A memory address which uses a single base register with no offset
  \item \texttt{Ump}  A memory address suitable for a load/store pair instruction in SI, DI, SF and DF modes
\end{itemize}

\textit{AMD GCN—`config/gcn/constraints.md’}

\begin{itemize}
  \item \texttt{I}  Immediate integer in the range \(-16\) to \(64\)
  \item \texttt{J}  Immediate 16-bit signed integer
  \item \texttt{Kf}  Immediate constant \(-1\)
  \item \texttt{L}  Immediate 15-bit unsigned integer
| A | Immediate constant that can be inlined in an instruction encoding: integer $-16..64$, or float $0.0, +/−0.5, +/−1.0, +/−2.0, +/−4.0, 1.0/(2.0\pi)$ |
| B | Immediate 32-bit signed integer that can be attached to an instruction encoding |
| C | Immediate 32-bit integer in range $-16..4294967295$ (i.e. 32-bit unsigned integer or ‘A’ constraint) |
| DA | Immediate 64-bit constant that can be split into two ‘A’ constants |
| DB | Immediate 64-bit constant that can be split into two ‘B’ constants |
| U | Any `unspec` |
| Y | Any `symbol_ref` or `label_ref` |
| v | VGPR register |
| Sg | SGPR register |
| SD | SGPR registers valid for instruction destinations, including VCC, M0 and EXEC |
| SS | SGPR registers valid for instruction sources, including VCC, M0, EXEC and SCC |
| Sm | SGPR registers valid as a source for scalar memory instructions (excludes M0 and EXEC) |
| Sv | SGPR registers valid as a source or destination for vector instructions (excludes EXEC) |
| ca | All condition registers: SCC, VCCZ, EXECZ |
| cs | Scalar condition register: SCC |
| cV | Vector condition register: VCC, VCC_LO, VCC_HI |
| e | EXEC register (EXEC_LO and EXEC_HI) |
| RB | Memory operand with address space suitable for `buffer_*` instructions |
| RF | Memory operand with address space suitable for `flat_*` instructions |
| RS | Memory operand with address space suitable for `s_*` instructions |
| RL | Memory operand with address space suitable for `ds_*` LDS instructions |
| RG | Memory operand with address space suitable for `ds_*` GDS instructions |
| RD | Memory operand with address space suitable for any `ds_*` instructions |
RM Memory operand with address space suitable for global_* instructions

ARC — ‘config/arc/constraints.md’

q Registers usable in ARCompact 16-bit instructions: r0-r3, r12-r15. This constraint can only match when the ‘-mq’ option is in effect.

e Registers usable as base-regs of memory addresses in ARCompact 16-bit memory instructions: r0-r3, r12-r15, sp. This constraint can only match when the ‘-mq’ option is in effect.

D ARC FPX (dpfp) 64-bit registers. D0, D1.

I A signed 12-bit integer constant.

Cal constant for arithmetic/logical operations. This might be any constant that can be put into a long immediate by the assembler or linker without involving a PIC relocation.

K A 3-bit unsigned integer constant.

L A 6-bit unsigned integer constant.

CnL One’s complement of a 6-bit unsigned integer constant.

CmL Two’s complement of a 6-bit unsigned integer constant.

M A 5-bit unsigned integer constant.

O A 7-bit unsigned integer constant.

P A 8-bit unsigned integer constant.

H Any const_double value.

ARM family — ‘config/arm/constraints.md’

h In Thumb state, the core registers r8-r15.

k The stack pointer register.

l In Thumb State the core registers r0-r7. In ARM state this is an alias for the r constraint.

t VFP floating-point registers s0-s31. Used for 32 bit values.

w VFP floating-point registers d0-d31 and the appropriate subset d0-d15 based on command line options. Used for 64 bit values only. Not valid for Thumb1.

y The iWMMX co-processor registers.

z The iWMMX GR registers.

G The floating-point constant 0.0

I Integer that is valid as an immediate operand in a data processing instruction. That is, an integer in the range 0 to 255 rotated by a multiple of 2
J Integer in the range \(-4095\) to \(4095\)
K Integer that satisfies constraint ‘I’ when inverted (ones complement)
L Integer that satisfies constraint ‘I’ when negated (twos complement)
M Integer in the range \(0\) to \(32\)
Q A memory reference where the exact address is in a single register (‘m’ is preferable for \texttt{asm} statements)
R An item in the constant pool
S A symbol in the text segment of the current file
Uv A memory reference suitable for VFP load/store insns (reg+constant offset)
Uy A memory reference suitable for iWMMXt load/store instructions.
Uq A memory reference suitable for the ARMv4 ldrsb instruction.

\textit{AVR family—‘config/avr/constraints.md’}

l Registers from r0 to r15
a Registers from r16 to r23
d Registers from r16 to r31
w Registers from r24 to r31. These registers can be used in ‘\texttt{adiw}’ command
e Pointer register (r26–r31)
b Base pointer register (r28–r31)
q Stack pointer register (SPH:SPL)
t Temporary register r0
x Register pair X (r27:r26)
y Register pair Y (r29:r28)
z Register pair Z (r31:r30)
I Constant greater than \(-1\), less than \(64\)
J Constant greater than \(-64\), less than \(1\)
K Constant integer \(2\)
L Constant integer \(0\)
M Constant that fits in 8 bits
N Constant integer \(-1\)
O Constant integer \(8, 16, \) or \(24\)
P  Constant integer 1
G  A floating point constant 0.0
Q  A memory address based on Y or Z pointer with displacement.

*Blackfin family—`config/bfin/constraints.md`*

- **a**: P register
- **d**: D register
- **z**: A call clobbered P register.
- **qn**: A single register. If \( n \) is in the range 0 to 7, the corresponding D register. If it is A, then the register P0.
- **D**: Even-numbered D register
- **W**: Odd-numbered D register
- **e**: Accumulator register.
- **A**: Even-numbered accumulator register.
- **B**: Odd-numbered accumulator register.
- **b**: I register
- **v**: B register
- **f**: M register
- **c**: Registers used for circular buffering, i.e. I, B, or L registers.
- **C**: The CC register.
- **t**: LT0 or LT1.
- **k**: LC0 or LC1.
- **u**: LB0 or LB1.
- **x**: Any D, P, B, M, I or L register.
- **y**: Additional registers typically used only in prologues and epilogues: RETS, RETN, RETI, RETX, RETE, ASTAT, SEQSTAT and USP.
- **w**: Any register except accumulators or CC.
- **Ksh**: Signed 16 bit integer (in the range \(-32768\) to 32767)
- **Kuh**: Unsigned 16 bit integer (in the range 0 to 65535)
- **Ks7**: Signed 7 bit integer (in the range \(-64\) to 63)
- **Ku7**: Unsigned 7 bit integer (in the range 0 to 127)
- **Ku5**: Unsigned 5 bit integer (in the range 0 to 31)
- **Ks4**: Signed 4 bit integer (in the range \(-8\) to 7)
- **Ks3**: Signed 3 bit integer (in the range \(-3\) to 4)
Ku3  Unsigned 3 bit integer (in the range 0 to 7)
Pn   Constant $n$, where $n$ is a single-digit constant in the range 0 to 4.
PA   An integer equal to one of the MACFLAG_XXX constants that is suitable for use with either accumulator.
PB   An integer equal to one of the MACFLAG_XXX constants that is suitable for use only with accumulator A1.
M1   Constant 255.
M2   Constant 65535.
J    An integer constant with exactly a single bit set.
L    An integer constant with all bits set except exactly one.
H
Q    Any SYMBOL_REF.

CR16 Architecture—‘config/cr16/cr16.h’
  b   Registers from r0 to r14 (registers without stack pointer)
  t   Register from r0 to r11 (all 16-bit registers)
  p   Register from r12 to r15 (all 32-bit registers)
  I   Signed constant that fits in 4 bits
  J   Signed constant that fits in 5 bits
  K   Signed constant that fits in 6 bits
  L   Unsigned constant that fits in 4 bits
  M   Signed constant that fits in 32 bits
  N   Check for 64 bits wide constants for add/sub instructions
  G   Floating point constant that is legal for store immediate

C-SKY—‘config/csky/constraints.md’
  a   The mini registers r0 - r7.
  b   The low registers r0 - r15.
  c   C register.
  y   HI and LO registers.
  l   LO register.
  h   HI register.
  v   Vector registers.
  z   Stack pointer register (SP).
  Q   A memory address which uses a base register with a short offset or with a index register with its scale.
W A memory address which uses a base register with a index register with its scale.

The C-SKY back end supports a large set of additional constraints that are only useful for instruction selection or splitting rather than inline asm, such as constraints representing constant integer ranges accepted by particular instruction encodings. Refer to the source code for details.

*Epiphany—`config/epiphany/constraints.md`*

- **U16** An unsigned 16-bit constant.
- **K** An unsigned 5-bit constant.
- **L** A signed 11-bit constant.
- **Cm1** A signed 11-bit constant added to −1. Can only match when the ‘--mreg-reg’ option is active.
- **Cl1** Left-shift of −1, i.e., a bit mask with a block of leading ones, the rest being a block of trailing zeroes. Can only match when the ‘--mreg-reg’ option is active.
- **Cr1** Right-shift of −1, i.e., a bit mask with a trailing block of ones, the rest being zeroes. Or to put it another way, one less than a power of two. Can only match when the ‘--mreg-reg’ option is active.
- **Cal** Constant for arithmetic/logical operations. This is like i, except that for position independent code, no symbols / expressions needing relocations are allowed.
- **Csy** Symbolic constant for call/jump instruction.
- **Rcs** The register class usable in short insns. This is a register class constraint, and can thus drive register allocation. This constraint won’t match unless ‘--mprefer-short-instr-regs’ is in effect.
- **Rsc** The the register class of registers that can be used to hold a sibcall call address. I.e., a caller-saved register.
- **Rct** Core control register class.
- **Rgs** The register group usable in short insns. This constraint does not use a register class, so that it only passively matches suitable registers, and doesn’t drive register allocation.
- **Car** Constant suitable for the addsi3_r pattern. This is a valid offset for byte, halfword, or word addressing.
- **Rra** Matches the return address if it can be replaced with the link register.
- **Rcc** Matches the integer condition code register.
- **Sra** Matches the return address if it is in a stack slot.
- **Cfm** Matches control register values to switch fp mode, which are encapsulated in UNSPEC_FP_MODE.
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FRV—`config/frv/frv.h`

- Register in the class ACC_REGS (acc0 to acc7).
- Register in the class EVEN_ACC_REGS (acc0 to acc7).
- Register in the class CC_REGS (fcc0 to fcc3 and icc0 to icc3).
- Register in the class GPR_REGS (gr0 to gr63).
- Register in the class EVEN_REGS (gr0 to gr63). Odd registers are excluded not in the class but through the use of a machine mode larger than 4 bytes.
- Register in the class FPR_REGS (fr0 to fr63).
- Register in the class FEVEN_REGS (fr0 to fr63). Odd registers are excluded not in the class but through the use of a machine mode larger than 4 bytes.
- Register in the class LR_REG (the lr register).
- Register in the class QUAD_REGS (gr2 to gr63). Register numbers not divisible by 4 are excluded not in the class but through the use of a machine mode larger than 8 bytes.
- Register in the class ICC_REGS (icc0 to icc3).
- Register in the class FCC_REGS (fcc0 to fcc3).
- Register in the class ICR_REGS (cc4 to cc7).
- Register in the class FCR_REGS (cc0 to cc3).
- Register in the class QUAD_FPR_REGS (fr0 to fr63). Register numbers not divisible by 4 are excluded not in the class but through the use of a machine mode larger than 8 bytes.
- Register in the class SPR_REGS (lcr and lr).
- Register in the class QUAD_ACC_REGS (acc0 to acc7).
- Register in the class ACCG_REGS (accg0 to accg7).
- Register in the class CR_REGS (cc0 to cc7).
- Floating point constant zero
- 6-bit signed integer constant
- 10-bit signed integer constant
- 16-bit signed integer constant
- 16-bit unsigned integer constant
- 12-bit signed integer constant that is negative—i.e. in the range of −2048 to −1
- Constant zero
P  12-bit signed integer constant that is greater than zero—i.e. in the range of 1 to 2047.

FT32—‘config/ft32/constraints.md’
A  An absolute address
B  An offset address
W  A register indirect memory operand
e  An offset address.
f  An offset address.
0  The constant zero or one
I  A 16-bit signed constant (−32768 . . . 32767)
w  A bitfield mask suitable for bext or bins
x  An inverted bitfield mask suitable for bext or bins
L  A 16-bit unsigned constant, multiple of 4 (0 . . . 65532)
S  A 20-bit signed constant (−524288 . . . 524287)
b  A constant for a bitfield width (1 . . . 16)
KA A 10-bit signed constant (−512 . . . 511)

Hewlett-Packard PA-RISC—‘config/pa/pa.h’
a  General register 1
f  Floating point register
q  Shift amount register
x  Floating point register (deprecated)
y  Upper floating point register (32-bit), floating point register (64-bit)
Z  Any register
I  Signed 11-bit integer constant
J  Signed 14-bit integer constant
K  Integer constant that can be deposited with a zdepi instruction
L  Signed 5-bit integer constant
M  Integer constant 0
N  Integer constant that can be loaded with a ldil instruction
O  Integer constant whose value plus one is a power of 2
P  Integer constant that can be used for and operations in depi and extru instructions
S  Integer constant 31
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| U  | Integer constant 63                         |
| G  | Floating-point constant 0.0                 |
| A  | A 1o_sum data-linkage-table memory operand |
| Q  | A memory operand that can be used as the destination operand of an integer store instruction |
| R  | A scaled or unscaled indexed memory operand |
| T  | A memory operand for floating-point loads and stores |
| W  | A register indirect memory operand          |

Intel IA-64—`config/ia64/ia64.h`

- a General register r0 to r3 for addl instruction
- b Branch register
- c Predicate register (‘c’ as in “conditional”)
- d Application register residing in M-unit
- e Application register residing in I-unit
- f Floating-point register
- m Memory operand. If used together with ‘<’ or ‘>’, the operand can have postincrement and postdecrement which require printing with ‘%Pn’ on IA-64.
- G Floating-point constant 0.0 or 1.0
- I 14-bit signed integer constant
- J 22-bit signed integer constant
- K 8-bit signed integer constant for logical instructions
- L 8-bit adjusted signed integer constant for compare pseudo-ops
- M 6-bit unsigned integer constant for shift counts
- N 9-bit signed integer constant for load and store postincrements
- O The constant zero
- P 0 or −1 for dep instruction
- Q Non-volatile memory for floating-point loads and stores
- R Integer constant in the range 1 to 4 for shladd instruction
- S Memory operand except postincrement and postdecrement. This is now roughly the same as ‘m’ when not used together with ‘<’ or ‘>’.

M32C—`config/m32c/m32c.c`

- Rsp
- Rfb
- Rsb ‘$sp’, ‘$fb’, ‘$sb’.
Rcr Any control register, when they’re 16 bits wide (nothing if control registers are 24 bits wide)
Rcl Any control register, when they’re 24 bits wide.
R0w $r0, $r1, $r2, $r3.
R1w $r1 or $r3, or $r3r1 for 32 bit values.
R2w $r0 or $r2, or $r2r0 for 32 bit values.
R3w $r0 or $r1 (registers with addressable high/low bytes)
R02 $r0 or $r2, or $r2r0 for 32 bit values.
R13 $r1 or $r3, or $r3r1 for 32 bit values.
Rdi A register that can hold a 64 bit value.
Rh1 $r0 or $r1 (registers with addressable high/low bytes)
R23 $r2 or $r3
Raa Address registers
Raw Address registers when they’re 16 bits wide.
Ral Address registers when they’re 24 bits wide.
Rqi Registers that can hold QI values.
Rad Registers that can be used with displacements ($a0, $a1, $sb).
Rsi Registers that can hold 32 bit values.
Rhi Registers that can hold 16 bit values.
Rhc Registers that can hold 16 bit values, including all control registers.
Rra $r0 through R1, plus $a0 and $a1.
Rfl The flags register.
Rmm The memory-based pseudo-_registers $mem0 through $mem15.
Rpi Registers that can hold pointers (16 bit registers for r8c, m16c; 24 bit registers for m32cm, m32c).
Rpa Matches multiple registers in a PARALLEL to form a larger register. Used to match function return values.
Is3 $8 . . . 7
IS1 $128 . . . 127
IS2 $32768 . . . 32767
IU2 $0 . . . 65535
In4 $8 . . . $1 or $1 . . . 8
In5 $16 . . . $1 or $1 . . . 16
In6 $32 . . . $1 or $1 . . . 32
IM2 $65536 . . . $1
Ilb  An 8 bit value with exactly one bit set.
Ilw  A 16 bit value with exactly one bit set.
Sd   The common src/dest memory addressing modes.
Sa   Memory addressed using $a0 or $a1.
Si   Memory addressed with immediate addresses.
Ss   Memory addressed using the stack pointer ($sp).
Sf   Memory addressed using the frame base register ($fb).
Ss   Memory addressed using the small base register ($sb).
S1   $r1h

MicroBlaze—`config/microblaze/constraints.md`

  d  A general register (r0 to r31).
  z  A status register (rmsr, $fcc1 to $fcc7).

MIPS—`config/mips/constraints.md`

  d  A general-purpose register. This is equivalent to r unless generating
      MIPS16 code, in which case the MIPS16 register set is used.
  f  A floating-point register (if available).
  h  Formerly the hi register. This constraint is no longer supported.
  l  The lo register. Use this register to store values that are no bigger
      than a word.
  x  The concatenated hi and lo registers. Use this register to store
      doubleword values.
  c  A register suitable for use in an indirect jump. This will always be
      $25 for `-mabicalls`.
  v  Register $3. Do not use this constraint in new code; it is retained
      only for compatibility with glibc.
  y  Equivalent to r; retained for backwards compatibility.
  z  A floating-point condition code register.
  i  A signed 16-bit constant (for arithmetic instructions).
  j  Integer zero.
  k  An unsigned 16-bit constant (for logic instructions).
  l  A signed 32-bit constant in which the lower 16 bits are zero. Such
      constants can be loaded using lui.
  m  A constant that cannot be loaded using lui, addiu or ori.
  n  A constant in the range $-65535$ to $-1$ (inclusive).
  o  A signed 15-bit constant.
P  A constant in the range 1 to 65535 (inclusive).
G  Floating-point zero.
R  An address that can be used in a non-macro load or store.
ZC A memory operand whose address is formed by a base register and offset that is suitable for use in instructions with the same addressing mode as \texttt{ll} and \texttt{sc}.
ZD An address suitable for a \texttt{prefetch} instruction, or for any other instruction with the same addressing mode as \texttt{prefetch}.

\textit{Motorola 680x0—`config/m68k/constraints.md’}
\begin{itemize}
\item a Address register
\item d Data register
\item f 68881 floating-point register, if available
\item I Integer in the range 1 to 8
\item J 16-bit signed number
\item K Signed number whose magnitude is greater than 0x80
\item L Integer in the range $\text{-}8$ to $\text{-}1$
\item M Signed number whose magnitude is greater than 0x100
\item N Range 24 to 31, rotatert:SI 8 to 1 expressed as rotate
\item O 16 (for rotate using swap)
\item P Range 8 to 15, rotatert:HI 8 to 1 expressed as rotate
\item R Numbers that \texttt{mov3q} can handle
\item G Floating point constant that is not a 68881 constant
\item S Operands that satisfy ‘m’ when -mpcrel is in effect
\item T Operands that satisfy ‘s’ when -mpcrel is not in effect
\item Q Address register indirect addressing mode
\item U Register offset addressing
\item W \texttt{const\_call\_operand}
\item Cs \texttt{symbol\_ref} or \texttt{const}
\item Ci \texttt{const\_int}
\item C0 \texttt{const\_int 0}
\item Cj Range of signed numbers that don’t fit in 16 bits
\item Cmvq Integers valid for \texttt{mvq}
\item Capsw Integers valid for a moveq followed by a swap
\item Cmvz Integers valid for \texttt{mvz}
### CMVS
Integers valid for mvs

### Ap
push_operand

### Ac
Non-register operands allowed in clr

#### Moxie—`config/moxie/constraints.md`
- **A**: An absolute address
- **B**: An offset address
- **W**: A register indirect memory operand
- **I**: A constant in the range of 0 to 255.
- **N**: A constant in the range of 0 to \(-255\).

#### MSP430—`config/msp430/constraints.md`
- **R12**: Register R12.
- **R13**: Register R13.
- **K**: Integer constant 1.
- **L**: Integer constant \(-20..1\)
- **M**: Integer constant 1-4.
- **Ya**: Memory references which do not require an extended MOVX instruction.
- **Yl**: Memory reference, labels only.
- **Ys**: Memory reference, stack only.

#### NDS32—`config/nds32/constraints.md`
- **w**: LOW register class $r0$ to $r7$ constraint for V3/V3M ISA.
- **l**: LOW register class $r0$ to $r7$.
- **d**: MIDDLE register class $r0$ to $r11$, $r16$ to $r19$.
- **h**: HIGH register class $r12$ to $r14$, $r20$ to $r31$.
- **t**: Temporary assist register $ta$ (i.e. $r15$).
- **k**: Stack register $sp$.
- **Iu03**: Unsigned immediate 3-bit value.
- **In03**: Negative immediate 3-bit value in the range of \(-7–0\).
- **Iu04**: Unsigned immediate 4-bit value.
- **Is05**: Signed immediate 5-bit value.
- **Iu05**: Unsigned immediate 5-bit value.
- **In05**: Negative immediate 5-bit value in the range of \(-31–0\).
- **Ip05**: Unsigned immediate 5-bit value for movpi45 instruction with range 16–47.
<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>Iu06</td>
<td>Unsigned immediate 6-bit value constraint for addri36.sp instruction.</td>
</tr>
<tr>
<td>Iu08</td>
<td>Unsigned immediate 8-bit value.</td>
</tr>
<tr>
<td>Iu09</td>
<td>Unsigned immediate 9-bit value.</td>
</tr>
<tr>
<td>Is10</td>
<td>Signed immediate 10-bit value.</td>
</tr>
<tr>
<td>Is11</td>
<td>Signed immediate 11-bit value.</td>
</tr>
<tr>
<td>Is15</td>
<td>Signed immediate 15-bit value.</td>
</tr>
<tr>
<td>Iu15</td>
<td>Unsigned immediate 15-bit value.</td>
</tr>
<tr>
<td>Ic15</td>
<td>A constant which is not in the range of imm15u but ok for bclr instruction.</td>
</tr>
<tr>
<td>Ie15</td>
<td>A constant which is not in the range of imm15u but ok for bset instruction.</td>
</tr>
<tr>
<td>It15</td>
<td>A constant which is not in the range of imm15u but ok for btgl instruction.</td>
</tr>
<tr>
<td>II15</td>
<td>A constant whose compliment value is in the range of imm15u and ok for bitci instruction.</td>
</tr>
<tr>
<td>Is16</td>
<td>Signed immediate 16-bit value.</td>
</tr>
<tr>
<td>Is17</td>
<td>Signed immediate 17-bit value.</td>
</tr>
<tr>
<td>Is19</td>
<td>Signed immediate 19-bit value.</td>
</tr>
<tr>
<td>Is20</td>
<td>Signed immediate 20-bit value.</td>
</tr>
<tr>
<td>Ihig</td>
<td>The immediate value that can be simply set high 20-bit.</td>
</tr>
<tr>
<td>Izeb</td>
<td>The immediate value 0xff.</td>
</tr>
<tr>
<td>Izeh</td>
<td>The immediate value 0xffff.</td>
</tr>
<tr>
<td>Ixls</td>
<td>The immediate value 0x01.</td>
</tr>
<tr>
<td>Ix11</td>
<td>The immediate value 0x7ff.</td>
</tr>
<tr>
<td>Ibms</td>
<td>The immediate value with power of 2.</td>
</tr>
<tr>
<td>Ifex</td>
<td>The immediate value with power of 2 minus 1.</td>
</tr>
<tr>
<td>U33</td>
<td>Memory constraint for 333 format.</td>
</tr>
<tr>
<td>U45</td>
<td>Memory constraint for 45 format.</td>
</tr>
<tr>
<td>U37</td>
<td>Memory constraint for 37 format.</td>
</tr>
</tbody>
</table>

*Nios II family—`config/nios2/constraints.md`*

<table>
<thead>
<tr>
<th>Code</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>I</td>
<td>Integer that is valid as an immediate operand in an instruction taking a signed 16-bit number. Range $-32768$ to $32767$.</td>
</tr>
<tr>
<td>J</td>
<td>Integer that is valid as an immediate operand in an instruction taking an unsigned 16-bit number. Range $0$ to $65535$.</td>
</tr>
</tbody>
</table>
K  Integer that is valid as an immediate operand in an instruction taking only the upper 16-bits of a 32-bit number. Range 32-bit numbers with the lower 16-bits being 0.
L  Integer that is valid as an immediate operand for a shift instruction. Range 0 to 31.
M  Integer that is valid as an immediate operand for only the value 0. Can be used in conjunction with the format modifier \texttt{z} to use \texttt{r0} instead of 0 in the assembly output.
N  Integer that is valid as an immediate operand for a custom instruction opcode. Range 0 to 255.
P  An immediate operand for R2 andc, andd, andci instructions.
S  Matches immediates which are addresses in the small data section and therefore can be added to \texttt{gp} as a 16-bit immediate to re-create their 32-bit value.
U  Matches constants suitable as an operand for the rdprs and cache instructions.
v  A memory operand suitable for Nios II R2 load/store exclusive instructions.
w  A memory operand suitable for load/store IO and cache instructions.
T  A \texttt{const} wrapped \texttt{UNSPEC} expression, representing a supported PIC or TLS relocation.

\textit{OpenRISC—`config/or1k/constraints.md’}

I  Integer that is valid as an immediate operand in an instruction taking a signed 16-bit number. Range $-32768$ to $32767$.
K  Integer that is valid as an immediate operand in an instruction taking an unsigned 16-bit number. Range 0 to 65535.
M  Signed 16-bit constant shifted left 16 bits. (Used with \texttt{l.movhi})
O  Zero
c  Register usable for sibcalls.

\textit{PDP-11—`config/pdp11/constraints.md’}

a  Floating point registers AC0 through AC3. These can be loaded from/to memory with a single instruction.
d  Odd numbered general registers (R1, R3, R5). These are used for 16-bit multiply operations.
D  A memory reference that is encoded within the opcode, but not auto-increment or auto-decrement.
f  Any of the floating point registers (AC0 through AC5).
Floating point constant 0.

Floating point registers AC4 and AC5. These cannot be loaded from/to memory with a single instruction.

An integer constant that fits in 16 bits.

An integer constant whose low order 16 bits are zero.

An integer constant that does not meet the constraints for codes ‘I’ or ‘J’.

The integer constant 1.

The integer constant −1.

The integer constant 0.

Integer constants 0 through 3; shifts by these amounts are handled as multiple single-bit shifts rather than a single variable-length shift.

A memory reference which requires an additional word (address or offset) after the opcode.

A memory reference that is encoded within the opcode.

A general purpose register (GPR), r0...r31.

A base register. Like r, but r0 is not allowed, so r1...r31.

A floating point register (FPR), f0...f31.

A floating point register. This is the same as f nowadays; historically f was for single-precision and d was for double-precision floating point.

An Altivec vector register (VR), v0...v31.

A VSX register (VSR), vs0...vs63. This is either an FPR (vs0...vs31 are f0...f31) or a VR (vs32...vs63 are v0...v31).

When using wa, you should use the %x output modifier, so that the correct register number is printed. For example:

```
asm ("xvadddp %x0,%x1,%x2"
     : "=wa" (v1)
     : "wa" (v2), "wa" (v3));
```

You should not use %x for v operands:

```
asm ("xsaddpp %0,%1,%2"
     : "=v" (v1)
     : "v" (v2), "v" (v3));
```

A special register (vrsave, ctr, or lr).

The count register, ctr.

The link register, lr.
Condition register field 0, cr0.

Any condition register field, cr0...cr7.

The carry bit, XER[CA].

Like wa, if `-mpower9-vector` and `-m64` are used; otherwise, NO_REGS.

No register (NO_REGS).

Like r, if `-mpowerpc64` is used; otherwise, NO_REGS.

Like d, if `-mpowerpc-gfxopt` is used; otherwise, NO_REGS.

Like b, if `-mpowerpc64` is used; otherwise, NO_REGS.

Signed 5-bit constant integer that can be loaded into an Altivec register.

Int constant that is the element number of the 64-bit scalar in a vector.

Vector constant that can be loaded with the XXSPLTIB instruction.

Memory operand suitable for power8 GPR load fusion.

Int constant that is the element number mfvsrld accesses in a vector.

Match vector constant with all 1’s if the XXLORC instruction is available.

Memory operand suitable for the ISA 3.0 vector d-form instructions.

Memory operand suitable for the load/store quad instructions.

Vector constant that can be loaded with XXSPLTIB & sign extension.

A memory operand for a DS-form instruction.

An indexed or indirect memory operand, ignoring the bottom 4 bits.

A signed 16-bit constant.

An unsigned 16-bit constant shifted left 16 bits (use L instead for SImode constants).

An unsigned 16-bit constant.

A signed 16-bit constant shifted left 16 bits.

An integer constant greater than 31.

An exact power of 2.

The integer constant zero.
P  A constant whose negation is a signed 16-bit constant.

eI  A signed 34-bit integer constant if prefixed instructions are supported.

G  A floating point constant that can be loaded into a register with one instruction per word.

H  A floating point constant that can be loaded into a register using three instructions.

m  A memory operand. Normally, m does not allow addresses that update the base register. If the < or > constraint is also used, they are allowed and therefore on PowerPC targets in that case it is only safe to use m<> in an _asm_ statement if that _asm_ statement accesses the operand exactly once. The _asm_ statement must also use %U<opno> as a placeholder for the “update” flag in the corresponding load or store instruction. For example:

```c
asm ("st%U0 %1,%0" : "=m<>" (mem) : "r" (val));
```

is correct but:

```c
asm ("st %1,%0" : "=m<>" (mem) : "r" (val));
```

is not.

es  A “stable” memory operand; that is, one which does not include any automodification of the base register. This used to be useful when m allowed automodification of the base register, but as those are now only allowed when < or > is used, es is basically the same as m without < and >.

Q  A memory operand addressed by just a base register.

Y  A memory operand for a DQ-form instruction.

Z  A memory operand accessed with indexed or indirect addressing.

R  An AIX TOC entry.

a  An indexed or indirect address.

U  A V.4 small data reference.

W  A vector constant that does not require memory.

j  The zero vector constant.

---

**PRU—`config/pru/constraints.md`**

I  An unsigned 8-bit integer constant.

J  An unsigned 16-bit integer constant.

L  An unsigned 5-bit integer constant (for shift counts).

T  A text segment (program memory) constant label.

Z  Integer constant zero.
<table>
<thead>
<tr>
<th>Symbol</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td><strong>Int3</strong></td>
<td>An integer constant in the range 1 . . . 7.</td>
</tr>
<tr>
<td><strong>Int8</strong></td>
<td>An integer constant in the range 0 . . . 255.</td>
</tr>
<tr>
<td><strong>J</strong></td>
<td>An integer constant in the range $-255 . . . 0$</td>
</tr>
<tr>
<td><strong>K</strong></td>
<td>The integer constant 1.</td>
</tr>
<tr>
<td><strong>L</strong></td>
<td>The integer constant -1.</td>
</tr>
<tr>
<td><strong>M</strong></td>
<td>The integer constant 0.</td>
</tr>
<tr>
<td><strong>N</strong></td>
<td>The integer constant 2.</td>
</tr>
<tr>
<td><strong>O</strong></td>
<td>The integer constant -2.</td>
</tr>
<tr>
<td><strong>P</strong></td>
<td>An integer constant in the range 1 . . . 15.</td>
</tr>
<tr>
<td><strong>Qbi</strong></td>
<td>The built-in compare types–eq, ne, gtu, ltu, geu, and leu.</td>
</tr>
<tr>
<td><strong>Qsc</strong></td>
<td>The synthetic compare types–gt, lt, ge, and le.</td>
</tr>
<tr>
<td><strong>Wab</strong></td>
<td>A memory reference with an absolute address.</td>
</tr>
<tr>
<td><strong>Wbc</strong></td>
<td>A memory reference using BC as a base register, with an optional offset.</td>
</tr>
<tr>
<td><strong>Wca</strong></td>
<td>A memory reference using AX, BC, DE, or HL for the address, for calls.</td>
</tr>
<tr>
<td><strong>Wcv</strong></td>
<td>A memory reference using any 16-bit register pair for the address, for calls.</td>
</tr>
<tr>
<td><strong>Wd2</strong></td>
<td>A memory reference using DE as a base register, with an optional offset.</td>
</tr>
<tr>
<td><strong>Wde</strong></td>
<td>A memory reference using DE as a base register, without any offset.</td>
</tr>
<tr>
<td><strong>Wfr</strong></td>
<td>Any memory reference to an address in the far address space.</td>
</tr>
<tr>
<td><strong>Wh1</strong></td>
<td>A memory reference using HL as a base register, with an optional one-byte offset.</td>
</tr>
<tr>
<td><strong>Whb</strong></td>
<td>A memory reference using HL as a base register, with B or C as the index register.</td>
</tr>
<tr>
<td><strong>Y</strong></td>
<td>Any memory reference to an address in the near address space.</td>
</tr>
<tr>
<td><strong>A</strong></td>
<td>The AX register.</td>
</tr>
<tr>
<td><strong>B</strong></td>
<td>The BC register.</td>
</tr>
<tr>
<td><strong>D</strong></td>
<td>The DE register.</td>
</tr>
<tr>
<td><strong>R</strong></td>
<td>A through L registers.</td>
</tr>
</tbody>
</table>
S The $SP$ register.
T The $HL$ register.
Z08W The 16-bit $R8$ register.
Z10W The 16-bit $R10$ register.
Zint The registers reserved for interrupts ($R24$ to $R31$).
a The $A$ register.
b The $B$ register.
c The $C$ register.
d The $D$ register.
e The $E$ register.
h The $H$ register.
l The $L$ register.
v The virtual registers.
w The $PSW$ register.
x The $X$ register.

RISC-V—‘config/riscv/constraints.md’
f A floating-point register (if available).
I An I-type 12-bit signed immediate.
J Integer zero.
K A 5-bit unsigned immediate for CSR access instructions.
A An address that is held in a general-purpose register.
S A constraint that matches an absolute symbolic address.

RX—‘config/rx/constraints.md’
Q An address which does not involve register indirect addressing or pre/post increment/decrement addressing.
Symbol A symbol reference.
Int08 A constant in the range $-256$ to $255$, inclusive.
Sint08 A constant in the range $-128$ to $127$, inclusive.
Sint16 A constant in the range $-32768$ to $32767$, inclusive.
Sint24 A constant in the range $-8388608$ to $8388607$, inclusive.
Uint04 A constant in the range $0$ to $15$, inclusive.

S/390 and zSeries—‘config/s390/s390.h’
a Address register (general purpose register except r0)
c  Condition code register

d  Data register (arbitrary general purpose register)

f  Floating-point register

I  Unsigned 8-bit constant (0–255)

J  Unsigned 12-bit constant (0–4095)

K  Signed 16-bit constant (−32768–32767)

L  Value appropriate as displacement.
   (0..4095)
   for short displacement
   (−524288..524287)
   for long displacement

M  Constant integer with a value of 0x7fffffff.

N  Multiple letter constraint followed by 4 parameter letters.
   0..9: number of the part counting from most to least significant
   H,Q: mode of the part
   D,S,H: mode of the containing operand
   0,F: value of the other parts (F—all bits set)

   The constraint matches if the specified part of a constant has a
   value different from its other parts.

Q  Memory reference without index register and with short displacement.

R  Memory reference with index register and short displacement.

S  Memory reference without index register but with long displacement.

T  Memory reference with index register and long displacement.

U  Pointer with short displacement.

W  Pointer with long displacement.

Y  Shift count operand.

SPARC—’config/sparc/sparc.h’

f  Floating-point register on the SPARC-V8 architecture and lower
   floating-point register on the SPARC-V9 architecture.

e  Floating-point register. It is equivalent to ‘f’ on the SPARC-V8
   architecture and contains both lower and upper floating-point reg-
   isters on the SPARC-V9 architecture.

c  Floating-point condition code register.
d  Lower floating-point register. It is only valid on the SPARC-V9 architecture when the Visual Instruction Set is available.

b  Floating-point register. It is only valid on the SPARC-V9 architecture when the Visual Instruction Set is available.

h  64-bit global or out register for the SPARC-V8+ architecture.

C  The constant all-ones, for floating-point.

A  Signed 5-bit constant

D  A vector constant

I  Signed 13-bit constant

J  Zero

K  32-bit constant with the low 12 bits clear (a constant that can be loaded with the `sethi` instruction)

L  A constant in the range supported by `movcc` instructions (11-bit signed immediate)

M  A constant in the range supported by `movrcc` instructions (10-bit signed immediate)

N  Same as ‘K’, except that it verifies that bits that are not in the lower 32-bit range are all zero. Must be used instead of ‘K’ for modes wider than `SImode`

O  The constant 4096

G  Floating-point zero

H  Signed 13-bit constant, sign-extended to 32 or 64 bits

P  The constant -1

Q  Floating-point constant whose integral representation can be moved into an integer register using a single `sethi` instruction

R  Floating-point constant whose integral representation can be moved into an integer register using a single `mov` instruction

S  Floating-point constant whose integral representation can be moved into an integer register using a `high/lo_sum` instruction sequence

T  Memory address aligned to an 8-byte boundary

U  Even register

W  Memory address for ‘e’ constraint registers

w  Memory address with only a base register

Y  Vector zero

*TI C6X family—`config/c6x/constraints.md`*

a  Register file A (A0–A31).
Register file B (B0–B31).

Predicate registers in register file A (A0–A2 on C64X and higher, A1 and A2 otherwise).

Predicate registers in register file B (B0–B2).

A call-used register in register file B (B0–B9, B16–B31).

Register file A, excluding predicate registers (A3–A31, plus A0 if not C64X or higher).

Register file B, excluding predicate registers (B3–B31).

Integer constant in the range 0 . . . 15.

Integer constant in the range 0 . . . 31.

Integer constant in the range –31 . . . 0.

Integer constant in the range –16 . . . 15.

Integer constant that can be the operand of an ADDA or a SUBA insn.

Integer constant in the range 0 . . . 65535.

Integer constant in the range –32768 . . . 32767.

Integer constant in the range $-2^{20}$ . . . $2^{20} - 1$.

Integer constant that is a valid mask for the clr instruction.

Integer constant that is a valid mask for the set instruction.

Memory location with A base register.

Memory location with B base register.

On C64x+ targets, a GP-relative small data reference.

Any kind of SYMBOL_REF, for use in a call address.

Any kind of immediate operand, unless it matches the S0 constraint.

Memory location with B base register, but not using a long offset.

A memory operand with an address that cannot be used in an unaligned access.

Register B14 (aka DP).
**TILE-Gx—`config/tilegx/constraints.md`**

<table>
<thead>
<tr>
<th>Register</th>
<th>Description</th>
</tr>
</thead>
<tbody>
<tr>
<td>R00</td>
<td>Each of these represents a register constraint for an individual register, from r0 to r10.</td>
</tr>
<tr>
<td>R01</td>
<td>Signed 8-bit integer constant.</td>
</tr>
<tr>
<td>R02</td>
<td>Signed 16-bit integer constant.</td>
</tr>
<tr>
<td>R03</td>
<td>Unsigned 16-bit integer constant.</td>
</tr>
<tr>
<td>R04</td>
<td>Integer constant that fits in one signed byte when incremented by one ((-129 \ldots 126)).</td>
</tr>
<tr>
<td>R05</td>
<td>Memory operand. If used together with '&lt;' or '&gt;', the operand can have postincrement which requires printing with '%%%n' and '%%%n' on TILE-Gx. For example:</td>
</tr>
<tr>
<td>R06</td>
<td>asm (&quot;st_add %I0,%1,%i0&quot; : &quot;=m&lt;&gt;&quot; (*mem) : &quot;r&quot; (val));</td>
</tr>
<tr>
<td>R07</td>
<td>A bit mask suitable for the BFINS instruction.</td>
</tr>
<tr>
<td>R08</td>
<td>Integer constant that is a byte tiled out eight times.</td>
</tr>
<tr>
<td>R09</td>
<td>The integer zero constant.</td>
</tr>
<tr>
<td>R10</td>
<td>Integer constant that is a sign-extended byte tiled out as four shorts.</td>
</tr>
<tr>
<td></td>
<td>Integer constant that fits in one signed byte when incremented ((-129 \ldots 126)), but excluding -1.</td>
</tr>
<tr>
<td></td>
<td>Integer constant that has all 1 bits consecutive and starting at bit 0.</td>
</tr>
<tr>
<td>T</td>
<td>A 16-bit fragment of a got, tls, or pc-relative reference.</td>
</tr>
<tr>
<td>U</td>
<td>Memory operand except postincrement. This is roughly the same as 'm' when not used together with '&lt;' or '&gt;'.</td>
</tr>
<tr>
<td>W</td>
<td>An 8-element vector constant with identical elements.</td>
</tr>
<tr>
<td>Y</td>
<td>A 4-element vector constant with identical elements.</td>
</tr>
<tr>
<td>Z0</td>
<td>The integer constant 0xffffffff.</td>
</tr>
<tr>
<td>Z1</td>
<td>The integer constant 0xffffffff00000000.</td>
</tr>
</tbody>
</table>
TILEPro—‘config/tilepro/constraints.md’

R00
R01
R02
R03
R04
R05
R06
R07
R08
R09
R10

Each of these represents a register constraint for an individual register, from r0 to r10.

I
Signed 8-bit integer constant.

J
Signed 16-bit integer constant.

K
Nonzero integer constant with low 16 bits zero.

L
Integer constant that fits in one signed byte when incremented by one (−129 ... 126).

m
Memory operand. If used together with ‘<’ or ‘>’, the operand can have postincrement which requires printing with ‘%In’ and ‘%in’ on TILEPro. For example:

```assembly
asm ("swadd %r0,%r1,%i0" : "=m<>" (mem) : "r" (val));
```

M
A bit mask suitable for the MM instruction.

N
Integer constant that is a byte tiled out four times.

O
The integer zero constant.

P
Integer constant that is a sign-extended byte tiled out as two shorts.

Q
Integer constant that fits in one signed byte when incremented (−129 ... 126), but excluding -1.

T
A symbolic operand, or a 16-bit fragment of a got, tls, or pc-relative reference.

U
Memory operand except postincrement. This is roughly the same as ‘m’ when not used together with ‘<’ or ‘>’.

W
A 4-element vector constant with identical elements.

Y
A 2-element vector constant with identical elements.

Visium—‘config/visium/constraints.md’

b
EAM register mdb

c
EAM register mdc

f
Floating point register

k
Register for sibcall optimization
General register, but not r29, r30 and r31

Register r1

Register r2

Register r3

Floating-point constant 0.0

Integer constant in the range 0 .. 65535 (16-bit immediate)

Integer constant in the range 1 .. 31 (5-bit immediate)

Integer constant in the range −65535 .. −1 (16-bit negative immediate)

Integer constant −1

Integer constant 0

Integer constant 32

*x86 family—*config/i386/constraints.md*

Legacy register—the eight integer registers available on all i386 processors (a, b, c, d, si, di, bp, sp).

Any register accessible as r1. In 32-bit mode, a, b, c, and d; in 64-bit mode, any integer register.

Any register accessible as rh: a, b, c, and d.

Any register that can be used as the index in a base+index memory access: that is, any general register except the stack pointer.

The a register.

The b register.

The c register.

The d register.

The si register.

The di register.

The a and d registers. This class is used for instructions that return double word results in the ax:dx register pair. Single word values will be allocated either in ax or dx. For example on i386 the following implements rdtsc:

```c
unsigned long long rdtsc (void)
{
    unsigned long long tick;
    __asm__ __volatile__("rdtsc":"A"(tick));
    return tick;
}
```

This is not correct on x86-64 as it would allocate tick in either ax or dx. You have to use the following variant instead:
unsigned long long rdtsc (void)
{
    unsigned int tickl, tickh;
    __asm__ __volatile__("rdtsc":"=a"(tickl),"=d"(tickh));
    return ((unsigned long long)tickh << 32)|tickl;
}

U The call-clobbered integer registers.
f Any 80387 floating-point (stack) register.
t Top of 80387 floating-point stack (%st(0)).
u Second from top of 80387 floating-point stack (%st(1)).
Yk Any mask register that can be used as a predicate, i.e. k1-k7.
k Any mask register.
y Any MMX register.
x Any SSE register.
v Any EVEX encodable SSE register (%xmm0-%xmm31).
w Any bound register.
Yz First SSE register (%xmm0).
Yi Any SSE register, when SSE2 and inter-unit moves are enabled.
Yj Any SSE register, when SSE2 and inter-unit moves from vector registers are enabled.
Ym Any MMX register, when inter-unit moves are enabled.
Yn Any MMX register, when inter-unit moves from vector registers are enabled.
Yp Any integer register when TARGET_PARTIAL_REG_STALL is disabled.
Ya Any integer register when zero extensions with AND are disabled.
Yb Any register that can be used as the GOT base when calling ___tls_get_addr: that is, any general register except a and sp registers, for ‘-fno-plt’ if linker supports it. Otherwise, b register.
Yf Any x87 register when 80387 floating-point arithmetic is enabled.
Yr Lower SSE register when avoiding REX prefix and all SSE registers otherwise.
Yv For AVX512VL, any EVEX-encodable SSE register (%xmm0-%xmm31), otherwise any SSE register.
Yh Any EVEX-encodable SSE register, that has number factor of four.
Bf Flags register operand.
Bg GOT memory operand.
Bm Vector memory operand.
Bc  Constant memory operand.
Bn  Memory operand without REX prefix.
Bs  Sibcall memory operand.
Bw  Call memory operand.
Bz  Constant call address operand.
BC  SSE constant -1 operand.
I   Integer constant in the range 0 . . . 31, for 32-bit shifts.
J   Integer constant in the range 0 . . . 63, for 64-bit shifts.
K   Signed 8-bit integer constant.
L   0xFF or 0xFFFF, for andsi as a zero-extending move.
M   0, 1, 2, or 3 (shifts for the lea instruction).
N   Unsigned 8-bit integer constant (for in and out instructions).
O   Integer constant in the range 0 . . . 127, for 128-bit shifts.
G   Standard 80387 floating point constant.
C   SSE constant zero operand.
e  32-bit signed integer constant, or a symbolic reference known to fit that range (for immediate operands in sign-extending x86-64 instructions).
We 32-bit signed integer constant, or a symbolic reference known to fit that range (for sign-extending conversion operations that require non-VOIDmode immediate operands).
Wz 32-bit unsigned integer constant, or a symbolic reference known to fit that range (for zero-extending conversion operations that require non-VOIDmode immediate operands).
Wd 128-bit integer constant where both the high and low 64-bit word satisfy the e constraint.
Z  32-bit unsigned integer constant, or a symbolic reference known to fit that range (for immediate operands in zero-extending x86-64 instructions).
Tv  VSIB address operand.
Ts  Address operand without segment register.

Xstormy16—‘config/stormy16/stormy16.h’
a  Register r0.
b  Register r1.
c  Register r2.
d  Register r8.
e Registers r0 through r7.
t Registers r0 and r1.
y The carry register.
z Registers r8 and r9.
I A constant between 0 and 3 inclusive.
J A constant that has exactly one bit set.
K A constant that has exactly one bit clear.
L A constant between 0 and 255 inclusive.
M A constant between −255 and 0 inclusive.
N A constant between −3 and 0 inclusive.
O A constant between 1 and 4 inclusive.
P A constant between −4 and −1 inclusive.
Q A memory reference that is a stack push.
R A memory reference that is a stack pop.
S A memory reference that refers to a constant address of known value.
T The register indicated by Rx (not implemented yet).
U A constant that is not between 2 and 15 inclusive.
Z The constant 0.

Xtensa—‘config/xtensa/constraints.md’
a General-purpose 32-bit register
b One-bit boolean register
A MAC16 40-bit accumulator register
I Signed 12-bit integer constant, for use in MOVI instructions
J Signed 8-bit integer constant, for use in ADDI instructions
K Integer constant valid for BccI instructions
L Unsigned constant valid for BccUI instructions

17.8.6 Disable insn alternatives using the enabled attribute

There are three insn attributes that may be used to selectively disable instruction alternatives:

enabled Says whether an alternative is available on the current subtarget.

preferred_for_size
Says whether an enabled alternative should be used in code that is optimized for size.
preferred_for_speed

Says whether an enabled alternative should be used in code that is optimized for speed.

All these attributes should use \texttt{(const\_int\ 1)} to allow an alternative or \texttt{(const\_int\ 0)} to disallow it. The attributes must be a static property of the subtarget; they cannot for example depend on the current operands, on the current optimization level, on the location of the insn within the body of a loop, on whether register allocation has finished, or on the current compiler pass.

The \texttt{enabled} attribute is a correctness property. It tells GCC to act as though the disabled alternatives were never defined in the first place. This is useful when adding new instructions to an existing pattern in cases where the new instructions are only available for certain cpu architecture levels (typically mapped to the \texttt{-march=} command-line option).

In contrast, the \texttt{preferred\_for\_size} and \texttt{preferred\_for\_speed} attributes are strong optimization hints rather than correctness properties. \texttt{preferred\_for\_size} tells GCC which alternatives to consider when adding or modifying an instruction that GCC wants to optimize for size. \texttt{preferred\_for\_speed} does the same thing for speed. Note that things like code motion can lead to cases where code optimized for size uses alternatives that are not preferred for size, and similarly for speed.

Although \texttt{define\_insn}s can in principle specify the \texttt{enabled} attribute directly, it is often clearer to have subsiduary attributes for each architectural feature of interest. The \texttt{define\_insn}s can then use these subsiduary attributes to say which alternatives require which features. The example below does this for \texttt{cpu\_facility}.

E.g. the following two patterns could easily be merged using the \texttt{enabled} attribute:

\begin{verbatim}
(define_insn "*movdi_old"
  [(set (match_operand:DI 0 "register_operand" ";=d")
        (match_operand:DI 1 "register_operand" " d")))
  "TARGET_NEW"
  "lgr %0,%1"
)

(define_insn "*movdi_new"
  [(set (match_operand:DI 0 "register_operand" "=d,f,d")
        (match_operand:DI 1 "register_operand" " d,d,f")))
  "TARGET_NEW"
  "@lgr %0,%1"
  "ldgr %0,%1"
  "lgdr %0,%1"
)
\end{verbatim}

\begin{verbatim}
to:

(define_insn "*movdi_combined"
  [(set (match_operand:DI 0 "register_operand" ";=d,f,d")
        (match_operand:DI 1 "register_operand" " d,d,f")))
  ""
  "@lgr %0,%1"
  "ldgr %0,%1"
  "lgdr %0,%1"
  [(set_attr "cpu\_facility" ";*,new,new")]
\end{verbatim}
with the `enabled` attribute defined like this:

```lisp
(define_attr "cpu_facility" "standard,new" (const_string "standard"))

(define_attr "enabled" ""
  (cond [(eq_attr "cpu_facility" "standard") (const_int 1)
        (and (eq_attr "cpu_facility" "new")
             (ne (symbol_ref "TARGET_NEW") (const_int 0)))
        (const_int 1)]
        (const_int 0)))
```

### 17.8.7 Defining Machine-Specific Constraints

Machine-specific constraints fall into two categories: register and non-register constraints. Within the latter category, constraints which allow subsets of all possible memory or address operands should be specially marked, to give `reload` more information.

Machine-specific constraints can be given names of arbitrary length, but they must be entirely composed of letters, digits, underscores (`_`), and angle brackets (`< >`). Like C identifiers, they must begin with a letter or underscore.

In order to avoid ambiguity in operand constraint strings, no constraint can have a name that begins with any other constraint’s name. For example, if `x` is defined as a constraint name, `xy` may not be, and vice versa. As a consequence of this rule, no constraint may begin with one of the generic constraint letters: `E F V X g i m n o p r s`.

Register constraints correspond directly to register classes. See Section 18.8 [Register Classes], page 530. There is thus not much flexibility in their definitions.

```lisp
define_register_constraint name regclass docstring
```

All three arguments are string constants. `name` is the name of the constraint, as it will appear in `match_operand` expressions. If `name` is a multi-letter constraint its length shall be the same for all constraints starting with the same letter. `regclass` can be either the name of the corresponding register class (see Section 18.8 [Register Classes], page 530), or a C expression which evaluates to the appropriate register class. If it is an expression, it must have no side effects, and it cannot look at the operand. The usual use of expressions is to map some register constraints to `NO_REGS` when the register class is not available on a given subarchitecture.

`docstring` is a sentence documenting the meaning of the constraint. Docstrings are explained further below.

Non-register constraints are more like predicates: the constraint definition gives a boolean expression which indicates whether the constraint matches.

```lisp
define_constraint name docstring exp
```

The `name` and `docstring` arguments are the same as for `define_register_constraint`, but note that the docstring comes immediately after the name for these expressions. `exp` is an RTL expression, obeying the same rules as the RTL expressions in predicate definitions. See Section 17.7.2 [Defining Predicates], page 360, for details. If it evaluates true, the constraint matches; if it evaluates false,
it doesn’t. Constraint expressions should indicate which RTL codes they might match, just like predicate expressions.

**match_test**  
C expressions have access to the following variables:

- **op**  
  The RTL object defining the operand.

- **mode**  
  The machine mode of op.

- **ival**  
  ‘`INTVAL (op)`’, if op is a const_int.

- **hval**  
  ‘`CONST_DOUBLE_HIGH (op)`’, if op is an integer const_double.

- **lval**  
  ‘`CONST_DOUBLE_LOW (op)`’, if op is an integer const_double.

- **rval**  
  ‘`CONST_DOUBLE_REAL_VALUE (op)`’, if op is a floating-point const_double.

The *val variables should only be used once another piece of the expression has verified that op is the appropriate kind of RTL object.

Most non-register constraints should be defined with `define_constraint`. The remaining two definition expressions are only appropriate for constraints that should be handled specially by `reload` if they fail to match.

**define_memory_constraint**  
*name* *docstring* *exp*  
[MD Expression]

Use this expression for constraints that match a subset of all memory operands: that is, `reload` can make them match by converting the operand to the form ‘`(mem (reg X))`’, where X is a base register (from the register class specified by `BASE_REG_CLASS`, see Section 18.8 [Register Classes], page 530).

For example, on the S/390, some instructions do not accept arbitrary memory references, but only those that do not make use of an index register. The constraint letter ‘Q’ is defined to represent a memory address of this type. If ‘Q’ is defined with `define_memory_constraint`, a ‘Q’ constraint can handle any memory operand, because `reload` knows it can simply copy the memory address into a base register if required. This is analogous to the way an ‘o’ constraint can handle any memory operand.

The syntax and semantics are otherwise identical to `define_constraint`.

**define_special_memory_constraint**  
*name* *docstring* *exp*  
[MD Expression]

Use this expression for constraints that match a subset of all memory operands: that is, `reload` cannot make them match by reloading the address as it is described for `define_memory_constraint` or such address reload is undesirable with the performance point of view.

For example, `define_special_memory_constraint` can be useful if specifically aligned memory is necessary or desirable for some insn operand.

The syntax and semantics are otherwise identical to `define_memory_constraint`.

**define_relaxed_memory_constraint**  
*name* *docstring* *exp*  
[MD Expression]

The test expression in a `define_memory_constraint` can assume that `TARGET_LEGITIMATE_ADDRESS_P` holds for the address inside a `mem rtx` and so it does not need to test this condition itself. In other words, a `define_memory_constraint` test of the form:
is enough to test whether an rtx is a mem and whether its address satisfies TARGET_MEM_CONSTRAINT (which is usually ‘m’). Thus the conditions imposed by a define_memory_constraint always apply on top of the conditions imposed by TARGET_MEM_CONSTRAINT.

However, it is sometimes useful to define memory constraints that allow addresses beyond those accepted by TARGET_LEGITIMATE_ADDRESS_P. define_relaxed_memory_constraint exists for this case. The test expression in a define_relaxed_memory_constraint is applied with no preconditions, so that the expression can determine “from scratch” exactly which addresses are valid and which are not.

The syntax and semantics are otherwise identical to define_memory_constraint.

define_address_constraint name docstring exp

Use this expression for constraints that match a subset of all address operands: that is, reload can make the constraint match by converting the operand to the form ‘(reg X)’, again with X a base register.

Constraints defined with define_address_constraint can only be used with the address_operand predicate, or machine-specific predicates that work the same way. They are treated analogously to the generic ‘p’ constraint.

The syntax and semantics are otherwise identical to define_constraint.

For historical reasons, names beginning with the letters ‘G H’ are reserved for constraints that match only const_doubles, and names beginning with the letters ‘I J K L M N O P’ are reserved for constraints that match only const_ints. This may change in the future. For the time being, constraints with these names must be written in a stylized form, so that genpreds can tell you did it correctly:

(define_constraint "[GHIJKLMNOP]..."
 "doc...
 (and (match_code "const_int") ; const_double for G/H
 condition...)) ; usually a match_test

It is fine to use names beginning with other letters for constraints that match const_doubles or const_ints.

Each docstring in a constraint definition should be one or more complete sentences, marked up in Texinfo format. They are currently unused. In the future they will be copied into the GCC manual, in Section 17.8.5 [Machine Constraints], page 369, replacing the hand-maintained tables currently found in that section. Also, in the future the compiler may use this to give more helpful diagnostics when poor choice of asm constraints causes a reload failure.

If you put the pseudo-Texinfo directive ‘@internal’ at the beginning of a docstring, then (in the future) it will appear only in the internals manual’s version of the machine-specific constraint tables. Use this for constraints that should not appear in asm statements.

17.8.8 Testing constraints from C

It is occasionally useful to test a constraint from C code rather than implicitly via the constraint string in a match_operand. The generated file ‘tm_p.h’ declares a few interfaces for working with constraints. At present these are defined for all constraints except g (which is equivalent to general_operand).
Some valid constraint names are not valid C identifiers, so there is a mangling scheme for referring to them from C. Constraint names that do not contain angle brackets or underscores are left unchanged. Underscores are doubled, each ‘<’ is replaced with ‘-_l’, and each ‘>’ with ‘-_g’. Here are some examples:

<table>
<thead>
<tr>
<th>Original</th>
<th>Mangled</th>
</tr>
</thead>
<tbody>
<tr>
<td>x</td>
<td>x</td>
</tr>
<tr>
<td>P42x</td>
<td>P42x</td>
</tr>
<tr>
<td>P4_x</td>
<td>P4__x</td>
</tr>
<tr>
<td>P4&gt;x</td>
<td>P4_gx</td>
</tr>
<tr>
<td>P4&gt;&gt;</td>
<td>P4_g_g</td>
</tr>
<tr>
<td>P4_g&gt;</td>
<td>P4__g_g</td>
</tr>
</tbody>
</table>

Throughout this section, the variable \( c \) is either a constraint in the abstract sense, or a constant from `enum constraint_num`; the variable \( m \) is a mangled constraint name (usually as part of a larger identifier).

**constraint_num**

For each constraint except \( g \), there is a corresponding enumeration constant: ‘CONSTRAINT_’ plus the mangled name of the constraint. Functions that take an `enum constraint_num` as an argument expect one of these constants.

**inline bool satisfies_constraint_m (rtx exp)**

For each non-register constraint \( m \) except \( g \), there is one of these functions; it returns `true` if \( exp \) satisfies the constraint. These functions are only visible if ‘rtl.h’ was included before ‘tm_p.h’.

**bool constraint_satisfied_p (rtx exp, enum constraint_num c)**

Like the `satisfies_constraint_m` functions, but the constraint to test is given as an argument, \( c \). If \( c \) specifies a register constraint, this function will always return `false`.

**enum reg_class reg_class_for_constraint (enum constraint_num c)**

Returns the register class associated with \( c \). If \( c \) is not a register constraint, or those registers are not available for the currently selected subtarget, returns `NO_REGS`.

Here is an example use of `satisfies_constraint_m`. In peephole optimizations (see Section 17.18 [Peephole Definitions], page 463), operand constraint strings are ignored, so if there are relevant constraints, they must be tested in the C condition. In the example, the optimization is applied if operand 2 does not satisfy the ‘K’ constraint. (This is a simplified version of a peephole definition from the i386 machine description.)

```c
(define_peephole2
  [(match_scratch:SI 3 "r")
   (set (match_operand:SI 0 "register_operand" "")
        (mult:SI (match_operand:SI 1 "memory_operand" "")
                 (match_operand:SI 2 "immediate_operand" "")))
   "!satisfies_constraint_K (operands[2])"
   [(set (match_dup 3) (match_dup 1))
    (set (match_dup 0) (mult:SI (match_dup 3) (match_dup 2)))]
```


17.9 Standard Pattern Names For Generation

Here is a table of the instruction names that are meaningful in the RTL generation pass of the compiler. Giving one of these names to an instruction pattern tells the RTL generation pass that it can use the pattern to accomplish a certain task.

`movm`  Here $m$ stands for a two-letter machine mode name, in lowercase. This instruction pattern moves data with that machine mode from operand 1 to operand 0. For example, `movsi` moves full-word data.

If operand 0 is a `subreg` with mode $m$ of a register whose own mode is wider than $m$, the effect of this instruction is to store the specified value in the part of the register that corresponds to mode $m$. Bits outside of $m$, but which are within the same target word as the `subreg` are undefined. Bits which are outside the target word are left unchanged.

This class of patterns is special in several ways. First of all, each of these names up to and including full word size must be defined, because there is no other way to copy a datum from one place to another. If there are patterns accepting operands in larger modes, `movm` must be defined for integer modes of those sizes.

Second, these patterns are not used solely in the RTL generation pass. Even the reload pass can generate move insns to copy values from stack slots into temporary registers. When it does so, one of the operands is a hard register and the other is an operand that can need to be reloaded into a register. Therefore, when given such a pair of operands, the pattern must generate RTL which needs no reloading and needs no temporary registers—no registers other than the operands. For example, if you support the pattern with a `define_expand`, then in such a case the `define_expand` mustn’t call `force_reg` or any other such function which might generate new pseudo registers.

This requirement exists even for subword modes on a RISC machine where fetching those modes from memory normally requires several insns and some temporary registers.

During reload a memory reference with an invalid address may be passed as an operand. Such an address will be replaced with a valid address later in the reload pass. In this case, nothing may be done with the address except to use it as it stands. If it is copied, it will not be replaced with a valid address. No attempt should be made to make such an address into a valid address and no routine (such as `change_address`) that will do so may be called. Note that `general_operand` will fail when applied to such an address.

The global variable `reload_in_progress` (which must be explicitly declared if required) can be used to determine whether such special handling is required. The variety of operands that have reloads depends on the rest of the machine description, but typically on a RISC machine these can only be pseudo registers that did not get hard registers, while on other machines explicit memory references will get optional reloads.
If a scratch register is required to move an object to or from memory, it can be allocated using `gen_reg_rtx` prior to life analysis.

If there are cases which need scratch registers during or after reload, you must provide an appropriate secondary_reload target hook.

The macro `can_create_pseudo_p` can be used to determine if it is unsafe to create new pseudo registers. If this variable is nonzero, then it is unsafe to call `gen_reg_rtx` to allocate a new pseudo.

The constraints on a `movm` must permit moving any hard register to any other hard register provided that `TARGET_HARD_REGNO_MODE_OK` permits mode \( m \) in both registers and `TARGET_REGISTER_MOVE_COST` applied to their classes returns a value of 2.

It is obligatory to support floating point `movm` instructions into and out of any registers that can hold fixed point values, because unions and structures (which have modes `SImode` or `DImode`) can be in those registers and they may have floating point members.

There may also be a need to support fixed point `movm` instructions in and out of floating point registers. Unfortunately, I have forgotten why this was so, and I don’t know whether it is still true. If `TARGET_HARD_REGNO_MODE_OK` rejects fixed point values in floating point registers, then the constraints of the fixed point `movm` instructions must be designed to avoid ever trying to reload into a floating point register.

`reload_in` and `reload_out` These named patterns have been obsoleted by the target hook `secondary_reload`.

Like `movm`, but used when a scratch register is required to move between operand 0 and operand 1. Operand 2 describes the scratch register. See the discussion of the `SECONDARY_RELOAD_CLASS` macro in see Section 18.8 [Register Classes], page 530.

There are special restrictions on the form of the `match_operands` used in these patterns. First, only the predicate for the reload operand is examined, i.e., `reload_in` examines operand 1, but not the predicates for operand 0 or 2. Second, there may be only one alternative in the constraints. Third, only a single register class letter may be used for the constraint; subsequent constraint letters are ignored. As a special exception, an empty constraint string matches the `ALL_REGS` register class. This may relieve ports of the burden of defining an `ALL_REGS` constraint letter just for these patterns.

`movstrict` Like `movm` except that if operand 0 is a subreg with mode \( m \) of a register whose natural mode is wider, the `movstrict` instruction is guaranteed not to alter any of the register except the part which belongs to mode \( m \).

`movmisalignm` This variant of a move pattern is designed to load or store a value from a memory address that is not naturally aligned for its mode. For a store, the
memory will be in operand 0; for a load, the memory will be in operand 1. The other operand is guaranteed not to be a memory, so that it's easy to tell whether this is a load or store.

This pattern is used by the autovectorizer, and when expanding a MISALIGNED INDIRECT_REF expression.

`load_multiple`
Load several consecutive memory locations into consecutive registers. Operand 0 is the first of the consecutive registers, operand 1 is the first memory location, and operand 2 is a constant: the number of consecutive registers.

Define this only if the target machine really has such an instruction; do not define this if the most efficient way of loading consecutive registers from memory is to do them one at a time.

On some machines, there are restrictions as to which consecutive registers can be stored into memory, such as particular starting or ending register numbers or only a range of valid counts. For those machines, use a define_expand (see Section 17.15 [Expander Definitions], page 454) and make the pattern fail if the restrictions are not met.

Write the generated insn as a parallel with elements being a set of one register from the appropriate memory location (you may also need use or clobber elements). Use a match_parallel (see Section 17.4 [RTL Template], page 351) to recognize the insn. See ‘rs6000.md’ for examples of the use of this insn pattern.

`store_multiple`
Similar to `load_multiple`, but store several consecutive registers into consecutive memory locations. Operand 0 is the first of the consecutive memory locations, operand 1 is the first register, and operand 2 is a constant: the number of consecutive registers.

`vec_load_lanesmn`
Perform an interleaved load of several vectors from memory operand 1 into register operand 0. Both operands have mode m. The register operand is viewed as holding consecutive vectors of mode n, while the memory operand is a flat array that contains the same number of elements. The operation is equivalent to:

```c
int c = GET_MODE_SIZE (m) / GET_MODE_SIZE (n);
for (j = 0; j < GET_MODE_NUNITS (n); j++)
  for (i = 0; i < c; i++)
    operand0[i][j] = operand1[j * c + i];
```

For example, ‘vec_load_lanestiv4hi’ loads 8 16-bit values from memory into a register of mode ‘TI’. The register contains two consecutive vectors of mode ‘V4HI’.

This pattern can only be used if:

TARGET_ARRAY_MODE_SUPPORTED_P (n, c)

is true. GCC assumes that, if a target supports this kind of instruction for some mode n, it also supports unaligned loads for vectors of mode n.

This pattern is not allowed to FAIL.
'vec_mask_load_lanesmn'
Like 'vec_load_lanesmn', but takes an additional mask operand (operand 2) that specifies which elements of the destination vectors should be loaded. Other elements of the destination vectors are set to zero. The operation is equivalent to:

```c
int c = GET_MODE_SIZE (m) / GET_MODE_SIZE (n);
for (j = 0; j < GET_MODE_NUNITS (n); j++)
    if (operand2[j])
        for (i = 0; i < c; i++)
            operand0[i][j] = operand1[j * c + i];
    else
        for (i = 0; i < c; i++)
            operand0[i][j] = 0;
```

This pattern is not allowed to FAIL.

'vec_store_lanesmn'
Equivalent to 'vec_load_lanesmn', with the memory and register operands reversed. That is, the instruction is equivalent to:

```c
int c = GET_MODE_SIZE (m) / GET_MODE_SIZE (n);
for (j = 0; j < GET_MODE_NUNITS (n); j++)
    for (i = 0; i < c; i++)
        operand0[j * c + i] = operand1[i][j];
```

for a memory operand 0 and register operand 1.

This pattern is not allowed to FAIL.

'vec_mask_store_lanesmn'
Like 'vec_store_lanesmn', but takes an additional mask operand (operand 2) that specifies which elements of the source vectors should be stored. The operation is equivalent to:

```c
int c = GET_MODE_SIZE (m) / GET_MODE_SIZE (n);
for (j = 0; j < GET_MODE_NUNITS (n); j++)
    if (operand2[j])
        for (i = 0; i < c; i++)
            operand0[j * c + i] = operand1[i][j];
```

This pattern is not allowed to FAIL.

'gather_loadmn'
Load several separate memory locations into a vector of mode m. Operand 1 is a scalar base address and operand 2 is a vector of mode n containing offsets from that base. Operand 0 is a destination vector with the same number of elements as n. For each element index i:

- extend the offset element i to address width, using zero extension if operand 3 is 1 and sign extension if operand 3 is zero;
- multiply the extended offset by operand 4;
- add the result to the base; and
- load the value at that address into element i of operand 0.

The value of operand 3 does not matter if the offsets are already address width.
'mask_gather_loadmn'
Like 'gather_loadmn', but takes an extra mask operand as operand 5. Bit i of
the mask is set if element i of the result should be loaded from memory and
clear if element i of the result should be set to zero.

'scatter_storemn'
Store a vector of mode m into several distinct memory locations. Operand 0
is a scalar base address and operand 1 is a vector of mode n containing offsets
from that base. Operand 4 is the vector of values that should be stored, which
has the same number of elements as n. For each element index i:

- extend the offset element i to address width, using zero extension if operand
  2 is 1 and sign extension if operand 2 is zero;
- multiply the extended offset by operand 3;
- add the result to the base; and
- store element i of operand 4 to that address.

The value of operand 2 does not matter if the offsets are already address width.

'mask_scatter_storemn'
Like 'scatter_storemn', but takes an extra mask operand as operand 5. Bit i
of the mask is set if element i of the result should be stored to memory.

'vec_setmn'
Set given field in the vector value. Operand 0 is the vector to modify, operand
1 is new value of field and operand 2 specify the field index.

'vec_extractmn'
Extract given field from the vector value. Operand 1 is the vector, operand
2 specify field index and operand 0 place to store value into. The n mode is
the mode of the field or vector of fields that should be extracted, should be
either element mode of the vector mode m, or a vector mode with the same
element mode and smaller number of elements. If n is a vector mode, the index
is counted in units of that mode.

'vec_initmn'
Initialize the vector to given values. Operand 0 is the vector to initialize and
operand 1 is parallel containing values for individual fields. The n mode is the
mode of the elements, should be either element mode of the vector mode m, or
a vector mode with the same element mode and smaller number of elements.

'vec_duplicatemn'
Initialize vector output operand 0 so that each element has the value given by
scalar input operand 1. The vector has mode m and the scalar has the mode
appropriate for one element of m.

This pattern only handles duplicates of non-constant inputs. Constant vectors
go through the movm pattern instead.

This pattern is not allowed to FAIL.
Initialize vector output operand 0 so that element \( i \) is equal to operand 1 plus \( i \) times operand 2. In other words, create a linear series whose base value is operand 1 and whose step is operand 2.

The vector output has mode \( m \) and the scalar inputs have the mode appropriate for one element of \( m \). This pattern is not used for floating-point vectors, in order to avoid having to specify the rounding behavior for \( i > 1 \).

This pattern is not allowed to FAIL.

Set operand 0 to a mask that is true while incrementing operand 1 gives a value that is less than operand 2. Operand 0 has mode \( n \) and operands 1 and 2 are scalar integers of mode \( m \). The operation is equivalent to:

```c
operand0[0] = operand1 < operand2;
for (i = 1; i < GET_MODE_NUNITS (n); i++)
  operand0[i] = operand0[i - 1] && (operand1 + i < operand2);
```

Check whether, given two pointers \( a \) and \( b \) and a length \( len \), a write of \( len \) bytes at \( a \) followed by a read of \( len \) bytes at \( b \) can be split into interleaved byte accesses ‘\( a[0] \), \( b[0] \), \( a[1] \), \( b[1] \), …’ without affecting the dependencies between the bytes. Set operand 0 to true if the split is possible and false otherwise.

Operands 1, 2 and 3 provide the values of \( a \), \( b \) and \( len \) respectively. Operand 4 is a constant integer that provides the known common alignment of \( a \) and \( b \). All inputs have mode \( m \).

This split is possible if:

\[
a = b || a + len <= b || b + len <= a
\]

You should only define this pattern if the target has a way of accelerating the test without having to do the individual comparisons.

Like ‘check_raw_ptrs’, but with the read and write swapped round. The split is possible in this case if:

\[
b <= a || a + len <= b
\]

Output a vector comparison. Operand 0 of mode \( n \) is the destination for predicate in operand 1 which is a signed vector comparison with operands of mode \( m \) in operands 2 and 3. Predicate is computed by element-wise evaluation of the vector comparison with a truth value of all-ones and a false value of all-zeros.

Similar to \( vec_cmpmn \) but perform unsigned vector comparison.

Similar to \( vec_cmpmn \) but perform equality or non-equality vector comparison only. If \( vec_cmpmn \) or \( vec_cmpumn \) instruction pattern is supported, it will be preferred over \( vec_cmpeqmn \), so there is no need to define this instruction pattern if the others are supported.
`vcondmn` Output a conditional vector move. Operand 0 is the destination to receive a combination of operand 1 and operand 2, which are of mode \( m \), dependent on the outcome of the predicate in operand 3 which is a signed vector comparison with operands of mode \( n \) in operands 4 and 5. The modes \( m \) and \( n \) should have the same size. Operand 0 will be set to the value \( \text{op1} \& \text{msk} | \text{op2} \& \sim \text{msk} \) where \( \text{msk} \) is computed by element-wise evaluation of the vector comparison with a truth value of all-ones and a false value of all-zeros.

`vcondum` Similar to `vcondmn` but performs unsigned vector comparison.

`vcondeqmn` Similar to `vcondmn` but performs equality or non-equality vector comparison only. If `vcondmn` or `vcondum` instruction pattern is supported, it will be preferred over `vcondeqmn`, so there is no need to define this instruction pattern if the others are supported.

`vcond_mask_mn` Similar to `vcondmn` but operand 3 holds a pre-computed result of vector comparison.

`maskloadmn` Perform a masked load of vector from memory operand 1 of mode \( m \) into register operand 0. Mask is provided in register operand 2 of mode \( n \).
This pattern is not allowed to \texttt{FAIL}.

`maskstoremn` Perform a masked store of vector from register operand 1 of mode \( m \) into memory operand 0. Mask is provided in register operand 2 of mode \( n \).
This pattern is not allowed to \texttt{FAIL}.

`len_load_m` Load the number of vector elements specified by operand 2 from memory operand 1 into vector register operand 0, setting the other elements of operand 0 to undefined values. Operands 0 and 1 have mode \( m \), which must be a vector mode. Operand 2 has whichever integer mode the target prefers. If operand 2 exceeds the number of elements in mode \( m \), the behavior is undefined. If the target prefers the length to be measured in bytes rather than elements, it should only implement this pattern for vectors of QI elements.
This pattern is not allowed to \texttt{FAIL}.

`len_store_m` Store the number of vector elements specified by operand 2 from vector register operand 1 into memory operand 0, leaving the other elements of operand 0 unchanged. Operands 0 and 1 have mode \( m \), which must be a vector mode. Operand 2 has whichever integer mode the target prefers. If operand 2 exceeds the number of elements in mode \( m \), the behavior is undefined. If the target prefers the length to be measured in bytes rather than elements, it should only implement this pattern for vectors of QI elements.
This pattern is not allowed to \texttt{FAIL}. 
'vec_perm'

Output a (variable) vector permutation. Operand 0 is the destination to receive elements from operand 1 and operand 2, which are of mode m. Operand 3 is the selector. It is an integral mode vector of the same width and number of elements as mode m.

The input elements are numbered from 0 in operand 1 through $2N - 1$ in operand 2. The elements of the selector must be computed modulo $2N$. Note that if rtx_equal_p(operand1, operand2), this can be implemented with just operand 1 and selector elements modulo N.

In order to make things easy for a number of targets, if there is no 'vec_perm' pattern for mode m, but there is for mode q where q is a vector of QImode of the same width as m, the middle-end will lower the mode m VEC_PERM_EXPR to mode q.

See also TARGET_VECTORIZER_VEC_PERM_CONST, which performs the analogous operation for constant selectors.

'pushm1'

Output a push instruction. Operand 0 is value to push. Used only when PUSH_ROUNDING is defined. For historical reason, this pattern may be missing and in such case an mov expander is used instead, with a MEM expression forming the push operation. The mov expander method is deprecated.

'addm3'

Add operand 2 and operand 1, storing the result in operand 0. All operands must have mode m. This can be used even on two-address machines, by means of constraints requiring operands 1 and 0 to be the same location.

'ssadmm3', 'usaddm3'
'subm3', 'ssubm3', 'ussubm3'
'mulm3', 'ssmulm3', 'usmulm3'
'divm3', 'ssdivm3'
'udivm3', 'usdivm3'
'modm3', 'umodm3'
'uminm3', 'umaxm3'
'andm3', 'iorm3', 'xorm3'

Similar, for other arithmetic operations.

'addvm4'

Like addm3 but takes a code_label as operand 3 and emits code to jump to it if signed overflow occurs during the addition. This pattern is used to implement the built-in functions performing signed integer addition with overflow checking.

'subvm4', 'mulvm4'

Similar, for other signed arithmetic operations.

'uaddvm4'

Like addvm4 but for unsigned addition. That is to say, the operation is the same as signed addition but the jump is taken only on unsigned overflow.

'usubvm4', 'umulvm4'

Similar, for other unsigned arithmetic operations.

'addptrm3'

Like addm3 but is guaranteed to only be used for address calculations. The expanded code is not allowed to clobber the condition code. It only needs to be
defined if `addm3` sets the condition code. If adds used for address calculations and normal adds are not compatible it is required to expand a distinct pattern (e.g., using an unspec). The pattern is used by LRA to emit address calculations. `addm3` is used if `addptrm3` is not defined.

`'fam4'` Multiply operand 2 and operand 1, then add operand 3, storing the result in operand 0 without doing an intermediate rounding step. All operands must have mode `m`. This pattern is used to implement the `fma`, `fmaf`, and `fmal` builtin functions from the ISO C99 standard.

`'fsm4'` Like `fam4`, except operand 3 subtracted from the product instead of added to the product. This is represented in the rtl as

```
(fma:m op1 op2 (neg:m op3))
```

`'fnam4'` Like `fam4` except that the intermediate product is negated before being added to operand 3. This is represented in the rtl as

```
(fma:m (neg:m op1) op2 op3)
```

`'fnms4'` Like `fsm4` except that the intermediate product is negated before subtracting operand 3. This is represented in the rtl as

```
(fma:m (neg:m op1) op2 (neg:m op3))
```

`'smin3', 'smaxm3'` Signed minimum and maximum operations. When used with floating point, if both operands are zeros, or if either operand is `NaN`, then it is unspecified which of the two operands is returned as the result.

`'fmin3', 'fmax3'` IEEE-conformant minimum and maximum operations. If one operand is a quiet `NaN`, then the other operand is returned. If both operands are quiet `NaN`, then a quiet `NaN` is returned. In the case when gcc supports signaling `NaN` (-fsignaling-nans) an invalid floating point exception is raised and a quiet `NaN` is returned.

All operands have mode `m`, which is a scalar or vector floating-point mode. These patterns are not allowed to FAIL.

`'reduc_smin_scal_m', 'reduc_smax_scal_m'` Find the signed minimum/maximum of the elements of a vector. The vector is operand 1, and operand 0 is the scalar result, with mode equal to the mode of the elements of the input vector.

`'reduc_umin_scal_m', 'reduc_umax_scal_m'` Find the unsigned minimum/maximum of the elements of a vector. The vector is operand 1, and operand 0 is the scalar result, with mode equal to the mode of the elements of the input vector.

`'reduc_plus_scalar_m'` Compute the sum of the elements of a vector. The vector is operand 1, and operand 0 is the scalar result, with mode equal to the mode of the elements of the input vector.
'reduc_and_scal_m'
'reduc_ior_scal_m'
'reduc_xor_scal_m'
  Compute the bitwise AND/OR/XOR reduction of the elements of a vector of mode m. Operand 1 is the vector input and operand 0 is the scalar result. The mode of the scalar result is the same as one element of m.

extract_last_m
  Find the last set bit in mask operand 1 and extract the associated element of vector operand 2. Store the result in scalar operand 0. Operand 2 has vector mode m while operand 0 has the mode appropriate for one element of m. Operand 1 has the usual mask mode for vectors of mode m; see TARGET_VECTORIZE_GET_MASK_MODE.

fold_extract_last_m
  If any bits of mask operand 2 are set, find the last set bit, extract the associated element from vector operand 3, and store the result in operand 0. Store operand 1 in operand 0 otherwise. Operand 3 has mode m and operands 0 and 1 have the mode appropriate for one element of m. Operand 2 has the usual mask mode for vectors of mode m; see TARGET_VECTORIZE_GET_MASK_MODE.

fold_left_plus_m
  Take scalar operand 1 and successively add each element from vector operand 2. Store the result in scalar operand 0. The vector has mode m and the scalars have the mode appropriate for one element of m. The operation is strictly in-order: there is no reassociation.

mask_fold_left_plus_m
  Like 'fold_left_plus_m', but takes an additional mask operand (operand 3) that specifies which elements of the source vector should be added.

'sdot_prodm'
  Compute the sum of the products of two signed elements. Operand 1 and operand 2 are of the same mode. Their product, which is of a wider mode, is computed and added to operand 3. Operand 3 is of a mode equal or wider than the mode of the product. The result is placed in operand 0, which is of the same mode as operand 3.
  Semantically the expressions perform the multiplication in the following signs
  \[
  \text{sdot}<\text{signed op0}, \text{signed op1}, \text{signed op2}, \text{signed op3}> == \\
  \quad \text{op0} = \text{sign-ext (op1) * sign-ext (op2) + op3}
  \]

'udot_prodm'
  Compute the sum of the products of two unsigned elements. Operand 1 and operand 2 are of the same mode. Their product, which is of a wider mode, is computed and added to operand 3. Operand 3 is of a mode equal or wider than the mode of the product. The result is placed in operand 0, which is of the same mode as operand 3.
  Semantically the expressions perform the multiplication in the following signs
  \[
  \text{udot}<\text{unsigned op0}, \text{unsigned op1}, \text{unsigned op2}, \text{unsigned op3}> == \\
  \]
\[ \text{op0} = \text{zero-ext (op1)} \times \text{zero-ext (op2)} + \text{op3} \]

\[ \ldots \]

\textit{usdot_prodm}'

Compute the sum of the products of elements of different signs. Operand 1 must be unsigned and operand 2 signed. Their product, which is of a wider mode, is computed and added to operand 3.Operand 3 is of a mode equal or wider than the mode of the product. The result is placed in operand 0, which is of the same mode as operand 3.

Semantically the expressions perform the multiplication in the following signs

\[
\begin{align*}
\text{usdot<signed op0, unsigned op1, signed op2, signed op3> } &= \\
\text{op0} = \left( \text{((signed-conv) zero-ext (op1))} \times \text{sign-ext (op2)} \right) + \text{op3}
\end{align*}
\]

\[ \ldots \]

\textit{ssadm}'

\textit{usadm}'

Compute the sum of absolute differences of two signed/unsigned elements. Operand 1 and operand 2 are of the same mode. Their absolute difference, which is of a wider mode, is computed and added to operand 3.Operand 3 is of a mode equal or wider than the mode of the absolute difference. The result is placed in operand 0, which is of the same mode as operand 3.

\textit{widen_ssumm3}'

\textit{widen_usumm3}'

Operands 0 and 2 are of the same mode, which is wider than the mode of operand 1. Add operand 1 to operand 2 and place the widened result in operand 0. (This is used express accumulation of elements into an accumulator of a wider mode.)

\textit{smulhm3}'

\textit{umulhm3}'

Signed/unsigned multiply high with scale. This is equivalent to the C code:

\[
\begin{align*}
narrow \text{ op0, op1, op2; } \\
\ldots \text{ op0 } &= \left( \text{narrow} \right) \left( \left( \text{wide} \right) \text{ op1 } \times \left( \text{wide} \right) \text{ op2} \right) \gg \left( N / 2 - 1 \right);
\end{align*}
\]

where the sign of ‘\text{narrow}’ determines whether this is a signed or unsigned operation, and \( N \) is the size of ‘\text{wide}’ in bits.

\textit{smulhrsm3}'

\textit{umulhrsm3}'

Signed/unsigned multiply high with round and scale. This is equivalent to the C code:

\[
\begin{align*}
narrow \text{ op0, op1, op2; } \\
\ldots \text{ op0 } &= \left( \text{narrow} \right) \left( \left( \text{((wide) op1 } \times \text{wide) op2} \right) \gg \left( N / 2 - 2 \right) + 1 \right) \gg 1);
\end{align*}
\]

where the sign of ‘\text{narrow}’ determines whether this is a signed or unsigned operation, and \( N \) is the size of ‘\text{wide}’ in bits.

\textit{sddiv_pow2m3}'

\textit{sddiv_pow2m3}'

Signed division by power-of-2 immediate. Equivalent to:
signed op0, op1;
... 
op0 = op1 / (1 << imm);

`vec_shl_insert_m`
Shift the elements in vector input operand 1 left one element (i.e. away from element 0) and fill the vacated element 0 with the scalar in operand 2. Store the result in vector output operand 0. Operands 0 and 1 have mode m and operand 2 has the mode appropriate for one element of m.

`vec_shl_m`
Whole vector left shift in bits, i.e. away from element 0. Operand 1 is a vector to be shifted. Operand 2 is an integer shift amount in bits. Operand 0 is where the resulting shifted vector is stored. The output and input vectors should have the same modes.

`vec_shr_m`
Whole vector right shift in bits, i.e. towards element 0. Operand 1 is a vector to be shifted. Operand 2 is an integer shift amount in bits. Operand 0 is where the resulting shifted vector is stored. The output and input vectors should have the same modes.

`vec_pack_trunc_m`
Narrow (demote) and merge the elements of two vectors. Operands 1 and 2 are vectors of the same mode having N integral or floating point elements of size S. Operand 0 is the resulting vector in which 2*N elements of size S/2 are concatenated after narrowing them down using truncation.

`vec_pack_sbool_trunc_m`
Narrow and merge the elements of two vectors. Operands 1 and 2 are vectors of the same type having N boolean elements. Operand 0 is the resulting vector in which 2*N elements are concatenated. The last operand (operand 3) is the number of elements in the output vector 2*N as a CONST_INT. This instruction pattern is used when all the vector input and output operands have the same scalar mode m and thus using vec_pack_trunc_m would be ambiguous.

`vec_pack_sfix_trunc_m`, `vec_pack_ufix_trunc_m`
Narrow, convert to signed/unsigned integral type and merge the elements of two vectors. Operands 1 and 2 are vectors of the same mode having N floating point elements of size S. Operand 0 is the resulting vector in which 2*N elements of size S/2 are concatenated.

`vec_pack_sfix_trunc_m`, `vec_pack_ufix_trunc_m`
Narrow, convert to signed/unsigned integral type and merge the elements of two vectors. Operands 1 and 2 are vectors of the same mode having N floating point elements of size S. Operand 0 is the resulting vector in which 2*N elements of size S/2 are concatenated.

`vec_pack_float_m`, `vec_packu_float_m`
Narrow, convert to floating point type and merge the elements of two vectors. Operands 1 and 2 are vectors of the same mode having N signed/unsigned
integral elements of size S. Operand 0 is the resulting vector in which 2*N elements of size S/2 are concatenated.

'vec_unpacks_hi_m', 'vec_unpacks_lo_m'
Extract and widen (promote) the high/low part of a vector of signed integral or floating point elements. The input vector (operand 1) has N elements of size S. Widen (promote) the high/low elements of the vector using signed or floating point extension and place the resulting N/2 values of size 2*S in the output vector (operand 0).

'vec_unpacku_hi_m', 'vec_unpacku_lo_m'
Extract and widen (promote) the high/low part of a vector of unsigned integral elements. The input vector (operand 1) has N elements of size S. Widen (promote) the high/low elements of the vector using zero extension and place the resulting N/2 values of size 2*S in the output vector (operand 0).

'vec_unpacks_sbool_hi_m', 'vec_unpacks_sbool_lo_m'
Extract the high/low part of a vector of boolean elements that have scalar mode m. The input vector (operand 1) has N elements, the output vector (operand 0) has N/2 elements. The last operand (operand 2) is the number of elements of the input vector N as a CONST_INT. These patterns are used if both the input and output vectors have the same scalar mode m and thus using vec_unpacks_hi_m or vec_unpacks_lo_m would be ambiguous.

'vec_unpacks_float_hi_m', 'vec_unpacks_float_lo_m'
'vec_unpacku_float_hi_m', 'vec_unpacku_float_lo_m'
Extract, convert to floating point type and widen the high/low part of a vector of signed/unsigned integral elements. The input vector (operand 1) has N elements of size S. Convert the high/low elements of the vector using floating point conversion and place the resulting N/2 values of size 2*S in the output vector (operand 0).

'vec_unpack_sfix_trunc_hi_m',
'vec_unpack_sfix_trunc_lo_m'
'vec_unpack_ufix_trunc_hi_m'
'vec_unpack_ufix_trunc_lo_m'
Extract, convert to signed/unsigned integer type and widen the high/low part of a vector of floating point elements. The input vector (operand 1) has N elements of size S. Convert the high/low elements of the vector to integers and place the resulting N/2 values of size 2*S in the output vector (operand 0).

'vec_widen_umult_hi_m', 'vec_widen_umult_lo_m'
'vec_widen_smult_hi_m', 'vec_widen_smult_lo_m'
'vec_widen_umult_even_m', 'vec_widen_umult_odd_m'
'vec_widen_smult_even_m', 'vec_widen_smult_odd_m'
Signed/Unsigned widening multiplication. The two inputs (operands 1 and 2) are vectors with N signed/unsigned elements of size S. Multiply the high/low or even/odd elements of the two vectors, and put the N/2 products of size 2*S in the output vector (operand 0). A target shouldn’t implement even/odd pattern pair if it is less efficient than lo/hi one.
vec_widen_ushiftl_hi_m', 'vec_widen_ushiftl_lo_m'
vec_widen_sshiftl_hi_m', 'vec_widen_sshiftl_lo_m'
Signed/Unsigned widening shift left. The first input (operand 1) is a vector with \(N\) signed/unsigned elements of size \(S\). Operand 2 is a constant. Shift the high/low elements of operand 1, and put the \(N/2\) results of size \(2*S\) in the output vector (operand 0).

vec_widen_uaddl_hi_m', 'vec_widen_uaddl_lo_m'
vec_widen_saddl_hi_m', 'vec_widen_saddl_lo_m'
Signed/Unsigned widening add long. Operands 1 and 2 are vectors with \(N\) signed/unsigned elements of size \(S\). Add the high/low elements of 1 and 2 together, widen the resulting elements and put the \(N/2\) results of size \(2*S\) in the output vector (operand 0).

vec_widen_usubl_hi_m', 'vec_widen_usubl_lo_m'
vec_widen_ssubl_hi_m', 'vec_widen_ssubl_lo_m'
Signed/Unsigned widening subtract long. Operands 1 and 2 are vectors with \(N\) signed/unsigned elements of size \(S\). Subtract the high/low elements of 2 from 1 and widen the resulting elements. Put the \(N/2\) results of size \(2*S\) in the output vector (operand 0).

vec_addsubm3
Alternating subtract, add with even lanes doing subtract and odd lanes doing addition. Operands 1 and 2 and the output operand are vectors with mode \(m\).

vec_fmaddsubm4
Alternating multiply subtract, add with even lanes doing subtract and odd lanes doing addition of the third operand to the multiplication result of the first two operands. Operands 1, 2 and 3 and the output operand are vectors with mode \(m\).

vec_fmsubaddm4
Alternating multiply add, subtract with even lanes doing addition and odd lanes doing subtraction of the third operand to the multiplication result of the first two operands. Operands 1, 2 and 3 and the output operand are vectors with mode \(m\).

These instructions are not allowed to FAIL.

mulhisi3
Multiply operands 1 and 2, which have mode HImode, and store a SImode product in operand 0.

mulqihi3', 'mulsidi3'
Similar widening-multiplication instructions of other widths.

umulqihi3', 'umulhisi3', 'umulsidi3'
Similar widening-multiplication instructions that do unsigned multiplication.

usmulqihi3', 'usmulhisi3', 'usmulsidi3'
Similar widening-multiplication instructions that interpret the first operand as unsigned and the second operand as signed, then do a signed multiplication.
'smulm3_highpart'
Perform a signed multiplication of operands 1 and 2, which have mode m, and store the most significant half of the product in operand 0. The least significant half of the product is discarded.

'umulm3_highpart'
Similar, but the multiplication is unsigned.

'maddmn4'
Multiply operands 1 and 2, sign-extend them to mode n, add operand 3, and store the result in operand 0. Operands 1 and 2 have mode m and operands 0 and 3 have mode n. Both modes must be integer or fixed-point modes and n must be twice the size of m.
In other words, maddmn4 is like mulmn3 except that it also adds operand 3.
These instructions are not allowed to FAIL.

'umaddmn4'
Like maddmn4, but zero-extend the multiplication operands instead of sign-extending them.

'ssmaddmn4'
Like maddmn4, but all involved operations must be signed-saturating.

'usmaddmn4'
Like umaddmn4, but all involved operations must be unsigned-saturating.

'msubmn4'
Multiply operands 1 and 2, sign-extend them to mode n, subtract the result from operand 3, and store the result in operand 0. Operands 1 and 2 have mode m and operands 0 and 3 have mode n. Both modes must be integer or fixed-point modes and n must be twice the size of m.
In other words, msubmn4 is like mulmn3 except that it also subtracts the result from operand 3.
These instructions are not allowed to FAIL.

'umsubmn4'
Like msubmn4, but zero-extend the multiplication operands instead of sign-extending them.

'smsubmn4'
Like msubmn4, but all involved operations must be signed-saturating.

'usmsubmn4'
Like umsubmn4, but all involved operations must be unsigned-saturating.

'divmodm4'
Signed division that produces both a quotient and a remainder. Operand 1 is divided by operand 2 to produce a quotient stored in operand 0 and a remainder stored in operand 3.
For machines with an instruction that produces both a quotient and a remainder, provide a pattern for 'divmodm4' but do not provide patterns for 'divm3' and 'modm3'. This allows optimization in the relatively common case when both the quotient and remainder are computed.
If an instruction that just produces a quotient or just a remainder exists and is more efficient than the instruction that produces both, write the output routine of ‘divmod4’ to call find_reg_note and look for a REG_UNUSED note on the quotient or remainder and generate the appropriate instruction.

‘udivmod4’
Similar, but does unsigned division.

‘ashlm3’, ‘ssashlm3’, ‘usashlm3’
Arithmetic-shift operand 1 left by a number of bits specified by operand 2, and store the result in operand 0. Here m is the mode of operand 0 and operand 1; operand 2’s mode is specified by the instruction pattern, and the compiler will convert the operand to that mode before generating the instruction. The shift or rotate expander or instruction pattern should explicitly specify the mode of the operand 2, it should never be VOIDmode. The meaning of out-of-range shift counts can optionally be specified by TARGET_SHIFT_TRUNCATION_MASK. See [TARGET_SHIFT_TRUNCATION_MASK], page 664. Operand 2 is always a scalar type.

‘ashrm3’, ‘lshrm3’, ‘rotlm3’, ‘rotrm3’
Other shift and rotate instructions, analogous to the ashlm3 instructions. Operand 2 is always a scalar type.

Vector shift and rotate instructions that take vectors as operand 2 instead of a scalar type.

‘avgm3_floor’
‘uavgm3_floor’
Signed and unsigned average instructions. These instructions add operands 1 and 2 without truncation, divide the result by 2, round towards -Inf, and store the result in operand 0. This is equivalent to the C code:

```
narrow op0, op1, op2;
...  
op0 = (narrow) (((wide) op1 + (wide) op2) >> 1);
```

where the sign of ‘narrow’ determines whether this is a signed or unsigned operation.

‘avgm3.ceil’
‘uavgm3.ceil’
Like ‘avgm3_floor’ and ‘uavgm3_floor’, but round towards +Inf. This is equivalent to the C code:

```
narrow op0, op1, op2;
...  
op0 = (narrow) (((wide) op1 + (wide) op2 + 1) >> 1);
```

‘bswapm2’ Reverse the order of bytes of operand 1 and store the result in operand 0.

‘negm2’, ‘ssnegm2’, ‘usnegm2’
Negate operand 1 and store the result in operand 0.

‘negvm3’ Like negm2 but takes a code_label as operand 2 and emits code to jump to it if signed overflow occurs during the negation.
‘absm2’ Store the absolute value of operand 1 into operand 0.

‘sqrtn2’ Store the square root of operand 1 into operand 0. Both operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘rsqrtn2’ Store the reciprocal of the square root of operand 1 into operand 0. Both operands have mode m, which is a scalar or vector floating-point mode. On most architectures this pattern is only approximate, so either its C condition or the TARGET_OPTAB_SUPPORTED_P hook should check for the appropriate math flags. (Using the C condition is more direct, but using TARGET_OPTAB_SUPPORTED_P can be useful if a target-specific built-in also uses the ‘rsqrtn2’ pattern.) This pattern is not allowed to FAIL.

‘fmodm3’ Store the remainder of dividing operand 1 by operand 2 into operand 0, rounded towards zero to an integer. All operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘remainderm3’ Store the remainder of dividing operand 1 by operand 2 into operand 0, rounded to the nearest integer. All operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘scalbm3’ Raise FLT_RADIX to the power of operand 2, multiply it by operand 1, and store the result in operand 0. All operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘ldexpm3’ Raise 2 to the power of operand 2, multiply it by operand 1, and store the result in operand 0. Operands 0 and 1 have mode m, which is a scalar or vector floating-point mode. Operand 2’s mode has the same number of elements as m and each element is wide enough to store an int. The integers are signed. This pattern is not allowed to FAIL.

‘cosm2’ Store the cosine of operand 1 into operand 0. Both operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘sinnm2’ Store the sine of operand 1 into operand 0. Both operands have mode m, which is a scalar or vector floating-point mode. This pattern is not allowed to FAIL.

‘sincosm3’ Store the cosine of operand 2 into operand 0 and the sine of operand 2 into operand 1. All operands have mode m, which is a scalar or vector floating-point mode.
Targets that can calculate the sine and cosine simultaneously can implement this pattern as opposed to implementing individual \texttt{sinm2} and \texttt{cosm2} patterns. The \texttt{sin} and \texttt{cos} built-in functions will then be expanded to the \texttt{sincosm3} pattern, with one of the output values left unused.

\texttt{'tanm2'} Store the tangent of operand 1 into operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'asim2'} Store the arc sine of operand 1 into operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'acosm2'} Store the arc cosine of operand 1 into operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'atanm2'} Store the arc tangent of operand 1 into operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'expm2'} Raise e (the base of natural logarithms) to the power of operand 1 and store the result in operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'expm1m2'} Raise e (the base of natural logarithms) to the power of operand 1, subtract 1, and store the result in operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
For inputs close to zero, the pattern is expected to be more accurate than a separate \texttt{expm2} and \texttt{subm3} would be.
This pattern is not allowed to FAIL.

\texttt{'exp10m2'} Raise 10 to the power of operand 1 and store the result in operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'exp2m2'} Raise 2 to the power of operand 1 and store the result in operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'logm2'} Store the natural logarithm of operand 1 into operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
This pattern is not allowed to FAIL.

\texttt{'log1pm2'} Add 1 to operand 1, compute the natural logarithm, and store the result in operand 0. Both operands have mode \textit{m}, which is a scalar or vector floating-point mode.
For inputs close to zero, the pattern is expected to be more accurate than a separate \texttt{admm3} and \texttt{logm2} would be.
This pattern is not allowed to FAIL.
'log10m2' Store the base-10 logarithm of operand 1 into operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'log2m2' Store the base-2 logarithm of operand 1 into operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'logbm2' Store the base-FLT_RADIX logarithm of operand 1 into operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'significandm2'

Store the significand of floating-point operand 1 in operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'powm3' Store the value of operand 1 raised to the exponent operand 2 into operand 0. All operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'atan2m3' Store the arc tangent (inverse tangent) of operand 1 divided by operand 2 into operand 0, using the signs of both arguments to determine the quadrant of the result. All operands have mode \( m \), which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

'floorm2' Store the largest integral value not greater than operand 1 in operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode. If `'-ffp-int-builtin-inexact'` is in effect, the “inexact” exception may be raised for noninteger operands; otherwise, it may not.

This pattern is not allowed to FAIL.

'btruncm2'

Round operand 1 to an integer, towards zero, and store the result in operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode. If `'-ffp-int-builtin-inexact'` is in effect, the “inexact” exception may be raised for noninteger operands; otherwise, it may not.

This pattern is not allowed to FAIL.

'roundm2' Round operand 1 to the nearest integer, rounding away from zero in the event of a tie, and store the result in operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode. If `'-ffp-int-builtin-inexact'` is in effect, the “inexact” exception may be raised for noninteger operands; otherwise, it may not.

This pattern is not allowed to FAIL.

'ceilm2' Store the smallest integral value not less than operand 1 in operand 0. Both operands have mode \( m \), which is a scalar or vector floating-point mode. If
`-ffp-int-builtin-inexact` is in effect, the “inexact” exception may be raised for noninteger operands; otherwise, it may not.

This pattern is not allowed to FAIL.

`nearbyintm2`  
Round operand 1 to an integer, using the current rounding mode, and store the result in operand 0. Do not raise an inexact condition when the result is different from the argument. Both operands have mode $m$, which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

`rintm2`  
Round operand 1 to an integer, using the current rounding mode, and store the result in operand 0. Raise an inexact condition when the result is different from the argument. Both operands have mode $m$, which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

`lrintmn2`  
Convert operand 1 (valid for floating point mode $m$) to fixed point mode $n$ as a signed number according to the current rounding mode and store in operand 0 (which has mode $n$).

`lroundmn2`  
Convert operand 1 (valid for floating point mode $m$) to fixed point mode $n$ as a signed number rounding to nearest and away from zero and store in operand 0 (which has mode $n$).

`lfloormn2`  
Convert operand 1 (valid for floating point mode $m$) to fixed point mode $n$ as a signed number rounding down and store in operand 0 (which has mode $n$).

`lceilmn2`  
Convert operand 1 (valid for floating point mode $m$) to fixed point mode $n$ as a signed number rounding up and store in operand 0 (which has mode $n$).

`copysignm3`  
Store a value with the magnitude of operand 1 and the sign of operand 2 into operand 0. All operands have mode $m$, which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

`xorsignm3`  
Equivalent to `op0 = op1 * copysign (1.0, op2)`: store a value with the magnitude of operand 1 and the sign of operand 2 into operand 0. All operands have mode $m$, which is a scalar or vector floating-point mode.

This pattern is not allowed to FAIL.

`cadd90m3`  
Perform vector add and subtract on even/odd number pairs. The operation being matched is semantically described as
for (int i = 0; i < N; i += 2)
{
    c[i] = a[i] - b[i+1];
    c[i+1] = a[i+1] + b[i];
}

This operation is semantically equivalent to performing a vector addition of complex numbers in operand 1 with operand 2 rotated by 90 degrees around the argand plane and storing the result in operand 0.

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.

The operation is only supported for vector modes m.

This pattern is not allowed to FAIL.

‘cadd270m3’
Perform vector add and subtract on even/odd number pairs. The operation being matched is semantically described as

\[
\begin{align*}
\text{for (int } i = 0; i < N; i += 2) \\
\{ \\
\quad c[i] &= a[i] + b[i+1]; \\
\quad c[i+1] &= a[i+1] - b[i]; \\
\} 
\end{align*}
\]

This operation is semantically equivalent to performing a vector addition of complex numbers in operand 1 with operand 2 rotated by 270 degrees around the argand plane and storing the result in operand 0.

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.

The operation is only supported for vector modes m.

This pattern is not allowed to FAIL.

‘cmla4’
Perform a vector multiply and accumulate that is semantically the same as a multiply and accumulate of complex numbers.

\[
\begin{align*}
\text{for (int } i = 0; i < N; i += 1) \\
\{ \\
\quad c[i] &= a[i] * b[i]; \\
\} 
\end{align*}
\]

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.

The operation is only supported for vector modes m.

This pattern is not allowed to FAIL.

‘cmla_conjm4’
Perform a vector multiply by conjugate and accumulate that is semantically the same as a multiply and accumulate of complex numbers where the second multiply arguments is conjugated.

\[
\begin{align*}
\text{complex } \text{TYPE } c[N]; \\
\text{complex } \text{TYPE } a[N]; \\
\text{complex } \text{TYPE } b[N]; \\
\text{for (int } i = 0; i < N; i += 1) \\
\{ \\
\quad c[i] &= a[i] * b[i]; \\
\} 
\end{align*}
\]
```c
complex TYPE b[N];
for (int i = 0; i < N; i += 1)
{
    c[i] += a[i] * conj (b[i]);
}
```

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.
The operation is only supported for vector modes \( m \).
This pattern is not allowed to \texttt{FAIL}.

```
cmlsm4'
Perform a vector multiply and subtract that is semantically the same as a multiply and subtract of complex numbers.

```c
complex TYPE c[N];
complex TYPE a[N];
complex TYPE b[N];
for (int i = 0; i < N; i += 1)
{
    c[i] -= a[i] * b[i];
}
```

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.
The operation is only supported for vector modes \( m \).
This pattern is not allowed to \texttt{FAIL}.

```
cmls_conj4'
Perform a vector multiply by conjugate and subtract that is semantically the same as a multiply and subtract of complex numbers where the second multiply arguments is conjugated.

```c
complex TYPE c[N];
complex TYPE a[N];
complex TYPE b[N];
for (int i = 0; i < N; i += 1)
{
    c[i] -= a[i] * conj (b[i]);
}
```

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.
The operation is only supported for vector modes \( m \).
This pattern is not allowed to \texttt{FAIL}.

```
cmulm4'
Perform a vector multiply that is semantically the same as multiply of complex numbers.

```c
complex TYPE c[N];
complex TYPE a[N];
complex TYPE b[N];
for (int i = 0; i < N; i += 1)
{
    c[i] = a[i] * b[i];
}
```

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.
The operation is only supported for vector modes $m$.
This pattern is not allowed to FAIL.

\texttt{`cmul\_conj\textsubscript{m}''} \\
Perform a vector multiply by conjugate that is semantically the same as a multiply of complex numbers where the second multiply arguments is conjugated.

\begin{verbatim}
complex TYPE c[N];
complex TYPE a[N];
complex TYPE b[N];
for (int i = 0; i < N; i += 1)
{
    c[i] = a[i] * conj (b[i]);
}
\end{verbatim}

In GCC lane ordering the real part of the number must be in the even lanes with the imaginary part in the odd lanes.
This pattern is not allowed to FAIL.

\texttt{`ffs\textsubscript{m}''} \\
Store into operand 0 one plus the index of the least significant 1-bit of operand 1. If operand 1 is zero, store zero.

$m$ is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode $m$ but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as int). When $m$ is a vector, both operands must have mode $m$.
This pattern is not allowed to FAIL.

\texttt{`clrsbm\textsubscript{m}''} \\
Count leading redundant sign bits. Store into operand 0 the number of redundant sign bits in operand 1, starting at the most significant bit position. A redundant sign bit is defined as any sign bit after the first. As such, this count will be one less than the count of leading sign bits.

$m$ is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode $m$ but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as int). When $m$ is a vector, both operands must have mode $m$.
This pattern is not allowed to FAIL.

\texttt{`clzm\textsubscript{m}''} \\
Store into operand 0 the number of leading 0-bits in operand 1, starting at the most significant bit position. If operand 1 is 0, the CLZ\_DEFINED\_VALUE\_AT\_ZERO macro defines if the result is undefined or has a useful value.

$m$ is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode $m$ but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as int). When $m$ is a vector, both operands must have mode $m$.
This pattern is not allowed to FAIL.
`ctz` Store into operand 0 the number of trailing 0-bits in operand 1, starting at the least significant bit position. If operand 1 is 0, the `CTZ_DEFINED_VALUE_AT_ZERO` (see Section 18.31 [Misc], page 661) macro defines if the result is undefined or has a useful value.

`m` is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode `m` but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as `int`). When `m` is a vector, both operands must have mode `m`.

This pattern is not allowed to FAIL.

`popcount` Store into operand 0 the number of 1-bits in operand 1.

`m` is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode `m` but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as `int`). When `m` is a vector, both operands must have mode `m`.

This pattern is not allowed to FAIL.

`parity` Store into operand 0 the parity of operand 1, i.e. the number of 1-bits in operand 1 modulo 2.

`m` is either a scalar or vector integer mode. When it is a scalar, operand 1 has mode `m` but operand 0 can have whatever scalar integer mode is suitable for the target. The compiler will insert conversion instructions as necessary (typically to convert the result to the same width as `int`). When `m` is a vector, both operands must have mode `m`.

This pattern is not allowed to FAIL.

`one_cmpl` Store the bitwise-complement of operand 1 into operand 0.

`cpymem` Block copy instruction. The destination and source blocks of memory are the first two operands, and both are `mem:BLK`s with an address in mode `Pmode`.

The number of bytes to copy is the third operand, in mode `m`. Usually, you specify `Pmode` for `m`. However, if you can generate better code knowing the range of valid lengths is smaller than those representable in a full Pmode pointer, you should provide a pattern with a mode corresponding to the range of values you can handle efficiently (e.g., `QImode` for values in the range 0–127; note we avoid numbers that appear negative) and also a pattern with `Pmode`.

The fourth operand is the known shared alignment of the source and destination, in the form of a `const_int` rtx. Thus, if the compiler knows that both source and destination are word-aligned, it may provide the value 4 for this operand.

Optional operands 5 and 6 specify expected alignment and size of block respectively. The expected alignment differs from alignment in operand 4 in a way that the blocks are not required to be aligned according to it in all cases. This
expected alignment is also in bytes, just like operand 4. Expected size, when unknown, is set to \((\text{const\_int } -1)\).

Descriptions of multiple \texttt{cpymem}\texttt{m} patterns can only be beneficial if the patterns for smaller modes have fewer restrictions on their first, second and fourth operands. Note that the mode \(m\) in \texttt{cpymem}\texttt{m} does not impose any restriction on the mode of individually copied data units in the block.

The \texttt{cpymem}\texttt{m} patterns need not give special consideration to the possibility that the source and destination strings might overlap. These patterns are used to do inline expansion of \texttt{\_\_builtin\_memcpy}.

\textit{\texttt{movmem\texttt{m}}}  
Block move instruction. The destination and source blocks of memory are the first two operands, and both are \texttt{mem:\texttt{BLK}s} with an address in mode \texttt{Pmode}. The number of bytes to copy is the third operand, in mode \(m\). Usually, you specify \texttt{Pmode} for \(m\). However, if you can generate better code knowing the range of valid lengths is smaller than those representable in a full \texttt{Pmode} pointer, you should provide a pattern with a mode corresponding to the range of values you can handle efficiently (e.g., \texttt{QImode} for values in the range \(0\)–\(127\); note we avoid numbers that appear negative) and also a pattern with \texttt{Pmode}.

The fourth operand is the known shared alignment of the source and destination, in the form of a \texttt{const\_int} \texttt{rtx}. Thus, if the compiler knows that both source and destination are word-aligned, it may provide the value \(4\) for this operand.

Optional operands 5 and 6 specify expected alignment and size of block respectively. The expected alignment differs from alignment in operand 4 in a way that the blocks are not required to be aligned according to it in all cases. This expected alignment is also in bytes, just like operand 4. Expected size, when unknown, is set to \((\text{const\_int } -1)\).

Descriptions of multiple \texttt{movmem}\texttt{m} patterns can only be beneficial if the patterns for smaller modes have fewer restrictions on their first, second and fourth operands. Note that the mode \(m\) in \texttt{movmem}\texttt{m} does not impose any restriction on the mode of individually copied data units in the block.

The \texttt{movmem}\texttt{m} patterns must correctly handle the case where the source and destination strings overlap. These patterns are used to do inline expansion of \texttt{\_\_builtin\_memmove}.

\textit{\texttt{movstr}}}  
String copy instruction, with \texttt{stpcpy} semantics. Operand 0 is an output operand in mode \texttt{Pmode}. The addresses of the destination and source strings are operands 1 and 2, and both are \texttt{mem:\texttt{BLK}s} with addresses in mode \texttt{Pmode}. The execution of the expansion of this pattern should store in operand 0 the address in which the \texttt{NUL} terminator was stored in the destination string.

This pattern has also several optional operands that are same as in \texttt{setmem}.

\textit{\texttt{setmem\texttt{m}}}  
Block set instruction. The destination string is the first operand, given as a \texttt{mem:\texttt{BLK}} whose address is in mode \texttt{Pmode}. The number of bytes to set is the second operand, in mode \(m\). The value to initialize the memory with is the third operand. Targets that only support the clearing of memory should reject any value that is not the constant \(0\). See ‘\texttt{cpymem\texttt{m}}’ for a discussion of the choice of mode.
The fourth operand is the known alignment of the destination, in the form of a `const_int` rtx. Thus, if the compiler knows that the destination is word-aligned, it may provide the value 4 for this operand.

Optional operands 5 and 6 specify expected alignment and size of block respectively. The expected alignment differs from alignment in operand 4 in a way that the blocks are not required to be aligned according to it in all cases. This expected alignment is also in bytes, just like operand 4. Expected size, when unknown, is set to `(const_int -1)`. Operand 7 is the minimal size of the block and operand 8 is the maximal size of the block (NULL if it cannot be represented as CONST_INT). Operand 9 is the probable maximal size (i.e. we cannot rely on it for correctness, but it can be used for choosing proper code sequence for a given size).

The use for multiple `setmemm` is as for `cpymem`.

`cmpstrnm` String compare instruction, with five operands. Operand 0 is the output; it has mode `m`. The remaining four operands are like the operands of `cpymem`.

The two memory blocks specified are compared byte by byte in lexicographic order starting at the beginning of each string. The instruction is not allowed to prefetch more than one byte at a time since either string may end in the first byte and reading past that may access an invalid page or segment and cause a fault. The comparison terminates early if the fetched bytes are different or if they are equal to zero. The effect of the instruction is to store a value in operand 0 whose sign indicates the result of the comparison.

`cmpstrm` String compare instruction, without known maximum length. Operand 0 is the output; it has mode `m`. The second and third operand are the blocks of memory to be compared; both are `mem:BLK` with an address in mode `Pmode`.

The fourth operand is the known shared alignment of the source and destination, in the form of a `const_int` rtx. Thus, if the compiler knows that both source and destination are word-aligned, it may provide the value 4 for this operand.

The two memory blocks specified are compared byte by byte in lexicographic order starting at the beginning of each string. The instruction is not allowed to prefetch more than one byte at a time since either string may end in the first byte and reading past that may access an invalid page or segment and cause a fault. The comparison will terminate when the fetched bytes are different or if they are equal to zero. The effect of the instruction is to store a value in operand 0 whose sign indicates the result of the comparison.

`cmpmemm` Block compare instruction, with five operands like the operands of `cmpstrm`.

The two memory blocks specified are compared byte by byte in lexicographic order starting at the beginning of each block. Unlike `cmpstrm` the instruction can prefetch any bytes in the two memory blocks. Also unlike `cmpstrm` the comparison will not stop if both bytes are zero. The effect of the instruction is to store a value in operand 0 whose sign indicates the result of the comparison.

`strlenm` Compute the length of a string, with three operands. Operand 0 is the result (of mode `m`), operand 1 is a `mem` referring to the first character of the string,
operand 2 is the character to search for (normally zero), and operand 3 is a constant describing the known alignment of the beginning of the string.

‘floatmn2’
Convert signed integer operand 1 (valid for fixed point mode m) to floating point mode n and store in operand 0 (which has mode n).

‘floatunsmn2’
Convert unsigned integer operand 1 (valid for fixed point mode m) to floating point mode n and store in operand 0 (which has mode n).

‘fixmn2’
Convert operand 1 (valid for floating point mode m) to fixed point mode n as a signed number and store in operand 0 (which has mode n). This instruction’s result is defined only when the value of operand 1 is an integer.
If the machine description defines this pattern, it also needs to define the ftrunc pattern.

‘fixunsmn2’
Convert operand 1 (valid for floating point mode m) to fixed point mode n as an unsigned number and store in operand 0 (which has mode n). This instruction’s result is defined only when the value of operand 1 is an integer.

‘ftruncm2’
Convert operand 1 (valid for floating point mode m) to an integer value, still represented in floating point mode m, and store it in operand 0 (valid for floating point mode m).

‘fix_truncm2’
Like ‘fixmn2’ but works for any floating point value of mode m by converting the value to an integer.

‘fixuns_truncm2’
Like ‘fixunsmn2’ but works for any floating point value of mode m by converting the value to an integer.

‘truncm2’
Truncate operand 1 (valid for mode m) to mode n and store in operand 0 (which has mode n). Both modes must be fixed point or both floating point.

‘extendm2’
Sign-extend operand 1 (valid for mode m) to mode n and store in operand 0 (which has mode n). Both modes must be fixed point or both floating point.

‘zero_extendm2’
Zero-extend operand 1 (valid for mode m) to mode n and store in operand 0 (which has mode n). Both modes must be fixed point.

‘fractm2’
Convert operand 1 of mode m to mode n and store in operand 0 (which has mode n). Mode m and mode n could be fixed-point to fixed-point, signed integer to fixed-point, fixed-point to signed integer, floating-point to fixed-point, or fixed-point to floating-point. When overflows or underflows happen, the results are undefined.
'satfractmn2'

Convert operand 1 of mode $m$ to mode $n$ and store in operand 0 (which has mode $n$). Mode $m$ and mode $n$ could be fixed-point to fixed-point, signed integer to fixed-point, or floating-point to fixed-point. When overflows or underflows happen, the instruction saturates the results to the maximum or the minimum.

'fractunsmn2'

Convert operand 1 of mode $m$ to mode $n$ and store in operand 0 (which has mode $n$). Mode $m$ and mode $n$ could be unsigned integer to fixed-point, or fixed-point to unsigned integer. When overflows or underflows happen, the results are undefined.

'satfractunsmn2'

Convert unsigned integer operand 1 of mode $m$ to fixed-point mode $n$ and store in operand 0 (which has mode $n$). When overflows or underflows happen, the instruction saturates the results to the maximum or the minimum.

'extv'

Extract a bit-field from register operand 1, sign-extend it, and store it in operand 0. Operand 2 specifies the width of the field in bits and operand 3 the starting bit, which counts from the most significant bit if `BITS_BIG_ENDIAN` is true and from the least significant bit otherwise.

Operands 0 and 1 both have mode $m$. Operands 2 and 3 have a target-specific mode.

'extvmisalign'

Extract a bit-field from memory operand 1, sign extend it, and store it in operand 0. Operand 2 specifies the width in bits and operand 3 the starting bit. The starting bit is always somewhere in the first byte of operand 1; it counts from the most significant bit if `BITS_BIG_ENDIAN` is true and from the least significant bit otherwise.

Operand 0 has mode $m$ while operand 1 has BLK mode. Operands 2 and 3 have a target-specific mode.

The instruction must not read beyond the last byte of the bit-field.

'extzv'

Like `extv` except that the bit-field value is zero-extended.

'extzvmisalign'

Like `extvmisalign` except that the bit-field value is zero-extended.

'insv'

Insert operand 3 into a bit-field of register operand 0. Operand 1 specifies the width of the field in bits and operand 2 the starting bit, which counts from the most significant bit if `BITS_BIG_ENDIAN` is true and from the least significant bit otherwise.

Operands 0 and 3 both have mode $m$. Operands 1 and 2 have a target-specific mode.

'insvmisalign'

Insert operand 3 into a bit-field of memory operand 0. Operand 1 specifies the width of the field in bits and operand 2 the starting bit. The starting bit is always somewhere in the first byte of operand 0; it counts from the most
significant bit if `BITS_BIG_ENDIAN` is true and from the least significant bit otherwise.

Operand 3 has mode $m$ while operand 0 has BLK mode. Operands 1 and 2 have a target-specific mode.

The instruction must not read or write beyond the last byte of the bit-field.

**`extv`**

Extract a bit-field from operand 1 (a register or memory operand), where operand 2 specifies the width in bits and operand 3 the starting bit, and store it in operand 0. Operand 0 must have mode `word_mode`. Operand 1 may have mode `byte_mode` or `word_mode`; often `word_mode` is allowed only for registers. Operands 2 and 3 must be valid for `word_mode`.

The RTL generation pass generates this instruction only with constants for operands 2 and 3 and the constant is never zero for operand 2.

The bit-field value is sign-extended to a full word integer before it is stored in operand 0.

This pattern is deprecated; please use `extvm` and `extvmisalign` instead.

**`extzv`**

Like `extv` except that the bit-field value is zero-extended.

This pattern is deprecated; please use `extzvm` and `extzvmisalign` instead.

**`insv`**

Store operand 3 (which must be valid for `word_mode`) into a bit-field in operand 0, where operand 1 specifies the width in bits and operand 2 the starting bit. Operand 0 may have mode `byte_mode` or `word_mode`; often `word_mode` is allowed only for registers. Operands 1 and 2 must be valid for `word_mode`.

The RTL generation pass generates this instruction only with constants for operands 1 and 2 and the constant is never zero for operand 1.

This pattern is deprecated; please use `insvm` and `insvmisalign` instead.

**`movmodec`**

Conditionally move operand 2 or operand 3 into operand 0 according to the comparison in operand 1. If the comparison is true, operand 2 is moved into operand 0, otherwise operand 3 is moved.

The mode of the operands being compared need not be the same as the operands being moved. Some machines, sparc64 for example, have instructions that conditionally move an integer value based on the floating point condition codes and vice versa.

If the machine does not have conditional move instructions, do not define these patterns.

**`addmodec`**

Similar to `movmodec` but for conditional addition. Conditionally move operand 2 or (operands 2 + operand 3) into operand 0 according to the comparison in operand 1. If the comparison is false, operand 2 is moved into operand 0, otherwise (operand 2 + operand 3) is moved.
When operand 1 is true, perform an operation on operands 2 and 3 and store
the result in operand 0, otherwise store operand 4 in operand 0. The operation
works elementwise if the operands are vectors.

The scalar case is equivalent to:

```
op0 = op1 ? op2 op op3 : op4;
```

while the vector case is equivalent to:

```
for (i = 0; i < GET_MODE_NUNITS (m); i++)
    op0[i] = op1[i] ? op2[i] op op3[i] : op4[i];
```

where, for example, `op` is `+` for `cond_addmode`.

When defined for floating-point modes, the contents of `op3[i]` are not in-
terpreted if `op1[i]` is false, just like they would not be in a normal C `?:`
condition.

Operands 0, 2, 3 and 4 all have mode `m`. Operand 1 is a scalar integer if `m` is
scalar, otherwise it has the mode returned by `TARGET_VECTORIZE_GET_MASK_`
MODE.

`cond_opmode` generally corresponds to a conditional form of `opmode3`. As an
exception, the vector forms of shifts correspond to patterns like `vashlmode3`
rather than patterns like `ashlmode3`.

```
cond_famode
cond_fnsmode
cond_fnmamode
cond_fnfsmode
```

Like `cond_addm`, except that the conditional operation takes 3 operands rather
than two. For example, the vector form of `cond_famode` is equivalent to:

```
for (i = 0; i < GET_MODE_NUNITS (m); i++)
    op0[i] = op1[i] ? fma (op2[i], op3[i], op4[i]) : op5[i];
```

`negmodecc`

Similar to `movmodecc` but for conditional negation. Conditionally move the
negation of operand 2 or the unchanged operand 3 into operand 0 according to
the comparison in operand 1. If the comparison is true, the negation of operand 2 is moved into operand 0, otherwise operand 3 is moved.

`notmodecc`
Similar to `negmodecc` but for conditional complement. Conditionally move the bitwise complement of operand 2 or the unchanged operand 3 into operand 0 according to the comparison in operand 1. If the comparison is true, the complement of operand 2 is moved into operand 0, otherwise operand 3 is moved.

`cstoremode4`
Store zero or nonzero in operand 0 according to whether a comparison is true. Operand 1 is a comparison operator. Operand 2 and operand 3 are the first and second operand of the comparison, respectively. You specify the mode that operand 0 must have when you write the `match_operand` expression. The compiler automatically sees which mode you have used and supplies an operand of that mode.

The value stored for a true condition must have 1 as its low bit, or else must be negative. Otherwise the instruction is not suitable and you should omit it from the machine description. You describe to the compiler exactly which value is stored by defining the macro `STORE_FLAG_VALUE` (see Section 18.31 [Misc], page 661). If a description cannot be found that can be used for all the possible comparison operators, you should pick one and use a `define_expand` to map all results onto the one you chose.

These operations may FAIL, but should do so only in relatively uncommon cases; if they would FAIL for common cases involving integer comparisons, it is best to restrict the predicates to not allow these operands. Likewise if a given comparison operator will always fail, independent of the operands (for floating-point modes, the `ordered_comparison_operator` predicate is often useful in this case).

If this pattern is omitted, the compiler will generate a conditional branch—for example, it may copy a constant one to the target and branching around an assignment of zero to the target—or a libcall. If the predicate for operand 1 only rejects some operators, it will also try reordering the operands and/or inverting the result value (e.g. by an exclusive OR). These possibilities could be cheaper or equivalent to the instructions used for the `cstoremode4` pattern followed by those required to convert a positive result from `STORE_FLAG_VALUE` to 1; in this case, you can and should make operand 1’s predicate reject some operators in the `cstoremode4` pattern, or remove the pattern altogether from the machine description.

`cbranchmode4`
Conditional branch instruction combined with a compare instruction. Operand 0 is a comparison operator. Operand 1 and operand 2 are the first and second operands of the comparison, respectively. Operand 3 is the `code_label` to jump to.

`jump` A jump inside a function; an unconditional branch. Operand 0 is the `code_label` to jump to. This pattern name is mandatory on all machines.
Subroutine call instruction returning no value. Operand 0 is the function to call; operand 1 is the number of bytes of arguments pushed as a `const_int`. Operand 2 is the result of calling the target hook `TARGET_FUNCTION_ARG` with the second argument `arg` yielding true for `arg.end_marker_p()`, in a call after all parameters have been passed to that hook. By default this is the first register beyond those used for arguments in the call, or `NULL` if all the argument-registers are used in the call.

On most machines, operand 2 is not actually stored into the RTL pattern. It is supplied for the sake of some RISC machines which need to put this information into the assembler code; they can put it in the RTL instead of operand 1.

Operand 0 should be a `mem` RTX whose address is the address of the function. Note, however, that this address can be a `symbol_ref` expression even if it would not be a legitimate memory address on the target machine. If it is also not a valid argument for a call instruction, the pattern for this operation should be a `define_expand` (see Section 17.15 [Expander Definitions], page 454) that places the address into a register and uses that register in the call instruction.

Subroutine call instruction returning a value. Operand 0 is the hard register in which the value is returned. There are three more operands, the same as the three operands of the `call` instruction (but with numbers increased by one).

Subroutines that return `BLKmode` objects use the `call` insn.

Similar to `call` and `call_value`, except used if defined and if `RETURN_POPS_ARGS` is nonzero. They should emit a `parallel` that contains both the function call and a `set` to indicate the adjustment made to the frame pointer.

For machines where `RETURN_POPS_ARGS` can be nonzero, the use of these patterns increases the number of functions for which the frame pointer can be eliminated, if desired.

Subroutine call instruction returning a value of any type. Operand 0 is the function to call; operand 1 is a memory location where the result of calling the function is to be stored; operand 2 is a `parallel` expression where each element is a `set` expression that indicates the saving of a function return value into the result block.

This instruction pattern should be defined to support `__builtin_apply` on machines where special instructions are needed to call a subroutine with arbitrary arguments or to save the value returned. This instruction pattern is required on machines that have multiple registers that can hold a return value (i.e. `FUNCTION_VALUE_REGNO_P` is true for more than one register).

Subroutine return instruction. This instruction pattern name should be defined only if a single instruction can do all the work of returning from a function.

Like the `movm` patterns, this pattern is also used after the RTL generation phase. In this case it is to support machines where multiple instructions are
usually needed to return from a function, but some class of functions only re-
quires one instruction to implement a return. Normally, the applicable functions
are those which do not need to save any registers or allocate stack space.
It is valid for this pattern to expand to an instruction using simple_return if
no epilogue is required.

‘simple_return’
Subroutine return instruction. This instruction pattern name should be defined
only if a single instruction can do all the work of returning from a function on a
path where no epilogue is required. This pattern is very similar to the return
instruction pattern, but it is emitted only by the shrink-wrapping optimization
on paths where the function prologue has not been executed, and a function
return should occur without any of the effects of the epilogue. Additional uses
may be introduced on paths where both the prologue and the epilogue have
executed.
For such machines, the condition specified in this pattern should only be true
when reload_completed is nonzero and the function’s epilogue would only be
a single instruction. For machines with register windows, the routine leaf_
function_p may be used to determine if a register window push is required.
Machines that have conditional return instructions should define patterns such
as
(define_insn ""
 [[set (pc)]
   (if_then_else (match_operator
      0 "comparison_operator"
        [(reg:CC CC_REG) (const_int 0)])
       (return)
       (pc)))]
"condition"
"..."

where condition would normally be the same condition specified on the named
‘return’ pattern.

‘untyped_return’
Untyped subroutine return instruction. This instruction pattern should be
defined to support __builtin_return on machines where special instructions
are needed to return a value of any type.
Operand 0 is a memory location where the result of calling a function with
__builtin_apply is stored; operand 1 is a parallel expression where each
element is a set expression that indicates the restoring of a function return
value from the result block.

‘nop’
No-op instruction. This instruction pattern name should always be defined to
output a no-op in assembler code. (const_int 0) will do as an RTL pattern.

‘indirect_jump’
An instruction to jump to an address which is operand zero. This pattern name
is mandatory on all machines.

‘casesi’ Instruction to jump through a dispatch table, including bounds checking. This
instruction takes five operands:
1. The index to dispatch on, which has mode \texttt{SImode}.
2. The lower bound for indices in the table, an integer constant.
3. The total range of indices in the table—the largest index minus the smallest one (both inclusive).
4. A label that precedes the table itself.
5. A label to jump to if the index has a value outside the bounds.

The table is an \texttt{addr_vec} or \texttt{addr_diff_vec} inside of a \texttt{jump_table_data}. The number of elements in the table is one plus the difference between the upper bound and the lower bound.

\texttt{tablejump}'

Instruction to jump to a variable address. This is a low-level capability which can be used to implement a dispatch table when there is no \texttt{casesi} pattern. This pattern requires two operands: the address or offset, and a label which should immediately precede the jump table. If the macro \texttt{CASE VECTOR PC RELATIVE} evaluates to a nonzero value then the first operand is an offset which counts from the address of the table; otherwise, it is an absolute address to jump to. In either case, the first operand has mode \texttt{Pmode}.

The \texttt{tablejump}' insn is always the last insn before the jump table it uses. Its assembler code normally has no need to use the second operand, but you should incorporate it in the RTL pattern so that the jump optimizer will not delete the table as unreachable code.

\texttt{doloop_end}'

Conditional branch instruction that decrements a register and jumps if the register is nonzero. Operand 0 is the register to decrement and test; operand 1 is the label to jump to if the register is nonzero. See Section 17.13 [Looping Patterns], page 451.

This optional instruction pattern should be defined for machines with low-overhead looping instructions as the loop optimizer will try to modify suitable loops to utilize it. The target hook \texttt{TARGET CAN USE DOLOOP P} controls the conditions under which low-overhead loops can be used.

\texttt{doloop_begin}'

Companion instruction to \texttt{doloop_end} required for machines that need to perform some initialization, such as loading a special counter register. Operand 1 is the associated \texttt{doloop_end} pattern and operand 0 is the register that it decrements.

If initialization insns do not always need to be emitted, use a \texttt{define expand} (see Section 17.15 [Expander Definitions], page 454) and make it fail.

\texttt{canonicalize_funcptr_for_compare}'

Canonicalize the function pointer in operand 1 and store the result into operand 0.

Operand 0 is always a \texttt{reg} and has mode \texttt{Pmode}; operand 1 may be a \texttt{reg}, \texttt{mem}, \texttt{symbol_ref}, \texttt{const_int}, etc and also has mode \texttt{Pmode}. 
Canonicalization of a function pointer usually involves computing the address of the function which would be called if the function pointer were used in an indirect call.

Only define this pattern if function pointers on the target machine can have different values but still call the same function when used in an indirect call.

'save_stack_block'
'save_stack_function'
'save_stack_nonlocal'
'restore_stack_block'
'restore_stack_function'
'restore_stack_nonlocal'

Most machines save and restore the stack pointer by copying it to or from an object of mode Pmode. Do not define these patterns on such machines.

Some machines require special handling for stack pointer saves and restores. On those machines, define the patterns corresponding to the non-standard cases by using a define_expand (see Section 17.15 [Expander Definitions], page 454) that produces the required insns. The three types of saves and restores are:

1. 'save_stack_block' saves the stack pointer at the start of a block that allocates a variable-sized object, and 'restore_stack_block' restores the stack pointer when the block is exited.

2. 'save_stack_function' and 'restore_stack_function' do a similar job for the outermost block of a function and are used when the function allocates variable-sized objects or calls alloca. Only the epilogue uses the restored stack pointer, allowing a simpler save or restore sequence on some machines.

3. 'save_stack_nonlocal' is used in functions that contain labels branched to by nested functions. It saves the stack pointer in such a way that the inner function can use 'restore_stack_nonlocal' to restore the stack pointer. The compiler generates code to restore the frame and argument pointer registers, but some machines require saving and restoring additional data such as register window information or stack backchains. Place insns in these patterns to save and restore any such required data.

When saving the stack pointer, operand 0 is the save area and operand 1 is the stack pointer. The mode used to allocate the save area defaults to Pmode but you can override that choice by defining the STACK_SAVEAREA_MODE macro (see Section 18.5 [Storage Layout], page 508). You must specify an integral mode, or VOIDmode if no save area is needed for a particular type of save (either because no save is needed or because a machine-specific save area can be used). Operand 0 is the stack pointer and operand 1 is the save area for restore operations. If 'save_stack_block' is defined, operand 0 must not be VOIDmode since these saves can be arbitrarily nested.

A save area is a mem that is at a constant offset from virtual_stack_vars_rtx when the stack pointer is saved for use by nonlocal gotos and a reg in the other two cases.
'allocate_stack'
Subtract (or add if STACK_GROWS_DOWNWARD is undefined) operand 1 from the stack pointer to create space for dynamically allocated data.

Store the resultant pointer to this space into operand 0. If you are allocating space from the main stack, do this by emitting a move insn to copy virtual_stack_dynamic_rtx to operand 0. If you are allocating the space elsewhere, generate code to copy the location of the space to operand 0. In the latter case, you must ensure this space gets freed when the corresponding space on the main stack is free.

Do not define this pattern if all that must be done is the subtraction. Some machines require other operations such as stack probes or maintaining the back chain. Define this pattern to emit those operations in addition to updating the stack pointer.

'check_stack'
If stack checking (see Section 18.9.3 [Stack Checking], page 546) cannot be done on your system by probing the stack, define this pattern to perform the needed check and signal an error if the stack has overflowed. The single operand is the address in the stack farthest from the current stack pointer that you need to validate. Normally, on platforms where this pattern is needed, you would obtain the stack limit from a global or thread-specific variable or register.

'probe_stack_address'
If stack checking (see Section 18.9.3 [Stack Checking], page 546) can be done on your system by probing the stack but without the need to actually access it, define this pattern and signal an error if the stack has overflowed. The single operand is the memory address in the stack that needs to be probed.

'probe_stack'
If stack checking (see Section 18.9.3 [Stack Checking], page 546) can be done on your system by probing the stack but doing it with a “store zero” instruction is not valid or optimal, define this pattern to do the probing differently and signal an error if the stack has overflowed. The single operand is the memory reference in the stack that needs to be probed.

'nonlocal_goto'
Emit code to generate a non-local goto, e.g., a jump from one function to a label in an outer function. This pattern has four arguments, each representing a value to be used in the jump. The first argument is to be loaded into the frame pointer, the second is the address to branch to (code to dispatch to the actual label), the third is the address of a location where the stack is saved, and the last is the address of the label, to be placed in the location for the incoming static chain.

On most machines you need not define this pattern, since GCC will already generate the correct code, which is to load the frame pointer and static chain, restore the stack (using the ‘restore_stack_nonlocal’ pattern, if defined), and jump indirectly to the dispatcher. You need only define this pattern if this code will not work on your machine.
'nonlocal_goto_receiver'
This pattern, if defined, contains code needed at the target of a nonlocal goto after the code already generated by GCC. You will not normally need to define this pattern. A typical reason why you might need this pattern is if some value, such as a pointer to a global table, must be restored when the frame pointer is restored. Note that a nonlocal goto only occurs within a unit-of-translation, so a global table pointer that is shared by all functions of a given module need not be restored. There are no arguments.

'exception_receiver'
This pattern, if defined, contains code needed at the site of an exception handler that isn’t needed at the site of a nonlocal goto. You will not normally need to define this pattern. A typical reason why you might need this pattern is if some value, such as a pointer to a global table, must be restored after control flow is branched to the handler of an exception. There are no arguments.

'builtin_setjmp_setup'
This pattern, if defined, contains additional code needed to initialize the jmp_buf. You will not normally need to define this pattern. A typical reason why you might need this pattern is if some value, such as a pointer to a global table, must be restored. Though it is preferred that the pointer value be recalculated if possible (given the address of a label for instance). The single argument is a pointer to the jmp_buf. Note that the buffer is five words long and that the first three are normally used by the generic mechanism.

'builtin_setjmp_receiver'
This pattern, if defined, contains code needed at the site of a built-in setjmp that isn’t needed at the site of a nonlocal goto. You will not normally need to define this pattern. A typical reason why you might need this pattern is if some value, such as a pointer to a global table, must be restored. It takes one argument, which is the label to which builtin_longjmp transferred control; this pattern may be emitted at a small offset from that label.

'builtin_longjmp'
This pattern, if defined, performs the entire action of the longjmp. You will not normally need to define this pattern unless you also define builtin_setjmp_setup. The single argument is a pointer to the jmp_buf.

'eh_return'
This pattern, if defined, affects the way __builtin_eh_return, and thence the call frame exception handling library routines, are built. It is intended to handle non-trivial actions needed along the abnormal return path. The address of the exception handler to which the function should return is passed as operand to this pattern. It will normally need to copied by the pattern to some special register or memory location. If the pattern needs to determine the location of the target call frame in order to do so, it may use EH_RETURN_STACKADJ_RTX, if defined; it will have already been assigned.
If this pattern is not defined, the default action will be to simply copy the return address to EH_RETURN_HANDLER_RTX. Either that macro or this pattern needs to be defined if call frame exception handling is to be used.
'prologue'
This pattern, if defined, emits RTL for entry to a function. The function entry is responsible for setting up the stack frame, initializing the frame pointer register, saving callee saved registers, etc.

Using a prologue pattern is generally preferred over defining TARGET_ASM_FUNCTION_PROLOGUE to emit assembly code for the prologue.

The prologue pattern is particularly useful for targets which perform instruction scheduling.

>window_save'
This pattern, if defined, emits RTL for a register window save. It should be defined if the target machine has register windows but the window events are decoupled from calls to subroutines. The canonical example is the SPARC architecture.

'epilogue'
This pattern emits RTL for exit from a function. The function exit is responsible for deallocating the stack frame, restoring callee saved registers and emitting the return instruction.

Using an epilogue pattern is generally preferred over defining TARGET_ASM_FUNCTION_EPILOGUE to emit assembly code for the epilogue.

The epilogue pattern is particularly useful for targets which perform instruction scheduling or which have delay slots for their return instruction.

'sibcall_epilogue'
This pattern, if defined, emits RTL for exit from a function without the final branch back to the calling function. This pattern will be emitted before any sibling call (aka tail call) sites.

The sibcall_epilogue pattern must not clobber any arguments used for parameter passing or any stack slots for arguments passed to the current function.

'trap'
This pattern, if defined, signals an error, typically by causing some kind of signal to be raised.

'ctrapMM4'
Conditional trap instruction. Operand 0 is a piece of RTL which performs a comparison, and operands 1 and 2 are the arms of the comparison. Operand 3 is the trap code, an integer.

A typical ctrap pattern looks like
(define_insn "ctrapMM4"
 [(trap_if (match_operator 0 "trap_operator"
 [[(match_operand 1 "register_operand")
 (match_operand 2 "immediate_operand")]]
 (match_operand 3 "const_int_operand" "i"))]
 ""
 "...")

'prefetch'
This pattern, if defined, emits code for a non-faulting data prefetch instruction. Operand 0 is the address of the memory to prefetch. Operand 1 is a constant
1 if the prefetch is preparing for a write to the memory address, or a constant 0 otherwise. Operand 2 is the expected degree of temporal locality of the data and is a value between 0 and 3, inclusive; 0 means that the data has no temporal locality, so it need not be left in the cache after the access; 3 means that the data has a high degree of temporal locality and should be left in all levels of cache possible; 1 and 2 mean, respectively, a low or moderate degree of temporal locality.

Targets that do not support write prefetches or locality hints can ignore the values of operands 1 and 2.

`blockage`
This pattern defines a pseudo insn that prevents the instruction scheduler and other passes from moving instructions and using register equivalences across the boundary defined by the blockage insn. This needs to be an UNSPEC_VOLATILE pattern or a volatile ASM.

`memory_blockage`
This pattern, if defined, represents a compiler memory barrier, and will be placed at points across which RTL passes may not propagate memory accesses. This instruction needs to read and write volatile BLKmode memory. It does not need to generate any machine instruction. If this pattern is not defined, the compiler falls back to emitting an instruction corresponding to `asm volatile ("":": "memory")`.

`memory_barrier`
If the target memory model is not fully synchronous, then this pattern should be defined to an instruction that orders both loads and stores before the instruction with respect to loads and stores after the instruction. This pattern has no operands.

`speculation_barrier`
If the target can support speculative execution, then this pattern should be defined to an instruction that will block subsequent execution until any prior speculation conditions has been resolved. The pattern must also ensure that the compiler cannot move memory operations past the barrier, so it needs to be an UNSPEC_VOLATILE pattern. The pattern has no operands.

If this pattern is not defined then the default expansion of `__builtin_speculation_safe_value` will emit a warning. You can suppress this warning by defining this pattern with a final condition of 0 (zero), which tells the compiler that a speculation barrier is not needed for this target.

`sync_compare_and_swap`
This pattern, if defined, emits code for an atomic compare-and-swap operation. Operand 1 is the memory on which the atomic operation is performed. Operand 2 is the “old” value to be compared against the current contents of the memory location. Operand 3 is the “new” value to store in the memory if the compare succeeds. Operand 0 is the result of the operation; it should contain the contents of the memory before the operation. If the compare succeeds, this should obviously be a copy of operand 2.
This pattern must show that both operand 0 and operand 1 are modified.

This pattern must issue any memory barrier instructions such that all memory operations before the atomic operation occur before the atomic operation and all memory operations after the atomic operation occur after the atomic operation.

For targets where the success or failure of the compare-and-swap operation is available via the status flags, it is possible to avoid a separate compare operation and issue the subsequent branch or store-flag operation immediately after the compare-and-swap. To this end, GCC will look for a MODE_CC set in the output of sync_compare_and_swap; if the machine description includes such a set, the target should also define special cbranchcc4 and/or cstorecc4 instructions. GCC will then be able to take the destination of the MODE_CC set and pass it to the cbranchcc4 or cstorecc4 pattern as the first operand of the comparison (the second will be (const_int 0)).

For targets where the operating system may provide support for this operation via library calls, the sync_compare_and_swap_optab may be initialized to a function with the same interface as the __sync_val_compare_and_swap_n built-in. If the entire set of __sync builtins are supported via library calls, the target can initialize all of the optabs at once with init_sync_libfuncs. For the purposes of C++11 std::atomic::is_lock_free, it is assumed that these library calls do not use any kind of interruptable locking.

'sync_addmode', 'sync_submode'
'sync_iormode', 'sync_andmode'
'sync_xormode', 'sync_nandmode'

These patterns emit code for an atomic operation on memory. Operand 0 is the memory on which the atomic operation is performed. Operand 1 is the second operand to the binary operator.

This pattern must issue any memory barrier instructions such that all memory operations before the atomic operation occur before the atomic operation and all memory operations after the atomic operation occur after the atomic operation.

If these patterns are not defined, the operation will be constructed from a compare-and-swap operation, if defined.

'sync_old_addmode', 'sync_old_submode'
'sync_old_iormode', 'sync_old_andmode'
'sync_old_xormode', 'sync_old_nandmode'

These patterns emit code for an atomic operation on memory, and return the value that the memory contained before the operation. Operand 0 is the result value, operand 1 is the memory on which the atomic operation is performed, and operand 2 is the second operand to the binary operator.

This pattern must issue any memory barrier instructions such that all memory operations before the atomic operation occur before the atomic operation and all memory operations after the atomic operation occur after the atomic operation.

If these patterns are not defined, the operation will be constructed from a compare-and-swap operation, if defined.
'sync_new_addmode', 'sync_new_submode'
'sync_new_iormode', 'sync_new_andmode'
'sync_new_xormode', 'sync_new_nandmode'

These patterns are like their sync_old_op counterparts, except that they return the value that exists in the memory location after the operation, rather than before the operation.

'sync_lock_test_and_setmode'

This pattern takes two forms, based on the capabilities of the target. In either case, operand 0 is the result of the operand, operand 1 is the memory on which the atomic operation is performed, and operand 2 is the value to set in the lock.

In the ideal case, this operation is an atomic exchange operation, in which the previous value in memory operand is copied into the result operand, and the value operand is stored in the memory operand.

For less capable targets, any value operand that is not the constant 1 should be rejected with FAIL. In this case the target may use an atomic test-and-set bit operation. The result operand should contain 1 if the bit was previously set and 0 if the bit was previously clear. The true contents of the memory operand are implementation defined.

This pattern must issue any memory barrier instructions such that the pattern as a whole acts as an acquire barrier, that is all memory operations after the pattern do not occur until the lock is acquired.

If this pattern is not defined, the operation will be constructed from a compare-and-swap operation, if defined.

'sync_lock_releasemode'

This pattern, if defined, releases a lock set by sync_lock_test_and_setmode. Operand 0 is the memory that contains the lock; operand 1 is the value to store in the lock.

If the target doesn’t implement full semantics for sync_lock_test_and_setmode, any value operand which is not the constant 0 should be rejected with FAIL, and the true contents of the memory operand are implementation defined.

This pattern must issue any memory barrier instructions such that the pattern as a whole acts as a release barrier, that is the lock is released only after all previous memory operations have completed.

If this pattern is not defined, then a memory_barrier pattern will be emitted, followed by a store of the value to the memory operand.

'atomic_compare_and_swapmode'

This pattern, if defined, emits code for an atomic compare-and-swap operation with memory model semantics. Operand 2 is the memory on which the atomic operation is performed. Operand 0 is an output operand which is set to true or false based on whether the operation succeeded. Operand 1 is an output operand which is set to the contents of the memory before the operation was attempted. Operand 3 is the value that is expected to be in memory. Operand 4 is the value to put in memory if the expected value is found there. Operand 5 is
set to 1 if this compare and swap is to be treated as a weak operation. Operand 6 is the memory model to be used if the operation is a success. Operand 7 is the memory model to be used if the operation fails.

If memory referred to in operand 2 contains the value in operand 3, then operand 4 is stored in memory pointed to by operand 2 and fencing based on the memory model in operand 6 is issued.

If memory referred to in operand 2 does not contain the value in operand 3, then fencing based on the memory model in operand 7 is issued.

If a target does not support weak compare-and-swap operations, or the port elects not to implement weak operations, the argument in operand 5 can be ignored. Note a strong implementation must be provided.

If this pattern is not provided, the `__atomic_compare_exchange` built-in functions will utilize the legacy `sync_compare_and_swap` pattern with an `__ATOMIC_SEQ_CST` memory model.

`atomic_loadmode`
This pattern implements an atomic load operation with memory model semantics. Operand 1 is the memory address being loaded from. Operand 0 is the result of the load. Operand 2 is the memory model to be used for the load operation.

If not present, the `__atomic_load` built-in function will either resort to a normal load with memory barriers, or a compare-and-swap operation if a normal load would not be atomic.

`atomic_storemode`
This pattern implements an atomic store operation with memory model semantics. Operand 0 is the memory address being stored to. Operand 1 is the value to be written. Operand 2 is the memory model to be used for the operation.

If not present, the `__atomic_store` built-in function will attempt to perform a normal store and surround it with any required memory fences. If the store would not be atomic, then an `__atomic_exchange` is attempted with the result being ignored.

`atomic_exchangemode`
This pattern implements an atomic exchange operation with memory model semantics. Operand 1 is the memory location the operation is performed on. Operand 0 is an output operand which is set to the original value contained in the memory pointed to by operand 1. Operand 2 is the value to be stored. Operand 3 is the memory model to be used.

If this pattern is not present, the built-in function `__atomic_exchange` will attempt to perform the operation with a compare and swap loop.

`atomic_addmode`, `atomic_submode`
`atomic_ormode`, `atomic_andmode`
`atomic_xormode`, `atomic_nandmode`
These patterns emit code for an atomic operation on memory with memory model semantics. Operand 0 is the memory on which the atomic operation is
performed. Operand 1 is the second operand to the binary operator. Operand 2 is the memory model to be used by the operation.

If these patterns are not defined, attempts will be made to use legacy \texttt{sync} patterns, or equivalent patterns which return a result. If none of these are available a compare-and-swap loop will be used.

\begin{quote}
\texttt{atomic_fetch_add\_mode}, \texttt{atomic_fetch_sub\_mode} \\
\texttt{atomic_fetch_or\_mode}, \texttt{atomic_fetch_and\_mode} \\
\texttt{atomic_fetch_xor\_mode}, \texttt{atomic_fetch_nand\_mode}
\end{quote}

These patterns emit code for an atomic operation on memory with memory model semantics, and return the original value. Operand 0 is an output operand which contains the value of the memory location before the operation was performed. Operand 1 is the memory on which the atomic operation is performed. Operand 2 is the second operand to the binary operator. Operand 3 is the memory model to be used by the operation.

If these patterns are not defined, attempts will be made to use legacy \texttt{sync} patterns. If none of these are available a compare-and-swap loop will be used.

\begin{quote}
\texttt{atomic_add\_fetchmode}, \texttt{atomic_sub\_fetchmode} \\
\texttt{atomic_or\_fetchmode}, \texttt{atomic_and\_fetchmode} \\
\texttt{atomic_xor\_fetchmode}, \texttt{atomic_nand\_fetchmode}
\end{quote}

These patterns emit code for an atomic operation on memory with memory model semantics and return the result after the operation is performed. Operand 0 is an output operand which contains the value after the operation. Operand 1 is the memory on which the atomic operation is performed. Operand 2 is the second operand to the binary operator. Operand 3 is the memory model to be used by the operation.

If these patterns are not defined, attempts will be made to use legacy \texttt{sync} patterns, or equivalent patterns which return the result before the operation followed by the arithmetic operation required to produce the result. If none of these are available a compare-and-swap loop will be used.

\begin{quote}
\texttt{atomic\_test\_and\_set}
\end{quote}

This pattern emits code for \texttt{__builtin\_atomic\_test\_and\_set}. Operand 0 is an output operand which is set to true if the previous previous contents of the byte was "set", and false otherwise. Operand 1 is the \texttt{QI\_mode} memory to be modified. Operand 2 is the memory model to be used.

The specific value that defines "set" is implementation defined, and is normally based on what is performed by the native atomic test and set instruction.

\begin{quote}
\texttt{atomic\_bit\_test\_and\_set\_mode} \\
\texttt{atomic\_bit\_test\_and\_complement\_mode} \\
\texttt{atomic\_bit\_test\_and\_reset\_mode}
\end{quote}

These patterns emit code for an atomic bitwise operation on memory with memory model semantics, and return the original value of the specified bit. Operand 0 is an output operand which contains the value of the specified bit from the memory location before the operation was performed. Operand 1 is the memory on which the atomic operation is performed. Operand 2 is the bit within the
operand, starting with least significant bit. Operand 3 is the memory model to be used by the operation. Operand 4 is a flag - it is const1_rtx if operand 0 should contain the original value of the specified bit in the least significant bit of the operand, and const0_rtx if the bit should be in its original position in the operand. atomic_bit_test_and_setmode atomically sets the specified bit after remembering its original value, atomic_bit_test_and_complementmode inverts the specified bit and atomic_bit_test_and_resetmode clears the specified bit.

If these patterns are not defined, attempts will be made to use atomic_fetch_ormode, atomic_fetch_xormode or atomic_fetch_andmode instruction patterns, or their sync counterparts. If none of these are available a compare-and-swap loop will be used.

`mem_thread_fence`
This pattern emits code required to implement a thread fence with memory model semantics. Operand 0 is the memory model to be used.

For the __ATOMIC_RELAXED model no instructions need to be issued and this expansion is not invoked.

The compiler always emits a compiler memory barrier regardless of what expanding this pattern produced.

If this pattern is not defined, the compiler falls back to expanding the memory_barrier pattern, then to emitting __sync_synchronize library call, and finally to just placing a compiler memory barrier.

`get_thread_pointermode`
`set_thread_pointermode`
These patterns emit code that reads/sets the TLS thread pointer. Currently, these are only needed if the target needs to support the __builtin_thread_pointer and __builtin_set_thread_pointer builtins.

The get/set patterns have a single output/input operand respectively, with mode intended to be Pmode.

`stack_protect_combined_set`
This pattern, if defined, moves a ptr_mode value from an address whose declaration RTX is given in operand 1 to the memory in operand 0 without leaving the value in a register afterward. If several instructions are needed by the target to perform the operation (eg. to load the address from a GOT entry then load the ptr_mode value and finally store it), it is the backend’s responsibility to ensure no intermediate result gets spilled. This is to avoid leaking the value some place that an attacker might use to rewrite the stack guard slot after having clobbered it.

If this pattern is not defined, then the address declaration is expanded first in the standard way and a stack_protect_set pattern is then generated to move the value from that address to the address in operand 0.

`stack_protect_set`
This pattern, if defined, moves a ptr_mode value from the valid memory location in operand 1 to the memory in operand 0 without leaving the value in a register
 afterward. This is to avoid leaking the value some place that an attacker might use to rewrite the stack guard slot after having clobbered it.

Note: on targets where the addressing modes do not allow to load directly from stack guard address, the address is expanded in a standard way first which could cause some spills.

If this pattern is not defined, then a plain move pattern is generated.

`stack_protect_combined_test`

This pattern, if defined, compares a ptr_mode value from an address whose declaration RTX is given in operand 1 with the memory in operand 0 without leaving the value in a register afterward and branches to operand 2 if the values were equal. If several instructions are needed by the target to perform the operation (eg. to load the address from a GOT entry then load the ptr_mode value and finally store it), it is the backend’s responsibility to ensure no intermediate result gets spilled. This is to avoid leaking the value some place that an attacker might use to rewrite the stack guard slot after having clobbered it.

If this pattern is not defined, then a plain move pattern is generated.

If this pattern is not defined, then a plain move pattern is generated.

`stack_protect_test`

This pattern, if defined, compares a ptr_mode value from the valid memory location in operand 1 with the memory in operand 0 without leaving the value in a register afterward and branches to operand 2 if the values were equal.

If this pattern is not defined, then a plain compare pattern and conditional branch pattern is used.

`clear_cache`

This pattern, if defined, flushes the instruction cache for a region of memory. The region is bounded to by the Pmode pointers in operand 0 inclusive and operand 1 exclusive.

If this pattern is not defined, a call to the library function `__clear_cache` is used.

### 17.10 When the Order of Patterns Matters

Sometimes an insn can match more than one instruction pattern. Then the pattern that appears first in the machine description is the one used. Therefore, more specific patterns (patterns that will match fewer things) and faster instructions (those that will produce better code when they do match) should usually go first in the description.

In some cases the effect of ordering the patterns can be used to hide a pattern when it is not valid. For example, the 68000 has an instruction for converting a fullword to floating point and another for converting a byte to floating point. An instruction converting an integer to floating point could match either one. We put the pattern to convert the fullword first to make sure that one will be used rather than the other. (Otherwise a large integer might be generated as a single-byte immediate quantity, which would not work.) Instead
of using this pattern ordering it would be possible to make the pattern for convert-a-byte smart enough to deal properly with any constant value.

17.11 Interdependence of Patterns

In some cases machines support instructions identical except for the machine mode of one or more operands. For example, there may be “sign-extend halfword” and “sign-extend byte” instructions whose patterns are

\[
\text{(set (match_operand:SI 0 ...)}
\]
\[
\text{(extend:SI (match_operand:HI 1 ...)))}
\]

\[
\text{(set (match_operand:SI 0 ...)}
\]
\[
\text{(extend:SI (match_operand:QI 1 ...)))}
\]

Constant integers do not specify a machine mode, so an instruction to extend a constant value could match either pattern. The pattern it actually will match is the one that appears first in the file. For correct results, this must be the one for the widest possible mode (\text{HImode}, here). If the pattern matches the \text{QImode} instruction, the results will be incorrect if the constant value does not actually fit that mode.

Such instructions to extend constants are rarely generated because they are optimized away, but they do occasionally happen in nonoptimized compilations.

If a constraint in a pattern allows a constant, the reload pass may replace a register with a constant permitted by the constraint in some cases. Similarly for memory references. Because of this substitution, you should not provide separate patterns for increment and decrement instructions. Instead, they should be generated from the same pattern that supports register-register add insns by examining the operands and generating the appropriate machine instruction.

17.12 Defining Jump Instruction Patterns

GCC does not assume anything about how the machine realizes jumps. The machine description should define a single pattern, usually a \text{define\_expand}, which expands to all the required insns.

Usually, this would be a comparison insn to set the condition code and a separate branch insn testing the condition code and branching or not according to its value. For many machines, however, separating compares and branches is limiting, which is why the more flexible approach with one \text{define\_expand} is used in GCC. The machine description becomes clearer for architectures that have compare-and-branch instructions but no condition code. It also works better when different sets of comparison operators are supported by different kinds of conditional branches (e.g. integer vs. floating-point), or by conditional branches with respect to conditional stores.

Two separate insns are always used on most machines that use a separate condition code register (see Section 18.15 [Condition Code], page 591).

Even in this case having a single entry point for conditional branches is advantageous, because it handles equally well the case where a single comparison instruction records the results of both signed and unsigned comparison of the given operands (with the branch insns coming in distinct signed and unsigned flavors) as in the x86 or SPARC, and the case where there are distinct signed and unsigned compare instructions and only one set of conditional branch instructions as in the PowerPC.
17.13 Defining Looping Instruction Patterns

Some machines have special jump instructions that can be utilized to make loops more efficient. A common example is the 68000 ‘dbra’ instruction which performs a decrement of a register and a branch if the result was greater than zero. Other machines, in particular digital signal processors (DSPs), have special block repeat instructions to provide low-overhead loop support. For example, the TI TMS320C3x/C4x DSPs have a block repeat instruction that loads special registers to mark the top and end of a loop and to count the number of loop iterations. This avoids the need for fetching and executing a ‘dbra’-like instruction and avoids pipeline stalls associated with the jump.

GCC has two special named patterns to support low overhead looping. They are ‘doloop_begin’ and ‘doloop_end’. These are emitted by the loop optimizer for certain well-behaved loops with a finite number of loop iterations using information collected during strength reduction.

The ‘doloop_end’ pattern describes the actual looping instruction (or the implicit looping operation) and the ‘doloop_begin’ pattern is an optional companion pattern that can be used for initialization needed for some low-overhead looping instructions.

Note that some machines require the actual looping instruction to be emitted at the top of the loop (e.g., the TMS320C3x/C4x DSPs). Emitting the true RTL for a looping instruction at the top of the loop can cause problems with flow analysis. So instead, a dummy doloop insn is emitted at the end of the loop. The machine dependent reorg pass checks for the presence of this doloop insn and then searches back to the top of the loop, where it inserts the true looping insn (provided there are no instructions in the loop which would cause problems). Any additional labels can be emitted at this point. In addition, if the desired special iteration counter register was not allocated, this machine dependent reorg pass could emit a traditional compare and jump instruction pair.

For the ‘doloop_end’ pattern, the loop optimizer allocates an additional pseudo register as an iteration counter. This pseudo register cannot be used within the loop (i.e., general induction variables cannot be derived from it), however, in many cases the loop induction variable may become redundant and removed by the flow pass.

The ‘doloop_end’ pattern must have a specific structure to be handled correctly by GCC. The example below is taken (slightly simplified) from the PDP-11 target:
The first part of the pattern describes the branch condition. GCC supports three cases for the way the target machine handles the loop counter:

- Loop terminates when the loop register decrements to zero. This is represented by a `ne` comparison of the register (its old value) with constant 1 (as in the example above).
- Loop terminates when the loop register decrements to −1. This is represented by a `ne` comparison of the register with constant zero.
- Loop terminates when the loop register decrements to a negative value. This is represented by a `ge` comparison of the register with constant zero. For this case, GCC will attach a `REG_NONNEG` note to the `doloop_end` insn if it can determine that the register will be non-negative.

Since the `doloop_end` insn is a jump insn that also has an output, the reload pass does not handle the output operand. Therefore, the constraint must allow for that operand to be in memory rather than a register. In the example shown above, that is handled (in the `doloop_end_insn` pattern) by using a loop instruction sequence that can handle memory operands when the memory alternative appears.

GCC does not check the mode of the loop register operand when generating the `doloop_end` pattern. If the pattern is only valid for some modes but not others, the pattern should...
be a define_expand pattern that checks the operand mode in the preparation code, and issues FAIL if an unsupported mode is found. The example above does this, since the machine instruction to be used only exists for Hi mode.

If the doloop_end pattern is a define_expand, there must also be a define_insn or define_insn_and_split matching the generated pattern. Otherwise, the compiler will fail during loop optimization.

17.14 Canonicalization of Instructions

There are often cases where multiple RTL expressions could represent an operation performed by a single machine instruction. This situation is most commonly encountered with logical, branch, and multiply-accumulate instructions. In such cases, the compiler attempts to convert these multiple RTL expressions into a single canonical form to reduce the number of insn patterns required.

In addition to algebraic simplifications, following canonicalizations are performed:

• For commutative and comparison operators, a constant is always made the second operand. If a machine only supports a constant as the second operand, only patterns that match a constant in the second operand need be supplied.

• For associative operators, a sequence of operators will always chain to the left; for instance, only the left operand of an integer plus can itself be a plus, and, or, xor, plus, mult, smin, smax, umin, and umax are associative when applied to integers, and sometimes to floating-point.

• For these operators, if only one operand is a neg, not, mult, plus, or minus expression, it will be the first operand.

• In combinations of neg, mult, plus, and minus, the neg operations (if any) will be moved inside the operations as far as possible. For instance, \((\text{neg} \ (\text{mult} \ A \ B))\) is canonicalized as \((\text{mult} \ (\text{neg} \ A) \ B)\), but \((\text{plus} \ (\text{mult} \ (\text{neg} \ B) \ C) \ A)\) is canonicalized as \((\text{minus} \ A \ (\text{mult} \ B \ C))\).

• For the compare operator, a constant is always the second operand if the first argument is a condition code register.

• For instructions that inherently set a condition code register, the compare operator is always written as the first RTL expression of the parallel instruction pattern. For example,

\[
\text{(define_insn "}
\text{[(set (reg:CCZ FLAGS_REG)}
\text{\(\\text{\(\text{(compare:CCZ}\)\)}}
\text{\(\text{\(\text{(plus:SI (match_operand:SI 1 "register_operand" \"r\")\)}}\)\)}}
\text{\(\text{\(\text{(match_operand:SI 2 "register_operand" \"r\")\)}}\)\)}}
\text{\(\text{\(\text{(const_int 0))}}\)\)}}
\text{\(\text{\(\text{(set (match_operand:SI 0 "register_operand" \"r\")\)}}\)\)}}
\text{\(\text{\(\text{(plus:SI (match_dup 1) (match_dup 2))})\)}}
\text{\(\"\)}}
\text{\"addl \%0, \%1, \%2\")\)\}

• An operand of neg, not, mult, plus, or minus is made the first operand under the same conditions as above.

• \((\text{ltu} \ (\text{plus} \ a \ b) \ b)\) is converted to \((\text{ltu} \ (\text{plus} \ a \ b) \ a)\). Likewise with \text{geu} instead of \text{ltu}.\)
• \((\text{minus } x (\text{const}\_\text{int } n))\) is converted to \((\text{plus } x (\text{const}\_\text{int } \text{-}n))\).

• Within address computations (i.e., inside \text{mem}), a left shift is converted into the appropriate multiplication by a power of two.

• De Morgan’s Law is used to move bitwise negation inside a bitwise logical-and or logical-or operation. If this results in only one operand being a \text{not} expression, it will be the first one.

A machine that has an instruction that performs a bitwise logical-and of one operand with the bitwise negation of the other should specify the pattern for that instruction as

\[
\text{define_insn "} \\
[(\text{set } (\text{match}\_\text{operand}:m 0 \ldots) \\
(\text{and}:m (\text{not}:m (\text{match}\_\text{operand}:m 1 \ldots)) \\
(\text{match}\_\text{operand}:m 2 \ldots))))] \\
"\ldots" \\
"\ldots"
\]

Similarly, a pattern for a “NAND” instruction should be written

\[
\text{define_insn "} \\
[(\text{set } (\text{match}\_\text{operand}:m 0 \ldots) \\
(\text{ior}:m (\text{not}:m (\text{match}\_\text{operand}:m 1 \ldots)) \\
(\text{not}:m (\text{match}\_\text{operand}:m 2 \ldots))))] \\
"\ldots" \\
"\ldots"
\]

In both cases, it is not necessary to include patterns for the many logically equivalent RTL expressions.

• The only possible RTL expressions involving both bitwise exclusive-or and bitwise negation are \((\text{xor}:m x y)\) and \((\text{not}:m (\text{xor}:m x y))\).

• The sum of three items, one of which is a constant, will only appear in the form

\[
(\text{plus}:m (\text{plus}:m x y) \text{ constant})
\]

• Equality comparisons of a group of bits (usually a single bit) with zero will be written using \text{zero\_extract} rather than the equivalent \text{and} or \text{sign\_extract} operations.

• \((\text{sign\_extend}:m1 (\text{mult}:m2 (\text{sign\_extend}:m2 x) (\text{sign\_extend}:m2 y)))\) is converted to \((\text{mult}:m1 (\text{sign\_extend}:m1 x) (\text{sign\_extend}:m1 y))\), and likewise for \text{zero\_extend}.

• \((\text{sign\_extend}:m1 (\text{mult}:m2 (\text{ashiftrt}:m2 x s) (\text{sign\_extend}:m2 y)))\) is converted to \((\text{mult}:m1 (\text{sign\_extend}:m1 (\text{ashiftrt}:m2 x s)) (\text{sign\_extend}:m1 y))\), and likewise for patterns using \text{zero\_extend} and \text{lshift\_rt}. If the second operand of \text{mult} is also a shift, then that is extended also. This transformation is only applied when it can be proven that the original operation had sufficient precision to prevent overflow.

Further canonicalization rules are defined in the function \text{commutative\_operand\_precedence} in ‘gcc/rtlanal.c’.

### 17.15 Defining RTL Sequences for Code Generation

On some target machines, some standard pattern names for RTL generation cannot be handled with single insn, but a sequence of RTL insns can represent them. For these target machines, you can write a \text{define\_expand} to specify how to generate the sequence of RTL.
A **define_expand** is an RTL expression that looks almost like a **define_insn**; but, unlike the latter, a **define_expand** is used only for RTL generation and it can produce more than one RTL insn.

A **define_expand** RTX has four operands:

- The name. Each **define_expand** must have a name, since the only use for it is to refer to it by name.
- The RTL template. This is a vector of RTL expressions representing a sequence of separate instructions. Unlike **define_insn**, there is no implicit surrounding **PARALLEL**.
- The condition, a string containing a C expression. This expression is used to express how the availability of this pattern depends on subclasses of target machine, selected by command-line options when GCC is run. This is just like the condition of a **define_insn** that has a standard name. Therefore, the condition (if present) may not depend on the data in the insn being matched, but only the target-machine-type flags. The compiler needs to test these conditions during initialization in order to learn exactly which named instructions are available in a particular run.
- The preparation statements, a string containing zero or more C statements which are to be executed before RTL code is generated from the RTL template. Usually these statements prepare temporary registers for use as internal operands in the RTL template, but they can also generate RTL insns directly by calling routines such as **emit_insn**, etc. Any such insns precede the ones that come from the RTL template.
- Optionally, a vector containing the values of attributes. See Section 17.19 [Insn Attributes], page 467.

Every RTL insn emitted by a **define_expand** must match some **define_insn** in the machine description. Otherwise, the compiler will crash when trying to generate code for the insn or trying to optimize it.

The RTL template, in addition to controlling generation of RTL insns, also describes the operands that need to be specified when this pattern is used. In particular, it gives a predicate for each operand.

A true operand, which needs to be specified in order to generate RTL from the pattern, should be described with a **match_operand** in its first occurrence in the RTL template. This enters information on the operand’s predicate into the tables that record such things. GCC uses the information to preload the operand into a register if that is required for valid RTL code. If the operand is referred to more than once, subsequent references should use **match_dup**.

The RTL template may also refer to internal “operands” which are temporary registers or labels used only within the sequence made by the **define_expand**. Internal operands are substituted into the RTL template with **match_dup**, never with **match_operand**. The values of the internal operands are not passed in as arguments by the compiler when it requests use of this pattern. Instead, they are computed within the pattern, in the preparation statements. These statements compute the values and store them into the appropriate elements of **operands** so that **match_dup** can find them.

There are two special macros defined for use in the preparation statements: **DONE** and **FAIL**. Use them with a following semicolon, as a statement.
DONE  Use the DONE macro to end RTL generation for the pattern. The only RTL insns resulting from the pattern on this occasion will be those already emitted by explicit calls to emit_insn within the preparation statements; the RTL template will not be generated.

FAIL  Make the pattern fail on this occasion. When a pattern fails, it means that the pattern was not truly available. The calling routines in the compiler will try other strategies for code generation using other patterns.

Failure is currently supported only for binary (addition, multiplication, shifting, etc.) and bit-field (extv, extzv, and insv) operations.

If the preparation falls through (invokes neither DONE nor FAIL), then the define_expand acts like a define_insn in that the RTL template is used to generate the insn.

The RTL template is not used for matching, only for generating the initial insn list. If the preparation statement always invokes DONE or FAIL, the RTL template may be reduced to a simple list of operands, such as this example:

```c
(define_expand "addsi3" 
 [(match_operand:SI 0 "register_operand" "")
   (match_operand:SI 1 "register_operand" "")
   (match_operand:SI 2 "register_operand" "]
 ""
)
{
  handle_add (operands[0], operands[1], operands[2]);
  DONE;
})
```

Here is an example, the definition of left-shift for the SPUR chip:

```c
(define_expand "ashlsi3" 
 [(set (match_operand:SI 0 "register_operand" "")
   (ashift:SI
     (match_operand:SI 1 "register_operand" "")
     (match_operand:SI 2 "nonmemory_operand" "")))]
 ""
)
{
  if (GET_CODE (operands[2]) != CONST_INT
    || (unsigned) INTVAL (operands[2]) > 3)
    FAIL;
}
```

This example uses define_expand so that it can generate an RTL insn for shifting when the shift-count is in the supported range of 0 to 3 but fail in other cases where machine insns aren’t available. When it fails, the compiler tries another strategy using different patterns (such as, a library call).

If the compiler were able to handle nontrivial condition-strings in patterns with names, then it would be possible to use a define_insn in that case. Here is another case (zero-extension on the 68000) which makes more use of the power of define_expand:

```c
(define_expand "zero_extendhisi2" 
 [(set (match_operand:SI 0 "general_operand" "")
   (const_int 0))
   (set (strict_low_part
     (subreg:HI
     (match_dup 0)
```
Here two RTL insns are generated, one to clear the entire output operand and the other to copy the input operand into its low half. This sequence is incorrect if the input operand refers to [the old value of] the output operand, so the preparation statement makes sure this isn’t so. The function make_safe_from copies the operands[1] into a temporary register if it refers to operands[0]. It does this by emitting another RTL insn.

Finally, a third example shows the use of an internal operand. Zero-extension on the SPUR chip is done by and-ing the result against a halfword mask. But this mask cannot be represented by a const_int because the constant value is too large to be legitimate on this machine. So it must be copied into a register with force_reg and then the register used in the and.

(define_expand "zero_extendhisi2"
[(set (match_operand:SI 0 "register_operand" ")
(and:SI (subreg:SI (match_operand:HI 1 "register_operand" "")
0)
(match_dup 2)))]

"operands[2]
= force_reg (SImode, GEN_INT (65535)); ")

Note: If the define_expand is used to serve a standard binary or unary arithmetic operation or a bit-field operation, then the last insn it generates must not be a code_label, barrier or note. It must be an insn, jump_insn or call_insn. If you don’t need a real insn at the end, emit an insn to copy the result of the operation into itself. Such an insn will generate no code, but it can avoid problems in the compiler.

17.16 Defining How to Split Instructions

There are two cases where you should specify how to split a pattern into multiple insns. On machines that have instructions requiring delay slots (see Section 17.19.8 [Delay Slots], page 476) or that have instructions whose output is not available for multiple cycles (see Section 17.19.9 [Processor pipeline description], page 477), the compiler phases that optimize these cases need to be able to move insns into one-instruction delay slots. However, some insns may generate more than one machine instruction. These insns cannot be placed into a delay slot.

Often you can rewrite the single insn as a list of individual insns, each corresponding to one machine instruction. The disadvantage of doing so is that it will cause the compilation to be slower and require more space. If the resulting insns are too complex, it may also suppress some optimizations. The compiler splits the insn if there is a reason to believe that it might improve instruction or delay slot scheduling.

The insn combiner phase also splits putative insns. If three insns are merged into one insn with a complex expression that cannot be matched by some define_insn pattern, the combiner phase attempts to split the complex pattern into two insns that are recognized. Usually it can break the complex pattern into two patterns by splitting out some subexpression. However, in some other cases, such as performing an addition of a large
constant in two insns on a RISC machine, the way to split the addition into two insns is machine-dependent.

The `define_split` definition tells the compiler how to split a complex insn into several simpler insns. It looks like this:

```c
(define_split
  [insn-pattern]
  "condition"
  [newinsn-pattern-1
   newinsn-pattern-2
   ...]
  "preparation-statements")
```

`insn-pattern` is a pattern that needs to be split and `condition` is the final condition to be tested, as in a `define_insn`. When an insn matching `insn-pattern` and satisfying `condition` is found, it is replaced in the insn list with the insns given by `newInsn-pattern-1`, `newInsn-pattern-2`, etc.

The `preparation-statements` are similar to those statements that are specified for `define_expand` (see Section 17.15 [Expander Definitions], page 454) and are executed before the new RTL is generated to prepare for the generated code or emit some insns whose pattern is not fixed. Unlike those in `define_expand`, however, these statements must not generate any new pseudo-registers. Once reload has completed, they also must not allocate any space in the stack frame.

There are two special macros defined for use in the preparation statements: `DONE` and `FAIL`. Use them with a following semicolon, as a statement.

**DONE** Use the `DONE` macro to end RTL generation for the splitter. The only RTL insns generated as replacement for the matched input insn will be those already emitted by explicit calls to `emit_insn` within the preparation statements; the replacement pattern is not used.

**FAIL** Make the `define_split` fail on this occasion. When a `define_split` fails, it means that the splitter was not truly available for the inputs it was given, and the input insn will not be split.

If the preparation falls through (invokes neither `DONE` nor `FAIL`), then the `define_split` uses the replacement template.

Patterns are matched against `insn-pattern` in two different circumstances. If an insn needs to be split for delay slot scheduling or insn scheduling, the insn is already known to be valid, which means that it must have been matched by some `define_insn` and, if `reload_completed` is nonzero, is known to satisfy the constraints of that `define_insn`. In that case, the new insn patterns must also be insns that are matched by some `define_insn` and, if `reload_completed` is nonzero, must also satisfy the constraints of those definitions.

As an example of this usage of `define_split`, consider the following example from `a29k.md`, which splits a `sign_extend` from HImode to SImode into a pair of shift insns:

```c
(define_split
  [(set (match_operand:SI 0 "gen_reg_operand" ")
   (sign_extend:SI (match_operand:HI 1 "gen_reg_operand" "")))]
  ""
  [(set (match_dup 0)
   (ashift:SI (match_dup 1)
```
When the combiner phase tries to split an insn pattern, it is always the case that the pattern is not matched by any define_insn. The combiner pass first tries to split a single set expression and then the same set expression inside a parallel, but followed by a clobber of a pseudo-reg to use as a scratch register. In these cases, the combiner expects exactly one or two new insn patterns to be generated. It will verify that these patterns match some define_insn definitions, so you need not do this test in the define_split (of course, there is no point in writing a define_split that will never produce insns that match).

Here is an example of this use of define_split, taken from 'rs6000.md':

```latex
(define_split
 [(set (match_operand:SI 0 "gen_reg_operand" 
    (plus:SI (match_operand:SI 1 "gen_reg_operand" 
    (match_operand:SI 2 "non_add_cint_operand" "")))))
   [(set (match_dup 0) (plus:SI (match_dup 1) (match_dup 3)))
    (set (match_dup 0) (plus:SI (match_dup 0) (match_dup 4)))
   ]
 ]

{ int low = INTVAL (operands[2]) & 0xffff;
  int high = (unsigned) INTVAL (operands[2]) >> 16;
  if (low & 0x8000)
    high++, low |= 0xffff0000;
  operands[3] = GEN_INT (high << 16);
  operands[4] = GEN_INT (low);
}
```

Here the predicate non_add_cint_operand matches any const_int that is not a valid operand of a single add insn. The add with the smaller displacement is written so that it can be substituted into the address of a subsequent operation.

An example that uses a scratch register, from the same file, generates an equality comparison of a register and a large constant:

```latex
(define_split
 [(set (match_operand:CC 0 "cc_reg_operand" 
    (compare:CC (match_operand:SI 1 "gen_reg_operand" "")
    (match_operand:SI 2 "non_short_cint_operand" "")))))
   [(set (match_dup 3) (xor:SI (match_dup 1) (match_dup 4)))
    (set (match_dup 0) (compare:CC (match_dup 3) (match_dup 5)))
   ]
 ]

{ /* Get the constant we are comparing against, C, and see what it looks like sign-extended to 16 bits. Then see what constant could be XOR'ed with C to get the sign-extended value. */
```
int c = INTVAL (operands[2]);
int sextc = (c << 16) >> 16;
int xorv = c ^ sextc;
operands[4] = GEN_INT (xorv);
operands[5] = GEN_INT (sextc);
}

To avoid confusion, don’t write a single define_split that accepts some insns that match some define_insn as well as some insns that don’t. Instead, write two separate define_split definitions, one for the insns that are valid and one for the insns that are not valid.

The splitter is allowed to split jump instructions into sequence of jumps or create new jumps in while splitting non-jump instructions. As the control flow graph and branch prediction information needs to be updated, several restriction apply.

Splitting of jump instruction into sequence that over by another jump instruction is always valid, as compiler expect identical behavior of new jump. When new sequence contains multiple jump instructions or new labels, more assistance is needed. Splitter is required to create only unconditional jumps, or simple conditional jump instructions. Additionally it must attach a REG_BR_PROB note to each conditional jump. A global variable split_branch_probability holds the probability of the original branch in case it was a simple conditional jump. −1 otherwise. To simplify recomputing of edge frequencies, the new sequence is required to have only forward jumps to the newly created labels.

For the common case where the pattern of a define_split exactly matches the pattern of a define_insn, use define_insn_and_split. It looks like this:

(define_insn_and_split
  [insn-pattern]
  "condition"
  "output-template"
  "split-condition"
  [new_insn-pattern-1
   new_insn-pattern-2
   ...]
  "preparation-statements"
  [insn-attributes])

insn-pattern, condition, output-template, and insn-attributes are used as in define_insn. The new_insn-pattern vector and the preparation-statements are used as in a define_split. The split-condition is also used as in define_split, with the additional behavior that if the condition starts with ‘&\&’, the condition used for the split will be the constructed as a logical “and” of the split condition with the insn condition. For example, from i386.md:
In this case, the actual split condition will be ‘TARGET_ZERO_EXTEND_WITH_AND && !optimize_size & reload_completed’.

The define_insn_and_split construction provides exactly the same functionality as two separate define_insn and define_split patterns. It exists for compactness, and as a maintenance tool to prevent having to ensure the two patterns’ templates match.

It is sometimes useful to have a define_insn_and_split that replaces specific operands of an instruction but leaves the rest of the instruction pattern unchanged. You can do this directly with a define_insn_and_split, but it requires a new-insn-pattern-1 that repeats most of the original insn-pattern. There is also the complication that an implicit parallel in insn-pattern must become an explicit parallel in new-insn-pattern-1, which is easy to overlook. A simpler alternative is to use define_insn_and_rewrite, which is a form of define_insn_and_split that automatically generates new-insn-pattern-1 by replacing each match_operand in insn-pattern with a corresponding match_dup, and each match_operator in the pattern with a corresponding match_op_dup. The arguments are otherwise identical to define_insn_and_split:

(define_insn_and_rewrite
  [insn-pattern]
  "condition"
  "split-condition"
  "preparation-statements"
  [insn-attributes])

The match_dups and match_op_dups in the new instruction pattern use any new operand values that the preparation-statements store in the operands array, as for a normal define_insn_and_split. preparation-statements can also emit additional instructions before the new instruction. They can even emit an entirely different sequence of instructions and use DONE to avoid emitting a new form of the original instruction.

The split in a define_insn_and_rewrite is only intended to apply to existing instructions that match insn-pattern. split-condition must therefore start with &&, so that the split condition applies on top of condition.

Here is an example from the AArch64 SVE port, in which operand 1 is known to be equivalent to an all-true constant and isn’t used by the output template:

(define_insn_and_rewrite "*while_ult<GPI:mode><PRED_ALL:mode>_cc"
  [(set (reg:CC CC_REGNUM)
    (compare:CC (unspec:SI [(match_operand:PRED_ALL 1)
                         (unspec:PRED_ALL
                           [(match_operand:GPI 2 "aarch64_reg_or_zero" "rZ")
                            (match_operand:GPI 3 "aarch64_reg_or_zero" "rZ")
                            UNSPEC_WHILE_LO)])
                         UNSPEC_PTEST_PTRUE)
    (const_int 0))]
  (set (match_operand:PRED_ALL 0 "register_operand" "=Upa")
    (unspec:PRED_ALL [(match_dup 2)
                      (match_dup 3)])
    UNSPEC_WHILE_LO)])
  "TARGET_SVE"
"whilelo\t%0.<PRED_ALL:Vetype>, %<w>2, %<w>3"

;; Force the compiler to drop the unused predicate operand, so that we
;; don't have an unnecessary PTRUE.
"&& !CONSTANT_P (operands[1])"
{
    operands[1] = CONSTM1_RTX (<MODE>mode);
}

The splitter in this case simply replaces operand 1 with the constant value that it is
known to have. The equivalent define_insn_and_split would be:

(define_insn_and_split "*while_ult<GPI:mode><PRED_ALL:mode>_cc"
[(set (reg:CC CC_REGNUM)
 (compare:CC
  (unspec:SI [(match_operand:PRED_ALL 1)
              (unspec:PRED_ALL
               [(match_operand:GPI 2 "aarch64_reg_or_zero" "rZ")
                (match_operand:GPI 3 "aarch64_reg_or_zero" "rZ")
                UNSPEC_WHILE_LO)])
             UNSPEC_PTEST_PTRUE)
  (const_int 0)]))
 (set (match_operand:PRED_ALL 0 "register_operand" "=Upa")
 (unspec:PRED_ALL [(match_dup 2)
              (match_dup 3)]
             UNSPEC_WHILE_LO))]

"TARGET_SVE"
"whilelo\t%0.<PRED_ALL:Vetype>, %<w>2, %<w>3"

;; Force the compiler to drop the unused predicate operand, so that we
;; don't have an unnecessary PTRUE.
"&& !CONSTANT_P (operands[1])"

[(parallel
 [(set (reg:CC CC_REGNUM)
  (compare:CC
   (unspec:SI [(match_dup 1)
              (unspec:PRED_ALL [(match_dup 2)
                (match_dup 3)]
             UNSPEC_WHILE_LO)])
   UNSPEC_PTEST_PTRUE)
  (const_int 0)]))
 (set (match_dup 0)
 (unspec:PRED_ALL [(match_dup 2)
              (match_dup 3)]
             UNSPEC_WHILE_LO))])]
{
    operands[1] = CONSTM1_RTX (<MODE>mode);
}

17.17 Including Patterns in Machine Descriptions.

The include pattern tells the compiler tools where to look for patterns that are in files
other than in the file ‘.md’. This is used only at build time and there is no preprocessing
allowed.

It looks like:

(include
 pathname)
For example:

(include "filestuff")

Where *pathname* is a string that specifies the location of the file, specifies the include file to be in `gcc/config/target/filestuff`. The directory `gcc/config/target` is regarded as the default directory.

Machine descriptions may be split up into smaller more manageable subsections and placed into subdirectories.

By specifying:

(include "BOGUS/filestuff")

the include file is specified to be in `gcc/config/target/BOGUS/filestuff`.

Specifying an absolute path for the include file such as;

(include "/u2/BOGUS/filestuff")

is permitted but is not encouraged.

### 17.17.1 RTL Generation Tool Options for Directory Search

The `-I dir` option specifies directories to search for machine descriptions. For example:

```
  genrecog -I /p1/abc/proc1 -I /p2/abcd/pro2 target.md
```

Add the directory *dir* to the head of the list of directories to be searched for header files. This can be used to override a system machine definition file, substituting your own version, since these directories are searched before the default machine description file directories. If you use more than one `-I` option, the directories are scanned in left-to-right order; the standard default directory come after.

### 17.18 Machine-Specific Peephole Optimizers

In addition to instruction patterns the `md` file may contain definitions of machine-specific peephole optimizations.

The combiner does not notice certain peephole optimizations when the data flow in the program does not suggest that it should try them. For example, sometimes two consecutive insns related in purpose can be combined even though the second one does not appear to use a register computed in the first one. A machine-specific peephole optimizer can detect such opportunities.

There are two forms of peephole definitions that may be used. The original *define_peephole* is run at assembly output time to match insns and substitute assembly text. Use of *define_peephole* is deprecated.

A newer *define_peephole2* matches insns and substitutes new insns. The *peephole2* pass is run after register allocation but before scheduling, which may result in much better code for targets that do scheduling.
17.18.1 RTL to Text Peephole Optimizers

A definition looks like this:

```
(define_peephole
  [insn-pattern-1
   insn-pattern-2
   ...]
  "condition"
  "template"
  "optional-instr-attributes")
```

The last string operand may be omitted if you are not using any machine-specific information in this machine description. If present, it must obey the same rules as in a `define_insn`.

In this skeleton, `insn-pattern-1` and so on are patterns to match consecutive insns. The optimization applies to a sequence of insns when `insn-pattern-1` matches the first one, `insn-pattern-2` matches the next, and so on.

Each of the insns matched by a peephole must also match a `define_insn`. Peepholes are checked only at the last stage just before code generation, and only optionally. Therefore, any insn which would match a peephole but no `define_insn` will cause a crash in code generation in an unoptimized compilation, or at various optimization stages.

The operands of the insns are matched with `match_operands`, `match_operator`, and `match_dup`, as usual. What is not usual is that the operand numbers apply to all the insn patterns in the definition. So, you can check for identical operands in two insns by using `match_operand` in one insn and `match_dup` in the other.

The operand constraints used in `match_operand` patterns do not have any direct effect on the applicability of the peephole, but they will be validated afterward, so make sure your constraints are general enough to apply whenever the peephole matches. If the peephole matches but the constraints are not satisfied, the compiler will crash.

It is safe to omit constraints in all the operands of the peephole; or you can write constraints which serve as a double-check on the criteria previously tested.

Once a sequence of insns matches the patterns, the `condition` is checked. This is a C expression which makes the final decision whether to perform the optimization (we do so if the expression is nonzero). If `condition` is omitted (in other words, the string is empty) then the optimization is applied to every sequence of insns that matches the patterns.

The defined peephole optimizations are applied after register allocation is complete. Therefore, the peephole definition can check which operands have ended up in which kinds of registers, just by looking at the operands.

The way to refer to the operands in `condition` is to write `operands[i]` for operand number `i` (as matched by `(match_operand i ...)`). Use the variable `insn` to refer to the last of the insns being matched; use `prev_active_insn` to find the preceding insns.

When optimizing computations with intermediate results, you can use `condition` to match only when the intermediate results are not used elsewhere. Use the C expression `dead_or_set_p (insn, op)`, where `insn` is the insn in which you expect the value to be used for the last time (from the value of `insn`, together with use of `prev_nonnote_insn`), and `op` is the intermediate value (from `operands[i]`).

Applying the optimization means replacing the sequence of insns with one new insn. The `template` controls ultimate output of assembler code for this combined insn. It works exactly
like the template of a `define_insn`. Operand numbers in this template are the same ones used in matching the original sequence of insns.

The result of a defined peephole optimizer does not need to match any of the insn patterns in the machine description; it does not even have an opportunity to match them. The peephole optimizer definition itself serves as the insn pattern to control how the insn is output.

Defined peephole optimizers are run as assembler code is being output, so the insns they produce are never combined or rearranged in any way.

Here is an example, taken from the 68000 machine description:

```c
(define_peephole
  [(set (reg:SI 15) (plus:SI (reg:SI 15) (const_int 4)))
   (set (match_operand:DF 0 "register_operand" "+f")
        (match_operand:DF 1 "register_operand" "ad"))]
  "FP_REG_P (operands[0]) && ! FP_REG_P (operands[1])"
  {rtx xoperands[2];
   xoperands[1] = gen_rtx_REG (SImode, REGNO (operands[1]) + 1);
   #ifdef MOTOROLA
   output_asm_insn ("move.l %1,(sp)", xoperands);
   output_asm_insn ("move.l %1,-(sp)", operands);
   return "fmove.d (sp)+,%0";
   #else
   output_asm_insn ("movel %1,sp@", xoperands);
   output_asm_insn ("movel %1,sp@-", operands);
   return "fmoved sp@+,%0";
   #endif
  })
```

The effect of this optimization is to change

```
  jbsr _foobar
  addql #4,sp
  movel d1,sp@
  movel d0,sp@-
  fmove dsp@+,fp0
```

into

```
  jbsr _foobar
  movel d1,sp@
  movel d0,sp@-
  fmove dsp@+,fp0
```

`insn-pattern-1` and so on look *almost* like the second operand of `define_insn`. There is one important difference: the second operand of `define_insn` consists of one or more RTX’s enclosed in square brackets. Usually, there is only one: then the same action can be written as an element of a `define_peephole`. But when there are multiple actions in a `define_insn`, they are implicitly enclosed in a `parallel`. Then you must explicitly write the `parallel`, and the square brackets within it, in the `define_peephole`. Thus, if an insn pattern looks like this,

```c
(define_insn "divmodsi4"
  [(set (match_operand:SI 0 "general_operand" "+d")
         (div:SI (match_operand:SI 1 "general_operand" "+0")
                 (match_operand:SI 2 "general_operand" "dmsK")))
   (set (match_operand:SI 3 "general_operand" "=d")
         (mod:SI (match_dup 1) (match_dup 2)))]
  "TARGET_68020"
```

...
"divs1%.l %2,%3:%0")

then the way to mention this insn in a peephole is as follows:

(define_peephole
[...
(parallel
  [(set (match_operand:SI 0 "general_operand" "+")
      (div:SI (match_operand:SI 1 "general_operand" "0")
               (match_operand:SI 2 "general_operand" "+")))
  (set (match_operand:SI 3 "general_operand" "+")
       (mod:SI (match_dup 1) (match_dup 2)))]
...]
...)

17.18.2 RTL to RTL Peephole Optimizers

The define_peephole2 definition tells the compiler how to substitute one sequence of
instructions for another sequence, what additional scratch registers may be needed and
what their lifetimes must be.

(define_peephole2
  [insn-pattern-1
   insn-pattern-2
   ...
   "condition"
   [new insn-pattern-1
    new insn-pattern-2
    ...
    "preparation-statements"]

The definition is almost identical to define_split (see Section 17.16 [Insn Splitting],
page 457) except that the pattern to match is not a single instruction, but a sequence of
instructions.

It is possible to request additional scratch registers for use in the output template. If
appropriate registers are not free, the pattern will simply not match.

Scratch registers are requested with a match_scratch pattern at the top level of the input
pattern. The allocated register (initially) will be dead at the point requested within the
original sequence. If the scratch is used at more than a single point, a match_dup pattern
at the top level of the input pattern marks the last position in the input sequence at which
the register must be available.

Here is an example from the IA-32 machine description:

(define_peephole2
  [(match_scratch:SI 2 "r")
   (parallel [(set (match_operand:SI 0 "register_operand" "+")
                   (match_operator:SI 3 "arith_or_logical_operator"
                   [(match_dup 0)
                    (match_operand:SI 1 "memory_operand" "+")]))
              (clobber (reg:CC 17))])
"! optimize_size && ! TARGET_READ_MODIFY"
[(set (match_dup 2) (match_dup 1))
 (parallel [(set (match_dup 0)
              (match_op_dup 3 [(match_dup 0) (match_dup 2)])
              (clobber (reg:CC 17)))]
"=")
This pattern tries to split a load from its use in the hopes that we'll be able to schedule around the memory load latency. It allocates a single SImode register of class GENERAL_REGS ("r") that needs to be live only at the point just before the arithmetic.

A real example requiring extended scratch lifetimes is harder to come by, so here's a silly made-up example:

```lisp
(define_peephole2
 [(match_scratch:SI 4 "r")
  (set (match_operand:SI 0 "=" "") (match_operand:SI 1 "=" ""))
  (set (match_operand:SI 2 "=" "") (match_dup 1))
  (match_dup 4)
  (set (match_operand:SI 3 "=" "") (match_dup 1)))]

"/* determine 1 does not overlap 0 and 2 */"
[(set (match_dup 4) (match_dup 1))
 (set (match_dup 0) (match_dup 4))
 (set (match_dup 2) (match_dup 4))
 (set (match_dup 3) (match_dup 4))]
"*/"
```

There are two special macros defined for use in the preparation statements: DONE and FAIL. Use them with a following semicolon, as a statement.

DONE Use the DONE macro to end RTL generation for the peephole. The only RTL insns generated as replacement for the matched input insn will be those already emitted by explicit calls to emit_insn within the preparation statements; the replacement pattern is not used.

FAIL Make the define_peephole2 fail on this occasion. When a define_peephole2 fails, it means that the replacement was not truly available for the particular inputs it was given. In that case, GCC may still apply a later define_peephole2 that also matches the given insn pattern. (Note that this is different from define_split, where FAIL prevents the input insn from being split at all.)

If the preparation falls through (invokes neither DONE nor FAIL), then the define_peephole2 uses the replacement template.

If we had not added the (match_dup 4) in the middle of the input sequence, it might have been the case that the register we chose at the beginning of the sequence is killed by the first or second set.

### 17.19 Instruction Attributes

In addition to describing the instruction supported by the target machine, the ‘md’ file also defines a group of attributes and a set of values for each. Every generated insn is assigned a value for each attribute. One possible attribute would be the effect that the insn has on the machine’s condition code.

#### 17.19.1 Defining Attributes and their Values

The define_attr expression is used to define each attribute required by the target machine. It looks like:

```lisp
(define_attr name list-of-values default)
```

name is a string specifying the name of the attribute being defined. Some attributes are used in a special way by the rest of the compiler. The enabled attribute can be
used to conditionally enable or disable insn alternatives (see Section 17.8.6 [Disable Insn Alternatives], page 399). The `predicable` attribute, together with a suitable `define_cond_exec` (see Section 17.20 [Conditional Execution], page 483), can be used to automatically generate conditional variants of instruction patterns. The `mnemonic` attribute can be used to check for the instruction mnemonic (see Section 17.19.7 [Mnemonic Attribute], page 475). The compiler internally uses the names `ce_enabled` and `nonce_enabled`, so they should not be used elsewhere as alternative names.

- `list-of-values` is either a string that specifies a comma-separated list of values that can be assigned to the attribute, or a null string to indicate that the attribute takes numeric values.

- `default` is an attribute expression that gives the value of this attribute for insns that match patterns whose definition does not include an explicit value for this attribute. See Section 17.19.4 [Attr Example], page 473, for more information on the handling of defaults. See Section 17.19.6 [Constant Attributes], page 475, for information on attributes that do not depend on any particular insn.

For each defined attribute, a number of definitions are written to the `insn-attr.h` file. For cases where an explicit set of values is specified for an attribute, the following are defined:

- A `#define` is written for the symbol `HAVE_ATTR_name`.
- An enumerated class is defined for `attr_name` with elements of the form `upper-name_upper-value` where the attribute name and value are first converted to uppercase.
- A function `get_attr_name` is defined that is passed an insn and returns the attribute value for that insn.

For example, if the following is present in the `md` file:

```c
(define_attr "type" "branch,fp,load,store,arith" ...)
```

the following lines will be written to the file `insn-attr.h`.

```c
#define HAVE_ATTR_type 1
enum attr_type {TYPE_BRANCH, TYPE_FP, TYPE_LOAD,
               TYPE_STORE, TYPE_ARITH};
extern enum attr_type get_attr_type ();
```

If the attribute takes numeric values, no `enum` type will be defined and the function to obtain the attribute's value will return `int`.

There are attributes which are tied to a specific meaning. These attributes are not free to use for other purposes:

- `length` The `length` attribute is used to calculate the length of emitted code chunks. This is especially important when verifying branch distances. See Section 17.19.5 [Insn Lengths], page 474.

- `enabled` The `enabled` attribute can be defined to prevent certain alternatives of an insn definition from being used during code generation. See Section 17.8.6 [Disable Insn Alternatives], page 399.

- `mnemonic` The `mnemonic` attribute can be defined to implement instruction specific checks in e.g. the pipeline description. See Section 17.19.7 [Mnemonic Attribute], page 475.
For each of these special attributes, the corresponding ‘HAVE_ATTR_name’ ‘#define’ is also written when the attribute is not defined; in that case, it is defined as ‘0’.

Another way of defining an attribute is to use:

```
(define_enum_attr "attr" "enum" default)
```

This works in just the same way as `define_attr`, except that the list of values is taken from a separate enumeration called `enum` (see [define_enum], page 488). This form allows you to use the same list of values for several attributes without having to repeat the list each time. For example:

```
(define_enum "processor" [
  model_a
  model_b
  ...
])
```

```
(define_enum_attr "arch" "processor"
  (const (symbol_ref "target_arch")))
```

defines the same attributes as:

```
(define_attr "arch" "model_a,model_b,..."
  (const (symbol_ref "target_arch")))
```

but without duplicating the processor list. The second example defines two separate C enums (`attr_arch` and `attr_tune`) whereas the first defines a single C enum (`processor`).

### 17.19.2 Attribute Expressions

RTL expressions used to define attributes use the codes described above plus a few specific to attribute definitions, to be discussed below. Attribute value expressions must have one of the following forms:

- **(const_int i)**
  The integer `i` specifies the value of a numeric attribute. `i` must be non-negative. The value of a numeric attribute can be specified either with a `const_int`, or as an integer represented as a string in `const_string`, `eq_attr` (see below), `attr`, `symbol_ref`, simple arithmetic expressions, and `set_attr` overrides on specific instructions (see Section 17.19.3 [Tagging Insns], page 472).

- **(const_string value)**
  The string `value` specifies a constant attribute value. If `value` is specified as ‘"*"’, it means that the default value of the attribute is to be used for the insn containing this expression. ‘"*"’ obviously cannot be used in the `default` expression of a `define_attr`

  If the attribute whose value is being specified is numeric, `value` must be a string containing a non-negative integer (normally `const_int` would be used in this case). Otherwise, it must contain one of the valid values for the attribute.

- **(if_then_else test true-value false-value)**
  `test` specifies an attribute test, whose format is defined below. The value of this expression is `true-value` if `test` is true, otherwise it is `false-value`. 
The first operand of this expression is a vector containing an even number of expressions and consisting of pairs of test and value expressions. The value of the cond expression is that of the value corresponding to the first true test expression. If none of the test expressions are true, the value of the cond expression is that of the default expression.

Test expressions can have one of the following forms:

(const_int i)
This test is true if i is nonzero and false otherwise.

(not test)
(ior test1 test2)
(and test1 test2)
These tests are true if the indicated logical function is true.

(match_operand:m n pred constraints)
This test is true if operand n of the insn whose attribute value is being determined has mode m (this part of the test is ignored if m is VOIDmode) and the function specified by the string pred returns a nonzero value when passed operand n and mode m (this part of the test is ignored if pred is the null string). The constraints operand is ignored and should be the null string.

(match_test c-expr)
The test is true if C expression c-expr is true. In non-constant attributes, c-expr has access to the following variables:

insn The rtl instruction under test.

which_alternative The define_insn alternative that insn matches. See Section 17.6 [Output Statement], page 356.

operands An array of insn’s rtl operands.

c-expr behaves like the condition in a C if statement, so there is no need to explicitly convert the expression into a boolean 0 or 1 value. For example, the following two tests are equivalent:

(match_test “x & 2”)
(match_test “(x & 2) != 0”)

(le arith1 arith2)
(leu arith1 arith2)
(lt arith1 arith2)
(ltu arith1 arith2)
(gt arith1 arith2)
(gtu arith1 arith2)
(ge arith1 arith2)
(geu arith1 arith2)
(ne arith1 arith2)
(eq arith1 arith2)
These tests are true if the indicated comparison of the two arithmetic expressions is true. Arithmetic expressions are formed with plus, minus, mult, div,
mod, abs, neg, and, ior, xor, not, ashift, lshiftrt, and ashiftrt expressions.

`const_int` and `symbol_ref` are always valid terms (see Section 17.19.5 [Insn Lengths], page 474, for additional forms). `symbol_ref` is a string denoting a C expression that yields an `int` when evaluated by the `get_attr_...` routine. It should normally be a global variable.

(eq_attr name value)

(name) is a string specifying the name of an attribute.

(value) is a string that is either a valid value for attribute name, a comma-separated list of values, or ‘!’ followed by a value or list. If value does not begin with a ‘!’, this test is true if the value of the name attribute of the current insn is in the list specified by value. If value begins with a ‘!’, this test is true if the attribute’s value is not in the specified list.

For example,

(eq_attr "type" "load,store")

is equivalent to

(ior (eq_attr "type" "load") (eq_attr "type" "store"))

If name specifies an attribute of ‘alternative’, it refers to the value of the compiler variable `which_alternative` (see Section 17.6 [Output Statement], page 356) and the values must be small integers. For example,

(eq_attr "alternative" "2,3")

is equivalent to

(ior (eq (symbol_ref "which_alternative") (const_int 2))
 (eq (symbol_ref "which_alternative") (const_int 3)))

Note that, for most attributes, an `eq_attr` test is simplified in cases where the value of the attribute being tested is known for all insns matching a particular pattern. This is by far the most common case.

(attr_flag name)

The value of an `attr_flag` expression is true if the flag specified by name is true for the insn currently being scheduled.

(name) is a string specifying one of a fixed set of flags to test. Test the flags forward and backward to determine the direction of a conditional branch.

This example describes a conditional branch delay slot which can be nullified for forward branches that are taken (annul-true) or for backward branches which are not taken (annul-false).

(define_delay (eq_attr "type" "cbranch")
 [(eq_attr "in_branch_delay" "true")
  (and (eq_attr "in_branch_delay" "true")
       (attr_flag "forward")
       (and (eq_attr "in_branch_delay" "true")
            (attr_flag "backward"))])

The `forward` and `backward` flags are false if the current insn being scheduled is not a conditional branch.

`attr_flag` is only used during delay slot scheduling and has no meaning to other passes of the compiler.
The value of another attribute is returned. This is most useful for numeric attributes, as `eq_attr` and `attr_flag` produce more efficient code for non-numeric attributes.

### 17.19.3 Assigning Attribute Values to Insns

The value assigned to an attribute of an insn is primarily determined by which pattern is matched by that insn (or which `define_peephole` generated it). Every `define_insn` and `define_peephole` can have an optional last argument to specify the values of attributes for matching insns. The value of any attribute not specified in a particular insn is set to the default value for that attribute, as specified in its `define_attr`. Extensive use of default values for attributes permits the specification of the values for only one or two attributes in the definition of most insn patterns, as seen in the example in the next section.

The optional last argument of `define_insn` and `define_peephole` is a vector of expressions, each of which defines the value for a single attribute. The most general way of assigning an attribute's value is to use a `set` expression whose first operand is an `attr` expression giving the name of the attribute being set. The second operand of the `set` is an attribute expression (see Section 17.19.2 [Expressions], page 469) giving the value of the attribute.

When the attribute value depends on the `alternative` attribute (i.e., which is the applicable alternative in the constraint of the insn), the `set_attr_alternative` expression can be used. It allows the specification of a vector of attribute expressions, one for each alternative.

When the generality of arbitrary attribute expressions is not required, the simpler `set_attr` expression can be used, which allows specifying a string giving either a single attribute value or a list of attribute values, one for each alternative.

The form of each of the above specifications is shown below. In each case, `name` is a string specifying the attribute to be set.

#### (attr name)

The value of another attribute is returned. This is most useful for numeric attributes, as `eq_attr` and `attr_flag` produce more efficient code for non-numeric attributes.

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When the attribute value depends on the ‘alternative’ attribute (i.e., which is the applicable alternative in the constraint of the insn), the `set_attr_alternative` expression can be used. It allows the specification of a vector of attribute expressions, one for each alternative.

When the generality of arbitrary attribute expressions is not required, the simpler `set_att` expression can be used, which allows specifying a string giving either a single attribute value or a list of attribute values, one for each alternative.

The form of each of the above specifications is shown below. In each case, `name` is a string specifying the attribute to be set.

#### (set_attr name value-string)

`value-string` is either a string giving the desired attribute value, or a string containing a comma-separated list giving the values for succeeding alternatives. The number of elements must match the number of alternatives in the constraint of the insn pattern.

Note that it may be useful to specify ‘*’ for some alternative, in which case the attribute will assume its default value for insns matching that alternative.

#### (set_attr_alternative name [value1 value2 ...])

Depending on the alternative of the insn, the value will be one of the specified values. This is a shorthand for using a `cond` with tests on the ‘alternative’ attribute.

#### (set (attr name) value)

The first operand of this `set` must be the special RTL expression `attr`, whose sole operand is a string giving the name of the attribute being set. `value` is the value of the attribute.

The following shows three different ways of representing the same attribute value specification:
(set_attr "type" "load,store,arith")

(set_attr_alternative "type"
  [(const_string "load") (const_string "store")
   (const_string "arith")])

(set (attr "type")
  (cond [(eq_attr "alternative" "1") (const_string "load")
         (eq_attr "alternative" "2") (const_string "store")
         (const_string "arith"))])

The define_asm_attributes expression provides a mechanism to specify the attributes assigned to insns produced from an asm statement. It has the form:

(define_asm_attributes [attr-sets])

where attr-sets is specified the same as for both the define_insn and the define_peephole expressions.

These values will typically be the “worst case” attribute values. For example, they might indicate that the condition code will be clobbered.

A specification for a length attribute is handled specially. The way to compute the length of an asm insn is to multiply the length specified in the expression define_asm_attributes by the number of machine instructions specified in the asm statement, determined by counting the number of semicolons and newlines in the string. Therefore, the value of the length attribute specified in a define_asm_attributes should be the maximum possible length of a single machine instruction.

17.19.4 Example of Attribute Specifications

The judicious use of defaulting is important in the efficient use of insn attributes. Typically, insns are divided into types and an attribute, customarily called type, is used to represent this value. This attribute is normally used only to define the default value for other attributes. An example will clarify this usage.

Assume we have a RISC machine with a condition code and in which only full-word operations are performed in registers. Let us assume that we can divide all insns into loads, stores, (integer) arithmetic operations, floating point operations, and branches.

Here we will concern ourselves with determining the effect of an insn on the condition code and will limit ourselves to the following possible effects: The condition code can be set unpredictably (clobbered), not be changed, be set to agree with the results of the operation, or only changed if the item previously set into the condition code has been modified.

Here is part of a sample ‘md’ file for such a machine:

(define_attr "type" "load,store,arith,fp,branch" (const_string "arith"))

(define_attr "cc" "clobber,unchanged,set,change0"
  (cond [(eq_attr "type" "load")
         (const_string "change0")
         (eq_attr "type" "store,branch")
         (const_string "unchanged")
         (eq_attr "type" "arith")
         (if_then_else (match_operand:SI 0 "" "")
                        (const_string "set")
                        (const_string "clobber"))]
       (const_string "clobber")))
(define_insn ""
  [(set (match_operand:SI 0 "general_operand" "=r,r,m")
       (match_operand:SI 1 "general_operand" "r,m,r"))]
   
   "" 
   
   "@
   move %0,%1
   load %0,%1
   store %0,%1"

  [(set_attr "type" "arith,load,store")])

Note that we assume in the above example that arithmetic operations performed on quantities smaller than a machine word clobber the condition code since they will set the condition code to a value corresponding to the full-word result.

### 17.19.5 Computing the Length of anInsn

For many machines, multiple types of branch instructions are provided, each for different length branch displacements. In most cases, the assembler will choose the correct instruction to use. However, when the assembler cannot do so, GCC can when a special attribute, the length attribute, is defined. This attribute must be defined to have numeric values by specifying a null string in its define_attr.

In the case of the length attribute, two additional forms of arithmetic terms are allowed in test expressions:

(match_dup n)

This refers to the address of operand n of the current insn, which must be a label_ref.

(pc)

For non-branch instructions and backward branch instructions, this refers to the address of the current insn. But for forward branch instructions, this refers to the address of the next insn, because the length of the current insn is to be computed.

For normal insns, the length will be determined by value of the length attribute. In the case of addr_vec and addr_diff_vec insn patterns, the length is computed as the number of vectors multiplied by the size of each vector.

Lengths are measured in addressable storage units (bytes).

Note that it is possible to call functions via the symbol_ref mechanism to compute the length of an insn. However, if you use this mechanism you must provide dummy clauses to express the maximum length without using the function call. You can see an example of this in the pa machine description for the call_symref pattern.

The following macros can be used to refine the length computation:

**ADJUST_INSN_LENGTH** (insn, length)

If defined, modifies the length assigned to instruction insn as a function of the context in which it is used. length is an lvalue that contains the initially computed length of the insn and should be updated with the correct length of the insn.

This macro will normally not be required. A case in which it is required is the ROMP. On this machine, the size of an addr_vec insn must be increased by two to compensate for the fact that alignment may be required.
The routine that returns \texttt{get_attr_length} (the value of the \texttt{length} attribute) can be used by the output routine to determine the form of the branch instruction to be written, as the example below illustrates.

As an example of the specification of variable-length branches, consider the IBM 360. If we adopt the convention that a register will be set to the starting address of a function, we can jump to labels within 4k of the start using a four-byte instruction. Otherwise, we need a six-byte sequence to load the address from memory and then branch to it.

On such a machine, a pattern for a branch instruction might be specified as follows:

\begin{verbatim}
(define_insn "jump"
  [(set (pc)
       (label_ref (match_operand 0 "" "")))]
  ""
  {return (get_attr_length (insn) == 4
      ? "b %l0" : "l r15,a(%l0); br r15");}

  [(set (attr "length")
      (if_then_else (lt (match_dup 0) (const_int 4096)) (const_int 4) (const_int 6)))]
\end{verbatim}

\subsection{17.19.6 Constant Attributes}
A special form of \texttt{define_attr}, where the expression for the default value is a \texttt{const} expression, indicates an attribute that is constant for a given run of the compiler. Constant attributes may be used to specify which variety of processor is used. For example,

\begin{verbatim}
(define_attr "cpu" "m88100,m88110,m88000"
  (const
   (cond [(symbol_ref "TARGET_88100") (const_string "m88100")
         (symbol_ref "TARGET_88110") (const_string "m88110")
         (const_string "m88000")])))

(define_attr "memory" "fast,slow"
  (const
   (if_then_else (symbol_ref "TARGET_FAST_MEM") (const_string "fast")
                (const_string "slow")))
\end{verbatim}

The routine generated for constant attributes has no parameters as it does not depend on any particular insn. RTL expressions used to define the value of a constant attribute may use the \texttt{symbol_ref} form, but may not use either the \texttt{match_operand} form or \texttt{eq_attr} forms involving insn attributes.

\subsection{17.19.7 Mnemonic Attribute}
The \texttt{mnemonic} attribute is a string type attribute holding the instruction mnemonic for an insn alternative. The attribute values will automatically be generated by the machine description parser if there is an attribute definition in the \texttt{md} file:

\begin{verbatim}
(define_attr "mnemonic" "unknown" (const_string "unknown"))
\end{verbatim}

The default value can be freely chosen as long as it does not collide with any of the instruction mnemonics. This value will be used whenever the machine description parser is not able to determine the mnemonic string. This might be the case for output templates containing more than a single instruction as in "\texttt{mvcle\t%0,%1,0;jo\t.-4}".
The **mnemonic** attribute set is not generated automatically if the instruction string is generated via C code.

An existing **mnemonic** attribute set in an insn definition will not be overridden by the md file parser. That way it is possible to manually set the instruction mnemonics for the cases where the md file parser fails to determine it automatically.

The **mnemonic** attribute is useful for dealing with instruction specific properties in the pipeline description without defining additional insn attributes.

```
(define_attr "ooo_expanded" ""
  (cond [[eq_attr "mnemonic" "dlr,dsgr,d,dsgf,stamp,dsgfr,dlgr"
         (const_int 1)]
         (const_int 0))
```

### 17.19.8 Delay Slot Scheduling

The insn attribute mechanism can be used to specify the requirements for delay slots, if any, on a target machine. An instruction is said to require a *delay slot* if some instructions that are physically after the instruction are executed as if they were located before it. Classic examples are branch and call instructions, which often execute the following instruction before the branch or call is performed.

On some machines, conditional branch instructions can optionally *annul* instructions in the delay slot. This means that the instruction will not be executed for certain branch outcomes. Both instructions that annul if the branch is true and instructions that annul if the branch is false are supported.

Delay slot scheduling differs from instruction scheduling in that determining whether an instruction needs a delay slot is dependent only on the type of instruction being generated, not on data flow between the instructions. See the next section for a discussion of data-dependent instruction scheduling.

The requirement of an insn needing one or more delay slots is indicated via the `define_delay` expression. It has the following form:

```
(define_delay test
  [delay-1 annul-true-1 annul-false-1
   delay-2 annul-true-2 annul-false-2
   ...
  ]
```

*test* is an attribute test that indicates whether this `define_delay` applies to a particular insn. If so, the number of required delay slots is determined by the length of the vector specified as the second argument. An insn placed in delay slot *n* must satisfy attribute test `delay-n`. *annul-true-n* is an attribute test that specifies which insns may be annulled if the branch is true. Similarly, *annul-false-n* specifies which insns in the delay slot may be annulled if the branch is false. If annulling is not supported for that delay slot, `(nil)` should be coded.

For example, in the common case where branch and call insns require a single delay slot, which may contain any insn other than a branch or call, the following would be placed in the 'md' file:

```
(define_delay (eq_attr "type" "branch,call")
  [[eq_attr "type" "!branch,call"] (nil) (nil)])
```

Multiple `define_delay` expressions may be specified. In this case, each such expression specifies different delay slot requirements and there must be no insn for which tests in two `define_delay` expressions are both true.
For example, if we have a machine that requires one delay slot for branches but two for calls, no delay slot can contain a branch or call insn, and any valid insn in the delay slot for the branch can be annulled if the branch is true, we might represent this as follows:

```
(define_delay (eq_attr "type" "branch")
    [(eq_attr "type" "!branch,call")
     (eq_attr "type" "!branch,call")
     (nil)])
```

```
(define_delay (eq_attr "type" "call")
    [(eq_attr "type" "!branch,call") (nil) (nil)
     (eq_attr "type" "!branch,call") (nil) (nil)])
```

17.19.9 Specifying processor pipeline description

To achieve better performance, most modern processors (super-pipelined, superscalar RISC, and VLIW processors) have many functional units on which several instructions can be executed simultaneously. An instruction starts execution if its issue conditions are satisfied. If not, the instruction is stalled until its conditions are satisfied. Such interlock (pipeline) delay causes interruption of the fetching of successor instructions (or demands nop instructions, e.g. for some MIPS processors).

There are two major kinds of interlock delays in modern processors. The first one is a data dependence delay determining instruction latency time. The instruction execution is not started until all source data have been evaluated by prior instructions (there are more complex cases when the instruction execution starts even when the data are not available but will be ready in given time after the instruction execution start). Taking the data dependence delays into account is simple. The data dependence (true, output, and anti-dependence) delay between two instructions is given by a constant. In most cases this approach is adequate. The second kind of interlock delays is a reservation delay. The reservation delay means that two instructions under execution will be in need of shared processors resources, i.e. buses, internal registers, and/or functional units, which are reserved for some time. Taking this kind of delay into account is complex especially for modern RISC processors.

The task of exploiting more processor parallelism is solved by an instruction scheduler. For a better solution to this problem, the instruction scheduler has to have an adequate description of the processor parallelism (or pipeline description). GCC machine descriptions describe processor parallelism and functional unit reservations for groups of instructions with the aid of regular expressions.

The GCC instruction scheduler uses a pipeline hazard recognizer to figure out the possibility of the instruction issue by the processor on a given simulated processor cycle. The pipeline hazard recognizer is automatically generated from the processor pipeline description. The pipeline hazard recognizer generated from the machine description is based on a deterministic finite state automaton (DFA): the instruction issue is possible if there is a transition from one automaton state to another one. This algorithm is very fast, and furthermore, its speed is not dependent on processor complexity.

\footnote{However, the size of the automaton depends on processor complexity. To limit this effect, machine descriptions can split orthogonal parts of the machine description among several automata: but then, since each of these must be stepped independently, this does cause a small decrease in the algorithm’s performance.}
The rest of this section describes the directives that constitute an automaton-based processor pipeline description. The order of these constructions within the machine description file is not important.

The following optional construction describes names of automata generated and used for the pipeline hazards recognition. Sometimes the generated finite state automaton used by the pipeline hazard recognizer is large. If we use more than one automaton and bind functional units to the automata, the total size of the automata is usually less than the size of the single automaton. If there is no one such construction, only one finite state automaton is generated.

\[\text{(define_automaton automata-names)}\]

\textit{automata-names} is a string giving names of the automata. The names are separated by commas. All the automata should have unique names. The automaton name is used in the constructions \textit{define_cpu_unit} and \textit{define_query_cpu_unit}.

Each processor functional unit used in the description of instruction reservations should be described by the following construction.

\[\text{(define_cpu_unit unit-names [automaton-name])}\]

\textit{unit-names} is a string giving the names of the functional units separated by commas. Don’t use name \textit{nothing}, it is reserved for other goals.

\textit{automaton-name} is a string giving the name of the automaton with which the unit is bound. The automaton should be described in construction \textit{define_automaton}. You should give \textit{automaton-name}, if there is a defined automaton.

The assignment of units to automata are constrained by the uses of the units in insn reservations. The most important constraint is: if a unit reservation is present on a particular cycle of an alternative for an insn reservation, then some unit from the same automaton must be present on the same cycle for the other alternatives of the insn reservation. The rest of the constraints are mentioned in the description of the subsequent constructions.

The following construction describes CPU functional units analogously to \textit{define_cpu_unit}. The reservation of such units can be queried for an automaton state. The instruction scheduler never queries reservation of functional units for given automaton state. So as a rule, you don’t need this construction. This construction could be used for future code generation goals (e.g. to generate VLIW insn templates).

\[\text{(define_query_cpu_unit unit-names [automaton-name])}\]

\textit{unit-names} is a string giving names of the functional units separated by commas.

\textit{automaton-name} is a string giving the name of the automaton with which the unit is bound.

The following construction is the major one to describe pipeline characteristics of an instruction.

\[\text{(define_insn_reservation insn-name default_latency condition regexp)}\]

\textit{default_latency} is a number giving latency time of the instruction. There is an important difference between the old description and the automaton based pipeline description. The latency time is used for all dependencies when we use the old description. In the automaton based pipeline description, the given latency time is only used for true dependencies. The cost of anti-dependencies is always zero and the cost of output dependencies is the
difference between latency times of the producing and consuming insns (if the difference is negative, the cost is considered to be zero). You can always change the default costs for any description by using the target hook \texttt{TARG}ET\_\texttt{SCHED\_ADJUST\_COST} (see Section 18.17 \textit{Scheduling}, page 601).

\textit{insn-name} is a string giving the internal name of the insn. The internal names are used in constructions \texttt{define\_bypass} and in the automaton description file generated for debugging. The internal name has nothing in common with the names in \texttt{define\_insn}. It is a good practice to use insn classes described in the processor manual.

\textit{condition} defines what RTL insns are described by this construction. You should remember that you will be in trouble if \textit{condition} for two or more different \texttt{define\_insn\_reservation} constructions is TRUE for an insn. In this case what reservation will be used for the insn is not defined. Such cases are not checked during generation of the pipeline hazards recognizer because in general recognizing that two conditions may have the same value is quite difficult (especially if the conditions contain \texttt{symbol\_ref}). It is also not checked during the pipeline hazard recognizer work because it would slow down the recognizer considerably.

\textit{regexp} is a string describing the reservation of the cpu's functional units by the instruction. The reservations are described by a regular expression according to the following syntax:

\begin{verbatim}
regexp = regexp ""," oneof
   | oneof
oneof = oneof "|" allof
   | allof
allof = allof "+" repeat
   | repeat
repeat = element "*" number
   | element

element = cpu_function_unit_name
   | reservation_name
   | result_name
   | "nothing"
   | "(" regexp ")" \\
\end{verbatim}

- ‘,’ is used for describing the start of the next cycle in the reservation.
- ‘|’ is used for describing a reservation described by the first regular expression or a reservation described by the second regular expression or etc.
- ‘+’ is used for describing a reservation described by the first regular expression and a reservation described by the second regular expression and etc.
- ‘*’ is used for convenience and simply means a sequence in which the regular expression are repeated \textit{number} times with cycle advancing (see ‘,’).
- ‘\texttt{cpu\_function\_unit\_name}’ denotes reservation of the named functional unit.
- ‘\texttt{reservation\_name}’ — see description of construction ‘\texttt{define\_reservation}’.
- ‘\texttt{nothing}’ denotes no unit reservations.
Sometimes unit reservations for different insns contain common parts. In such case, you can simplify the pipeline description by describing the common part by the following construction

\[
(\text{define\_reservation} \ reservation-name\ \text{regexp})
\]

\(reservation-name\) is a string giving name of \(\text{regexp}\). Functional unit names and reservation names are in the same name space. So the reservation names should be different from the functional unit names and cannot be the reserved name ‘nothing’.

The following construction is used to describe exceptions in the latency time for given instruction pair. This is so called bypasses.

\[
(\text{define\_bypass} \ number\ \text{out\_insn\_names} \ \text{in\_insn\_names}\ [\text{guard}])
\]

\(number\) defines when the result generated by the instructions given in string \(\text{out\_insn\_names}\) will be ready for the instructions given in string \(\text{in\_insn\_names}\). Each of these strings is a comma-separated list of filename-style globs and they refer to the names of \(\text{define\_insn\_reservations}\). For example:

\[
(\text{define\_bypass} \ 1\ "\text{cpu1\_load\_*},\ \text{cpu1\_store\_*}" \ "\text{cpu1\_load\_*})
\]

defines a bypass between instructions that start with ‘\text{cpu1\_load\_*}’ or ‘\text{cpu1\_store\_*}’ and those that start with ‘\text{cpu1\_load\_*}’.

\(guard\) is an optional string giving the name of a C function which defines an additional guard for the bypass. The function will get the two insns as parameters. If the function returns zero the bypass will be ignored for this case. The additional guard is necessary to recognize complicated bypasses, e.g. when the consumer is only an address of insn ‘\text{store}’ (not a stored value).

If there are more one bypass with the same output and input insns, the chosen bypass is the first bypass with a guard in description whose guard function returns nonzero. If there is no such bypass, then bypass without the guard function is chosen.

The following five constructions are usually used to describe VLIW processors, or more precisely, to describe a placement of small instructions into VLIW instruction slots. They can be used for RISC processors, too.

\[
(\text{exclusion\_set} \ unit\_names\ unit\_names)\\
(\text{presence\_set} \ unit\_names\ patterns)\\
(\text{final\_presence\_set} \ unit\_names\ patterns)\\
(\text{absence\_set} \ unit\_names\ patterns)\\
(\text{final\_absence\_set} \ unit\_names\ patterns)
\]

\(unit\_names\) is a string giving names of functional units separated by commas.

\(patterns\) is a string giving patterns of functional units separated by comma. Currently pattern is one unit or units separated by white-spaces.

The first construction (‘\text{exclusion\_set}’) means that each functional unit in the first string cannot be reserved simultaneously with a unit whose name is in the second string and vice versa. For example, the construction is useful for describing processors (e.g. some SPARC processors) with a fully pipelined floating point functional unit which can execute simultaneously only single floating point insns or only double floating point insns.

The second construction (‘\text{presence\_set}’) means that each functional unit in the first string cannot be reserved unless at least one of pattern of units whose names are in the second string is reserved. This is an asymmetric relation. For example, it is useful for
description that VLIW ‘slot1’ is reserved after ‘slot0’ reservation. We could describe it by the following construction

\[(\text{presence\_set} \text{ "slot1" } \text{ "slot0"})\]

Or ‘slot1’ is reserved only after ‘slot0’ and unit ‘b0’ reservation. In this case we could write

\[(\text{presence\_set} \text{ "slot1" } \text{ "slot0 b0"})\]

The third construction (‘final\_presence\_set’) is analogous to ‘presence\_set’. The difference between them is when checking is done. When an instruction is issued in given automaton state reflecting all current and planned unit reservations, the automaton state is changed. The first state is a source state, the second one is a result state. Checking for ‘presence\_set’ is done on the source state reservation, checking for ‘final\_presence\_set’ is done on the result reservation. This construction is useful to describe a reservation which is actually two subsequent reservations. For example, if we use

\[(\text{presence\_set} \text{ "slot1" } \text{ "slot0"})\]

the following insn will be never issued (because ‘slot1’ requires ‘slot0’ which is absent in the source state).

\[(\text{define\_reservation} \text{ "insn\_and\_nop" } \text{ "slot0 + slot1"})\]

but it can be issued if we use analogous ‘final\_presence\_set’.

The forth construction (‘absence\_set’) means that each functional unit in the first string can be reserved only if each pattern of units whose names are in the second string is not reserved. This is an asymmetric relation (actually ‘exclusion\_set’ is analogous to this one but it is symmetric). For example it might be useful in a VLIW description to say that ‘slot0’ cannot be reserved after either ‘slot1’ or ‘slot2’ have been reserved. This can be described as:

\[(\text{absence\_set} \text{ "slot0" } \text{ "slot1, slot2"})\]

Or ‘slot2’ cannot be reserved if ‘slot0’ and unit ‘b0’ are reserved or ‘slot1’ and unit ‘b1’ are reserved. In this case we could write

\[(\text{absence\_set} \text{ "slot2" } \text{ "slot0 b0, slot1 b1"})\]

All functional units mentioned in a set should belong to the same automaton.

The last construction (‘final\_absence\_set’) is analogous to ‘absence\_set’ but checking is done on the result (state) reservation. See comments for ‘final\_presence\_set’.

You can control the generator of the pipeline hazard recognizer with the following construction.

\[(\text{automata\_option} \text{ options})\]

‘options’ is a string giving options which affect the generated code. Currently there are the following options:

- ‘no-minimization’ makes no minimization of the automaton. This is only worth to do when we are debugging the description and need to look more accurately at reservations of states.
- ‘time’ means printing time statistics about the generation of automata.
- ‘stats’ means printing statistics about the generated automata such as the number of DFA states, NDFA states and arcs.
- ‘v’ means a generation of the file describing the result automata. The file has suffix ‘.dfa’ and can be used for the description verification and debugging.
• `w` means a generation of warning instead of error for non-critical errors.

• `no-comb-vect` prevents the automaton generator from generating two data structures and comparing them for space efficiency. Using a comb vector to represent transitions may be better, but it can be very expensive to construct. This option is useful if the build process spends an unacceptably long time in genautomata.

• `ndfa` makes nondeterministic finite state automata. This affects the treatment of operator ‘|’ in the regular expressions. The usual treatment of the operator is to try the first alternative and, if the reservation is not possible, the second alternative. The nondeterministic treatment means trying all alternatives, some of them may be rejected by reservations in the subsequent insns.

• `collapse-ndfa` modifies the behavior of the generator when producing an automaton. An additional state transition to collapse a nondeterministic NDFA state to a deterministic DFA state is generated. It can be triggered by passing `const0_rtx` to `state_transition`. In such an automaton, cycle advance transitions are available only for these collapsed states. This option is useful for ports that want to use the `ndfa` option, but also want to use `define_query_cpu_unit` to assign units to insns issued in a cycle.

• `progress` means output of a progress bar showing how many states were generated so far for automaton being processed. This is useful during debugging a DFA description. If you see too many generated states, you could interrupt the generator of the pipeline hazard recognizer and try to figure out a reason for generation of the huge automaton.

As an example, consider a superscalar RISC machine which can issue three insns (two integer insns and one floating point insn) on the cycle but can finish only two insns. To describe this, we define the following functional units.

```lisp
(define_cpu_unit "i0_pipeline, i1_pipeline, f_pipeline")
(define_cpu_unit "port0, port1")
```

All simple integer insns can be executed in any integer pipeline and their result is ready in two cycles. The simple integer insns are issued into the first pipeline unless it is reserved, otherwise they are issued into the second pipeline. Integer division and multiplication insns can be executed only in the second integer pipeline and their results are ready correspondingly in 9 and 4 cycles. The integer division is not pipelined, i.e. the subsequent integer division insn cannot be issued until the current division insn finished. Floating point insns are fully pipelined and their results are ready in 3 cycles. Where the result of a floating point insn is used by an integer insn, an additional delay of one cycle is incurred. To describe all of this we could specify

```lisp
(define_cpu_unit "div")
```

```lisp
(define_insn_reservation "simple" 2 (eq_attr "type" "int")
  "(i0_pipeline | i1_pipeline), (port0 | port1)"
)
```

```lisp
(define_insn_reservation "mult" 4 (eq_attr "type" "mult")
  "i1_pipeline, nothing*2, (port0 | port1)"
)
```

```lisp
(define_insn_reservation "div" 9 (eq_attr "type" "div")
  "i1_pipeline, div*7, div + (port0 | port1)"
)
```

```lisp
(define_insn_reservation "float" 3 (eq_attr "type" "float")
  "f_pipeline, nothing, (port0 | port1)"
)
```
(define_bypass 4 "float" "simple,mult,div")

To simplify the description we could describe the following reservation
(define_reservation "finish" "port0|port1")

and use it in all define_insn_reservation as in the following construction
(define_insn_reservation "simple" 2 (eq_attr "type" "int"
  "(i0_pipeline | i1_pipeline), finish")

17.20 Conditional Execution

A number of architectures provide for some form of conditional execution, or predication. The hallmark of this feature is the ability to nullify most of the instructions in the instruction set. When the instruction set is large and not entirely symmetric, it can be quite tedious to describe these forms directly in the `.md` file. An alternative is the define_cond_exec template.

(define_cond_exec
  [predicate-pattern]
  "condition"
  "output-template"
  "optional-inInsn-attribues")

`predicate-pattern` is the condition that must be true for the insn to be executed at runtime and should match a relational operator. One can use `match_operator` to match several relational operators at once. Any `match_operand` operands must have no more than one alternative.

`condition` is a C expression that must be true for the generated pattern to match.

`output-template` is a string similar to the define_insn output template (see Section 17.5 [Output Template], page 355), except that the '//' and '@' special cases do not apply. This is only useful if the assembly text for the predicate is a simple prefix to the main insn. In order to handle the general case, there is a global variable `current_insn_predicate` that will contain the entire predicate if the current insn is predicated, and will otherwise be `NULL`.

`optional-inInsn-attribues` is an optional vector of attributes that gets appended to the insn attributes of the produced cond_exec rtx. It can be used to add some distinguishing attribute to cond_exec rttxs produced that way. An example usage would be to use this attribute in conjunction with attributes on the main pattern to disable particular alternatives under certain conditions.

When define_cond_exec is used, an implicit reference to the predicable instruction attribute is made. See Section 17.19 [Insn Attributes], page 467. This attribute must be a boolean (i.e. have exactly two elements in its list-of-values), with the possible values being no and yes. The default and all uses in the insns must be a simple constant, not a complex expressions. It may, however, depend on the alternative, by using a comma-separated list of values. If that is the case, the port should also define an enabled attribute (see Section 17.8.6 [Disable Insn Alternatives], page 399), which should also allow only no and yes as its values.

For each define_insn for which the predicable attribute is true, a new define_insn pattern will be generated that matches a predicated version of the instruction. For example,

(define_insn "addsi"
  [(set (match_operand:SI 0 "register_operand" "r")
        (plus:SI (match_operand:SI 1 "register_operand" "r"))

((define_bypass 4 "float" "simple,mult,div")

To simplify the description we could describe the following reservation
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and use it in all define_insn_reservation as in the following construction
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        (plus:SI (match_operand:SI 1 "register_operand" "r"))

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To simplify the description we could describe the following reservation
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For each define_insn for which the predicable attribute is true, a new define_insn pattern will be generated that matches a predicated version of the instruction. For example,
(match_operand:SI 2 "register_operand" "r")))
"test2"
"add %2,%1,%0")

(define_cond_exec
[(ne (match_operand:CC 0 "register_operand" "c")
     (const_int 0))
"test2"
"(%0")

generates a new pattern

(define_insn ""
[(cond_exec
(ne (match_operand:CC 3 "register_operand" "c") (const_int 0))
(set (match_operand:SI 0 "register_operand" "r")
     (plus:SI (match_operand:SI 1 "register_operand" "r")
              (match_operand:SI 2 "register_operand" "r")))]]
"((test2) && (test1))"
"(%3) add %2,%1,%0")

17.21 RTL Templates Transformations

For some hardware architectures there are common cases when the RTL templates for the
instructions can be derived from the other RTL templates using simple transformations.
E.g., ‘i386.md’ contains an RTL template for the ordinary sub instruction—*subsi_1,
and for the sub instruction with subsequent zero-extension—*subsi_1_zext. Such cases
can be easily implemented by a single meta-template capable of generating a modified case
based on the initial one:

(define_subst ""
[((cond_exec
(ne (match_operand:CC 3 "register_operand" "c") (const_int 0))
(set (match_operand:SI 0 "register_operand" "r")
     (plus:SI (match_operand:SI 1 "register_operand" "r")
              (match_operand:SI 2 "register_operand" "r"))))]
"((test2) && (test1))"
"(%3) add %2,%1,%0")

input-template is a pattern describing the source RTL template, which will be transformed.

c_condition is a C expression that is conjunct with the condition from the input-template
to generate a condition to be used in the output-template.

output-template is a pattern that will be used in the resulting template.

define_subst mechanism is tightly coupled with the notion of the subst attribute (see
Section 17.23.4 [Subst Iterators], page 493). The use of define_subst is triggered by a
reference to a subst attribute in the transforming RTL template. This reference initiates
duplication of the source RTL template and substitution of the attributes with their values.
The source RTL template is left unchanged, while the copy is transformed by define-
subst. This transformation can fail in the case when the source RTL template is not
matched against the input-template of the define_subst. In such case the copy is deleted.

define_subst can be used only in define_insn and define_expand, it cannot be used
in other expressions (e.g. in define_insn_and_split).

17.21.1 define_subst Example

To illustrate how define_subst works, let us examine a simple template transformation.
Suppose there are two kinds of instructions: one that touches flags and the other that 
does not. The instructions of the second type could be generated with the following `define_ 
subst`:

```
(define_subst "add_clobber_subst"
  [(set (match_operand:SI 0 "== ==")  
     (match_operand:SI 1 "== =="))"
  [(set (match_dup 0)  
    (match_dup 1))  
    (clobber (reg:CC FLAGS_REG))])
```

This `define_subst` can be applied to any RTL pattern containing `set` of mode SI and 
generates a copy with clobber when it is applied.

Assume there is an RTL template for a `max` instruction to be used in `define_subst` 
mentioned above:

```
(define_insn "maxsi"
  [(set (match_operand:SI 0 "register_operand" "=r")  
    (max:SI  
      (match_operand:SI 1 "register_operand" "r")  
      (match_operand:SI 2 "register_operand" "r")))]  
"max\t{%2, %1, %0|%0, %1, %2}"
[...])
```

To mark the RTL template for `define_subst` application, subst-attributes are used. 
They should be declared in advance:

```
(define_subst_attr "add_clobber_name" "add_clobber_subst" 
  "_noclobber" "_clobber")
```

Here `add_clobber_name` is the attribute name, `add_clobber_subst` is the name of the 
corresponding `define_subst`, the third argument (`_noclobber`) is the attribute value that 
would be substituted into the unchanged version of the source RTL template, and the last 
argument (`_clobber`) is the value that would be substituted into the second, transformed, 
version of the RTL template.

Once the subst-attribute has been defined, it should be used in RTL templates which need 
to be processed by the `define_subst`. So, the original RTL template should be changed:

```
(define_insn "maxsi<add_clobber_name>"
  [(set (match_operand:SI 0 "register_operand" "=r")  
    (max:SI  
      (match_operand:SI 1 "register_operand" "r")  
      (match_operand:SI 2 "register_operand" "r")))]  
"max\t{%2, %1, %0|%0, %1, %2}"
[...])
```

The result of the `define_subst` usage would look like the following:

```
(define_insn "maxsi_noclobber"
  [(set (match_operand:SI 0 "register_operand" "=r")  
    (max:SI  
      (match_operand:SI 1 "register_operand" "r")  
      (match_operand:SI 2 "register_operand" "r")))]  
"max\t{%2, %1, %0|%0, %1, %2}"
[...])
```
```
(define_insn "maxsi_clobber"
  [(set (match_operand:SI 0 "register_operand" "=r")
```
```
17.21.2 Pattern Matching in define_subst

All expressions, allowed in define_insn or define_expand, are allowed in the input-template of define_subst, except match_par_dup, match_scratch, match_parallel. The meanings of expressions in the input-template were changed:

match_operand matches any expression (possibly, a subtree in RTL-template), if modes of the match_operand and this expression are the same, or mode of the match_operand is VOIDmode, or this expression is match_dup, match_op_dup. If the expression is match_operand too, and predicate of match_operand from the input pattern is not empty, then the predicates are compared. That can be used for more accurate filtering of accepted RTL-templates.

match_operator matches common operators (like plus, minus), unspec, unspec_volatile operators and match_operator from the original pattern if the modes match and match_operator from the input pattern has the same number of operands as the operator from the original pattern.

17.21.3 Generation of output template in define_subst

If all necessary checks for define_subst application pass, a new RTL-pattern, based on the output-template, is created to replace the old template. Like in input-patterns, meanings of some RTL expressions are changed when they are used in output-patterns of a define_subst. Thus, match_dup is used for copying the whole expression from the original pattern, which matched corresponding match_operand from the input pattern.

match_dup N is used in the output template to be replaced with the expression from the original pattern, which matched match_operand N from the input pattern. As a consequence, match_dup cannot be used to point to match_operands from the output pattern, it should always refer to a match_operand from the input pattern. If a match_dup N occurs more than once in the output template, its first occurrence is replaced with the expression from the original pattern, and the subsequent expressions are replaced with match_dup N, i.e., a reference to the first expression.

In the output template one can refer to the expressions from the original pattern and create new ones. For instance, some operands could be added by means of standard match_operand.

After replacing match_dup with some RTL-subtree from the original pattern, it could happen that several match_operands in the output pattern have the same indexes. It is unknown, how many and what indexes would be used in the expression which would replace match_dup, so such conflicts in indexes are inevitable. To overcome this issue, match_operands and match_operators, which were introduced into the output pattern, are renumerated when all match_dups are replaced.

Number of alternatives in match_operands introduced into the output template M could differ from the number of alternatives in the original pattern N, so in the resultant pat-
tern there would be $N \times M$ alternatives. Thus, constraints from the original pattern would be duplicated $N$ times, constraints from the output pattern would be duplicated $M$ times, producing all possible combinations.

### 17.22 Constant Definitions

Using literal constants inside instruction patterns reduces legibility and can be a maintenance problem.

To overcome this problem, you may use the `define_constants` expression. It contains a vector of name-value pairs. From that point on, wherever any of the names appears in the MD file, it is as if the corresponding value had been written instead. You may use `define_constants` multiple times; each appearance adds more constants to the table. It is an error to redefine a constant with a different value.

To come back to the a29k load multiple example, instead of

```lisp
(define_insn ""
  [(match_parallel 0 "load_multiple_operation"
    [(set (match_operand:SI 1 "gpc_reg_operand" ";r")
      (match_operand:SI 2 "memory_operand" "m"))
     (use (reg:SI 179))
     (clobber (reg:SI 179)))]
"
  "loadm 0,0,%1,%2")
```

You could write:

```lisp
(define_constants [ (R_BP 177) (R_FC 178) (R_CR 179) (R_Q 180) ]
(define_insn ""
  [(match_parallel 0 "load_multiple_operation"
    [(set (match_operand:SI 1 "gpc_reg_operand" ";r")
      (match_operand:SI 2 "memory_operand" "m"))
     (use (reg:SI R_CR))
     (clobber (reg:SI R_CR)))]
"
  "loadm 0,0,%1,%2")
```

The constants that are defined with a `define_constant` are also output in the insn-codes.h header file as `#defines`.

You can also use the machine description file to define enumerations. Like the constants defined by `define_constant`, these enumerations are visible to both the machine description file and the main C code.

The syntax is as follows:

```lisp
(define_c_enum "name" [ value0 value1 (value32 32) value33 ...
  valuesn ]
```
This definition causes the equivalent of the following C code to appear in `insn-constants.h`:

```c
enum name {
    value0 = 0,
    value1 = 1,
    value32 = 32,
    value33 = 33,
    ...
    valuenn = n
};
#define NUM cname _VALUES (n + 1)
```

where `cname` is the capitalized form of `name`. It also makes each `valuei` available in the machine description file, just as if it had been declared with:

```c
(define_constants [(valuei i)])
```

Each `valuei` is usually an upper-case identifier and usually begins with `cname`.

You can split the enumeration definition into as many statements as you like. The above example is directly equivalent to:

```c
(define_c_enum "name" [value0])
(define_c_enum "name" [value1])
...
(define_c_enum "name" [valuenn])
```

Splitting the enumeration helps to improve the modularity of each individual `.md` file. For example, if a port defines its synchronization instructions in a separate `sync.md` file, it is convenient to define all synchronization-specific enumeration values in `sync.md` rather than in the main `.md` file.

Some enumeration names have special significance to GCC:

**unspecv** If an enumeration called `unspecv` is defined, GCC will use it when printing out `unspec_volatile` expressions. For example:

```c
(define_c_enum "unspecv" [UNSPECV_BLOCKAGE])
```

causes GCC to print `(unspec_volatile ... 0)` as:

```c
(unspec_volatile ... UNSPECV_BLOCKAGE)
```

**unspec** If an enumeration called `unspec` is defined, GCC will use it when printing out `unspec` expressions. GCC will also use it when printing out `unspec_volatile` expressions unless an `unspecv` enumeration is also defined. You can therefore decide whether to keep separate enumerations for volatile and non-volatile expressions or whether to use the same enumeration for both.

Another way of defining an enumeration is to use `define_enum`:

```c
(define_enum "name" [
    value0
    value1
    ...
    valuenn])
```

This directive implies:
(define_c_enum "name" [  
cname_cvalue0  
cname_cvalue1  
...  
cname_cvaluen  ])

where cvaluei is the capitalized form of valuei. However, unlike define_c_enum, the enumerations defined by define_enum can be used in attribute specifications (see [define_enum_attr], page 469).

17.23 Iterators

Ports often need to define similar patterns for more than one machine mode or for more than one rtx code. GCC provides some simple iterator facilities to make this process easier.

17.23.1 Mode Iterators

Ports often need to define similar patterns for two or more different modes. For example:

- If a processor has hardware support for both single and double floating-point arithmetic, the SFmode patterns tend to be very similar to the DFmode ones.
- If a port uses SImode pointers in one configuration and DImode pointers in another, it will usually have very similar SImode and DImode patterns for manipulating pointers.

Mode iterators allow several patterns to be instantiated from one ‘.md’ file template. They can be used with any type of rtx-based construct, such as a define_insn, define_split, or define_peephole2.

17.23.1.1 Defining Mode Iterators

The syntax for defining a mode iterator is:

(define_mode_iterator name [(mode1 "cond1") ... (moden "condn")])

This allows subsequent ‘.md’ file constructs to use the mode suffix :name. Every construct that does so will be expanded n times, once with every use of :name replaced by :mode1, once with every use replaced by :mode2, and so on. In the expansion for a particular modei, every C condition will also require that condi be true.

For example:

(define_mode_iterator P [(SI "Pmode == SImode") (DI "Pmode == DImode")])

defines a new mode suffix :P. Every construct that uses :P will be expanded twice, once with every :P replaced by :SI and once with every :P replaced by :DI. The :SI version will only apply if Pmode == SImode and the :DI version will only apply if Pmode == DImode.

As with other ‘.md’ conditions, an empty string is treated as “always true”. (mode "") can also be abbreviated to mode. For example:

(define_mode_iterator GPR [SI (DI "TARGET_64BIT")])

means that the :DI expansion only applies if TARGET_64BIT but that the :SI expansion has no such constraint.

Iterators are applied in the order they are defined. This can be significant if two iterators are used in a construct that requires substitutions. See Section 17.23.1.2 [Substitutions], page 490.
17.23.1.2 Substitution in Mode Iterators

If an `.md` file construct uses mode iterators, each version of the construct will often need slightly different strings or modes. For example:

- When a `define_expand` defines several `addm3` patterns (see Section 17.9 [Standard Names], page 405), each expander will need to use the appropriate mode name for `m`.
- When a `define_insn` defines several instruction patterns, each instruction will often use a different assembler mnemonic.
- When a `define_insn` requires operands with different modes, using an iterator for one of the operand modes usually requires a specific mode for the other operand(s).

GCC supports such variations through a system of “mode attributes”. There are two standard attributes: `mode`, which is the name of the mode in lower case, and `MODE`, which is the same thing in upper case. You can define other attributes using:

```
(define_mode_attr name [[(mode1 "value1") ... (moden "valuen")]])
```

where `name` is the name of the attribute and `valuei` is the value associated with `modei`.

When GCC replaces some `:iterator` with `:mode`, it will scan each string and mode in the pattern for sequences of the form `<iterator:attr>`, where `attr` is the name of a mode attribute. If the attribute is defined for `mode`, the whole `<...>` sequence will be replaced by the appropriate attribute value.

For example, suppose an `.md` file has:

```
(define_mode_iterator P [(SI "Pmode == SImode") (DI "Pmode == DImode")])
(define_mode_attr load [(SI "lw") (DI "ld")])
```

If one of the patterns that uses :P contains the string `"<P:load>\t%0,%1"`, the SI version of that pattern will use `"lw\t%0,%1"` and the DI version will use `"ld\t%0,%1"`.

Here is an example of using an attribute for a mode:

```
(define_mode_iterator LONG [SI DI])
(define_mode_attr SHORT [(SI "HI") (DI "SI")])
(define_insn ...
   (sign_extend:LONG (match_operand:<LONG:SHORT> "register_operand" "=d")) ...
   (set_attr "type" "arith")
   (set_attr "mode" "<MODE>")))
```

This is exactly equivalent to:

```
(define_insn "sub<mode>3"
   [(set (match_operand:GPR 0 "register_operand" "=d")
     (minus:GPR (match_operand:GPR 1 "register_operand" "d")
       (match_operand:GPR 2 "register_operand" "d")))]
   "<d>subu\t%0,%1,%2"
   [(set_attr "type" "arith")
    (set_attr "mode" "<MODE>")])
```

17.23.1.3 Mode Iterator Examples

Here is an example from the MIPS port. It defines the following modes and attributes (among others):

```
(define_mode_iterator GPR [SI (DI "TARGET_64BIT")])
(define_mode_attr d [(SI ")") (DI "d")])
```

and uses the following template to define both subi3 and subdi3:

```
(define_insn sub<mode>3
   [(set (match_operand:GPR 0 "register_operand" "=d")
     (minus:GPR (match_operand:GPR 1 "register_operand" "d")
       (match_operand:GPR 2 "register_operand" "d")))]
   "<d>subu\t%0,%1,%2"
   [(set_attr "type" "arith")
    (set_attr "mode" "<MODE>")])
```
(define_insn "subsi3"
  [(set (match_operand:SI 0 "register_operand" "=d")
       (minus:SI (match_operand:SI 1 "register_operand" "d")
                 (match_operand:SI 2 "register_operand" "d")))
   ""
   "subu\t%0,%1,%2"
  [(set_attr "type" "arith")
   (set_attr "mode" "SI")])

(define_insn "subdi3"
  [(set (match_operand:DI 0 "register_operand" "=d")
       (minus:DI (match_operand:DI 1 "register_operand" "d")
                 (match_operand:DI 2 "register_operand" "d")))
   ""
   "dsubu\t%0,%1,%2"
  [(set_attr "type" "arith")
   (set_attr "mode" "DI")])

### 17.23.2 Code Iterators

Code iterators operate in a similar way to mode iterators. See Section 17.23.1 [Mode Iterators], page 489.

The construct:

```
(define_code_iterator name [(code1 "cond1") ... (coden "condn")])
```

defines a pseudo rtx code name that can be instantiated as codei if condition condi is true. Each codei must have the same rtx format. See Section 14.2 [RTL Classes], page 264.

As with mode iterators, each pattern that uses name will be expanded n times, once with all uses of name replaced by code1, once with all uses replaced by code2, and so on. See Section 17.23.1.1 [Defining Mode Iterators], page 489.

It is possible to define attributes for codes as well as for modes. There are two standard code attributes: code, the name of the code in lower case, and CODE, the name of the code in upper case. Other attributes are defined using:

```
(define_code_attr name [(code1 "value1") ... (coden "valuen")])
```

Instruction patterns can use code attributes as rtx codes, which can be useful if two sets of codes act in tandem. For example, the following define_insn defines two patterns, one calculating a signed absolute difference and another calculating an unsigned absolute difference:

```
(define_code_iterator any_max [smax umax])
(define_code_attr paired_min [[(smax "smin") (umax "umin")]])
(define_insn ...
  [(set (match_operand:SI 0 ...) (minus:SI (any_max:SI (match_operand:SI 1 ...) (match_operand:SI 2 ...)))
       (<paired_min>:SI (match_dup 1) (match_dup 2)))]
  ...)"n
```

The signed version of the instruction uses smax and smin while the unsigned version uses umax and umin. There are no versions that pair smax with umin or umax with smin.

Here’s an example of code iterators in action, taken from the MIPS port:

```
(define_code_iterator any_cond [unordered ordered unlt unge uneq ltgt unle ungt eq ne gt ge lt le gtu geu ltu leu])
```
(define_expand "b<code>"
  (set (pc)
    (if_then_else (any_cond:CC (cc0) (const_int 0))
      (label_ref (match_operand 0 ""))
      (pc)))
"
{
  gen_conditional_branch (operands, <CODE>);
  DONE;
})

This is equivalent to:

(define_expand "bunordered"
  (set (pc)
    (if_then_else (unordered:CC (cc0) (const_int 0))
      (label_ref (match_operand 0 ""))
      (pc)))
"
{
  gen_conditional_branch (operands, UNORDERED);
  DONE;
})

(define_expand "bordered"
  (set (pc)
    (if_then_else (ordered:CC (cc0) (const_int 0))
      (label_ref (match_operand 0 ""))
      (pc)))
"
{
  gen_conditional_branch (operands, ORDERED);
  DONE;
})

...

17.23.3 Int Iterators

Int iterators operate in a similar way to code iterators. See Section 17.23.2 [Code Iterators], page 491.

The construct:

(define_int_iterator name [(int1 "cond1") ... (intn "condn")])

defines a pseudo integer constant name that can be instantiated as inti if condition condi is true. Each int must have the same rtx format. See Section 14.2 [RTL Classes], page 264. Int iterators can appear in only those rtx fields that have 'i', 'n', 'w', or 'p' as the specifier. This means that each int has to be a constant defined using define_constant or define_c_enum.

As with mode and code iterators, each pattern that uses name will be expanded n times, once with all uses of name replaced by int1, once with all uses replaced by int2, and so on. See Section 17.23.1.1 [Defining Mode Iterators], page 489.

It is possible to define attributes for ints as well as for codes and modes. Attributes are defined using:
Here’s an example of int iterators in action, taken from the ARM port:

(define_int_iterator QABSNEG [UNSPEC_VQABS UNSPEC_VQNEG])

(define_int_attr absneg [(UNSPEC_VQABS "abs") (UNSPEC_VQNEG "neg")])

(define_insn "neon_vq<absneg><mode>
 [(set (match_operand:VDQIW 0 "s_register_operand" "+w")
 (unspec:VDQIW [(match_operand:VDQIW 1 "s_register_operand" "+w")
 (match_operand:SI 2 "immediate_operand" "+i")
 QABSNEG)])
 "TARGET_NEON"
 "vq<absneg>.<V_s_elem>	%<V_reg>0, %<V_reg>1"
 [(set_attr "type" "neon_vqneg_vqabs")])

This is equivalent to:

(define_insn "neon_vqabs<mode>
 [(set (match_operand:VDQIW 0 "s_register_operand" "+w")
 (unspec:VDQIW [(match_operand:VDQIW 1 "s_register_operand" "+w")
 (match_operand:SI 2 "immediate_operand" "+i")
 UNSPEC_VQABS)])
 "TARGET_NEON"
 "vqabs.<V_s_elem>	%<V_reg>0, %<V_reg>1"
 [(set_attr "type" "neon_vqneg_vqabs")])

(define_insn "neon_vqneg<mode>
 [(set (match_operand:VDQIW 0 "s_register_operand" "+w")
 (unspec:VDQIW [(match_operand:VDQIW 1 "s_register_operand" "+w")
 (match_operand:SI 2 "immediate_operand" "+i")
 UNSPEC_VQNEG)])
 "TARGET_NEON"
 "vqneg.<V_s_elem>	%<V_reg>0, %<V_reg>1"
 [(set_attr "type" "neon_vqneg_vqabs")])

### 17.23.4 Subst Iterators

Subst iterators are special type of iterators with the following restrictions: they could not be declared explicitly, they always have only two values, and they do not have explicit dedicated name. Subst-iterators are triggered only when corresponding subst-attribute is used in RTL-pattern.

Subst iterators transform templates in the following way: the templates are duplicated, the subst-attributes in these templates are replaced with the corresponding values, and a new attribute is implicitly added to the given define_insn/define_expand. The name of the added attribute matches the name of define_subst. Such attributes are declared implicitly, and it is not allowed to have a define_attr named as a define_subst.

Each subst iterator is linked to a define_subst. It is declared implicitly by the first appearance of the corresponding define_subst_attr, and it is not allowed to define it explicitly.

Declarations of subst-attributes have the following syntax:
(define_subst_attr "name"
  "subst-name"
  "no-subst-value"
  "subst-applied-value")

name is a string with which the given subst-attribute could be referred to.

subst-name shows which define_subst should be applied to an RTL-template if the
given subst-attribute is present in the RTL-template.

no-subst-value is a value with which subst-attribute would be replaced in the first copy
of the original RTL-template.

subst-applied-value is a value with which subst-attribute would be replaced in the second
copy of the original RTL-template.

17.23.5 Parameterized Names

Ports sometimes need to apply iterators using C++ code, in order to get the code or RTL pattern
for a specific instruction. For example, suppose we have the ‘neon_vq<absneg><mode>’
pattern given above:

(define_int_iterator QABSNEG [UNSPEC_VQABS UNSPEC_VQNEG])
(define_int_attr absneg [(UNSPEC_VQABS "abs") (UNSPEC_VQNEG "neg")] )
(define_insn "neon_vq<absneg><mode>"
  [(set (match_operand:VDQIW 0 "s_register_operand" "+w")
        (unspec:VDQIW [(match_operand:VDQIW 1 "s_register_operand"
                        "w")
                       (match_operand:SI 2 "immediate_operand" "+i")]
                      QABSNEG))]
  ...
)

A port might need to generate this pattern for a variable ‘QABSNEG’ value and a variable
‘VDQIW’ mode. There are two ways of doing this. The first is to build the rtx for the pattern
directly from C++ code; this is a valid technique and avoids any risk of combinatorial
explosion. The second is to prefix the instruction name with the special character ‘@’,
which tells GCC to generate the four additional functions below. In each case, name is the
name of the instruction without the leading ‘@’ character, without the ‘<...>’ placeholders,
and with any underscore before a ‘<...>’ placeholder removed if keeping it would lead to a
double or trailing underscore.

‘insn_code maybe_code_for_name (i1, i2, ...)’
See whether replacing the first ‘<...>’ placeholder with iterator value i1, the
second with iterator value i2, and so on, gives a valid instruction. Return its
code if so, otherwise return CODE_FOR_nothing.

‘insn_code code_for_name (i1, i2, ...)’
Same, but abort the compiler if the requested instruction does not exist.

‘rtx maybe_gen_name (i1, i2, ..., op0, op1, ...)’
Check for a valid instruction in the same way as maybe_code_for_name. If the
instruction exists, generate an instance of it using the operand values given by
op0, op1, and so on, otherwise return null.
Same, but abort the compiler if the requested instruction does not exist, or if the instruction generator invoked the FAIL macro.

For example, changing the pattern above to:

```lisp
(define_insn "@neon_vq<absneg><mode>"
  [(set (match_operand:VDQIW 0 "s_register_operand" "=w")
    (unspec:VDQIW [(match_operand:VDQIW 1 "s_register_operand" "w")
      (match_operand:SI 2 "immediate_operand" "i")]
      QABSNAG))]
  ...
)
```

would define the same patterns as before, but in addition would generate the four functions below:

```lisp
insn_code maybe_code_for_neon_vq (int, machine_mode);
insn_code code_for_neon_vq (int, machine_mode);
rtx maybe_gen_neon_vq (int, machine_mode, rtx, rtx, rtx);
rtx gen_neon_vq (int, machine_mode, rtx, rtx, rtx);
```

Calling ‘code_for_neon_vq (UNSPEC_VQABS, V8QIMode)’ would then give CODE_FOR_neon_vqabsv8qi.

It is possible to have multiple ‘@’ patterns with the same name and same types of iterator. For example:

```lisp
(define_insn "@some_arithmetic_op<mode>"
  [(set (match_operand:INTEGER_MODES 0 "register_operand") ...)]
  ...
)
```

```lisp
(define_insn "@some_arithmetic_op<mode>"
  [(set (match_operand:FLOAT_MODES 0 "register_operand") ...)]
  ...
)
```

would produce a single set of functions that handles both INTEGER_MODES and FLOAT_MODES.

It is also possible for these ‘@’ patterns to have different numbers of operands from each other. For example, patterns with a binary rtl code might take three operands (one output and two inputs) while patterns with a ternary rtl code might take four operands (one output and three inputs). This combination would produce separate ‘maybe_gen_name’ and ‘gen_name’ functions for each operand count, but it would still produce a single ‘maybe_code_for_name’ and a single ‘code_for_name’.
Chapter 18: Target Description Macros and Functions

18 Target Description Macros and Functions

In addition to the file `machine.md`, a machine description includes a C header file conventionally given the name `machine.h` and a C source file named `machine.c`. The header file defines numerous macros that convey the information about the target machine that does not fit into the scheme of the `.md` file. The file `tm.h` should be a link to `machine.h`. The header file `config.h` includes `tm.h` and most compiler source files include `config.h`. The source file defines a variable `targetm`, which is a structure containing pointers to functions and data relating to the target machine. `machine.c` should also contain their definitions, if they are not defined elsewhere in GCC, and other functions called through the macros defined in the `.h` file.

18.1 The Global targetm Variable

```
struct gcc_target targetm

The target `.c` file must define the global `targetm` variable which contains pointers to functions and data relating to the target machine. The variable is declared in `target.h`; `target-def.h` defines the macro `TARGET_INITIALIZER` which is used to initialize the variable, and macros for the default initializers for elements of the structure. The `.c` file should override those macros for which the default definition is inappropriate. For example:

```c
#include "target.h"
#include "target-def.h"

/*** Initialize the GCC target structure. */

#undef TARGET_COMP_TYPE_ATTRIBUTES
#define TARGET_COMP_TYPE_ATTRIBUTES machine_comp_type_attributes

struct gcc_target targetm = TARGET_INITIALIZER;
```

Where a macro should be defined in the `.c` file in this manner to form part of the `targetm` structure, it is documented below as a “Target Hook” with a prototype. Many macros will change in future from being defined in the `.h` file to being part of the `targetm` structure.

Similarly, there is a `targetcm` variable for hooks that are specific to front ends for C-family languages, documented as “C Target Hook”. This is declared in `c-family/c-target.h`, the initializer `TARGETCM_INITIALIZER` in `c-family/c-target-def.h`. If targets initialize `targetcm` themselves, they should set `target_has_targetcm=yes` in `config.gcc`; otherwise a default definition is used.

Similarly, there is a `targetm_common` variable for hooks that are shared between the compiler driver and the compilers proper, documented as “Common Target Hook”. This is declared in `common/common-target.h`, the initializer `TARGETM_COMMON_INITIALIZER` in `common/common-target-def.h`. If targets initialize `targetm_common` themselves, they should set `target_has_targetm_common=yes` in `config.gcc`; otherwise a default definition is used.

Similarly, there is a `targetdm` variable for hooks that are specific to the D language front end, documented as “D Target Hook”. This is declared in `d/d-target.h`, the initializer
TARGETDM_INITIALIZER in ‘d/d-target-def.h’. If targets initialize targetdm themselves, they should set target_has_targetdm=yes in ‘config.gcc’; otherwise a default definition is used.

18.2 Controlling the Compilation Driver, ‘gcc’

You can control the compilation driver.

**DRIVER_SELF_SPECS**

A list of specs for the driver itself. It should be a suitable initializer for an array of strings, with no surrounding braces.

The driver applies these specs to its own command line between loading default ‘specs’ files (but not command-line specified ones) and choosing the multilib directory or running any subcommands. It applies them in the order given, so each spec can depend on the options added by earlier ones. It is also possible to remove options using ‘%<option’ in the usual way.

This macro can be useful when a port has several interdependent target options. It provides a way of standardizing the command line so that the other specs are easier to write.

Do not define this macro if it does not need to do anything.

**OPTION_DEFAULT_SPECS**

A list of specs used to support configure-time default options (i.e. ‘--with’ options) in the driver. It should be a suitable initializer for an array of structures, each containing two strings, without the outermost pair of surrounding braces.

The first item in the pair is the name of the default. This must match the code in ‘config.gcc’ for the target. The second item is a spec to apply if a default with this name was specified. The string ‘%(VALUE)’ in the spec will be replaced by the value of the default everywhere it occurs.

The driver will apply these specs to its own command line between loading default ‘specs’ files and processing DRIVER_SELF_SPECS, using the same mechanism as DRIVER_SELF_SPECS.

Do not define this macro if it does not need to do anything.

**CPP_SPEC**

A C string constant that tells the GCC driver program options to pass to CPP. It can also specify how to translate options you give to GCC into options for GCC to pass to the CPP.

Do not define this macro if it does not need to do anything.

**CPLUSPLUS_CPP_SPEC**

This macro is just like CPP_SPEC, but is used for C++, rather than C. If you do not define this macro, then the value of CPP_SPEC (if any) will be used instead.

**CC1_SPEC**

A C string constant that tells the GCC driver program options to pass to cc1, cc1plus, f771, and the other language front ends. It can also specify how to translate options you give to GCC into options for GCC to pass to front ends.

Do not define this macro if it does not need to do anything.
CC1PLUS_SPEC
A C string constant that tells the GCC driver program options to pass to cc1plus. It can also specify how to translate options you give to GCC into options for GCC to pass to the cc1plus.
Do not define this macro if it does not need to do anything. Note that everything defined in CC1_SPEC is already passed to cc1plus so there is no need to duplicate the contents of CC1_SPEC in CC1PLUS_SPEC.

ASM_SPEC
A C string constant that tells the GCC driver program options to pass to the assembler. It can also specify how to translate options you give to GCC into options for GCC to pass to the assembler. See the file ‘sun3.h’ for an example of this.
Do not define this macro if it does not need to do anything.

ASM_FINAL_SPEC
A C string constant that tells the GCC driver program how to run any programs which cleanup after the normal assembler. Normally, this is not needed. See the file ‘mips.h’ for an example of this.
Do not define this macro if it does not need to do anything.

AS_NEEDS_DASH_FOR_PIPED_INPUT
Define this macro, with no value, if the driver should give the assembler an argument consisting of a single dash, ‘-’, to instruct it to read from its standard input (which will be a pipe connected to the output of the compiler proper). This argument is given after any ‘-o’ option specifying the name of the output file.
If you do not define this macro, the assembler is assumed to read its standard input if given no non-option arguments. If your assembler cannot read standard input at all, use a ‘%{pipe:%e}’ construct; see ‘mips.h’ for instance.

LINK_SPEC
A C string constant that tells the GCC driver program options to pass to the linker. It can also specify how to translate options you give to GCC into options for GCC to pass to the linker.
Do not define this macro if it does not need to do anything.

LIB_SPEC
Another C string constant used much like LINK_SPEC. The difference between the two is that LIB_SPEC is used at the end of the command given to the linker.
If this macro is not defined, a default is provided that loads the standard C library from the usual place. See ‘gcc.c’.

LIBGCC_SPEC
Another C string constant that tells the GCC driver program how and when to place a reference to ‘libgcc.a’ into the linker command line. This constant is placed both before and after the value of LIB_SPEC.
If this macro is not defined, the GCC driver provides a default that passes the string ‘-lgcc’ to the linker.
REAL_LIBGCC_SPEC  [Macro]
By default, if ENABLE_SHARED_LIBGCC is defined, the LIBGCC_SPEC is not directly used by the driver program but is instead modified to refer to different versions of ‘libgcc.a’ depending on the values of the command line flags ‘-static’, ‘-shared’, ‘-static-libgcc’, and ‘-shared-libgcc’. On targets where these modifications are inappropriate, define REAL_LIBGCC_SPEC instead. REAL_LIBGCC_SPEC tells the driver how to place a reference to ‘libgcc’ on the link command line, but, unlike LIBGCC_SPEC, it is used unmodified.

USE_LD_AS_NEEDED  [Macro]
A macro that controls the modifications to LIBGCC_SPEC mentioned in REAL_LIBGCC_SPEC. If nonzero, a spec will be generated that uses ‘--as-needed’ or equivalent options and the shared ‘libgcc’ in place of the static exception handler library, when linking without any of -static, -static-libgcc, or -shared-libgcc.

LINK_EH_SPEC  [Macro]
If defined, this C string constant is added to LINK_SPEC. When USE_LD_AS_NEEDED is zero or undefined, it also affects the modifications to LIBGCC_SPEC mentioned in REAL_LIBGCC_SPEC.

STARTFILE_SPEC  [Macro]
Another C string constant used much like LINK_SPEC. The difference between the two is that STARTFILE_SPEC is used at the very beginning of the command given to the linker.

If this macro is not defined, a default is provided that loads the standard C startup file from the usual place. See ‘gcc.c’.

ENDFILE_SPEC  [Macro]
Another C string constant used much like LINK_SPEC. The difference between the two is that ENDFILE_SPEC is used at the very end of the command given to the linker.

Do not define this macro if it does not need to do anything.

THREAD_MODEL_SPEC  [Macro]
GCC -v will print the thread model GCC was configured to use. However, this doesn’t work on platforms that are multilibbed on thread models, such as AIX 4.3. On such platforms, define THREAD_MODEL_SPEC such that it evaluates to a string without blanks that names one of the recognized thread models. %*, the default value of this macro, will expand to the value of thread_file set in ‘config.gcc’.

SYSROOT_SUFFIX_SPEC  [Macro]
Define this macro to add a suffix to the target sysroot when GCC is configured with a sysroot. This will cause GCC to search for usr/lib, et al, within sysroot+suffix.

SYSROOT_HEADERS_SUFFIX_SPEC  [Macro]
Define this macro to add a headers_suffix to the target sysroot when GCC is configured with a sysroot. This will cause GCC to pass the updated sysroot+headers_suffix to CPP, causing it to search for usr/include, et al, within sysroot+headers_suffix.
EXTRA_SPECS

[Macro]
Define this macro to provide additional specifications to put in the ‘specs’ file that
can be used in various specifications like CC1_SPEC.
The definition should be an initializer for an array of structures, containing a string
constant, that defines the specification name, and a string constant that provides the
specification.
Do not define this macro if it does not need to do anything.
EXTRA_SPECS is useful when an architecture contains several related targets, which
have various ..._SPECS which are similar to each other, and the maintainer would
like one central place to keep these definitions.
For example, the PowerPC System V.4 targets use EXTRA_SPECS to define either
_CALL_SYSV when the System V calling sequence is used or _CALL_AIX when the older
AIX-based calling sequence is used.
The ‘config/rs6000/rs6000.h’ target file defines:
#define EXTRA_SPECS
{ "cpp_sysv_default", CPP_SYSV_DEFAULT },
#define CPP_SYSV_DEFAULT ""
The ‘config/rs6000/sysv.h’ target file defines:
#undef CPP_SPEC
#define CPP_SPEC \"%{posix: -D_POSIX_SOURCE } \%
{scall-sysv: -D_CALL_SYSV } \%
{!mcall-sysv: %{cpp_sysv_default} } \%
{msoft-float: -D_SOFT_FLOAT} %{mcpu=403: -D_SOFT_FLOAT}"\n#undef CPP_SYSV_DEFAULT
#define CPP_SYSV_DEFAULT "-D_CALL_SYSV"
while the ‘config/rs6000/eabiaix.h’ target file defines CPP_SYSV_DEFAULT as:
#undef CPP_SYSV_DEFAULT
#define CPP_SYSV_DEFAULT "-D_CALL_AIX"

LINK_LIBGCC_SPECIAL_1

[Macro]
Define this macro if the driver program should find the library ‘libgcc.a’. If you do
not define this macro, the driver program will pass the argument ‘-lgcc’ to tell the
linker to do the search.

LINK_GCC_C_SEQUENCE_SPEC

[Macro]
The sequence in which libgcc and libc are specified to the linker. By default this is
%G %L %G.

POST_LINK_SPEC

[Macro]
Define this macro to add additional steps to be executed after linker. The default
value of this macro is empty string.

LINK_COMMAND_SPEC

[Macro]
A C string constant giving the complete command line need to execute the linker.
When you do this, you will need to update your port each time a change is made to
the link command line within ‘gcc.c’. Therefore, define this macro only if you need
to completely redefine the command line for invoking the linker and there is no other way to accomplish the effect you need. Overriding this macro may be avoidable by overriding \texttt{LINK\_GCC\_C\_SEQUENCE\_SPEC} instead.

\texttt{bool TARGET\_ALWAYS\_STRIP\_DOTDOT} \hspace{1em} [Common Target Hook]
True if ‘..’ components should always be removed from directory names computed relative to GCC’s internal directories, false (default) if such components should be preserved and directory names containing them passed to other tools such as the linker.

\texttt{MULTILIB\_DEFAULTS} \hspace{1em} [Macro]
Define this macro as a C expression for the initializer of an array of string to tell the driver program which options are defaults for this target and thus do not need to be handled specially when using \texttt{MULTILIB\_OPTIONS}.

Do not define this macro if \texttt{MULTILIB\_OPTIONS} is not defined in the target makefile fragment or if none of the options listed in \texttt{MULTILIB\_OPTIONS} are set by default. See Section 20.1 [Target Fragment], page 687.

\texttt{RELATIVE\_PREFIX\_NOT\_LINKDIR} \hspace{1em} [Macro]
Define this macro to tell \texttt{gcc} that it should only translate a ‘-B’ prefix into a ‘-L’ linker option if the prefix indicates an absolute file name.

\texttt{MD\_EXEC\_PREFIX} \hspace{1em} [Macro]
If defined, this macro is an additional prefix to try after \texttt{STANDARD\_EXEC\_PREFIX}. \texttt{MD\_EXEC\_PREFIX} is not searched when the compiler is built as a cross compiler. If you define \texttt{MD\_EXEC\_PREFIX}, then be sure to add it to the list of directories used to find the assembler in ‘\texttt{configure.ac}’.

\texttt{STANDARD\_STARTFILE\_PREFIX} \hspace{1em} [Macro]
Define this macro as a C string constant if you wish to override the standard choice of \texttt{libdir} as the default prefix to try when searching for startup files such as ‘\texttt{crt0.o}’. \texttt{STANDARD\_STARTFILE\_PREFIX} is not searched when the compiler is built as a cross compiler.

\texttt{STANDARD\_STARTFILE\_PREFIX\_1} \hspace{1em} [Macro]
Define this macro as a C string constant if you wish to override the standard choice of /\texttt{lib} as a prefix to try after the default prefix when searching for startup files such as ‘\texttt{crt0.o}’. \texttt{STANDARD\_STARTFILE\_PREFIX\_1} is not searched when the compiler is built as a cross compiler.

\texttt{STANDARD\_STARTFILE\_PREFIX\_2} \hspace{1em} [Macro]
Define this macro as a C string constant if you wish to override the standard choice of /\texttt{lib} as yet another prefix to try after the default prefix when searching for startup files such as ‘\texttt{crt0.o}’. \texttt{STANDARD\_STARTFILE\_PREFIX\_2} is not searched when the compiler is built as a cross compiler.

\texttt{MD\_STARTFILE\_PREFIX} \hspace{1em} [Macro]
If defined, this macro supplies an additional prefix to try after the standard prefixes. \texttt{MD\_EXEC\_PREFIX} is not searched when the compiler is built as a cross compiler.
MD_STARTFILE_PREFIX_1  [Macro]
If defined, this macro supplies yet another prefix to try after the standard prefixes.
It is not searched when the compiler is built as a cross compiler.

INIT_ENVIRONMENT  [Macro]
Define this macro as a C string constant if you wish to set environment variables for
programs called by the driver, such as the assembler and loader. The driver passes
the value of this macro to putenv to initialize the necessary environment variables.

LOCAL_INCLUDE_DIR  [Macro]
Define this macro as a C string constant if you wish to override the standard choice
of '/usr/local/include' as the default prefix to try when searching for local
header files. LOCAL_INCLUDE_DIR comes before NATIVE_SYSTEM_HEADER_DIR (set in
'config.gcc', normally '/usr/include') in the search order.
Cross compilers do not search either '/usr/local/include' or its replacement.

NATIVE_SYSTEM_HEADER_COMPONENT  [Macro]
The “component” corresponding to NATIVE_SYSTEM_HEADER_DIR. See INCLUDE_DEFAULTS,
below, for the description of components. If you do not define this macro,
no component is used.

INCLUDE_DEFAULTS  [Macro]
Define this macro if you wish to override the entire default search path for include
files. For a native compiler, the default search path usually consists of GCC_INCLUDE_DIR,
LOCAL_INCLUDE_DIR, GPLPLUS_INCLUDE_DIR, and NATIVE_SYSTEM_HEADER_DIR. In addition,
GPLPLUS_INCLUDE_DIR and GCC_INCLUDE_DIR are defined automatically by 'Makefile', and specify private search areas for GCC. The directory
GPLPLUS_INCLUDE_DIR is used only for C++ programs.

The definition should be an initializer for an array of structures. Each array element
should have four elements: the directory name (a string constant), the component
name (also a string constant), a flag for C++-only directories, and a flag showing that
the includes in the directory don’t need to be wrapped in extern ‘C’ when compiling
C++. Mark the end of the array with a null element.

The component name denotes what GNU package the include file is part of, if any,
in all uppercase letters. For example, it might be ‘GCC’ or ‘BINUTILS’. If the package
is part of a vendor-supplied operating system, code the component name as ‘0’.

For example, here is the definition used for VAX/VMS:

```
#define INCLUDE_DEFAULTS \
{  
  { "GNU_GXX_INCLUDE:"", "G++", 1, 1}, \n  { "GNU_CC_INCLUDE:"", "GCC", 0, 0}, \n  { "SYS$SYSROOT:[SYSLIB.]", 0, 0, 0}, \n  { ".", 0, 0, 0}, \n  { 0, 0, 0, 0} \n}
```

Here is the order of prefixes tried for exec files:
1. Any prefixes specified by the user with ‘-B’.
2. The environment variable `GCC_EXEC_PREFIX` or, if `GCC_EXEC_PREFIX` is not set and the compiler has not been installed in the configure-time prefix, the location in which the compiler has actually been installed.

3. The directories specified by the environment variable `COMPILER_PATH`.

4. The macro `STANDARD_EXEC_PREFIX`, if the compiler has been installed in the configured-time prefix.

5. The location ‘/usr/libexec/gcc/’, but only if this is a native compiler.

6. The location ‘/usr/lib/gcc/’, but only if this is a native compiler.

7. The macro `MD_EXEC_PREFIX`, if defined, but only if this is a native compiler.

Here is the order of prefixes tried for startfiles:

1. Any prefixes specified by the user with ‘-B’.

2. The environment variable `GCC_EXEC_PREFIX` or its automatically determined value based on the installed toolchain location.

3. The directories specified by the environment variable `LIBRARY_PATH` (or port-specific name; native only, cross compilers do not use this).

4. The macro `STANDARD_EXEC_PREFIX`, but only if the toolchain is installed in the configured prefix or this is a native compiler.

5. The location ‘/usr/libexec/gcc/’, but only if this is a native compiler.

6. The macro `MD_EXEC_PREFIX`, if defined, but only if this is a native compiler.

7. The macro `MD_STARTFILE_PREFIX`, if defined, but only if this is a native compiler, or we have a target system root.

8. The macro `MD_STARTFILE_PREFIX_1`, if defined, but only if this is a native compiler, or we have a target system root.

9. The macro `STANDARD_STARTFILE_PREFIX`, with any sysroot modifications. If this path is relative it will be prefixed by `GCC_EXEC_PREFIX` and the machine suffix or `STANDARD_EXEC_PREFIX` and the machine suffix.

10. The macro `STANDARD_STARTFILE_PREFIX_1`, but only if this is a native compiler, or we have a target system root. The default for this macro is ‘/lib/’.

11. The macro `STANDARD_STARTFILE_PREFIX_2`, but only if this is a native compiler, or we have a target system root. The default for this macro is ‘/usr/lib/’.

### 18.3 Run-time Target Specification

Here are run-time target specifications.

**TARGET_CPU_CPP_BUILTINS ()**

This function-like macro expands to a block of code that defines built-in preprocessor macros and assertions for the target CPU, using the functions `builtin_define`, `builtin_define_std` and `builtin_assert`. When the front end calls this macro it provides a trailing semicolon, and since it has finished command line option processing your code can use those results freely.

`builtin_assert` takes a string in the form you pass to the command-line option ‘-A’, such as `cpu=mips`, and creates the assertion. `builtin_define` takes a string in the form accepted by option ‘-D’ and unconditionally defines the macro.
builtin_define_std takes a string representing the name of an object-like macro. If it doesn’t lie in the user’s namespace, builtin_define_std defines it unconditionally. Otherwise, it defines a version with two leading underscores, and another version with two leading and trailing underscores, and defines the original only if an ISO standard was not requested on the command line. For example, passing unix defines __unix, __unix__ and possibly unix; passing _mips defines __mips, __mips__ and possibly _mips, and passing _ABI64 defines only _ABI64.

You can also test for the C dialect being compiled. The variable c_language is set to one of clk_c, clk_cplusplus or clk_objective_c. Note that if we are preprocessing assembler, this variable will be clk_c but the function-like macro preprocessing_asm_p() will return true, so you might want to check for that first. If you need to check for strict ANSI, the variable flag_iso can be used. The function-like macro preprocessing_trad_p() can be used to check for traditional preprocessing.

TARGET_OS_CPP_BUILTINS ()  
[Macro]  
Similarly to TARGET_CPU_CPP_BUILTINS but this macro is optional and is used for the target operating system instead.

TARGET_OBJFMT_CPP_BUILTINS ()  
[Macro]  
Similarly to TARGET_CPU_CPP_BUILTINS but this macro is optional and is used for the target object format. ‘elfos.h’ uses this macro to define __ELF__, so you probably do not need to define it yourself.

extern int target_flags  
[Variable]  
This variable is declared in ‘options.h’, which is included before any target-specific headers.

int TARGET_DEFAULT_TARGET_FLAGS  
[Common Target Hook]  
This variable specifies the initial value of target_flags. Its default setting is 0.

bool TARGET_HANDLE_OPTION (struct gcc_options *opts,  
struct gcc_options *opts_set, const struct cl_decoded_option *decoded,  
location_t loc)  
[Common Target Hook]  
This hook is called whenever the user specifies one of the target-specific options described by the ‘.opt’ definition files (see Chapter 8 [Options], page 123). It has the opportunity to do some option-specific processing and should return true if the option is valid. The default definition does nothing but return true.

decoded specifies the option and its arguments. opts and opts_set are the gcc_options structures to be used for storing option state, and loc is the location at which the option was passed (UNKNOWN_LOCATION except for options passed via attributes).

bool TARGET_HANDLE_C_OPTION (size_t code, const char *arg, int  
value)  
[C Target Hook]  
This target hook is called whenever the user specifies one of the target-specific C language family options described by the ‘.opt’ definition files (see Chapter 8 [Options], page 123). It has the opportunity to do some option-specific processing and should return true if the option is valid. The arguments are like for TARGET_HANDLE_OPTION. The default definition does nothing but return false.
In general, you should use `TARGET_HANDLE_OPTION` to handle options. However, if processing an option requires routines that are only available in the C (and related language) front ends, then you should use `TARGET_HANDLE_C_OPTION` instead.

```c
tree TARGET_OBJC_CONSTRUCT_STRING_OBJECT (tree string)  // [C Target Hook]
Targets may provide a string object type that can be used within and between C, C++ and their respective Objective-C dialects. A string object might, for example, embed encoding and length information. These objects are considered opaque to the compiler and handled as references. An ideal implementation makes the composition of the string object match that of the Objective-C `NSString` (`NXString` for GNUStep), allowing efficient interworking between C-only and Objective-C code. If a target implements string objects then this hook should return a reference to such an object constructed from the normal ‘C’ string representation provided in `string`. At present, the hook is used by Objective-C only, to obtain a common-format string object when the target provides one.
```

```c
void TARGET_OBJC_DECLARE_UNRESOLVED_CLASS_REFERENCE (const char *classname)  // [C Target Hook]
Declare that Objective C class `classname` is referenced by the current TU.
```

```c
void TARGET_OBJC_DECLARE_CLASS_DEFINITION (const char *classname)  // [C Target Hook]
Declare that Objective C class `classname` is defined by the current TU.
```

```c
bool TARGET_STRING_OBJECT_REF_TYPE_P (const tree stringref)  // [C Target Hook]
If a target implements string objects then this hook should return true if `stringref` is a valid reference to such an object.
```

```c
void TARGET_CHECK_STRING_OBJECT_FORMAT_ARG (tree format_arg, tree args_list)  // [C Target Hook]
If a target implements string objects then this hook should should provide a facility to check the function arguments in `args_list` against the format specifiers in `format_arg` where the type of `format_arg` is one recognized as a valid string reference type.
```

```c
void TARGET_OVERRIDE_OPTIONS_AFTER_CHANGE (void)  // [Target Hook]
This target function is similar to the hook `TARGET_OPTION_OVERRIDE` but is called when the optimize level is changed via an attribute or pragma or when it is reset at the end of the code affected by the attribute or pragma. It is not called at the beginning of compilation when `TARGET_OPTION_OVERRIDE` is called so if you want to perform these actions then, you should have `TARGET_OPTION_OVERRIDE` call `TARGET_OVERRIDE_OPTIONS_AFTER_CHANGE`.
```

```c
C_COMMON_OVERRIDE_OPTIONS  // [Macro]
This is similar to the `TARGET_OPTION_OVERRIDE` hook but is only used in the C language frontends (C, Objective-C, C++, Objective-C++) and so can be used to alter option flag variables which only exist in those frontends.
```
const struct default_options * [Common Target Hook]

TARGET_OPTION_OPTIMIZATION_TABLE
Some machines may desire to change what optimizations are performed for various
optimization levels. This variable, if defined, describes options to enable at particular
sets of optimization levels. These options are processed once just after the optimization
level is determined and before the remainder of the command options have been
parsed, so may be overridden by other options passed explicitly.
This processing is run once at program startup and when the optimization options
are changed via #pragma GCC optimize or by using the optimize attribute.

void TARGET_OPTION_INIT_STRUCT (struct gcc_options *opts) [Common Target Hook]
Set target-dependent initial values of fields in opts.

SWITCHABLE_TARGET [Macro]
Some targets need to switch between substantially different subtargets during com-
ilation. For example, the MIPS target has one subtarget for the traditional MIPS
architecture and another for MIPS16. Source code can switch between these two
subarchitectures using the mips16 and nomips16 attributes.
Such subtargets can differ in things like the set of available registers, the set of avail-
able instructions, the costs of various operations, and so on. GCC caches a lot of
this type of information in global variables, and recomputing them for each subtar-
get takes a significant amount of time. The compiler therefore provides a facility for
maintaining several versions of the global variables and quickly switching between
them; see 'target-globals.h' for details.
Define this macro to 1 if your target needs this facility. The default is 0.

bool TARGET_FLOAT_EXCEPTIONS_ROUNDING_SUPPORTED_P (void) [Target Hook]
Returns true if the target supports IEEE 754 floating-point exceptions and rounding
modes, false otherwise. This is intended to relate to the float and double types,
but not necessarily long double. By default, returns true if the adddf3 instruction
pattern is available and false otherwise, on the assumption that hardware floating
point supports exceptions and rounding modes but software floating point does not.

18.4 Defining data structures for per-function information.
If the target needs to store information on a per-function basis, GCC provides a macro and
a couple of variables to allow this. Note, just using statics to store the information is a bad
idea, since GCC supports nested functions, so you can be halfway through encoding one
function when another one comes along.

GCC defines a data structure called struct function which contains all of the data
specific to an individual function. This structure contains a field called machine whose
type is struct machine_function *, which can be used by targets to point to their own
specific data.

If a target needs per-function specific data it should define the type struct machine_
function and also the macro INIT_EXPANDERS. This macro should be used to initialize the
function pointer init_machine_status. This pointer is explained below.
One typical use of per-function, target specific data is to create an RTX to hold the register containing the function’s return address. This RTX can then be used to implement the __builtin_return_address function, for level 0.

Note—earlier implementations of GCC used a single data area to hold all of the per-function information. Thus when processing of a nested function began the old per-function data had to be pushed onto a stack, and when the processing was finished, it had to be popped off the stack. GCC used to provide function pointers called save_machine_status and restore_machine_status to handle the saving and restoring of the target specific information. Since the single data area approach is no longer used, these pointers are no longer supported.

INIT_EXPANDERS [Macro]
Macro called to initialize any target specific information. This macro is called once per function, before generation of any RTL has begun. The intention of this macro is to allow the initialization of the function pointer init_machine_status.

void (*)(struct function *) init_machine_status [Variable]
If this function pointer is non-NULL it will be called once per function, before function compilation starts, in order to allow the target to perform any target specific initialization of the struct function structure. It is intended that this would be used to initialize the machine of that structure.

struct machine_function structures are expected to be freed by GC. Generally, any memory that they reference must be allocated by using GC allocation, including the structure itself.

18.5 Storage Layout

Note that the definitions of the macros in this table which are sizes or alignments measured in bits do not need to be constant. They can be C expressions that refer to static variables, such as the target_flags. See Section 18.3 [Run-time Target], page 504.

BITS_BIG_ENDIAN [Macro]
Define this macro to have the value 1 if the most significant bit in a byte has the lowest number; otherwise define it to have the value zero. This means that bit-field instructions count from the most significant bit. If the machine has no bit-field instructions, then this must still be defined, but it doesn’t matter which value it is defined to. This macro need not be a constant.

This macro does not affect the way structure fields are packed into bytes or words; that is controlled by BYTES_BIG_ENDIAN.

BYTES_BIG_ENDIAN [Macro]
Define this macro to have the value 1 if the most significant byte in a word has the lowest number. This macro need not be a constant.

WORDS_BIG_ENDIAN [Macro]
Define this macro to have the value 1 if, in a multiword object, the most significant word has the lowest number. This applies to both memory locations and registers; see REG_WORDS_BIG_ENDIAN if the order of words in memory is not the same as the order in registers. This macro need not be a constant.
REG_WORDS_BIG_ENDIAN

On some machines, the order of words in a multiword object differs between registers in memory. In such a situation, define this macro to describe the order of words in a register. The macro WORDS_BIG_ENDIAN controls the order of words in memory.

FLOAT_WORDS_BIG_ENDIAN

Define this macro to have the value 1 if DFmode, XFmode or TFmode floating point numbers are stored in memory with the word containing the sign bit at the lowest address; otherwise define it to have the value 0. This macro need not be a constant.

You need not define this macro if the ordering is the same as for multi-word integers.

BITS_PER_WORD

Number of bits in a word. If you do not define this macro, the default is BITS_PER_UNIT * UNITS_PER_WORD.

MAX_BITS_PER_WORD

Maximum number of bits in a word. If this is undefined, the default is BITS_PER_WORD. Otherwise, it is the constant value that is the largest value that BITS_PER_WORD can have at runtime.

UNITS_PER_WORD

Number of storage units in a word; normally the size of a general-purpose register, a power of two from 1 or 8.

MIN_UNITS_PER_WORD

Minimum number of units in a word. If this is undefined, the default is UNITS_PER_WORD. Otherwise, it is the constant value that is the smallest value that UNITS_PER_WORD can have at runtime.

POINTER_SIZE

Width of a pointer, in bits. You must specify a value no wider than the width of Pmode. If it is not equal to the width of Pmode, you must define POINTERS_EXTEND_UNSIGNED. If you do not specify a value the default is BITS_PER_WORD.

POINTERS_EXTEND_UNSIGNED

A C expression that determines how pointers should be extended from ptr_mode to either Pmode or word_mode. It is greater than zero if pointers should be zero-extended, zero if they should be sign-extended, and negative if some other sort of conversion is needed. In the last case, the extension is done by the target’s ptr_extend instruction.

You need not define this macro if the ptr_mode, Pmode and word_mode are all the same width.

PROMOTE_MODE (m, unsignedp, type)

A macro to update m and unsignedp when an object whose type is type and which has the specified mode and signedness is to be stored in a register. This macro is only called when type is a scalar type.

On most RISC machines, which only have operations that operate on a full register, define this macro to set m to word_mode if m is an integer mode narrower than
BITS_PER_WORD. In most cases, only integer modes should be widened because wider-precision floating-point operations are usually more expensive than their narrower counterparts.

For most machines, the macro definition does not change unsignedp. However, some machines, have instructions that preferentially handle either signed or unsigned quantities of certain modes. For example, on the DEC Alpha, 32-bit loads from memory and 32-bit add instructions sign-extend the result to 64 bits. On such machines, set unsignedp according to which kind of extension is more efficient.

Do not define this macro if it would never modify m.

```
enum flt_eval_method TARGET_C_EXCESS_PRECISION (enum excess_precision_type type)
    [Target Hook]
    Return a value, with the same meaning as the C99 macro FLT_EVAL_METHOD that describes which excess precision should be applied. type is either EXCESS_PRECISION_TYPE_IMPLICIT, EXCESS_PRECISION_TYPE_FAST, EXCESS_PRECISION_TYPE_STANDARD, or EXCESS_PRECISION_TYPE_FLOAT16. For EXCESS_PRECISION_TYPE_IMPLICIT, the target should return which precision and range operations will be implicitly evaluated in regardless of the excess precision explicitly added. For EXCESS_PRECISION_TYPE_STANDARD, EXCESS_PRECISION_TYPE_FLOAT16, and EXCESS_PRECISION_TYPE_FAST, the target should return the explicit excess precision that should be added depending on the value set for ‘-fexcess-precision=[standard|fast]’. Note that unpredictable explicit excess precision does not make sense, so a target should never return FLT_EVAL_METHOD_UNPREDICTABLE when type is EXCESS_PRECISION_TYPE_STANDARD, EXCESS_PRECISION_TYPE_FLOAT16 or EXCESS_PRECISION_TYPE_FAST.
    Return a value, with the same meaning as the C99 macro FLT_EVAL_METHOD that describes which excess precision should be applied.
```

```
machine_mode TARGET_PROMOTE_FUNCTION_MODE (const tree type, [Target Hook]
machine_mode mode, int *punsignedp, const tree funtype, int for_return)
    Like PROMOTE_MODE, but it is applied to outgoing function arguments or function return values. The target hook should return the new mode and possibly change *punsignedp if the promotion should change signedness. This function is called only for scalar or pointer types.
    for_return allows to distinguish the promotion of arguments and return values. If it is 1, a return value is being promoted and TARGET_FUNCTION_VALUE must perform the same promotions done here. If it is 2, the returned mode should be that of the register in which an incoming parameter is copied, or the outgoing result is computed; then the hook should return the same mode as promote_mode, though the signedness may be different.
    type can be NULL when promoting function arguments of libcalls.
    The default is to not promote arguments and return values. You can also define the hook to default_promote_function_mode_always_promote if you would like to apply the same rules given by PROMOTE_MODE.
```
PARM_BOUNDARY [Macro]
Normal alignment required for function parameters on the stack, in bits. All stack parameters receive at least this much alignment regardless of data type. On most machines, this is the same as the size of an integer.

STACK_BOUNDARY [Macro]
Define this macro to the minimum alignment enforced by hardware for the stack pointer on this machine. The definition is a C expression for the desired alignment (measured in bits). This value is used as a default if PREFERRED_STACK_BOUNDARY is not defined. On most machines, this should be the same as PARM_BOUNDARY.

PREFERRED_STACK_BOUNDARY [Macro]
Define this macro if you wish to preserve a certain alignment for the stack pointer, greater than what the hardware enforces. The definition is a C expression for the desired alignment (measured in bits). This macro must evaluate to a value equal to or larger than STACK_BOUNDARY.

INCOMING_STACK_BOUNDARY [Macro]
Define this macro if the incoming stack boundary may be different from PREFERRED_STACK_BOUNDARY. This macro must evaluate to a value equal to or larger than STACK_BOUNDARY.

FUNCTION_BOUNDARY [Macro]
Alignment required for a function entry point, in bits.

BIGGEST_ALIGNMENT [Macro]
Biggest alignment that any data type can require on this machine, in bits. Note that this is not the biggest alignment that is supported, just the biggest alignment that, when violated, may cause a fault.

HOST_WIDE_INT TARGET_ABSOLUTE_BIGGEST_ALIGNMENT [Target Hook]
If defined, this target hook specifies the absolute biggest alignment that a type or variable can have on this machine, otherwise, BIGGEST_ALIGNMENT is used.

MALLOC_ABI_ALIGNMENT [Macro]
Alignment, in bits, a C conformant malloc implementation has to provide. If not defined, the default value is BITS_PER_WORD.

ATTRIBUTE_ALIGNED_VALUE [Macro]
Alignment used by the __attribute__((aligned)) construct. If not defined, the default value is BIGGEST_ALIGNMENT.

MINIMUM_ATOMIC_ALIGNMENT [Macro]
If defined, the smallest alignment, in bits, that can be given to an object that can be referenced in one operation, without disturbing any nearby object. Normally, this is BITS_PER_UNIT, but may be larger on machines that don’t have byte or half-word store operations.

BIGGEST_FIELD_ALIGNMENT [Macro]
Biggest alignment that any structure or union field can require on this machine, in bits. If defined, this overrides BIGGEST_ALIGNMENT for structure and union fields.
only, unless the field alignment has been set by the `__attribute__((aligned (n)))` construct.

**ADJUST_FIELD_ALIGN (field, type, computed)**  
[Macro]  
An expression for the alignment of a structure field `field` of type `type` if the alignment computed in the usual way (including applying of `BIGGEST_ALIGNMENT` and `BIGGEST_FIELD_ALIGNMENT` to the alignment) is `computed`. It overrides alignment only if the field alignment has not been set by the `__attribute__((aligned (n)))` construct. Note that `field` may be `NULL_TREE` in case we just query for the minimum alignment of a field of type `type` in structure context.

**MAX_STACK_ALIGNMENT**  
[Macro]  
Biggest stack alignment guaranteed by the backend. Use this macro to specify the maximum alignment of a variable on stack.  
If not defined, the default value is `STACK_BOUNDARY`.

**MAX_OFILE_ALIGNMENT**  
[Macro]  
Biggest alignment supported by the object file format of this machine. Use this macro to limit the alignment which can be specified using the `__attribute__((aligned (n)))` construct for functions and objects with static storage duration. The alignment of automatic objects may exceed the object file format maximum up to the maximum supported by GCC. If not defined, the default value is `BIGGEST_ALIGNMENT`.  
On systems that use ELF, the default (in `config/elfos.h`) is the largest supported 32-bit ELF section alignment representable on a 32-bit host e.g. `(((uint64_t) 1 << 28) * 8)`. On 32-bit ELF the largest supported section alignment in bits is `(0x80000000 * 8)`, but this is not representable on 32-bit hosts.

**void TARGET_LOWER_LOCAL_DECL_ALIGNMENT (tree decl)**  
[Target Hook]  
Define this hook to lower alignment of local, parm or result decl `(decl)`.

**HOST_WIDE_INT TARGET_STATIC_RTX_ALIGNMENT (machine_mode mode)**  
[Target Hook]  
This hook returns the preferred alignment in bits for a statically-allocated rtx, such as a constant pool entry. `mode` is the mode of the rtx. The default implementation returns `GET_MODE_ALIGNMENT (mode)`.

**DATA_ALIGNMENT (type, basic-align)**  
[Macro]  
If defined, a C expression to compute the alignment for a variable in the static store. `type` is the data type, and `basic-align` is the alignment that the object would ordinarily have. The value of this macro is used instead of that alignment to align the object. If this macro is not defined, then `basic-align` is used.  
One use of this macro is to increase alignment of medium-size data to make it all fit in fewer cache lines. Another is to cause character arrays to be word-aligned so that `strcpy` calls that copy constants to character arrays can be done inline.

**DATA_ABI_ALIGNMENT (type, basic-align)**  
[Macro]  
Similar to `DATA_ALIGNMENT`, but for the cases where the ABI mandates some alignment increase, instead of optimization only purposes. E.g. AMD x86-64 psABI says
that variables with array type larger than 15 bytes must be aligned to 16 byte boundaries.
If this macro is not defined, then _basic-align_ is used.

**HOST_WIDE_INT TARGET_CONSTANT_ALIGNMENT** (const.tree _constant_, HOST.WIDE.INT _basic_align_)  
[Target Hook]

This hook returns the alignment in bits of a constant that is being placed in memory. _constant_ is the constant and _basic_align_ is the alignment that the object would ordinarily have.

The default definition just returns _basic_align_.

The typical use of this hook is to increase alignment for string constants to be word aligned so that _strcpy_ calls that copy constants can be done inline. The function _constant_alignment_word_strings_ provides such a definition.

**LOCAL_ALIGNMENT** (type, _basic-align_)  
[Macro]

If defined, a C expression to compute the alignment for a variable in the local store. _type_ is the data type, and _basic-align_ is the alignment that the object would ordinarily have. The value of this macro is used instead of that alignment to align the object.

If this macro is not defined, then _basic-align_ is used.

One use of this macro is to increase alignment of medium-size data to make it all fit in fewer cache lines.

If the value of this macro has a type, it should be an unsigned type.

**HOST_WIDE_INT TARGET_VECTOR_ALIGNMENT** (const.tree _type_)  
[Target Hook]

This hook can be used to define the alignment for a vector of type _type_, in order to comply with a platform ABI. The default is to require natural alignment for vector types. The alignment returned by this hook must be a power-of-two multiple of the default alignment of the vector element type.

**STACK_SLOT_ALIGNMENT** (type, _mode_, _basic-align_)  
[Macro]

If defined, a C expression to compute the alignment for stack slot. _type_ is the data type, _mode_ is the widest mode available, and _basic-align_ is the alignment that the slot would ordinarily have. The value of this macro is used instead of that alignment to align the slot.

If this macro is not defined, then _basic-align_ is used when _type_ is NULL. Otherwise, _LOCAL_ALIGNMENT_ will be used.

This macro is to set alignment of stack slot to the maximum alignment of all possible modes which the slot may have.

If the value of this macro has a type, it should be an unsigned type.

**LOCAL_DECL_ALIGNMENT** (decl)  
[Macro]

If defined, a C expression to compute the alignment for a local variable _decl_.

If this macro is not defined, then _LOCAL_ALIGNMENT (TREE_TYPE (decl), DECL_ALIGN (decl))_ is used.

One use of this macro is to increase alignment of medium-size data to make it all fit in fewer cache lines.

If the value of this macro has a type, it should be an unsigned type.
MINIMUM_ALIGNMENT \((\text{exp, mode, align})\)  
If defined, a C expression to compute the minimum required alignment for dynamic stack realignment purposes for \(\text{exp}\) (a type or decl), \(\text{mode}\), assuming normal alignment \(\text{align}\).

If this macro is not defined, then \(\text{align}\) will be used.

EMPTY_FIELD_BOUNDARY  
Alignment in bits to be given to a structure bit-field that follows an empty field such as \(\text{int : 0;}\).  
If \(\text{PCC_BITFIELD_TYPE_MATTERS}\) is true, it overrides this macro.

STRUCTURE_SIZE_BOUNDARY  
Number of bits which any structure or union’s size must be a multiple of. Each structure or union’s size is rounded up to a multiple of this.

If you do not define this macro, the default is the same as \(\text{BITS_PER_UNIT}\).

STRICT_ALIGNMENT  
Define this macro to be the value 1 if instructions will fail to work if given data not on the nominal alignment. If instructions will merely go slower in that case, define this macro as 0.

PCC_BITFIELD_TYPE_MATTERS  
Define this if you wish to imitate the way many other C compilers handle alignment of bit-fields and the structures that contain them.

The behavior is that the type written for a named bit-field (\(\text{int, short}\), or other integer type) imposes an alignment for the entire structure, as if the structure really did contain an ordinary field of that type. In addition, the bit-field is placed within the structure so that it would fit within such a field, not crossing a boundary for it.

Thus, on most machines, a named bit-field whose type is written as \(\text{int}\) would not cross a four-byte boundary, and would force four-byte alignment for the whole structure. (The alignment used may not be four bytes; it is controlled by the other alignment parameters.)

An unnamed bit-field will not affect the alignment of the containing structure.

If the macro is defined, its definition should be a C expression; a nonzero value for the expression enables this behavior.

Note that if this macro is not defined, or its value is zero, some bit-fields may cross more than one alignment boundary. The compiler can support such references if there are ‘\text{insv}', ‘\text{extv}', and ‘\text{extzv}' insns that can directly reference memory.

The other known way of making bit-fields work is to define \(\text{STRUCTURE_SIZE_BOUNDARY}\) as large as \(\text{BIGGEST_ALIGNMENT}\). Then every structure can be accessed with fullwords.

Unless the machine has bit-field instructions or you define \(\text{STRUCTURE_SIZE_BOUNDARY}\) that way, you must define \(\text{PCC_BITFIELD_TYPE_MATTERS}\) to have a nonzero value.

If your aim is to make GCC use the same conventions for laying out bit-fields as are used by another compiler, here is how to investigate what the other compiler does. Compile and run this program:
struct foo1
{
    char x;
    char :0;
    char y;
};

struct foo2
{
    char x;
    int :0;
    char y;
};

main()
{
    printf("Size of foo1 is %d\n", sizeof(struct foo1));
    printf("Size of foo2 is %d\n", sizeof(struct foo2));
    exit(0);
}

If this prints 2 and 5, then the compiler’s behavior is what you would get from PCC_BITFIELD_TYPE_MATTERS.

BITFIELD_NBYTES_LIMITED [Macro]
Like PCC_BITFIELD_TYPE_MATTERS except that its effect is limited to aligning a bitfield within the structure.

bool TARGET_ALIGN_ANON_BITFIELD (void) [Target Hook]
When PCC_BITFIELD_TYPE_MATTERS is true this hook will determine whether unnamed bitfields affect the alignment of the containing structure. The hook should return true if the structure should inherit the alignment requirements of an unnamed bitfield’s type.

bool TARGET_NARROW_VOLATILE_BITFIELD (void) [Target Hook]
This target hook should return true if accesses to volatile bitfields should use the narrowest mode possible. It should return false if these accesses should use the bitfield container type.

The default is false.

bool TARGET_MEMBER_TYPE_FORCES_BLK (const tree field, machine_mode mode) [Target Hook]
Return true if a structure, union or array containing field should be accessed using BLKMODE.

If field is the only field in the structure, mode is its mode, otherwise mode is VOID-mode. mode is provided in the case where structures of one field would require the structure’s mode to retain the field’s mode.

Normally, this is not needed.
ROUND_TYPE_ALIGN (type, computed, specified)  [Macro]
Define this macro as an expression for the alignment of a type (given by type as a tree node) if the alignment computed in the usual way is computed and the alignment explicitly specified was specified.
The default is to use specified if it is larger; otherwise, use the smaller of computed and BIGGEST_ALIGNMENT.

MAX_FIXED_MODE_SIZE  [Macro]
An integer expression for the size in bits of the largest integer machine mode that should actually be used. All integer machine modes of this size or smaller can be used for structures and unions with the appropriate sizes. If this macro is undefined, GET_MODE_BITSIZE (DImode) is assumed.

STACK_SAVEAREA_MODE (save_level)  [Macro]
If defined, an expression of type machine_mode that specifies the mode of the save area operand of a save_stack_level named pattern (see Section 17.9 [Standard Names], page 405). save_level is one of SAVE_BLOCK, SAVE_FUNCTION, or SAVE_NONLOCAL and selects which of the three named patterns is having its mode specified.
You need not define this macro if it always returns Pmode. You would most commonly define this macro if the save_stack_level patterns need to support both a 32- and a 64-bit mode.

STACK_SIZE_MODE  [Macro]
If defined, an expression of type machine_mode that specifies the mode of the size increment operand of an allocate_stack named pattern (see Section 17.9 [Standard Names], page 405).
You need not define this macro if it always returns word_mode. You would most commonly define this macro if the allocate_stack pattern needs to support both a 32- and a 64-bit mode.

scalar_int_mode TARGET_LIBGCC_CMP_RETURN_MODE (void)  [Target Hook]
This target hook should return the mode to be used for the return value of compare instructions expanded to libgcc calls. If not defined word_mode is returned which is the right choice for a majority of targets.

scalar_int_mode TARGET_LIBGCC_SHIFT_COUNT_MODE (void)  [Target Hook]
This target hook should return the mode to be used for the shift count operand of shift instructions expanded to libgcc calls. If not defined word_mode is returned which is the right choice for a majority of targets.

scalar_int_mode TARGET_UNWIND_WORD_MODE (void)  [Target Hook]
Return machine mode to be used for _Unwind_Word type. The default is to use word_mode.

bool TARGET_MS_BITFIELD_LAYOUT_P (const tree record_type)  [Target Hook]
This target hook returns true if bit-fields in the given record_type are to be laid out following the rules of Microsoft Visual C/C++, namely: (i) a bit-field won’t share the same storage unit with the previous bit-field if their underlying types have different
sizes, and the bit-field will be aligned to the highest alignment of the underlying types of itself and of the previous bit-field; (ii) a zero-sized bit-field will affect the alignment of the whole enclosing structure, even if it is unnamed; except that (iii) a zero-sized bit-field will be disregarded unless it follows another bit-field of nonzero size. If this hook returns `true`, other macros that control bit-field layout are ignored.

When a bit-field is inserted into a packed record, the whole size of the underlying type is used by one or more same-size adjacent bit-fields (that is, if its long:3, 32 bits is used in the record, and any additional adjacent long bit-fields are packed into the same chunk of 32 bits. However, if the size changes, a new field of that size is allocated). In an unpacked record, this is the same as using alignment, but not equivalent when packing.

If both MS bit-fields and `__attribute__((packed))` are used, the latter will take precedence. If `__attribute__((packed))` is used on a single field when MS bit-fields are in use, it will take precedence for that field, but the alignment of the rest of the structure may affect its placement.

```c
bool TARGET_DECIMAL_FLOAT_SUPPORTED_P (void) [Target Hook]
>Returns true if the target supports decimal floating point.
```

```c
bool TARGET_FIXED_POINT_SUPPORTED_P (void) [Target Hook]
>Returns true if the target supports fixed-point arithmetic.
```

```c
void TARGET_EXPAND_TO_RTL_HOOK (void) [Target Hook]
>This hook is called just before expansion into rtl, allowing the target to perform additional initializations or analysis before the expansion. For example, the rs6000 port uses it to allocate a scratch stack slot for use in copying SDmode values between memory and floating point registers whenever the function being expanded has any SDmode usage.
```

```c
void TARGET_INSTANTIATE_DECLS (void) [Target Hook]
>This hook allows the backend to perform additional instantiations on rtl that are not actually in any insns yet, but will be later.
```

```c
const char * TARGET_MANGLE_TYPE (const tree type) [Target Hook]
>If your target defines any fundamental types, or any types your target uses should be mangled differently from the default, define this hook to return the appropriate encoding for these types as part of a C++ mangled name. The type argument is the tree structure representing the type to be mangled. The hook may be applied to trees which are not target-specific fundamental types; it should return `NULL` for all such types, as well as arguments it does not recognize. If the return value is not `NULL`, it must point to a statically-allocated string constant.

Target-specific fundamental types might be new fundamental types or qualified versions of ordinary fundamental types. Encode new fundamental types as `un name`, where `name` is the name used for the type in source code, and `n` is the length of `name` in decimal. Encode qualified versions of ordinary types as `U n name code`, where `name` is the name used for the type qualifier in source code, `n` is the length of `name` as above, and `code` is the code used to represent the unqualified version of this type.
(See `write_builtin_type` in `cp/mangle.c` for the list of codes.) In both cases the spaces are for clarity; do not include any spaces in your string.

This hook is applied to types prior to typedef resolution. If the mangled name for a particular type depends only on that type’s main variant, you can perform typedef resolution yourself using `TYPE_MAIN_VARIANT` before mangling.

The default version of this hook always returns `NULL`, which is appropriate for a target that does not define any new fundamental types.

### 18.6 Layout of Source Language Data Types

These macros define the sizes and other characteristics of the standard basic data types used in programs being compiled. Unlike the macros in the previous section, these apply to specific features of C and related languages, rather than to fundamental aspects of storage layout.

**[Macro]**

`INT_TYPE_SIZE`

A C expression for the size in bits of the type `int` on the target machine. If you don’t define this, the default is one word.

**[Macro]**

`SHORT_TYPE_SIZE`

A C expression for the size in bits of the type `short` on the target machine. If you don’t define this, the default is half a word. (If this would be less than one storage unit, it is rounded up to one unit.)

**[Macro]**

`LONG_TYPE_SIZE`

A C expression for the size in bits of the type `long` on the target machine. If you don’t define this, the default is one word.

**[Macro]**

`ADA_LONG_TYPE_SIZE`

On some machines, the size used for the Ada equivalent of the type `long` by a native Ada compiler differs from that used by C. In that situation, define this macro to be a C expression to be used for the size of that type. If you don’t define this, the default is the value of `LONG_TYPE_SIZE`.

**[Macro]**

`LONG_LONG_TYPE_SIZE`

A C expression for the size in bits of the type `long long` on the target machine. If you don’t define this, the default is two words. If you want to support GNU Ada on your machine, the value of this macro must be at least 64.

**[Macro]**

`CHAR_TYPE_SIZE`

A C expression for the size in bits of the type `char` on the target machine. If you don’t define this, the default is `BITS_PER_UNIT`.

**[Macro]**

`BOOL_TYPE_SIZE`

A C expression for the size in bits of the C++ type `bool` and C99 type `_Bool` on the target machine. If you don’t define this, and you probably shouldn’t, the default is `CHAR_TYPE_SIZE`.

**[Macro]**

`FLOAT_TYPE_SIZE`

A C expression for the size in bits of the type `float` on the target machine. If you don’t define this, the default is one word.
DOUBLE_TYPE_SIZE [Macro]
A C expression for the size in bits of the type double on the target machine. If you
don’t define this, the default is two words.

LONG_DOUBLE_TYPE_SIZE [Macro]
A C expression for the size in bits of the type long double on the target machine. If you
don’t define this, the default is two words.

SHORT_FRACT_TYPE_SIZE [Macro]
A C expression for the size in bits of the type short _Fract on the target machine.
If you don’t define this, the default is BITS_PER_UNIT.

FRACT_TYPE_SIZE [Macro]
A C expression for the size in bits of the type _Fract on the target machine. If you
don’t define this, the default is BITS_PER_UNIT * 2.

LONG_FRACT_TYPE_SIZE [Macro]
A C expression for the size in bits of the type long _Fract on the target machine. If you
don’t define this, the default is BITS_PER_UNIT * 4.

LONG_LONG_FRACT_TYPE_SIZE [Macro]
A C expression for the size in bits of the type long long _Fract on the target machine.
If you don’t define this, the default is BITS_PER_UNIT * 8.

SHORT_ACCUM_TYPE_SIZE [Macro]
A C expression for the size in bits of the type short _Accum on the target machine.
If you don’t define this, the default is BITS_PER_UNIT * 2.

ACCUM_TYPE_SIZE [Macro]
A C expression for the size in bits of the type _Accum on the target machine. If you
don’t define this, the default is BITS_PER_UNIT * 4.

LONG_ACCUM_TYPE_SIZE [Macro]
A C expression for the size in bits of the type long _Accum on the target machine. If you
don’t define this, the default is BITS_PER_UNIT * 8.

LONG_LONG_ACCUM_TYPE_SIZE [Macro]
A C expression for the size in bits of the type long long _Accum on the target machine.
If you don’t define this, the default is BITS_PER_UNIT * 16.

LIBGCC2_GNU_PREFIX [Macro]
This macro corresponds to the TARGET_LIBFUNC_GNU_PREFIX target hook and should
be defined if that hook is overriden to be true. It causes function names in libgcc
to be changed to use a __gnu_ prefix for their name rather than the default __. A
port which uses this macro should also arrange to use ‘t-gnu-prefix’ in the libgcc
‘config.host’.

WIDEST_HARDWARE_FP_SIZE [Macro]
A C expression for the size in bits of the widest floating-point format supported by
the hardware. If you define this macro, you must specify a value less than or equal
to the value of LONG_DOUBLE_TYPE_SIZE. If you do not define this macro, the value
of LONG_DOUBLE_TYPE_SIZE is the default.
DEFAULT_SIGNED_CHAR  [Macro]
An expression whose value is 1 or 0, according to whether the type char should be
signed or unsigned by default. The user can always override this default with the
options '-fsigned-char' and '-funsigned-char'.

bool TARGET_DEFAULT_SHORT_ENUMS (void)  [Target Hook]
This target hook should return true if the compiler should give an enum type only
as many bytes as it takes to represent the range of possible values of that type. It
should return false if all enum types should be allocated like int.
The default is to return false.

SIZE_TYPE  [Macro]
A C expression for a string describing the name of the data type to use for size values.
The typedef name size_t is defined using the contents of the string.
The string can contain more than one keyword. If so, separate them with spaces,
and write first any length keyword, then unsigned if appropriate, and finally int.
The string must exactly match one of the data type names defined in the function
c_common_nodes_and_builtins in the file `c-family/c-common.c`. You may not
omit int or change the order—that would cause the compiler to crash on startup.
If you don’t define this macro, the default is "long unsigned int".

SIZETYPE  [Macro]
GCC defines internal types (sizetype, ssizetype, bitsizetype and sbitsizetype)
for expressions dealing with size. This macro is a C expression for a string describing
the name of the data type from which the precision of sizetype is extracted.
The string has the same restrictions as SIZE_TYPE string.
If you don’t define this macro, the default is SIZE_TYPE.

PTRDIFF_TYPE  [Macro]
A C expression for a string describing the name of the data type to use for the result of
subtracting two pointers. The typedef name ptrdiff_t is defined using the contents
of the string. See SIZE_TYPE above for more information.
If you don’t define this macro, the default is "long int".

WCHAR_TYPE  [Macro]
A C expression for a string describing the name of the data type to use for wide
characters. The typedef name wchar_t is defined using the contents of the string.
See SIZE_TYPE above for more information.
If you don’t define this macro, the default is "int".

WCHAR_TYPE_SIZE  [Macro]
A C expression for the size in bits of the data type for wide characters. This is used
in cpp, which cannot make use of WCHAR_TYPE.

WINT_TYPE  [Macro]
A C expression for a string describing the name of the data type to use for wide
characters passed to printf and returned from getwc. The typedef name wint_t is
defined using the contents of the string. See SIZE_TYPE above for more information.
If you don’t define this macro, the default is "unsigned int".
INTMAX_TYPE

A C expression for a string describing the name of the data type that can represent any value of any standard or extended signed integer type. The typedef name intmax_t is defined using the contents of the string. See SIZE_TYPE above for more information.

If you don’t define this macro, the default is the first of "int", "long int", or "long long int" that has as much precision as long long int.

UINTMAX_TYPE

A C expression for a string describing the name of the data type that can represent any value of any standard or extended unsigned integer type. The typedef name uintmax_t is defined using the contents of the string. See SIZE_TYPE above for more information.

If you don’t define this macro, the default is the first of "unsigned int", "long unsigned int", or "long long unsigned int" that has as much precision as long long unsigned int.

C expressions for the standard types sig_atomic_t, int8_t, int16_t, int32_t, int64_t, uint8_t, uint16_t, uint32_t, uint64_t, int_least8_t, int_least16_t, int_least32_t, int_least64_t, uint_least8_t, uint_least16_t, uint_least32_t, uint_least64_t, int_fast8_t, int_fast16_t, int_fast32_t, int_fast64_t, intptr_t, uintptr_t.
uint_fast8_t, uint_fast16_t, uint_fast32_t, uint_fast64_t, intptr_t, and uintptr_t. See SIZE_TYPE above for more information.

If any of these macros evaluates to a null pointer, the corresponding type is not supported; if GCC is configured to provide <stdint.h> in such a case, the header provided may not conform to C99, depending on the type in question. The defaults for all of these macros are null pointers.

**TARGET_PTRMEMFUNC_VBIT_LOCATION**

[Macro]

The C++ compiler represents a pointer-to-member-function with a struct that looks like:

```c
struct {
    union {
        void (*fn)();
        ptrdiff_t vtable_index;
    };
    ptrdiff_t delta;
};
```

The C++ compiler must use one bit to indicate whether the function that will be called through a pointer-to-member-function is virtual. Normally, we assume that the low-order bit of a function pointer must always be zero. Then, by ensuring that the vtable_index is odd, we can distinguish which variant of the union is in use. But, on some platforms function pointers can be odd, and so this doesn’t work. In that case, we use the low-order bit of the delta field, and shift the remainder of the delta field to the left.

GCC will automatically make the right selection about where to store this bit using the FUNCTION_BOUNDARY setting for your platform. However, some platforms such as ARM/Thumb have FUNCTION_BOUNDARY set such that functions always start at even addresses, but the lowest bit of pointers to functions indicate whether the function at that address is in ARM or Thumb mode. If this is the case of your architecture, you should define this macro to ptrmemfunc_vbit_in_delta.

In general, you should not have to define this macro. On architectures in which function addresses are always even, according to FUNCTION_BOUNDARY, GCC will automatically define this macro to ptrmemfunc_vbit_in_pfn.

**TARGET_VTABLE_USES_DESCRIPTORS**

[Macro]

Normally, the C++ compiler uses function pointers in vtables. This macro allows the target to change to use “function descriptors” instead. Function descriptors are found on targets for whom a function pointer is actually a small data structure. Normally the data structure consists of the actual code address plus a data pointer to which the function’s data is relative.

If vtables are used, the value of this macro should be the number of words that the function descriptor occupies.

**TARGET_VTABLE_ENTRY_ALIGN**

[Macro]

By default, the vtable entries are void pointers, the so the alignment is the same as pointer alignment. The value of this macro specifies the alignment of the vtable entry in bits. It should be defined only when special alignment is necessary. */
TARGET_VTABLE_DATA_ENTRY_DISTANCE [Macro]
There are a few non-descriptor entries in the vtable at offsets below zero. If these entries must be padded (say, to preserve the alignment specified by TARGET_VTABLE_ENTRY_ALIGN), set this to the number of words in each data entry.

18.7 Register Usage
This section explains how to describe what registers the target machine has, and how (in general) they can be used.

The description of which registers a specific instruction can use is done with register classes; see Section 18.8 [Register Classes], page 530. For information on using registers to access a stack frame, see Section 18.9.4 [Frame Registers], page 548. For passing values in registers, see Section 18.9.7 [Register Arguments], page 554. For returning values in registers, see Section 18.9.8 [Scalar Return], page 562.

18.7.1 Basic Characteristics of Registers
Registers have various characteristics.

FIRST_PSEUDO_REGISTER [Macro]
Number of hardware registers known to the compiler. They receive numbers 0 through FIRST_PSEUDO_REGISTER-1; thus, the first pseudo register’s number really is assigned the number FIRST_PSEUDO_REGISTER.

FIXED_REGISTERS [Macro]
An initializer that says which registers are used for fixed purposes all throughout the compiled code and are therefore not available for general allocation. These would include the stack pointer, the frame pointer (except on machines where that can be used as a general register when no frame pointer is needed), the program counter on machines where that is considered one of the addressable registers, and any other numbered register with a standard use.

This information is expressed as a sequence of numbers, separated by commas and surrounded by braces. The nth number is 1 if register n is fixed, 0 otherwise.

The table initialized from this macro, and the table initialized by the following one, may be overridden at run time either automatically, by the actions of the macro CONDITIONAL_REGISTER_USAGE, or by the user with the command options ‘-ffixed-reg’, ‘-fcall-used-reg’ and ‘-fcall-saved-reg’.

CALL_USED_REGISTERS [Macro]
Like FIXED_REGISTERS but has 1 for each register that is clobbered (in general) by function calls as well as for fixed registers. This macro therefore identifies the registers that are not available for general allocation of values that must live across function calls.

If a register has 0 in CALL_USED_REGISTERS, the compiler automatically saves it on function entry and restores it on function exit, if the register is used within the function.

Exactly one of CALL_USED_REGISTERS and CALL_REALLY_USED_REGISTERS must be defined. Modern ports should define CALL_REALLY_USED_REGISTERS.
CALL_REALLY_USED_REGSISTERS

Like CALL_USED_REGSISTERS except this macro doesn’t require that the entire set of FIXED_REGSISTERS be included. (CALL_USED_REGSISTERS must be a superset of FIXED_REGSISTERS).

Exactly one of CALL_USED_REGSISTERS and CALL_REALLY_USED_REGSISTERS must be defined. Modern ports should define CALL_REALLY_USED_REGSISTERS.

const predefined_function_abi & TARGET_FNTYPE_ABI

(const_tree type)
Return the ABI used by a function with type type; see the definition of predefined_function_abi for details of the ABI descriptor. Targets only need to define this hook if they support interoperability between several ABIs in the same translation unit.

const predefined_function_abi & TARGET_INSN_CALLEE_ABI

(const rtx insn *insn)
This hook returns a description of the ABI used by the target of call instruction insn; see the definition of predefined_function_abi for details of the ABI descriptor. Only the global function insn_callee_abi should call this hook directly.
Targets only need to define this hook if they support interoperability between several ABIs in the same translation unit.

bool TARGET_HARD_REGNO_CALL_PART_CLOBBERED (unsigned int abi_id, unsigned int regno, machine_mode mode)

ABIs usually specify that calls must preserve the full contents of a particular register, or that calls can alter any part of a particular register. This information is captured by the target macro CALL_REALLY_USED_REGSISTERS. However, some ABIs specify that calls must preserve certain bits of a particular register but can alter others. This hook should return true if this applies to at least one of the registers in ‘(reg:mode regno)’, and if as a result the call would alter part of the mode value. For example, if a call preserves the low 32 bits of a 64-bit hard register regno but can clobber the upper 32 bits, this hook should return true for a 64-bit mode but false for a 32-bit mode.

The value of abi_id comes from the predefined_function_abi structure that describes the ABI of the call; see the definition of the structure for more details. If (as is usual) the target uses the same ABI for all functions in a translation unit, abi_id is always 0.

The default implementation returns false, which is correct for targets that don’t have partly-clobbered registers.

const char * TARGET_GET_MULTILIB_ABI_NAME (void)

This hook returns name of multilib ABI name.

void TARGET_CONDITIONAL_REGISTER_USAGE (void)

This hook may conditionally modify five variables fixed_regs, call_used_regs, global_regs, reg_names, and reg_class_contents, to take into account any dependence of these register sets on target flags. The first three of these are of type char [] (interpreted as boolean vectors). global_regs is a const char *[], and reg_class_contents is a HARD_REG_SET. Before the macro is called,
fixed_regs, call_used_regs, reg_class_contents, and reg_names have been initialized from FIXED_REGISTERS, CALL_USED_REGISTERS, REG_CLASS_CONTENTS, and REGISTER_NAMES, respectively. global_regs has been cleared, and any ‘-ffixed-reg’, ‘-fcall-used-reg’ and ‘-fcall-saved-reg’ command options have been applied.

If the usage of an entire class of registers depends on the target flags, you may indicate this to GCC by using this macro to modify fixed_regs and call_used_regs to 1 for each of the registers in the classes which should not be used by GCC. Also make define_register_constraints return NO_REGS for constraints that shouldn’t be used.

(However, if this class is not included in GENERAL_REGS and all of the insn patterns whose constraints permit this class are controlled by target switches, then GCC will automatically avoid using these registers when the target switches are opposed to them.)

INCOMING_REGNO (out) [Macro]
Define this macro if the target machine has register windows. This C expression returns the register number as seen by the called function corresponding to the register number out as seen by the calling function. Return out if register number out is not an outbound register.

OUTGOING_REGNO (in) [Macro]
Define this macro if the target machine has register windows. This C expression returns the register number as seen by the calling function corresponding to the register number in as seen by the called function. Return in if register number in is not an inbound register.

LOCAL_REGNO (regno) [Macro]
Define this macro if the target machine has register windows. This C expression returns true if the register is call-saved but is in the register window. Unlike most call-saved registers, such registers need not be explicitly restored on function exit or during non-local gotos.

PC_REGNUM [Macro]
If the program counter has a register number, define this as that register number. Otherwise, do not define it.

18.7.2 Order of Allocation of Registers
Registers are allocated in order.

REG_ALLOC_ORDER [Macro]
If defined, an initializer for a vector of integers, containing the numbers of hard registers in the order in which GCC should prefer to use them (from most preferred to least).

If this macro is not defined, registers are used lowest numbered first (all else being equal).

One use of this macro is on machines where the highest numbered registers must always be saved and the save-multiple-registers instruction supports only sequences of
consecutive registers. On such machines, define `REG_ALLOC_ORDER` to be an initializer that lists the highest numbered allocable register first.

**ADJUST_REG_ALLOC_ORDER**

A C statement (sans semicolon) to choose the order in which to allocate hard registers for pseudo-registers local to a basic block.

Store the desired register order in the array `reg_alloc_order`. Element 0 should be the register to allocate first; element 1, the next register; and so on.

The macro body should not assume anything about the contents of `reg_alloc_order` before execution of the macro.

On most machines, it is not necessary to define this macro.

**HONOR_REG_ALLOC_ORDER**

Normally, IRA tries to estimate the costs for saving a register in the prologue and restoring it in the epilogue. This discourages it from using call-saved registers. If a machine wants to ensure that IRA allocates registers in the order given by `REG_ALLOC_ORDER` even if some call-saved registers appear earlier than call-used ones, then define this macro as a C expression to nonzero. Default is 0.

**IRA_HARD_REGNO_ADD_COST_MULTIPLIER** *(regno)*

In some case register allocation order is not enough for the Integrated Register Allocator (IRA) to generate a good code. If this macro is defined, it should return a floating point value based on `regno`. The cost of using `regno` for a pseudo will be increased by approximately the pseudo’s usage frequency times the value returned by this macro. Not defining this macro is equivalent to having it always return 0.0.

On most machines, it is not necessary to define this macro.

### 18.7.3 How Values Fit in Registers

This section discusses the macros that describe which kinds of values (specifically, which machine modes) each register can hold, and how many consecutive registers are needed for a given mode.

**unsigned int TARGET_HARD_REGNO_NREGS** *(unsigned int regno, machine mode mode)*

This hook returns the number of consecutive hard registers, starting at register number `regno`, required to hold a value of mode `mode`. This hook must never return zero, even if a register cannot hold the requested mode - indicate that with `TARGET_HARD_REGNO_MODE_OK` and/or `TARGET_CAN_CHANGE_MODE_CLASS` instead.

The default definition returns the number of words in `mode`.

**HARD_REGNO_NREGS_HAS_PADDING** *(regno, mode)*

A C expression that is nonzero if a value of mode `mode`, stored in memory, ends with padding that causes it to take up more space than in registers starting at register number `regno` (as determined by multiplying GCC’s notion of the size of the register when containing this mode by the number of registers returned by `TARGET_HARD_REGNO_NREGS`). By default this is zero.

For example, if a floating-point value is stored in three 32-bit registers but takes up 128 bits in memory, then this would be nonzero.
This macro only needs to be defined if there are cases where `subreg_get_info` would otherwise wrongly determine that a `subreg` can be represented by an offset to the register number, when in fact such a `subreg` would contain some of the padding not stored in registers and so not be representable.

**HARD_REGNO_NREGS_WITH_PADDING (regno, mode)**  
For values of `regno` and `mode` for which `HARD_REGNO_NREGS_HAS_PADDING` returns nonzero, a C expression returning the greater number of registers required to hold the value including any padding. In the example above, the value would be four.

**REGMODE_NATURAL_SIZE (mode)**  
Define this macro if the natural size of registers that hold values of mode `mode` is not the word size. It is a C expression that should give the natural size in bytes for the specified mode. It is used by the register allocator to try to optimize its results. This happens for example on SPARC 64-bit where the natural size of floating-point registers is still 32-bit.

**bool TARGET_HARD_REGNO_MODE_OK (unsigned int regno, machine_mode mode)**  
This hook returns true if it is permissible to store a value of mode `mode` in hard register number `regno` (or in several registers starting with that one). The default definition returns true unconditionally. You need not include code to check for the numbers of fixed registers, because the allocation mechanism considers them to be always occupied.

On some machines, double-precision values must be kept in even/odd register pairs. You can implement that by defining this hook to reject odd register numbers for such modes.

The minimum requirement for a mode to be OK in a register is that the 'movmode' instruction pattern support moves between the register and other hard register in the same class and that moving a value into the register and back out not alter it.

Since the same instruction used to move `word_mode` will work for all narrower integer modes, it is not necessary on any machine for this hook to distinguish between these modes, provided you define patterns 'movhi', etc., to take advantage of this. This is useful because of the interaction between `TARGET_HARD_REGNO_MODE_OK` and `TARGET_MODES_TIEABLE_P`; it is very desirable for all integer modes to be tieable.

Many machines have special registers for floating point arithmetic. Often people assume that floating point machine modes are allowed only in floating point registers. This is not true. Any registers that can hold integers can safely hold a floating point machine mode, whether or not floating arithmetic can be done on it in those registers. Integer move instructions can be used to move the values.

On some machines, though, the converse is true: fixed-point machine modes may not go in floating registers. This is true if the floating registers normalize any value stored in them, because storing a non-floating value there would garble it. In this case, `TARGET_HARD_REGNO_MODE_OK` should reject fixed-point machine modes in floating registers. But if the floating registers do not automatically normalize, if you can store any bit pattern in one and retrieve it unchanged without a trap, then any machine mode may go in a floating register, so you can define this hook to say so.
The primary significance of special floating registers is rather that they are the registers acceptable in floating point arithmetic instructions. However, this is of no concern to `TARGET_HARD_REGNO_MODE_OK`. You handle it by writing the proper constraints for those instructions.

On some machines, the floating registers are especially slow to access, so that it is better to store a value in a stack frame than in such a register if floating point arithmetic is not being done. As long as the floating registers are not in class `GENERAL_REGS`, they will not be used unless some pattern’s constraint asks for one.

```
HARD_REGNO_RENAME_OK (from, to)  [Macro]
A C expression that is nonzero if it is OK to rename a hard register from to another hard register to.

One common use of this macro is to prevent renaming of a register to another register that is not saved by a prologue in an interrupt handler.

The default is always nonzero.
```

```
bool TARGET_MODES_TIEABLE_P (machine_mode mode1, machine_mode mode2)  [Target Hook]
This hook returns true if a value of mode `mode1` is accessible in mode `mode2` without copying.

If `TARGET_HARD_REGNO_MODE_OK (r, mode1)` and `TARGET_HARD_REGNO_MODE_OK (r, mode2)` are always the same for any `r`, then `TARGET_MODES_TIEABLE_P (mode1, mode2)` should be true. If they differ for any `r`, you should define this hook to return false unless some other mechanism ensures the accessibility of the value in a narrower mode.

You should define this hook to return true in as many cases as possible since doing so will allow GCC to perform better register allocation. The default definition returns true unconditionally.
```

```
bool TARGET_HARD_REGNO_SCRATCH_OK (unsigned int regno)  [Target Hook]
This target hook should return true if it is OK to use a hard register `regno` as scratch reg in peephole2.

One common use of this macro is to prevent using of a register that is not saved by a prologue in an interrupt handler.

The default version of this hook always returns true.
```

```
AVOID_CC_MODE_COPIES  [Macro]
Define this macro if the compiler should avoid copies to/from CCmode registers. You should only define this macro if support for copying to/from CCmode is incomplete.
```

### 18.7.4 Handling Leaf Functions

On some machines, a leaf function (i.e., one which makes no calls) can run more efficiently if it does not make its own register window. Often this means it is required to receive its arguments in the registers where they are passed by the caller, instead of the registers where they would normally arrive.

The special treatment for leaf functions generally applies only when other conditions are met; for example, often they may use only those registers for its own variables and
temporaries. We use the term “leaf function” to mean a function that is suitable for this special handling, so that functions with no calls are not necessarily “leaf functions”.

GCC assigns register numbers before it knows whether the function is suitable for leaf function treatment. So it needs to renumber the registers in order to output a leaf function. The following macros accomplish this.

**LEAF_REGISTERS**  
Name of a char vector, indexed by hard register number, which contains 1 for a register that is allowable in a candidate for leaf function treatment.

If leaf function treatment involves renumbering the registers, then the registers marked here should be the ones before renumbering—those that GCC would ordinarily allocate. The registers which will actually be used in the assembler code, after renumbering, should not be marked with 1 in this vector.

Define this macro only if the target machine offers a way to optimize the treatment of leaf functions.

**LEAF_REG_REMAP**(regno)  
A C expression whose value is the register number to which regno should be renumbered, when a function is treated as a leaf function.

If regno is a register number which should not appear in a leaf function before renumbering, then the expression should yield −1, which will cause the compiler to abort.

Define this macro only if the target machine offers a way to optimize the treatment of leaf functions, and registers need to be renumbered to do this.

**TARGET_ASM_FUNCTION_PROLOGUE** and **TARGET_ASM_FUNCTION_EPILOGUE** must usually treat leaf functions specially. They can test the C variable current_function_is_leaf which is nonzero for leaf functions. current_function_is_leaf is set prior to local register allocation and is valid for the remaining compiler passes. They can also test the C variable current_function_uses_only_leaf_regs which is nonzero for leaf functions which only use leaf registers. current_function_uses_only_leaf_regs is valid after all passes that modify the instructions have been run and is only useful if **LEAF_REGISTERS** is defined.

### 18.7.5 Registers That Form a Stack

There are special features to handle computers where some of the “registers” form a stack. Stack registers are normally written by pushing onto the stack, and are numbered relative to the top of the stack.

Currently, GCC can only handle one group of stack-like registers, and they must be consecutively numbered. Furthermore, the existing support for stack-like registers is specific to the 80387 floating point coprocessor. If you have a new architecture that uses stack-like registers, you will need to do substantial work on ‘reg-stack.c’ and write your machine description to cooperate with it, as well as defining these macros.

**STACK_REGS**  
Define this if the machine has any stack-like registers.
STACK_REG_COVER_CLASS [Macro]

This is a cover class containing the stack registers. Define this if the machine has any
stack-like registers.

FIRST_STACK_REG [Macro]

The number of the first stack-like register. This one is the top of the stack.

LAST_STACK_REG [Macro]

The number of the last stack-like register. This one is the bottom of the stack.

18.8 Register Classes

On many machines, the numbered registers are not all equivalent. For example, certain
registers may not be allowed for indexed addressing; certain registers may not be allowed in
some instructions. These machine restrictions are described to the compiler using register
classes.

You define a number of register classes, giving each one a name and saying which of the
registers belong to it. Then you can specify register classes that are allowed as operands to
target instruction patterns.

In general, each register will belong to several classes. In fact, one class must be named
ALL_REGS and contain all the registers. Another class must be named NO_REGS and contain
no registers. Often the union of two classes will be another class; however, this is not
required.

One of the classes must be named GENERAL_REGS. There is nothing terribly special about
the name, but the operand constraint letters ‘r’ and ‘g’ specify this class. If GENERAL_REGS
is the same as ALL_REGS, just define it as a macro which expands to ALL_REGS.

Order the classes so that if class x is contained in class y then x has a lower class number
than y.

The way classes other than GENERAL_REGS are specified in operand constraints is through
machine-dependent operand constraint letters. You can define such letters to correspond
to various classes, then use them in operand constraints.

You must define the narrowest register classes for allocatable registers, so that each class
either has no subclasses, or that for some mode, the move cost between registers within the
class is cheaper than moving a register in the class to or from memory (see Section 18.16
[Costs], page 594).

You should define a class for the union of two classes whenever some instruction allows
both classes. For example, if an instruction allows either a floating point (coprocessor)
register or a general register for a certain operand, you should define a class FLOAT_OR_
GENERAL_REGS which includes both of them. Otherwise you will get suboptimal code, or
even internal compiler errors when reload cannot find a register in the class computed via
reg_class_subunion.

You must also specify certain redundant information about the register classes: for each
class, which classes contain it and which ones are contained in it; for each pair of classes,
the largest class contained in their union.

When a value occupying several consecutive registers is expected in a certain class, all
the registers used must belong to that class. Therefore, register classes cannot be used to
enforce a requirement for a register pair to start with an even-numbered register. The way to specify this requirement is with \texttt{TARGET\_HARD\_REGNO\_MODE\_OK}.

Register classes used for input-operands of bitwise-and or shift instructions have a special requirement: each such class must have, for each fixed-point machine mode, a subclass whose registers can transfer that mode to or from memory. For example, on some machines, the operations for single-byte values (\texttt{QImode}) are limited to certain registers. When this is so, each register class that is used in a bitwise-and or shift instruction must have a subclass consisting of registers from which single-byte values can be loaded or stored. This is so that \texttt{PREFERRED\_RELOAD\_CLASS} can always have a possible value to return.

\begin{verbatim}
enum reg_class
  An enumerated type that must be defined with all the register class names as enumerated values. \texttt{NO_REGS} must be first. \texttt{ALL_REGS} must be the last register class, followed by one more enumerated value, \texttt{LIM_REG_CLASSES}, which is not a register class but rather tells how many classes there are.

  Each register class has a number, which is the value of casting the class name to type \texttt{int}. The number serves as an index in many of the tables described below.

N_REG_CLASSES
  The number of distinct register classes, defined as follows:
  
  \#define N_REG_CLASSES (int) LIM_REG_CLASSES

REG_CLASS_NAMES
  An initializer containing the names of the register classes as C string constants. These names are used in writing some of the debugging dumps.

REG_CLASS_CONTENTS
  An initializer containing the contents of the register classes, as integers which are bit masks. The \texttt{n}th integer specifies the contents of class \texttt{n}. The way the integer \texttt{mask} is interpreted is that register \texttt{r} is in the class if \texttt{mask \& (1 << r)} is 1.

  When the machine has more than 32 registers, an integer does not suffice. Then the integers are replaced by sub-initializers, braced groupings containing several integers. Each sub-initializer must be suitable as an initializer for the type \texttt{HARD\_REG\_SET} which is defined in \texttt{'hard-reg-set.h'}. In this situation, the first integer in each sub-initializer corresponds to registers 0 through 31, the second integer to registers 32 through 63, and so on.

REGNO_REG_CLASS (regno)
  A C expression whose value is a register class containing hard register \texttt{regno}. In general there is more than one such class; choose a class which is \texttt{minimal}, meaning that no smaller class also contains the register.

BASE_REG_CLASS
  A macro whose definition is the name of the class to which a valid base register must belong. A base register is one used in an address which is the register value plus a displacement.
\end{verbatim}
MODE_BASE_REG_CLASS (mode)  
This is a variation of the BASE_REG_CLASS macro which allows the selection of a base 
register in a mode dependent manner. If mode is VOIDmode then it should return 
the same value as BASE_REG_CLASS.

MODE_BASE_REG_REG_CLASS (mode)  
A C expression whose value is the register class to which a valid base register must 
belong in order to be used in a base plus index register address. You should define 
this macro if base plus index addresses have different requirements than other base 
register uses.

MODE_CODE_BASE_REG_CLASS (mode, address_space, outer_code, 
index_code)  
A C expression whose value is the register class to which a valid base register for 
a memory reference in mode mode to address space address_space must belong. 
outer_code and index_code define the context in which the base register occurs. 
outer_code is the code of the immediately enclosing expression (MEM for the top level of 
an address, ADDRESS for something that occurs in an address_operand). index_code 
is the code of the corresponding index expression if outer_code is PLUS; SCRATCH 
otherwise.

INDEX_REG_CLASS  
A macro whose definition is the name of the class to which a valid index register must 
belong. An index register is one used in an address where its value is either multiplied 
by a scale factor or added to another register (as well as added to a displacement).

REGNO_OK_FOR_BASE_P (num)  
A C expression which is nonzero if register number num is suitable for use as a base 
register in operand addresses.

REGNO_MODE_OK_FOR_BASE_P (num, mode)  
A C expression that is just like REGNO_OK_FOR_BASE_P, except that that expression 
may examine the mode of the memory reference in mode. You should define this 
macro if the mode of the memory reference affects whether a register may be used as 
a base register. If you define this macro, the compiler will use it instead of REGNO_OK_ 
FOR_BASE_P. The mode may be VOIDmode for addresses that appear outside a MEM, 
i.e., as an address_operand.

REGNO_MODE_OK_FOR_REG_BASE_P (num, mode)  
A C expression which is nonzero if register number num is suitable for use as a base 
register in base plus index operand addresses, accessing memory in mode mode. It 
may be either a suitable hard register or a pseudo register that has been allocated 
such a hard register. You should define this macro if base plus index addresses have 
different requirements than other base register uses.

Use of this macro is deprecated; please use the more general REGNO_MODE_CODE_OK_ 
FOR_BASE_P.
**REGNO_MODE_CODE_OK_FOR_BASE_P** *(num, mode, address_space, outer_code, index_code)*

A C expression which is nonzero if register number *num* is suitable for use as a base register in operand addresses, accessing memory in mode *mode* in address space *address_space*. This is similar to **REGNO_MODE_OK_FOR_BASE_P**, except that that expression may examine the context in which the register appears in the memory reference. *outer_code* is the code of the immediately enclosing expression (MEM if at the top level of the address, ADDRESS for something that occurs in an *address_operand*). *index_code* is the code of the corresponding index expression if *outer_code* is PLUS; SCRATCH otherwise. The mode may be VOID*mode* for addresses that appear outside a MEM, i.e., as an *address_operand*.

**REGNO_OK_FOR_INDEX_P** *(num)*

A C expression which is nonzero if register number *num* is suitable for use as an index register in operand addresses. It may be either a suitable hard register or a pseudo register that has been allocated such a hard register.

The difference between an index register and a base register is that the index register may be scaled. If an address involves the sum of two registers, neither one of them scaled, then either one may be labeled the “base” and the other the “index”; but whichever labeling is used must fit the machine’s constraints of which registers may serve in each capacity. The compiler will try both labelings, looking for one that is valid, and will reload one or both registers only if neither labeling works.

**reg_class_t** TARGET_PREFERRED_RENAME_CLASS *(reg_class_t rclass)*

A target hook that places additional preference on the register class to use when it is necessary to rename a register in class *rclass* to another class, or perhaps NO_REGS, if no preferred register class is found or hook preferred_rename_class is not implemented. Sometimes returning a more restrictive class makes better code. For example, on ARM, thumb-2 instructions using LO_REGS may be smaller than instructions using GENERIC_REGS. By returning LO_REGS from preferred_rename_class, code size can be reduced.

**reg_class_t** TARGET_PREFERRED_RELOAD_CLASS *(rtx x, reg_class_t rclass)*

A target hook that places additional restrictions on the register class to use when it is necessary to copy value *x* into a register in class *rclass*. The value is a register class; perhaps *rclass*, or perhaps another, smaller class.

The default version of this hook always returns value of *rclass* argument. Sometimes returning a more restrictive class makes better code. For example, on the 68000, when *x* is an integer constant that is in range for a ‘moveq’ instruction, the value of this macro is always DATA_REGS as long as *rclass* includes the data registers. Requiring a data register guarantees that a ‘moveq’ will be used.

One case where TARGET_PREFERRED_RELOAD_CLASS must not return *rclass* is if *x* is a legitimate constant which cannot be loaded into some register class. By returning NO_REGS you can force *x* into a memory location. For example, rs6000 can load immediate values into general-purpose registers, but does not have an instruction...
for loading an immediate value into a floating-point register, so \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS} returns \texttt{NO\_REGS} when \texttt{x} is a floating-point constant. If the constant can't be loaded into any kind of register, code generation will be better if \texttt{TARGET\_LEGITIMATE\_CONSTANT\_P} makes the constant illegitimate instead of using \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS}.

If an insn has pseudos in it after register allocation, reload will go through the alternatives and call repeatedly \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS} to find the best one. Returning \texttt{NO\_REGS}, in this case, makes reload add a ! in front of the constraint: the x86 back-end uses this feature to discourage usage of 387 registers when math is done in the SSE registers (and vice versa).

\textbf{PREFERRED\_RELOAD\_CLASS} (\texttt{x}, \texttt{class}) \quad [\text{Macro}]
\begin{itemize}
  \item A C expression that places additional restrictions on the register class to use when it is necessary to copy value \texttt{x} into a register in class \texttt{class}. The value is a register class; perhaps \texttt{class}, or perhaps another, smaller class. On many machines, the following definition is safe:
\end{itemize}

\begin{verbatim}
#define PREFERRED_RELOAD_CLASS(X,CLASS) CLASS
\end{verbatim}

Sometimes returning a more restrictive class makes better code. For example, on the 68000, when \texttt{x} is an integer constant that is in range for a \texttt{moveq} instruction, the value of this macro is always \texttt{DATA\_REGS} as long as \texttt{class} includes the data registers. Requiring a data register guarantees that a \texttt{moveq} will be used.

One case where \texttt{PREFERRED\_RELOAD\_CLASS} must not return \texttt{class} is if \texttt{x} is a legitimate constant which cannot be loaded into some register class. By returning \texttt{NO\_REGS} you can force \texttt{x} into a memory location. For example, rs6000 can load immediate values into general-purpose registers, but does not have an instruction for loading an immediate value into a floating-point register, so \texttt{PREFERRED\_RELOAD\_CLASS} returns \texttt{NO\_REGS} when \texttt{x} is a floating-point constant. If the constant cannot be loaded into any kind of register, code generation will be better if \texttt{TARGET\_LEGITIMATE\_CONSTANT\_P} makes the constant illegitimate instead of using \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS}.

If an insn has pseudos in it after register allocation, reload will go through the alternatives and call repeatedly \texttt{PREFERRED\_RELOAD\_CLASS} to find the best one. Returning \texttt{NO\_REGS}, in this case, makes reload add a ! in front of the constraint: the x86 back-end uses this feature to discourage usage of 387 registers when math is done in the SSE registers (and vice versa).

\textbf{TARGET\_PREFERRED\_OUTPUT\_RELOAD\_CLASS} (\texttt{rtx x}, \texttt{reg\_class_t rclass}) \quad [\text{Target Hook}]
\begin{itemize}
  \item Like \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS}, but for output reloads instead of input reloads.
\end{itemize}

The default version of this hook always returns value of \texttt{rclass} argument.

You can also use \texttt{TARGET\_PREFERRED\_OUTPUT\_RELOAD\_CLASS} to discourage reload from using some alternatives, like \texttt{TARGET\_PREFERRED\_RELOAD\_CLASS}.

\textbf{LIMIT\_RELOAD\_CLASS} (\texttt{mode}, \texttt{class}) \quad [\text{Macro}]
\begin{itemize}
  \item A C expression that places additional restrictions on the register class to use when it is necessary to be able to hold a value of mode \texttt{mode} in a reload register for which class \texttt{class} would ordinarily be used.
\end{itemize}
Unlike `PREFERRED_RELOAD_CLASS`, this macro should be used when there are certain modes that simply cannot go in certain reload classes.

The value is a register class; perhaps `class`, or perhaps another, smaller class.

Don’t define this macro unless the target machine has limitations which require the macro to do something nontrivial.

```c
reg_class_t TARGET_SECONDARY_RELOAD (bool in_p, rtx x,  
  reg_class_t reload_class, machine_mode reload_mode,  
  secondary_reload_info *sri)
```

Many machines have some registers that cannot be copied directly to or from memory or even from other types of registers. An example is the ‘MQ’ register, which on most machines, can only be copied to or from general registers, but not memory. Below, we shall be using the term ‘intermediate register’ when a move operation cannot be performed directly, but has to be done by copying the source into the intermediate register first, and then copying the intermediate register to the destination. An intermediate register always has the same mode as source and destination. Since it holds the actual value being copied, reload might apply optimizations to re-use an intermediate register and eliding the copy from the source when it can determine that the intermediate register still holds the required value.

Another kind of secondary reload is required on some machines which allow copying all registers to and from memory, but require a scratch register for stores to some memory locations (e.g., those with symbolic address on the RT, and those with certain symbolic address on the SPARC when compiling PIC). Scratch registers need not have the same mode as the value being copied, and usually hold a different value than that being copied. Special patterns in the md file are needed to describe how the copy is performed with the help of the scratch register; these patterns also describe the number, register class(es) and mode(s) of the scratch register(s).

In some cases, both an intermediate and a scratch register are required.

For input reloads, this target hook is called with nonzero `in_p`, and `x` is an `rtx` that needs to be copied to a register of class `reload_class` in `reload_mode`. For output reloads, this target hook is called with zero `in_p`, and a register of class `reload_class` needs to be copied to `rtx x` in `reload_mode`.

If copying a register of `reload_class` from/to `x` requires an intermediate register, the hook `secondary_reload` should return the register class required for this intermediate register. If no intermediate register is required, it should return `NO_REGS`. If more than one intermediate register is required, describe the one that is closest in the copy chain to the reload register.

If scratch registers are needed, you also have to describe how to perform the copy from/to the reload register to/from this closest intermediate register. Or if no intermediate register is required, but still a scratch register is needed, describe the copy from/to the reload register to/from the reload operand `x`.

You do this by setting `sri->icode` to the instruction code of a pattern in the md file which performs the move. Operands 0 and 1 are the output and input of this copy, respectively. Operands from operand 2 onward are for scratch operands. These scratch operands must have a mode, and a single-register-class output constraint.
When an intermediate register is used, the `secondary_reload` hook will be called again to determine how to copy the intermediate register to/from the reload operand \( x \), so your hook must also have code to handle the register class of the intermediate operand.

\( x \) might be a pseudo-register or a `subreg` of a pseudo-register, which could either be in a hard register or in memory. Use `true_regnum` to find out; it will return \(-1\) if the pseudo is in memory and the hard register number if it is in a register.

Scratch operands in memory (constraint "=m" / "=&m") are currently not supported. For the time being, you will have to continue to use `TARGET_SECONDARY_MEMORY_NEEDED` for that purpose.

`copy_cost` also uses this target hook to find out how values are copied. If you want it to include some extra cost for the need to allocate (a) scratch register(s), set `sri->extra_cost` to the additional cost. Or if two dependent moves are supposed to have a lower cost than the sum of the individual moves due to expected fortuitous scheduling and/or special forwarding logic, you can set `sri->extra_cost` to a negative amount.

```
SECONDARY_RELOAD_CLASS (class, mode, x)  [Macro]
SECONDARY_INPUT_RELOAD_CLASS (class, mode, x)  [Macro]
SECONDARY_OUTPUT_RELOAD_CLASS (class, mode, x)  [Macro]
```

These macros are obsolete, new ports should use the target hook `TARGET_SECONDARY_RELOAD` instead.

These are obsolete macros, replaced by the `TARGET_SECONDARY_RELOAD` target hook. Older ports still define these macros to indicate to the reload phase that it may need to allocate at least one register for a reload in addition to the register to contain the data. Specifically, if copying \( x \) to a register `class` in `mode` requires an intermediate register, you were supposed to define `SECONDARY_INPUT_RELOAD_CLASS` to return the largest register class all of whose registers can be used as intermediate registers or scratch registers.

If copying a register `class` in `mode` to \( x \) requires an intermediate or scratch register, `SECONDARY_OUTPUT_RELOAD_CLASS` was supposed to be defined to define to return the largest register class required. If the requirements for input and output reloads were the same, the macro `SECONDARY_RELOAD_CLASS` should have been used instead of defining both macros identically.

The values returned by these macros are often `GENERAL_REGS`. Return `NO_REGS` if no spare register is needed; i.e., if \( x \) can be directly copied to or from a register of `class` in `mode` without requiring a scratch register. Do not define this macro if it would always return `NO_REGS`.

If a scratch register is required (either with or without an intermediate register), you were supposed to define patterns for `reload_inm` or `reload_outm`, as required (see Section 17.9 [Standard Names], page 405. These patterns, which were normally implemented with a `define_expand`, should be similar to the ‘movm’ patterns, except that operand 2 is the scratch register.

These patterns need constraints for the reload register and scratch register that contain a single register class. If the original reload register (whose class is `class`) can meet the constraint given in the pattern, the value returned by these macros is used
for the class of the scratch register. Otherwise, two additional reload registers are required. Their classes are obtained from the constraints in the insn pattern.

x might be a pseudo-register or a subreg of a pseudo-register, which could either be in a hard register or in memory. Use true_regnum to find out; it will return −1 if the pseudo is in memory and the hard register number if it is in a register.

These macros should not be used in the case where a particular class of registers can only be copied to memory and not to another class of registers. In that case, secondary reload registers are not needed and would not be helpful. Instead, a stack location must be used to perform the copy and the movm pattern should use memory as an intermediate storage. This case often occurs between floating-point and general registers.

```c
bool TARGET_SECONDARY_MEMORY_NEEDED (machine_mode mode, 
    reg_class_t class1, reg_class_t class2)
```

Certain machines have the property that some registers cannot be copied to some other registers without using memory. Define this hook on those machines to return true if objects of mode m in registers of class1 can only be copied to registers of class class2 by storing a register of class1 into memory and loading that memory location into a register of class2. The default definition returns false for all inputs.

```c
SECONDARY_MEMORY_NEEDED_RTX (mode)
```

Normally when TARGET_SECONDARY_MEMORY_NEEDED is defined, the compiler allocates a stack slot for a memory location needed for register copies. If this macro is defined, the compiler instead uses the memory location defined by this macro.

Do not define this macro if you do not define TARGET_SECONDARY_MEMORY_NEEDED.

```c
machine_mode TARGET_SECONDARY_MEMORY_NEEDED_MODE
    (machine_mode mode)
```

If TARGET_SECONDARY_MEMORY_NEEDED tells the compiler to use memory when moving between two particular registers of mode mode, this hook specifies the mode that the memory should have.

The default depends on TARGET_LRA_P. Without LRA, the default is to use a word-sized mode for integral modes that are smaller than a word. This is right thing to do on most machines because it ensures that all bits of the register are copied and prevents accesses to the registers in a narrower mode, which some machines prohibit for floating-point registers.

However, this default behavior is not correct on some machines, such as the DEC Alpha, that store short integers in floating-point registers differently than in integer registers. On those machines, the default widening will not work correctly and you must define this hook to suppress that widening in some cases. See the file `alpha.c` for details.

With LRA, the default is to use mode unmodified.

```c
void TARGET_SELECT_EARLY_REMAT_Modes (sbitmap modes)
```

On some targets, certain modes cannot be held in registers around a standard ABI call and are relatively expensive to spill to the stack. The early rematerialization
pass can help in such cases by aggressively recomputing values after calls, so that they don’t need to be spilled.

This hook returns the set of such modes by setting the associated bits in modes. The default implementation selects no modes, which has the effect of disabling the early rematerialization pass.

```c
bool TARGET_CLASSLIKELY_SPIPPLED_P (reg_class_t rclass)  // Target Hook
A target hook which returns true if pseudos that have been assigned to registers of class rclass would likely be spilled because registers of rclass are needed for spill registers.

The default version of this target hook returns true if rclass has exactly one register and false otherwise. On most machines, this default should be used. For generally register-starved machines, such as i386, or machines with right register constraints, such as SH, this hook can be used to avoid excessive spilling.

This hook is also used by some of the global intra-procedural code transformations to throttle code motion, to avoid increasing register pressure.
```

```c
unsigned char TARGETCLASSMAXNREGS (reg_class_t rclass, machine_mode mode)  // Target Hook
A target hook returns the maximum number of consecutive registers of class rclass needed to hold a value of mode mode.

This is closely related to the macro TARGET_HARD_REGNO_NREGS. In fact, the value returned by TARGETCLASSMAXNREGS (rclass, mode) target hook should be the maximum value of TARGET_HARD_REGNO_NREGS (regno, mode) for all regno values in the class rclass.

This target hook helps control the handling of multiple-word values in the reload pass.

The default version of this target hook returns the size of mode in words.
```

```c
CLASS_MAX_NREGS (class, mode)  // Macro
A C expression for the maximum number of consecutive registers of class class needed to hold a value of mode mode.

This is closely related to the macro TARGET_HARD_REGNO_NREGS. In fact, the value of the macro CLASS_MAX_NREGS (class, mode) should be the maximum value of TARGET_HARD_REGNO_NREGS (regno, mode) for all regno values in the class class.

This macro helps control the handling of multiple-word values in the reload pass.
```

```c
bool TARGET_CANCHANGE_MODECLASS (machine_mode from, machine_mode to, reg_class_t rclass)  // Target Hook
This hook returns true if it is possible to bitcast values held in registers of class rclass from mode from to mode to and if doing so preserves the low-order bits that are common to both modes. The result is only meaningful if rclass has registers that can hold both from and to. The default implementation returns true.

As an example of when such bitcasting is invalid, loading 32-bit integer or floating-point objects into floating-point registers on Alpha extends them to 64 bits. Therefore loading a 64-bit object and then storing it as a 32-bit object does not store the low-order 32 bits, as would be the case for a normal register. Therefore, ‘alpha.h’ defines TARGET_CANCHANGE_MODECLASS to return:
(GET_MODE_SIZE (from) == GET_MODE_SIZE (to) || !reg_classes_intersect_p (FLOAT_REGS, rclass))

Even if storing from a register in mode \textit{to} would be valid, if both \textit{from} and \textit{raw_reg_mode} for \textit{rclass} are wider than \textit{word_mode}, then we must prevent \textit{to} narrowing the mode. This happens when the middle-end assumes that it can load or store pieces of an \textit{N}-word pseudo, and that the pseudo will eventually be allocated to \textit{N word_mode} hard registers. Failure to prevent this kind of mode change will result in the entire \textit{raw_reg_mode} being modified instead of the partial value that the middle-end intended.

\begin{verbatim}
reg_class_t TARGET_IRA_CHANGE_PSEUDO_ALLOCNCLASS (int, reg_class_t, reg_class_t)
A target hook which can change allocno class for given pseudo from allocno and best class calculated by IRA.
The default version of this target hook always returns given class.
\end{verbatim}

\begin{verbatim}
bool TARGET_LRA_P (void)
A target hook which returns true if we use LRA instead of reload pass.
The default version of this target hook returns true. New ports should use LRA, and existing ports are encouraged to convert.
\end{verbatim}

\begin{verbatim}
int TARGET_REGISTER_PRIORITY (int)
A target hook which returns the register priority number to which the register hard_regno belongs to. The bigger the number, the more preferable the hard register usage (when all other conditions are the same). This hook can be used to prefer some hard register over others in LRA. For example, some x86-64 register usage needs additional prefix which makes instructions longer. The hook can return lower priority number for such registers make them less favorable and as result making the generated code smaller.
The default version of this target hook returns always zero.
\end{verbatim}

\begin{verbatim}
bool TARGET_REGISTER_USAGE_LEVELING_P (void)
A target hook which returns true if we need register usage leveling. That means if a few hard registers are equally good for the assignment, we choose the least used hard register. The register usage leveling may be profitable for some targets. Don’t use the usage leveling for targets with conditional execution or targets with big register files as it hurts if-conversion and cross-jumping optimizations.
The default version of this target hook returns always false.
\end{verbatim}

\begin{verbatim}
bool TARGET_DIFFERENT_ADDR_DISPLACEMENT_P (void)
A target hook which returns true if an address with the same structure can have different maximal legitimate displacement. For example, the displacement can depend on memory mode or on operand combinations in the insn.
The default version of this target hook returns always false.
\end{verbatim}

\begin{verbatim}
bool TARGET_CANNOT_SUBSTITUTE_MEM_EQUIV_P (rtx subst)
A target hook which returns \textit{true} if \textit{subst} can’t substitute safely pseudos with equivalent memory values during register allocation. The default version of this target
\end{verbatim}
hook returns `false`. On most machines, this default should be used. For generally machines with non orthogonal register usage for addressing, such as SH, this hook can be used to avoid excessive spilling.

```c
bool TARGET_LEGITIMIZE_ADDRESS_DISPLACEMENT (rtx *offset1, rtx *offset2, poly_int64 orig_offset, machine_mode mode)
```
This hook tries to split address offset `orig_offset` into two parts: one that should be added to the base address to create a local anchor point, and an additional offset that can be applied to the anchor to address a value of mode `mode`. The idea is that the local anchor could be shared by other accesses to nearby locations.

The hook returns true if it succeeds, storing the offset of the anchor from the base in `offset1` and the offset of the final address from the anchor in `offset2`. The default implementation returns false.

```c
reg_class_t TARGET_SPILL_CLASS (reg_class_t, machine_mode)
```
This hook defines a class of registers which could be used for spilling pseudos of the given mode and class, or `NO_REGS` if only memory should be used. Not defining this hook is equivalent to returning `NO_REGS` for all inputs.

```c
bool TARGET_ADDITIONAL_ALLOCNO_CLASS_P (reg_class_t)
```
This hook should return `true` if given class of registers should be an allocno class in any way. Usually RA uses only one register class from all classes containing the same register set. In some complicated cases, you need to have two or more such classes as allocno ones for RA correct work. Not defining this hook is equivalent to returning `false` for all inputs.

```c
scalar_int_mode TARGET_CSTORE_MODE (enum insn_code icode)
```
This hook defines the machine mode to use for the boolean result of conditional store patterns. The `ICODE` argument is the instruction code for the cstore being performed. Not defining this hook is the same as accepting the mode encoded into operand 0 of the cstore expander patterns.

```c
int TARGET_COMPUTE_PRESSURE_CLASSES (enum reg_class *pressure_classes)
```
A target hook which lets a backend compute the set of pressure classes to be used by those optimization passes which take register pressure into account, as opposed to letting IRA compute them. It returns the number of register classes stored in the array `pressure_classes`.

## 18.9 Stack Layout and Calling Conventions
This describes the stack layout and calling conventions.

### 18.9.1 Basic Stack Layout
Here is the basic stack layout.

```c
STACK_GROWS_DOWNWARD
```
Define this macro to be true if pushing a word onto the stack moves the stack pointer to a smaller address, and false otherwise.
This macro defines the operation used when something is pushed on the stack. In RTL, a push operation will be 
\( \text{set (mem (STACK_PUSH_CODE (reg sp))) ...} \)

The choices are \texttt{PRE\_DEC}, \texttt{POST\_DEC}, \texttt{PRE\_INC}, and \texttt{POST\_INC}. Which of these is 
correct depends on the stack direction and on whether the stack pointer points to the 
last item on the stack or whether it points to the space for the next item on the stack.
The default is \texttt{PRE\_DEC} when \texttt{STACK\_GROWS\_DOWNWARD} is true, which is almost always 
right, and \texttt{PRE\_INC} otherwise, which is often wrong.

Define this macro to nonzero value if the addresses of local variable slots are at 
negative offsets from the frame pointer.

Define this macro if successive arguments to a function occupy decreasing addresses 
on the stack.

This hook returns the offset from the frame pointer to the first local variable slot 
to be allocated. If \texttt{FRAME\_GROWS\_DOWNWARD}, it is the offset to \textit{end} of the first slot 
allocated, otherwise it is the offset to \textit{beginning} of the first slot allocated. The default 
implementation returns 0.

Define to zero to disable final alignment of the stack during reload. The nonzero 
default for this macro is suitable for most ports.

On ports where \texttt{TARGET\_STARTING\_FRAME\_OFFSET} is nonzero or where there is a reg-
ister save block following the local block that doesn’t require alignment to \texttt{STACK\_ 
BOUNDARY}, it may be beneficial to disable stack alignment and do it in the backend.

Offset from the stack pointer register to the first location at which outgoing arguments 
are placed. If not specified, the default value of zero is used. This is the proper value 
for most machines.

If \texttt{ARGS\_GROW\_DOWNWARD}, this is the offset to the location above the first location at 
which outgoing arguments are placed.

Offset from the argument pointer register to the first argument’s address. On some 
machines it may depend on the data type of the function.

If \texttt{ARGS\_GROW\_DOWNWARD}, this is the offset to the location above the first argument’s 
address.

Offset from the stack pointer register to an item dynamically allocated on the stack, 
e.g., by \texttt{alloca}.

The default value for this macro is \texttt{STACK\_POINTER\_OFFSET} plus the length of the 
outgoing arguments. The default is correct for most machines. See ‘\texttt{function.c}’ for 
details.
**INITIAL_FRAME_ADDRESS_RTX** [Macro]
A C expression whose value is RTL representing the address of the initial stack frame. This address is passed to RETURN_ADDR_RTX and DYNAMIC_CHAIN_ADDRESS. If you don’t define this macro, a reasonable default value will be used. Define this macro in order to make frame pointer elimination work in the presence of __builtin_frame_address (count) and __builtin_return_address (count) for count not equal to zero.

**DYNAMIC_CHAIN_ADDRESS (frameaddr)** [Macro]
A C expression whose value is RTL representing the address in a stack frame where the pointer to the caller’s frame is stored. Assume that frameaddr is an RTL expression for the address of the stack frame itself.

If you don’t define this macro, the default is to return the value of frameaddr—that is, the stack frame address is also the address of the stack word that points to the previous frame.

**SETUP_FRAME_ADDRESSES** [Macro]
A C expression that produces the machine-specific code to setup the stack so that arbitrary frames can be accessed. For example, on the SPARC, we must flush all of the register windows to the stack before we can access arbitrary stack frames. You will seldom need to define this macro. The default is to do nothing.

**rtx TARGET_BUILTIN_SETJMP_FRAME_VALUE (void)** [Target Hook]
This target hook should return an rtx that is used to store the address of the current frame into the built in setjmp buffer. The default value, virtual_stack_vars_rtx, is correct for most machines. One reason you may need to define this target hook is if hard_frame_pointer_rtx is the appropriate value on your machine.

**FRAME_ADDR_RTX (frameaddr)** [Macro]
A C expression whose value is RTL representing the value of the frame address for the current frame. frameaddr is the frame pointer of the current frame. This is used for __builtin_frame_address. You need only define this macro if the frame address is not the same as the frame pointer. Most machines do not need to define it.

**RETURN_ADDR_RTX (count, frameaddr)** [Macro]
A C expression whose value is RTL representing the value of the return address for the frame count steps up from the current frame, after the prologue. frameaddr is the frame pointer of the count frame, or the frame pointer of the count – 1 frame if RETURN_ADDR_IN_PREVIOUS_FRAME is nonzero.

The value of the expression must always be the correct address when count is zero, but may be NULL_RTX if there is no way to determine the return address of other frames.

**RETURN_ADDR_IN_PREVIOUS_FRAME** [Macro]
Define this macro to nonzero value if the return address of a particular stack frame is accessed from the frame pointer of the previous stack frame. The zero default for this macro is suitable for most ports.
INCOMING_RETURN_ADDR_RTX

A C expression whose value is RTL representing the location of the incoming return address at the beginning of any function, before the prologue. This RTL is either a REG, indicating that the return value is saved in ‘REG’, or a MEM representing a location in the stack.

You only need to define this macro if you want to support call frame debugging information like that provided by DWARF 2.

If this RTL is a REG, you should also define DWARF_FRAME_RETURN_COLUMN to DWARF_FRAME_REGNUM (REGNO).

DWARF_ALT_FRAME_RETURN_COLUMN

A C expression whose value is an integer giving a DWARF 2 column number that may be used as an alternative return column. The column must not correspond to any gcc hard register (that is, it must not be in the range of DWARF_FRAME_REGNUM).

This macro can be useful if DWARF_FRAME_RETURN_COLUMN is set to a general register, but an alternative column needs to be used for signal frames. Some targets have also used different frame return columns over time.

DWARF_ZERO_REG

A C expression whose value is an integer giving a DWARF 2 register number that is considered to always have the value zero. This should only be defined if the target has an architected zero register, and someone decided it was a good idea to use that register number to terminate the stack backtrace. New ports should avoid this.

void TARGET_DWARF_HANDLE_FRAME_UNSPEC (const char *label, rtx pattern, int index)

This target hook allows the backend to emit frame-related insns that contain UNSPECs or UNSPEC_VOLATILEs. The DWARF 2 call frame debugging info engine will invoke it on insns of the form

(set (reg) (unspec [[...] UNSPEC_INDEX])

and

(set (reg) (unspec_volatile [[...] UNSPECV_INDEX])

to let the backend emit the call frame instructions. label is the CFI label attached to the insn, pattern is the pattern of the insn and index is UNSPEC_INDEX or UNSPECV_INDEX.

unsigned int TARGET_DWARF_POLY_INDETERMINATE_VALUE (unsigned int i, unsigned int *factor, int *offset)

Express the value of poly_int indeterminate i as a DWARF expression, with i counting from 1. Return the number of a DWARF register R and set ‘*factor’ and ‘*offset’ such that the value of the indeterminate is:

value_of(R) / factor - offset

A target only needs to define this hook if it sets ‘NUM_POLY_INT_COEFFS’ to a value greater than 1.

INCOMING_FRAME_SP_OFFSET

A C expression whose value is an integer giving the offset, in bytes, from the value of the stack pointer register to the top of the stack frame at the beginning of any
function, before the prologue. The top of the frame is defined to be the value of the
stack pointer in the previous frame, just before the call instruction.

You only need to define this macro if you want to support call frame debugging
information like that provided by DWARF 2.

DEFAULT_INCOMING_FRAME_SP_OFFSET [Macro]
Like INCOMING_FRAME_SP_OFFSET, but must be the same for all functions of the same
ABI, and when using GAS .cfi_• directives must also agree with the default CFI
GAS emits. Define this macro only if INCOMING_FRAME_SP_OFFSET can have different
values between different functions of the same ABI or when INCOMING_FRAME_SP_
OFFSET does not agree with GAS default CFI.

ARG_POINTER_CFA_OFFSET (fundecl) [Macro]
A C expression whose value is an integer giving the offset, in bytes, from the argument
pointer to the canonical frame address (cfa). The final value should coincide with that
calculated by INCOMING_FRAME_SP_OFFSET. Which is unfortunately not usable during
virtual register instantiation.

The default value for this macro is FIRST_PARM_OFFSET (fundecl) + ctrl-
>args.pretend_args_size, which is correct for most machines; in general, the
arguments are found immediately before the stack frame. Note that this is not the
case on some targets that save registers into the caller’s frame, such as SPARC and
rs6000, and so such targets need to define this macro.

You only need to define this macro if the default is incorrect, and you want to support
call frame debugging information like that provided by DWARF 2.

FRAME_POINTER_CFA_OFFSET (fundecl) [Macro]
If defined, a C expression whose value is an integer giving the offset in bytes from the
frame pointer to the canonical frame address (cfa). The final value should coincide
with that calculated by INCOMING_FRAME_SP_OFFSET.

Normally the CFA is calculated as an offset from the argument pointer, via ARG_
POINTER_CFA_OFFSET, but if the argument pointer is variable due to the ABI, this
may not be possible. If this macro is defined, it implies that the virtual register
instantiation should be based on the frame pointer instead of the argument pointer.

Only one of FRAME_POINTER_CFA_OFFSET and ARG_POINTER_CFA_OFFSET should be
defined.

CFA_FRAME_BASE_OFFSET (fundecl) [Macro]
If defined, a C expression whose value is an integer giving the offset in bytes from the
canonical frame address (cfa) to the frame base used in DWARF 2 debug information.
The default is zero. A different value may reduce the size of debug information on
some ports.

18.9.2 Exception Handling Support

EH_RETURN_DATA_REGNO (N) [Macro]
A C expression whose value is the Nth register number used for data by exception
handlers, or INVALID_REGNUM if fewer than N registers are usable.
The exception handling library routines communicate with the exception handlers via a set of agreed upon registers. Ideally these registers should be call-clobbered; it is possible to use call-saved registers, but may negatively impact code size. The target must support at least 2 data registers, but should define 4 if there are enough free registers.

You must define this macro if you want to support call frame exception handling like that provided by DWARF 2.

**EH_RETURN_STACKADJ_RTX**

A C expression whose value is RTL representing a location in which to store a stack adjustment to be applied before function return. This is used to unwind the stack to an exception handler’s call frame. It will be assigned zero on code paths that return normally.

Typically this is a call-clobbered hard register that is otherwise untouched by the epilogue, but could also be a stack slot.

Do not define this macro if the stack pointer is saved and restored by the regular prolog and epilog code in the call frame itself; in this case, the exception handling library routines will update the stack location to be restored in place. Otherwise, you must define this macro if you want to support call frame exception handling like that provided by DWARF 2.

**EH_RETURN_HANDLER_RTX**

A C expression whose value is RTL representing a location in which to store the address of an exception handler to which we should return. It will not be assigned on code paths that return normally.

Typically this is the location in the call frame at which the normal return address is stored. For targets that return by popping an address off the stack, this might be a memory address just below the target call frame rather than inside the current call frame. If defined, **EH_RETURN_STACKADJ_RTX** will have already been assigned, so it may be used to calculate the location of the target call frame.

Some targets have more complex requirements than storing to an address calculable during initial code generation. In that case the **eh_return** instruction pattern should be used instead.

If you want to support call frame exception handling, you must define either this macro or the **eh_return** instruction pattern.

**RETURN_ADDR_OFFSET**

If defined, an integer-valued C expression for which rtl will be generated to add it to the exception handler address before it is searched in the exception handling tables, and to subtract it again from the address before using it to return to the exception handler.

**ASM_PREFERRED_EH_DATA_FORMAT**

This macro chooses the encoding of pointers embedded in the exception handling sections. If at all possible, this should be defined such that the exception handling section will not require dynamic relocations, and so may be read-only.
code is 0 for data, 1 for code labels, 2 for function pointers. global is true if the symbol may be affected by dynamic relocations. The macro should return a combination of the DW_EH_PE_* defines as found in ‘dwarf2.h’.

If this macro is not defined, pointers will not be encoded but represented directly.

**ASM_MAYBE_OUTPUT_ENCODED_ADDR RTX** *(file, encoding, size, addr, done)*

This macro allows the target to emit whatever special magic is required to represent the encoding chosen by ASM_PREFERRED_EH_DATA_FORMAT. Generic code takes care of pc-relative and indirect encodings; this must be defined if the target uses text-relative or data-relative encodings.

This is a C statement that branches to done if the format was handled. encoding is the format chosen, size is the number of bytes that the format occupies, addr is the SYMBOL_REF to be emitted.

**MD_FALLBACK_FRAME_STATE_FOR** *(context, fs)*

This macro allows the target to add CPU and operating system specific code to the call-frame unwinder for use when there is no unwind data available. The most common reason to implement this macro is to unwind through signal frames.

This macro is called from uw_frame_state_for in ‘unwind-dw2.c’, ‘unwind-dw2-xtensa.c’ and ‘unwind-ia64.c’. context is an _Unwind_Context; fs is an _Unwind_FrameState. Examine context->ra for the address of the code being executed and context->cfa for the stack pointer value. If the frame can be decoded, the register save addresses should be updated in fs and the macro should evaluate to _URC_NO_REASON. If the frame cannot be decoded, the macro should evaluate to _URC_END_OF_STACK.

For proper signal handling in Java this macro is accompanied by MAKE_THROW_FRAME, defined in ‘libjava/include/*-signal.h’ headers.

**MD_HANDLE_UNWABI** *(context, fs)*

This macro allows the target to add operating system specific code to the call-frame unwinder to handle the IA-64 .unwabi unwinding directive, usually used for signal or interrupt frames.

This macro is called from uw_update_context in libgcc’s ‘unwind-ia64.c’. context is an _Unwind_Context; fs is an _Unwind_FrameState. Examine fs->unwabi for the abi and context in the .unwabi directive. If the .unwabi directive can be handled, the register save addresses should be updated in fs.

**TARGET_USES_WEAK_UNWIND_INFO**

A C expression that evaluates to true if the target requires unwind info to be given comdat linkage. Define it to be 1 if comdat linkage is necessary. The default is 0.

**18.9.3 Specifying How Stack Checking is Done**

GCC will check that stack references are within the boundaries of the stack, if the option ‘-fstack-check’ is specified, in one of three ways:

1. If the value of the STACK_CHECK_BUILTIN macro is nonzero, GCC will assume that you have arranged for full stack checking to be done at appropriate places in the configuration files. GCC will not do other special processing.

---

*Note: The above text is a transcription of the content from the GNU Compiler Collection (GCC) Internals document. It has been formatted for readability and clarity. It may not be an exact representation of the original document due to the limitations of text-based transcription.*
2. If \texttt{STACK\_CHECK\_BUILTIN} is zero and the value of the \texttt{STACK\_CHECK\_STATIC\_BUILTIN} macro is nonzero, GCC will assume that you have arranged for static stack checking (checking of the static stack frame of functions) to be done at appropriate places in the configuration files. GCC will only emit code to do dynamic stack checking (checking on dynamic stack allocations) using the third approach below.

3. If neither of the above are true, GCC will generate code to periodically “probe” the stack pointer using the values of the macros defined below.

If neither \texttt{STACK\_CHECK\_BUILTIN} nor \texttt{STACK\_CHECK\_STATIC\_BUILTIN} is defined, GCC will change its allocation strategy for large objects if the option ‘\texttt{-fstack-check}’ is specified: they will always be allocated dynamically if their size exceeds \texttt{STACK\_CHECK\_MAX\_VAR\_SIZE} bytes.

\[\text{Macro}\]

\texttt{STACK\_CHECK\_BUILTIN}
A nonzero value if stack checking is done by the configuration files in a machine-dependent manner. You should define this macro if stack checking is required by the ABI of your machine or if you would like to do stack checking in some more efficient way than the generic approach. The default value of this macro is zero.

\[\text{Macro}\]

\texttt{STACK\_CHECK\_STATIC\_BUILTIN}
A nonzero value if static stack checking is done by the configuration files in a machine-dependent manner. You should define this macro if you would like to do static stack checking in some more efficient way than the generic approach. The default value of this macro is zero.

\[\text{Macro}\]

\texttt{STACK\_CHECK\_PROBE\_INTERVAL\_EXP}
An integer specifying the interval at which GCC must generate stack probe instructions, defined as 2 raised to this integer. You will normally define this macro so that the interval be no larger than the size of the “guard pages” at the end of a stack area. The default value of 12 (4096-byte interval) is suitable for most systems.

\[\text{Macro}\]

\texttt{STACK\_CHECK\_MOVING\_SP}
An integer which is nonzero if GCC should move the stack pointer page by page when doing probes. This can be necessary on systems where the stack pointer contains the bottom address of the memory area accessible to the executing thread at any point in time. In this situation an alternate signal stack is required in order to be able to recover from a stack overflow. The default value of this macro is zero.

\[\text{Macro}\]

\texttt{STACK\_CHECK\_PROTECT}
The number of bytes of stack needed to recover from a stack overflow, for languages where such a recovery is supported. The default value of 4KB/8KB with the \texttt{setjmp/longjmp}-based exception handling mechanism and 8KB/12KB with other exception handling mechanisms should be adequate for most architectures and operating systems.

The following macros are relevant only if neither \texttt{STACK\_CHECK\_BUILTIN} nor \texttt{STACK\_CHECK\_STATIC\_BUILTIN} is defined; you can omit them altogether in the opposite case.
STACK_CHECK_MAX_FRAME_SIZE [Macro]
The maximum size of a stack frame, in bytes. GCC will generate probe instructions in non-leaf functions to ensure at least this many bytes of stack are available. If a stack frame is larger than this size, stack checking will not be reliable and GCC will issue a warning. The default is chosen so that GCC only generates one instruction on most systems. You should normally not change the default value of this macro.

STACK_CHECK_FIXED_FRAME_SIZE [Macro]
GCC uses this value to generate the above warning message. It represents the amount of fixed frame used by a function, not including space for any callee-saved registers, temporaries and user variables. You need only specify an upper bound for this amount and will normally use the default of four words.

STACK_CHECK_MAX_VAR_SIZE [Macro]
The maximum size, in bytes, of an object that GCC will place in the fixed area of the stack frame when the user specifies `-fstack-check`. GCC computed the default from the values of the above macros and you will normally not need to override that default.

HOST_WIDE_INT [Target Hook]
TARGET_STACK_CLASH_PROTECTION_ALLOCA_PROBE_RANGE (void)
Some targets have an ABI defined interval for which no probing needs to be done. When a probe does need to be done this same interval is used as the probe distance up when doing stack clash protection for alloca. On such targets this value can be set to override the default probing up interval. Define this variable to return nonzero if such a probe range is required or zero otherwise. Defining this hook also requires your functions which make use of alloca to have at least 8 byes of outgoing arguments. If this is not the case the stack will be corrupted. You need not define this macro if it would always have the value zero.

18.9.4 Registers That Address the Stack Frame
This discusses registers that address the stack frame.

STACK_POINTER_REGNUM [Macro]
The register number of the stack pointer register, which must also be a fixed register according to FIXED_REGISTERS. On most machines, the hardware determines which register this is.

FRAME_POINTER_REGNUM [Macro]
The register number of the frame pointer register, which is used to access automatic variables in the stack frame. On some machines, the hardware determines which register this is. On other machines, you can choose any register you wish for this purpose.

HARD_FRAME_POINTER_REGNUM [Macro]
On some machines the offset between the frame pointer and starting offset of the automatic variables is not known until after register allocation has been done (for example, because the saved registers are between these two locations). On those
machines, define `FRAME_POINTER_REGNUM` the number of a special, fixed register to be used internally until the offset is known, and define `HARD_FRAME_POINTER_REGNUM` to be the actual hard register number used for the frame pointer.

You should define this macro only in the very rare circumstances when it is not possible to calculate the offset between the frame pointer and the automatic variables until after register allocation has been completed. When this macro is defined, you must also indicate in your definition of `ELIMINABLE_REGS` how to eliminate `FRAME_POINTER_REGNUM` into either `HARD_FRAME_POINTER_REGNUM` or `STACK_POINTER_REGNUM`.

Do not define this macro if it would be the same as `FRAME_POINTER_REGNUM`.

ARG_POINTER_REGNUM

The register number of the arg pointer register, which is used to access the function’s argument list. On some machines, this is the same as the frame pointer register. On some machines, the hardware determines which register this is. On other machines, you can choose any register you wish for this purpose. If this is not the same register as the frame pointer register, then you must mark it as a fixed register according to `FIXED_REGISTERS`, or arrange to be able to eliminate it (see Section 18.9.5 [Elimination], page 551).

HARD_FRAME_POINTER_IS_FRAME_POINTER

Define this to a preprocessor constant that is nonzero if `hard_frame_pointer_rtx` and `frame_pointer_rtx` should be the same. The default definition is `(HARD_FRAME_POINTER_REGNUM == FRAME_POINTER_REGNUM)’; you only need to define this macro if that definition is not suitable for use in preprocessor conditionals.

HARD_FRAME_POINTER_IS_ARG_POINTER

Define this to a preprocessor constant that is nonzero if `hard_frame_pointer_rtx` and `arg_pointer_rtx` should be the same. The default definition is `(HARD_FRAME_POINTER_REGNUM == ARG_POINTER_REGNUM)’; you only need to define this macro if that definition is not suitable for use in preprocessor conditionals.

RETURN_ADDRESS_POINTER_REGNUM

The register number of the return address pointer register, which is used to access the current function’s return address from the stack. On some machines, the return address is not at a fixed offset from the frame pointer or stack pointer or argument pointer. This register can be defined to point to the return address on the stack, and then be converted by `ELIMINABLE_REGS` into either the frame pointer or stack pointer.

Do not define this macro unless there is no other way to get the return address from the stack.

STATIC_CHAIN_REGNUM

Register numbers used for passing a function’s static chain pointer. If register windows are used, the register number as seen by the called function is `STATIC_CHAIN_INCOMING_REGNUM`, while the register number as seen by the calling function is `STATIC_CHAIN_REGNUM`. If these registers are the same, `STATIC_CHAIN_INCOMING_REGNUM` need not be defined.

The static chain register need not be a fixed register.
If the static chain is passed in memory, these macros should not be defined; instead, the `TARGET_STATIC_CHAIN` hook should be used.

```
rtx TARGET_STATIC_CHAIN (const tree fnndecl_or_type, bool incoming_p)  [Target Hook]
```

This hook replaces the use of `STATIC_CHAIN_REGNUM` et al for targets that may use different static chain locations for different nested functions. This may be required if the target has function attributes that affect the calling conventions of the function and those calling conventions use different static chain locations.

The default version of this hook uses `STATIC_CHAIN_REGNUM` et al.

If the static chain is passed in memory, this hook should be used to provide rtx giving `mem` expressions that denote where they are stored. Often the `mem` expression as seen by the caller will be at an offset from the stack pointer and the `mem` expression as seen by the callee will be at an offset from the frame pointer. The variables `stack_pointer_rtx`, `frame_pointer_rtx`, and `arg_pointer_rtx` will have been initialized and should be used to refer to those items.

```
DWARF_FRAME_REGISTERS  [Macro]
```

This macro specifies the maximum number of hard registers that can be saved in a call frame. This is used to size data structures used in DWARF2 exception handling. Prior to GCC 3.0, this macro was needed in order to establish a stable exception handling ABI in the face of adding new hard registers for ISA extensions. In GCC 3.0 and later, the EH ABI is insulated from changes in the number of hard registers. Nevertheless, this macro can still be used to reduce the runtime memory requirements of the exception handling routines, which can be substantial if the ISA contains a lot of registers that are not call-saved.

If this macro is not defined, it defaults to `FIRST_PSEUDO_REGISTER`.

```
PRE_GCC3_DWARF_FRAME_REGISTERS  [Macro]
```

This macro is similar to `DWARF_FRAME_REGISTERS`, but is provided for backward compatibility in pre GCC 3.0 compiled code.

If this macro is not defined, it defaults to `DWARF_FRAME_REGISTERS`.

```
DWARF_REG_TO_UNWIND_COLUMN (regno)  [Macro]
```

Define this macro if the target’s representation for dwarf registers is different than the internal representation for unwind column. Given a dwarf register, this macro should return the internal unwind column number to use instead.

```
DWARF_FRAME_REGNUM (regno)  [Macro]
```

Define this macro if the target’s representation for dwarf registers used in `.eh_frame` or `.debug_frame` is different from that used in other debug info sections. Given a GCC hard register number, this macro should return the `.eh_frame` register number. The default is `DBX_REGISTER_NUMBER (regno)`.

```
DWARF2_FRAME_REG_OUT (regno, for_eh)  [Macro]
```

Define this macro to map register numbers held in the call frame info that GCC has collected using `DWARF_FRAME_REGNUM` to those that should be output in `.debug_frame` (`for_eh` is zero) and `.eh_frame` (`for_eh` is nonzero). The default is to return `regno`. 
REG_VALUE_IN_UNWIND_CONTEXT [Macro]
Define this macro if the target stores register values as _Unwind_Word type in unwind context. It should be defined if target register size is larger than the size of void *. The default is to store register values as void * type.

ASSUME_EXTENDED_UNWIND_CONTEXT [Macro]
Define this macro to be 1 if the target always uses extended unwind context with version, args_size and by_value fields. If it is undefined, it will be defined to 1 when REG_VALUE_IN_UNWIND_CONTEXT is defined and 0 otherwise.

DWARF_LAZY_REGISTER_VALUE (regno, value) [Macro]
Define this macro if the target has pseudo DWARF registers whose values need to be computed lazily on demand by the unwinder (such as when referenced in a CFA expression). The macro returns true if regno is such a register and stores its value in ‘*value’ if so.

18.9.5 Eliminating Frame Pointer and Arg Pointer
This is about eliminating the frame pointer and arg pointer.

bool TARGET_FRAME_POINTER_REQUIRED (void) [Target Hook]
This target hook should return true if a function must have and use a frame pointer. This target hook is called in the reload pass. If its return value is true the function will have a frame pointer.

This target hook can in principle examine the current function and decide according to the facts, but on most machines the constant false or the constant true suffices. Use false when the machine allows code to be generated with no frame pointer, and doing so saves some time or space. Use true when there is no possible advantage to avoiding a frame pointer.

In certain cases, the compiler does not know how to produce valid code without a frame pointer. The compiler recognizes those cases and automatically gives the function a frame pointer regardless of what targetm.frame_pointer_required returns. You don’t need to worry about them.

In a function that does not require a frame pointer, the frame pointer register can be allocated for ordinary usage, unless you mark it as a fixed register. See FIXED_REGISTERS for more information.

Default return value is false.

ELIMINABLE_REGS [Macro]
This macro specifies a table of register pairs used to eliminate unneeded registers that point into the stack frame.

The definition of this macro is a list of structure initializations, each of which specifies an original and replacement register.

On some machines, the position of the argument pointer is not known until the compilation is completed. In such a case, a separate hard register must be used for the argument pointer. This register can be eliminated by replacing it with either the frame pointer or the argument pointer, depending on whether or not the frame pointer has been eliminated.
In this case, you might specify:

```c
#define ELIMINABLE_REGS \
{ARG_POINTER_REGNUM, STACK_POINTER_REGNUM}, \
{ARG_POINTER_REGNUM, FRAME_POINTER_REGNUM}, \
{FRAME_POINTER_REGNUM, STACK_POINTER_REGNUM}}
```

Note that the elimination of the argument pointer with the stack pointer is specified first since that is the preferred elimination.

```c
bool TARGET_CAN_ELIMINATE (const int from_reg, const int to_reg) [Target Hook]
```

This target hook should return `true` if the compiler is allowed to try to replace register number `from_reg` with register number `to_reg`. This target hook will usually be `true`, since most of the cases preventing register elimination are things that the compiler already knows about.

Default return value is `true`.

```c
INITIAL_ELIMINATION_OFFSET (from-reg, to-reg, offset-var) [Macro]
```

This macro returns the initial difference between the specified pair of registers. The value would be computed from information such as the result of `get_frame_size()` and the tables of registers `df_regs_ever_live_p` and `call_used_regs`.

```c
void TARGET_COMPUTE_FRAME_LAYOUT (void) [Target Hook]
```

This target hook is called once each time the frame layout needs to be recalculated. The calculations can be cached by the target and can then be used by `INITIAL_ELIMINATION_OFFSET` instead of re-computing the layout on every invocation of that hook. This is particularly useful for targets that have an expensive frame layout function. Implementing this callback is optional.

### 18.9.6 Passing Function Arguments on the Stack

The macros in this section control how arguments are passed on the stack. See the following section for other macros that control passing certain arguments in registers.

```c
bool TARGET_PROMOTE_PROTOTYPES (const tree fntype) [Target Hook]
```

This target hook returns `true` if an argument declared in a prototype as an integral type smaller than `int` should actually be passed as an `int`. In addition to avoiding errors in certain cases of mismatch, it also makes for better code on certain machines. The default is to not promote prototypes.

```c
bool TARGET_PUSH_ARGUMENT (unsigned int npush) [Target Hook]
```

This target hook returns `true` if push instructions will be used to pass outgoing arguments. When the push instruction usage is optional, `npush` is nonzero to indicate the number of bytes to push. Otherwise, `npush` is zero. If the target machine does not have a push instruction or push instruction should be avoided, `false` should be returned. That directs GCC to use an alternate strategy: to allocate the entire argument block and then store the arguments into it. If this target hook may return `true`, `PUSH_ROUNDING` must be defined.
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**PUSH_ARGS_REVERSED**

A C expression. If nonzero, function arguments will be evaluated from last to first, rather than from first to last. If this macro is not defined, it defaults to `PUSH_ARGS` on targets where the stack and args grow in opposite directions, and 0 otherwise.

**PUSH_ROUNDING** *(npushed)*

A C expression that is the number of bytes actually pushed onto the stack when an instruction attempts to push `npushed` bytes.

On some machines, the definition

```
#define PUSH_ROUNDING(BYTES) (BYTES)
```

will suffice. But on other machines, instructions that appear to push one byte actually push two bytes in an attempt to maintain alignment. Then the definition should be

```
#define PUSH_ROUNDING(BYTES) (((BYTES) + 1) & ~1)
```

If the value of this macro has a type, it should be an unsigned type.

**ACCUMULATE_OUTGOING_ARGS**

A C expression. If nonzero, the maximum amount of space required for outgoing arguments will be computed and placed into `crtl->outgoing_args_size`. No space will be pushed onto the stack for each call; instead, the function prologue should increase the stack frame size by this amount.

Setting both `PUSH_ARGS` and `ACCUMULATE_OUTGOING_ARGS` is not proper.

**REG_PARM_STACK_SPACE** *(fndecl)*

Define this macro if functions should assume that stack space has been allocated for arguments even when their values are passed in registers.

The value of this macro is the size, in bytes, of the area reserved for arguments passed in registers for the function represented by `fndecl`, which can be zero if GCC is calling a library function. The argument `fndecl` can be the `FUNCTION_DECL`, or the type itself of the function.

This space can be allocated by the caller, or be a part of the machine-dependent stack frame: `OUTGOING_REG_PARM_STACK_SPACE` says which.

**INCOMING_REG_PARM_STACK_SPACE** *(fndecl)*

Like `REG_PARM_STACK_SPACE`, but for incoming register arguments. Define this macro if space guaranteed when compiling a function body is different to space required when making a call, a situation that can arise with K&R style function definitions.

**OUTGOING_REG_PARM_STACK_SPACE** *(fntype)*

Define this to a nonzero value if it is the responsibility of the caller to allocate the area reserved for arguments passed in registers when calling a function of `fntype`. `fntype` may be NULL if the function called is a library function.

If `ACCUMULATE_OUTGOING_ARGS` is defined, this macro controls whether the space for these arguments counts in the value of `crtl->outgoing_args_size`.

**STACK_PARMS_IN_REG_PARM_AREA**

Define this macro if `REG_PARM_STACK_SPACE` is defined, but the stack parameters don’t skip the area specified by it.
Normally, when a parameter is not passed in registers, it is placed on the stack beyond the `REG_PARM_STACK_SPACE` area. Defining this macro suppresses this behavior and causes the parameter to be passed on the stack in its natural location.

```c
poly_int64 TARGET_RETURN_POPS_ARGS (tree fundecl, tree funtype, poly_int64 size)
```

This target hook returns the number of bytes of its own arguments that a function pops on returning, or 0 if the function pops no arguments and the caller must therefore pop them all after the function returns.

`fundecl` is a C variable whose value is a tree node that describes the function in question. Normally it is a node of type `FUNCTION_DECL` that describes the declaration of the function. From this you can obtain the `DECL_ATTRIBUTES` of the function.

`funtype` is a C variable whose value is a tree node that describes the function in question. Normally it is a node of type `FUNCTION_TYPE` that describes the data type of the function. From this it is possible to obtain the data types of the value and arguments (if known).

When a call to a library function is being considered, `fundecl` will contain an identifier node for the library function. Thus, if you need to distinguish among various library functions, you can do so by their names. Note that “library function” in this context means a function used to perform arithmetic, whose name is known specially in the compiler and was not mentioned in the C code being compiled.

`size` is the number of bytes of arguments passed on the stack. If a variable number of bytes is passed, it is zero, and argument popping will always be the responsibility of the calling function.

On the VAX, all functions always pop their arguments, so the definition of this macro is `size`. On the 68000, using the standard calling convention, no functions pop their arguments, so the value of the macro is always 0 in this case. But an alternative calling convention is available in which functions that take a fixed number of arguments pop them but other functions (such as `printf`) pop nothing (the caller pops all). When this convention is in use, `funtype` is examined to determine whether a function takes a fixed number of arguments.

```c
CALL_POPS_ARGS (cum)
```

A C expression that should indicate the number of bytes a call sequence pops off the stack. It is added to the value of `RETURN_POPS_ARGS` when compiling a function call.

`cum` is the variable in which all arguments to the called function have been accumulated.

On certain architectures, such as the SH5, a call trampoline is used that pops certain registers off the stack, depending on the arguments that have been passed to the function. Since this is a property of the call site, not of the called function, `RETURN_POPS_ARGS` is not appropriate.

### 18.9.7 Passing Arguments in Registers

This section describes the macros which let you control how various types of arguments are passed in registers or how they are arranged in the stack.
rtx TARGET_FUNCTION_ARG (cumulative_args_t ca, const function_arg_info &arg)  

Return an RTX indicating whether function argument arg is passed in a register and if so, which register. Argument ca summarizes all the previous arguments. The return value is usually either a reg RTX for the hard register in which to pass the argument, or zero to pass the argument on the stack. The return value can be a const_int which means argument is passed in a target specific slot with specified number. Target hooks should be used to store or load argument in such case. See TARGET_STORE_BOUNDS_FOR_ARG and TARGET_LOAD_BOUNDS_FOR_ARG for more information. 

The value of the expression can also be a parallel RTX. This is used when an argument is passed in multiple locations. The mode of the parallel should be the mode of the entire argument. The parallel holds any number of expr_list pairs; each one describes where part of the argument is passed. In each expr_list the first operand must be a reg RTX for the hard register in which to pass this part of the argument, and the mode of the register RTX indicates how large this part of the argument is. The second operand of the expr_list is a const_int which gives the offset in bytes into the entire argument of where this part starts. As a special exception the first expr_list in the parallel RTX may have a first operand of zero. This indicates that the entire argument is also stored on the stack. 

The last time this hook is called, it is called with MODE == VOIDmode, and its result is passed to the call or call_value pattern as operands 2 and 3 respectively. The usual way to make the ISO library ‘stdarg.h’ work on a machine where some arguments are usually passed in registers, is to cause nameless arguments to be passed on the stack instead. This is done by making TARGET_FUNCTION_ARG return 0 whenever named is false. 

You may use the hook targetm.calls.must_pass_in_stack in the definition of this macro to determine if this argument is of a type that must be passed in the stack. If REG_PARM_STACK_SPACE is not defined and TARGET_FUNCTION_ARG returns nonzero for such an argument, the compiler will abort. If REG_PARM_STACK_SPACE is defined, the argument will be computed in the stack and then loaded into a register.

bool TARGET_MUST_PASS_IN_STACK (const function_arg_info &arg)  

This target hook should return true if we should not pass arg solely in registers. The file ‘expr.h’ defines a definition that is usually appropriate, refer to ‘expr.h’ for additional documentation.

rtx TARGET_FUNCTION_INCOMING_ARG (cumulative_args_t ca, const function_arg_info &arg)  

Define this hook if the caller and callee on the target have different views of where arguments are passed. Also define this hook if there are functions that are never directly called, but are invoked by the hardware and which have nonstandard calling conventions. 

In this case TARGET_FUNCTION_ARG computes the register in which the caller passes the value, and TARGET_FUNCTION_INCOMING_ARG should be defined in a similar fashion to tell the function being called where the arguments will arrive.
TARGET_FUNCTION_INCOMING_ARG can also return arbitrary address computation using hard register, which can be forced into a register, so that it can be used to pass special arguments.

If TARGET_FUNCTION_INCOMING_ARG is not defined, TARGET_FUNCTION_ARG serves both purposes.

bool TARGET_USE_PSEUDO_PIC_REG (void)  
This hook should return 1 in case pseudo register should be created for pic_offset_table_rtx during function expand.

void TARGET_INIT_PIC_REG (void)  
Perform a target dependent initialization of pic_offset_table_rtx. This hook is called at the start of register allocation.

int TARGET_ARG_PARTIAL_BYTES (cumulative_args_t cum, const function_arg_info &arg)  
This target hook returns the number of bytes at the beginning of an argument that must be put in registers. The value must be zero for arguments that are passed entirely in registers or that are entirely pushed on the stack.

On some machines, certain arguments must be passed partially in registers and partially in memory. On these machines, typically the first few words of arguments are passed in registers, and the rest on the stack. If a multi-word argument (a double or a structure) crosses that boundary, its first few words must be passed in registers and the rest must be pushed. This macro tells the compiler when this occurs, and how many bytes should go in registers.

TARGET_FUNCTION_ARG for these arguments should return the first register to be used by the caller for this argument; likewise TARGET_FUNCTION_INCOMING_ARG, for the called function.

bool TARGET_PASS_BY_REFERENCE (cumulative_args_t cum, const function_arg_info &arg)  
This target hook should return true if argument arg at the position indicated by cum should be passed by reference. This predicate is queried after target independent reasons for being passed by reference, such as TREE_ADDRESSABLE (arg.type).

If the hook returns true, a copy of that argument is made in memory and a pointer to the argument is passed instead of the argument itself. The pointer is passed in whatever way is appropriate for passing a pointer to that type.

bool TARGET_CALLEE_COPIES (cumulative_args_t cum, const function_arg_info &arg)  
The function argument described by the parameters to this hook is known to be passed by reference. The hook should return true if the function argument should be copied by the callee instead of copied by the caller.

For any argument for which the hook returns true, if it can be determined that the argument is not modified, then a copy need not be generated.

The default version of this hook always returns false.
CUMULATIVE_ARGS

A C type for declaring a variable that is used as the first argument of TARGET_FUNCTION_ARG and other related values. For some target machines, the type int suffices and can hold the number of bytes of argument so far.

There is no need to record in CUMULATIVE_ARGS anything about the arguments that have been passed on the stack. The compiler has other variables to keep track of that. For target machines on which all arguments are passed on the stack, there is no need to store anything in CUMULATIVE_ARGS; however, the data structure must exist and should not be empty, so use int.

OVERRIDE_ABI_FORMAT (fndecl)

If defined, this macro is called before generating any code for a function, but after the cfun descriptor for the function has been created. The back end may use this macro to update cfun to reflect an ABI other than that which would normally be used by default. If the compiler is generating code for a compiler-generated function, fndecl may be NULL.

INIT_CUMULATIVE_ARGS (cum, fntype, libname, fndecl, n_named_args)

A C statement (sans semicolon) for initializing the variable cum for the state at the beginning of the argument list. The variable has type CUMULATIVE_ARGS. The value of fntype is the tree node for the data type of the function which will receive the args, or 0 if the args are to a compiler support library function. For direct calls that are not libcalls, fndecl contain the declaration node of the function. fndecl is also set when INIT_CUMULATIVE_ARGS is used to find arguments for the function being compiled. n_named_args is set to the number of named arguments, including a structure return address if it is passed as a parameter, when making a call. When processing incoming arguments, n_named_args is set to −1.

When processing a call to a compiler support library function, libname identifies which one. It is a symbol_ref rtx which contains the name of the function, as a string. libname is 0 when an ordinary C function call is being processed. Thus, each time this macro is called, either libname or fntype is nonzero, but never both of them at once.

INIT_CUMULATIVE_LIBCALL_ARGS (cum, mode, libname)

Like INIT_CUMULATIVE_ARGS but only used for outgoing libcalls, it gets a MODE argument instead of fntype, that would be NULL. indirect would always be zero, too. If this macro is not defined, INIT_CUMULATIVE_ARGS (cum, NULL_RTX, libname, 0) is used instead.

INIT_CUMULATIVE_INCOMING_ARGS (cum, fntype, libname)

Like INIT_CUMULATIVE_ARGS but overrides it for the purposes of finding the arguments for the function being compiled. If this macro is undefined, INIT_CUMULATIVE_ARGS is used instead.

The value passed for libname is always 0, since library routines with special calling conventions are never compiled with GCC. The argument libname exists for symmetry with INIT_CUMULATIVE_ARGS.
void TARGET_FUNCTION_ARG_ADVANCE (cumulative_args_t ca, const function_arg_info &arg)  
    [Target Hook]
    This hook updates the summarizer variable pointed to by ca to advance past argument 
    arg in the argument list. Once this is done, the variable cum is suitable for analyzing 
    the following argument with TARGET_FUNCTION_ARG, etc.
    This hook need not do anything if the argument in question was passed on the stack. 
    The compiler knows how to track the amount of stack space used for arguments 
    without any special help.

HOST_WIDE_INT TARGET_FUNCTION_ARG_OFFSET (machine_mode mode, const tree type)  
    [Target Hook]
    This hook returns the number of bytes to add to the offset of an argument of type 
    type and mode mode when passed in memory. This is needed for the SPU, which 
    passes char and short arguments in the preferred slot that is in the middle of the 
    quad word instead of starting at the top. The default implementation returns 0.

pad_direction TARGET_FUNCTION_ARG_PADDING (machine_mode mode, const tree type)  
    [Target Hook]
    This hook determines whether, and in which direction, to pad out an argument of 
    mode mode and type type. It returns PAD_UPWARD to insert padding above the argument, 
    PAD_DOWNWARD to insert padding below the argument, or PAD_NONE to inhibit 
    padding.
    The amount of padding is not controlled by this hook, but by TARGET_FUNCTION_ 
    ARG_ROUND_BOUNDARY. It is always just enough to reach the next multiple of that 
    boundary.
    This hook has a default definition that is right for most systems. For little-endian 
    machines, the default is to pad upward. For big-endian machines, the default is to 
    pad downward for an argument of constant size shorter than an int, and upward 
    otherwise.

PAD_VARARGS_DOWN  
    [Macro]
    If defined, a C expression which determines whether the default implementation of 
    va_arg will attempt to pad down before reading the next argument, if that argument 
    is smaller than its aligned space as controlled by PARM_BOUNDARY. If this macro is not 
    defined, all such arguments are padded down if BYTES_BIG_ENDIAN is true.

BLOCK_REG_PADDING (mode, type, first)  
    [Macro]
    Specify padding for the last element of a block move between registers and memory. 
    first is nonzero if this is the only element. Defining this macro allows better control of 
    register function parameters on big-endian machines, without using PARALLEL rtl. In 
    particular, MUST_PASS_IN_STACK need not test padding and mode of types in registers, 
    as there is no longer a "wrong" part of a register; For example, a three byte aggregate 
    may be passed in the high part of a register if so required.

unsigned int TARGET_FUNCTION_ARG_BOUNDARY (machine_mode mode, const tree type)  
    [Target Hook]
    This hook returns the alignment boundary, in bits, of an argument with the specified 
    mode and type. The default hook returns PARM_BOUNDARY for all arguments.
unsigned int TARGET_FUNCTION_ARG_ROUND_BOUNDARY [Target Hook]
(machine_mode mode, const_tree type)

Normally, the size of an argument is rounded up to PARM_BOUNDARY, which is the default value for this hook. You can define this hook to return a different value if an argument size must be rounded to a larger value.

FUNCTION_ARG_REGNO_P (regno) [Macro]

A C expression that is nonzero if regno is the number of a hard register in which function arguments are sometimes passed. This does not include implicit arguments such as the static chain and the structure-value address. On many machines, no registers can be used for this purpose since all function arguments are pushed on the stack.

bool TARGET_SPLIT_COMPLEX_ARG (const_tree type) [Target Hook]

This hook should return true if parameter of type type are passed as two scalar parameters. By default, GCC will attempt to pack complex arguments into the target’s word size. Some ABIs require complex arguments to be split and treated as their individual components. For example, on AIX64, complex floats should be passed in a pair of floating point registers, even though a complex float would fit in one 64-bit floating point register.

The default value of this hook is NULL, which is treated as always false.

tree TARGET_BUILD_BUILTIN_VA_LIST (void) [Target Hook]

This hook returns a type node for va_list for the target. The default version of the hook returns void*.

int TARGET_ENUM_VA_LIST_P (int idx, const char **pname, tree *ptree) [Target Hook]

This target hook is used in function c_common_nodes_and_builtins to iterate through the target specific builtin types for va_list. The variable idx is used as iterator. pname has to be a pointer to a const char * and ptree a pointer to a tree typed variable. The arguments pname and ptree are used to store the result of this macro and are set to the name of the va_list builtin type and its internal type. If the return value of this macro is zero, then there is no more element. Otherwise the IDX should be increased for the next call of this macro to iterate through all types.

tree TARGET_FN_ABI_VA_LIST (tree fndecl) [Target Hook]

This hook returns the va_list type of the calling convention specified by fndecl. The default version of this hook returns va_list_type_node.

tree TARGET_CANONICAL_VA_LIST_TYPE (tree type) [Target Hook]

This hook returns the va_list type of the calling convention specified by the type of type. If type is not a valid va_list type, it returns NULL_TREE.

tree TARGET_GIMPLIFY_VA_ARG_EXPR (tree valist, tree type, gimple_seq *pre_p, gimple_seq *post_p) [Target Hook]

This hook performs target-specific gimplification of VA_ARG_EXPR. The first two parameters correspond to the arguments to va_arg; the latter two are as in gimplify.c:gimplify_expr.
bool TARGET_VALID_POINTER_MODE (scalar_int_mode mode) [Target Hook]
Define this to return nonzero if the port can handle pointers with machine mode `mode`. The default version of this hook returns true for both `ptr_mode` and `Pmode`.

bool TARGET_REF_MAY_ALIAS_ERRNO (ao_ref *ref) [Target Hook]
Define this to return nonzero if the memory reference `ref` may alias with the system C library `errno` location. The default version of this hook assumes the system C library `errno` location is either a declaration of type `int` or accessed by dereferencing a pointer to `int`.

machine_mode TARGET_TRANSLATE_MODE_ATTRIBUTE (machine_mode mode) [Target Hook]
Define this hook if during mode attribute processing, the port should translate `machine_mode mode` to another mode. For example, rs6000’s `KFmode`, when it is the same as `TFmode`.
The default version of the hook returns that mode that was passed in.

bool TARGET_SCALAR_MODE_SUPPORTED_P (scalar_mode mode) [Target Hook]
Define this to return nonzero if the port is prepared to handle insns involving scalar mode `mode`. For a scalar mode to be considered supported, all the basic arithmetic and comparisons must work.
The default version of this hook returns true for any mode required to handle the basic C types (as defined by the port). Included here are the double-word arithmetic supported by the code in ‘optabs.c’.

bool TARGET_VECTOR_MODE_SUPPORTED_P (machine_mode mode) [Target Hook]
Define this to return nonzero if the port is prepared to handle insns involving vector mode `mode`. At the very least, it must have move patterns for this mode.

bool TARGET_COMPATIBLE_VECTOR_TYPES_P (const_tree type1, const_tree type2) [Target Hook]
Return true if there is no target-specific reason for treating vector types `type1` and `type2` as distinct types. The caller has already checked for target-independent reasons, meaning that the types are known to have the same mode, to have the same number of elements, and to have what the caller considers to be compatible element types.
The main reason for defining this hook is to reject pairs of types that are handled differently by the target’s calling convention. For example, when a new N-bit vector architecture is added to a target, the target may want to handle normal N-bit `VECTOR_TYPE` arguments and return values in the same way as before, to maintain backwards compatibility. However, it may also provide new, architecture-specific `VECTOR_TYPE`es that are passed and returned in a more efficient way. It is then important to maintain a distinction between the “normal” `VECTOR_TYPE`es and the new architecture-specific ones.
The default implementation returns true, which is correct for most targets.

opt_machine_mode TARGET_ARRAY_MODE (machine_mode mode, unsigned HOST_WIDE_INT nelems) [Target Hook]
Return the mode that GCC should use for an array that has `nelems` elements, with each element having mode `mode`. Return no mode if the target has no special re-
quirements. In the latter case, GCC looks for an integer mode of the appropriate size if available and uses BLKmode otherwise. Usually the search for the integer mode is limited to \texttt{MAX\_FIXED\_MODE\_SIZE}, but the \texttt{TARGET\_ARRAY\_MODE\_SUPPORTED\_P} hook allows a larger mode to be used in specific cases.

The main use of this hook is to specify that an array of vectors should also have a vector mode. The default implementation returns no mode.

\begin{verbatim}
bool TARGET\_ARRAY\_MODE\_SUPPORTED\_P (machine_mode mode, unsigned HOST\_WIDE\_INT nelems)
Return true if GCC should try to use a scalar mode to store an array of \texttt{nelems} elements, given that each element has mode \texttt{mode}. Returning true here overrides the usual \texttt{MAX\_FIXED\_MODE} limit and allows GCC to use any defined integer mode.

One use of this hook is to support vector load and store operations that operate on several homogeneous vectors. For example, ARM NEON has operations like:

\begin{verbatim}
int8x8x3\_t vld3_s8 (const int8\_t \*)
\end{verbatim}

where the return type is defined as:

\begin{verbatim}
typedef struct int8x8x3\_t {
  int8\_t val[3];
} int8x8x3\_t;
\end{verbatim}

If this hook allows \texttt{val} to have a scalar mode, then \texttt{int8x8x3\_t} can have the same mode. GCC can then store \texttt{int8x8x3\_ts} in registers rather than forcing them onto the stack.

\begin{verbatim}
bool TARGET\_LIBGCC\_FLOATING\_MODE\_SUPPORTED\_P (scalar_float_mode mode)
Define this to return nonzero if libgcc provides support for the floating-point mode \texttt{mode}, which is known to pass \texttt{TARGET\_SCALAR\_MODE\_SUPPORTED\_P}. The default version of this hook returns true for all of \texttt{SFmode}, \texttt{DFmode}, \texttt{XFmode} and \texttt{TFmode}, if such modes exist.
\end{verbatim}

\begin{verbatim}
opt_scalar_float_mode TARGET\_FLOATN\_MODE (int n, bool extended)
Define this to return the machine mode to use for the type \_Float\texttt{n}, if \texttt{extended} is false, or the type \_Float\texttt{nx}, if \texttt{extended} is true. If such a type is not supported, return \texttt{opt_scalar_float_mode ()}. The default version of this hook returns \texttt{SFmode} for \_Float\texttt{32}, \texttt{DFmode} for \_Float\texttt{64} and \_Float\texttt{32x} and \texttt{TFmode} for \_Float\texttt{128}, if those modes exist and satisfy the requirements for those types and pass \texttt{TARGET\_SCALAR\_MODE\_SUPPORTED\_P} and \texttt{TARGET\_LIBGCC\_FLOATING\_MODE\_SUPPORTED\_P}; for \_Float\texttt{64x}, it returns the first of \texttt{XFmode} and \texttt{TFmode} that exists and satisfies the same requirements; for other types, it returns \texttt{opt_scalar_float_mode ()}. The hook is only called for values of \texttt{n} and \texttt{extended} that are valid according to ISO/IEC TS 18661-3:2015; that is, \texttt{n} is one of 32, 64, 128, or, if \texttt{extended} is false, 16 or greater than 128 and a multiple of 32.
\end{verbatim}

\begin{verbatim}
bool TARGET\_FLOATN\_BUILTIN\_P (int func)
Define this to return true if the \_Float\texttt{n} and \_Float\texttt{nx} built-in functions should implicitly enable the built-in function without the \_\texttt{builtin}\_ prefix in addition to
\end{verbatim}

the normal built-in function with the __builtin__ prefix. The default is to only enable
built-in functions without the __builtin__ prefix for the GNU C language. In strict
ANSI/ISO mode, the built-in function without the __builtin__ prefix is not enabled.
The argument FUNC is the enum built_in_function id of the function to be enabled.

bool TARGET_SMALL_REGISTER_CLASSES_FOR_MODE_P [Target Hook]
(machine_mode mode)
Define this to return nonzero for machine modes for which the port has small register
classes. If this target hook returns nonzero for a given mode, the compiler will try to
minimize the lifetime of registers in mode. The hook may be called with VOID_mode as
argument. In this case, the hook is expected to return nonzero if it returns nonzero
for any mode.

On some machines, it is risky to let hard registers live across arbitrary insns. Typically,
these machines have instructions that require values to be in specific registers (like
an accumulator), and reload will fail if the required hard register is used for another
purpose across such an insn.

Passes before reload do not know which hard registers will be used in an instruction,
but the machine modes of the registers set or used in the instruction are already
known. And for some machines, register classes are small for, say, integer registers but
not for floating point registers. For example, the AMD x86-64 architecture requires
specific registers for the legacy x86 integer instructions, but there are many SSE
registers for floating point operations. On such targets, a good strategy may be to
return nonzero from this hook for INTEGRAL_MODE_P machine modes but zero for the
SSE register classes.

The default version of this hook returns false for any mode. It is always safe to
redefine this hook to return with a nonzero value. But if you unnecessarily define it,
you will reduce the amount of optimizations that can be performed in some cases. If
you do not define this hook to return a nonzero value when it is required, the compiler
will run out of spill registers and print a fatal error message.

18.9.8 How Scalar Function Values Are Returned
This section discusses the macros that control returning scalars as values—values that can
fit in registers.

rtx TARGET_FUNCTION_VALUE (const_tree ret_type, const_tree
fn_decl_or_type, bool outgoing) [Target Hook]
Define this to return an RTX representing the place where a function returns
or receives a value of data type ret_type, a tree node representing a data type.
fn_decl_or_type is a tree node representing FUNCTION_DECL or FUNCTION_TYPE of a
function being called. If outgoing is false, the hook should compute the register in
which the caller will see the return value. Otherwise, the hook should return an
RTX representing the place where a function returns a value.

On many machines, only TYPE_MODE (ret_type) is relevant. (Actually, on most
machines, scalar values are returned in the same place regardless of mode.) The
value of the expression is usually a reg RTX for the hard register where the return
value is stored. The value can also be a parallel RTX, if the return value is in
multiple places. See TARGET_FUNCTION_ARG for an explanation of the parallel form. Note that the callee will populate every location specified in the parallel, but if the first element of the parallel contains the whole return value, callers will use that element as the canonical location and ignore the others. The m68k port uses this type of parallel to return pointers in both ‘%a0’ (the canonical location) and ‘%d0’.

If TARGET_PROMOTE_FUNCTION_RETURN returns true, you must apply the same promotion rules specified in PROMOTE_MODE if valtype is a scalar type.

If the precise function being called is known, func is a tree node (FUNCTION_DECL) for it; otherwise, func is a null pointer. This makes it possible to use a different value-returning convention for specific functions when all their calls are known.

Some target machines have “register windows” so that the register in which a function returns its value is not the same as the one in which the caller sees the value. For such machines, you should return different RTX depending on outgoing.

TARGET_FUNCTION_VALUE is not used for return values with aggregate data types, because these are returned in another way. See TARGET_STRUCT_VALUE_RTX and related macros, below.

FUNCTION_VALUE (valtype, func)  
This macro has been deprecated. Use TARGET_FUNCTION_VALUE for a new target instead.

LIBCALL_VALUE (mode)  
A C expression to create an RTX representing the place where a library function returns a value of mode mode.

Note that “library function” in this context means a compiler support routine, used to perform arithmetic, whose name is known specially by the compiler and was not mentioned in the C code being compiled.

rtx TARGET_LIBCALL_VALUE (machine_mode mode, const rtx fun)  
Define this hook if the back-end needs to know the name of the libcall function in order to determine where the result should be returned.

The mode of the result is given by mode and the name of the called library function is given by fun. The hook should return an RTX representing the place where the library function result will be returned.

If this hook is not defined, then LIBCALL_VALUE will be used.

FUNCTION_VALUE_REGNO_P (regno)  
A C expression that is nonzero if regno is the number of a hard register in which the values of called function may come back.

A register whose use for returning values is limited to serving as the second of a pair (for a value of type double, say) need not be recognized by this macro. So for most machines, this definition suffices:

#define FUNCTION_VALUE_REGNO_P(N) ((N) == 0)

If the machine has register windows, so that the caller and the called function use different registers for the return value, this macro should recognize only the caller’s register numbers.
This macro has been deprecated. Use `TARGET_FUNCTION_VALUE_REGNO_P` for a new target instead.

```c
bool TARGET_FUNCTION_VALUE_REGNO_P (const unsigned int regno) [Target Hook]
```

A target hook that return true if `regno` is the number of a hard register in which the values of called function may come back.

A register whose use for returning values is limited to serving as the second of a pair (for a value of type `double`, say) need not be recognized by this target hook.

If the machine has register windows, so that the caller and the called function use different registers for the return value, this target hook should recognize only the caller's register numbers.

If this hook is not defined, then `FUNCTION_VALUE_REGNO_P` will be used.

```c
APPLY_RESULT_SIZE [Macro]
```

Define this macro if 'untyped_call' and 'untyped_return' need more space than is implied by `FUNCTION_VALUE_REGNO_P` for saving and restoring an arbitrary return value.

```c
bool TARGET_OMIT_STRUCT_RETURN_REG [Target Hook]
```

Normally, when a function returns a structure by memory, the address is passed as an invisible pointer argument, but the compiler also arranges to return the address from the function like it would a normal pointer return value. Define this to true if that behavior is undesirable on your target.

```c
bool TARGET_RETURN_IN_MSB (const tree type) [Target Hook]
```

This hook should return true if values of type `type` are returned at the most significant end of a register (in other words, if they are padded at the least significant end). You can assume that `type` is returned in a register; the caller is required to check this.

Note that the register provided by `TARGET_FUNCTION_VALUE` must be able to hold the complete return value. For example, if a 1-, 2- or 3-byte structure is returned at the most significant end of a 4-byte register, `TARGET_FUNCTION_VALUE` should provide an `SImode rtx`.

18.9.9 How Large Values Are Returned

When a function value's mode is `BLKmode` (and in some other cases), the value is not returned according to `TARGET_FUNCTION_VALUE` (see Section 18.9.8 [Scalar Return], page 562). Instead, the caller passes the address of a block of memory in which the value should be stored. This address is called the `structure value address`.

This section describes how to control returning structure values in memory.

```c
bool TARGET_RETURN_IN_MEMORY (const tree type, const tree fntype) [Target Hook]
```

This target hook should return a nonzero value to say to return the function value in memory, just as large structures are always returned. Here `type` will be the data type of the value, and `fntype` will be the type of the function doing the returning, or `NULL` for libcalls.
Note that values of mode `BLKmode` must be explicitly handled by this function. Also, the option ‘-fpcc-struct-return’ takes effect regardless of this macro. On most systems, it is possible to leave the hook undefined; this causes a default definition to be used, whose value is the constant 1 for `BLKmode` values, and 0 otherwise.

Do not use this hook to indicate that structures and unions should always be returned in memory. You should instead use `DEFAULT_PCC_STRUCT_RETURN` to indicate this.

**DEFAULT_PCC_STRUCT_RETURN**

Define this macro to be 1 if all structure and union return values must be in memory. Since this results in slower code, this should be defined only if needed for compatibility with other compilers or with an ABI. If you define this macro to be 0, then the conventions used for structure and union return values are decided by the `TARGET_RETURN_IN_MEMORY` target hook.

If not defined, this defaults to the value 1.

**rtx TARGET_STRUCT_VALUE_RTX (tree fndecl, int incoming)**

This target hook should return the location of the structure value address (normally a `mem` or `reg`), or 0 if the address is passed as an “invisible” first argument. Note that `fndecl` may be `NULL`, for libcalls. You do not need to define this target hook if the address is always passed as an “invisible” first argument.

On some architectures the place where the structure value address is found by the called function is not the same place that the caller put it. This can be due to register windows, or it could be because the function prologue moves it to a different place. `incoming` is 1 or 2 when the location is needed in the context of the called function, and 0 in the context of the caller.

If `incoming` is nonzero and the address is to be found on the stack, return a `mem` which refers to the frame pointer. If `incoming` is 2, the result is being used to fetch the structure value address at the beginning of a function. If you need to emit adjusting code, you should do it at this point.

**PCC_STATIC_STRUCT_RETURN**

Define this macro if the usual system convention on the target machine for returning structures and unions is for the called function to return the address of a static variable containing the value.

Do not define this if the usual system convention is for the caller to pass an address to the subroutine.

This macro has effect in ‘-fpcc-struct-return’ mode, but it does nothing when you use ‘-freg-struct-return’ mode.

**fixed_size_mode TARGET_GET_RAW_RESULT_MODE (int regno)**

This target hook returns the mode to be used when accessing raw return registers in `__builtin_return`. Define this macro if the value in `reg_raw_mode` is not correct.

**fixed_size_mode TARGET_GET_RAW_ARG_MODE (int regno)**

This target hook returns the mode to be used when accessing raw argument registers in `__builtin_apply_args`. Define this macro if the value in `reg_raw_mode` is not correct.
bool TARGET_EMPTY_RECORD_P (const tree type)  
This target hook returns true if the type is an empty record. The default is to return false.

void TARGET_WARN_PARAMETER_PASSING_ABI (cumulative_args_t ca, tree type)  
This target hook warns about the change in empty class parameter passing ABI.

18.9.10 Caller-Saves Register Allocation
If you enable it, GCC can save registers around function calls. This makes it possible to use call-clobbered registers to hold variables that must live across calls.

HARD_REGNO_CALLER_SAVE_MODE (regno, nregs)  
A C expression specifying which mode is required for saving nregs of a pseudo-register in call-clobbered hard register regno. If regno is unsuitable for caller save, VOIDmode should be returned. For most machines this macro need not be defined since GCC will select the smallest suitable mode.

18.9.11 Function Entry and Exit
This section describes the macros that output function entry (prologue) and exit (epilogue) code.

void TARGET_ASM_PRINT_PATCHABLE_FUNCTION_ENTRY (FILE *file, unsigned HOST_WIDE_INT patch_area_size, bool record_p)  
Generate a patchable area at the function start, consisting of patch_area_size NOP instructions. If the target supports named sections and if record_p is true, insert a pointer to the current location in the table of patchable functions. The default implementation of the hook places the table of pointers in the special section named __patchable_function_entries.

void TARGET_ASM_FUNCTION_PROLOGUE (FILE *file)  
If defined, a function that outputs the assembler code for entry to a function. The prologue is responsible for setting up the stack frame, initializing the frame pointer register, saving registers that must be saved, and allocating size additional bytes of storage for the local variables. file is a stdio stream to which the assembler code should be output.

The label for the beginning of the function need not be output by this macro. That has already been done when the macro is run.

To determine which registers to save, the macro can refer to the array regn_eff__live: element r is nonzero if hard register r is used anywhere within the function. This implies the function prologue should save register r, provided it is not one of the call-used registers. (TARGET_ASM_FUNCTION_EPILOGUE must likewise use regn_eff_live.)

On machines that have “register windows”, the function entry code does not save on the stack the registers that are in the windows, even if they are supposed to be preserved by function calls; instead it takes appropriate steps to “push” the register stack, if any non-call-used registers are used in the function.
On machines where functions may or may not have frame-pointers, the function entry code must vary accordingly; it must set up the frame pointer if one is wanted, and not otherwise. To determine whether a frame pointer is in wanted, the macro can refer to the variable `frame_pointer_needed`. The variable’s value will be 1 at run time in a function that needs a frame pointer. See Section 18.9.5 [Elimination], page 551.

The function entry code is responsible for allocating any stack space required for the function. This stack space consists of the regions listed below. In most cases, these regions are allocated in the order listed, with the last listed region closest to the top of the stack (the lowest address if `STACK_GROWS_DOWNWARD` is defined, and the highest address if it is not defined). You can use a different order for a machine if doing so is more convenient or required for compatibility reasons. Except in cases where required by standard or by a debugger, there is no reason why the stack layout used by GCC need agree with that used by other compilers for a machine.

```c
void TARGET_ASM_FUNCTION_END_PROLOGUE (FILE *file)  [Target Hook]
   If defined, a function that outputs assembler code at the end of a prologue. This should be used when the function prologue is being emitted as RTL, and you have some extra assembler that needs to be emitted. See [prologue instruction pattern], page 441.

void TARGET_ASM_FUNCTION_BEGIN_EPILOGUE (FILE *file) [Target Hook]
   If defined, a function that outputs assembler code at the start of an epilogue. This should be used when the function epilogue is being emitted as RTL, and you have some extra assembler that needs to be emitted. See [epilogue instruction pattern], page 442.

void TARGET_ASM_FUNCTION_EPILOGUE (FILE *file) [Target Hook]
   If defined, a function that outputs the assembler code for exit from a function. The epilogue is responsible for restoring the saved registers and stack pointer to their values when the function was called, and returning control to the caller. This macro takes the same argument as the macro `TARGET_ASM_FUNCTION_PROLOGUE`, and the registers to restore are determined from `regs_ever_live` and `CALL_USED_REGISTERS` in the same way.

On some machines, there is a single instruction that does all the work of returning from the function. On these machines, give that instruction the name ‘return’ and do not define the macro `TARGET_ASM_FUNCTION_EPILOGUE` at all.

Do not define a pattern named ‘return’ if you want the `TARGET_ASM_FUNCTION_EPILOGUE` to be used. If you want the target switches to control whether return instructions or epilogues are used, define a ‘return’ pattern with a validity condition that tests the target switches appropriately. If the ‘return’ pattern’s validity condition is false, epilogues will be used.

On machines where functions may or may not have frame-pointers, the function exit code must vary accordingly. Sometimes the code for these two cases is completely different. To determine whether a frame pointer is wanted, the macro can refer to the variable `frame_pointer_needed`. The variable’s value will be 1 when compiling a function that needs a frame pointer.
Normally, \texttt{TARGET_ASM_FUNCTION_PROLOGUE} and \texttt{TARGET_ASM_FUNCTION_EPILOGUE} must treat leaf functions specially. The C variable \texttt{current_function_is_leaf} is nonzero for such a function. See Section 18.7.4 [Leaf Functions], page 528.

On some machines, some functions pop their arguments on exit while others leave that for the caller to do. For example, the 68020 when given ‘-mrtd’ pops arguments in functions that take a fixed number of arguments.

Your definition of the macro \texttt{RETURN_POPS_ARGS} decides which functions pop their own arguments. \texttt{TARGET_ASM_FUNCTION_EPILOGUE} needs to know what was decided. The number of bytes of the current function’s arguments that this function should pop is available in \texttt{crtl->args.pops_args}. See Section 18.9.8 [Scalar Return], page 562.

- A region of \texttt{crtl->args.pretend_args_size} bytes of uninitialized space just underneath the first argument arriving on the stack. (This may not be at the very start of the allocated stack region if the calling sequence has pushed anything else since pushing the stack arguments. But usually, on such machines, nothing else has been pushed yet, because the function prologue itself does all the pushing.) This region is used on machines where an argument may be passed partly in registers and partly in memory, and, in some cases to support the features in \texttt{<stdarg.h>}

- An area of memory used to save certain registers used by the function. The size of this area, which may also include space for such things as the return address and pointers to previous stack frames, is machine-specific and usually depends on which registers have been used in the function. Machines with register windows often do not require a save area.

- A region of at least \texttt{size} bytes, possibly rounded up to an allocation boundary, to contain the local variables of the function. On some machines, this region and the save area may occur in the opposite order, with the save area closer to the top of the stack.

- Optionally, when \texttt{ACCUMULATE_OUTGOING_ARGS} is defined, a region of \texttt{crtl->outgoing_args_size} bytes to be used for outgoing argument lists of the function. See Section 18.9.6 [Stack Arguments], page 552.

\textbf{EXIT\_IGNORE\_STACK} \hfill \textbf{[Macro]}

Define this macro as a C expression that is nonzero if the return instruction or the function epilogue ignores the value of the stack pointer; in other words, if it is safe to delete an instruction to adjust the stack pointer before a return from the function. The default is 0.

Note that this macro’s value is relevant only for functions for which frame pointers are maintained. It is never safe to delete a final stack adjustment in a function that has no frame pointer, and the compiler knows this regardless of \texttt{EXIT\_IGNORE\_STACK}.

\textbf{EPILOGUE\_USES} (\texttt{regno}) \hfill \textbf{[Macro]}

Define this macro as a C expression that is nonzero for registers that are used by the epilogue or the ‘return’ pattern. The stack and frame pointer registers are already assumed to be used as needed.

\textbf{EH\_USES} (\texttt{regno}) \hfill \textbf{[Macro]}

Define this macro as a C expression that is nonzero for registers that are used by the exception handling mechanism, and so should be considered live on entry to an exception edge.
A function that outputs the assembler code for a thunk function, used to implement C++ virtual function calls with multiple inheritance. The thunk acts as a wrapper around a virtual function, adjusting the implicit object parameter before handing control off to the real function.

First, emit code to add the integer \( \delta \) to the location that contains the incoming first argument. Assume that this argument contains a pointer, and is the one used to pass the \texttt{this} pointer in C++. This is the incoming argument before the function prologue, e.g. \texttt{\%o0} on a sparc. The addition must preserve the values of all other incoming arguments.

Then, if \( \text{vcall\_offset} \) is nonzero, an additional adjustment should be made after adding \( \delta \). In particular, if \( p \) is the adjusted pointer, the following adjustment should be made:

\[
p += (*((ptrdiff_t **)p)[\text{vcall\_offset}/\text{sizeof(ptrdiff_t)}])
\]

After the additions, emit code to jump to \texttt{function}, which is a \texttt{FUNCTION\_DECL}. This is a direct pure jump, not a call, and does not touch the return address. Hence returning from \texttt{FUNCTION} will return to whoever called the current \texttt{thunk}.

The effect must be as if \texttt{function} had been called directly with the adjusted first argument. This macro is responsible for emitting all of the code for a thunk function; \texttt{TARG\_ASM\_FUNCTION\_PROLOGUE} and \texttt{TARG\_ASM\_FUNCTION\_EPILOGUE} are not invoked.

The \textit{thunk\_fndecl} is redundant. (\( \delta \) and \textit{function} have already been extracted from it.) It might possibly be useful on some targets, but probably not.

If you do not define this macro, the target-independent code in the C++ front end will generate a less efficient heavyweight thunk that calls \textit{function} instead of jumping to it. The generic approach does not support varargs.

A function that returns true if \texttt{TARGET\_ASM\_OUTPUT\_MI\_THUNK} would be able to output the assembler code for the thunk function specified by the arguments it is passed, and false otherwise. In the latter case, the generic approach will be used by the C++ front end, with the limitations previously exposed.

\section*{18.9.12 Generating Code for Profiling}

These macros will help you generate code for profiling.

A C statement or compound statement to output to \texttt{file} some assembler code to call the profiling subroutine \texttt{mcount}.

The details of how \texttt{mcount} expects to be called are determined by your operating system environment, not by GCC. To figure them out, compile a small program for
profiling using the system’s installed C compiler and look at the assembler code that results.

Older implementations of mcount expect the address of a counter variable to be loaded into some register. The name of this variable is ‘LP’ followed by the number labelno, so you would generate the name using ‘LP%d’ in a fprintf.

PROFILE_HOOK [Macro]
A C statement or compound statement to output to file some assembly code to call the profiling subroutine mcount even the target does not support profiling.

NO_PROFILE_COUNTERS [Macro]
Define this macro to be an expression with a nonzero value if the mcount subroutine on your system does not need a counter variable allocated for each function. This is true for almost all modern implementations. If you define this macro, you must not use the labelno argument to FUNCTION_PROFILER.

PROFILE_BEFORE_PROLOGUE [Macro]
Define this macro if the code for function profiling should come before the function prologue. Normally, the profiling code comes after.

bool TARGET_KEEP_LEAF_WHEN_PROFILED (void) [Target Hook]
This target hook returns true if the target wants the leaf flag for the current function to stay true even if it calls mcount. This might make sense for targets using the leaf flag only to determine whether a stack frame needs to be generated or not and for which the call to mcount is generated before the function prologue.

18.9.13 Permitting tail calls

bool TARGET_FUNCTION_OK_FOR_SIBCALL (tree decl, tree exp) [Target Hook]
True if it is OK to do sibling call optimization for the specified call expression exp. decl will be the called function, or NULL if this is an indirect call.

It is not uncommon for limitations of calling conventions to prevent tail calls to functions outside the current unit of translation, or during PIC compilation. The hook is used to enforce these restrictions, as the sibcall md pattern cannot fail, or fall over to a “normal” call. The criteria for successful sibling call optimization may vary greatly between different architectures.

void TARGET_EXTRA_LIVE_ON_ENTRY (bitmap regs) [Target Hook]
Add any hard registers to regs that are live on entry to the function. This hook only needs to be defined to provide registers that cannot be found by examination of FUNCTION_ARG_REGNO_P, the callee saved registers, STATIC_CHAIN_INCOMING_REGNUM, STATIC_CHAIN_REGNUM, TARGET_STRUCT_VALUE_RTX, FRAME_POINTER_REGNUM, EHUSES, FRAME_POINTER_REGNUM, ARG_POINTER_REGNUM, and the PIC_OFFSET_TABLE_REGNUM.

void TARGET_SET_UP_BY_PROLOGUE (struct hard_reg_set_container *) [Target Hook]
This hook should add additional registers that are computed by the prologue to the hard regset for shrink-wrapping optimization purposes.
bool TARGET_WARN_FUNC_RETURN (tree)  
True if a function’s return statements should be checked for matching the function’s return type. This includes checking for falling off the end of a non-void function. Return false if no such check should be made.

18.9.14 Shrink-wrapping separate components

The prologue may perform a variety of target dependent tasks such as saving callee-saved registers, saving the return address, aligning the stack, creating a stack frame, initializing the PIC register, setting up the static chain, etc.

On some targets some of these tasks may be independent of others and thus may be shrink-wrapped separately. These independent tasks are referred to as components and are handled generically by the target independent parts of GCC.

Using the following hooks those prologue or epilogue components can be shrink-wrapped separately, so that the initialization (and possibly teardown) those components do is not done as frequently on execution paths where this would unnecessary.

What exactly those components are is up to the target code; the generic code treats them abstractly, as a bit in an sbitmap. These sbitmaps are allocated by the shrink_wrap.get_separate_components and shrink_wrap.components_for_bb hooks, and deallocated by the generic code.

sbitmap TARGET_SHRINK_WRAP_GET_SEPARATE_COMPONENTS (void)  [Target Hook]
This hook should return an sbitmap with the bits set for those components that can be separately shrink-wrapped in the current function. Return NULL if the current function should not get any separate shrink-wrapping. Don’t define this hook if it would always return NULL. If it is defined, the other hooks in this group have to be defined as well.

sbitmap TARGET_SHRINK_WRAP_COMPONENTS_FOR_BB (basic_block)  [Target Hook]
This hook should return an sbitmap with the bits set for those components where either the prologue component has to be executed before the basic_block, or the epilogue component after it, or both.

void TARGET_SHRINK_WRAP_DISQUALIFY_COMPONENTS (sbitmap components, edge e, sbitmap edge_components, bool is_prologue)  [Target Hook]
This hook should clear the bits in the components bitmap for those components in edge_components that the target cannot handle on edge e, where is_prologue says if this is for a prologue or an epilogue instead.

void TARGET_SHRINK_WRAP_EMIT_PROLOGUE_COMPONENTS (sbitmap)  [Target Hook]
Emit prologue insns for the components indicated by the parameter.

void TARGET_SHRINK_WRAP_EMIT_EPILOGUE_COMPONENTS (sbitmap)  [Target Hook]
Emit epilogue insns for the components indicated by the parameter.
Mark the components in the parameter as handled, so that the prologue and epilogue named patterns know to ignore those components. The target code should not hang on to the bitmap, it will be deleted after this call.

18.9.15 Stack smashing protection

This hook returns a DECL node for the external variable to use for the stack protection guard. This variable is initialized by the runtime to some random value and is used to initialize the guard value that is placed at the top of the local stack frame. The type of this variable must be ptr_type_node.

The default version of this hook creates a variable called '__stack_chk_guard', which is normally defined in 'libgcc2.c'.

This hook returns a CALL_EXPR that alerts the runtime that the stack protect guard variable has been modified. This expression should involve a call to a noreturn function.

The default version of this hook invokes a function called '__stack_chk_fail', taking no arguments. This function is normally defined in 'libgcc2.c'.

Returns true if the target wants GCC’s default stack protect runtime support, otherwise return false. The default implementation always returns true.

Whether this target supports splitting the stack when the options described in opts have been passed. This is called after options have been parsed, so the target may reject splitting the stack in some configurations. The default version of this hook returns false. If report is true, this function may issue a warning or error; if report is false, it must simply return a value.

The hook is used for options that have a non-trivial list of possible option values. OPTION_CODE is option code of opt_code enum type. PREFIX is used for bash completion and allows an implementation to return more specific completion based on the prefix. All string values should be allocated from heap memory and consumers should release them. The result will be pruned to cases with PREFIX if not NULL.

18.9.16 Miscellaneous register hooks

Set to true if each call that binds to a local definition explicitly clobbers or sets all non-fixed registers modified by performing the call. That is, by the call pattern itself, or by code that might be inserted by the linker (e.g. stubs, veneers,
branch islands), but not including those modifiable by the callee. The affected registers may be mentioned explicitly in the call pattern, or included as clobbers in CALL, INSN, FUNCTION, USAGE. The default version of this hook is set to false. The purpose of this hook is to enable the fipa-ra optimization.

18.10 Implementing the Varargs Macros

GCC comes with an implementation of <varargs.h> and <stdarg.h> that work without change on machines that pass arguments on the stack. Other machines require their own implementations of varargs, and the two machine independent header files must have conditionals to include it.

ISO <stdarg.h> differs from traditional <varargs.h> mainly in the calling convention for va_start. The traditional implementation takes just one argument, which is the variable in which to store the argument pointer. The ISO implementation of va_start takes an additional second argument. The user is supposed to write the last named argument of the function here.

However, va_start should not use this argument. The way to find the end of the named arguments is with the built-in functions described below.

__builtin_savereg ()

[Macro]

Use this built-in function to save the argument registers in memory so that the varargs mechanism can access them. Both ISO and traditional versions of va_start must use __builtin_savereg, unless you use TARGET_EXPAND_BUILTIN_SAVES (see below) instead.

On some machines, __builtin_savereg is open-coded under the control of the target hook TARGET_EXPAND_BUILTIN_SAVES. On other machines, it calls a routine written in assembler language, found in 'libgcc2.c'.

Code generated for the call to __builtin_savereg appears at the beginning of the function, as opposed to where the call to __builtin_savereg is written, regardless of what the code is. This is because the registers must be saved before the function starts to use them for its own purposes.

__builtin_next_arg (lastarg)

[Macro]

This builtin returns the address of the first anonymous stack argument, as type void *. If ARGS_GROW_DOWNWARD, it returns the address of the location above the first anonymous stack argument. Use it in va_start to initialize the pointer for fetching arguments from the stack. Also use it in va_start to verify that the second parameter lastarg is the last named argument of the current function.

__builtin_classify_type (object)

[Macro]

Since each machine has its own conventions for which data types are passed in which kind of register, your implementation of va_arg has to embody these conventions. The easiest way to categorize the specified data type is to use __builtin_classify_type together with sizeof and __alignof__.

__builtin_classify_type ignores the value of object, considering only its data type. It returns an integer describing what kind of type that is—integer, floating, pointer, structure, and so on.
The file `typeclass.h` defines an enumeration that you can use to interpret the values of `__builtin_classify_type`.

These machine description macros help implement varargs:

```c
rtx TARGET_EXPAND_BUILTIN_SAVEREQS (void)  [Target Hook]
If defined, this hook produces the machine-specific code for a call to `__builtin_saveregs`. This code will be moved to the very beginning of the function, before any parameter access are made. The return value of this function should be an RTX that contains the value to use as the return of `__builtin_saveregs`.

void TARGET_SETUP_INCOMING_VARARGS (cumulative_args_t
  args_so_far, const function_arg_info &arg, int *pretend_args_size, int
  second_time)  [Target Hook]
This target hook offers an alternative to using `__builtin_saveregs` and defining the hook `TARGET_EXPAND_BUILTIN_SAVEREQS`. Use it to store the anonymous register arguments into the stack so that all the arguments appear to have been passed consecutively on the stack. Once this is done, you can use the standard implementation of varargs that works for machines that pass all their arguments on the stack.

The argument `args_so_far` points to the `CUMULATIVE_ARGS` data structure, containing the values that are obtained after processing the named arguments. The argument `arg` describes the last of these named arguments.

The target hook should do two things: first, push onto the stack all the argument registers not used for the named arguments, and second, store the size of the data thus pushed into the int-valued variable pointed to by `pretend_args_size`. The value that you store here will serve as additional offset for setting up the stack frame.

Because you must generate code to push the anonymous arguments at compile time without knowing their data types, `TARGET_SETUP_INCOMING_VARARGS` is only useful on machines that have just a single category of argument register and use it uniformly for all data types.

If the argument `second_time` is nonzero, it means that the arguments of the function are being analyzed for the second time. This happens for an inline function, which is not actually compiled until the end of the source file. The hook `TARGET_SETUP_INCOMING_VARARGS` should not generate any instructions in this case.

```c
bool TARGET_STRICT_ARGUMENT_NAMING (cumulative_args_t ca)  [Target Hook]
Define this hook to return `true` if the location where a function argument is passed depends on whether or not it is a named argument.

This hook controls how the `named` argument to `TARGET_FUNCTION_ARG` is set for varargs andstdarg functions. If this hook returns `true`, the `named` argument is always true for named arguments, and false for unnamed arguments. If it returns `false`, but `TARGET_PRETEND_OUTGOING_VARARGS_NAMED` returns `true`, then all arguments are treated as named. Otherwise, all named arguments except the last are treated as named.

You need not define this hook if it always returns `false`.```
void TARGET_CALL_ARGS (rtx, tree)  
While generating RTL for a function call, this target hook is invoked once for each 
argument passed to the function, either a register returned by TARGET_FUNCTION_ARG 
or a memory location. It is called just before the point where argument registers are 
stored. The type of the function to be called is also passed as the second argument; 
it is NULL_TREE for libcalls. The TARGET_END_CALL_ARGS hook is invoked just after 
the code to copy the return reg has been emitted. This functionality can be used 
to perform special setup of call argument registers if a target needs it. For functions 
without arguments, the hook is called once with pc_rtx passed instead of an argument 
register. Most ports do not need to implement anything for this hook.

void TARGET_END_CALL_ARGS (void)  
This target hook is invoked while generating RTL for a function call, just after the 
point where the return reg is copied into a pseudo. It signals that all the call argument 
and return registers for the just emitted call are now no longer in use. Most ports do 
not need to implement anything for this hook.

bool TARGET_PRETEND_OUTGOING_VARARGS_NAMED (cumulative_args_t ca)  
If you need to conditionally change ABIs so that one works with TARGET_SETUP_ 
INCOMING_VARARGS, but the other works like neither TARGET_SETUP_INCOMING_ 
VARARGS nor TARGET_STRICT_ARGUMENT_NAMING was defined, then define this hook 
to return true if TARGET_SETUP_INCOMING_VARARGS is used, false otherwise. 
Otherwise, you should not define this hook.

rtx TARGET_LOAD_BOUNDS_FOR_ARG (rtx slot, rtx arg, rtx slot_no)  
This hook is used by expand pass to emit insn to load bounds of arg passed in slot. 
Expand pass uses this hook in case bounds of arg are not passed in register. If slot 
is a memory, then bounds are loaded as for regular pointer loaded from memory. If 
slot is not a memory then slot_no is an integer constant holding number of the target 
dependent special slot which should be used to obtain bounds. Hook returns RTX 
holding loaded bounds.

void TARGET_STORE_BOUNDS_FOR_ARG (rtx arg, rtx slot, rtx bounds, rtx slot_no)  
This hook is used by expand pass to emit insn to store bounds of arg passed in slot. 
Expand pass uses this hook in case bounds of arg are not passed in register. If slot 
is a memory, then bounds are stored as for regular pointer stored in memory. If slot 
is not a memory then slot_no is an integer constant holding number of the target 
dependent special slot which should be used to store bounds.

rtx TARGET_LOAD_RETURNED_BOUNDS (rtx slot)  
This hook is used by expand pass to emit insn to load bounds returned by function 
call in slot. Hook returns RTX holding loaded bounds.

void TARGET_STORE_RETURNED_BOUNDS (rtx slot, rtx bounds)  
This hook is used by expand pass to emit insn to store bounds returned by function 
call into slot.
18.11 Support for Nested Functions

Taking the address of a nested function requires special compiler handling to ensure that the static chain register is loaded when the function is invoked via an indirect call.

GCC has traditionally supported nested functions by creating an executable trampoline at run time when the address of a nested function is taken. This is a small piece of code which normally resides on the stack, in the stack frame of the containing function. The trampoline loads the static chain register and then jumps to the real address of the nested function.

The use of trampolines requires an executable stack, which is a security risk. To avoid this problem, GCC also supports another strategy: using descriptors for nested functions. Under this model, taking the address of a nested function results in a pointer to a non-executable function descriptor object. Initializing the static chain from the descriptor is handled at indirect call sites.

On some targets, including HPPA and IA-64, function descriptors may be mandated by the ABI or be otherwise handled in a target-specific way by the back end in its code generation strategy for indirect calls. GCC also provides its own generic descriptor implementation to support the ‘-fno-trampolines’ option. In this case runtime detection of function descriptors at indirect call sites relies on descriptor pointers being tagged with a bit that is never set in bare function addresses. Since GCC’s generic function descriptors are not ABI-compliant, this option is typically used only on a per-language basis (notably by Ada) or when it can otherwise be applied to the whole program.

For languages other than Ada, the -ftrampolines and -fno-trampolines options currently have no effect, and trampolines are always generated on platforms that need them for nested functions.

Define the following hook if your backend either implements ABI-specified descriptor support, or can use GCC’s generic descriptor implementation for nested functions.

```c
int TARGET_CUSTOM_FUNCTION_DESCRIPTORS [Target Hook]
```

If the target can use GCC’s generic descriptor mechanism for nested functions, define this hook to a power of 2 representing an unused bit in function pointers which can be used to differentiate descriptors at run time. This value gives the number of bytes by which descriptor pointers are misaligned compared to function pointers. For example, on targets that require functions to be aligned to a 4-byte boundary, a value of either 1 or 2 is appropriate unless the architecture already reserves the bit for another purpose, such as on ARM.

Define this hook to 0 if the target implements ABI support for function descriptors in its standard calling sequence, like for example HPPA or IA-64.

Using descriptors for nested functions eliminates the need for trampolines that reside on the stack and require it to be made executable.

The following macros tell GCC how to generate code to allocate and initialize an executable trampoline. You can also use this interface if your back end needs to create ABI-specified non-executable descriptors; in this case the "trampoline" created is the descriptor containing data only.

The instructions in an executable trampoline must do two things: load a constant address into the static chain register, and jump to the real address of the nested function. On CISC
machines such as the m68k, this requires two instructions, a move immediate and a jump. Then the two addresses exist in the trampoline as word-long immediate operands. On RISC machines, it is often necessary to load each address into a register in two parts. Then pieces of each address form separate immediate operands.

The code generated to initialize the trampoline must store the variable parts—the static chain value and the function address—into the immediate operands of the instructions. On a CISC machine, this is simply a matter of copying each address to a memory reference at the proper offset from the start of the trampoline. On a RISC machine, it may be necessary to take out pieces of the address and store them separately.

```c
void TARGET_ASM_TRAMPOLINE_TEMPLATE (FILE *f)       [Target Hook]
    This hook is called by assemble_trampoline_template to output, on the stream f, assembler code for a block of data that contains the constant parts of a trampoline. This code should not include a label—the label is taken care of automatically.

    If you do not define this hook, it means no template is needed for the target. Do not define this hook on systems where the block move code to copy the trampoline into place would be larger than the code to generate it on the spot.

TRAMPOLINE_SECTION       [Macro]
    Return the section into which the trampoline template is to be placed (see Section 18.18 [Sections], page 609). The default value is readonly_data_section.

TRAMPOLINE_SIZE           [Macro]
    A C expression for the size in bytes of the trampoline, as an integer.

TRAMPOLINE_ALIGNMENT      [Macro]
    Alignment required for trampolines, in bits.

    If you don’t define this macro, the value of FUNCTION_ALIGNMENT is used for aligning trampolines.

void TARGET_TRAMPOLINE_INIT (rtx m_tramp, tree fndecl, rtx static_chain)  [Target Hook]
    This hook is called to initialize a trampoline. m_tramp is an RTX for the memory block for the trampoline; fndecl is the FUNCTIONDECL for the nested function; static_chain is an RTX for the static chain value that should be passed to the function when it is called.

    If the target defines TARGET_ASM_TRAMPOLINE_TEMPLATE, then the first thing this hook should do is emit a block move into m_tramp from the memory block returned by assemble_trampoline_template. Note that the block move need only cover the constant parts of the trampoline. If the target isolates the variable parts of the trampoline to the end, not all TRAMPOLINE_SIZE bytes need be copied.

    If the target requires any other actions, such as flushing caches (possibly calling function maybe_emit_call_builtin__clear_cache) or enabling stack execution, these actions should be performed after initializing the trampoline proper.
void TARGET_EMIT_CALL_BUILTIN___CLEAR_CACHE (rtx begin, [Target Hook]
   rtx end)
On targets that do not define a clear_cache insn expander, but that define the
CLEAR_CACHEInsn macro, maybe_emit_call_builtin___clear_cache relies on this target
hook to clear an address range in the instruction cache.

The default implementation calls the __clear_cache builtin, taking the assembler
name from the builtin declaration. Overriding definitions may call alternate functions,
with alternate calling conventions, or emit alternate RTX to perform the job.

rtx TARGET_TRAMPOLINE_ADJUST_ADDRESS (rtx addr) [Target Hook]
This hook should perform any machine-specific adjustment in the address of the
trampoline. Its argument contains the address of the memory block that was passed
to TARGET_TRAMPOLINE_INIT. In case the address to be used for a function call should
be different from the address at which the template was stored, the different address
should be returned; otherwise addr should be returned unchanged. If this hook is not
defined, addr will be used for function calls.

Implementing trampolines is difficult on many machines because they have separate in-
stinction and data caches. Writing into a stack location fails to clear the memory in the
instruction cache, so when the program jumps to that location, it executes the old contents.

Here are two possible solutions. One is to clear the relevant parts of the instruction cache
whenever a trampoline is set up. The other is to make all trampolines identical, by having
them jump to a standard subroutine. The former technique makes trampoline execution
faster; the latter makes initialization faster.

To clear the instruction cache when a trampoline is initialized, define the following macro.

CLEAR_INSN_CACHE (beg, end) [Macro]
If defined, expands to a C expression clearing the instruction cache in the specified
interval. The definition of this macro would typically be a series of asm statements.
Both beg and end are pointer expressions.

To use a standard subroutine, define the following macro. In addition, you must make
sure that the instructions in a trampoline fill an entire cache line with identical instructions,
or else ensure that the beginning of the trampoline code is always aligned at the same point
in its cache line. Look in `m68k.h` as a guide.

TRANSFER_FROM_TRAMPOLINE [Macro]
Define this macro if trampolines need a special subroutine to do their work. The
macro should expand to a series of asm statements which will be compiled with GCC.
They go in a library function named __transfer_from_trampoline.

If you need to avoid executing the ordinary prologue code of a compiled C function
when you jump to the subroutine, you can do so by placing a special label of your
own in the assembler code. Use one asm statement to generate an assembler label,
and another to make the label global. Then trampolines can use that label to jump
directly to your special assembler code.


18.12 Implicit Calls to Library Routines

Here is an explanation of implicit calls to library routines.

**DECLARE_LIBRARY_RENAMES** [Macro]
This macro, if defined, should expand to a piece of C code that will get expanded when compiling functions for libgcc.a. It can be used to provide alternate names for GCC’s internal library functions if there are ABI-mandated names that the compiler should provide.

**void TARGET_INIT_LIBFUNCS (void)** [Target Hook]
This hook should declare additional library routines or rename existing ones, using the functions `set_optab_libfunc` and `init_one_libfunc` defined in ‘optabs.c’. `init_optabs` calls this macro after initializing all the normal library routines.

The default is to do nothing. Most ports don’t need to define this hook.

**bool TARGET_LIBFUNC_GNU_PREFIX** [Target Hook]
If false (the default), internal library routines start with two underscores. If set to true, these routines start with `__gnu_` instead. E.g., `__muldi3` changes to `__gnu_muldi3`. This currently only affects functions defined in ‘libgcc2.c’. If this is set to true, the ‘tm.h’ file must also `#define LIBGCC2_GNU_PREFIX`.

**FLOAT_LIB_COMPARE_RETURNS_BOOL (mode, comparison)** [Macro]
This macro should return `true` if the library routine that implements the floating point comparison operator `comparison` in mode `mode` will return a boolean, and `false` if it will return a tristate.

GCC’s own floating point libraries return tristates from the comparison operators, so the default returns false always. Most ports don’t need to define this macro.

**TARGET_LIB_INT_CMP_BIASED** [Macro]
This macro should evaluate to `true` if the integer comparison functions (like `__cmpdi2`) return 0 to indicate that the first operand is smaller than the second, 1 to indicate that they are equal, and 2 to indicate that the first operand is greater than the second. If this macro evaluates to `false` the comparison functions return -1, 0, and 1 instead of 0, 1, and 2. If the target uses the routines in ‘libgcc.a’, you do not need to define this macro.

**TARGET_HAS_NO_HW_DIVIDE** [Macro]
This macro should be defined if the target has no hardware divide instructions. If this macro is defined, GCC will use an algorithm which make use of simple logical and arithmetic operations for 64-bit division. If the macro is not defined, GCC will use an algorithm which make use of a 64-bit by 32-bit divide primitive.

**TARGET_EDOM** [Macro]
The value of `EDOM` on the target machine, as a C integer constant expression. If you don’t define this macro, GCC does not attempt to deposit the value of `EDOM` into `errno` directly. Look in ‘/usr/include/errno.h’ to find the value of `EDOM` on your system.

If you do not define `TARGET_EDOM`, then compiled code reports domain errors by calling the library function and letting it report the error. If mathematical functions
on your system use `matherr` when there is an error, then you should leave `TARGET_EDOM` undefined so that `matherr` is used normally.

**GEN_ERRNO_RTX**

[Macro]
Define this macro as a C expression to create an rtl expression that refers to the global “variable” `errno`. (On certain systems, `errno` may not actually be a variable.) If you don’t define this macro, a reasonable default is used.

**bool TARGET_LIBC_HAS_FUNCTION**

[Target Hook]

```
enum function_class fn_class,  
tree type
```

This hook determines whether a function from a class of functions `fn_class` is present in the target C library. If `type` is NULL, the caller asks for support for all standard (float, double, long double) types. If `type` is non-NULL, the caller asks for support for a specific type.

**bool TARGET_LIBC_HAS_FAST_FUNCTION**

[Target Hook]

```
int fcode
```

This hook determines whether a function from a class of functions `fcode` has a fast implementation.

**NEXT_OBJC_RUNTIME**

[Macro]
Set this macro to 1 to use the "NeXT" Objective-C message sending conventions by default. This calling convention involves passing the object, the selector and the method arguments all at once to the method-lookup library function. This is the usual setting when targeting Darwin/Mac OS X systems, which have the NeXT runtime installed.

If the macro is set to 0, the "GNU" Objective-C message sending convention will be used by default. This convention passes just the object and the selector to the method-lookup function, which returns a pointer to the method.

In either case, it remains possible to select code-generation for the alternate scheme, by means of compiler command line switches.

### 18.13 Addressing Modes

This is about addressing modes.

**HAVE_PRE_INCREMENT**

[Macro]
A C expression that is nonzero if the machine supports pre-increment addressing.

**HAVE_PRE_DECREMENT**

[Macro]
A C expression that is nonzero if the machine supports pre-decrement addressing.

**HAVE_POST_INCREMENT**

[Macro]
A C expression that is nonzero if the machine supports post-increment addressing.

**HAVE_POST_DECREMENT**

[Macro]
A C expression that is nonzero if the machine supports post-decrement addressing.

**HAVE_PRE_MODIFY_DISP**

[Macro]
A C expression that is nonzero if the machine supports pre- or post-address side-effect generation involving constants other than the size of the memory operand.

**HAVE_POST_MODIFY_DISP**

[Macro]
A C expression that is nonzero if the machine supports pre- or post-address side-effect generation involving a register displacement.
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**CONSTANT_ADDRESS_P** \((x)\)  
A C expression that is 1 if the RTX \(x\) is a constant which is a valid address. On most machines the default definition of \((\text{CONSTANT_P} (x) \&\& \text{GET_CODE} (x) \neq \text{CONST_DOUBLE})\) is acceptable, but a few machines are more restrictive as to which constant addresses are supported.

**CONSTANT_P** \((x)\)  
\(\text{CONSTANT_P}\), which is defined by target-independent code, accepts integer-values expressions whose values are not explicitly known, such as \(\text{symbol_ref}\), \(\text{label_ref}\), and high expressions and \text{const} arithmetic expressions, in addition to \text{const_int} and \text{const_double} expressions.

**MAX_REGS_PER_ADDRESS**  
A number, the maximum number of registers that can appear in a valid memory address. Note that it is up to you to specify a value equal to the maximum number that \(\text{TARGET_LEGITIMATE_ADDRESS_P}\) would ever accept.

**bool** \(\text{TARGET_LEGITIMATE_ADDRESS_P}\) \((\text{machine_mode mode, rtx x, bool strict})\)  
A function that returns whether \(x\) (an RTX) is a legitimate memory address on the target machine for a memory operand of mode \(\text{mode}\). Legitimate addresses are defined in two variants: a strict variant and a non-strict one. The \text{strict} parameter chooses which variant is desired by the caller.

The strict variant is used in the reload pass. It must be defined so that any pseudo-register that has not been allocated a hard register is considered a memory reference. This is because in contexts where some kind of register is required, a pseudo-register with no hard register must be rejected. For non-hard registers, the strict variant should look up the \text{reg_renumber} array; it should then proceed using the hard register number in the array, or treat the pseudo as a memory reference if the array holds \(-1\).

The non-strict variant is used in other passes. It must be defined to accept all pseudo-registers in every context where some kind of register is required.

Normally, constant addresses which are the sum of a \(\text{symbol_ref}\) and an integer are stored inside a \text{const} RTX to mark them as constant. Therefore, there is no need to recognize such sums specifically as legitimate addresses. Normally you would simply recognize any \text{const} as legitimate.

Usually \(\text{PRINT_OPERAND_ADDRESS}\) is not prepared to handle constant sums that are not marked with \text{const}. It assumes that a naked \text{plus} indicates indexing. If so, then you \text{must} reject such naked constant sums as illegitimate addresses, so that none of them will be given to \(\text{PRINT_OPERAND_ADDRESS}\).

On some machines, whether a symbolic address is legitimate depends on the section that the address refers to. On these machines, define the target hook \(\text{TARGET_ENCODE_SECTION_INFO}\) to store the information into the \(\text{symbol_ref}\), and then check for it here. When you see a \text{const}, you will have to look inside it to find the \(\text{symbol_ref}\) in order to determine the section. See Section 18.20 [Assembler Format], page 615.

Some ports are still using a deprecated legacy substitute for this hook, the \(\text{GO_IF_LEGITIMATE_ADDRESS}\) macro. This macro has this syntax:
#define GO_IF_LEGITIMATE_ADDRESS (mode, x, label)
and should goto label if the address x is a valid address on the target machine for
a memory operand of mode mode.

Compiler source files that want to use the strict variant of this macro define the macro
REG_OK_STRICT. You should use an #ifdef REG_OK_STRICT conditional to define the
strict variant in that case and the non-strict variant otherwise.

Using the hook is usually simpler because it limits the number of files that are re-
compiled when changes are made.

TARGET_MEMCONSTRAINT
[Macro]
A single character to be used instead of the default 'm' character for general memory
addresses. This defines the constraint letter which matches the memory addresses
accepted by TARGET_LEGITIMATE_ADDRESS_P. Define this macro if you want to sup-
port new address formats in your back end without changing the semantics of the
'm' constraint. This is necessary in order to preserve functionality of inline assembly
constructs using the 'm' constraint.

FIND_BASE_TERM (x)
[Macro]
A C expression to determine the base term of address x, or to provide a simplified
version of x from which 'alias.c' can easily find the base term. This macro is used
in only two places: find_base_value and find_base_term in 'alias.c'.

It is always safe for this macro to not be defined. It exists so that alias analysis can
understand machine-dependent addresses.

The typical use of this macro is to handle addresses containing a label_ref or sym-
bol_ref within an UNSPEC.

rtx TARGET_LEGITIMIZE_ADDRESS (rtx x, rtx oldx, machine_mode mode)
[Target Hook]
This hook is given an invalid memory address x for an operand of mode mode and
should try to return a valid memory address.

x will always be the result of a call to break_out_memory_refs, and oldx will be the
operand that was given to that function to produce x.

The code of the hook should not alter the substructure of x. If it transforms x into
a more legitimate form, it should return the new x.

It is not necessary for this hook to come up with a legitimate address, with the
exception of native TLS addresses (see Section 18.25 [Emulated TLS], page 655). The
compiler has standard ways of doing so in all cases. In fact, if the target supports
only emulated TLS, it is safe to omit this hook or make it return x if it cannot find
a valid way to legitimize the address. But often a machine-dependent strategy can
generate better code.

LEGITIMIZE_RELOAD_ADDRESS (x, mode, opnum, type, ind_levels, win)
[Macro]
A C compound statement that attempts to replace x, which is an address that needs
reloading, with a valid memory address for an operand of mode mode. win will be a
C statement label elsewhere in the code. It is not necessary to define this macro, but
it might be useful for performance reasons.
For example, on the i386, it is sometimes possible to use a single reload register instead of two by reloading a sum of two pseudo registers into a register. On the other hand, for number of RISC processors offsets are limited so that often an intermediate address needs to be generated in order to address a stack slot. By defining `LEGITIMIZE_RELOAD_ADDRESS` appropriately, the intermediate addresses generated for adjacent some stack slots can be made identical, and thus be shared.

Note: This macro should be used with caution. It is necessary to know something of how reload works in order to effectively use this, and it is quite easy to produce macros that build in too much knowledge of reload internals.

Note: This macro must be able to reload an address created by a previous invocation of this macro. If it fails to handle such addresses then the compiler may generate incorrect code or abort.

The macro definition should use `push_reload` to indicate parts that need reloading; `opnum`, `type` and `ind_levels` are usually suitable to be passed unaltered to `push_reload`.

The code generated by this macro must not alter the substructure of `x`. If it transforms `x` into a more legitimate form, it should assign `x` (which will always be a C variable) a new value. This also applies to parts that you change indirectly by calling `push_reload`.

The macro definition may use `strict_memory_address_p` to test if the address has become legitimate.

If you want to change only a part of `x`, one standard way of doing this is to use `copy_rtx`. Note, however, that it unshares only a single level of rtl. Thus, if the part to be changed is not at the top level, you’ll need to replace first the top level. It is not necessary for this macro to come up with a legitimate address; but often a machine-dependent strategy can generate better code.

```c
bool TARGET_MODE_DEPENDENT_ADDRESS_P (const rtx addr, addr_space_t addrspace) [Target Hook]

This hook returns true if memory address `addr` in address space `addrspace` can have different meanings depending on the machine mode of the memory reference it is used for or if the address is valid for some modes but not others.

Autoincrement and autodecrement addresses typically have mode-dependent effects because the amount of the increment or decrement is the size of the operand being addressed. Some machines have other mode-dependent addresses. Many RISC machines have no mode-dependent addresses.

You may assume that `addr` is a valid address for the machine.

The default version of this hook returns false.
```

```c
bool TARGET_LEGITIMATE_CONSTANT_P (machine_mode mode, rtx x) [Target Hook]

This hook returns true if `x` is a legitimate constant for a `mode`-mode immediate operand on the target machine. You can assume that `x` satisfies `CONSTANT_P`, so you need not check this.

The default definition returns true.
```
bool TARGET_PRECOMPUTE_TLS_P (machine_mode mode, rtx x)  [Target Hook]
This hook returns true if x is a TLS operand on the target machine that should be
pre-computed when used as the argument in a call. You can assume that x satisfies
CONSTANT_P, so you need not check this.
The default definition returns false.

rtx TARGET_DELEGITIMIZE_ADDRESS (rtx x)  [Target Hook]
This hook is used to undo the possibly obfuscating effects of the LEGITIMIZE_ADDRESS
and LEGITIMIZE_RELOAD_ADDRESS target macros. Some backend implementations
of these macros wrap symbol references inside an UNSPEC rtx to represent PIC or
similar addressing modes. This target hook allows GCC's optimizers to understand
the semantics of these opaque UNSPECs by converting them back into their original
form.

bool TARGET_CONST_NOT_OK_FOR_DEBUG_P (rtx x)  [Target Hook]
This hook should return true if x should not be emitted into debug sections.

bool TARGET_CANNOT_FORCE_CONST_MEM (machine_mode mode, rtx x)  [Target Hook]
This hook should return true if x is of a form that cannot (or should not) be spilled
to the constant pool. mode is the mode of x.
The default version of this hook returns false.
The primary reason to define this hook is to prevent reload from deciding that a
non-legitimate constant would be better reloaded from the constant pool instead of
spilling and reloading a register holding the constant. This restriction is often true of
addresses of TLS symbols for various targets.

bool TARGET_USE_BLOCKS_FOR_CONSTANT_P (machine_mode mode, const rtx x)  [Target Hook]
This hook should return true if pool entries for constant x can be placed in an object_
block structure. mode is the mode of x.
The default version returns false for all constants.

bool TARGET_USE_BLOCKS_FORDECL_P (const tree decl)  [Target Hook]
This hook should return true if pool entries for decl should be placed in an object_
block structure.
The default version returns true for all decls.

tree TARGET_BUILTIN_RECIPROCAL (tree fndecl)  [Target Hook]
This hook should return the DECL of a function that implements the reciprocal of
the machine-specific builtin function fndecl, or NULL_TREE if such a function is not
available.

tree TARGET_VECTORIZE_BUILTIN_MASK_FOR_LOAD (void)  [Target Hook]
This hook should return the DECL of a function f that given an address addr as an
argument returns a mask m that can be used to extract from two vectors the relevant
data that resides in addr in case addr is not properly aligned.
The autovectorizer, when vectorizing a load operation from an address \( \text{addr} \) that may be unaligned, will generate two vector loads from the two aligned addresses around \( \text{addr} \). It then generates a \texttt{REALIGN\_LOAD} operation to extract the relevant data from the two loaded vectors. The first two arguments to \texttt{REALIGN\_LOAD}, \( v1 \) and \( v2 \), are the two vectors, each of size \( \text{VS} \), and the third argument, \( \text{OFF} \), defines how the data will be extracted from these two vectors: if \( \text{OFF} \) is 0, then the returned vector is \( v2 \); otherwise, the returned vector is composed from the last \( \text{VS}-\text{OFF} \) elements of \( v1 \) concatenated to the first \( \text{OFF} \) elements of \( v2 \).

If this hook is defined, the autovectorizer will generate a call to \( f \) (using the \texttt{DECL} tree that this hook returns) and will use the return value of \( f \) as the argument \( \text{OFF} \) to \texttt{REALIGN\_LOAD}. Therefore, the mask \( m \) returned by \( f \) should comply with the semantics expected by \texttt{REALIGN\_LOAD} described above. If this hook is not defined, then \( \text{addr} \) will be used as the argument \( \text{OFF} \) to \texttt{REALIGN\_LOAD}, in which case the low \( \log_2(\text{VS}) - 1 \) bits of \( \text{addr} \) will be considered.

\begin{verbatim}
int TARGET_VECTORIZE_BUILTIN_VECTORIZATION_COST (enum vect_cost_for_stmt type_of_cost, tree vectype, int misalign)
    // Returns cost of different scalar or vector statements for vectorization cost model. For vector memory operations the cost may depend on type (vectype) and misalignment value (misalign).

poly_uint64 TARGET_VECTORIZE_PREFERRED_VECTOR_ALIGNMENT (const tree type)
    // This hook returns the preferred alignment in bits for accesses to vectors of type \( \text{type} \) in vectorized code. This might be less than or greater than the ABI-defined value returned by \texttt{TARGET\_VECTOR\_ALIGNMENT}. It can be equal to the alignment of a single element, in which case the vectorizer will not try to optimize for alignment.
    // The default hook returns \texttt{TYPE\_ALIGN(\text{type})}, which is correct for most targets.

bool TARGET_VECTORIZE_VECTOR_ALIGNMENT_REACHABLE (const tree type, bool is_packed)
    // Return true if vector alignment is reachable (by peeling N iterations) for the given scalar type \( \text{type} \). is_packed is false if the scalar access using \( \text{type} \) is known to be naturally aligned.

bool TARGET_VECTORIZE_VEC_PERM_CONST (machine_mode mode, rtx output, rtx in0, rtx in1, const vec_perm_indices &sel)
    // This hook is used to test whether the target can permute up to two vectors of mode \( \text{mode} \) using the permutation vector \( \text{sel} \), and also to emit such a permutation. In the former case \( \text{in0}, \text{in1} \) and \( \text{out} \) are all null. In the latter case \( \text{in0} \) and \( \text{in1} \) are the source vectors and \( \text{out} \) is the destination vector; all three are operands of mode \( \text{mode} \). \( \text{in1} \) is the same as \( \text{in0} \) if \( \text{sel} \) describes a permutation on one vector instead of two.
    // Return true if the operation is possible, emitting instructions for it if rtxes are provided.
    // If the hook returns false for a mode with multibyte elements, GCC will try the equivalent byte operation. If that also fails, it will try forcing the selector into a register and using the \texttt{vec\_permmode} instruction pattern. There is no need for the hook to handle these two implementation approaches itself.
\end{verbatim}
tree TARGET_VECTORIZE_BUILTIN_VECTORIZED_FUNCTION

(unsigned code, tree vec_type_out, tree vec_type_in)

This hook should return the decl of a function that implements the vectorized variant
of the function with the combined_fn code code or NULL_TREE if such a function
is not available. The return type of the vectorized function shall be of vector type
vec_type_out and the argument types should be vec_type_in.

tree TARGET_VECTORIZE_BUILTIN_MD_VECTORIZED_FUNCTION

(tree fndecl, tree vec_type_out, tree vec_type_in)

This hook should return the decl of a function that implements the vectorized variant
of target built-in function fndecl. The return type of the vectorized function shall
be of vector type vec_type_out and the argument types should be vec_type_in.

bool TARGET_VECTORIZE_SUPPORT_VECTOR_MISALIGNMENT

(machine_mode mode, const_tree type, int misalignment, bool is_packed)

This hook should return true if the target supports misaligned vector store/load of a
specific factor denoted in the misalignment parameter. The vector store/load should
be of machine mode mode and the elements in the vectors should be of type type.
is_packed parameter is true if the memory access is defined in a packed struct.

machine_mode TARGET_VECTORIZE_PREFERRED_SIMD_MODE

(scalar_mode mode)

This hook should return the preferred mode for vectorizing scalar mode mode. The
default is equal to word_mode, because the vectorizer can do some transformations
even in absence of specialized SIMD hardware.

machine_mode TARGET_VECTORIZE_SPLIT_REDUCTION

(machine_mode)

This hook should return the preferred mode to split the final reduction step on mode
to. The reduction is then carried out reducing upper against lower halves of vectors
recursively until the specified mode is reached. The default is mode which means no
splitting.

unsigned int

TARGET_VECTORIZE_AUTOVECTORIZE_VECTOR_MODES (vector_modes

*modes, bool all)

If using the mode returned by TARGET_VECTORIZE_PREFERRED_SIMD_MODE is not the
only approach worth considering, this hook should add one mode to modes for each
useful alternative approach. These modes are then passed to TARGET_VECTORIZE_
RELATED_MODE to obtain the vector mode for a given element mode.

The modes returned in modes should use the smallest element mode possible for the
vectorization approach that they represent, preferring integer modes over floating-
pointing modes in the event of a tie. The first mode should be the TARGET_VECTORIZE_
PREFERRED_SIMD_MODE for its element mode.

If all is true, add suitable vector modes even when they are generally not expected to
be worthwhile.

The hook returns a bitmask of flags that control how the modes in modes are used.
The flags are:
VECT_COMPARE_COSTS

Tells the loop vectorizer to try all the provided modes and pick the one with the lowest cost. By default the vectorizer will choose the first mode that works.

The hook does not need to do anything if the vector returned by TARGET_VECTORIZE_PREFERRED_SIMD_MODE is the only one relevant for autovectorization. The default implementation adds no modes and returns 0.

opt_machine_mode TARGET_VECTORIZE_RELATED_MODE [Target Hook]
(machine_mode vector_mode, scalar_mode element_mode, poly_uint64 nunits)
If a piece of code is using vector mode vector_mode and also wants to operate on elements of mode element_mode, return the vector mode it should use for those elements. If nunits is nonzero, ensure that the mode has exactly nunits elements, otherwise pick whichever vector size pairs the most naturally with vector_mode. Return an empty opt_machine_mode if there is no supported vector mode with the required properties.

There is no prescribed way of handling the case in which nunits is zero. One common choice is to pick a vector mode with the same size as vector_mode; this is the natural choice if the target has a fixed vector size. Another option is to choose a vector mode with the same number of elements as vector_mode; this is the natural choice if the target has a fixed number of elements. Alternatively, the hook might choose a middle ground, such as trying to keep the number of elements as similar as possible while applying maximum and minimum vector sizes.

The default implementation uses mode_for_vector to find the requested mode, returning a mode with the same size as vector_mode when nunits is zero. This is the correct behavior for most targets.

opt_machine_mode TARGET_VECTORIZE_GET_MASK_MODE [Target Hook]
(machine_mode mode)
Return the mode to use for a vector mask that holds one boolean result for each element of vector mode mode. The returned mask mode can be a vector of integers (class MODE_VECTOR_INT), a vector of booleans (class MODE_VECTOR_BOOL) or a scalar integer (class MODE_INT). Return an empty opt_machine_mode if no such mask mode exists.

The default implementation returns a MODE_VECTOR_INT with the same size and number of elements as mode, if such a mode exists.

bool TARGET_VECTORIZE_EMPTY_MASK_IS_EXPENSIVE (unsigned ifn) [Target Hook]
This hook returns true if masked internal function ifn (really of type internal_fn) should be considered expensive when the mask is all zeros. GCC can then try to branch around the instruction instead.

void * TARGET_VECTORIZE_INIT_COST (class loop *loop_info, bool costing_for_scalar) [Target Hook]
This hook should initialize target-specific data structures in preparation for modeling the costs of vectorizing a loop or basic block. The default allocates three unsigned
integers for accumulating costs for the prologue, body, and epilogue of the loop or basic block. If `loop_info` is non-NULL, it identifies the loop being vectorized; otherwise a single block is being vectorized. If `costing_for_scalar` is true, it indicates the current cost model is for the scalar version of a loop or block; otherwise it is for the vector version.

```c
unsigned TARGET_VECTORIZE_ADD_STMT_COST (class vec_info *,  
void *data, int count, enum vect_cost_for_stmt kind, class _stmt_vec_info  
*stmt_info, tree vectype, int misalign, enum vect_cost_model_location  
where)
```

This hook should update the target-specific `data` in response to adding `count` copies of the given `kind` of statement to a loop or basic block. The default adds the builtin vectorizer cost for the copies of the statement to the accumulator specified by `where`, (the prologue, body, or epilogue) and returns the amount added. The return value should be viewed as a tentative cost that may later be revised.

```c
void TARGET_VECTORIZE_FINISH_COST (void *data, unsigned  
*prologue_cost, unsigned *body_cost, unsigned *epilogue_cost)
```

This hook should complete calculations of the cost of vectorizing a loop or basic block based on `data`, and return the prologue, body, and epilogue costs as unsigned integers. The default returns the value of the three accumulators.

```c
void TARGET_VECTORIZE_DESTROY_COST_DATA (void *data)
```

This hook should release `data` and any related data structures allocated by `TARGET_VECTORIZE_INIT_COST`. The default releases the accumulator.

```c
tree TARGET_VECTORIZE_BUILTIN_GATHER (const tree  
mem_vectype, const tree index_type, int scale)
```

Target builtin that implements vector gather operation. `mem_vectype` is the vector type of the load and `index_type` is scalar type of the index, scaled by `scale`. The default is `NULL_TREE` which means to not vectorize gather loads.

```c
tree TARGET_VECTORIZE_BUILTIN_SCATTER (const tree vectype,  
const tree index_type, int scale)
```

Target builtin that implements vector scatter operation. `vectype` is the vector type of the store and `index_type` is scalar type of the index, scaled by `scale`. The default is `NULL_TREE` which means to not vectorize scatter stores.

```c
int TARGET_SIMD_CLONE_COMPUTE_VECSIZE_AND_SIMDLEN (struct  
cgraph_node *, struct cgraph_simd_clone *, tree, int)
```

This hook should set `vecsize_mangle`, `vecsize_int`, `vecsize_float` fields in `simd_clone` structure pointed by `clone_info` argument and also `simdlen` field if it was previously 0. The hook should return 0 if SIMD clones shouldn’t be emitted, or number of `vecsize_mangle` variants that should be emitted.

```c
void TARGET_SIMD_CLONE_ADJUST (struct cgraph_node *)
```

This hook should add implicit `attribute(target("...")))` attribute to SIMD clone `node` if needed.
int TARGET_SIMD_CLONE_USABLE (struct cgraph_node *) [Target Hook]
This hook should return -1 if SIMD clone node shouldn’t be used in vectorized loops in current function, or non-negative number if it is usable. In that case, the smaller the number is, the more desirable it is to use it.

int TARGET_SIMT_VF (void) [Target Hook]
Return number of threads in SIMT thread group on the target.

int TARGET_OMP_DEVICE_KIND_ARCH_ISA (enum omp_device_kind_arch_isa trait, const char *name) [Target Hook]
Return 1 if trait name is present in the OpenMP context’s device trait set, return 0 if not present in any OpenMP context in the whole translation unit, or -1 if not present in the current OpenMP context but might be present in another OpenMP context in the same TU.

bool TARGET_GOACC_VALIDATE_DIMS (tree decl, int *dims, int fn_level, unsigned used) [Target Hook]
This hook should check the launch dimensions provided for an OpenACC compute region, or routine. Defaulted values are represented as -1 and non-constant values as 0. The fn_level is negative for the function corresponding to the compute region. For a routine it is the outermost level at which partitioned execution may be spawned. The hook should verify non-default values. If DECL is NULL, global defaults are being validated and unspecified defaults should be filled in. Diagnostics should be issued as appropriate. Return true, if changes have been made. You must override this hook to provide dimensions larger than 1.

int TARGET_GOACC_DIM_LIMIT (int axis) [Target Hook]
This hook should return the maximum size of a particular dimension, or zero if unbounded.

bool TARGET_GOACC_FORK_JOIN (gcall *call, const int *dims, bool is_fork) [Target Hook]
This hook can be used to convert IFN_GOACC_FORK and IFN_GOACC_JOIN function calls to target-specific gimple, or indicate whether they should be retained. It is executed during the oacc_device_lower pass. It should return true, if the call should be retained. It should return false, if it is to be deleted (either because target-specific gimple has been inserted before it, or there is no need for it). The default hook returns false, if there are no RTL expanders for them.

void TARGET_GOACC_REDUCTION (gcall *call) [Target Hook]
This hook is used by the oacc_transform pass to expand calls to the GOACC_REDUCTION internal function, into a sequence of gimple instructions. call is gimple statement containing the call to the function. This hook removes statement call after the expanded sequence has been inserted. This hook is also responsible for allocating any storage for reductions when necessary.

tree TARGET_PREFERRED_ELSE_VALUE (unsigned ifn, tree type, unsigned nops, tree *ops) [Target Hook]
This hook returns the target’s preferred final argument for a call to conditional internal function ifn (really of type internal_fn). type specifies the return type of the
function and ops are the operands to the conditional operation, of which there are nops.
For example, if ifn is IFN_COND_ADD, the hook returns a value of type type that should be used when ‘ops[0]’ and ‘ops[1]’ are conditionally added together.
This hook is only relevant if the target supports conditional patterns like cond_addm. The default implementation returns a zero constant of type type.

```c
[Target Hook]
tree TARGET_GOACC_ADJUST_PRIVATE_DECL (location_t loc, tree var, int level)
This hook, if defined, is used by accelerator target back-ends to adjust OpenACC variable declarations that should be made private to the given parallelism level (i.e. GOMP_DIM_GANG, GOMP_DIM_WORKER or GOMP_DIM_VECTOR). A typical use for this hook is to force variable declarations at the gang level to reside in GPU shared memory. loc may be used for diagnostic purposes.
You may also use the TARGET_GOACC_EXPAND_VAR_DECL hook if the adjusted variable declaration needs to be expanded to RTL in a non-standard way.

[Target Hook]
rtx TARGET_GOACC_EXPAND_VAR_DECL (tree var)
This hook, if defined, is used by accelerator target back-ends to expand specially handled kinds of VARDECL expressions. A particular use is to place variables with specific attributes inside special accelerator memories. A return value of NULL indicates that the target does not handle this VARDECL, and normal RTL expanding is resumed.
Only define this hook if your accelerator target needs to expand certain VARDECL nodes in a way that differs from the default. You can also adjust private variables at OpenACC device-lowering time using the TARGET_GOACC_ADJUST_PRIVATEDECL target hook.

[Target Hook]
tree TARGET_GOACC_CREATE_WORKER_BROADCAST_RECORD (tree rec, bool sender, const char *name)
Create a record used to propagate local-variable state from an active worker to other workers. A possible implementation might adjust the type of REC to place the new variable in shared GPU memory.
Presence of this target hook indicates that middle end neutering/broadcasting be used.

18.14 Anchored Addresses
GCC usually addresses every static object as a separate entity. For example, if we have:
```c
static int a, b, c;
int foo (void) { return a + b + c; }
```the code for foo will usually calculate three separate symbolic addresses: those of a, b and c. On some targets, it would be better to calculate just one symbolic address and access the three variables relative to it. The equivalent pseudocode would be something like:
```c
int foo (void)
{
    register int *xr = &x;
    return xr[&a - &x] + xr[&b - &x] + xr[&c - &x];
}
```
(which isn’t valid C). We refer to shared addresses like \( x \) as “section anchors”. Their use is controlled by \(-fsection-anchors\).

The hooks below describe the target properties that GCC needs to know in order to make effective use of section anchors. It won’t use section anchors at all unless either \TARGET_MIN_ANCHOR_OFFSET or \TARGET_MAX_ANCHOR_OFFSET is set to a nonzero value.

**HOST_WIDE_INT TARGET_MIN_ANCHOR_OFFSET**  
[Target Hook]  
The minimum offset that should be applied to a section anchor. On most targets, it should be the smallest offset that can be applied to a base register while still giving a legitimate address for every mode. The default value is 0.

**HOST_WIDE_INT TARGET_MAX_ANCHOR_OFFSET**  
[Target Hook]  
Like \TARGET_MIN_ANCHOR_OFFSET, but the maximum (inclusive) offset that should be applied to section anchors. The default value is 0.

**void TARGET_ASM_OUTPUT_ANCHOR (rtx x)**  
[Target Hook]  
Write the assembly code to define section anchor \( x \), which is a SYMBOL_REF for which \( \text{SYMBOL_REF_ANCHOR_P (x)} \) is true. The hook is called with the assembly output position set to the beginning of \( \text{SYMBOL_REF_BLOCK (x)} \).

If \ASM_OUTPUT_DEF\ is available, the hook’s default definition uses it to define the symbol as \(' . + \text{SYMBOL_REF_BLOCK_OFFSET (x)}'\). If \ASM_OUTPUT_DEF\ is not available, the hook’s default definition is \NULL, which disables the use of section anchors altogether.

**bool TARGET_USE_ANCHORS_FOR_SYMBOL_P (const rtx x)**  
[Target Hook]  
Return true if GCC should attempt to use anchors to access SYMBOL_REF \( x \). You can assume \( \text{SYMBOL_REF_HAS_BLOCK_INFO_P (x)} \) and \(!\text{SYMBOL_REF_ANCHOR_P (x)}\).

The default version is correct for most targets, but you might need to intercept this hook to handle things like target-specific attributes or target-specific sections.

### 18.15 Condition Code Status

Condition codes in GCC are represented as registers, which provides better schedulability for architectures that do have a condition code register, but on which most instructions do not affect it. The latter category includes most RISC machines.

Implicit clobbering would pose a strong restriction on the placement of the definition and use of the condition code. In the past the definition and use were always adjacent. However, recent changes to support trapping arithmetic may result in the definition and user being in different blocks. Thus, there may be a NOTE_INSN_BASIC_BLOCK between them. Additionally, the definition may be the source of exception handling edges.

These restrictions can prevent important optimizations on some machines. For example, on the IBM RS/6000, there is a delay for taken branches unless the condition code register is set three instructions earlier than the conditional branch. The instruction scheduler cannot perform this optimization if it is not permitted to separate the definition and use of the condition code register.

If there is a specific condition code register in the machine, use a hard register. If the condition code or comparison result can be placed in any general register, or if there are multiple condition registers, use a pseudo register. Registers used to store the condition code value will usually have a mode that is in class \MODE_CC.  

Alternatively, you can use **BImode** if the comparison operator is specified already in the compare instruction. In this case, you are not interested in most macros in this section.

### 18.15.1 Representation of condition codes using registers

**SELECT_CC_MODE** *(op, x, y)*

On many machines, the condition code may be produced by other instructions than compares, for example the branch can use directly the condition code set by a subtract instruction. However, on some machines when the condition code is set this way some bits (such as the overflow bit) are not set in the same way as a test instruction, so that a different branch instruction must be used for some conditional branches. When this happens, use the machine mode of the condition code register to record different formats of the condition code register. Modes can also be used to record which compare instruction (e.g. a signed or an unsigned comparison) produced the condition codes.

If other modes than **CCmode** are required, add them to `machine-modes.def` and define **SELECT_CC_MODE** to choose a mode given an operand of a compare. This is needed because the modes have to be chosen not only during RTL generation but also, for example, by instruction combination. The result of **SELECT_CC_MODE** should be consistent with the mode used in the patterns; for example to support the case of the add on the SPARC discussed above, we have the pattern

```c
#define SELECT_CC_MODE(OP,X,Y) \
(GET_MODE_CLASS (GET_MODE (X)) == MODE_FLOAT \
? ((OP == LT || OP == LE || OP == GT || OP == GE) \
? CCFPEmode : CCFPmode) \
: ((GET_CODE (X) == PLUS || GET_CODE (X) == MINUS \
|| GET_CODE (X) == NEG || GET_CODE (x) == ASHIFT) \
? CCNZmode : CCmode))
```

Another reason to use modes is to retain information on which operands were used by the comparison; see **REVERSIBLE_CC_MODE** later in this section.

You should define this macro if and only if you define extra CC modes in `machine-modes.def`.

**void TARGET_CANONICALIZE_COMPARISON (int *code, rtx *op0, rtx **op1, bool op0_preserve_value)**

On some machines not all possible comparisons are defined, but you can convert an invalid comparison into a valid one. For example, the Alpha does not have a `GT` comparison, but you can use an `LT` comparison instead and swap the order of the operands.
On such machines, implement this hook to do any required conversions. `code` is the initial comparison code and `op0` and `op1` are the left and right operands of the comparison, respectively. If `op0_preserve_value` is `true` the implementation is not allowed to change the value of `op0` since the value might be used in RTXs which aren’t comparisons. E.g. the implementation is not allowed to swap operands in that case.

GCC will not assume that the comparison resulting from this macro is valid but will see if the resulting insn matches a pattern in the `md` file.

You need not implement this hook if it would never change the comparison code or operands.

**REVERSIBLE_CC_MODE (mode)**

A C expression whose value is one if it is always safe to reverse a comparison whose mode is `mode`. If `SELECT_CC_MODE` can ever return `mode` for a floating-point inequality comparison, then `REVERSIBLE_CC_MODE (mode)` must be zero.

You need not define this macro if it would always returns zero or if the floating-point format is anything other than `IEEE_FLOAT_FORMAT`. For example, here is the definition used on the SPARC, where floating-point inequality comparisons are given either `CCFPmode` or `CCFPEmode`:

```c
#define REVERSIBLE_CC_MODE(MODE) \
((MODE) != CCFPmode && (MODE) != CCFPEmode)
```

**REVERSE_CONDITION (code, mode)**

A C expression whose value is reversed condition code of the `code` for comparison done in `CC_MODE` mode. The macro is used only in case `REVERSIBLE_CC_MODE (mode)` is nonzero. Define this macro in case machine has some non-standard way how to reverse certain conditionals. For instance in case all floating point conditions are non-trapping, compiler may freely convert unordered compares to ordered ones. Then definition may look like:

```c
#define REVERSE_CONDITION(CODE, MODE) \
((MODE) != CCFPmode ? reverse_condition (CODE) \
 : reverse_condition_maybe_unordered (CODE))
```

**bool TARGET_FIXED_CONDITION_CODE_REGS (unsigned int *p1, unsigned int *p2)**

On targets which use a hard register rather than a pseudo-register to hold condition codes, the regular CSE passes are often not able to identify cases in which the hard register is set to a common value. Use this hook to enable a small pass which optimizes such cases. This hook should return true to enable this pass, and it should set the integers to which its arguments point to the hard register numbers used for condition codes. When there is only one such register, as is true on most systems, the integer pointed to by `p2` should be set to `INVALID_REGNUM`.

The default version of this hook returns false.

**machine_mode TARGET_CC_MODES_COMPATIBLE (machine_mode m1, machine_mode m2)**

On targets which use multiple condition code modes in class `MODE_CC`, it is sometimes the case that a comparison can be validly done in more than one mode. On such a
system, define this target hook to take two mode arguments and to return a mode in which both comparisons may be validly done. If there is no such mode, return VOIDmode.

The default version of this hook checks whether the modes are the same. If they are, it returns that mode. If they are different, it returns VOIDmode.

unsigned int TARGET_FLAGS_REGNUM

If the target has a dedicated flags register, and it needs to use the post-reload comparison elimination pass, or the delay slot filler pass, then this value should be set appropriately.

18.16 Describing Relative Costs of Operations

These macros let you describe the relative speed of various operations on the target machine.

REGISTER_MOVE_COST (mode, from, to)

A C expression for the cost of moving data of mode mode from a register in class from to one in class to. The classes are expressed using the enumeration values such as GENERAL_REGS. A value of 2 is the default; other values are interpreted relative to that.

It is not required that the cost always equal 2 when from is the same as to; on some machines it is expensive to move between registers if they are not general registers.

If reload sees an insn consisting of a single set between two hard registers, and if REGISTER_MOVE_COST applied to their classes returns a value of 2, reload does not check to ensure that the constraints of the insn are met. Setting a cost of other than 2 will allow reload to verify that the constraints are met. You should do this if the ‘movm’ pattern’s constraints do not allow such copying.

These macros are obsolete, new ports should use the target hook TARGET_REGISTER_MOVE_COST instead.

int TARGET_REGISTER_MOVE_COST (machine_mode mode, reg_class_t from, reg_class_t to)

This target hook should return the cost of moving data of mode mode from a register in class from to one in class to. The classes are expressed using the enumeration values such as GENERAL_REGS. A value of 2 is the default; other values are interpreted relative to that.

It is not required that the cost always equal 2 when from is the same as to; on some machines it is expensive to move between registers if they are not general registers.

If reload sees an insn consisting of a single set between two hard registers, and if TARGET_REGISTER_MOVE_COST applied to their classes returns a value of 2, reload does not check to ensure that the constraints of the insn are met. Setting a cost of other than 2 will allow reload to verify that the constraints are met. You should do this if the ‘movm’ pattern’s constraints do not allow such copying.

The default version of this function returns 2.

MEMORY_MOVE_COST (mode, class, in)

A C expression for the cost of moving data of mode mode between a register of class class and memory; in is zero if the value is to be written to memory, nonzero if it is to
be read in. This cost is relative to those in \texttt{REGISTER\_MOVE\_COST}. If moving between
registers and memory is more expensive than between two registers, you should define
this macro to express the relative cost.

If you do not define this macro, GCC uses a default cost of 4 plus the cost of copying
via a secondary reload register, if one is needed. If your machine requires a secondary
reload register to copy between memory and a register of \texttt{class} but the reload mech-
anism is more complex than copying via an intermediate, define this macro to reflect
the actual cost of the move.

GCC defines the function \texttt{memory\_move\_secondary\_cost} if secondary reloads are
needed. It computes the costs due to copying via a secondary register. If your
machine copies from memory using a secondary register in the conventional way but
the default base value of 4 is not correct for your machine, define this macro to add
some other value to the result of that function. The arguments to that function are
the same as to this macro.

These macros are obsolete, new ports should use the target hook \texttt{TARGET\_MEMORY\-
MOVE\_COST} instead.

\begin{verbatim}
int TARGET\_MEMORY\_MOVE\_COST (machine\_mode mode, reg\_class rclass, bool in)

This target hook should return the cost of moving data of mode \texttt{mode} between a
register of class \texttt{rclass} and memory; \texttt{in} is \texttt{false} if the value is to be written to memory,
\texttt{true} if it is to be read in. This cost is relative to those in \texttt{TARGET\_REGISTER\_MOVE\-
COST}. If moving between registers and memory is more expensive than between two
registers, you should add this target hook to express the relative cost.

If you do not add this target hook, GCC uses a default cost of 4 plus the cost of
copying via a secondary reload register, if one is needed. If your machine requires a
secondary reload register to copy between memory and a register of \texttt{rclass} but the
reload mechanism is more complex than copying via an intermediate, use this target
hook to reflect the actual cost of the move.

GCC defines the function \texttt{memory\_move\_secondary\_cost} if secondary reloads are
needed. It computes the costs due to copying via a secondary register. If your
machine copies from memory using a secondary register in the conventional way but
the default base value of 4 is not correct for your machine, use this target hook to
add some other value to the result of that function. The arguments to that function
are the same as to this target hook.

\end{verbatim}

\texttt{BRANCH\_COST (speed\_p, predictable\_p)}

A C expression for the cost of a branch instruction. A value of 1 is the default; other
values are interpreted relative to that. Parameter \texttt{speed\_p} is true when the branch
in question should be optimized for speed. When it is false, \texttt{BRANCH\_COST} should
return a value optimal for code size rather than performance. \texttt{predictable\_p} is true
for well-predicted branches. On many architectures the \texttt{BRANCH\_COST} can be reduced
then.

Here are additional macros which do not specify precise relative costs, but only that
certain actions are more expensive than GCC would ordinarily expect.
SLOW_BYTE_ACCESS

[Macro]

Define this macro as a C expression which is nonzero if accessing less than a word of memory (i.e. a char or a short) is no faster than accessing a word of memory, i.e., if such access require more than one instruction or if there is no difference in cost between byte and (aligned) word loads.

When this macro is not defined, the compiler will access a field by finding the smallest containing object; when it is defined, a fullword load will be used if alignment permits. Unless bytes accesses are faster than word accesses, using word accesses is preferable since it may eliminate subsequent memory access if subsequent accesses occur to other fields in the same word of the structure, but to different bytes.

bool TARGET_SLOW_UNALIGNED_ACCESS (machine_mode mode, unsigned int align)  

This hook returns true if memory accesses described by the mode and alignment parameters have a cost many times greater than aligned accesses, for example if they are emulated in a trap handler. This hook is invoked only for unaligned accesses, i.e. when alignment < GET_MODE_ALIGNMENT (mode).

When this hook returns true, the compiler will act as if STRICT_ALIGNMENT were true when generating code for block moves. This can cause significantly more instructions to be produced. Therefore, do not make this hook return true if unaligned accesses only add a cycle or two to the time for a memory access.

The hook must return true whenever STRICT_ALIGNMENT is true. The default implementation returns STRICT_ALIGNMENT.

MOVE_RATIO (speed)

[Macro]

The threshold of number of scalar memory-to-memory move insns, below which a sequence of insns should be generated instead of a string move insn or a library call. Increasing the value will always make code faster, but eventually incurs high cost in increased code size.

Note that on machines where the corresponding move insn is a define_expand that emits a sequence of insns, this macro counts the number of such sequences.

The parameter speed is true if the code is currently being optimized for speed rather than size.

If you don’t define this, a reasonable default is used.

bool TARGET_USE_BYPieces_INFRASTRUCTURE_P (unsigned HOST_WIDE_INT size, unsigned int alignment, enum by_pieces_operation op, bool speed_p)

GCC will attempt several strategies when asked to copy between two areas of memory, or to set, clear or store to memory, for example when copying a struct. The by_pieces infrastructure implements such memory operations as a sequence of load, store or move insns. Alternate strategies are to expand the cpymem or setmem optabs, to emit a library call, or to emit unit-by-unit, loop-based operations.

This target hook should return true if, for a memory operation with a given size and alignment, using the by_pieces infrastructure is expected to result in better code generation. Both size and alignment are measured in terms of storage units.
The parameter `op` is one of: `CLEAR_BYPieces, MOVE_BYPieces, SET_BYPieces, STORE_BYPieces` or `COMPARE_BYPieces`. These describe the type of memory operation under consideration.

The parameter `speed` is true if the code is currently being optimized for speed rather than size.

Returning true for higher values of `size` can improve code generation for speed if the target does not provide an implementation of the `cpymem` or `setmem` standard names, if the `cpymem` or `setmem` implementation would be more expensive than a sequence of insns, or if the overhead of a library call would dominate that of the body of the memory operation.

Returning true for higher values of `size` may also cause an increase in code size, for example where the number of insns emitted to perform a move would be greater than that of a library call.

```c
bool TARGET_OVERLAP_OP_BY_PIECES_P (void) [Target Hook]
This target hook should return true if when the by_pieces infrastructure is used, an offset adjusted unaligned memory operation in the smallest integer mode for the last piece operation of a memory region can be generated to avoid doing more than one smaller operations.
```

```c
int TARGET_COMPARE_BY_PIECES_BRANCH_RATIO (machine_mode mode) [Target Hook]
When expanding a block comparison in MODE, gcc can try to reduce the number of branches at the expense of more memory operations. This hook allows the target to override the default choice. It should return the factor by which branches should be reduced over the plain expansion with one comparison per mode-sized piece. A port can also prevent a particular mode from being used for block comparisons by returning a negative number from this hook.
```

```c
MOVE_MAX_PIECES [Macro]
A C expression used by `move_by_pieces` to determine the largest unit a load or store used to copy memory is. Defaults to `MOVE_MAX`.
```

```c
STORE_MAX_PIECES [Macro]
A C expression used by `store_by_pieces` to determine the largest unit a store used to memory is. Defaults to `MOVE_MAX_PIECES`, or two times the size of `HOST_WIDE_INT`, whichever is smaller.
```

```c
COMPARE_MAX_PIECES [Macro]
A C expression used by `compare_by_pieces` to determine the largest unit a load or store used to compare memory is. Defaults to `MOVE_MAX_PIECES`.
```

```c
CLEAR_RATIO (speed) [Macro]
The threshold of number of scalar move insns, below which a sequence of insns should be generated to clear memory instead of a string clear insn or a library call. Increasing the value will always make code faster, but eventually incurs high cost in increased code size.
```
The parameter `speed` is true if the code is currently being optimized for speed rather than size.

If you don’t define this, a reasonable default is used.

**SET_RATIO** *(speed)*  
[Macro]  
The threshold of number of scalar move insns, *below* which a sequence of insns should be generated to set memory to a constant value, instead of a block set insn or a library call. Increasing the value will always make code faster, but eventually incurs high cost in increased code size.

The parameter `speed` is true if the code is currently being optimized for speed rather than size.

If you don’t define this, it defaults to the value of *MOVE_RATIO*.

**USE_LOAD_POST_INCREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a load postincrement is a good thing to use for a given mode. Defaults to the value of *HAVE_POST_INCREMENT*.

**USE_LOAD_POST_DECREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a load postdecrement is a good thing to use for a given mode. Defaults to the value of *HAVE_POST_DECREMENT*.

**USE_LOAD_PRE_INCREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a load preincrement is a good thing to use for a given mode. Defaults to the value of *HAVE_PRE_INCREMENT*.

**USE_LOAD_PRE_DECREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a load predecrement is a good thing to use for a given mode. Defaults to the value of *HAVE_PRE_DECREMENT*.

**USE_STORE_POST_INCREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a store postincrement is a good thing to use for a given mode. Defaults to the value of *HAVE_POST_INCREMENT*.

**USE_STORE_POST_DECREMENT** *(mode)*  
[Macro]  
A C expression used to determine whether a store postdecrement is a good thing to use for a given mode. Defaults to the value of *HAVE_POST_DECREMENT*.

**USE_STORE_PRE_INCREMENT** *(mode)*  
[Macro]  
This macro is used to determine whether a store preincrement is a good thing to use for a given mode. Defaults to the value of *HAVE_PRE_INCREMENT*.

**USE_STORE_PRE_DECREMENT** *(mode)*  
[Macro]  
This macro is used to determine whether a store predecrement is a good thing to use for a given mode. Defaults to the value of *HAVE_PRE_DECREMENT*.

**NO_FUNCTION_CSE**  
[Macro]  
Define this macro to be true if it is as good or better to call a constant function address than to call an address kept in a register.
LOGICAL_OP_NON_SHORT_CIRCUIT

[Macro]

Define this macro if a non-short-circuit operation produced by ‘fold_range_test ()’ is optimal. This macro defaults to true if BRANCH_COST is greater than or equal to the value 2.

bool TARGET_OPTAB_SUPPORTED_P (int op, machine_mode mode1,
machine_mode mode2, optimization_type opt_type)

[Target Hook]

Return true if the optimizers should use optab op with modes mode1 and mode2 for optimization type opt_type. The optab is known to have an associated ‘.md’ instruction whose C condition is true. mode2 is only meaningful for conversion optabs; for direct optabs it is a copy of mode1.

For example, when called with op equal to rint_optab and mode1 equal to DFmode, the hook should say whether the optimizers should use optab rintdf2.

The default hook returns true for all inputs.

bool TARGET_RTX_COSTS (rtx x, machine_mode mode, int
outer_code, int opno, int *total, bool speed)

[Target Hook]

This target hook describes the relative costs of RTL expressions.

The cost may depend on the precise form of the expression, which is available for examination in x, and the fact that x appears as operand opno of an expression with rtx code outer_code. That is, the hook can assume that there is some rtx y such that ‘GET_CODE (y) == outer_code’ and such that either (a) ‘XEXP (y, opno) == x’ or (b) ‘XVEC (y, opno)’ contains x.

mode is x’s machine mode, or for cases like const_int that do not have a mode, the mode in which x is used.

In implementing this hook, you can use the construct COSTS_N_INSNS (n) to specify a cost equal to n fast instructions.

On entry to the hook, *total contains a default estimate for the cost of the expression. The hook should modify this value as necessary. Traditionally, the default costs are COSTS_N_INSNS (5) for multiplications, COSTS_N_INSNS (7) for division and modulus operations, and COSTS_N_INSNS (1) for all other operations.

When optimizing for code size, i.e. when speed is false, this target hook should be used to estimate the relative size cost of an expression, again relative to COSTS_N_INSNS.

The hook returns true when all subexpressions of x have been processed, and false when rtx_cost should recurse.

int TARGET_ADDRESS_COST (rtx address, machine_mode mode,
addr_space_t as, bool speed)

[Target Hook]

This hook computes the cost of an addressing mode that contains address. If not defined, the cost is computed from the address expression and the TARGET_RTX_COST hook.

For most CISC machines, the default cost is a good approximation of the true cost of the addressing mode. However, on RISC machines, all instructions normally have the same length and execution time. Hence all addresses will have equal costs.
In cases where more than one form of an address is known, the form with the lowest cost will be used. If multiple forms have the same, lowest, cost, the one that is the most complex will be used.

For example, suppose an address that is equal to the sum of a register and a constant is used twice in the same basic block. When this macro is not defined, the address will be computed in a register and memory references will be indirect through that register. On machines where the cost of the addressing mode containing the sum is no higher than that of a simple indirect reference, this will produce an additional instruction and possibly require an additional register. Proper specification of this macro eliminates this overhead for such machines.

This hook is never called with an invalid address.

On machines where an address involving more than one register is as cheap as an address computation involving only one register, defining TARGET_ADDRESS_COST to reflect this can cause two registers to be live over a region of code where only one would have been if TARGET_ADDRESS_COST were not defined in that manner. This effect should be considered in the definition of this macro. Equivalent costs should probably only be given to addresses with different numbers of registers on machines with lots of registers.

```c
int TARGET_INSN_COST (rtx_insn *insn, bool speed) [Target Hook]
This target hook describes the relative costs of RTL instructions.
In implementing this hook, you can use the construct COSTS_N_INSNS (n) to specify a cost equal to n fast instructions.
When optimizing for code size, i.e. when speed is false, this target hook should be used to estimate the relative size cost of an expression, again relative to COSTS_N_INSNS.
```

```c
unsigned int TARGET_MAX_NOCE_IFCVT_SEQ_COST (edge e) [Target Hook]
This hook returns a value in the same units as TARGET RTX COSTS, giving the maximum acceptable cost for a sequence generated by the RTL if-conversion pass when conditional execution is not available. The RTL if-conversion pass attempts to convert conditional operations that would require a branch to a series of unconditional operations and movmodecc insns. This hook returns the maximum cost of the unconditional instructions and the movmodecc insns. RTL if-conversion is cancelled if the cost of the converted sequence is greater than the value returned by this hook.
e is the edge between the basic block containing the conditional branch to the basic block which would be executed if the condition were true.
The default implementation of this hook uses the max-rtl-if-conversion-[un]predictable parameters if they are set, and uses a multiple of BRANCH_COST otherwise.
```

```c
bool TARGET_NOCE_CONVERSION_PROFITABLE_P (rtx_insn *seq, struct noce_if_info *if_info) [Target Hook]
This hook returns true if the instruction sequence seq is a good candidate as a replacement for the if-convertible sequence described in if_info.
```
bool TARGET_NEW_ADDRESS_PROFITABLE_P (rtx memref, rtx_insn * insn, rtx new_addr)  
Return true if it is profitable to replace the address in memref with new_addr. This allows targets to prevent the scheduler from undoing address optimizations. The instruction containing the memref is insn. The default implementation returns true.

bool TARGET_NO_SPECULATION_IN_DELAY_SLOTS_P (void)  
This predicate controls the use of the eager delay slot filler to disallow speculatively executed instructions being placed in delay slots. Targets such as certain MIPS architectures possess both branches with and without delay slots. As the eager delay slot filler can decrease performance, disabling it is beneficial when ordinary branches are available. Use of delay slot branches filled using the basic filler is often still desirable as the delay slot can hide a pipeline bubble.

HOST_WIDE_INT TARGET_ESTIMATED_POLY_VALUE (poly_int64 val, poly_value_estimate_kind kind)  
Return an estimate of the runtime value of val, for use in things like cost calculations or profiling frequencies. kind is used to ask for the minimum, maximum, and likely estimates of the value through the POLY_VALUE_MIN, POLY_VALUE_MAX and POLY_VALUE_LIKELY values. The default implementation returns the lowest possible value of val.

18.17 Adjusting the Instruction Scheduler

The instruction scheduler may need a fair amount of machine-specific adjustment in order to produce good code. GCC provides several target hooks for this purpose. It is usually enough to define just a few of them: try the first ones in this list first.

int TARGET_SCHED_ISSUE_RATE (void)  
This hook returns the maximum number of instructions that can ever issue at the same time on the target machine. The default is one. Although the insn scheduler can define itself the possibility of issue an insn on the same cycle, the value can serve as an additional constraint to issue insns on the same simulated processor cycle (see hooks ‘TARGET_SCHED_REORDER’ and ‘TARGET_SCHED_REORDER2’). This value must be constant over the entire compilation. If you need it to vary depending on what the instructions are, you must use ‘TARGET_SCHED_VARIABLE_ISSUE’.

int TARGET_SCHED_VARIABLE_ISSUE (FILE *file, int verbose, rtx_insn *insn, int more)  
This hook is executed by the scheduler after it has scheduled an insn from the ready list. It should return the number of insns which can still be issued in the current cycle. The default is ‘more - 1’ for insns other than CLOBBER and USE, which normally are not counted against the issue rate. You should define this hook if some insns take more machine resources than others, so that fewer insns can follow them in the same cycle. file is either a null pointer, or a stdio stream to write any debug output to. verbose is the verbose level provided by ‘-f sched-verbose-n’. insn is the instruction that was scheduled.
```c
int TARGET_SCHED_ADJUST_COST (rtx_insn *insn, int dep_type1,
                           rtx_insn *dep_insn, int cost, unsigned int dw)
This function corrects the value of cost based on the relationship between insn and
dep_insn through a dependence of type dep_type, and strength dw. It should return
the new value. The default is to make no adjustment to cost. This can be used for
example to specify to the scheduler using the traditional pipeline description that an
output- or anti-dependence does not incur the same cost as a data-dependence. If the
scheduler using the automaton based pipeline description, the cost of anti-dependence
is zero and the cost of output-dependence is maximum of one and the difference of
latency times of the first and the second insns. If these values are not acceptable,
you could use the hook to modify them too. See also see Section 17.19.9 [Processor
pipeline description], page 477.
```

```c
int TARGET_SCHED_ADJUST_PRIORITY (rtx_insn *insn, int priority)
This hook adjusts the integer scheduling priority priority of insn. It should return
the new priority. Increase the priority to execute insn earlier, reduce the priority to
execute insn later. Do not define this hook if you do not need to adjust the scheduling
priorities of insns.
```

```c
int TARGET_SCHED_REORDER (FILE *file, int verbose, rtx_insn **ready,
                           int *n_readyp, int clock)
This hook is executed by the scheduler after it has scheduled the ready list, to allow
the machine description to reorder it (for example to combine two small instructions
together on 'VLIW' machines). file is either a null pointer, or a stdio stream to write
any debug output to. verbose is the verbose level provided by ‘-fsched-verbose-n’.
ready is a pointer to the ready list of instructions that are ready to be scheduled.
n_readyp is a pointer to the number of elements in the ready list. The scheduler
reads the ready list in reverse order, starting with ready[(*n_readyp - 1)] and going to
ready[0]. clock is the timer tick of the scheduler. You may modify the ready list and
the number of ready insns. The return value is the number of insns that can issue
this cycle; normally this is just issue_rate. See also ‘TARGET_SCHED_REORDER2’.
```

```c
int TARGET_SCHED_REORDER2 (FILE *file, int verbose, rtx_insn **ready,
                        int *n_readyp, int clock)
Like ‘TARGET_SCHED_REORDER’, but called at a different time. That function is called
whenever the scheduler starts a new cycle. This one is called once per iteration over
a cycle, immediately after ‘TARGET_SCHED_VARIABLE_ISSUE’; it can reorder the ready
list and return the number of insns to be scheduled in the same cycle. Defining this
hook can be useful if there are frequent situations where scheduling one insn causes
other insns to become ready in the same cycle. These other insns can then be taken
into account properly.
```

```c
bool TARGET_SCHED_MACRO_FUSION_P (void)
This hook is used to check whether target platform supports macro fusion.
```
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bool TARGET_SCHED_MACRO_FUSION_PAIR_P (rtx_insn *prev, rtx_insn *curr) [Target Hook]
This hook is used to check whether two insns should be macro fused for a target microarchitecture. If this hook returns true for the given insn pair (prev and curr), the scheduler will put them into a sched group, and they will not be scheduled apart. The two insns will be either two SET insns or a compare and a conditional jump and this hook should validate any dependencies needed to fuse the two insns together.

void TARGET_SCHED_DEPENDENCIES_EVALUATION_HOOK (rtx_insn *head, rtx_insn *tail) [Target Hook]
This hook is called after evaluation forward dependencies of insns in chain given by two parameter values (head and tail correspondingly) but before insns scheduling of the insn chain. For example, it can be used for better insn classification if it requires analysis of dependencies. This hook can use backward and forward dependencies of the insn scheduler because they are already calculated.

void TARGET_SCHED_INIT (FILE *file, int verbose, int max_ready) [Target Hook]
This hook is executed by the scheduler at the beginning of each block of instructions that are to be scheduled. file is either a null pointer, or a stdio stream to write any debug output to. verbose is the verbose level provided by `-f_sched-verbose-n`. max_ready is the maximum number of insns in the current scheduling region that can be live at the same time. This can be used to allocate scratch space if it is needed, e.g. by `TARGET_SCHED_REORDER`.

void TARGET_SCHED_FINISH (FILE *file, int verbose) [Target Hook]
This hook is executed by the scheduler at the end of each block of instructions that are to be scheduled. It can be used to perform cleanup of any actions done by the other scheduling hooks. file is either a null pointer, or a stdio stream to write any debug output to. verbose is the verbose level provided by `-f_sched-verbose-n`.

void TARGET_SCHED_INIT_GLOBAL (FILE *file, int verbose, int old_max_uid) [Target Hook]
This hook is executed by the scheduler after function level initializations. file is either a null pointer, or a stdio stream to write any debug output to. verbose is the verbose level provided by `-f_sched-verbose-n`. old_max_uid is the maximum insn uid when scheduling begins.

void TARGET_SCHED_FINISH_GLOBAL (FILE *file, int verbose) [Target Hook]
This is the cleanup hook corresponding to TARGET_SCHED_INIT_GLOBAL. file is either a null pointer, or a stdio stream to write any debug output to. verbose is the verbose level provided by `-f_sched-verbose-n`.

rtx TARGET_SCHED_DFA_PRE_CYCLEInsn (void) [Target Hook]
The hook returns an RTL insn. The automaton state used in the pipeline hazard recognizer is changed as if the insn were scheduled when the new simulated processor cycle starts. Usage of the hook may simplify the automaton pipeline description for some VLIW processors. If the hook is defined, it is used only for the automaton based pipeline description. The default is not to change the state when the new simulated processor cycle starts.
void TARGET_SCHED_INIT_DFA_PRE_CYCLE_INSN (void)  [Target Hook]
The hook can be used to initialize data used by the previous hook.

rtx_insn * TARGET_SCHED_DFA_POST_CYCLE_INSN (void)  [Target Hook]
The hook is analogous to ‘TARGET_SCHED_DFA_PRE_CYCLE_INSN’ but used to changed
the state as if the insn were scheduled when the new simulated processor cycle finishes.

void TARGET_SCHED_INIT_DFA_POST_CYCLE_INSN (void)  [Target Hook]
The hook is analogous to ‘TARGET_SCHED_INIT_DFA_PRE_CYCLE_INSN’ but used to
initialize data used by the previous hook.

void TARGET_SCHED_DFA_PRE_ADVANCE_CYCLE (void)  [Target Hook]
The hook to notify target that the current simulated cycle is about to finish. The
hook is analogous to ‘TARGET_SCHED_DFA_PRE_CYCLE_INSN’ but used to change the
state in more complicated situations - e.g., when advancing state on a single insn is
not enough.

void TARGET_SCHED_DFA_POST_ADVANCE_CYCLE (void)  [Target Hook]
The hook to notify target that new simulated cycle has just started. The hook is
analogous to ‘TARGET_SCHED_DFA_POST_CYCLE_INSN’ but used to change the
state in more complicated situations - e.g., when advancing state on a single insn is not
enough.

int TARGET_SCHED_FIRST_CYCLE_MULTIPASS_DFA_LOOKAHEAD
   (void)  [Target Hook]
This hook controls better choosing an insn from the ready insn queue for the DFA-
based insn scheduler. Usually the scheduler chooses the first insn from the queue.
If the hook returns a positive value, an additional scheduler code tries all permu-
tations of ‘TARGET_SCHED_FIRST_CYCLE_MULTIPASS_DFA_LOOKAHEAD ()’ subsequent
ready insns to choose an insn whose issue will result in maximal number of issued
insns on the same cycle. For the VLIW processor, the code could actually solve the
problem of packing simple insns into the VLIW insn. Of course, if the rules of VLIW
packing are described in the automaton.
This code also could be used for superscalar RISC processors. Let us consider a
superscalar RISC processor with 3 pipelines. Some insns can be executed in pipelines
A or B, some insns can be executed only in pipelines B or C, and one insn can be
executed in pipeline B. The processor may issue the 1st insn into A and the 2nd one
into B. In this case, the 3rd insn will wait for freeing B until the next cycle. If the
scheduler issues the 3rd insn the first, the processor could issue all 3 insns per cycle.
Actually this code demonstrates advantages of the automaton based pipeline hazard
recognizer. We try quickly and easy many insn schedules to choose the best one.
The default is no multipass scheduling.

int TARGET_SCHED_FIRST_CYCLE_MULTIPASS_DFA_LOOKAHEAD_GUARD
   (rtx_insn *insn, int ready_index)  [Target Hook]
This hook controls what insns from the ready insn queue will be considered for the
multipass insn scheduling. If the hook returns zero for insn, the insn will be considered
in multipass scheduling. Positive return values will remove insn from consideration on the current round of multipass scheduling. Negative return values will remove insn from consideration for given number of cycles. Backends should be careful about returning non-zero for highest priority instruction at position 0 in the ready list. ready_index is passed to allow backends make correct judgements.

The default is that any ready insns can be chosen to be issued.

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_BEGIN (void *data, signed char *ready_try, int n_ready, bool first_cycle_insn_p) {
    // This hook prepares the target backend for a new round of multipass scheduling.
}
```

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_ISSUE (void *data, signed char *ready_try, int n_ready, rtx_insn *insn, const void *prev_data) {
    // This hook is called when multipass scheduling evaluates instruction INSN.
}
```

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_BACKTRACK (const void *data, signed char *ready_try, int n_ready) {
    // This is called when multipass scheduling backtracks from evaluation of an instruction.
}
```

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_END (const void *data) {
    // This hook notifies the target about the result of the concluded current round of multipass scheduling.
}
```

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_INIT (void *data) {
    // This hook initializes target-specific data used in multipass scheduling.
}
```

```
void TARGET_SCHED_FIRST_CYCLE_MULTIPASS_FINI (void *data) {
    // This hook finalizes target-specific data used in multipass scheduling.
}
```

```
int TARGET_SCHED_DFA_NEW_CYCLE (FILE *dump, int verbose, rtx_insn *insn, int last_clock, int clock, int *sort_p) {
    // This hook is called by the insn scheduler before issuing insn on cycle clock. If the hook returns nonzero, insn is not issued on this processor cycle. Instead, the processor cycle is advanced. If *sort_p is zero, the insn ready queue is not sorted on the new cycle start as usually. dump and verbose specify the file and verbosity level to use for debugging output. last_clock and clock are, respectively, the processor cycle on which the previous insn has been issued, and the current processor cycle.
}
```

```
bool TARGET_SCHED_IS_COSTLY_DEPENDENCE (struct _dep *_dep, int cost, int distance) {
    // This hook is used to define which dependences are considered costly by the target, so costly that it is not advisable to schedule the insns that are involved in the dependence too close to one another. The parameters to this hook are as follows: The first parameter _dep is the dependence being evaluated. The second parameter cost is the cost of the dependence as estimated by the scheduler, and the third parameter distance is the distance in cycles between the two insns. The hook returns true if considering the distance between the two insns the dependence between them is considered costly by the target, and false otherwise.
}
```
Defining this hook can be useful in multiple-issue out-of-order machines, where (a) it’s practically hopeless to predict the actual data/resource delays, however: (b) there’s a better chance to predict the actual grouping that will be formed, and (c) correctly emulating the grouping can be very important. In such targets one may want to allow issuing dependent insns closer to one another—i.e., closer than the dependence distance; however, not in cases of “costly dependences”, which this hooks allows to define.

```c
void TARGET_SCHED_H_I_D_EXTENDED (void)  [Target Hook]
This hook is called by the insn scheduler after emitting a new instruction to the instruction stream. The hook notifies a target backend to extend its per instruction data structures.

void * TARGET_SCHED_ALLOC_SCHED_CONTEXT (void)  [Target Hook]
Return a pointer to a store large enough to hold target scheduling context.

void TARGET_SCHED_INIT_SCHED_CONTEXT (void *tc, bool clean_p)  [Target Hook]
Initialize store pointed to by tc to hold target scheduling context. It clean_p is true then initialize tc as if scheduler is at the beginning of the block. Otherwise, copy the current context into tc.

void TARGET_SCHED_SET_SCHED_CONTEXT (void *tc)  [Target Hook]
Copy target scheduling context pointed to by tc to the current context.

void TARGET_SCHED_CLEAR_SCHED_CONTEXT (void *tc)  [Target Hook]
Deallocation internal data in target scheduling context pointed to by tc.

void TARGET_SCHED_FREE_SCHED_CONTEXT (void *tc)  [Target Hook]
Deallocate a store for target scheduling context pointed to by tc.

int TARGET_SCHED_SPECULATE_INSN (rtx_insn *insn, unsigned int dep_status, rtx *new_pat)  [Target Hook]
This hook is called by the insn scheduler when insn has only speculative dependencies and therefore can be scheduled speculatively. The hook is used to check if the pattern of insn has a speculative version and, in case of successful check, to generate that speculative pattern. The hook should return 1, if the instruction has a speculative form, or −1, if it doesn’t. request describes the type of requested speculation. If the return value equals 1 then new_pat is assigned the generated speculative pattern.

bool TARGET_SCHED_NEEDS_BLOCK_P (unsigned int dep_status)  [Target Hook]
This hook is called by the insn scheduler during generation of recovery code for insn. It should return true, if the corresponding check instruction should branch to recovery code, or false otherwise.

rtx TARGET_SCHED_GEN_SPEC_CHECK (rtx_insn *insn, rtx_insn *label, unsigned int ds)  [Target Hook]
This hook is called by the insn scheduler to generate a pattern for recovery check instruction. If mutate_p is zero, then insn is a speculative instruction for which the check should be generated. label is either a label of a basic block, where recovery
code should be emitted, or a null pointer, when requested check doesn’t branch to recovery code (a simple check). If \( \text{mutate}_p \) is nonzero, then a pattern for a branchy check corresponding to a simple check denoted by \( \text{insn} \) should be generated. In this case \( \text{label} \) can’t be null.

**void TARGET_SCHED_SET_SCHED_FLAGS** (\texttt{struct spec\_info\_def \*spec\_info}) [Target Hook]

This hook is used by the insn scheduler to find out what features should be enabled/used. The structure \( \ast \text{spec\_info} \) should be filled in by the target. The structure describes speculation types that can be used in the scheduler.

**bool TARGET_SCHED_CAN_SPECULATE_INSNS** (\texttt{rtx\_insn \*insn}) [Target Hook]

Some instructions should never be speculated by the schedulers, usually because the instruction is too expensive to get this wrong. Often such instructions have long latency, and often they are not fully modeled in the pipeline descriptions. This hook should return \texttt{false} if \( \text{insn} \) should not be speculated.

**int TARGET_SCHED_SMS_RES_MII** (\texttt{struct ddg \*g}) [Target Hook]

This hook is called by the swing modulo scheduler to calculate a resource-based lower bound which is based on the resources available in the machine and the resources required by each instruction. The target backend can use \( \text{g} \) to calculate such bound. A very simple lower bound will be used in case this hook is not implemented: the total number of instructions divided by the issue rate.

**bool TARGET_SCHED_DISPATCH** (\texttt{rtx\_insn \*insn, int x}) [Target Hook]

This hook is called by Haifa Scheduler. It returns true if dispatch scheduling is supported in hardware and the condition specified in the parameter is true.

**void TARGET_SCHED_DISPATCH_DO** (\texttt{rtx\_insn \*insn, int x}) [Target Hook]

This hook is called by Haifa Scheduler. It performs the operation specified in its second parameter.

**bool TARGET_SCHED_EXPOSED_PIPELINE** [Target Hook]

True if the processor has an exposed pipeline, which means that not just the order of instructions is important for correctness when scheduling, but also the latencies of operations.

**int TARGET_SCHED_REASSOCIATION_WIDTH** (\texttt{unsigned int opc, machine\_mode mode}) [Target Hook]

This hook is called by tree reassociator to determine a level of parallelism required in output calculations chain.

**void TARGET_SCHED_FUSION_PRIORITY** (\texttt{rtx\_insn \*insn, int \*max\_pri, int \*fusion\_pri, int \*pri}) [Target Hook]

This hook is called by scheduling fusion pass. It calculates fusion priorities for each instruction passed in by parameter. The priorities are returned via pointer parameters.

\( \text{insn} \) is the instruction whose priorities need to be calculated. \( \text{max\_pri} \) is the maximum priority can be returned in any cases. \( \text{fusion\_pri} \) is the pointer parameter through
which `insn`'s fusion priority should be calculated and returned. `pri` is the pointer parameter through which `insn`'s priority should be calculated and returned.

Same `fusion_pri` should be returned for instructions which should be scheduled together. Different `pri` should be returned for instructions with same `fusion_pri`. `fusion_pri` is the major sort key, `pri` is the minor sort key. All instructions will be scheduled according to the two priorities. All priorities calculated should be between 0 (exclusive) and `max_pri` (inclusive). To avoid false dependencies, `fusion_pri` of instructions which need to be scheduled together should be smaller than `fusion_pri` of irrelevant instructions.

Given below example:

```plaintext
ldr r10, [r1, 4]  ; fusion_pri=99, pri=96
add r4, r4, r10    
ldr r15, [r2, 8]  ; fusion_pri=100, pri=100
sub r5, r5, r15    
ldr r11, [r1, 0]  ; fusion_pri=99, pri=100
add r4, r4, r11    
ldr r16, [r2, 12]; fusion_pri=98, pri=88
sub r5, r5, r16    
```

On targets like ARM/AArch64, the two pairs of consecutive loads should be merged. Since peephole2 pass can’t help in this case unless consecutive loads are actually next to each other in instruction flow. That’s where this scheduling fusion pass works. This hook calculates priority for each instruction based on its fusion type, like:

```plaintext
ldr r10, [r1, 4]  ; fusion_pri=99, pri=96
add r4, r4, r10    
ldr r15, [r2, 8]  ; fusion_pri=100, pri=100
sub r5, r5, r15    
ldr r11, [r1, 0]  ; fusion_pri=99, pri=100
add r4, r4, r11    
ldr r16, [r2, 12]; fusion_pri=98, pri=88
sub r5, r5, r16    
```

Scheduling fusion pass then sorts all ready to issue instructions according to the priorities. As a result, instructions of same fusion type will be pushed together in instruction flow, like:

```plaintext
ldr r11, [r1, 0]    
ldr r10, [r1, 4]    
ldr r15, [r2, 8]    
ldr r16, [r2, 12]    
add r4, r4, r10    
sub r5, r5, r15    
add r4, r4, r11    
sub r5, r5, r16    
```

Now peephole2 pass can simply merge the two pairs of loads.

Since scheduling fusion pass relies on peephole2 to do real fusion work, it is only enabled by default when peephole2 is in effect.

This is firstly introduced on ARM/AArch64 targets, please refer to the hook implementation for how different fusion types are supported.
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void TARGET_EXPAND_DIVMOD_LIBFUNC (rtx libfunc, [Target Hook]
    machine_mode mode, rtx op0, rtx op1, rtx *quot, rtx *rem)
Define this hook for enabling divmod transform if the port does not have hardware
divmod insn but defines target-specific divmod libfuncs.

18.18 Dividing the Output into Sections (Texts, Data, . . .)

An object file is divided into sections containing different types of data. In the most common
case, there are three sections: the text section, which holds instructions and read-only data;
the data section, which holds initialized writable data; and the bss section, which holds
uninitialized data. Some systems have other kinds of sections.

`varasm.c` provides several well-known sections, such as text_section, data_section
and bss_section. The normal way of controlling a foo_section variable is to define the
associated FOO_SECTION_ASM_OP macro, as described below. The macros are only read once,
when `varasm.c` initializes itself, so their values must be run-time constants. They may
however depend on command-line flags.

Note: Some run-time files, such `crtstuff.c`, also make use of the FOO_SECTION_ASM_OP
macros, and expect them to be string literals.

Some assemblers require a different string to be written every time a section is selected. If
your assembler falls into this category, you should define the TARGET_ASM_INIT_SECTIONS
hook and use get_unnamed_section to set up the sections.

You must always create a text_section, either by defining TEXT_SECTION_ASM_OP or
by initializing text_section in TARGET_ASM_INIT_SECTIONS. The same is true of data_-
section and DATA_SECTION_ASM_OP. If you do not create a distinct readonly_data-
section, the default is to reuse text_section.

All the other `varasm.c` sections are optional, and are null if the target does not provide
them.

TEXT_SECTION_ASM_OP [Macro]
A C expression whose value is a string, including spacing, containing the assembler
operation that should precede instructions and read-only data. Normally `\t.text`
is right.

HOT_TEXT_SECTION_NAME [Macro]
If defined, a C string constant for the name of the section containing most frequently
executed functions of the program. If not defined, GCC will provide a default defini-
tion if the target supports named sections.

UNLIKELY_EXECUTED_TEXT_SECTION_NAME [Macro]
If defined, a C string constant for the name of the section containing unlikely executed
functions in the program.

DATA_SECTION_ASM_OP [Macro]
A C expression whose value is a string, including spacing, containing the assem-
blver operation to identify the following data as writable initialized data. Normally
`\t.data` is right.
SDATA_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as initialized, writable small data.

READONLY_DATA_SECTION_ASM_OP [Macro]
A C expression whose value is a string, including spacing, containing the assembler
operation to identify the following data as read-only initialized data.

BSS_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as uninitialized global data. If not
declared, and ASM_OUTPUT_ALIGNED_BSS not defined, uninitialized global data will be
output in the data section if ‘-fno-common’ is passed, otherwise ASM_OUTPUT_COMMON
will be used.

SBSS_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as uninitialized, writable small
data.

TLS_COMMON_ASM_OP [Macro]
If defined, a C expression whose value is a string containing the assembler operation
to identify the following data as thread-local common data. The default is ".tls_
common".

TLS_SECTION_ASM_FLAG [Macro]
If defined, a C expression whose value is a character constant containing the flag used
to mark a section as a TLS section. The default is ‘T’.

INIT_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as initialization code. If not defined,
GCC will assume such a section does not exist. This section has no corresponding
init_section variable; it is used entirely in runtime code.

FINI_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as finalization code. If not defined,
GCC will assume such a section does not exist. This section has no corresponding
fini_section variable; it is used entirely in runtime code.

INIT_ARRAY_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as part of the .init_array (or
equivalent) section. If not defined, GCC will assume such a section does not exist.
Do not define both this macro and INIT_SECTION_ASM_OP.

FINI_ARRAY_SECTION_ASM_OP [Macro]
If defined, a C expression whose value is a string, including spacing, containing the
assembler operation to identify the following data as part of the .fini_array (or
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equivalent) section. If not defined, GCC will assume such a section does not exist.
Do not define both this macro and FINI SECTION ASM OP.

MACH DEP SECTION ASM FLAG

If defined, a C expression whose value is a character constant containing the flag used
to mark a machine-dependent section. This corresponds to the SECTION MACH DEP
section flag.

CRT CALL STATIC FUNCTION (section op, function)

If defined, an ASM statement that switches to a different section via section op, calls
function, and switches back to the text section. This is used in 'crtstuff.c' if INIT
SECTION ASM OP or FINI SECTION ASM OP to calls to initialization and finalization
functions from the init and fini sections. By default, this macro uses a simple function
call. Some ports need hand-crafted assembly code to avoid dependencies on registers
initialized in the function prologue or to ensure that constant pools don’t end up too
far way in the text section.

TARGET LIBGCC SDATA SECTION

If defined, a string which names the section into which small variables defined in
crtstuff and libgcc should go. This is useful when the target has options for optimizing
access to small data, and you want the crtstuff and libgcc routines to be conservative
in what they expect of your application yet liberal in what your application expects.
For example, for targets with a .sdata section (like MIPS), you could compile crtstuff
with -G 0 so that it doesn’t require small data support from your application, but use
this macro to put small data into .sdata so that your application can access these
variables whether it uses small data or not.

FORCE CODE SECTION ALIGN

If defined, an ASM statement that aligns a code section to some arbitrary boundary.
This is used to force all fragments of the .init and .fini sections to have to same
alignment and thus prevent the linker from having to add any padding.

JUMP_TABLES IN TEXT SECTION

Define this macro to be an expression with a nonzero value if jump tables (for
tablejump insns) should be output in the text section, along with the assembler
instructions. Otherwise, the readonly data section is used.
This macro is irrelevant if there is no separate readonly data section.

void TARGET ASM INIT SECTIONS (void)

Define this hook if you need to do something special to set up the 'varasm.c' sections,
or if your target has some special sections of its own that you need to create.
GCC calls this hook after processing the command line, but before writing any as-
sembly code, and before calling any of the section-returning hooks described below.

int TARGET ASM RELOC RW MASK (void)

Return a mask describing how relocations should be treated when selecting sections.
Bit 1 should be set if global relocations should be placed in a read-write section; bit
0 should be set if local relocations should be placed in a read-write section.
The default version of this function returns 3 when ‘-fpic’ is in effect, and 0 otherwise. The hook is typically redefined when the target cannot support (some kinds of) dynamic relocations in read-only sections even in executables.

```c
bool TARGET_ASM_GENERATE_PIC_ADDR_DIFF_VEC (void) [Target Hook]
Return true to generate ADDR_DIFF_VEC table or false to generate ADDR_VEC table for jumps in case of -fPIC.
The default version of this function returns true if flag_pic equals true and false otherwise
```

```c
section * TARGET_ASM_SELECT_SECTION (tree exp, int reloc,
    unsigned HOST_WIDE_INT align) [Target Hook]
Return the section into which exp should be placed. You can assume that exp is either a VAR_DECL node or a constant of some sort. reloc indicates whether the initial value of exp requires link-time relocations. Bit 0 is set when variable contains local relocations only, while bit 1 is set for global relocations. align is the constant alignment in bits.
The default version of this function takes care of putting read-only variables in readonly_data_section. See also USE_SELECT_SECTION_FOR_FUNCTIONS.
```

```c
USE_SELECT_SECTION_FOR_FUNCTIONS [Macro]
Define this macro if you wish TARGET_ASM_SELECT_SECTION to be called for FUNCTION_DECLS as well as for variables and constants.
In the case of a FUNCTION_DECL, reloc will be zero if the function has been determined to be likely to be called, and nonzero if it is unlikely to be called.
```

```c
void TARGET_ASM_UNIQUE_SECTION (tree decl, int reloc) [Target Hook]
Build up a unique section name, expressed as a STRING_CST node, and assign it to ‘DECL_SECTION_NAME (decl)’. As with TARGET_ASM_SELECT_SECTION, reloc indicates whether the initial value of exp requires link-time relocations.
The default version of this function appends the symbol name to the ELF section name that would normally be used for the symbol. For example, the function foo would be placed in .text.foo. Whatever the actual target object format, this is often good enough.
```

```c
section * TARGET_ASM_FUNCTION_RODATA_SECTION (tree decl, bool relocatable) [Target Hook]
Return the readonly data or reloc readonly data section associated with ‘DECL_SECTION_NAME (decl)’. relocatable selects the latter over the former. The default version of this function selects .gnu.linkonce.r.name if the function’s section is .gnu.linkonce.t.name, .rodata.name or .data.rel.ro.name if function is in .text.name, and the normal readonly-data or reloc readonly data section otherwise.
```

```c
const char * TARGET_ASM_MERGEABLE_RODATA_PREFIX [Target Hook]
Usually, the compiler uses the prefix ".rodata" to construct section names for mergeable constant data. Define this macro to override the string if a different section name should be used.
```
section * TARGET_ASM_TM_CLONE_TABLE_SECTION (void)               [Target Hook]
Return the section that should be used for transactional memory clone tables.

section * TARGET_ASM_SELECT_RTX_SECTION (machine_mode mode, rtx x, unsigned HOST_WIDE_INT align)  [Target Hook]
Return the section into which a constant x, of mode mode, should be placed. You can assume that x is some kind of constant in RTL. The argument mode is redundant except in the case of a const_int rtx. align is the constant alignment in bits.
The default version of this function takes care of putting symbolic constants in flag_pic mode in data_section and everything else in readonly_data_section.

tree TARGET_MANGLE_DECL_ASSEMBLER_NAME (tree decl, tree id)              [Target Hook]
Define this hook if you need to postprocess the assembler name generated by target-independent code. The id provided to this hook will be the computed name (e.g., the macro DECL_NAME of the decl in C, or the mangled name of the decl in C++). The return value of the hook is an IDENTIFIER_NODE for the appropriate mangled name on your target system. The default implementation of this hook just returns the id provided.

void TARGET_ENCODE_SECTION_INFO (tree decl, rtx rtl, int new_decl_p)  [Target Hook]
Define this hook if references to a symbol or a constant must be treated differently depending on something about the variable or function named by the symbol (such as what section it is in).
The hook is executed immediately after rtl has been created for decl, which may be a variable or function declaration or an entry in the constant pool. In either case, rtl is the rtl in question. Do not use DECL_RTL (decl) in this hook; that field may not have been initialized yet.

In the case of a constant, it is safe to assume that the rtl is a mem whose address is a symbol_ref. Most decls will also have this form, but that is not guaranteed. Global register variables, for instance, will have a reg for their rtl. (Normally the right thing to do with such unusual rtl is leave it alone.)

The new_decl_p argument will be true if this is the first time that TARGET_ENCODE_SECTION_INFO has been invoked on this decl. It will be false for subsequent invocations, which will happen for duplicate declarations. Whether or not anything must be done for the duplicate declaration depends on whether the hook examines DECL_ATTRIBUTES. new_decl_p is always true when the hook is called for a constant.

The usual thing for this hook to do is to record flags in the symbol_ref, using SYMBOL_REF_FLAG or SYMBOL_REF_FLAGS. Historically, the name string was modified if it was necessary to encode more than one bit of information, but this practice is now discouraged; use SYMBOL_REF_FLAGS.
The default definition of this hook, default_encode_section_info in 'varasm.c', sets a number of commonly-useful bits in SYMBOL_REF_FLAGS. Check whether the default does what you need before overriding it.

const char * TARGET_STRIP_NAME_ENCODING (const char *name)              [Target Hook]
Decode name and return the real name part, sans the characters that TARGET_ENCODE_SECTION_INFO may have added.
bool TARGET_IN_SMALL_DATA_P (const tree exp)  
Returns true if exp should be placed into a “small data” section. The default version of this hook always returns false.

bool TARGET_HAVE_SRODATA_SECTION  
Contains the value true if the target places read-only “small data” into a separate section. The default value is false.

bool TARGET_PROFILE_BEFORE_PROLOGUE (void)  
It returns true if target wants profile code emitted before prologue. The default version of this hook use the target macro PROFILE_BEFORE_PROLOGUE.

bool TARGET_BINDS_LOCAL_P (const tree exp)  
Returns true if exp names an object for which name resolution rules must resolve to the current “module” (dynamic shared library or executable image). The default version of this hook implements the name resolution rules for ELF, which has a looser model of global name binding than other currently supported object file formats.

bool TARGET_HAVE_TLS  
Contains the value true if the target supports thread-local storage. The default value is false.

18.19 Position Independent Code
This section describes macros that help implement generation of position independent code. Simply defining these macros is not enough to generate valid PIC; you must also add support to the hook TARGET_LEGITIMATE_ADDRESS_P and to the macro PRINT_OPERAND_ADDRESS, as well as LEGITIMIZE_ADDRESS. You must modify the definition of ‘movsi’ to do something appropriate when the source operand contains a symbolic address. You may also need to alter the handling of switch statements so that they use relative addresses.

PIC_OFFSET_TABLE_REGNUM  
The register number of the register used to address a table of static data addresses in memory. In some cases this register is defined by a processor’s “application binary interface” (ABI). When this macro is defined, RTL is generated for this register once, as with the stack pointer and frame pointer registers. If this macro is not defined, it is up to the machine-dependent files to allocate such a register (if necessary). Note that this register must be fixed when in use (e.g. when flag_pic is true).

PIC_OFFSET_TABLE_REG_CALL_CLOBBERED  
A C expression that is nonzero if the register defined by PIC_OFFSET_TABLE_REGNUM is clobbered by calls. If not defined, the default is zero. Do not define this macro if PIC_OFFSET_TABLE_REGNUM is not defined.

LEGITIMATE_PIC_OPERAND_P (x)  
A C expression that is nonzero if x is a legitimate immediate operand on the target machine when generating position independent code. You can assume that x satisfies CONSTANT_P, so you need not check this. You can also assume flag_pic is true, so you need not check it either. You need not define this macro if all constants (including SYMBOL_REF) can be immediate operands when generating position independent code.
18.20 Defining the Output Assembler Language

This section describes macros whose principal purpose is to describe how to write instructions in assembler language—rather than what the instructions do.

18.20.1 The Overall Framework of an Assembler File

This describes the overall framework of an assembly file.

```c
void TARGET_ASM_FILE_START (void)                     [Target Hook]
Output to asm_out_file any text which the assembler expects to find at the begin-ning of a file. The default behavior is controlled by two flags, documented below.
Unless your target’s assembler is quite unusual, if you override the default, you should call default_file_start at some point in your target hook. This lets other target files rely on these variables.

bool TARGET_ASM_FILE_START_APP_OFF                     [Target Hook]
If this flag is true, the text of the macro ASM_APP_OFF will be printed as the very first line in the assembly file, unless ‘-fverbose-asm’ is in effect. (If that macro has been defined to the empty string, this variable has no effect.) With the normal definition of ASM_APP_OFF, the effect is to notify the GNU assembler that it need not bother stripping comments or extra whitespace from its input. This allows it to work a bit faster.

The default is false. You should not set it to true unless you have verified that your port does not generate any extra whitespace or comments that will cause GAS to issue errors in NO_APP mode.

bool TARGET_ASM_FILE_START_FILE_DIRECTIVE              [Target Hook]
If this flag is true, output_file_directive will be called for the primary source file, immediately after printing ASM_APP_OFF (if that is enabled). Most ELF assemblers expect this to be done. The default is false.

void TARGET_ASM_FILE_END (void)                        [Target Hook]
Output to asm_out_file any text which the assembler expects to find at the end of a file. The default is to output nothing.

void file_end_indicate_exec_stack ()                   [Function]
Some systems use a common convention, the ‘.note.GNU-stack’ special section, to indicate whether or not an object file relies on the stack being executable. If your system uses this convention, you should define TARGET_ASM_FILE_END to this function. If you need to do other things in that hook, have your hook function call this function.

void TARGET_ASM_LTO_START (void)                      [Target Hook]
Output to asm_out_file any text which the assembler expects to find at the start of an LTO section. The default is to output nothing.

void TARGET_ASM_LTO_END (void)                         [Target Hook]
Output to asm_out_file any text which the assembler expects to find at the end of an LTO section. The default is to output nothing.
void TARGET_ASM_CODE_END (void)
    [Target Hook]
    Output to asm_out_file any text which is needed before emitting unwind info and
debug info at the end of a file. Some targets emit here PIC setup thunks that cannot
be emitted at the end of file, because they couldn't have unwind info then. The
default is to output nothing.

ASM_COMMENT_START
    [Macro]
    A C string constant describing how to begin a comment in the target assembler
language. The compiler assumes that the comment will end at the end of the line.

ASM_APP_ON
    [Macro]
    A C string constant for text to be output before each asm statement or group of
consecutive ones. Normally this is "#APP", which is a comment that has no effect on
most assemblers but tells the GNU assembler that it must check the lines that follow
for all valid assembler constructs.

ASM_APP_OFF
    [Macro]
    A C string constant for text to be output after each asm statement or group of con-
secutive ones. Normally this is "#NO_APP", which tells the GNU assembler to resume
making the time-saving assumptions that are valid for ordinary compiler output.

ASM_OUTPUT_SOURCE_FILENAME (stream, name)
    [Macro]
    A C statement to output COFF information or DWARF debugging information which
indicates that filename name is the current source file to the stdio stream stream.
    This macro need not be defined if the standard form of output for the file format in
use is appropriate.

void TARGET_ASM_OUTPUT_SOURCE_FILENAME (FILE *file, const
char *name)
    [Target Hook]
    Output DWARF debugging information which indicates that filename name is the
current source file to the stdio stream file.
    This target hook need not be defined if the standard form of output for the file format
in use is appropriate.

void TARGET_ASM_OUTPUT_IDENT (const char *name)
    [Target Hook]
    Output a string based on name, suitable for the ‘#ident’ directive, or the equivalent
directive or pragma in non-C-family languages. If this hook is not defined, nothing is
output for the ‘#ident’ directive.

OUTPUT_QUOTED_STRING (stream, string)
    [Macro]
    A C statement to output the string string to the stdio stream stream. If you do not
call the function output_quoted_string in your config files, GCC will only call it
to output filenames to the assembler source. So you can use it to canonicalize the
format of the filename using this macro.

void TARGET_ASM_NAMED_SECTION (const char *name, unsigned int flags, tree decl)
    [Target Hook]
    Output assembly directives to switch to section name. The section should have at-
tributes as specified by flags, which is a bit mask of the SECTION_* flags defined in
‘output.h’. If decl is non-NULL, it is the VAR_DECL or FUNCTION_DECL with which
this section is associated.
bool TARGET_ASM_ELF_FLAGS_NUMERIC (unsigned int flags, unsigned int *num) [Target Hook]
    This hook can be used to encode ELF section flags for which no letter code has been
defined in the assembler. It is called by default_asm_named_section whenever the
section flags need to be emitted in the assembler output. If the hook returns true,
then the numerical value for ELF section flags should be calculated from flags and
saved in *num; the value is printed out instead of the normal sequence of letter codes.
If the hook is not defined, or if it returns false, then num is ignored and the traditional
letter sequence is emitted.

section * TARGET_ASM_FUNCTION_SECTION (tree decl, enum node_frequency freq, bool startup, bool exit) [Target Hook]
    Return preferred text (sub)section for function decl. Main purpose of this function is
to separate cold, normal and hot functions. startup is true when function is known to
be used only at startup (from static constructors or it is main()). exit is true when
function is known to be used only at exit (from static destructors). Return NULL if
function should go to default text section.

void TARGET_ASM_FUNCTION_SWITCHED_TEXT_SECTIONS (FILE *file, tree decl, bool new_is_cold) [Target Hook]
    Used by the target to emit any assembler directives or additional labels needed when
a function is partitioned between different sections. Output should be written to file.
The function decl is available as decl and the new section is ‘cold’ if new_is_cold is
true.

bool TARGET_HAVE_NAMED_SECTIONS [Common Target Hook]
    This flag is true if the target supports TARGET_ASM_NAMED_SECTION. It must not be
modified by command-line option processing.

bool TARGET_HAVE_SWITCHABLE_BSS_SECTIONS [Target Hook]
    This flag is true if we can create zeroed data by switching to a BSS section and then
using ASM_OUTPUT_SKIP to allocate the space. This is true on most ELF targets.

unsigned int TARGET_SECTION_TYPE_FLAGS (tree decl, const char *name, int reloc) [Target Hook]
    Choose a set of section attributes for use by TARGET_ASM_NAMED_SECTION based on
a variable or function decl, a section name, and whether or not the declaration's
initializer may contain runtime relocations. decl may be null, in which case read-
write data should be assumed.

The default version of this function handles choosing code vs data, read-only vs read-
write data, and flag_pic. You should only need to override this if your target has
special flags that might be set via __attribute__.

void TARGET_ASM_RECORD_GCC_SWITCHES (const char *) [Target Hook]
    Provides the target with the ability to record the gcc command line switches provided
as argument.

By default this hook is set to NULL, but an example implementation is provided for
ELF based targets. Called elf_record_gcc_switches, it records the switches as ASCII
text inside a new, string mergeable section in the assembler output file. The name of the new section is provided by the `TARGET_ASM_RECORD_GCC_SWITCHES_SECTION` target hook.

```c
const char * TARGET_ASM_RECORD_GCC_SWITCHES_SECTION
```

This is the name of the section that will be created by the example ELF implementation of the `TARGET_ASM_RECORD_GCC_SWITCHES` target hook.

### 18.20.2 Output of Data

```c
const char * TARGET_ASM_BYTE_OP
const char * TARGET_ASM_ALIGNED_HI_OP
const char * TARGET_ASM_ALIGNED_PSI_OP
const char * TARGET_ASM_ALIGNED_SI_OP
const char * TARGET_ASM_ALIGNED_PDI_OP
const char * TARGET_ASM_ALIGNED_DI_OP
const char * TARGET_ASM_ALIGNED_PTI_OP
const char * TARGET_ASM_ALIGNED_TI_OP
const char * TARGET_ASM_UNALIGNED_HI_OP
const char * TARGET_ASM_UNALIGNED_PSI_OP
const char * TARGET_ASM_UNALIGNED_SI_OP
const char * TARGET_ASM_UNALIGNED_PDI_OP
const char * TARGET_ASM_UNALIGNED_DI_OP
const char * TARGET_ASM_UNALIGNED_PTI_OP
const char * TARGET_ASM_UNALIGNED_TI_OP
```

These hooks specify assembly directives for creating certain kinds of integer object. The `TARGET_ASM_BYTE_OP` directive creates a byte-sized object, the `TARGET_ASM_ALIGNED_HI_OP` one creates an aligned two-byte object, and so on. Any of the hooks may be `NULL`, indicating that no suitable directive is available.

The compiler will print these strings at the start of a new line, followed immediately by the object’s initial value. In most cases, the string should contain a tab, a pseudo-op, and then another tab.

```c
bool TARGET_ASM_INTEGER (rtx x, unsigned int size, int aligned_p)
```

The `assemble_integer` function uses this hook to output an integer object. `x` is the object’s value, `size` is its size in bytes and `aligned_p` indicates whether it is aligned. The function should return `true` if it was able to output the object. If it returns `false`, `assemble_integer` will try to split the object into smaller parts.

The default implementation of this hook will use the `TARGET_ASM_BYTE_OP` family of strings, returning `false` when the relevant string is `NULL`.

```c
void TARGET_ASM_DECL_END (void)
```

Define this hook if the target assembler requires a special marker to terminate an initialized variable declaration.
bool TARGET_ASM_OUTPUT_ADDR_CONST_EXTRA (FILE *file, rtx x)  [Target Hook]
A target hook to recognize rtx patterns that output_addr_const can’t deal with,
and output assembly code to file corresponding to the pattern x. This may be used
to allow machine-dependent UNSPECs to appear within constants.
If target hook fails to recognize a pattern, it must return false, so that a standard
error message is printed. If it prints an error message itself, by calling, for example,
output_operand_lossage, it may just return true.

ASM_OUTPUT_ASCII (stream, ptr, len)  [Macro]
A C statement to output to the stdout stream stream an assembler instruction to
assemble a string constant containing the len bytes at ptr. ptr will be a C expression
of type char * and len a C expression of type int.
If the assembler has a .ascii pseudo-op as found in the Berkeley Unix assembler, do
not define the macro ASM_OUTPUT_ASCII.

ASM_OUTPUT_FDESC (stream, decl, n)  [Macro]
A C statement to output word n of a function descriptor for decl. This must be
declared if TARGET_VTABLE_USES_DESCRIPTORS is defined, and is otherwise unused.

CONSTANT_POOL_BEFORE_FUNCTION  [Macro]
You may define this macro as a C expression. You should define the expression to
have a nonzero value if GCC should output the constant pool for a function before
the code for the function, or a zero value if GCC should output the constant pool
after the function. If you do not define this macro, the usual case, GCC will output
the constant pool before the function.

ASM_OUTPUT_POOL_PROLOGUE (file, funname, fundecl, size)  [Macro]
A C statement to output assembler commands to define the start of the constant pool
for a function. funname is a string giving the name of the function. Should the return
type of the function be required, it can be obtained via fundecl. size is the size, in
bytes, of the constant pool that will be written immediately after this call.

If no constant-pool prefix is required, the usual case, this macro need not be defined.

ASM_OUTPUT_SPECIAL_POOL_ENTRY (file, x, mode, align, labelno, jumpto)  [Macro]
A C statement (with or without semicolon) to output a constant in the constant pool,
if it needs special treatment. (This macro need not do anything for RTL expressions
that can be output normally.)

The argument file is the standard I/O stream to output the assembler code on. x is
the RTL expression for the constant to output, and mode is the machine mode (in
case x is a ‘const_int’). align is the required alignment for the value x; you should
output an assembler directive to force this much alignment.

The argument labelno is a number to use in an internal label for the address of
this pool entry. The definition of this macro is responsible for outputting the label
definition at the proper place. Here is how to do this:

(*targetm.asm_out.internal_label) (file, "LC", labelno);
When you output a pool entry specially, you should end with a `goto` to the label `jumpto`. This will prevent the same pool entry from being output a second time in the usual manner.

You need not define this macro if it would do nothing.

**ASM_OUTPUT_POOL_EPILOGUE (file funname fundecl size)**  
A C statement to output assembler commands to at the end of the constant pool for a function. `funname` is a string giving the name of the function. Should the return type of the function be required, you can obtain it via `fundecl`. `size` is the size, in bytes, of the constant pool that GCC wrote immediately before this call.

If no constant-pool epilogue is required, the usual case, you need not define this macro.

**IS_ASM_LOGICAL_LINE_SEPARATOR (C, STR)**  
Define this macro as a C expression which is nonzero if `C` is used as a logical line separator by the assembler. `STR` points to the position in the string where `C` was found; this can be used if a line separator uses multiple characters.

If you do not define this macro, the default is that only the character ‘;’ is treated as a logical line separator.

**const char * TARGET_ASM_OPEN_PAREN**  
**const char * TARGET_ASM_CLOSE_PAREN**  
These target hooks are C string constants, describing the syntax in the assembler for grouping arithmetic expressions. If not overridden, they default to normal parentheses, which is correct for most assemblers.

These macros are provided by `real.h` for writing the definitions of `ASM_OUTPUT_DOUBLE` and the like:

**REAL_VALUE_TO_TARGET_SINGLE (x, l)**  
**REAL_VALUE_TO_TARGET_DOUBLE (x, l)**  
**REAL_VALUE_TO_TARGET_LONG_DOUBLE (x, l)**  
**REAL_VALUE_TO_TARGET_DECIMAL32 (x, l)**  
**REAL_VALUE_TO_TARGET_DECIMAL64 (x, l)**  
**REAL_VALUE_TO_TARGET_DECIMAL128 (x, l)**  
These translate `x`, of type `REAL_VALUE_TYPE`, to the target’s floating point representation, and store its bit pattern in the variable `l`. For `REAL_VALUE_TO_TARGET_SINGLE` and `REAL_VALUE_TO_TARGET_DECIMAL32`, this variable should be a simple `long int`. For the others, it should be an array of `long int`. The number of elements in this array is determined by the size of the desired target floating point data type: 32 bits of it go in each `long int` array element. Each array element holds 32 bits of the result, even if `long int` is wider than 32 bits on the host machine.

The array element values are designed so that you can print them out using `printf` in the order they should appear in the target machine’s memory.

### 18.20.3 Output of Uninitialized Variables

Each of the macros in this section is used to do the whole job of outputting a single uninitialized variable.
ASM_OUTPUT_COMMON (stream, name, size, rounded) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream the assembler
definition of a common-label named name whose size is size bytes. The variable rounded is the size rounded up to whatever alignment the caller wants. It is possible that size may be zero, for instance if a struct with no other member than a zero-length array is defined. In this case, the backend must output a symbol definition that allocates at least one byte, both so that the address of the resulting object does not compare equal to any other, and because some object formats cannot even express the concept of a zero-sized common symbol, as that is how they represent an ordinary undefined external.

Use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for defining the name, and a newline.

This macro controls how the assembler definitions of uninitialized common global variables are output.

ASM_OUTPUT_ALIGNED_COMMON (stream, name, size, alignment) [Macro]
Like ASM_OUTPUT_COMMON except takes the required alignment as a separate, explicit argument. If you define this macro, it is used in place of ASM_OUTPUT_COMMON, and gives you more flexibility in handling the required alignment of the variable. The alignment is specified as the number of bits.

ASM_OUTPUT_ALIGNED_DECL_COMMON (stream, decl, name, size, alignment) [Macro]
Like ASM_OUTPUT_ALIGNED_COMMON except that decl of the variable to be output, if there is one, or NULL_TREE if there is no corresponding variable. If you define this macro, GCC will use it in place of both ASM_OUTPUT_COMMON and ASM_OUTPUT_ALIGNED_COMMON. Define this macro when you need to see the variable’s decl in order to chose what to output.

ASM_OUTPUT_ALIGNED_BSS (stream, decl, name, size, alignment) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream the assembler definition of uninitialized global decl named name whose size is size bytes. The variable alignment is the alignment specified as the number of bits.

Try to use function asm_output_aligned_bss defined in file ‘varasm.c’ when defining this macro. If unable, use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for defining the name, and a newline.

There are two ways of handling global BSS. One is to define this macro. The other is to have TARGET_ASM_SELECT_SECTION return a switchable BSS section (see [TARGET_HAVE_SWITCHABLE_BSS_SECTIONS], page 617). You do not need to do both.

Some languages do not have common data, and require a non-common form of global BSS in order to handle uninitialized globals efficiently. C++ is one example of this. However, if the target does not support global BSS, the front end may choose to make globals common in order to save space in the object file.
ASM_OUTPUT_LOCAL (stream, name, size, rounded) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream the assembler definition of a local-common-label named name whose size is size bytes. The variable rounded is the size rounded up to whatever alignment the caller wants.

Use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for defining the name, and a newline.

This macro controls how the assembler definitions of uninitialized static variables are output.

ASM_OUTPUT_ALIGNED_LOCAL (stream, name, size, alignment) [Macro]
Like ASM_OUTPUT_LOCAL except takes the required alignment as a separate, explicit argument. If you define this macro, it is used in place of ASM_OUTPUT_LOCAL, and gives you more flexibility in handling the required alignment of the variable. The alignment is specified as the number of bits.

ASM_OUTPUT_ALIGNED_DECL_LOCAL (stream, decl, name, size, alignment) [Macro]
Like ASM_OUTPUT_ALIGNED_LOCAL except that decl of the variable to be output, if there is one, or NULL_TREE if there is no corresponding variable. If you define this macro, GCC will use it in place of both ASM_OUTPUT_LOCAL and ASM_OUTPUT_ALIGNED_LOCAL. Define this macro when you need to see the variable’s decl in order to chose what to output.

18.20.4 Output and Generation of Labels
This is about outputting labels.

ASM_OUTPUT_LABEL (stream, name) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream the assembler definition of a label named name. Use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for defining the name, and a newline. A default definition of this macro is provided which is correct for most systems.

ASM_OUTPUT_FUNCTION_LABEL (stream, name, decl) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream the assembler definition of a label named name of a function. Use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for defining the name, and a newline. A default definition of this macro is provided which is correct for most systems.

If this macro is not defined, then the function name is defined in the usual manner as a label (by means of ASM_OUTPUT_LABEL).

ASM_OUTPUT_INTERNAL_LABEL (stream, name) [Macro]
Identical to ASM_OUTPUT_LABEL, except that name is known to refer to a compiler-generated label. The default definition uses assemble_name_raw, which is like assemble_name except that it is more efficient.
**SIZE_ASM_OP**

A C string containing the appropriate assembler directive to specify the size of a symbol, without any arguments. On systems that use ELF, the default (in ‘config/elfos.h’) is ‘"\t.size\t"'; on other systems, the default is not to define this macro.

Define this macro only if it is correct to use the default definitions of **ASM_OUTPUT_SIZE_DIRECTIVE** and **ASM_OUTPUT_MEASURED_SIZE** for your system. If you need your own custom definitions of those macros, or if you do not need explicit symbol sizes at all, do not define this macro.

**ASM_OUTPUT_SIZE_DIRECTIVE** *(stream, name, size)*

A C statement (sans semicolon) to output to the stdio stream *stream* a directive telling the assembler that the size of the symbol *name* is *size*. *size* is a **HOST_WIDE_INT**. If you define **SIZE_ASM_OP**, a default definition of this macro is provided.

**ASM_OUTPUT_MEASURED_SIZE** *(stream, name)*

A C statement (sans semicolon) to output to the stdio stream *stream* a directive telling the assembler to calculate the size of the symbol *name* by subtracting its address from the current address.

If you define **SIZE_ASM_OP**, a default definition of this macro is provided. The default assumes that the assembler recognizes a special ‘.’ symbol as referring to the current address, and can calculate the difference between this and another symbol. If your assembler does not recognize ‘.’ or cannot do calculations with it, you will need to redefine **ASM_OUTPUT_MEASURED_SIZE** to use some other technique.

**NO_DOLLAR_IN_LABEL**

Define this macro if the assembler does not accept the character ‘$’ in label names. By default constructors and destructors in G++ have ‘$’ in the identifiers. If this macro is defined, ‘.’ is used instead.

**NO_DOT_IN_LABEL**

Define this macro if the assembler does not accept the character ‘.’ in label names. By default constructors and destructors in G++ have names that use ‘.’. If this macro is defined, these names are rewritten to avoid ‘.’.

**TYPE_ASM_OP**

A C string containing the appropriate assembler directive to specify the type of a symbol, without any arguments. On systems that use ELF, the default (in ‘config/elfos.h’) is ‘"\t.type\t"'; on other systems, the default is not to define this macro.

Define this macro only if it is correct to use the default definition of **ASM_OUTPUT_TYPE_DIRECTIVE** for your system. If you need your own custom definition of this macro, or if you do not need explicit symbol types at all, do not define this macro.

**TYPE_OPERAND_FMT**

A C string which specifies (using printf syntax) the format of the second operand to **TYPE_ASM_OP**. On systems that use ELF, the default (in ‘config/elfos.h’) is ‘"@%s"'; on other systems, the default is not to define this macro.
Define this macro only if it is correct to use the default definition of `ASM_OUTPUT_TYPE_DIRECTIVE` for your system. If you need your own custom definition of this macro, or if you do not need explicit symbol types at all, do not define this macro.

`ASM_OUTPUT_TYPE_DIRECTIVE (stream, type)` [Macro]
A C statement (sans semicolon) to output to the stdio stream `stream` a directive telling the assembler that the type of the symbol `name` is `type`. `type` is a C string; currently, that string is always either "function" or "object", but you should not count on this.

If you define `TYPE_ASM_OP` and `TYPE_OPERAND_FMT`, a default definition of this macro is provided.

`ASM_DECLARE_FUNCTION_NAME (stream, name, decl)` [Macro]
A C statement (sans semicolon) to output to the stdio stream `stream` any text necessary for declaring the name `name` of a function which is being defined. This macro is responsible for outputting the label definition (perhaps using `ASM_OUTPUT_FUNCTION_LABEL`). The argument `decl` is the `FUNCTION_DECL` tree node representing the function.

If this macro is not defined, then the function name is defined in the usual manner as a label (by means of `ASM_OUTPUT_FUNCTION_LABEL`).

You may wish to use `ASM_OUTPUT_TYPE_DIRECTIVE` in the definition of this macro.

`ASM_DECLARE_FUNCTION_SIZE (stream, name, decl)` [Macro]
A C statement (sans semicolon) to output to the stdio stream `stream` any text necessary for declaring the size of a function which is being defined. The argument `name` is the name of the function. The argument `decl` is the `FUNCTION_DECL` tree node representing the function.

If this macro is not defined, then the function size is not defined.

You may wish to use `ASM_OUTPUT_MEASURED_SIZE` in the definition of this macro.

`ASM_DECLARE_COLD_FUNCTION_NAME (stream, name, decl)` [Macro]
A C statement (sans semicolon) to output to the stdio stream `stream` any text necessary for declaring the name `name` of a cold function partition which is being defined. This macro is responsible for outputting the label definition (perhaps using `ASM_OUTPUT_FUNCTION_LABEL`). The argument `decl` is the `FUNCTION_DECL` tree node representing the function.

If this macro is not defined, then the cold partition name is defined in the usual manner as a label (by means of `ASM_OUTPUT_LABEL`).

You may wish to use `ASM_OUTPUT_TYPE_DIRECTIVE` in the definition of this macro.

`ASM_DECLARE_COLD_FUNCTION_SIZE (stream, name, decl)` [Macro]
A C statement (sans semicolon) to output to the stdio stream `stream` any text necessary for declaring the size of a cold function partition which is being defined. The argument `name` is the name of the cold partition of the function. The argument `decl` is the `FUNCTION_DECL` tree node representing the function.

If this macro is not defined, then the partition size is not defined.

You may wish to use `ASM_OUTPUT_MEASURED_SIZE` in the definition of this macro.
**ASM_DECLARE_OBJECT_NAME** *(stream, name, decl)*  
A C statement (sans semicolon) to output to the stdio stream *stream* any text necessary for declaring the name *name* of an initialized variable which is being defined. This macro must output the label definition (perhaps using **ASM_OUTPUT_LABEL**). The argument *decl* is the **VAR_DECL** tree node representing the variable.

If this macro is not defined, then the variable name is defined in the usual manner as a label (by means of **ASM_OUTPUT_LABEL**).

You may wish to use **ASM_OUTPUT_TYPE_DIRECTIVE** and/or **ASM_OUTPUT_SIZE_DIRECTIVE** in the definition of this macro.

**void** **TARGET_ASM_DECLARE_CONSTANT_NAME** *(FILE *file, const char *name, const tree expr, HOST_WIDE_INT size)*  
A target hook to output to the stdio stream *file* any text necessary for declaring the name *name* of a constant which is being defined. This target hook is responsible for outputting the label definition (perhaps using **assemble_label**). The argument *expr* is the value of the constant, and *size* is the size of the constant in bytes. The name will be an internal label.

The default version of this target hook, define the *name* in the usual manner as a label (by means of **assemble_label**).

You may wish to use **ASM_OUTPUT_TYPE_DIRECTIVE** in this target hook.

**ASM_DECLARE_REGISTER_GLOBAL** *(stream, decl, regno, name)*  
A C statement (sans semicolon) to output to the stdio stream *stream* any text necessary for claiming a register *regno* for a global variable *decl* with name *name*.

If you don’t define this macro, that is equivalent to defining it to do nothing.

**ASM_FINISH_DECLARE_OBJECT** *(stream, decl, toplevel, atend)*  
A C statement (sans semicolon) to finish up declaring a variable name once the compiler has processed its initializer fully and thus has had a chance to determine the size of an array when controlled by an initializer. This is used on systems where it’s necessary to declare something about the size of the object.

If you don’t define this macro, that is equivalent to defining it to do nothing.

You may wish to use **ASM_OUTPUT_SIZE_DIRECTIVE** and/or **ASM_OUTPUT_MEASURED_SIZE** in the definition of this macro.

**void** **TARGET_ASM_GLOBALIZE_LABEL** *(FILE *stream, const char *name)*  
This target hook is a function to output to the stdio stream *stream* some commands that will make the label name global; that is, available for reference from other files.

The default implementation relies on a proper definition of **GLOBAL_ASM_OP**.

**void** **TARGET_ASM_GLOBALIZE_DECL_NAME** *(FILE *stream, tree decl)*  
This target hook is a function to output to the stdio stream *stream* some commands that will make the name associated with *decl* global; that is, available for reference from other files.

The default implementation uses the **TARGET_ASM_GLOBALIZE_LABEL** target hook.
void TARGET_ASM_ASSEMBLE_UNDEFINED_DECL (FILE *stream, const char *name, const tree decl) [Target Hook]

This target hook is a function to output to the stdio stream stream some commands that will declare the name associated with decl which is not defined in the current translation unit. Most assemblers do not require anything to be output in this case.

ASM_WEAKEN_LABEL (stream, name) [Macro]
A C statement (sans semicolon) to output to the stdio stream stream some commands that will make the label name weak; that is, available for reference from other files but only used if no other definition is available. Use the expression assemble_name (stream, name) to output the name itself; before and after that, output the additional assembler syntax for making that name weak, and a newline.

If you don’t define this macro or ASM_WEAKEN_DECL, GCC will not support weak symbols and you should not define the SUPPORTS_WEAK macro.

ASM_WEAKEN_DECL (stream, decl, name, value) [Macro]
Combines (and replaces) the function of ASM_WEAKEN_LABEL and ASM_OUTPUT_WEAK_ALIAS, allowing access to the associated function or variable decl. If value is not NULL, this C statement should output to the stdio stream stream assembler code which defines (equates) the weak symbol name to have the value value. If value is NULL, it should output commands to make name weak.

ASM_OUTPUT_WEAKREF (stream, decl, name, value) [Macro]
Outputs a directive that enables name to be used to refer to symbol value with weak-symbol semantics. decl is the declaration of name.

SUPPORTS_WEAK [Macro]
A preprocessor constant expression which evaluates to true if the target supports weak symbols.

If you don’t define this macro, ‘defaults.h’ provides a default definition. If either ASM_WEAKEN_LABEL or ASM_WEAKEN_DECL is defined, the default definition is ‘1’; otherwise, it is ‘0’.

TARGET_SUPPORTS_WEAK [Macro]
A C expression which evaluates to true if the target supports weak symbols.

If you don’t define this macro, ‘defaults.h’ provides a default definition. The default definition is ‘(SUPPORTS_WEAK)’. Define this macro if you want to control weak symbol support with a compiler flag such as ‘-melf’.

MAKE_DECL_ONE_ONLY (decl) [Macro]
A C statement (sans semicolon) to mark decl to be emitted as a public symbol such that extra copies in multiple translation units will be discarded by the linker. Define this macro if your object file format provides support for this concept, such as the ‘COMDAT’ section flags in the Microsoft Windows PE/COFF format, and this support requires changes to decl, such as putting it in a separate section.

SUPPORTS_ONE_ONLY [Macro]
A C expression which evaluates to true if the target supports one-only semantics.
If you don’t define this macro, ‘varasm.c’ provides a default definition. If `MAKE_DECL_ONE_ONLY` is defined, the default definition is ‘1’; otherwise, it is ‘0’. Define this macro if you want to control one-only symbol support with a compiler flag, or if setting the `DECL_ONE_ONLY` flag is enough to mark a declaration to be emitted as one-only.

```c
void TARGET_ASM_ASSEMBLE_VISIBILITY (tree decl, int visibility) [Target Hook]
```

This target hook is a function to output to `asm_out_file` some commands that will make the symbol(s) associated with `decl` have hidden, protected or internal visibility as specified by `visibility`.

```c
TARGET_WEAK_NOT_IN_ARCHIVE_TOC [Macro]
```

A C expression that evaluates to true if the target’s linker expects that weak symbols do not appear in a static archive’s table of contents. The default is 0.

Leaving weak symbols out of an archive’s table of contents means that, if a symbol will only have a definition in one translation unit and will have undefined references from other translation units, that symbol should not be weak. Defining this macro to be nonzero will thus have the effect that certain symbols that would normally be weak (explicit template instantiations, and vtables for polymorphic classes with noninline key methods) will instead be nonweak.

The C++ ABI requires this macro to be zero. Define this macro for targets where full C++ ABI compliance is impossible and where linker restrictions require weak symbols to be left out of a static archive’s table of contents.

```c
ASM_OUTPUT_EXTERNAL (stream, decl, name) [Macro]
```

A C statement (sans semicolon) to output to the stdio stream `stream` any text necessary for declaring the name of an external symbol named `name` which is referenced in this compilation but not defined. The value of `decl` is the tree node for the declaration.

This macro need not be defined if it does not need to output anything. The GNU assembler and most Unix assemblers don’t require anything.

```c
void TARGET_ASM_EXTERNAL_LIBCALL (rtx symref) [Target Hook]
```

This target hook is a function to output to `asm_out_file` an assembler pseudo-op to declare a library function name external. The name of the library function is given by `symref`, which is a `symbol_ref`.

```c
void TARGET_ASM_MARK_DECL_PRESERVED (const char *symbol) [Target Hook]
```

This target hook is a function to output to `asm_out_file` an assembler directive to annotate `symbol` as used. The Darwin target uses the `.no_dead_code_strip` directive.

```c
ASM_OUTPUT_LABELREF (stream, name) [Macro]
```

A C statement (sans semicolon) to output to the stdio stream `stream` a reference in assembler syntax to a label named `name`. This should add ‘_’ to the front of the name, if that is customary on your operating system, as it is in most Berkeley Unix systems. This macro is used in `assemble_name`. 
tree TARGET_MANGLE_ASSEMBLER_NAME (const char *name)  [Target Hook]
   Given a symbol name, perform same mangling as varasm.c's assemble_name, but
   in memory rather than to a file stream, returning result as an IDENTIFIER_NODE.
   Required for correct LTO symtabs. The default implementation calls the TARGET_STRIP_NAME_ENCODING hook and then prepends the USER_LABEL_PREFIX, if any.

ASM_OUTPUT_SYMBOL_REF (stream, sym)  [Macro]
   A C statement (sans semicolon) to output a reference to SYMBOL_REF sym. If not
   defined, assemble_name will be used to output the name of the symbol. This macro
   may be used to modify the way a symbol is referenced depending on information
   encoded by TARGET_ENCODE_SECTION_INFO.

ASM_OUTPUT_LABEL_REF (stream, buf)  [Macro]
   A C statement (sans semicolon) to output a reference to buf, the result of ASM_GENERATE_INTERNAL_LABEL. If not defined, assemble_name will be used to output
   the name of the symbol. This macro is not used by output_asm_label, or the %1 specifier that calls it; the intention is that this macro should be set when it is necessary
   to output a label differently when its address is being taken.

void TARGET_ASM_INTERNAL_LABEL (FILE *stream, const char *prefix, unsigned long labelno)  [Target Hook]
   A function to output to the stdio stream stream a label whose name is made from
   the string prefix and the number labelno.
   It is absolutely essential that these labels be distinct from the labels used for user-level functions and variables. Otherwise, certain programs will have name conflicts with
   internal labels.
   It is desirable to exclude internal labels from the symbol table of the object file. Most
   assemblers have a naming convention for labels that should be excluded; on many
   systems, the letter ‘L’ at the beginning of a label has this effect. You should find out
   what convention your system uses, and follow it.
   The default version of this function utilizes ASM_GENERATE_INTERNAL_LABEL.

ASM_OUTPUT_DEBUG_LABEL (stream, prefix, num)  [Macro]
   A C statement to output to the stdio stream stream a debug info label whose name
   is made from the string prefix and the number num. This is useful for VLIW targets,
   where debug info labels may need to be treated differently than branch target
   labels. On some systems, branch target labels must be at the beginning of instruction
   bundles, but debug info labels can occur in the middle of instruction bundles.
   If this macro is not defined, then (*targetm.asm_out.internal_label) will be used.

ASM_GENERATE_INTERNAL_LABEL (string, prefix, num)  [Macro]
   A C statement to store into the string string a label whose name is made from
   the string prefix and the number num.
   This string, when output subsequently by assemble_name, should produce the output
   that (*targetm.asm_out.internal_label) would produce with the same prefix and
   num.
   If the string begins with ‘*’, then assemble_name will output the rest of the string
   unchanged. It is often convenient for ASM_GENERATE_INTERNAL_LABEL to use ‘*’ in
this way. If the string doesn’t start with ‘*’, then \texttt{ASM\_OUTPUT\_LABELREF} gets to output the string, and may change it. (Of course, \texttt{ASM\_OUTPUT\_LABELREF} is also part of your machine description, so you should know what it does on your machine.)

\textbf{ASM\_FORMAT\_PRIVATE\_NAME (outvar, name, number)} \hspace{1cm} [Macro]

A C expression to assign to outvar (which is a variable of type \texttt{char *}) a newly allocated string made from the string name and the number number, with some suitable punctuation added. Use \texttt{alloca} to get space for the string.

The string will be used as an argument to \texttt{ASM\_OUTPUT\_LABELREF} to produce an assembler label for an internal static variable whose name is name. Therefore, the string must be such as to result in valid assembler code. The argument number is different each time this macro is executed; it prevents conflicts between similarly-named internal static variables in different scopes.

Ideally this string should not be a valid C identifier, to prevent any conflict with the user’s own symbols. Most assemblers allow periods or percent signs in assembler symbols; putting at least one of these between the name and the number will suffice.

If this macro is not defined, a default definition will be provided which is correct for most systems.

\textbf{ASM\_OUTPUT\_DEF (stream, name, value)} \hspace{1cm} [Macro]

A C statement to output to the stdio stream stream assembler code which defines (equates) the symbol name to have the value value.

If \texttt{SET\_ASM\_OP} is defined, a default definition is provided which is correct for most systems.

\textbf{ASM\_OUTPUT\_DEF\_FROM\_DECLS (stream, decl\_of\_name, decl\_of\_value)} \hspace{1cm} [Macro]

A C statement to output to the stdio stream stream assembler code which defines (equates) the symbol whose tree node is decl\_of\_name to have the value of the tree node decl\_of\_value. This macro will be used in preference to ‘\texttt{ASM\_OUTPUT\_DEF}’ if it is defined and if the tree nodes are available.

If \texttt{SET\_ASM\_OP} is defined, a default definition is provided which is correct for most systems.

\textbf{TARGET\_DEFERRED\_OUTPUT\_DEFS (decl\_of\_name, decl\_of\_value)} \hspace{1cm} [Macro]

A C statement that evaluates to true if the assembler code which defines (equates) the symbol whose tree node is decl\_of\_name to have the value of the tree node decl\_of\_value should be emitted near the end of the current compilation unit. The default is to not defer output of defines. This macro affects defines output by ‘\texttt{ASM\_OUTPUT\_DEF}’ and ‘\texttt{ASM\_OUTPUT\_DEF\_FROM\_DECLS}’.

\textbf{ASM\_OUTPUT\_WEAK\_ALIAS (stream, name, value)} \hspace{1cm} [Macro]

A C statement to output to the stdio stream stream assembler code which defines (equates) the weak symbol name to have the value value. If value is \texttt{NULL}, it defines name as an undefined weak symbol.

Define this macro if the target only supports weak aliases; define \texttt{ASM\_OUTPUT\_DEF} instead if possible.
OBJC_GEN_METHOD_LABEL (buf, is_inst, class_name, cat_name, sel_name)

Define this macro to override the default assembler names used for Objective-C methods.

The default name is a unique method number followed by the name of the class (e.g. `_1_Foo`). For methods in categories, the name of the category is also included in the assembler name (e.g. `_1_Foo_Bar`).

These names are safe on most systems, but make debugging difficult since the method’s selector is not present in the name. Therefore, particular systems define other ways of computing names.

`buf` is an expression of type `char *` which gives you a buffer in which to store the name; its length is as long as `class_name`, `cat_name` and `sel_name` put together, plus 50 characters extra.

The argument `is_inst` specifies whether the method is an instance method or a class method; `class_name` is the name of the class; `cat_name` is the name of the category (or NULL if the method is not in a category); and `sel_name` is the name of the selector.

On systems where the assembler can handle quoted names, you can use this macro to provide more human-readable names.

18.20.5 How Initialization Functions Are Handled

The compiled code for certain languages includes constructors (also called initialization routines)—functions to initialize data in the program when the program is started. These functions need to be called before the program is “started”—that is to say, before `main` is called.

Compiling some languages generates destructors (also called termination routines) that should be called when the program terminates.

To make the initialization and termination functions work, the compiler must output something in the assembler code to cause those functions to be called at the appropriate time. When you port the compiler to a new system, you need to specify how to do this.

There are two major ways that GCC currently supports the execution of initialization and termination functions. Each way has two variants. Much of the structure is common to all four variations.

The linker must build two lists of these functions—a list of initialization functions, called `__CTOR_LIST__`, and a list of termination functions, called `__DTOR_LIST__`.

Each list always begins with an ignored function pointer (which may hold 0, −1, or a count of the function pointers after it, depending on the environment). This is followed by a series of zero or more function pointers to constructors (or destructors), followed by a function pointer containing zero.

Depending on the operating system and its executable file format, either `crtstuff.c` or `libgcc2.c` traverses these lists at startup time and exit time. Constructors are called in reverse order of the list; destructors in forward order.

The best way to handle static constructors works only for object file formats which provide arbitrarily-named sections. A section is set aside for a list of constructors, and another for a list of destructors. Traditionally these are called `.ctors` and `.dtors`. Each object file
that defines an initialization function also puts a word in the constructor section to point to that function. The linker accumulates all these words into one contiguous `.ctors` section. Termination functions are handled similarly.

This method will be chosen as the default by `target-def.h` if `TARGET_ASM_NAMED_SECTION` is defined. A target that does not support arbitrary sections, but does support special designated constructor and destructor sections may define `CTORS_SECTION_ASM_OP` and `DTORS_SECTION_ASM_OP` to achieve the same effect.

When arbitrary sections are available, there are two variants, depending upon how the code in `crtstuff.c` is called. On systems that support a `.init` section which is executed at program startup, parts of `crtstuff.c` are compiled into that section. The program is linked by the `gcc` driver like this:

```
ld -o output_file crt.o crtbegin.o ... -lgcc crtend.o crtn.o
```

The prologue of a function (`__init`) appears in the `.init` section of `crti.o`; the epilogue appears in `crtn.o`. Likewise for the function `__fini` in the `.fini` section. Normally these files are provided by the operating system or by the GNU C library, but are provided by GCC for a few targets.

The objects `crtbegin.o` and `crtend.o` are (for most targets) compiled from `crtstuff.c`. They contain, among other things, code fragments within the `.init` and `.fini` sections that branch to routines in the `.text` section. The linker will pull all parts of a section together, which results in a complete `__init` function that invokes the routines we need at startup.

To use this variant, you must define the `INIT_SECTION_ASM_OP` macro properly.

If no init section is available, when GCC compiles any function called `main` (or more accurately, any function designated as a program entry point by the language front end calling `expand_main_function`), it inserts a procedure call to `__main` as the first executable code after the function prologue. The `__main` function is defined in `libgcc2.c` and runs the global constructors.

In file formats that don’t support arbitrary sections, there are again two variants. In the simplest variant, the GNU linker (GNU `ld`) and an ‘a.out’ format must be used. In this case, `TARGET_ASM_CONSTRUCTOR` is defined to produce a .stabs entry of type ‘N_SETT’, referencing the name `__CTOR_LIST__`, and with the address of the void function containing the initialization code as its value. The GNU linker recognizes this as a request to add the value to a set; the values are accumulated, and are eventually placed in the executable as a vector in the format described above, with a leading (ignored) count and a trailing zero element. `TARGET_ASM_DESTRUCTOR` is handled similarly. Since no init section is available, the absence of `INIT_SECTION_ASM_OP` causes the compilation of `main` to call `__main` as above, starting the initialization process.

The last variant uses neither arbitrary sections nor the GNU linker. This is preferable when you want to do dynamic linking and when using file formats which the GNU linker does not support, such as ‘ECOFF’. In this case, `TARGET_HAVE_CTORS_DTORS` is false, initialization and termination functions are recognized simply by their names. This requires an extra program in the linkage step, called `collect2`. This program pretends to be the linker, for use with GCC; it does its job by running the ordinary linker, but also arranges to include the vectors of initialization and termination functions. These functions are called
via __main as described above. In order to use this method, use_collect2 must be defined in the target in ‘config.gcc’.

18.20.6 Macros Controlling Initialization Routines

Here are the macros that control how the compiler handles initialization and termination functions:

INIT_SECTION_ASM_OP [Macro]
If defined, a C string constant, including spacing, for the assembler operation to identify the following data as initialization code. If not defined, GCC will assume such a section does not exist. When you are using special sections for initialization and termination functions, this macro also controls how ‘crtstuff.c’ and ‘libgcc2.c’ arrange to run the initialization functions.

HAS_INIT_SECTION [Macro]
If defined, main will not call __main as described above. This macro should be defined for systems that control start-up code on a symbol-by-symbol basis, such as OSF/1, and should not be defined explicitly for systems that support INIT_SECTION_ASM_OP.

LD_INIT_SWITCH [Macro]
If defined, a C string constant for a switch that tells the linker that the following symbol is an initialization routine.

LD_FINI_SWITCH [Macro]
If defined, a C string constant for a switch that tells the linker that the following symbol is a finalization routine.

COLLECT_SHARED_INIT_FUNC (stream, func) [Macro]
If defined, a C statement that will write a function that can be automatically called when a shared library is loaded. The function should call func, which takes no arguments. If not defined, and the object format requires an explicit initialization function, then a function called GLOBAL__DI will be generated.

This function and the following one are used by collect2 when linking a shared library that needs constructors or destructors, or has DWARF2 exception tables embedded in the code.

COLLECT_SHARED_FINI_FUNC (stream, func) [Macro]
If defined, a C statement that will write a function that can be automatically called when a shared library is unloaded. The function should call func, which takes no arguments. If not defined, and the object format requires an explicit finalization function, then a function called GLOBAL__DD will be generated.

INVOKE__main [Macro]
If defined, main will call __main despite the presence of INIT_SECTION_ASM_OP. This macro should be defined for systems where the init section is not actually run automatically, but is still useful for collecting the lists of constructors and destructors.

SUPPORTS_INIT_PRIORITY [Macro]
If nonzero, the C++ init_priority attribute is supported and the compiler should emit instructions to control the order of initialization of objects. If zero, the compiler will issue an error message upon encountering an init_priority attribute.
bool TARGET_HAVE_CTORS_DTORS
[Target Hook]
This value is true if the target supports some “native” method of collecting constructors and destructors to be run at startup and exit. It is false if we must use collect2.

void TARGET_ASM_CONSTRUCTOR (rtx symbol, int priority)
[Target Hook]
If defined, a function that outputs assembler code to arrange to call the function referenced by symbol at initialization time.
Assume that symbol is a SYMBOL_REF for a function taking no arguments and with no return value. If the target supports initialization priorities, priority is a value between 0 and MAX_INIT_PRIORITY; otherwise it must be DEFAULT_INIT_PRIORITY.
If this macro is not defined by the target, a suitable default will be chosen if (1) the target supports arbitrary section names, (2) the target defines CTORS_SECTION_ASM_OP, or (3) USE_COLLECT2 is not defined.

void TARGET_ASM_DESTRUCTOR (rtx symbol, int priority)
[Target Hook]
This is like TARGET_ASM_CONSTRUCTOR but used for termination functions rather than initialization functions.

If TARGET_HAVE_CTORS_DTORS is true, the initialization routine generated for the generated object file will have static linkage.

If your system uses collect2 as the means of processing constructors, then that program normally uses nm to scan an object file for constructor functions to be called.

On certain kinds of systems, you can define this macro to make collect2 work faster (and, in some cases, make it work at all):

OBJECT_FORMAT_COFF
[Macro]
Define this macro if the system uses COFF (Common Object File Format) object files, so that collect2 can assume this format and scan object files directly for dynamic constructor/destructor functions.
This macro is effective only in a native compiler; collect2 as part of a cross compiler always uses nm for the target machine.

REAL_NM_FILE_NAME
[Macro]
Define this macro as a C string constant containing the file name to use to execute nm. The default is to search the path normally for nm.

NM_FLAGS
[Macro]
collect2 calls nm to scan object files for static constructors and destructors and LTO info. By default, ‘-n’ is passed. Define NM_FLAGS to a C string constant if other options are needed to get the same output format as GNU nm -n produces.

If your system supports shared libraries and has a program to list the dynamic dependencies of a given library or executable, you can define these macros to enable support for running initialization and termination functions in shared libraries:

LDD_SUFFIX
[Macro]
Define this macro to a C string constant containing the name of the program which lists dynamic dependencies, like ldd under SunOS 4.
PARSE_LDD_OUTPUT (ptr)  [Macro]
Define this macro to be C code that extracts filenames from the output of the program denoted by LDD_SUFFIX. ptr is a variable of type char * that points to the beginning of a line of output from LDD_SUFFIX. If the line lists a dynamic dependency, the code must advance ptr to the beginning of the filename on that line. Otherwise, it must set ptr to NULL.

SHLIB_SUFFIX  [Macro]
Define this macro to a C string constant containing the default shared library extension of the target (e.g., "so"). collect2 strips version information after this suffix when generating global constructor and destructor names. This define is only needed on targets that use collect2 to process constructors and destructors.

18.20.7 Output of Assembler Instructions
This describes assembler instruction output.

REGISTER_NAMES  [Macro]
A C initializer containing the assembler’s names for the machine registers, each one as a C string constant. This is what translates register numbers in the compiler into assembler language.

ADDITIONAL_REGISTER_NAMES  [Macro]
If defined, a C initializer for an array of structures containing a name and a register number. This macro defines additional names for hard registers, thus allowing the asm option in declarations to refer to registers using alternate names.

OVERLAPPING_REGISTER_NAMES  [Macro]
If defined, a C initializer for an array of structures containing a name, a register number and a count of the number of consecutive machine registers the name overlaps. This macro defines additional names for hard registers, thus allowing the asm option in declarations to refer to registers using alternate names. Unlike ADDITIONALREGISTER_NAMES, this macro should be used when the register name implies multiple underlying registers.

This macro should be used when it is important that a clobber in an asm statement clobbers all the underlying values implied by the register name. For example, on ARM, clobbering the double-precision VFP register “d0” implies clobbering both single-precision registers “s0” and “s1”.

ASM_OUTPUT_OPCODE (stream, ptr)  [Macro]
Define this macro if you are using an unusual assembler that requires different names for the machine instructions.

The definition is a C statement or statements which output an assembler instruction opcode to the stdio stream stream. The macro-operand ptr is a variable of type char * which points to the opcode name in its “internal” form—the form that is written in the machine description. The definition should output the opcode name to stream, performing any translation you desire, and increment the variable ptr to point at the end of the opcode so that it will not be output twice.
In fact, your macro definition may process less than the entire opcode name, or more than the opcode name; but if you want to process text that includes '\%'-sequences to substitute operands, you must take care of the substitution yourself. Just be sure to increment \texttt{ptr} over whatever text should not be output normally.

If you need to look at the operand values, they can be found as the elements of \texttt{recog_data.operand}.

If the macro definition does nothing, the instruction is output in the usual way.

\textbf{FINAL\_PRESCAN\_INSN} \texttt{(insn, opvec, noperands)} \textbf{[Macro]}

If defined, a C statement to be executed just prior to the output of assembler code for \texttt{insn}, to modify the extracted operands so they will be output differently.

Here the argument \texttt{opvec} is the vector containing the operands extracted from \texttt{insn}, and \texttt{noperands} is the number of elements of the vector which contain meaningful data for this insn. The contents of this vector are what will be used to convert the insn template into assembler code, so you can change the assembler output by changing the contents of the vector.

This macro is useful when various assembler syntaxes share a single file of instruction patterns; by defining this macro differently, you can cause a large class of instructions to be output differently (such as with rearranged operands). Naturally, variations in assembler syntax affecting individual insn patterns ought to be handled by writing conditional output routines in those patterns.

If this macro is not defined, it is equivalent to a null statement.

\textbf{void TARGET\_ASM\_FINAL\_POSTSCAN\_INSN} \texttt{(FILE *file, rtx insn \*, rtx \*opvec, int noperands)} \textbf{[Target Hook]}

If defined, this target hook is a function which is executed just after the output of assembler code for \texttt{insn}, to change the mode of the assembler if necessary.

Here the argument \texttt{opvec} is the vector containing the operands extracted from \texttt{insn}, and \texttt{noperands} is the number of elements of the vector which contain meaningful data for this insn. The contents of this vector are what was used to convert the insn template into assembler code, so you can change the assembler mode by checking the contents of the vector.

\textbf{PRINT\_OPERAND} \texttt{(stream, x, code)} \textbf{[Macro]}

A C compound statement to output to stdio stream \texttt{stream} the assembler syntax for an instruction operand \texttt{x}. \texttt{x} is an RTL expression.

\texttt{code} is a value that can be used to specify one of several ways of printing the operand. It is used when identical operands must be printed differently depending on the context. \texttt{code} comes from the '\%' specification that was used to request printing of the operand. If the specification was just '\%' then \texttt{code} is 0; if the specification was '\%ltr digit' then \texttt{code} is the ASCII code for \texttt{ltr}.

If \texttt{x} is a register, this macro should print the register’s name. The names can be found in an array \texttt{reg\_names} whose type is \texttt{char *[]} \texttt{reg\_names} is initialized from \texttt{REGISTER\_NAMES}.

When the machine description has a specification '\%punct' (a '\%' followed by a punctuation character), this macro is called with a null pointer for \texttt{x} and the punctuation character for \texttt{code}. 
PRINT_OPERAND_PUNCT_VALID_P (code) [Macro]
A C expression which evaluates to true if code is a valid punctuation character for use in the PRINT_OPERAND macro. If PRINT_OPERAND_PUNCT_VALID_P is not defined, it means that no punctuation characters (except for the standard one, ‘%’) are used in this way.

PRINT_OPERAND_ADDRESS (stream, x) [Macro]
A C compound statement to output to stdio stream stream the assembler syntax for an instruction operand that is a memory reference whose address is x. x is an RTL expression.

On some machines, the syntax for a symbolic address depends on the section that the address refers to. On these machines, define the hook TARGET_ENCODE_SECTION_INFO to store the information into the symbol_ref, and then check for it here. See Section 18.20 [Assembler Format], page 615.

DBR_OUTPUT_SEQEND (file) [Macro]
A C statement, to be executed after all slot-filler instructions have been output. If necessary, call dbr_sequence_length to determine the number of slots filled in a sequence (zero if not currently outputting a sequence), to decide how many no-ops to output, or whatever.

Don’t define this macro if it has nothing to do, but it is helpful in reading assembly output if the extent of the delay sequence is made explicit (e.g. with white space).

Note that output routines for instructions with delay slots must be prepared to deal with not being output as part of a sequence (i.e. when the scheduling pass is not run, or when no slot fillers could be found.) The variable final_sequence is null when not processing a sequence, otherwise it contains the sequence rtx being output.

REGISTER_PREFIX [Macro]
LOCAL_LABEL_PREFIX [Macro]
USER_LABEL_PREFIX [Macro]
IMMEDIATE_PREFIX [Macro]
If defined, C string expressions to be used for the ‘%R’, ‘%L’, ‘%U’, and ‘%I’ options of asm_fprintf (see ‘final.c’). These are useful when a single ‘md’ file must support multiple assembler formats. In that case, the various ‘tm.h’ files can define these macros differently.

ASM_FPRINTF_EXTENSIONS (file, argptr, format) [Macro]
If defined this macro should expand to a series of case statements which will be parsed inside the switch statement of the asm_fprintf function. This allows targets to define extra printf formats which may useful when generating their assembler statements. Note that uppercase letters are reserved for future generic extensions to asm_fprintf, and so are not available to target specific code. The output file is given by the parameter file. The varargs input pointer is argptr and the rest of the format string, starting the character after the one that is being switched upon, is pointed to by format.
Chapter 18: Target Description Macros and Functions

**ASM_OUTPUT_ADDR_DIFF_ELT (stream, body, value, rel)**

A C statement to output to the stdio stream `stream` an assembler pseudo-instruction to generate a difference between two labels. `value` and `rel` are the numbers of two internal labels. The definitions of these labels are output using `(*targetm.asm_out.internal_label)`, and they must be printed in the same way here. For example,

```c
fprintf (stream, "\t.word L%d-L%d\n", value, rel)
```

You must provide this macro on machines where the addresses in a dispatch table are relative to the table's own address. If defined, GCC will also use this macro on all machines when producing PIC. `body` is the body of the `ADDR_DIFF_VEC`; it is provided so that the mode and flags can be read.
**ASM_OUTPUT_ADDR_VEC_ELT** *(stream, value)*  
This macro should be provided on machines where the addresses in a dispatch table are absolute.

The definition should be a C statement to output to the stdio stream *stream* an assembler pseudo-instruction to generate a reference to a label. *value* is the number of an internal label whose definition is output using (*targetm.asm_out.internal_label*). For example,

```c
fprintf (stream, "\t.word L%d\n", value)
```

**ASM_OUTPUT_CASE_LABEL** *(stream, prefix, num, table)*  
Define this if the label before a jump-table needs to be output specially. The first three arguments are the same as for (*targetm.asm_out.internal_label*); the fourth argument is the jump-table which follows (a *jump_table_data* containing an *addr_vec* or *addr_diff_vec*).

This feature is used on system V to output a *swbeg* statement for the table.

If this macro is not defined, these labels are output with (*targetm.asm_out.internal_label*).

**ASM_OUTPUT_CASE_END** *(stream, num, table)*  
Define this if something special must be output at the end of a jump-table. The definition should be a C statement to be executed after the assembler code for the table is written. It should write the appropriate code to stdio stream *stream*. The argument *table* is the jump-table insn, and *num* is the label-number of the preceding label.

If this macro is not defined, nothing special is output at the end of the jump-table.

**void TARGET_ASM_POST_CFI_STARTPROC** *(FILE *, tree)*  
This target hook is used to emit assembly strings required by the target after the *.cfi_startproc* directive. The first argument is the file stream to write the strings to and the second argument is the function’s declaration. The expected use is to add more *.cfi_* directives.

The default is to not output any assembly strings.

**void TARGET_ASM_EMIT_UNWIND_LABEL** *(FILE *stream, tree decl, int for_eh, int empty)*  
This target hook emits a label at the beginning of each FDE. It should be defined on targets where FDEs need special labels, and it should write the appropriate label, for the FDE associated with the function declaration *decl*, to the stdio stream *stream*. The third argument, *for_eh*, is a boolean: true if this is for an exception table. The fourth argument, *empty*, is a boolean: true if this is a placeholder label for an omitted FDE.

The default is that FDEs are not given nonlocal labels.

**void TARGET_ASM_EMIT_EXCEPT_TABLE_LABEL** *(FILE *stream)*  
This target hook emits a label at the beginning of the exception table. It should be defined on targets where it is desirable for the table to be broken up according to function.

The default is that no label is emitted.
void TARGET_ASM_EMIT_EXCEPT_PERSONALITY (rtx personality)  [Target Hook]
    If the target implements TARGET_ASM_UNWIND_EMIT, this hook may be used to emit
    a directive to install a personality hook into the unwind info. This hook should not
    be used if dwarf2 unwind info is used.

void TARGET_ASM_UNWIND_EMIT (FILE *stream, rtx_insn *insn)  [Target Hook]
    This target hook emits assembly directives required to unwind the given instruction.
    This is only used when TARGET_EXCEPT_UNWIND_INFO returns UI_TARGET.

rtx TARGET_ASM_MAKE_EH_SYMBOL_INDIRECT (rtx origsymbol,  [Target Hook]
        bool pubvis)
    If necessary, modify personality and LSDA references to handle indirection. The
    original symbol is in origsymbol and if pubvis is true the symbol is visible outside
    the TU.

bool TARGET_ASM_UNWIND_EMIT_BEFORE_INSN  [Target Hook]
    True if the TARGET_ASM_UNWIND_EMIT hook should be called before the assembly for
    insn has been emitted, false if the hook should be called afterward.

bool TARGET_ASM_SHOULD_RESTORE_CFA_STATE (void)  [Target Hook]
    For DWARF-based unwind frames, two CFI instructions provide for save and restore
    of register state. GCC maintains the current frame address (CFA) separately from the
    register bank but the unwinder in libgcc preserves this state along with the registers
    (and this is expected by the code that writes the unwind frames). This hook allows
    the target to specify that the CFA data is not saved/restored along with the registers
    by the target unwinder so that suitable additional instructions should be emitted to
    restore it.

18.20.9 Assembler Commands for Exception Regions

This describes commands marking the start and the end of an exception region.

EH_FRAME_SECTION_NAME  [Macro]
    If defined, a C string constant for the name of the section containing exception han-
    dling frame unwind information. If not defined, GCC will provide a default definition
    if the target supports named sections. ‘crtstuff.c’ uses this macro to switch to the
    appropriate section.

    You should define this symbol if your target supports DWARF 2 frame unwind infor-
    mation and the default definition does not work.

EH_FRAME_THROUGH_COLLECT2  [Macro]
    If defined, DWARF 2 frame unwind information will identified by specially named
    labels. The collect2 process will locate these labels and generate code to register the
    frames.

    This might be necessary, for instance, if the system linker will not place the eh_frames
    in-between the sentinals from ‘crtstuff.c’, or if the system linker does garbage
    collection and sections cannot be marked as not to be collected.
EH_TABLES_CAN_BE_READ_ONLY

Define this macro to 1 if your target is such that no frame unwind information encoding used with non-PIC code will ever require a runtime relocation, but the linker may not support merging read-only and read-write sections into a single read-write section.

MASK_RETURN_ADDR

An rtx used to mask the return address found via RETURN_ADDR_RTX, so that it does not contain any extraneous set bits in it.

DWARF2_UNWIND_INFO

Define this macro to 0 if your target supports DWARF 2 frame unwind information, but it does not yet work with exception handling. Otherwise, if your target supports this information (if it defines INCOMING_RETURN_ADDR_RTX and OBJECT_FORMAT_ELF), GCC will provide a default definition of 1.

enum unwind_info_type TARGET_EXCEPT_UNWIND_INFO

This hook defines the mechanism that will be used for exception handling by the target. If the target has ABI specified unwind tables, the hook should return UI_TARGET. If the target is to use the setjmp/longjmp-based exception handling scheme, the hook should return UI_SJLJ. If the target supports DWARF 2 frame unwind information, the hook should return UI_DWARF2.

A target may, if exceptions are disabled, choose to return UI_NONE. This may end up simplifying other parts of target-specific code. The default implementation of this hook never returns UI_NONE.

Note that the value returned by this hook should be constant. It should not depend on anything except the command-line switches described by opts. In particular, the setting UI_SJLJ must be fixed at compiler start-up as C pre-processor macros and builtin functions related to exception handling are set up depending on this setting.

The default implementation of the hook first honors the ‘--enable-sjlj-exceptions’ configure option, then DWARF2_UNWIND_INFO, and finally defaults to UI_SJLJ. If DWARF2_UNWIND_INFO depends on command-line options, the target must define this hook so that opts is used correctly.

bool TARGET_UNWIND_TABLES_DEFAULT

This variable should be set to true if the target ABI requires unwinding tables even when exceptions are not used. It must not be modified by command-line option processing.

DONT_USE_BUILTIN_SETJMP

Define this macro to 1 if the setjmp/longjmp-based scheme should use the setjmp/longjmp functions from the C library instead of the __builtin_setjmp/__builtin_longjmp machinery.

JMP_BUF_SIZE

This macro has no effect unless DONT_USE_BUILTIN_SETJMP is also defined. Define this macro if the default size of jmp_buf buffer for the setjmp/longjmp-based exception
handling mechanism is not large enough, or if it is much too large. The default size is \texttt{FIRST\_PSEUDO\_REGISTER \ast \texttt{sizeof(void *)}}.

\textbf{DWARF\_CIE\_DATA\_ALIGNMENT} \hspace{1cm} \textbf{[Macro]}

This macro need only be defined if the target might save registers in the function prologue at an offset to the stack pointer that is not aligned to \texttt{UNITS\_PER\_WORD}. The definition should be the negative minimum alignment if \texttt{STACK\_GROWS\_DOWNWARD} is true, and the positive minimum alignment otherwise. See Section 18.21.5 \textbf{[DWARF]}, page 647. Only applicable if the target supports DWARF 2 frame unwind information.

\textbf{bool \ \texttt{TARGET\_TERMINATE\_DW2\_EH\_FRAME\_INFO}} \hspace{1cm} \textbf{[Target Hook]}

Contains the value \texttt{true} if the target should add a zero word onto the end of a Dwarf-2 frame info section when used for exception handling. Default value is \texttt{false} if \texttt{EH\_FRAME\_SECTION\_NAME} is defined, and \texttt{true} otherwise.

\textbf{rtx \ \texttt{TARGET\_DWARF\_REGISTER\_SPAN (rtx reg)}} \hspace{1cm} \textbf{[Target Hook]}

Given a register, this hook should return a parallel of registers to represent where to find the register pieces. Define this hook if the register and its mode are represented in Dwarf in non-contiguous locations, or if the register should be represented in more than one register in Dwarf. Otherwise, this hook should return \texttt{NULL\_RTX}. If not defined, the default is to return \texttt{NULL\_RTX}.

\textbf{machine\_mode \ \texttt{TARGET\_DWARF\_FRAME\_REG\_MODE (int regno)}} \hspace{1cm} \textbf{[Target Hook]}

Given a register, this hook should return the mode which the corresponding Dwarf frame register should have. This is normally used to return a smaller mode than the raw mode to prevent call clobbered parts of a register altering the frame register size.

\textbf{void \ \texttt{TARGET\_INIT\_DWARF\_REG\_SIZES\_EXTRA (tree address)}} \hspace{1cm} \textbf{[Target Hook]}

If some registers are represented in Dwarf-2 unwind information in multiple pieces, define this hook to fill in information about the sizes of those pieces in the table used by the unwinder at runtime. It will be called by \texttt{expand\_builtin\_init\_dwarf\_reg\_sizes} after filling in a single size corresponding to each hard register; \texttt{address} is the address of the table.

\textbf{bool \ \texttt{TARGET\_ASM\_TTYPE (rtx sym)}} \hspace{1cm} \textbf{[Target Hook]}

This hook is used to output a reference from a frame unwinding table to the \texttt{type\_info} object identified by \texttt{sym}. It should return \texttt{true} if the reference was output. Returning \texttt{false} will cause the reference to be output using the normal Dwarf2 routines.

\textbf{bool \ \texttt{TARGET\_ARM\_EABI\_UNWINDER}} \hspace{1cm} \textbf{[Target Hook]}

This flag should be set to \texttt{true} on targets that use an ARM EABI based unwinding library, and \texttt{false} on other targets. This effects the format of unwinding tables, and how the unwinder in entered after running a cleanup. The default is \texttt{false}.

\textbf{18.20.10 Assembler Commands for Alignment}

This describes commands for alignment.

\textbf{JUMP\_ALIGN (label)} \hspace{1cm} \textbf{[Macro]}

The alignment (log base 2) to put in front of \texttt{label}, which is a common destination of jumps and has no fallthru incoming edge.
This macro need not be defined if you don’t want any special alignment to be done at such a time. Most machine descriptions do not currently define the macro.

Unless it’s necessary to inspect the label parameter, it is better to set the variable align_jumps in the target’s TARGET_OPTION_OVERRIDE. Otherwise, you should try to honor the user’s selection in align_jumps in a JUMP_ALIGN implementation.

**LABEL_ALIGN_AFTER_BARRIER (label)**

The alignment (log base 2) to put in front of label, which follows a BARRIER.

This macro need not be defined if you don’t want any special alignment to be done at such a time. Most machine descriptions do not currently define the macro.

**LOOP_ALIGN (label)**

The alignment (log base 2) to put in front of label that heads a frequently executed basic block (usually the header of a loop).

This macro need not be defined if you don’t want any special alignment to be done at such a time. Most machine descriptions do not currently define the macro.

Unless it’s necessary to inspect the label parameter, it is better to set the variable align_loops in the target’s TARGET_OPTION_OVERRIDE. Otherwise, you should try to honor the user’s selection in align_loops in a LOOP_ALIGN implementation.

**LABEL_ALIGN (label)**

The alignment (log base 2) to put in front of label. If LABEL_ALIGN_AFTER_BARRIER / LOOP_ALIGN specify a different alignment, the maximum of the specified values is used.

Unless it’s necessary to inspect the label parameter, it is better to set the variable align_labels in the target’s TARGET_OPTION_OVERRIDE. Otherwise, you should try to honor the user’s selection in align_labels in a LABEL_ALIGN implementation.

**ASM_OUTPUT_SKIP (stream, nbytes)**

A C statement to output to the stdio stream stream an assembler instruction to advance the location counter by nbytes bytes. Those bytes should be zero when loaded. nbytes will be a C expression of type unsigned HOST_WIDE_INT.

**ASM_NO_SKIP_IN_TEXT**

Define this macro if ASM_OUTPUT_SKIP should not be used in the text section because it fails to put zeros in the bytes that are skipped. This is true on many Unix systems, where the pseudo–op to skip bytes produces no-op instructions rather than zeros when used in the text section.

**ASM_OUTPUT_ALIGN (stream, power)**

A C statement to output to the stdio stream stream an assembler command to advance the location counter to a multiple of 2 to the power bytes. power will be a C expression of type int.

**ASM_OUTPUT_ALIGN_WITH_NOP (stream, power)**

Like ASM_OUTPUT_ALIGN, except that the “nop” instruction is used for padding, if necessary.
18.21 Controlling Debugging Information Format

This describes how to specify debugging information.

18.21.1 Macros Affecting All Debugging Formats

These macros affect all debugging formats.

DBX_REGISTER_NUMBER (regno)  [Macro]
A C expression that returns the DBX register number for the compiler register number regno. In the default macro provided, the value of this expression will be regno itself. But sometimes there are some registers that the compiler knows about and DBX does not, or vice versa. In such cases, some register may need to have one number in the compiler and another for DBX.

If two registers have consecutive numbers inside GCC, and they can be used as a pair to hold a multiword value, then they must have consecutive numbers after renumbering with DBX_REGISTER_NUMBER. Otherwise, debuggers will be unable to access such a pair, because they expect register pairs to be consecutive in their own numbering scheme.

If you find yourself defining DBX_REGISTER_NUMBER in way that does not preserve register pairs, then what you must do instead is redefine the actual register numbering scheme.

DEBUGGER_AUTO_OFFSET (x)  [Macro]
A C expression that returns the integer offset value for an automatic variable having address x (an RTL expression). The default computation assumes that x is based on the frame-pointer and gives the offset from the frame-pointer. This is required for targets that produce debugging output for DBX and allow the frame-pointer to be eliminated when the ‘-g’ option is used.

DEBUGGER_ARG_OFFSET (offset, x)  [Macro]
A C expression that returns the integer offset value for an argument having address x (an RTL expression). The nominal offset is offset.

PREFERRED_DEBUGGING_TYPE  [Macro]
A C expression that returns the type of debugging output GCC should produce when the user specifies just ‘-g’. Define this if you have arranged for GCC to support more than one format of debugging output. Currently, the allowable values are DBX_DEBUG, DWARF2_DEBUG, XCOFF_DEBUG, VMS_DEBUG, and VMS_AND_DWARF2_DEBUG.

When the user specifies ‘-ggdb’, GCC normally also uses the value of this macro to select the debugging output format, but with two exceptions. If DWARF2_DEBUGGING_INFO is defined, GCC uses the value DWARF2_DEBUG. Otherwise, if DBX_DEBUGGING_INFO is defined, GCC uses DBX_DEBUG.
The value of this macro only affects the default debugging output; the user can always get a specific type of output by using ‘-gstabs’, ‘-gdwarf-2’, ‘-gxcoff’, or ‘-gvms’.

### 18.21.2 Specific Options for DBX Output

These are specific options for DBX output.

**DBX_DEBUGGING_INFO** [Macro]
Define this macro if GCC should produce debugging output for DBX in response to the ‘-g’ option.

**XCOFF_DEBUGGING_INFO** [Macro]
Define this macro if GCC should produce XCOFF format debugging output in response to the ‘-g’ option. This is a variant of DBX format.

**DEFAULT_GDB_EXTENSIONS** [Macro]
Define this macro to control whether GCC should by default generate GDB’s extended version of DBX debugging information (assuming DBX-format debugging information is enabled at all). If you don’t define the macro, the default is 1: always generate the extended information if there is any occasion to.

**DEBUG_SYMS_TEXT** [Macro]
Define this macro if all .stabs commands should be output while in the text section.

**ASM_STABS_OP** [Macro]
A C string constant, including spacing, naming the assembler pseudo op to use instead of "\t.stabs\t" to define an ordinary debugging symbol. If you don’t define this macro, "\t.stabs\t" is used. This macro applies only to DBX debugging information format.

**ASM_STABD_OP** [Macro]
A C string constant, including spacing, naming the assembler pseudo op to use instead of "\t.stabd\t" to define a debugging symbol whose value is the current location. If you don’t define this macro, "\t.stabd\t" is used. This macro applies only to DBX debugging information format.

**ASM_STABN_OP** [Macro]
A C string constant, including spacing, naming the assembler pseudo op to use instead of "\t.stabn\t" to define a debugging symbol with no name. If you don’t define this macro, "\t.stabn\t" is used. This macro applies only to DBX debugging information format.

**DBX_NO_XREFS** [Macro]
Define this macro if DBX on your system does not support the construct ‘xstagname’. On some systems, this construct is used to describe a forward reference to a structure named tagname. On other systems, this construct is not supported at all.

**DBX_CONTIN_LENGTH** [Macro]
A symbol name in DBX-format debugging information is normally continued (split into two separate .stabs directives) when it exceeds a certain length (by default, 80 characters). On some operating systems, DBX requires this splitting; on others,
splitting must not be done. You can inhibit splitting by defining this macro with the value zero. You can override the default splitting-length by defining this macro as an expression for the length you desire.

**DBX_CONTIN_CHAR**

[Macro]

Normally continuation is indicated by adding a ‘\’ character to the end of a .stabs string when a continuation follows. To use a different character instead, define this macro as a character constant for the character you want to use. Do not define this macro if backslash is correct for your system.

**DBX_STATIC_STAB_DATA_SECTION**

[Macro]

Define this macro if it is necessary to go to the data section before outputting the ‘.stabs’ pseudo-op for a non-global static variable.

**DBX_TYPE DECL_STABS_CODE**

[Macro]

The value to use in the “code” field of the .stabs directive for a typedef. The default is N_LSYM.

**DBX_STATIC CONST VAR_CODE**

[Macro]

The value to use in the “code” field of the .stabs directive for a static variable located in the text section. DBX format does not provide any “right” way to do this. The default is N_FUN.

**DBX_REGPARM STABS CODE**

[Macro]

The value to use in the “code” field of the .stabs directive for a parameter passed in registers. DBX format does not provide any “right” way to do this. The default is N_RSYM.

**DBX_REGPARM STABS LETTER**

[Macro]

The letter to use in DBX symbol data to identify a symbol as a parameter passed in registers. DBX format does not customarily provide any way to do this. The default is ’P’.

**DBX FUNCTION FIRST**

[Macro]

Define this macro if the DBX information for a function and its arguments should precede the assembler code for the function. Normally, in DBX format, the debugging information entirely follows the assembler code.

**DBX BLOCKS FUNCTION RELATIVE**

[Macro]

Define this macro, with value 1, if the value of a symbol describing the scope of a block (N_LBRAC or N_RBRAC) should be relative to the start of the enclosing function. Normally, GCC uses an absolute address.

**DBX LINES FUNCTION RELATIVE**

[Macro]

Define this macro, with value 1, if the value of a symbol indicating the current line number (N_SLINE) should be relative to the start of the enclosing function. Normally, GCC uses an absolute address.

**DBX USE BINCL**

[Macro]

Define this macro if GCC should generate N_BINCL and N_EINCL stabs for included header files, as on Sun systems. This macro also directs GCC to output a type number
as a pair of a file number and a type number within the file. Normally, GCC does not generate \texttt{N\_BINCL} or \texttt{N\_EINCL} stabs, and it outputs a single number for a type number.

18.21.3 Open-Ended Hooks for DBX Format

These are hooks for DBX format.

\textbf{DBX\_OUTPUT\_SOURCE\_LINE} \texttt{(stream, line, counter)} \footnote{[Macro]}

A C statement to output DBX debugging information before code for line number \texttt{line} of the current source file to the stdio stream \texttt{stream}. \texttt{counter} is the number of time the macro was invoked, including the current invocation; it is intended to generate unique labels in the assembly output.

This macro should not be defined if the default output is correct, or if it can be made correct by defining \texttt{DBX\_LINES\_FUNCTION\_RELATIVE}.

\textbf{NO\_DBX\_FUNCTION\_END} \footnote{[Macro]}

Some stabs encapsulation formats (in particular ECOFF), cannot handle the \texttt{.stabs "",N\_FUN,,0,0,Lscope-function-1} gdb dbx extension construct. On those machines, define this macro to turn this feature off without disturbing the rest of the gdb extensions.

\textbf{NO\_DBX\_BNSYM\_ENSYM} \footnote{[Macro]}

Some assemblers cannot handle the \texttt{.stabd BNSYM/ENSYM,0,0} gdb dbx extension construct. On those machines, define this macro to turn this feature off without disturbing the rest of the gdb extensions.

18.21.4 File Names in DBX Format

This describes file names in DBX format.

\textbf{DBX\_OUTPUT\_MAIN\_SOURCE\_FILENAME} \texttt{(stream, name)} \footnote{[Macro]}

A C statement to output DBX debugging information to the stdio stream \texttt{stream}, which indicates that file \texttt{name} is the main source file—the file specified as the input file for compilation. This macro is called only once, at the beginning of compilation.

This macro need not be defined if the standard form of output for DBX debugging information is appropriate.

It may be necessary to refer to a label equal to the beginning of the text section. You can use \texttt{`assemble\_name (stream, ltext\_label\_name)`} to do so. If you do this, you must also set the variable \texttt{used\_ltext\_label\_name} to \texttt{true}.

\textbf{NO\_DBX\_MAIN\_SOURCE\_DIRECTORY} \footnote{[Macro]}

Define this macro, with value 1, if GCC should not emit an indication of the current directory for compilation and current source language at the beginning of the file.

\textbf{NO\_DBX\_GCC\_MARKER} \footnote{[Macro]}

Define this macro, with value 1, if GCC should not emit an indication that this object file was compiled by GCC. The default is to emit an \texttt{N\_OPT} stab at the beginning of every source file, with \texttt{`gcc2\_compiled.'} for the string and value 0.
DBX_OUTPUT_MAIN_SOURCE_FILE_END (stream, name)  
A C statement to output DBX debugging information at the end of compilation of the main source file name. Output should be written to the stdio stream stream. If you don’t define this macro, nothing special is output at the end of compilation, which is correct for most machines.

DBX_OUTPUT_NULL_N_SO_AT_MAIN_SOURCE_FILE_END  
Define this macro instead of defining DBX_OUTPUT_MAIN_SOURCE_FILE_END, if what needs to be output at the end of compilation is an N_SO stab with an empty string, whose value is the highest absolute text address in the file.

18.21.5 Macros for DWARF Output

Here are macros for DWARF output.

DWARF2_DEBUGGING_INFO  
Define this macro if GCC should produce dwarf version 2 format debugging output in response to the ‘-g’ option.

int TARGET_DWARF_CALLING_CONVENTION (const tree function)  
Define this to enable the dwarf attribute DW_AT_calling_convention to be emitted for each function. Instead of an integer return the enum value for the DW_CC_ tag.

To support optional call frame debugging information, you must also define INCOMING_RETURN_ADDR_RTX and either set RTX_FRAME_RELATED_P on the prologue insns if you use RTL for the prologue, or call dwarf2out_def_cfa and dwarf2out_reg_save as appropriate from TARGET_ASM_FUNCTION_PROLOGUE if you don’t.

DWARF2_FRAME_INFO  
Define this macro to a nonzero value if GCC should always output Dwarf 2 frame information. If TARGET_EXCEPT_UNWIND_INFO (see Section 18.20.9 [Exception Region Output], page 639) returns UI_DWARF2, and exceptions are enabled, GCC will output this information not matter how you define DWARF2_FRAME_INFO.

enum unwind_info_type TARGET_DEBUG_UNWIND_INFO (void)  
This hook defines the mechanism that will be used for describing frame unwind information to the debugger. Normally the hook will return UI_DWARF2 if DWARF 2 debug information is enabled, and return UI_NONE otherwise. A target may return UI_DWARF2 even when DWARF 2 debug information is disabled in order to always output DWARF 2 frame information. A target may return UI_TARGET if it has ABI specified unwind tables. This will suppress generation of the normal debug frame unwind information.

DWARF2_ASM_LINE_DEBUG_INFO  
Define this macro to be a nonzero value if the assembler can generate Dwarf 2 line debug info sections. This will result in much more compact line number tables, and hence is desirable if it works.
**DWARF2_ASM_VIEW_DEBUG_INFO**  
**[Macro]**  
Define this macro to be a nonzero value if the assembler supports view assignment and verification in `.loc`. If it does not, but the user enables location views, the compiler may have to fallback to internal line number tables.

**int TARGET_RESET_LOCATION_VIEW (rtx_insn *)**  
**[Target Hook]**  
This hook, if defined, enables `-ginternal-reset-location-views`, and uses its result to override cases in which the estimated min insn length might be nonzero even when a PC advance (i.e., a view reset) cannot be taken for granted.

If the hook is defined, it must return a positive value to indicate the insn definitely advances the PC, and so the view number can be safely assumed to be reset; a negative value to mean the insn definitely does not advance the PC, and so the view number must not be reset; or zero to decide based on the estimated insn length.

If insn length is to be regarded as reliable, set the hook to `hook_int_rtx_insn_0`.

**bool TARGET_WANT_DEBUG_PUB_SECTIONS**  
**[Target Hook]**  
True if the `.debug_pubtypes` and `.debug_pubnames` sections should be emitted. These sections are not used on most platforms, and in particular GDB does not use them.

**bool TARGET_DELAY_SCHED2**  
**[Target Hook]**  
True if sched2 is not to be run at its normal place. This usually means it will be run as part of machine-specific reorg.

**bool TARGET_DELAY_VARTRACK**  
**[Target Hook]**  
True if vartrack is not to be run at its normal place. This usually means it will be run as part of machine-specific reorg.

**bool TARGET_NO_REGISTER_ALLOCATION**  
**[Target Hook]**  
True if register allocation and the passes following it should not be run. Usually true only for virtual assembler targets.

**ASM_OUTPUT_DWARF_DELTA (stream, size, label1, label2)**  
**[Macro]**  
A C statement to issue assembly directives that create a difference `lab1` minus `lab2`, using an integer of the given size.

**ASM_OUTPUT_DWARF_VMS_DELTA (stream, size, label1, label2)**  
**[Macro]**  
A C statement to issue assembly directives that create a difference between the two given labels in system defined units, e.g. instruction slots on IA64 VMS, using an integer of the given size.

**ASM_OUTPUT_DWARF_OFFSET (stream, size, label, offset, section)**  
**[Macro]**  
A C statement to issue assembly directives that create a section-relative reference to the given `label` plus `offset`, using an integer of the given size. The label is known to be defined in the given `section`.

**ASM_OUTPUT_DWARF_PCREL (stream, size, label)**  
**[Macro]**  
A C statement to issue assembly directives that create a self-relative reference to the given `label`, using an integer of the given size.
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**ASM_OUTPUT_DWARF_DATAREL** *(stream, size, label)*  
A C statement to issue assembly directives that create a reference to the given *label* relative to the dbase, using an integer of the given *size*.

**ASM_OUTPUT_DWARF_TABLE_REF** *(label)*  
A C statement to issue assembly directives that create a reference to the DWARF table identifier *label* from the current section. This is used on some systems to avoid garbage collecting a DWARF table which is referenced by a function.

**void TARGET_ASM_OUTPUT_DWARF_DTPREL** *(FILE *file, int size, rtx x)*  
If defined, this target hook is a function which outputs a DTP-relative reference to the given TLS symbol of the specified size.

### 18.21.6 Macros for VMS Debug Format

Here are macros for VMS debug format.

**VMS_DEBUGGING_INFO**  
Define this macro if GCC should produce debugging output for VMS in response to the *'-g'* option. The default behavior for VMS is to generate minimal debug info for a traceback in the absence of *'-g'* unless explicitly overridden with *'-g0'*.

This behavior is controlled by **TARGET_OPTION_OPTIMIZATION** and **TARGET_OPTION_OVERRIDE**.

### 18.21.7 Macros for CTF Debug Format

Here are macros for CTF debug format.

**CTF_DEBUGGING_INFO**  
Define this macro if GCC should produce debugging output in CTF debug format in response to the *'-gctf'* option.

### 18.21.8 Macros for BTF Debug Format

Here are macros for BTF debug format.

**BTF_DEBUGGING_INFO**  
Define this macro if GCC should produce debugging output in BTF debug format in response to the *'-gbtf'* option.

### 18.22 Cross Compilation and Floating Point

While all modern machines use twos-complement representation for integers, there are a variety of representations for floating point numbers. This means that in a cross-compiler the representation of floating point numbers in the compiled program may be different from that used in the machine doing the compilation.

Because different representation systems may offer different amounts of range and precision, all floating point constants must be represented in the target machine’s format. Therefore, the cross compiler cannot safely use the host machine’s floating point arithmetic; it must emulate the target’s arithmetic. To ensure consistency, GCC always uses
emulation to work with floating point values, even when the host and target floating point formats are identical.

The following macros are provided by `real.h` for the compiler to use. All parts of the compiler which generate or optimize floating-point calculations must use these macros. They may evaluate their operands more than once, so operands must not have side effects.

**REAL_VALUE_TYPE**

The C data type to be used to hold a floating point value in the target machine’s format. Typically this is a `struct` containing an array of `HOST_WIDE_INT`, but all code should treat it as an opaque quantity.

**HOST_WIDE_INT REAL_VALUE_FIX (REAL_VALUE_TYPE x)**

Truncates x to a signed integer, rounding toward zero.

**unsigned HOST_WIDE_INT REAL_VALUE_UNSIGNED_FIX (REAL_VALUE_TYPE x)**

Truncates x to an unsigned integer, rounding toward zero. If x is negative, returns zero.

**REAL_VALUE_TYPE REAL_VALUE_ATOF (const char *string, machine_mode mode)**

Converts string into a floating point number in the target machine’s representation for mode mode. This routine can handle both decimal and hexadecimal floating point constants, using the syntax defined by the C language for both.

**int REAL_VALUE_NEGATIVE (REAL_VALUE_TYPE x)**

Returns 1 if x is negative (including negative zero), 0 otherwise.

**int REAL_VALUE_ISINF (REAL_VALUE_TYPE x)**

Determines whether x represents infinity (positive or negative).

**int REAL_VALUE_ISNAN (REAL_VALUE_TYPE x)**

Determines whether x represents a “NaN” (not-a-number).

**REAL_VALUE_TYPE REAL_VALUE_NEGATE (REAL_VALUE_TYPE x)**

Returns the negative of the floating point value x.

**REAL_VALUE_TYPE REAL_VALUE_ABS (REAL_VALUE_TYPE x)**

Returns the absolute value of x.

### 18.23 Mode Switching Instructions

The following macros control mode switching optimizations:

**OPTIMIZE_MODE_SWITCHING (entity)**

Define this macro if the port needs extra instructions inserted for mode switching in an optimizing compilation.

For an example, the SH4 can perform both single and double precision floating point operations, but to perform a single precision operation, the FPSCR PR bit has to be cleared, while for a double precision operation, this bit has to be set. Changing the
PR bit requires a general purpose register as a scratch register, hence these FPSCR sets have to be inserted before reload, i.e. you cannot put this into instruction emitting or Target_Machine_Dependent_Reorg.

You can have multiple entities that are mode-switched, and select at run time which entities actually need it. **Optimize_Mode_Switching** should return nonzero for any entity that needs mode-switching. If you define this macro, you also have to define **Num_Modes_For_Mode_Switching**, **Target_Mode_Needed**, **Target_Mode_Priority** and **Target_Mode_Emit**. **Target_Mode_After**, **Target_Mode_Entry**, and **Target_Mode_Exit** are optional.

**Num_Modes_For_Mode_Switching**

If you define **Optimize_Mode_Switching**, you have to define this as initializer for an array of integers. Each initializer element N refers to an entity that needs mode switching, and specifies the number of different modes that might need to be set for this entity. The position of the initializer in the initializer—starting counting at zero—determines the integer that is used to refer to the mode-switched entity in question. In macros that take mode arguments / yield a mode result, modes are represented as numbers 0 . . . N − 1. N is used to specify that no mode switch is needed / supplied.

```c
void Target_Mode_Emit (int entity, int mode, int prev_mode, HARD_REG_SET regs_live)
```

Generate one or more insns to set entity to mode. hard_reg_live is the set of hard registers live at the point where the insn(s) are to be inserted. prev_mode indicates the mode to switch from. Sets of a lower numbered entity will be emitted before sets of a higher numbered entity to a mode of the same or lower priority.

```c
int Target_Mode_Needed (int entity, rtx_insn *insn)
```

entity is an integer specifying a mode-switched entity. If **Optimize_Mode_Switching** is defined, you must define this macro to return an integer value not larger than the corresponding element in **Num_Modes_For_Mode_Switching**, to denote the mode that entity must be switched into prior to the execution of insn.

```c
int Target_Mode_After (int entity, int mode, rtx_insn *insn)
```

entity is an integer specifying a mode-switched entity. If this macro is defined, it is evaluated for every insn during mode switching. It determines the mode that an insn results in (if different from the incoming mode).

```c
int Target_Mode_Entry (int entity)
```

If this macro is defined, it is evaluated for every entity that needs mode switching. It should evaluate to an integer, which is a mode that entity is assumed to be switched to at function entry. If **Target_Mode_Entry** is defined then **Target_Mode_Exit** must be defined.

```c
int Target_Mode_Exit (int entity)
```

If this macro is defined, it is evaluated for every entity that needs mode switching. It should evaluate to an integer, which is a mode that entity is assumed to be switched to at function exit. If **Target_Mode_Exit** is defined then **Target_Mode_Entry** must be defined.
int TARGET_MODE_PRIORITY (int entity, int n)  [Target Hook]
This macro specifies the order in which modes for entity are processed. 0 is the high-
est priority, NUM_MODES_FOR_MODE_SWITCHING[entity] - 1 the lowest. The value
of the macro should be an integer designating a mode for entity. For any fixed
entity, mode_priority (entity, n) shall be a bijection in 0 . . . num_modes_for_mode_
switching[entity] - 1.

18.24 Defining target-specific uses of __attribute__
Target-specific attributes may be defined for functions, data and types. These are described
using the following target hooks; they also need to be documented in `extend.texi'.

const struct attribute_spec * TARGET_ATTRIBUTE_TABLE  [Target Hook]
If defined, this target hook points to an array of `struct attribute_spec' (defined in
`tree-core.h') specifying the machine specific attributes for this target and some of
the restrictions on the entities to which these attributes are applied and the arguments
they take.

bool TARGET_ATTRIBUTE_TAKES_IDENTIFIER_P (const tree name)  [Target Hook]
If defined, this target hook is a function which returns true if the machine-specific
attribute named name expects an identifier given as its first argument to be passed on
as a plain identifier, not subjected to name lookup. If this is not defined, the default
is false for all machine-specific attributes.

int TARGET_COMP_TYPE_ATTRIBUTES (const tree type1, const tree
    type2)  [Target Hook]
If defined, this target hook is a function which returns zero if the attributes on type1
and type2 are incompatible, one if they are compatible, and two if they are nearly
compatible (which causes a warning to be generated). If this is not defined, machine-
specific attributes are supposed always to be compatible.

void TARGET_SET_DEFAULT_TYPE_ATTRIBUTES (tree type)  [Target Hook]
If defined, this target hook is a function which assigns default attributes to the newly
defined type.

tree TARGET_MERGE_TYPE_ATTRIBUTES (tree type1, tree type2)  [Target Hook]
Define this target hook if the merging of type attributes needs special handling. If
defined, the result is a list of the combined TYPE_ATTRIBUTES of type1 and type2. It
is assumed that comptypes has already been called and returned 1. This function
may call merge_attributes to handle machine-independent merging.

tree TARGET_MERGE_DECL_ATTRIBUTES (tree olddecl, tree
    newdecl)  [Target Hook]
Define this target hook if the merging of decl attributes needs special handling. If
defined, the result is a list of the combined DECL_ATTRIBUTES of olddecl and newdecl.
newdecl is a duplicate declaration of olddecl. Examples of when this is needed are
when one attribute overrides another, or when an attribute is nullified by a subsequent
definition. This function may call merge_attributes to handle machine-independent
merging.
If the only target-specific handling you require is ‘dllimport’ for Microsoft Windows targets, you should define the macro TARGET_DLLIMPORT_DECL_ATTRIBUTES to 1. The compiler will then define a function called merge_dllimport_decl_attributes which can then be defined as the expansion of TARGET_MERGE_DECL_ATTRIBUTES. You can also add handle_dll_attribute in the attribute table for your port to perform initial processing of the ‘dllimport’ and ‘dllexport’ attributes. This is done in ‘i386/cygwin.h’ and ‘i386/i386.c’, for example.

```c
bool TARGET_VALID_DLLIMPORT_ATTRIBUTE_P (const tree decl)
  decl is a variable or function with __attribute__((dllimport)) specified. Use this hook if the target needs to add extra validation checks to handle_dll_attribute.

TARGET_DECLSPEC
  Define this macro to a nonzero value if you want to treat __declspec(X) as equivalent to __attribute((X)). By default, this behavior is enabled only for targets that define TARGET_DLLIMPORT_DECL_ATTRIBUTES. The current implementation of __declspec is via a built-in macro, but you should not rely on this implementation detail.

void TARGET_INSERT_ATTRIBUTES (tree node, tree *attr_ptr)
  Define this target hook if you want to be able to add attributes to a decl when it is being created. This is normally useful for back ends which wish to implement a pragma by using the attributes which correspond to the pragma’s effect. The node argument is the decl which is being created. The attr_ptr argument is a pointer to the attribute list for this decl. The list itself should not be modified, since it may be shared with other decls, but attributes may be chained on the head of the list and *attr_ptr modified to point to the new attributes, or a copy of the list may be made if further changes are needed.

tree TARGET_HANDLE_GENERIC_ATTRIBUTE (tree *node, tree name, tree args, int flags, bool *no_add_attrs)
  Define this target hook if you want to be able to perform additional target-specific processing of an attribute which is handled generically by a front end. The arguments are the same as those which are passed to attribute handlers. So far this only affects the noinit and section attribute.

bool TARGET_FUNCTION_ATTRIBUTE_INLINABLE_P (const_tree fndecl)
  This target hook returns true if it is OK to inline fndecl into the current function, despite its having target-specific attributes, false otherwise. By default, if a function has a target specific attribute attached to it, it will not be inlined.

bool TARGET_OPTION_VALID_ATTRIBUTE_P (tree fndecl, tree name, tree args, int flags)
  This hook is called to parse attribute(target("...")), which allows setting target-specific options on individual functions. These function-specific options may differ from the options specified on the command line. The hook should return true if the options are valid.
  The hook should set the DECL_FUNCTION_SPECIFIC_TARGET field in the function declaration to hold a pointer to a target-specific struct cl_target_option structure.
void TARGET_OPTION_SAVE (struct cl_target_option *ptr, struct gcc_options *opts, struct gcc_options *opts_set)  
This hook is called to save any additional target-specific information in the 
struct cl_target_option structure for function-specific options from the struct 
gcc_options structure. See Section 8.1 [Option file format], page 123.

void TARGET_OPTION_RESTORE (struct gcc_options *opts, struct gcc_options *opts_set, struct cl_target_option *ptr)  
This hook is called to restore any additional target-specific information in the struct 
cl_target_option structure for function-specific options to the struct gcc_options 
structure.

void TARGET_OPTION_POST_STREAM_IN (struct cl_target_option *ptr)  
This hook is called to update target-specific information in the struct cl_target_option 
structure after it is streamed in from LTO bytecode.

void TARGET_OPTION_PRINT (FILE *file, int indent, struct cl_target_option *ptr)  
This hook is called to print any additional target-specific information in the struct 
cl_target_option structure for function-specific options.

bool TARGET_OPTION_PRAGMA_PARSE (tree args, tree pop_target)  
This target hook parses the options for #pragma GCC target, which sets the 
target-specific options for functions that occur later in the input stream. The 
options accepted should be the same as those handled by the TARGET_OPTION_ 
VALID_ATTRIBUTE_P hook.

void TARGET_OPTION_OVERRIDE (void)  
Sometimes certain combinations of command options do not make sense on a particular 
target machine. You can override the hook TARGET_OPTION_OVERRIDE to take 
account of this. This hooks is called once just after all the command options have 
been parsed.

Don’t use this hook to turn on various extra optimizations for ‘-O’. That is what 
TARGET_OPTION_OPTIMIZATION is for.

If you need to do something whenever the optimization level is changed via the optimize 
attribute or pragma, see TARGET_OVERRIDE_OPTIONS_AFTER_CHANGE

bool TARGET_OPTION_FUNCTION_VERSIONS (tree decl1, tree decl2)  
This target hook returns true if DECL1 and DECL2 are versions of the same function. DECL1 and DECL2 are function versions if and only if they have the same 
function signature and different target specific attributes, that is, they are compiled 
for different target machines.

bool TARGET_CAN_INLINE_P (tree caller, tree callee)  
This target hook returns false if the caller function cannot inline callee, based on 
target specific information. By default, inlining is not allowed if the callee function 
has function specific target options and the caller does not use the same options.
void TARGET_RELAYOUT_FUNCTION (tree fndecl)  [Target Hook]
This target hook fixes function fndecl after attributes are processed. Default does nothing. On ARM, the default function’s alignment is updated with the attribute target.

18.25 Emulating TLS
For targets whose psABI does not provide Thread Local Storage via specific relocations and instruction sequences, an emulation layer is used. A set of target hooks allows this emulation layer to be configured for the requirements of a particular target. For instance the psABI may in fact specify TLS support in terms of an emulation layer.

The emulation layer works by creating a control object for every TLS object. To access the TLS object, a lookup function is provided which, when given the address of the control object, will return the address of the current thread’s instance of the TLS object.

const char * TARGET_EMUTLS_GET_ADDRESS  [Target Hook]
Contains the name of the helper function that uses a TLS control object to locate a TLS instance. The default causes libgcc’s emulated TLS helper function to be used.

const char * TARGET_EMUTLS_REGISTER_COMMON  [Target Hook]
Contains the name of the helper function that should be used at program startup to register TLS objects that are implicitly initialized to zero. If this is NULL, all TLS objects will have explicit initializers. The default causes libgcc’s emulated TLS registration function to be used.

const char * TARGET_EMUTLS_VAR_SECTION  [Target Hook]
Contains the name of the section in which TLS control variables should be placed. The default of NULL allows these to be placed in any section.

const char * TARGET_EMUTLS_TMPL_SECTION  [Target Hook]
Contains the name of the section in which TLS initializers should be placed. The default of NULL allows these to be placed in any section.

const char * TARGET_EMUTLS_VAR_PREFIX  [Target Hook]
Contains the prefix to be prepended to TLS control variable names. The default of NULL uses a target-specific prefix.

const char * TARGET_EMUTLS_TMPL_PREFIX  [Target Hook]
Contains the prefix to be prepended to TLS initializer objects. The default of NULL uses a target-specific prefix.

tree TARGET_EMUTLS_VAR_FIELDS (tree type, tree *name)  [Target Hook]
Specifies a function that generates the FIELDDECLs for a TLS control object type. type is the RECORD_TYPE the fields are for and name should be filled with the structure tag, if the default of __emutls_object is unsuitable. The default creates a type suitable for libgcc’s emulated TLS function.
tree TARGET_EMUTLS_VAR_INIT (tree var, tree decl, tree tml_addr)  
[Target Hook]
Specifies a function that generates the CONSTRUCTOR to initialize a TLS control object. var is the TLS control object, decl is the TLS object and tml_addr is the address of the initializer. The default initializes libgcc’s emulated TLS control object.

bool TARGET_EMUTLS_VAR_ALIGN_FIXED  
[Target Hook]
Specifies whether the alignment of TLS control variable objects is fixed and should not be increased as some backends may do to optimize single objects. The default is false.

bool TARGET_EMUTLS_DEBUG_FORM_TLS_ADDRESS  
[Target Hook]
Specifies whether a DWARF DW_OP_form_tls_address location descriptor may be used to describe emulated TLS control objects.

18.26 Defining coprocessor specifics for MIPS targets.
The MIPS specification allows MIPS implementations to have as many as 4 coprocessors, each with as many as 32 private registers. GCC supports accessing these registers and transferring values between the registers and memory using asm-ized variables. For example:

```c
register unsigned int cp0count asm("c0r1");
unsigned int d;

d = cp0count + 3;
```

(“c0r1” is the default name of register 1 in coprocessor 0; alternate names may be added as described below, or the default names may be overridden entirely in SUBTARGET_CONDITIONAL_REGISTER_USAGE.)

Coprocessor registers are assumed to be epilogue-used; sets to them will be preserved even if it does not appear that the register is used again later in the function.

Another note: according to the MIPS spec, coprocessor 1 (if present) is the FPU. One accesses COP1 registers through standard mips floating-point support; they are not included in this mechanism.

18.27 Parameters for Precompiled Header Validity Checking

void * TARGET_GET_PCH_VALIDITY (size_t *sz)  
[Target Hook]
This hook returns a pointer to the data needed by TARGET_PCH_VALID_P and sets ‘*sz’ to the size of the data in bytes.

const char * TARGET_PCH_VALID_P (const void *data, size_t sz)  
[Target Hook]
This hook checks whether the options used to create a PCH file are compatible with the current settings. It returns NULL if so and a suitable error message if not. Error messages will be presented to the user and must be localized using ‘_ (msg)’.

data is the data that was returned by TARGET_GET_PCH_VALIDITY when the PCH file was created and sz is the size of that data in bytes. It’s safe to assume that the data was created by the same version of the compiler, so no format checking is needed.

The default definition of default_pch_valid_p should be suitable for most targets.
const char * TARGET_CHECK_PCH_TARGET_FLAGS (int pch_flags) [Target Hook]
If this hook is nonnull, the default implementation of TARGET_PCH_VALID_P will use it to check for compatible values of target_flags. pch_flags specifies the value that target_flags had when the PCH file was created. The return value is the same as for TARGET_PCH_VALID_P.

void TARGET_PREPARE_PCH_SAVE (void) [Target Hook]
Called before writing out a PCH file. If the target has some garbage-collected data that needs to be in a particular state on PCH loads, it can use this hook to enforce that state. Very few targets need to do anything here.

18.28 C++ ABI parameters

tree TARGET_CXX_GUARD_TYPE (void) [Target Hook]
Define this hook to override the integer type used for guard variables. These are used to implement one-time construction of static objects. The default is long long integer type node.

bool TARGET_CXX_GUARD_MASK_BIT (void) [Target Hook]
This hook determines how guard variables are used. It should return false (the default) if the first byte should be used. A return value of true indicates that only the least significant bit should be used.

tree TARGET_CXX_GET_COOKIE_SIZE (tree type) [Target Hook]
This hook returns the size of the cookie to use when allocating an array whose elements have the indicated type. Assumes that it is already known that a cookie is needed. The default is max(sizeof (size_t), alignof(type)), as defined in section 2.7 of the IA64/Generic C++ ABI.

bool TARGET_CXX_COOKIE_HAS_SIZE (void) [Target Hook]
This hook should return true if the element size should be stored in array cookies. The default is to return false.

int TARGET_CXX_IMPORT.Export_CLASS (tree type, int import_export) [Target Hook]
If defined by a backend this hook allows the decision made to export class type to be overruled. Upon entry import_export will contain 1 if the class is going to be exported, −1 if it is going to be imported and 0 otherwise. This function should return the modified value and perform any other actions necessary to support the backend’s targeted operating system.

bool TARGET_CXX_CDTOR_RETURNS_THIS (void) [Target Hook]
This hook should return true if constructors and destructors return the address of the object created/destroyed. The default is to return false.

bool TARGET_CXX_KEY_METHOD_MAY_BE_INLINE (void) [Target Hook]
This hook returns true if the key method for a class (i.e., the method which, if defined in the current translation unit, causes the virtual table to be emitted) may be an inline
function. Under the standard Itanium C++ ABI the key method may be an inline function so long as the function is not declared inline in the class definition. Under some variants of the ABI, an inline function can never be the key method. The default is to return true.

```c
void TARGET_CXX_DETERMINE_CLASS_DATA_VISIBILITY (tree decl) [Target Hook]
dcl is a virtual table, virtual table table, typeinfo object, or other similar implicit class data object that will be emitted with external linkage in this translation unit. No ELF visibility has been explicitly specified. If the target needs to specify a visibility other than that of the containing class, use this hook to set DECL_VISIBILITY and DECL_VISIBILITY_SPECIFIED.
```

```c
bool TARGET_CXX_CLASS_DATA_ALWAYS_COMDAT (void) [Target Hook]
This hook returns true (the default) if virtual tables and other similar implicit class data objects are always COMDAT if they have external linkage. If this hook returns false, then class data for classes whose virtual table will be emitted in only one translation unit will not be COMDAT.
```

```c
bool TARGET_CXX_LIBRARY_RTTI_COMDAT (void) [Target Hook]
This hook returns true (the default) if the RTTI information for the basic types which is defined in the C++ runtime should always be COMDAT, false if it should not be COMDAT.
```

```c
bool TARGET_CXX_USE_AEABI_ATEXIT (void) [Target Hook]
This hook returns true if __aeabi_atexit (as defined by the ARM EABI) should be used to register static destructors when `-fuse-cxa-atexit' is in effect. The default is to return false to use __cxa_atexit.
```

```c
bool TARGET_CXX_USE_ATEXIT_FOR_CXA_ATEXIT (void) [Target Hook]
This hook returns true if the target atexit function can be used in the same manner as __cxa_atexit to register C++ static destructors. This requires that atexit-registered functions in shared libraries are run in the correct order when the libraries are unloaded. The default is to return false.
```

```c
void TARGET_CXX_ADJUST_CLASS_AT_DEFINITION (tree type) [Target Hook]
type is a C++ class (i.e., RECORD_TYPE or UNION_TYPE) that has just been defined. Use this hook to make adjustments to the class (eg, tweak visibility or perform any other required target modifications).
```

```c
tree TARGET_CXX_DECL_MANGLING_CONTEXT (const_tree decl) [Target Hook]
Return target-specific mangling context of decl or NULL_TREE.
```

### 18.29 D ABI parameters

```c
void TARGET_D_CPU_VERSIONS (void) [D Target Hook]
Declare all environmental version identifiers relating to the target CPU using the function builtin_version, which takes a string representing the name of the version. Version identifiers predefined by this hook apply to all modules that are being compiled and imported.
```
void TARGET_D_OS_VERSIONS (void)   [D Target Hook]
Similarly to TARGET_D_CPU_VERSIONS, but is used for versions relating to the target operating system.

void TARGET_D_REGISTER_CPU_TARGET_INFO (void)   [D Target Hook]
Register all target information keys relating to the target CPU using the function d_add_target_info_handlers, which takes a 'struct d_target_info_spec' (defined in 'd/d-target.h'). The keys added by this hook are made available at compile time by the __traits(getTargetInfo) extension, the result is an expression describing the requested target information.

void TARGET_D_REGISTER_OS_TARGET_INFO (void)   [D Target Hook]
Same as TARGET_D_CPU_TARGET_INFO, but is used for keys relating to the target operating system.

const char * TARGET_D_MINFO_SECTION   [D Target Hook]
Contains the name of the section in which module info references should be placed. This section is expected to be bracketed by two symbols to indicate the start and end address of the section, so that the runtime library can collect all modules for each loaded shared library and executable. The default value of NULL disables the use of sections altogether.

const char * TARGET_D_MINFO_START_NAME   [D Target Hook]
If TARGET_D_MINFO_SECTION is defined, then this must also be defined as the name of the symbol indicating the start address of the module info section

const char * TARGET_D_MINFO_END_NAME   [D Target Hook]
If TARGET_D_MINFO_SECTION is defined, then this must also be defined as the name of the symbol indicating the end address of the module info section

bool TARGET_D_HAS_STDCALL_CONVENTION (unsigned int *link_system, unsigned int *link_windows)   [D Target Hook]
Returns true if the target supports the stdcall calling convention. The hook should also set link_system to 1 if the stdcall attribute should be applied to functions with extern(System) linkage, and link_windows to 1 to apply stdcall to functions with extern(Windows) linkage.

bool TARGET_D_TEMPLATES_ALWAYS_COMDAT   [D Target Hook]
This flag is true if instantiated functions and variables are always COMDAT if they have external linkage. If this flag is false, then instantiated decls will be emitted as weak symbols. The default is false.

18.30 Adding support for named address spaces
The draft technical report of the ISO/IEC JTC1 S22 WG14 N1275 standards committee, Programming Languages - C - Extensions to support embedded processors, specifies a syntax for embedded processors to specify alternate address spaces. You can configure a GCC port to support section 5.1 of the draft report to add support for address spaces other than the default address space. These address spaces are new keywords that are similar to the volatile and const type attributes.
Pointers to named address spaces can have a different size than pointers to the generic address space.

For example, the SPU port uses the __ea address space to refer to memory in the host processor, rather than memory local to the SPU processor. Access to memory in the __ea address space involves issuing DMA operations to move data between the host processor and the local processor memory address space. Pointers in the __ea address space are either 32 bits or 64 bits based on the '-mea32' or '-mea64' switches (native SPU pointers are always 32 bits).

Internally, address spaces are represented as a small integer in the range 0 to 15 with address space 0 being reserved for the generic address space.

To register a named address space qualifier keyword with the C front end, the target may call the c_register_addr_space routine. For example, the SPU port uses the following to declare __ea as the keyword for named address space #1:

```c
#define ADDR_SPACE_EA 1
c_register_addr_space("__ea", ADDR_SPACE_EA);
```

**[Target Hook]**

```c
scalar_int_mode TARGET_ADDR_SPACE_POINTER_MODE (addr_space_t address_space)
```

Define this to return the machine mode to use for pointers to address_space if the target supports named address spaces. The default version of this hook returns ptr_mode.

**[Target Hook]**

```c
scalar_int_mode TARGET_ADDR_SPACE_ADDRESS_MODE (addr_space_t address_space)
```

Define this to return the machine mode to use for addresses in address_space if the target supports named address spaces. The default version of this hook returns Pmode.

**[Target Hook]**

```c
bool TARGET_ADDR_SPACE_VALID_POINTER_MODE (scalar_int_mode mode, addr_space_t as)
```

Define this to return nonzero if the port can handle pointers with machine mode mode to address space as. This target hook is the same as the TARGET_VALID_POINTER_MODE target hook, except that it includes explicit named address space support. The default version of this hook returns true for the modes returned by either the TARGET_ADDR_SPACE_POINTER_MODE or TARGET_ADDR_SPACE_ADDRESS_MODE target hooks for the given address space.

**[Target Hook]**

```c
bool TARGET_ADDR_SPACE_LEGITIMATE_ADDRESS_P (machine_mode mode, rtx exp, bool strict, addr_space_t as)
```

Define this to return true if exp is a valid address for mode mode in the named address space as. The strict parameter says whether strict addressing is in effect after reload has finished. This target hook is the same as the TARGET_LEGITIMATE_ADDRESS_P target hook, except that it includes explicit named address space support.

**[Target Hook]**

```c
rtx TARGET_ADDR_SPACE_LEGITIMIZE_ADDRESS (rtx x, rtx oldx, machine_mode mode, addr_space_t as)
```

Define this to modify an invalid address x to be a valid address with mode mode in the named address space as. This target hook is the same as the TARGET_LEGITIMIZE_ADDRESS target hook, except that it includes explicit named address space support.
bool TARGET_ADDR_SPACE_SUBSET_P (addr_space_t subset, addr_space_t superset) [Target Hook]
Define this to return whether the subset named address space is contained within the superset named address space. Pointers to a named address space that is a subset of another named address space will be converted automatically without a cast if used together in arithmetic operations. Pointers to a superset address space can be converted to pointers to a subset address space via explicit casts.

bool TARGET_ADDR_SPACE_ZERO_ADDRESS_VALID (addr_space_t as) [Target Hook]
Define this to modify the default handling of address 0 for the address space. Return true if 0 should be considered a valid address.

rtx TARGET_ADDR_SPACE_CONVERT (rtx op, tree from_type, tree to_type) [Target Hook]
Define this to convert the pointer expression represented by the RTL op with type from_type that points to a named address space to a new pointer expression with type to_type that points to a different named address space. When this hook it called, it is guaranteed that one of the two address spaces is a subset of the other, as determined by the TARGET_ADDR_SPACE_SUBSET_P target hook.

int TARGET_ADDR_SPACE_DEBUG (addr_space_t as) [Target Hook]
Define this to define how the address space is encoded in dwarf. The result is the value to be used with DW_AT_address_class.

void TARGET_ADDR_SPACE_DIAGNOSE_USAGE (addr_space_t as, location_t loc) [Target Hook]
Define this hook if the availability of an address space depends on command line options and some diagnostics should be printed when the address space is used. This hook is called during parsing and allows to emit a better diagnostic compared to the case where the address space was not registered with c_register_addr_space. as is the address space as registered with c_register_addr_space. loc is the location of the address space qualifier token. The default implementation does nothing.

18.31 Miscellaneous Parameters
Here are several miscellaneous parameters.

HAS_LONG_COND_BRANCH [Macro]
Define this boolean macro to indicate whether or not your architecture has conditional branches that can span all of memory. It is used in conjunction with an optimization that partitions hot and cold basic blocks into separate sections of the executable. If this macro is set to false, gcc will convert any conditional branches that attempt to cross between sections into unconditional branches or indirect jumps.

HAS_LONG_UNCOND_BRANCH [Macro]
Define this boolean macro to indicate whether or not your architecture has unconditional branches that can span all of memory. It is used in conjunction with an optimization that partitions hot and cold basic blocks into separate sections of the
executable. If this macro is set to false, gcc will convert any unconditional branches that attempt to cross between sections into indirect jumps.

**CASE_VECTOR_MODE**  
An alias for a machine mode name. This is the machine mode that elements of a jump-table should have.

**CASE_VECTOR_SHORTEN_MODE**  
Optional: return the preferred mode for an `addr_diff_vec` when the minimum and maximum offset are known. If you define this, it enables extra code in branch shortening to deal with `addr_diff_vec`. To make this work, you also have to define `INSN_ALIGN` and make the alignment for `addr_diff_vec` explicit. The `body` argument is provided so that the offset_unsigned and scale flags can be updated.

**CASE_VECTOR_PC_RELATIVE**  
Define this macro to be a C expression to indicate when jump-tables should contain relative addresses. You need not define this macro if jump-tables never contain relative addresses, or jump-tables should contain relative addresses only when `-fPIC` or `-fPIC` is in effect.

**unsigned int TARGET_CASE_VALUES_THRESHOLD (void)**  
This function return the smallest number of different values for which it is best to use a jump-table instead of a tree of conditional branches. The default is four for machines with a `casesi` instruction and five otherwise. This is best for most machines.

**WORD_REGISTER_OPERATIONS**  
Define this macro to 1 if operations between registers with integral mode smaller than a word are always performed on the entire register. To be more explicit, if you start with a pair of `word_mode` registers with known values and you do a subword, for example `QImode`, addition on the low part of the registers, then the compiler may consider that the result has a known value in `word_mode` too if the macro is defined to 1. Most RISC machines have this property and most CISC machines do not.

**unsigned int TARGET_MIN_ARITHMETIC_PRECISION (void)**  
On some RISC architectures with 64-bit registers, the processor also maintains 32-bit condition codes that make it possible to do real 32-bit arithmetic, although the operations are performed on the full registers.

On such architectures, defining this hook to 32 tells the compiler to try using 32-bit arithmetical operations setting the condition codes instead of doing full 64-bit arithmetic.

More generally, define this hook on RISC architectures if you want the compiler to try using arithmetical operations setting the condition codes with a precision lower than the word precision.

You need not define this hook if `WORD_REGISTER_OPERATIONS` is not defined to 1.

**LOAD_EXTEND_OP**  
Define this macro to be a C expression indicating when insns that read memory in `mem_mode`, an integral mode narrower than a word, set the bits outside of `mem_mode`
to be either the sign-extension or the zero-extension of the data read. Return \texttt{SIGN\

\texttt{EXTEND}} for values of \texttt{mem_mode} for which the \texttt{insn} sign-extends, \texttt{ZERO\

\texttt{EXTEND}} for which it zero-extends, and \texttt{UNKNOWN} for other modes.

This macro is not called with \texttt{mem_mode} non-integral or with a width greater than or

\texttt{equal to BITS_PER_WORD}, so you may return any value in this case. Do not define this

\texttt{macro} if it would always return \texttt{UNKNOWN}. On machines where this \texttt{macro} is defined,

\texttt{you will normally define it as the constant \texttt{SIGN\

\texttt{EXTEND}} or \texttt{ZERO\

\texttt{EXTEND}}. You may return a non-\texttt{UNKNOWN} value even if for some hard registers the sign extension

is not performed, if for the \texttt{REGNO_REG\_CLASS} of these hard registers \texttt{TARGET\_CAN\

\texttt{CHANGE\_MODE\_CLASS}} returns false when the from \texttt{mode} is \texttt{mem_mode} and the to

\texttt{mode} is any integral mode larger than this but not larger than \texttt{word_mode}. You must return \texttt{UNKNOWN} if for some hard registers that allow this mode, \texttt{TARGET\

\texttt{CAN\_CHANGE\_MODE\_CLASS}} says that they cannot change to \texttt{word_mode}, but that they
can change to another integral mode that is larger then \texttt{mem_mode} but still smaller than
\texttt{word_mode}.

\texttt{SHORT\_IMMEDIATES\_SIGN\_EXTEND} \hfill [Macro]

Define this \texttt{macro} to 1 if loading short immediate values into registers sign extends.

\texttt{unsigned int TARGET\_MIN\_DIVISIONS\_FOR\_RECIP\_MUL} \hfill [Target Hook]

\begin{verbatim}
(machine\_mode mode)
\end{verbatim}

\texttt{When \texttt{-ffast-math} is in effect, GCC tries to optimize divisions by the same divisor,}

\texttt{by turning them into multiplications by the reciprocal. This target hook specifies}

\texttt{the minimum number of divisions that should be there for GCC to perform the}

\texttt{optimization for a variable of \texttt{mode} \texttt{mode}. The default implementation returns 3 if}

\texttt{the machine has an instruction for the division, and 2 if it does not.}

\texttt{MOVE\_MAX} \hfill [Macro]

The maximum number of bytes that a single instruction can move quickly between

memory and registers or between two memory locations.

\texttt{MAX\_MOVE\_MAX} \hfill [Macro]

The maximum number of bytes that a single instruction can move quickly between

memory and registers or between two memory locations. If this is undefined, the

default is \texttt{MOVE\_MAX}. Otherwise, it is the constant value that is the largest value that

\texttt{MOVE\_MAX} can have at run-time.

\texttt{SHIFT\_COUNT\_TRUNCATED} \hfill [Macro]

\texttt{A C expression that is nonzero if on this machine the number of bits actually used}

for the count of a shift operation is equal to the number of bits needed to represent

the size of the object being shifted. When this \texttt{macro} is nonzero, the compiler will

assume that it is safe to omit a sign-extend, zero-extend, and certain bitwise ‘and’

\texttt{instructions} that truncates the count of a shift operation. On machines that have

\texttt{instructions} that act on bit-fields at variable positions, which may include ‘bit test’

\texttt{instructions}, a nonzero \texttt{SHIFT\_COUNT\_TRUNCATED} also enables deletion of truncations

of the values that serve as arguments to bit-field instructions.

If both types of instructions truncate the count (for shifts) and position (for bit-field

operations), or if no variable-position bit-field instructions exist, you should define

this \texttt{macro}.}
However, on some machines, such as the 80386 and the 680x0, truncation only applies to shift operations and not the (real or pretended) bit-field operations. Define \texttt{SHIFT\_COUNT\_TRUNCATED} to be zero on such machines. Instead, add patterns to the \texttt{md} file that include the implied truncation of the shift instructions.

You need not define this macro if it would always have the value of zero.

\begin{verbatim}
unsigned HOST_WIDE_INT TARGET_SHIFT_TRUNCATION_MASK
  (machine_mode mode)
This function describes how the standard shift patterns for \texttt{mode} deal with shifts by negative amounts or by more than the width of the mode. See \cite{shift patterns}, page 420.

On many machines, the shift patterns will apply a mask \texttt{m} to the shift count, meaning that a fixed-width shift of \texttt{x} by \texttt{y} is equivalent to an arbitrary-width shift of \texttt{x} by \texttt{y} & \texttt{m}. If this is true for mode \texttt{mode}, the function should return \texttt{m}, otherwise it should return 0. A return value of 0 indicates that no particular behavior is guaranteed.

Note that, unlike \texttt{SHIFT\_COUNT\_TRUNCATED}, this function does \textit{not} apply to general shift rtxes; it applies only to instructions that are generated by the named shift patterns.

The default implementation of this function returns GET\_MODE\_BITSIZE (\texttt{mode}) - 1 if \texttt{SHIFT\_COUNT\_TRUNCATED} and 0 otherwise. This definition is always safe, but if \texttt{SHIFT\_COUNT\_TRUNCATED} is false, and some shift patterns nevertheless truncate the shift count, you may get better code by overriding it.
\end{verbatim}

\begin{verbatim}
bool TARGET_TRULY_NOOP_TRUNCATION (poly_uint64 outprec, poly_uint64 inprec)
This hook returns true if it is safe to “convert” a value of \texttt{inprec} bits to one of \texttt{outprec} bits (where \texttt{outprec} is smaller than \texttt{inprec}) by merely operating on it as if it had only \texttt{outprec} bits. The default returns true unconditionally, which is correct for most machines. When \texttt{TARGET\_TRULY\_NOOP\_TRUNCATION} returns false, the machine description should provide a \texttt{trunc} optab to specify the RTL that performs the required truncation.

If \texttt{TARGET\_MODES\_TIEABLE\_P} returns false for a pair of modes, suboptimal code can result if this hook returns true for the corresponding mode sizes. Making this hook return false in such cases may improve things.
\end{verbatim}

\begin{verbatim}
int TARGET\_MODE\_REP\_EXTENDED (scalar_int_mode mode, scalar_int_mode rep_mode)
The representation of an integral mode can be such that the values are always extended to a wider integral mode. Return \texttt{SIGN\_EXTEND} if values of \texttt{mode} are represented in sign-extended form to \texttt{rep\_mode}. Return \texttt{UNKNOWN} otherwise. (Currently, none of the targets use zero-extended representation this way so unlike \texttt{LOAD\_EXTEND\_OP}, \texttt{TARGET\_MODE\_REP\_EXTENDED} is expected to return either \texttt{SIGN\_EXTEND} or \texttt{UNKNOWN}. Also no target extends \texttt{mode} to \texttt{rep\_mode} so that \texttt{rep\_mode} is not the next widest integral mode and currently we take advantage of this fact.)

Similarly to \texttt{LOAD\_EXTEND\_OP} you may return a \texttt{non\_UNKNOWN} value even if the extension is not performed on certain hard registers as long as for the \texttt{REGNO\_REG\_CLASS} of these hard registers \texttt{TARGET\_CAN\_CHANGE\_MODE\_CLASS} returns false.
\end{verbatim}
Note that \texttt{TARGET\_MODE\_REP\_EXTENDED} and \texttt{LOAD\_EXTEND\_OP} describe two related properties. If you define \texttt{TARGET\_MODE\_REP\_EXTENDED (mode, word\_mode)} you probably also want to define \texttt{LOAD\_EXTEND\_OP (mode)} to return the same type of extension. In order to enforce the representation of \texttt{mode}, \texttt{TARGET\_TRULY\_NOOP\_TRUNCATION} should return false when truncating to \texttt{mode}.

\begin{verbatim}
bool TARGET_SETJMP_PRESERVES_NONVOLATILE_REGS_P (void)  
  [Target Hook]
  On some targets, it is assumed that the compiler will spill all pseudos that are live across a call to \texttt{setjmp}, while other targets treat \texttt{setjmp} calls as normal function calls.
  This hook returns false if \texttt{setjmp} calls do not preserve all non-volatile registers so that gcj that must spill all pseudos that are live across \texttt{setjmp} calls. Define this to return true if the target does not need to spill all pseudos live across \texttt{setjmp} calls.
  The default implementation conservatively assumes all pseudos must be spilled across \texttt{setjmp} calls.
\end{verbatim}

\begin{verbatim}
STORE\_FLAG\_VALUE  
  [Macro]
  A C expression describing the value returned by a comparison operator with an integral mode and stored by a store-flag instruction (`\texttt{cstoremode4}') when the condition is true. This description must apply to all the `\texttt{cstoremode4}' patterns and all the comparison operators whose results have a \texttt{MODE\_INT} mode.
  A value of 1 or \texttt{-1} means that the instruction implementing the comparison operator returns exactly 1 or \texttt{-1} when the comparison is true and 0 when the comparison is false. Otherwise, the value indicates which bits of the result are guaranteed to be 1 when the comparison is true. This value is interpreted in the mode of the comparison operation, which is given by the mode of the first operand in the `\texttt{cstoremode4}' pattern. Either the low bit or the sign bit of \texttt{STORE\_FLAG\_VALUE} be on. Presently, only those bits are used by the compiler.
  If \texttt{STORE\_FLAG\_VALUE} is neither 1 or \texttt{-1}, the compiler will generate code that depends only on the specified bits. It can also replace comparison operators with equivalent operations if they cause the required bits to be set, even if the remaining bits are undefined. For example, on a machine whose comparison operators return an SImode value and where \texttt{STORE\_FLAG\_VALUE} is defined as `\texttt{0x80000000}', saying that just the sign bit is relevant, the expression
  \begin{verbatim}
  (ne:SI (and:SI x (const_int power-of-2)) (const_int 0))
\end{verbatim}
  can be converted to
  \begin{verbatim}
  (ashift:SI x (const_int n))
\end{verbatim}
  where \texttt{n} is the appropriate shift count to move the bit being tested into the sign bit.
  There is no way to describe a machine that always sets the low-order bit for a true value, but does not guarantee the value of any other bits, but we do not know of any machine that has such an instruction. If you are trying to port GCC to such a machine, include an instruction to perform a logical-and of the result with 1 in the pattern for the comparison operators and let us know at \texttt{gcc@gcc.gnu.org}.
  Often, a machine will have multiple instructions that obtain a value from a comparison (or the condition codes). Here are rules to guide the choice of value for \texttt{STORE\_FLAG\_VALUE}, and hence the instructions to be used:
\end{verbatim}
• Use the shortest sequence that yields a valid definition for STORE_FLAG_VALUE. It is more efficient for the compiler to “normalize” the value (convert it to, e.g., 1 or 0) than for the comparison operators to do so because there may be opportunities to combine the normalization with other operations.

• For equal-length sequences, use a value of 1 or −1, with −1 being slightly preferred on machines with expensive jumps and 1 preferred on other machines.

• As a second choice, choose a value of ‘0x80000001’ if instructions exist that set both the sign and low-order bits but do not define the others.

• Otherwise, use a value of ‘0x80000000’.

Many machines can produce both the value chosen for STORE_FLAG_VALUE and its negation in the same number of instructions. On those machines, you should also define a pattern for those cases, e.g., one matching

(set A (neg:m (ne:m B C)))

Some machines can also perform and or plus operations on condition code values with less instructions than the corresponding ‘cstoremode4’ insn followed by and or plus. On those machines, define the appropriate patterns. Use the names incscc and decscc, respectively, for the patterns which perform plus or minus operations on condition code values. See ‘rs6000.md’ for some examples. The GNU Superoptimizer can be used to find such instruction sequences on other machines.

If this macro is not defined, the default value, 1, is used. You need not define STORE_FLAG_VALUE if the machine has no store-flag instructions, or if the value generated by these instructions is 1.

FLOAT_STORE_FLAG_VALUE (mode) [Macro]
A C expression that gives a nonzero REAL_VALUE_TYPE value that is returned when comparison operators with floating-point results are true. Define this macro on machines that have comparison operations that return floating-point values. If there are no such operations, do not define this macro.

VECTOR_STORE_FLAG_VALUE (mode) [Macro]
A C expression that gives an rtx representing the nonzero true element for vector comparisons. The returned rtx should be valid for the inner mode of mode which is guaranteed to be a vector mode. Define this macro on machines that have vector comparison operations that return a vector result. If there are no such operations, do not define this macro. Typically, this macro is defined as const1_rtx or constm1_rtx. This macro may return NULL_RTX to prevent the compiler optimizing such vector comparison operations for the given mode.

CLZ_DEFINED_VALUE_AT_ZERO (mode, value) [Macro]
CTZ_DEFINED_VALUE_AT_ZERO (mode, value) [Macro]
A C expression that indicates whether the architecture defines a value for clz or ctz with a zero operand. A result of 0 indicates the value is undefined. If the value is defined for only the RTL expression, the macro should evaluate to 1; if the value applies also to the corresponding optab entry (which is normally the case if it expands directly into the corresponding RTL), then the macro should evaluate to 2. In the cases where the value is defined, value should be set to this value.
If this macro is not defined, the value of \texttt{clz} or \texttt{ctz} at zero is assumed to be undefined. This macro must be defined if the target’s expansion for \texttt{ffs} relies on a particular value to get correct results. Otherwise it is not necessary, though it may be used to optimize some corner cases, and to provide a default expansion for the \texttt{ffs} optab.

Note that regardless of this macro the “definedness” of \texttt{clz} and \texttt{ctz} at zero do not extend to the builtin functions visible to the user. Thus one may be free to adjust the value at will to match the target expansion of these operations without fear of breaking the API.

\textbf{Pmode} \hfill \texttt{[Macro]}

An alias for the machine mode for pointers. On most machines, define this to be the integer mode corresponding to the width of a hardware pointer; \texttt{SImode} on 32-bit machine or \texttt{DImode} on 64-bit machines. On some machines you must define this to be one of the partial integer modes, such as \texttt{PSImode}.

The width of \texttt{Pmode} must be at least as large as the value of \texttt{POINTER_SIZE}. If it is not equal, you must define the macro \texttt{POINTERS_EXTEND_UNSIGNED} to specify how pointers are extended to \texttt{Pmode}.

\textbf{FUNCTION\_MODE} \hfill \texttt{[Macro]}

An alias for the machine mode used for memory references to functions being called, in call RTL expressions. On most CISC machines, where an instruction can begin at any byte address, this should be \texttt{QImode}. On most RISC machines, where all instructions have fixed size and alignment, this should be a mode with the same size and alignment as the machine instruction words - typically \texttt{SImode} or \texttt{HImode}.

\textbf{STDC\_0\_IN\_SYSTEM\_HEADERS} \hfill \texttt{[Macro]}

In normal operation, the preprocessor expands \texttt{__STDC__} to the constant 1, to signify that GCC conforms to ISO Standard C. On some hosts, like Solaris, the system compiler uses a different convention, where \texttt{__STDC__} is normally 0, but is 1 if the user specifies strict conformance to the C Standard.

Defining \texttt{STDC\_0\_IN\_SYSTEM\_HEADERS} makes GNU CPP follows the host convention when processing system header files, but when processing user files \texttt{__STDC__} will always expand to 1.

\textbf{const char * TARGET\_C\_PREINCLUDE \hfill \texttt{(void)}} \hfill \texttt{[C Target Hook]}

Define this hook to return the name of a header file to be included at the start of all compilations, as if it had been included with \texttt{#include <file>}. If this hook returns \texttt{NULL}, or is not defined, or the header is not found, or if the user specifies \texttt{’-ffreestanding’} or \texttt{’-nostdinc’}, no header is included.

This hook can be used together with a header provided by the system C library to implement ISO C requirements for certain macros to be predefined that describe properties of the whole implementation rather than just the compiler.

\textbf{bool TARGET\_CXX\_IMPLICIT\_EXTERN\_C \hfill \texttt{(const char*)} \hfill \texttt{[C Target Hook]}}

Define this hook to add target-specific C++ implicit extern C functions. If this function returns true for the name of a file-scope function, that function implicitly gets extern “C” linkage rather than whatever language linkage the declaration would normally have. An example of such function is \texttt{WinMain} on Win32 targets.
**SYSTEM_IMPLICIT_EXTERN_C**

[Macro]

Define this macro if the system header files do not support C++. This macro handles system header files by pretending that system header files are enclosed in `extern "C" {...}`.

**REGISTER_TARGET_PRAGMAS ()**

[Macro]

Define this macro if you want to implement any target-specific pragmas. If defined, it is a C expression which makes a series of calls to `c_register_pragma` or `c_register_pragma_with_expansion` for each pragma. The macro may also do any setup required for the pragmas.

The primary reason to define this macro is to provide compatibility with other compilers for the same target. In general, we discourage definition of target-specific pragmas for GCC.

If the pragma can be implemented by attributes then you should consider defining the target hook `TARGET_INSERT_ATTRIBUTES` as well.

Preprocessor macros that appear on pragma lines are not expanded. All `#pragma` directives that do not match any registered pragma are silently ignored, unless the user specifies `--unknown-pragmas`.

**void c_register_pragma (const char *space, const char *name, void (*callback)(struct cpp_reader *))**

**void c_register_pragma_with_expansion (const char *space, const char *name, void (*callback)(struct cpp_reader *))**

Each call to `c_register_pragma` or `c_register_pragma_with_expansion` establishes one pragma. The callback routine will be called when the preprocessor encounters a pragma of the form

```
#pragma [space] name ...
```

*space* is the case-sensitive namespace of the pragma, or NULL to put the pragma in the global namespace. The callback routine receives *pfile* as its first argument, which can be passed on to cpplib's functions if necessary. You can lex tokens after the *name* by calling `pragma_lex`. Tokens that are not read by the callback will be silently ignored.

The end of the line is indicated by a token of type `CPP_EOF`. Macro expansion occurs on the arguments of pragmas registered with `c_register_pragma_with_expansion` but not on the arguments of pragmas registered with `c_register_pragma`.

Note that the use of `pragma_lex` is specific to the C and C++ compilers. It will not work in the Java or Fortran compilers, or any other language compilers for that matter. Thus if `pragma_lex` is going to be called from target-specific code, it must only be done so when building the C and C++ compilers. This can be done by defining the variables `c_target_objs` and `cxx_target_objs` in the target entry in the `config.gcc` file. These variables should name the target-specific, language-specific object file which contains the code that uses `pragma_lex`. Note it will also be necessary to add a rule to the makefile fragment pointed to by `tmake_file` that shows how to build this object file.

**HANDLE_PRAGMA_PACK_WITH_EXPANSION**

[Macro]

Define this macro if macros should be expanded in the arguments of `#pragma pack`. 
TARGET_DEFAULT_PACK_STRUCT

If your target requires a structure packing default other than 0 (meaning the machine
default), define this macro to the necessary value (in bytes). This must be a value
that would also be valid to use with ‘#pragma pack()’ (that is, a small power of two).

DOLLARS_IN_IDENTIFIERS

Define this macro to control use of the character ‘$’ in identifier names for the C
family of languages. 0 means ‘$’ is not allowed by default; 1 means it is allowed. 1 is
the default; there is no need to define this macro in that case.

INSN_SETS_ARE_DELAYED (insn)

Define this macro as a C expression that is nonzero if it is safe for the delay slot
scheduler to place instructions in the delay slot of insn, even if they appear to use
a resource set or clobbered in insn. insn is always a jump_insn or an insn: GCC
knows that every call_insn has this behavior. On machines where some insn or
jump_insn is really a function call and hence has this behavior, you should define
this macro.

You need not define this macro if it would always return zero.

INSN_REFERENCES_ARE_DELAYED (insn)

Define this macro as a C expression that is nonzero if it is safe for the delay slot
scheduler to place instructions in the delay slot of insn, even if they appear to set or
clobber a resource referenced in insn. insn is always a jump_insn or an insn. On
machines where some insn or jump_insn is really a function call and its operands are
registers whose use is actually in the subroutine it calls, you should define this macro.
Doing so allows the delay slot scheduler to move instructions which copy arguments
into the argument registers into the delay slot of insn.

You need not define this macro if it would always return zero.

MULTIPLE_SYMBOL_SPACES

Define this macro as a C expression that is nonzero if, in some cases, global symbols
from one translation unit may not be bound to undefined symbols in another transla-
tion unit without user intervention. For instance, under Microsoft Windows symbols
must be explicitly imported from shared libraries (DLLs).

You need not define this macro if it would always evaluate to zero.

rtx_insn * TARGET_MD_ASM_ADJUST (vec<rtx>& outputs,
vec<rtx>& inputs, vec<machine_mode>& input_modes, vec<const char*>&
constraints, vec<rtx>& clobbers, HARD_REG_SET& clobbered_regs,
location_t loc)

This target hook may add clobbers to clobbers and clobbered_regs for any hard regs
the port wishes to automatically clobber for an asm. The outputs and inputs may be
inspected to avoid clobbering a register that is already used by the asm. loc is the
source location of the asm.

It may modify the outputs, inputs, input_modes, and constraints as necessary for
other pre-processing. In this case the return value is a sequence of insns to emit after
the asm. Note that changes to inputs must be accompanied by the corresponding
changes to input_modes.
MATH_LIBRARY
Define this macro as a C string constant for the linker argument to link in the system
math library, minus the initial ‘"-l"’, or ‘""’ if the target does not have a separate
math library.
You need only define this macro if the default of ‘"m"’ is wrong.

LIBRARY_PATH_ENV
Define this macro as a C string constant for the environment variable that specifies
where the linker should look for libraries.
You need only define this macro if the default of ‘"LIBRARY_PATH"’ is wrong.

TARGET_POSIX_IO
Define this macro if the target supports the following POSIX file functions, access,
mkdir and file locking with fcntl / F_SETLK. Defining TARGET_POSIX_IO will
enable the test coverage code to use file locking when exiting a program, which avoids
race conditions if the program has forked. It will also create directories at run-time
for cross-profiling.

MAX_CONDITIONAL_EXECUTE
A C expression for the maximum number of instructions to execute via conditional
execution instructions instead of a branch. A value of BRANCH_COST+1 is the default.

IFCVT_MODIFY_TESTS (ce_info, true_expr, false_expr)
Used if the target needs to perform machine-dependent modifications on the condi-
tionals used for turning basic blocks into conditionally executed code. ce_info points
to a data structure, struct ce_if_block, which contains information about the cur-
cently processed blocks. true_expr and false_expr are the tests that are used for
converting the then-block and the else-block, respectively. Set either true_expr or
false_expr to a null pointer if the tests cannot be converted.

IFCVT_MODIFY_MULTIPLE_TESTS (ce_info, bb, true_expr, false_expr)
Like IFCVT_MODIFY_TESTS, but used when converting more complicated if-statements
into conditions combined by and and or operations. bb contains the basic block that
contains the test that is currently being processed and about to be turned into a
condition.

IFCVT_MODIFY_INSN (ce_info, pattern, insn)
A C expression to modify the PATTERN of an INSN that is to be converted to
conditional execution format. ce_info points to a data structure, struct ce_if_
block, which contains information about the currently processed blocks.

IFCVT_MODIFY_FINAL (ce_info)
A C expression to perform any final machine dependent modifications in converting
code to conditional execution. The involved basic blocks can be found in the struct
ce_if_block structure that is pointed to by ce_info.

IFCVT_MODIFY_CANCEL (ce_info)
A C expression to cancel any machine dependent modifications in converting code to
conditional execution. The involved basic blocks can be found in the struct ce_if_
block structure that is pointed to by ce_info.
IFCVT_MACHDEP_INIT (ce_info)  [Macro]
A C expression to initialize any machine specific data for if-conversion of the if-block in the struct ce_if_block structure that is pointed to by ce_info.

void TARGET_MACHINE_DEPENDENT_REORG (void)  [Target Hook]
If non-null, this hook performs a target-specific pass over the instruction stream. The compiler will run it at all optimization levels, just before the point at which it normally does delayed-branch scheduling.

The exact purpose of the hook varies from target to target. Some use it to do transformations that are necessary for correctness, such as laying out in-function constant pools or avoiding hardware hazards. Others use it as an opportunity to do some machine-dependent optimizations.

You need not implement the hook if it has nothing to do. The default definition is null.

void TARGET_INIT_BUILTINS (void)  [Target Hook]
Define this hook if you have any machine-specific built-in functions that need to be defined. It should be a function that performs the necessary setup.

Machine specific built-in functions can be useful to expand special machine instructions that would otherwise not normally be generated because they have no equivalent in the source language (for example, SIMD vector instructions or prefetch instructions).

To create a built-in function, call the function lang_hooks.builtin_function which is defined by the language front end. You can use any type nodes set up by build_common_tree_nodes; only language front ends that use those two functions will call ‘TARGET_INIT_BUILTINS’.

tree TARGET_BUILTIN_DECL (unsigned code, bool initialize_p)  [Target Hook]
Define this hook if you have any machine-specific built-in functions that need to be defined. It should be a function that returns the builtin function declaration for the builtin function code code. If there is no such builtin and it cannot be initialized at this time if initialize_p is true the function should return NULL_TREE. If code is out of range the function should return error_mark_node.

rtx TARGET_EXPAND_BUILTIN (tree exp, rtx target, rtx subtarget, machine_mode mode, int ignore)  [Target Hook]
Expand a call to a machine specific built-in function that was set up by ‘TARGET_INIT_BUILTINS’. exp is the expression for the function call; the result should go to target if that is convenient, and have mode mode if that is convenient. subtarget may be used as the target for computing one of exp’s operands. ignore is nonzero if the value is to be ignored. This function should return the result of the call to the built-in function.

tree TARGET_RESOLVE_OVERLOADED_BUILTIN (unsigned int loc, tree fndecl, void *arglist)  [Target Hook]
Select a replacement for a machine specific built-in function that was set up by ‘TARGET_INIT_BUILTINS’. This is done before regular type checking, and so allows
the target to implement a crude form of function overloading. \texttt{fndecl} is the declaration of the built-in function. \texttt{arglist} is the list of arguments passed to the built-in function. The result is a complete expression that implements the operation, usually another \texttt{CALL_EXPR}. \texttt{arglist} really has type \texttt{VEC(tree,gc)\*}.

bool \texttt{TARGET\_CHECK\_BUILTIN\_CALL (location_t loc, vec<location_t> \texttt{arg\_loc}, tree \texttt{fndecl}, tree \texttt{orig\_fndecl}, unsigned int \texttt{nargs}, tree *\texttt{args})}  

Perform semantic checking on a call to a machine-specific built-in function after its arguments have been constrained to the function signature. Return true if the call is valid, otherwise report an error and return false.

This hook is called after \texttt{TARGET\_RESOLVE\_OVERLOADED\_BUILTIN}. The call was originally to built-in function \texttt{orig\_fndecl}, but after the optional \texttt{TARGET\_RESOLVE\_OVERLOADED\_BUILTIN} step is now to built-in function \texttt{fndecl}. \texttt{loc} is the location of the call and \texttt{args} is an array of function arguments, of which there are \texttt{nargs}. \texttt{arg\_loc} specifies the location of each argument.

\texttt{tree TARGET\_FOLD\_BUILTIN (tree \texttt{fndecl}, int \texttt{n\_args}, tree *\texttt{argp}, bool \texttt{ignore})}  

Fold a call to a machine specific built-in function that was set up by \texttt{TARGET\_INIT\_BUILTINs}. \texttt{fndecl} is the declaration of the built-in function. \texttt{n\_args} is the number of arguments passed to the function; the arguments themselves are pointed to by \texttt{argp}. The result is another tree, valid for both GIMPLE and GENERIC, containing a simplified expression for the call’s result. If \texttt{ignore} is true the value will be ignored.

bool \texttt{TARGET\_GIMPLE\_FOLD\_BUILTIN (gimple\_stmt\_iterator *\texttt{gsi})}  

Fold a call to a machine specific built-in function that was set up by \texttt{TARGET\_INIT\_BUILTINs}. \texttt{gsi} points to the gimple statement holding the function call. Returns true if any change was made to the GIMPLE stream.

int \texttt{TARGET\_COMPARE\_VERSION\_PRIORITY (tree \texttt{decl1}, tree \texttt{decl2})}  

This hook is used to compare the target attributes in two functions to determine which function’s features get higher priority. This is used during function multi-versioning to figure out the order in which two versions must be dispatched. A function version with a higher priority is checked for dispatching earlier. \texttt{decl1} and \texttt{decl2} are the two function decls that will be compared.

\texttt{tree TARGET\_GET\_FUNCTION\_VERSIONS\_DISPATCHER (void *\texttt{decl})}  

This hook is used to get the dispatcher function for a set of function versions. The dispatcher function is called to invoke the right function version at run-time. \texttt{decl} is one version from a set of semantically identical versions.

\texttt{tree TARGET\_GENERATE\_VERSION\_DISPATCHER\_BODY (void *\texttt{arg})}  

This hook is used to generate the dispatcher logic to invoke the right function version at run-time for a given set of function versions. \texttt{arg} points to the callgraph node of the dispatcher function whose body must be generated.

bool \texttt{TARGET\_PREDICT\_DOLOOP\_P (class loop *\texttt{loop})}  

Return true if we can predict it is possible to use a low-overhead loop for a particular loop. The parameter \texttt{loop} is a pointer to the loop. This target hook is required
only when the target supports low-overhead loops, and will help ivopts to make some decisions. The default version of this hook returns false.

```c
bool TARGET_HAVE_COUNT_REG_DECR_P [Target Hook]
Return true if the target supports hardware count register for decrement and branch. The default value is false.
```

```c
int64_t TARGET_DOLOOP_COST_FOR_GENERIC [Target Hook]
One IV candidate dedicated for doloop is introduced in IVOPTs, we can calculate the computation cost of adopting it to any generic IV use by function get_computation_cost as before. But for targets which have hardware count register support for decrement and branch, it may have to move IV value from hardware count register to general purpose register while doloop IV candidate is used for generic IV uses. It probably takes expensive penalty. This hook allows target owners to define the cost for this especially for generic IV uses. The default value is zero.
```

```c
int64_t TARGET_DOLOOP_COST_FOR_ADDRESS [Target Hook]
One IV candidate dedicated for doloop is introduced in IVOPTs, we can calculate the computation cost of adopting it to any address IV use by function get_computation_cost as before. But for targets which have hardware count register support for decrement and branch, it may have to move IV value from hardware count register to general purpose register while doloop IV candidate is used for address IV uses. It probably takes expensive penalty. This hook allows target owners to define the cost for this especially for address IV uses. The default value is zero.
```

```c
bool TARGET_CAN_USE_DOLOOP_P (const widest_int &iterations, const widest_int &iterations_max, unsigned int loop_depth, bool entered_at_top) [Target Hook]
Return true if it is possible to use low-overhead loops (doloop_end and doloop_begin) for a particular loop. iterations gives the exact number of iterations, or 0 if not known. iterations_max gives the maximum number of iterations, or 0 if not known. loop_depth is the nesting depth of the loop, with 1 for innermost loops, 2 for loops that contain innermost loops, and so on. entered_at_top is true if the loop is only entered from the top.

This hook is only used if doloop_end is available. The default implementation returns true. You can use can_use_doloop_if_innermost if the loop must be the innermost, and if there are no other restrictions.
```

```c
const char * TARGET_INVALID_WITHIN_DOLOOP (const rtx_insn *) [Target Hook]
Take an instruction in insn and return NULL if it is valid within a low-overhead loop, otherwise return a string explaining why doloop could not be applied.

Many targets use special registers for low-overhead looping. For any instruction that clobbers these this function should return a string indicating the reason why the doloop could not be applied. By default, the RTL loop optimizer does not use a present doloop pattern for loops containing function calls or branch on table instructions.
machine_mode TARGET_PREFERRED_DOLOOP_MODE (machine_mode mode) [Target Hook]
    This hook takes a mode for a doooup IV, where mode is the original mode for the operation. If the target prefers an alternate mode for the operation, then this hook should return that mode; otherwise the original mode should be returned. For example, on a 64-bit target, DImode might be preferred over SImode. Both the original and the returned modes should be MODE_INT.

bool TARGET_LEGITIMATE_COMBINED_INSN (rtx_insn *insn) [Target Hook]
    Take an instruction in insn and return false if the instruction is not appropriate as a combination of two or more instructions. The default is to accept all instructions.

bool TARGET_CAN_FOLLOW_JUMP (const rtx_insn *follower, const rtx_insn *followee) [Target Hook]
    FOLLOWER and FOLLOWEE are JUMP_INSN instructions; return true if FOLLOWER may be modified to follow FOLLOWEE; false, if it can't. For example, on some targets, certain kinds of branches can't be made to follow through a hot/cold partitioning.

bool TARGET_COMMUTATIVE_P (const rtx x, int outer_code) [Target Hook]
    This target hook returns true if x is considered to be commutative. Usually, this is just COMMUTATIVE_P (x), but the HP PA doesn't consider PLUS to be commutative inside a MEM. outer_code is the rtx code of the enclosing rtl, if known, otherwise it is UNKNOWN.

rtx TARGET_ALLOCATE_INITIAL_VALUE (rtx hard_reg) [Target Hook]
    When the initial value of a hard register has been copied in a pseudo register, it is often not necessary to actually allocate another register to this pseudo register, because the original hard register or a stack slot it has been saved into can be used. TARGET_ALLOCATE_INITIAL_VALUE is called at the start of register allocation once for each hard register that had its initial value copied by using get_func_hard_reg_initial_val or get_hard_reg_initial_val. Possible values are NULL_RTX, if you don't want to do any special allocation, a REG rtx—that would typically be the hard register itself, if it is known not to be clobbered—or a MEM. If you are returning a MEM, this is only a hint for the allocator; it might decide to use another register anyways. You may use current_function_is_leaf or REG_N_SETS in the hook to determine if the hard register in question will not be clobbered. The default value of this hook is NULL, which disables any special allocation.

int TARGET_UNSPEC_MAY_TRAP_P (const rtx x, unsigned flags) [Target Hook]
    This target hook returns nonzero if x, an unspec or unspec_volatile operation, might cause a trap. Targets can use this hook to enhance precision of analysis for unspec and unspec_volatile operations. You may call may_trap_p_1 to analyze inner elements of x in which case flags should be passed along.

void TARGET_SET_CURRENT_FUNCTION (tree decl) [Target Hook]
    The compiler invokes this hook whenever it changes its current function context (cfun). You can define this function if the back end needs to perform any initialization or reset actions on a per-function basis. For example, it may be used to
implement function attributes that affect register usage or code generation patterns. The argument `decl` is the declaration for the new function context, and may be null to indicate that the compiler has left a function context and is returning to processing at the top level. The default hook function does nothing.

GCC sets `cfun` to a dummy function context during initialization of some parts of the back end. The hook function is not invoked in this situation; you need not worry about the hook being invoked recursively, or when the back end is in a partially-initialized state. `cfun` might be `NULL` to indicate processing at top level, outside of any function scope.

**TARGET_OBJECT_SUFFIX**

[Macro]

Define this macro to be a C string representing the suffix for object files on your target machine. If you do not define this macro, GCC will use `*.o` as the suffix for object files.

**TARGET_EXECUTABLE_SUFFIX**

[Macro]

Define this macro to be a C string representing the suffix to be automatically added to executable files on your target machine. If you do not define this macro, GCC will use the null string as the suffix for executable files.

**COLLECT_EXPORT_LIST**

[Macro]

If defined, `collect2` will scan the individual object files specified on its command line and create an export list for the linker. Define this macro for systems like AIX, where the linker discards object files that are not referenced from `main` and uses export lists.

```c
bool TARGET_CANNOT_MODIFY_JUMPS_P (void)                     [Target Hook]
This target hook returns true past the point in which new jump instructions could be created. On machines that require a register for every jump such as the SHmedia ISA of SH5, this point would typically be reload, so this target hook should be defined to a function such as:

static bool
cannot_modify_jumps_past_reload_p ()
{
    return (reload_completed || reload_in_progress);
}
```

```c
bool TARGET_HAVE_CONDITIONAL_EXECUTION (void)                  [Target Hook]
This target hook returns true if the target supports conditional execution. This target hook is required only when the target has several different modes and they have different conditional execution capability, such as ARM.
```

```c
rtx TARGET_GEN_CCMP_FIRST (rtx_insn **prep_seq, rtx_insn **gen_seq, int code, tree op0, tree op1) [Target Hook]
This function prepares to emit a comparison insn for the first compare in a sequence of conditional comparisons. It returns an appropriate comparison with `CC` for passing to `gen_ccmp_next` or `cbranch_optab`. The insns to prepare the compare are saved in `prep_seq` and the compare insns are saved in `gen_seq`. They will be emitted when all the compares in the conditional comparision are generated without error. `code` is the `rtx_code` of the compare for `op0` and `op1`.
```
rtx TARGET_GEN_CCMP_NEXT (rtx_insn **prep_seq, rtx_insn **gen_seq, rtx insn prev, int cmp_code, tree op0, tree op1, int bit_code) [Target Hook]

This function prepares to emit a conditional comparison within a sequence of conditional comparisons. It returns an appropriate comparison with CC for passing to gen_ccmp_next or cbranch_optab. The insns to prepare the compare are saved in prep_seq and the compare insns are saved in gen_seq. They will be emitted when all the compares in the conditional comparison are generated without error. The prev expression is the result of a prior call to gen_ccmp_first or gen_ccmp_next. It may return NULL if the combination of prev and this comparison is not supported, otherwise the result must be appropriate for passing to gen_ccmp_next or cbranch_optab. code is the rtx_code of the compare for op0 and op1. bit_code is AND or IOR, which is the op on the compares.

rtx TARGET_GEN_MEMSET_SCRATCH RTX (machine_mode mode) [Target Hook]

This hook should return an rtx for a scratch register in mode to be used when expanding memset calls. The backend can use a hard scratch register to avoid stack realignment when expanding memset. The default is gen_reg_rtx.

unsigned TARGET_LOOP_UNROLL_ADJUST (unsigned nunroll, class *loop) [Target Hook]

This target hook returns a new value for the number of times loop should be unrolled. The parameter nunroll is the number of times the loop is to be unrolled. The parameter loop is a pointer to the loop, which is going to be checked for unrolling. This target hook is required only when the target has special constraints like maximum number of memory accesses.

POWI_MAX_MULTS [Macro]

If defined, this macro is interpreted as a signed integer C expression that specifies the maximum number of floating point multiplications that should be emitted when expanding exponentiation by an integer constant inline. When this value is defined, exponentiation requiring more than this number of multiplications is implemented by calling the system library's pow, powf or powl routines. The default value places no upper bound on the multiplication count.

void TARGET_EXTRA_INCLUDES (const char *sysroot, const char *iprefix, int stdinc) [Macro]

This target hook should register any extra include files for the target. The parameter stdinc indicates if normal include files are present. The parameter sysroot is the system root directory. The parameter iprefix is the prefix for the gcc directory.

void TARGET_EXTRA_PRE_INCLUDES (const char *sysroot, const char *iprefix, int stdinc) [Macro]

This target hook should register any extra include files for the target before any standard headers. The parameter stdinc indicates if normal include files are present. The parameter sysroot is the system root directory. The parameter iprefix is the prefix for the gcc directory.
void TARGET_OPTF (char *path)  
This target hook should register special include paths for the target. The parameter  
path is the include to register. On Darwin systems, this is used for Framework  
includes, which have semantics that are different from ‘-I’.

bool TARGET_USE_LOCAL_THUNK_ALIAS_P (tree fndecl)  
This target macro returns true if it is safe to use a local alias for a virtual function  
fndecl when constructing thunks, false otherwise. By default, the macro returns  
true for all functions, if a target supports aliases (i.e. defines ASM_OUTPUT_DEF),  
false otherwise,

TARGET_FORMAT_TYPES  
If defined, this macro is the name of a global variable containing target-specific format  
checking information for the ‘-Wformat’ option. The default is to have no target-  
specific format checks.

TARGET_N_FORMAT_TYPES  
If defined, this macro is the number of entries in TARGET_FORMAT_TYPES.

TARGET_OVERRIDES_FORMAT_ATTRIBUTES  
If defined, this macro is the name of a global variable containing target-specific format  
overrides for the ‘-Wformat’ option. The default is to have no target-specific format  
overrides. If defined, TARGET_FORMAT_TYPES must be defined, too.

TARGET_OVERRIDES_FORMAT_ATTRIBUTES_COUNT  
If defined, this macro specifies the number of entries in TARGET_OVERRIDES_FORMAT_  
ATTRIBUTES.

TARGET_OVERRIDES_FORMAT_INIT  
If defined, this macro specifies the optional initialization routine for target specific  
customizations of the system printf and scanf formatter settings.

const char * TARGET_INVALID_ARG_FOR_UNPROTOTYPED_FN  
(const_tree typelist, const_tree funcdecl, const_tree val)  
If defined, this macro returns the diagnostic message when it is illegal to pass argument  
val to function funcdecl with prototype typelist.

const char * TARGET_INVALID_CONVERSION (const_tree  
fromtype, const_tree totype)  
If defined, this macro returns the diagnostic message when it is invalid to convert  
from fromtype to totype, or NULL if validity should be determined by the front end.

const char * TARGET_INVALID_UNARY_OP (int op, const_tree  
type)  
If defined, this macro returns the diagnostic message when it is invalid to apply  
operation op (where unary plus is denoted by CONVERT_EXPR) to an operand of type  
type, or NULL if validity should be determined by the front end.
const char * TARGET_INVALID_BINARY_OP (int op, const tree type1, const tree type2) [Target Hook]

If defined, this macro returns the diagnostic message when it is invalid to apply operation op to operands of types type1 and type2, or NULL if validity should be determined by the front end.

tree TARGET_PROMOTED_TYPE (const tree type) [Target Hook]

If defined, this target hook returns the type to which values of type should be promoted when they appear in expressions, analogous to the integer promotions, or NULL_TREE to use the front end’s normal promotion rules. This hook is useful when there are target-specific types with special promotion rules. This is currently used only by the C and C++ front ends.

tree TARGET_CONVERT_TO_TYPE (tree type, tree expr) [Target Hook]

If defined, this hook returns the result of converting expr to type. It should return the converted expression, or NULL_TREE to apply the front end’s normal conversion rules. This hook is useful when there are target-specific types with special conversion rules. This is currently used only by the C and C++ front ends.

bool TARGET_VERIFY_TYPE_CONTEXT (location_t loc, type_context_kind context, const tree type, bool silent_p) [Target Hook]

If defined, this hook returns false if there is a target-specific reason why type cannot be used in the source language context described by context. When silent_p is false, the hook also reports an error against loc for invalid uses of type. Calls to this hook should be made through the global function verify_type_context, which makes the silent_p parameter default to false and also handles error_mark_node.

The default implementation always returns true.

OBJC_JBLEN [Macro]

This macro determines the size of the objective C jump buffer for the NeXT runtime. By default, OBJC_JBLEN is defined to an innocuous value.

LIBGCC2_UNWIND_ATTRIBUTE [Macro]

Define this macro if any target-specific attributes need to be attached to the functions in ‘libgcc’ that provide low-level support for call stack unwinding. It is used in declarations in ‘unwind-generic.h’ and the associated definitions of those functions.

void TARGET_UPDATE_STACK_BOUNDARY (void) [Target Hook]

Define this macro to update the current function stack boundary if necessary.

rtx TARGET_GET_DRAP_RTX (void) [Target Hook]

This hook should return an rtx for Dynamic Realign Argument Pointer (DRAP) if a different argument pointer register is needed to access the function’s argument list due to stack realignment. Return NULL if no DRAP is needed.

HARD_REG_SET TARGET_ZERO_CALL_USED_REGS (HARD_REG_SET selected_regs) [Target Hook]

This target hook emits instructions to zero the subset of selected_regs that could conceivably contain values that are useful to an attacker. Return the set of registers that were actually cleared.
The default implementation uses normal move instructions to zero all the registers in selected_regs. Define this hook if the target has more efficient ways of zeroing certain registers, or if you believe that certain registers would never contain values that are useful to an attacker.

```c
bool TARGET_ALLOCATE_STACK_SLOTS_FOR_ARGS (void) [Target Hook]
When optimization is disabled, this hook indicates whether or not arguments should be allocated to stack slots. Normally, GCC allocates stacks slots for arguments when not optimizing in order to make debugging easier. However, when a function is declared with `__attribute__((naked))`, there is no stack frame, and the compiler cannot safely move arguments from the registers in which they are passed to the stack. Therefore, this hook should return true in general, but false for naked functions. The default implementation always returns true.
```

```c
unsigned HOST_WIDE_INT TARGET_CONST_ANCHOR [Target Hook]
On some architectures it can take multiple instructions to synthesize a constant. If there is another constant already in a register that is close enough in value then it is preferable that the new constant is computed from this register using immediate addition or subtraction. We accomplish this through CSE. Besides the value of the constant we also add a lower and an upper constant anchor to the available expressions. These are then queried when encountering new constants. The anchors are computed by rounding the constant up and down to a multiple of the value of TARGET_CONST_ANCHOR. TARGET_CONST_ANCHOR should be the maximum positive value accepted by immediate-add plus one. We currently assume that the value of TARGET_CONST_ANCHOR is a power of 2. For example, on MIPS, where add-immediate takes a 16-bit signed value, TARGET_CONST_ANCHOR is set to ’0x8000’. The default value is zero, which disables this optimization.
```

```c
unsigned HOST_WIDE_INT TARGET_ASAN_SHADOW_OFFSET (void) [Target Hook]
Return the offset bitwise ored into shifted address to get corresponding Address Sanitizer shadow memory address. NULL if Address Sanitizer is not supported by the target. May return 0 if Address Sanitizer is not supported by a subtarget.
```

```c
unsigned HOST_WIDE_INT TARGET_MEMMODEL_CHECK (unsigned HOST_WIDE_INT val) [Target Hook]
Validate target specific memory model mask bits. When NULL no target specific memory model bits are allowed.
```

```c
unsigned char TARGET_ATOMIC_TEST_AND_SET_TRUEVAL [Target Hook]
This value should be set if the result written by atomic_test_and_set is not exactly 1, i.e. the bool true.
```

```c
bool TARGET_HAS_IFUNC_P (void) [Target Hook]
It returns true if the target supports GNU indirect functions. The support includes the assembler, linker and dynamic linker. The default value of this hook is based on target’s libc.
```
unsigned int TARGET_ATOMIC_ALIGN_FOR_MODE (machine_mode mode) [Target Hook]
If defined, this function returns an appropriate alignment in bits for an atomic object of machine_mode mode. If 0 is returned then the default alignment for the specified mode is used.

void TARGET_ATOMIC_ASSIGN_EXPAND_FENV (tree *hold, tree *clear, tree *update) [Target Hook]
ISO C11 requires atomic compound assignments that may raise floating-point exceptions to raise exceptions corresponding to the arithmetic operation whose result was successfully stored in a compare-and-exchange sequence. This requires code equivalent to calls to feholdexcept, feclearexcept and feupdateenv to be generated at appropriate points in the compare-and-exchange sequence. This hook should set *hold to an expression equivalent to the call to feholdexcept, *clear to an expression equivalent to the call to feclearexcept and *update to an expression equivalent to the call to feupdateenv. The three expressions are NULL_TREE on entry to the hook and may be left as NULL_TREE if no code is required in a particular place. The default implementation leaves all three expressions as NULL_TREE. The __atomic_feraiseexcept function from libatomic may be of use as part of the code generated in *update.

void TARGET_RECORD_OFFLOAD_SYMBOL (tree) [Target Hook]
Used when offloaded functions are seen in the compilation unit and no named sections are available. It is called once for each symbol that must be recorded in the offload function and variable table.

char * TARGET_OFFLOAD_OPTIONS (void) [Target Hook]
Used when writing out the list of options into an LTO file. It should translate any relevant target-specific options (such as the ABI in use) into one of the '-foffload' options that exist as a common interface to express such options. It should return a string containing these options, separated by spaces, which the caller will free.

TARGET_SUPPORTS_WIDE_INT [Macro]
On older ports, large integers are stored in CONST_DOUBLE rtl objects. Newer ports define TARGET_SUPPORTS_WIDE_INT to be nonzero to indicate that large integers are stored in CONST_WIDE_INT rtl objects. The CONST_WIDE_INT allows very large integer constants to be represented. CONST_DOUBLE is limited to twice the size of the host’s HOST_WIDE_INT representation.

Converting a port mostly requires looking for the places where CONST_DOUBLEs are used with VOIDmode and replacing that code with code that accesses CONST_WIDE_INTs. "grep -i const_double" at the port level gets you to 95% of the changes that need to be made. There are a few places that require a deeper look.

- There is no equivalent to hval and lval for CONST_WIDE_INTs. This would be difficult to express in the md language since there are a variable number of elements.

Most ports only check that hval is either 0 or -1 to see if the value is small. As mentioned above, this will no longer be necessary since small constants are always CONST_INT. Of course there are still a few exceptions, the alpha’s constraint used
by the zap instruction certainly requires careful examination by C code. However, all the current code does is pass the hval and lval to C code, so evolving the c code to look at the CONST_WIDE_INT is not really a large change.

- Because there is no standard template that ports use to materialize constants, there is likely to be some futzing that is unique to each port in this code.
- The rtx costs may have to be adjusted to properly account for larger constants that are represented as CONST_WIDE_INT.

All and all it does not take long to convert ports that the maintainer is familiar with.

bool TARGET_HAVE_SPECULATION_SAFE_VALUE (bool active) [Target Hook]
This hook is used to determine the level of target support for __builtin_speculation_safe_value. If called with an argument of false, it returns true if the target has been modified to support this builtin. If called with an argument of true, it returns true if the target requires active mitigation execution might be speculative. The default implementation returns false if the target does not define a pattern named speculation_barrier. Else it returns true for the first case and whether the pattern is enabled for the current compilation for the second case.

For targets that have no processors that can execute instructions speculatively an alternative implementation of this hook is available: simply redefine this hook to speculation_safe_value_not_needed along with your other target hooks.

rtx TARGET_SPECULATION_SAFE_VALUE (machine_mode mode, rtx result, rtx val, rtx failval) [Target Hook]
This target hook can be used to generate a target-specific code sequence that implements the __builtin_speculation_safe_value built-in function. The function must always return val in result in mode mode when the cpu is not executing speculatively, but must never return that when speculating until it is known that the speculation will not be unwound. The hook supports two primary mechanisms for implementing the requirements. The first is to emit a speculation barrier which forces the processor to wait until all prior speculative operations have been resolved; the second is to use a target-specific mechanism that can track the speculation state and to return failval if it can determine that speculation must be unwound at a later time.

The default implementation simply copies val to result and emits a speculation_barrier instruction if that is defined.

void TARGET_RUN_TARGET_SELFTESTS (void) [Target Hook]
If selftests are enabled, run any selftests for this target.

bool TARGET_MEMTAG_CAN_TAG_ADDRESSES () [Target Hook]
True if the backend architecture naturally supports ignoring some region of pointers. This feature means that '-fsanitize=hwaddress' can work.

At preset, this feature does not support address spaces. It also requires Pmode to be the same as ptr_mode.

uint8_t TARGET_MEMTAG_TAG_SIZE () [Target Hook]
Return the size of a tag (in bits) for this platform.

The default returns 8.
uint8_t TARGET_MEMTAG_GRANULE_SIZE ()

Return the size in real memory that each byte in shadow memory refers to. I.e. if a variable is \( X \) bytes long in memory, then this hook should return the value \( Y \) such that the tag in shadow memory spans \( X/Y \) bytes.

Most variables will need to be aligned to this amount since two variables that are neighbors in memory and share a tag granule would need to share the same tag.

The default returns 16.

rtx TARGET_MEMTAG_INSERT_RANDOM_TAG (rtx untagged, rtx target)

Return an RTX representing the value of untagged but with a (possibly) random tag in it. Put that value into target if it is convenient to do so. This function is used to generate a tagged base for the current stack frame.

rtx TARGET_MEMTAG_ADD_TAG (rtx base, poly_int64 addr_offset, uint8_t tag_offset)

Return an RTX that represents the result of adding \( addr\_offset \) to the address in pointer \( base \) and \( tag\_offset \) to the tag in pointer \( base \). The resulting RTX must either be a valid memory address or be able to get put into an operand with force_operand.

Unlike other memtag hooks, this must return an expression and not emit any RTL.

rtx TARGET_MEMTAG_SET_TAG (rtx untagged_base, rtx tag, rtx target)

Return an RTX representing untagged_base but with the tag \( tag \). Try and store this in target if convenient. untagged_base is required to have a zero tag when this hook is called. The default of this hook is to set the top byte of untagged_base to \( tag \).

rtx TARGET_MEMTAG_EXTRACT_TAG (rtx tagged_pointer, rtx target)

Return an RTX representing the tag stored in tagged_pointer. Store the result in target if it is convenient. The default represents the top byte of the original pointer.

rtx TARGET_MEMTAG_UNTAGGED_POINTER (rtx tagged_pointer, rtx target)

Return an RTX representing tagged_pointer with its tag set to zero. Store the result in target if convenient. The default clears the top byte of the original pointer.

HOST_WIDE_INT TARGET_GCOV_TYPE_SIZE (void)

Returns the gcov type size in bits. This type is used for example for counters incremented by profiling and code-coverage events. The default value is 64, if the type size of long long is greater than 32, otherwise the default value is 32. A 64-bit type is recommended to avoid overflows of the counters. If the ‘-fprofile-update=atomic’ is used, then the counters are incremented using atomic operations. Targets not supporting 64-bit atomic operations may override the default value and request a 32-bit type.
19 Host Configuration

Most details about the machine and system on which the compiler is actually running are detected by the configure script. Some things are impossible for configure to detect; these are described in two ways, either by macros defined in a file named ‘xm-machine.h’ or by hook functions in the file specified by the out_host_hook_obj variable in ‘config.gcc’. (The intention is that very few hosts will need a header file but nearly every fully supported host will need to override some hooks.)

If you need to define only a few macros, and they have simple definitions, consider using the xm_defines variable in your ‘config.gcc’ entry instead of creating a host configuration header. See Section 6.3.2.2 [System Config], page 65.

19.1 Host Common

Some things are just not portable, even between similar operating systems, and are too difficult for autoconf to detect. They get implemented using hook functions in the file specified by the host_hook_obj variable in ‘config.gcc’.

void HOST_HOOKS_EXTRA_SIGNALS (void) [Host Hook]
This host hook is used to set up handling for extra signals. The most common thing to do in this hook is to detect stack overflow.

void * HOST_HOOKS_GT_PCH_GET_ADDRESS (size_t size, int fd) [Host Hook]
This host hook returns the address of some space that is likely to be free in some subsequent invocation of the compiler. We intend to load the PCH data at this address such that the data need not be relocated. The area should be able to hold size bytes. If the host uses mmap, fd is an open file descriptor that can be used for probing.

int HOST_HOOKS_GT_PCH_USE_ADDRESS (void * address, size_t size, int fd, size_t offset) [Host Hook]
This host hook is called when a PCH file is about to be loaded. We want to load size bytes from fd at offset into memory at address. The given address will be the result of a previous invocation of HOST_HOOKS_GT_PCH_GET_ADDRESS. Return −1 if we couldn’t allocate size bytes at address. Return 0 if the memory is allocated but the data is not loaded. Return 1 if the hook has performed everything.

If the implementation uses reserved address space, free any reserved space beyond size, regardless of the return value. If no PCH will be loaded, this hook may be called with size zero, in which case all reserved address space should be freed.

Do not try to handle values of address that could not have been returned by this executable; just return −1. Such values usually indicate an out-of-date PCH file (built by some other GCC executable), and such a PCH file won’t work.

size_t HOST_HOOKS_GT_PCH_ALLOC_GRANULARITY (void); [Host Hook]
This host hook returns the alignment required for allocating virtual memory. Usually this is the same as getpagesize, but on some hosts the alignment for reserving memory differs from the pagesize for committing memory.
19.2 Host Filesystem

GCC needs to know a number of things about the semantics of the host machine’s filesystem. Filesystems with Unix and MS-DOS semantics are automatically detected. For other systems, you can define the following macros in ‘xm-machine.h’.

HAVE_DOS_BASED_FILE_SYSTEM
This macro is automatically defined by ‘system.h’ if the host file system obeys the semantics defined by MS-DOS instead of Unix. DOS file systems are case insensitive, file specifications may begin with a drive letter, and both forward slash and backslash (‘/’ and ‘\’) are directory separators.

DIR_SEPARATOR
DIR_SEPARATOR_2
If defined, these macros expand to character constants specifying separators for directory names within a file specification. ‘system.h’ will automatically give them appropriate values on Unix and MS-DOS file systems. If your file system is neither of these, define one or both appropriately in ‘xm-machine.h’.

However, operating systems like VMS, where constructing a pathname is more complicated than just stringing together directory names separated by a special character, should not define either of these macros.

PATH_SEPARATOR
If defined, this macro should expand to a character constant specifying the separator for elements of search paths. The default value is a colon (‘:’). DOS-based systems usually, but not always, use semicolon (‘;’).

VMS
Define this macro if the host system is VMS.

HOST_OBJECT_SUFFIX
Define this macro to be a C string representing the suffix for object files on your host machine. If you do not define this macro, GCC will use ‘.o’ as the suffix for object files.

HOST_EXECUTABLE_SUFFIX
Define this macro to be a C string representing the suffix for executable files on your host machine. If you do not define this macro, GCC will use the null string as the suffix for executable files.

HOST_BIT_BUCKET
A pathname defined by the host operating system, which can be opened as a file and written to, but all the information written is discarded. This is commonly known as a bit bucket or null device. If you do not define this macro, GCC will use ‘/dev/null’ as the bit bucket. If the host does not support a bit bucket, define this macro to an invalid filename.

UPDATE_PATH_HOST_CANONICALIZE (path)
If defined, a C statement (sans semicolon) that performs host-dependent canonicalization when a path used in a compilation driver or preprocessor is canonicalized. path is a malloc-ed path to be canonicalized. If the C statement does canonicalize path into a different buffer, the old path should be freed and the new buffer should have been allocated with malloc.
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DUMPFILE_FORMAT
Definition: This macro is a C string representing the format to use for constructing the index part of debugging dump file names. The resultant string must fit in fifteen bytes. The full filename will be the concatenation of: the prefix of the assembler file name, the string resulting from applying this format to an index number, and a string unique to each dump file kind, e.g. `rtl`.

If you do not define this macro, GCC will use `.%02d.'. You should define this macro if using the default will create an invalid file name.

DELETE_IF_ORDINARY
Definition: This macro is a C statement (sans semicolon) that performs host-dependent removal of ordinary temp files in the compilation driver.

If you do not define this macro, GCC will use the default version. You should define this macro if the default version does not reliably remove the temp file as, for example, on VMS which allows multiple versions of a file.

HOST_LACKS_INODE_NUMBERS
Definition: This macro is defined if the host filesystem does not report meaningful inode numbers in struct stat.

19.3 Host Misc

FATAL_EXIT_CODE
Definition: A C expression for the status code to be returned when the compiler exits after serious errors. The default is the system-provided macro `EXIT_FAILURE`, or `1` if the system doesn’t define that macro. Define this macro only if these defaults are incorrect.

SUCCESS_EXIT_CODE
Definition: A C expression for the status code to be returned when the compiler exits without serious errors. (Warnings are not serious errors.) The default is the system-provided macro `EXIT_SUCCESS`, or `0` if the system doesn’t define that macro. Define this macro only if these defaults are incorrect.

USE_C_ALLOCA
Definition: Define this macro if GCC should use the C implementation of `alloca` provided by `libiberty.a`. This only affects how some parts of the compiler itself allocate memory. It does not change code generation.

When GCC is built with a compiler other than itself, the C `alloca` is always used. This is because most other implementations have serious bugs. You should define this macro only on a system where no stack-based `alloca` can possibly work. For instance, if a system has a small limit on the size of the stack, GCC’s `builtin alloca` will not work reliably.

COLLECT2_HOST_INITIALIZATION
Definition: If defined, a C statement (sans semicolon) that performs host-dependent initialization when collect2 is being initialized.

GCC_DRIVER_HOST_INITIALIZATION
Definition: If defined, a C statement (sans semicolon) that performs host-dependent initialization when a compilation driver is being initialized.
HOST_LONG_LONG_FORMAT
If defined, the string used to indicate an argument of type long long to functions like printf. The default value is "ll".

HOST_LONG_FORMAT
If defined, the string used to indicate an argument of type long to functions like printf. The default value is "l".

HOST_PTR_PRINTF
If defined, the string used to indicate an argument of type void * to functions like printf. The default value is "%p".

In addition, if configure generates an incorrect definition of any of the macros in ‘auto-host.h’, you can override that definition in a host configuration header. If you need to do this, first see if it is possible to fix configure.
20 Makefile Fragments

When you configure GCC using the `configure` script, it will construct the file `Makefile` from the template file `Makefile.in`. When it does this, it can incorporate makefile fragments from the `config` directory. These are used to set Makefile parameters that are not amenable to being calculated by autoconf. The list of fragments to incorporate is set by `config.gcc` (and occasionally `config.build` and `config.host`); See Section 6.3.2.2 [System Config], page 65.

Fragments are named either `t-target` or `x-host`, depending on whether they are relevant to configuring GCC to produce code for a particular target, or to configuring GCC to run on a particular host. Here `target` and `host` are mnemonics which usually have some relationship to the canonical system name, but no formal connection.

If these files do not exist, it means nothing needs to be added for a given target or host. Most targets need a few `t-target` fragments, but needing `x-host` fragments is rare.

20.1 Target Makefile Fragments

Target makefile fragments can set these Makefile variables.

**LIBGCC2_CFLAGS**
Compiler flags to use when compiling `libgcc2.c`.

**LIB2FUNCS_EXTRA**
A list of source file names to be compiled or assembled and inserted into `libgcc.a`.

**CRTSTUFF_T_CFLAGS**
Special flags used when compiling `crtstuff.c`. See Section 18.20.5 [Initialization], page 630.

**CRTSTUFF_T_CFLAGS_S**
Special flags used when compiling `crtstuff.c` for shared linking. Used if you use `crtbeginS.o` and `crtendS.o` in `EXTRA-PARTS`. See Section 18.20.5 [Initialization], page 630.

**MULTILIB_OPTIONS**
For some targets, invoking GCC in different ways produces objects that cannot be linked together. For example, for some targets GCC produces both big and little endian code. For these targets, you must arrange for multiple versions of `libgcc.a` to be compiled, one for each set of incompatible options. When GCC invokes the linker, it arranges to link in the right version of `libgcc.a`, based on the command line options used.

For some targets, invoking GCC in different ways produces objects that cannot be linked together. For example, for some targets GCC produces both big and little endian code. For these targets, you must arrange for multiple versions of `libgcc.a` to be compiled, one for each set of incompatible options. When GCC invokes the linker, it arranges to link in the right version of `libgcc.a`, based on the command line options used.

The **MULTILIB_OPTIONS** macro lists the set of options for which special versions of `libgcc.a` must be built. Write options that are mutually incompatible side by side, separated by a slash. Write options that may be used together separated by a space. The build procedure will build all combinations of compatible options.

For example, if you set **MULTILIB_OPTIONS** to `m68000/m68020 msoft-float`, `Makefile` will build special versions of `libgcc.a` using the following sets of
options: `-m68000`, `-m68020`, `-msoft-float`, `-m68000 -msoft-float`, and `-m68020 -msoft-float`.

**MULTILIB_DIRNAMES**

If `MULTILIB_OPTIONS` is used, this variable specifies the directory names that should be used to hold the various libraries. Write one element in `MULTILIB_DIRNAMES` for each element in `MULTILIB_OPTIONS`. If `MULTILIB_DIRNAMES` is not used, the default value will be `MULTILIB_OPTIONS`, with all slashes treated as spaces.

`MULTILIB_DIRNAMES` describes the multilib directories using GCC conventions and is applied to directories that are part of the GCC installation. When multilib-enabled, the compiler will add a subdirectory of the form `prefix/multilib` before each directory in the search path for libraries and crt files.

For example, if `MULTILIB_OPTIONS` is set to `m68000/m68020 msoft-float`, then the default value of `MULTILIB_DIRNAMES` is `m68000 m68020 msoft-float`. You may specify a different value if you desire a different set of directory names.

**MULTILIB_MATCHES**

Sometimes the same option may be written in two different ways. If an option is listed in `MULTILIB_OPTIONS`, GCC needs to know about any synonyms. In that case, set `MULTILIB_MATCHES` to a list of items of the form `option=option` to describe all relevant synonyms. For example, `m68000=mc68000 m68020=mc68020`.

**MULTILIB_EXCEPTIONS**

Sometimes when there are multiple sets of `MULTILIB_OPTIONS` being specified, there are combinations that should not be built. In that case, set `MULTILIB_EXCEPTIONS` to be all of the switch exceptions in shell case syntax that should not be built.

For example the ARM processor cannot execute both hardware floating point instructions and the reduced size THUMB instructions at the same time, so there is no need to build libraries with both of these options enabled. Therefore `MULTILIB_EXCEPTIONS` is set to:

```
*mthumb/*mhard-float*
```

**MULTILIB_REQUIRED**

Sometimes when there are only a few combinations are required, it would be a big effort to come up with a `MULTILIB_EXCEPTIONS` list to cover all undesired ones. In such a case, just listing all the required combinations in `MULTILIB_REQUIRED` would be more straightforward.

The way to specify the entries in `MULTILIB_REQUIRED` is same with the way used for `MULTILIB_EXCEPTIONS`, only this time what are required will be specified. Suppose there are multiple sets of `MULTILIB_OPTIONS` and only two combinations are required, one for ARMv7-M and one for ARMv7-R with hard floating-point ABI and FPU, the `MULTILIB_REQUIRED` can be set to:

```
MULTILIB_REQUIRED = mthumb/march=armv7-m
MULTILIB_REQUIRED += march=armv7-r/mfloat-abi=hard/mfpu=vfpv3-d16
```
The **MULTILIB_REQUIRED** can be used together with **MULTILIB_EXCEPTIONS**.

The option combinations generated from **MULTILIB_OPTIONS** will be filtered by **MULTILIB_EXCEPTIONS** and then by **MULTILIB_REQUIRED**.

**MULTILIB_REUSE**

Sometimes it is desirable to reuse one existing multilib for different sets of options. Such kind of reuse can minimize the number of multilib variants. And for some targets it is better to reuse an existing multilib than to fallback to default multilib when there is no corresponding multilib. This can be done by adding reuse rules to **MULTILIB_REUSE**.

A reuse rule is comprised of two parts connected by equality sign. The left part is the option set used to build multilib and the right part is the option set that will reuse this multilib. Both parts should only use options specified in **MULTILIB_OPTIONS** and the equality signs found in options name should be replaced with periods. An explicit period in the rule can be escaped by preceding it with a backslash. The order of options in the left part matters and should be same with those specified in **MULTILIB_REQUIRED** or aligned with the order in **MULTILIB_OPTIONS**. There is no such limitation for options in the right part as we don’t build multilib from them.

**MULTILIB_REUSE** is different from **MULTILIB_MATCHES** in that it sets up relations between two option sets rather than two options. Here is an example to demo how we reuse libraries built in Thumb mode for applications built in ARM mode:

```
MULTILIB_REUSE = mthumb/march.armv7-r=marm/march.armv7-r
```

Before the advent of **MULTILIB_REUSE**, GCC select multilib by comparing command line options with options used to build multilib. The **MULTILIB_REUSE** is complementary to that way. Only when the original comparison matches nothing it will work to see if it is OK to reuse some existing multilib.

**MULTILIB_EXTRA_OPTS**

Sometimes it is desirable that when building multiple versions of ‘libgcc.a’ certain options should always be passed on to the compiler. In that case, set **MULTILIB_EXTRA_OPTS** to be the list of options to be used for all builds. If you set this, you should probably set **CRTSTUFF_T_CFLAGS** to a dash followed by it.

**MULTILIB_OSDIRNAMES**

If **MULTILIB_OPTIONS** is used, this variable specifies a list of subdirectory names, that are used to modify the search path depending on the chosen multilib. Unlike **MULTILIB_DIRNAMES**, **MULTILIB_OSDIRNAMES** describes the multilib directories using operating systems conventions, and is applied to the directories such as `lib` or those in the **LIBRARY_PATH** environment variable. The format is either the same as of **MULTILIB_DIRNAMES**, or a set of mappings. When it is the same as **MULTILIB_DIRNAMES**, it describes the multilib directories using operating system conventions, rather than GCC conventions. When it is a set of mappings of the form `gccdir=osdir`, the left side gives the GCC convention and the right gives the equivalent OS defined location. If the `osdir` part begins with a ‘!’, GCC will not search in the non-multilib directory and use exclusively the multilib directory. Otherwise, the compiler will examine the search path for
libraries and crt files twice; the first time it will add _multilib_ to each directory in the search path, the second it will not.

For configurations that support both multilib and multiarch, _MULTILIB_OSDIRNAMES_ also encodes the multiarch name, thus subsuming _MULTIARCH_DIRNAME_. The multiarch name is appended to each directory name, separated by a colon (e.g. `../lib32:i386-linux-gnu`).

Each multiarch subdirectory will be searched before the corresponding OS multilib directory, for example `/lib/i386-linux-gnu` before `/lib/../../lib32`. The multiarch name will also be used to modify the system header search path, as explained for _MULTIARCH_DIRNAME_.

**MULTIARCH_DIRNAME**

This variable specifies the multiarch name for configurations that are multiarch-enabled but not multilibbed configurations.

The multiarch name is used to augment the search path for libraries, crt files and system header files with additional locations. The compiler will add a multiarch subdirectory of the form `prefix/multiarch` before each directory in the library and crt search path. It will also add two directories `LOCAL_INCLUDE_DIR/multiarch` and `NATIVE_SYSTEM_HEADER_DIR/multiarch` to the system header search path, respectively before `LOCAL_INCLUDE_DIR` and `NATIVE_SYSTEM_HEADER_DIR`.

_MULTIARCH_DIRNAME_ is not used for configurations that support both multilib and multiarch. In that case, multiarch names are encoded in _MULTILIB_OSDIRNAMES_ instead.

More documentation about multiarch can be found at [https://wiki.debian.org/Multiarch](https://wiki.debian.org/Multiarch).

**SPECS**

Unfortunately, setting _MULTILIB_EXTRA_OPTS_ is not enough, since it does not affect the build of target libraries, at least not the build of the default multilib. One possible work-around is to use _DRIVER_SELF_SPECS_ to bring options from the ‘specs’ file as if they had been passed in the compiler driver command line. However, you don’t want to be adding these options after the toolchain is installed, so you can instead tweak the ‘specs’ file that will be used during the toolchain build, while you still install the original, built-in ‘specs’. The trick is to set _SPECS_ to some other filename (say ‘specs.install’), that will then be created out of the built-in specs, and introduce a ‘Makefile’ rule to generate the ‘specs’ file that’s going to be used at build time out of your ‘specs.install’.

**T_CFLAGS**

These are extra flags to pass to the C compiler. They are used both when building GCC, and when compiling things with the just-built GCC. This variable is deprecated and should not be used.

### 20.2 Host Makefile Fragments

The use of ‘x-host’ fragments is discouraged. You should only use it for makefile dependencies.
21 collect2

GCC uses a utility called collect2 on nearly all systems to arrange to call various initialization functions at start time.

The program collect2 works by linking the program once and looking through the linker output file for symbols with particular names indicating they are constructor functions. If it finds any, it creates a new temporary ‘.c’ file containing a table of them, compiles it, and links the program a second time including that file.

The actual calls to the constructors are carried out by a subroutine called __main, which is called (automatically) at the beginning of the body of main (provided main was compiled with GNU CC). Calling __main is necessary, even when compiling C code, to allow linking C and C++ object code together. (If you use ‘-nostdlib’, you get an unresolved reference to __main, since it’s defined in the standard GCC library. Include ‘-lgcc’ at the end of your compiler command line to resolve this reference.)

The program collect2 is installed as ld in the directory where the passes of the compiler are installed. When collect2 needs to find the real ld, it tries the following file names:

- a hard coded linker file name, if GCC was configured with the ‘--with-ld’ option.
- ‘real-ld’ in the directories listed in the compiler’s search directories.
- ‘real-ld’ in the directories listed in the environment variable PATH.
- The file specified in the REAL_LD_FILE_NAME configuration macro, if specified.
- ‘ld’ in the compiler’s search directories, except that collect2 will not execute itself recursively.
- ‘ld’ in PATH.

“The compiler’s search directories” means all the directories where gcc searches for passes of the compiler. This includes directories that you specify with ‘-B’.

Cross-compilers search a little differently:

- ‘real-ld’ in the compiler’s search directories.
- ‘target-real-ld’ in PATH.
- The file specified in the REAL_LD_FILE_NAME configuration macro, if specified.
- ‘ld’ in the compiler’s search directories.
- ‘target-ld’ in PATH.

collect2 explicitly avoids running ld using the file name under which collect2 itself was invoked. In fact, it remembers up a list of such names—in case one copy of collect2 finds another copy (or version) of collect2 installed as ld in a second place in the search path.

collect2 searches for the utilities nm and strip using the same algorithm as above for ld.
22 Standard Header File Directories

GCC_INCLUDE_DIR means the same thing for native and cross. It is where GCC stores its private include files, and also where GCC stores the fixed include files. A cross compiled GCC runs fixincludes on the header files in ‘$(tooldir)/include’. (If the cross compilation header files need to be fixed, they must be installed before GCC is built. If the cross compilation header files are already suitable for GCC, nothing special need be done).

GPLUSPLUS_INCLUDE_DIR means the same thing for native and cross. It is where g++ looks first for header files. The C++ library installs only target independent header files in that directory.

LOCAL_INCLUDE_DIR is used only by native compilers. GCC doesn’t install anything there. It is normally ‘/usr/local/include’. This is where local additions to a packaged system should place header files.

CROSS_INCLUDE_DIR is used only by cross compilers. GCC doesn’t install anything there.

TOOL_INCLUDE_DIR is used for both native and cross compilers. It is the place for other packages to install header files that GCC will use. For a cross-compiler, this is the equivalent of ‘/usr/include’. When you build a cross-compiler, fixincludes processes any header files in this directory.
23 Memory Management and Type Information

GCC uses some fairly sophisticated memory management techniques, which involve determining information about GCC’s data structures from GCC’s source code and using this information to perform garbage collection and implement precompiled headers.

A full C++ parser would be too complicated for this task, so a limited subset of C++ is interpreted and special markers are used to determine what parts of the source to look at. All struct, union and template structure declarations that define data structures that are allocated under control of the garbage collector must be marked. All global variables that hold pointers to garbage-collected memory must also be marked. Finally, all global variables that need to be saved and restored by a precompiled header must be marked. (The precompiled header mechanism can only save static variables if they’re scalar. Complex data structures must be allocated in garbage-collected memory to be saved in a precompiled header.)

The full format of a marker is

\[ \text{GTY} ((\text{option} \ [\text{param}], \text{option} \ [\text{param}] \ldots)) \]

but in most cases no options are needed. The outer double parentheses are still necessary, though: GTY(\(())\). Markers can appear:

- In a structure definition, before the open brace;
- In a global variable declaration, after the keyword static or extern; and
- In a structure field definition, before the name of the field.

Here are some examples of marking simple data structures and globals.

```c
struct GTY(\(())\) tag
{
  fields...
};

typedef struct GTY(\(())\) tag
{
  fields...
} *typename;

static GTY(\(())\) struct tag *list; /* points to GC memory */
static GTY(\(())\) int counter; /* save counter in a PCH */
```

The parser understands simple typedefs such as typedef struct tag *name; and typedef int name; These don’t need to be marked.

Since gengtype’s understanding of C++ is limited, there are several constructs and declarations that are not supported inside classes/structures marked for automatic GC code generation. The following C++ constructs produce a gengtype error on structures/classes marked for automatic GC code generation:

- Type definitions inside classes/structures are not supported.
- Enumerations inside classes/structures are not supported.

If you have a class or structure using any of the above constructs, you need to mark that class as GTY ((user)) and provide your own marking routines (see section Section 23.3 [User GC], page 700 for details).

It is always valid to include function definitions inside classes. Those are always ignored by gengtype, as it only cares about data members.
23.1 The Inside of a GTY(())

Sometimes the C code is not enough to fully describe the type structure. Extra information can be provided with GTY options and additional markers. Some options take a parameter, which may be either a string or a type name, depending on the parameter. If an option takes no parameter, it is acceptable either to omit the parameter entirely, or to provide an empty string as a parameter. For example, GTY ((skip)) and GTY ((skip (""))) are equivalent.

When the parameter is a string, often it is a fragment of C code. Four special escapes may be used in these strings, to refer to pieces of the data structure being marked:

- %h: The current structure.
- %1: The structure that immediately contains the current structure.
- %0: The outermost structure that contains the current structure.
- %a: A partial expression of the form [i1][i2]... that indexes the array item currently being marked.

For instance, suppose that you have a structure of the form

```c
struct A {
  ...
};
struct B {
  struct A foo[12];
};
```


As in ordinary C, adjacent strings will be concatenated; this is helpful when you have a complicated expression.

```c
GTY ((chain_next ("TREE_CODE (&%h.generic) == INTEGER_TYPE" " ? TYPE_NEXT_VARIANT (&%h.generic)" " : TREE_CHAIN (&%h.generic)")))
```

The available options are:

- **length ("expression")**
  
  There are two places the type machinery will need to be explicitly told the length of an array of non-atomic objects. The first case is when a structure ends in a variable-length array, like this:

```c
struct GTY(() ) rtvec_def {
  int num_elem; /* number of elements */
  rtx GTY ((length ("%h.num_elem"))) elem[1];
};
```

In this case, the length option is used to override the specified array length (which should usually be 1). The parameter of the option is a fragment of C code that calculates the length.

The second case is when a structure or a global variable contains a pointer to an array, like this:

```c
struct gimple_omp_for_iter * GTY((length ("%h.collapse"))) iter;
```

In this case, `iter` has been allocated by writing something like
x->iter = ggc_alloc_cleared_vec_gimple_omp_for_iter (collapse);

and the collapse provides the length of the field.

This second use of length also works on global variables, like:

static GTY((length("reg_known_value_size"))) rtx *reg_known_value;

Note that the length option is only meant for use with arrays of non-atomic objects, that is, objects that contain pointers pointing to other GTY-managed objects. For other GC-allocated arrays and strings you should use atomic.

skip

If skip is applied to a field, the type machinery will ignore it. This is somewhat dangerous; the only safe use is in a union when one field really isn’t ever used.

for_user

Use this to mark types that need to be marked by user gc routines, but are not referred to in a template argument. So if you have some user gc type T1 and a non user gc type T2 you can give T2 the for_user option so that the marking functions for T1 can call non mangled functions to mark T2.

desc ("expression")
tag ("constant")
default

The type machinery needs to be told which field of a union is currently active. This is done by giving each field a constant tag value, and then specifying a discriminator using desc. The value of the expression given by desc is compared against each tag value, each of which should be different. If no tag is matched, the field marked with default is used if there is one, otherwise no field in the union will be marked.

In the desc option, the “current structure” is the union that it discriminates. Use %1 to mean the structure containing it. There are no escapes available to the tag option, since it is a constant.

For example,

```c
struct GTY(()) tree_binding
{
  struct tree_common common;
  union tree_binding_u {
    tree GTY ((tag ("0"))) scope;
    struct cp_binding_level * GTY ((tag ("1"))) level;
  } GTY ((desc ("BINDING_HAS_LEVEL_P ((tree)&%0)"))) xscope;
  tree value;
};
```

In this example, the value of BINDING_HAS_LEVEL_P when applied to a struct tree_binding * is presumed to be 0 or 1. If 1, the type mechanism will treat the field level as being present and if 0, will treat the field scope as being present.

The desc and tag options can also be used for inheritance to denote which subclass an instance is. See Section 23.2 [Inheritance and GTY], page 700 for more information.
cache

When the cache option is applied to a global variable gt_cache is called on that variable between the mark and sweep phases of garbage collection. The gt_clear_cache function is free to mark blocks as used, or to clear pointers in the variable.

deletable

deletable, when applied to a global variable, indicates that when garbage collection runs, there's no need to mark anything pointed to by this variable, it can just be set to NULL instead. This is used to keep a list of free structures around for re-use.

maybe_undef

When applied to a field, maybe_undef indicates that it’s OK if the structure that this fields points to is never defined, so long as this field is always NULL. This is used to avoid requiring backends to define certain optional structures. It doesn’t work with language frontends.

nested_ptr (type, "to expression", "from expression")

The type machinery expects all pointers to point to the start of an object. Sometimes for abstraction purposes it’s convenient to have a pointer which points inside an object. So long as it’s possible to convert the original object to and from the pointer, such pointers can still be used. type is the type of the original object, the to expression returns the pointer given the original object, and the from expression returns the original object given the pointer. The pointer will be available using the %h escape.

chain_next ("expression")
chain_prev ("expression")

It’s helpful for the type machinery to know if objects are often chained together in long lists; this lets it generate code that uses less stack space by iterating along the list instead of recursing down it. chain_next is an expression for the next item in the list, chain_prev is an expression for the previous item. For singly linked lists, use only chain_next; for doubly linked lists, use both. The machinery requires that taking the next item of the previous item gives the original item. chain_circular is similar to chain_next, but can be used for circular single linked lists.

reorder ("function name")

Some data structures depend on the relative ordering of pointers. If the precompiled header machinery needs to change that ordering, it will call the function referenced by the reorder option, before changing the pointers in the object that’s pointed to by the field the option applies to. The function must take four arguments, with the signature ‘void *, void *, gt_pointer_operator, void *’. The first parameter is a pointer to the structure that contains the object being updated, or the object itself if there is no containing structure. The second parameter is a cookie that should be ignored. The third parameter is a routine that, given a pointer, will
update it to its correct new value. The fourth parameter is a cookie that must be passed to the second parameter.

PCH cannot handle data structures that depend on the absolute values of pointers. reorder functions can be expensive. When possible, it is better to depend on properties of the data, like an ID number or the hash of a string instead.

**atomic**

The `atomic` option can only be used with pointers. It informs the GC machinery that the memory that the pointer points to does not contain any pointers, and hence it should be treated by the GC and PCH machinery as an “atomic” block of memory that does not need to be examined when scanning memory for pointers. In particular, the machinery will not scan that memory for pointers to mark them as reachable (when marking pointers for GC) or to relocate them (when writing a PCH file).

The `atomic` option differs from the `skip` option. `atomic` keeps the memory under Garbage Collection, but makes the GC ignore the contents of the memory. `skip` is more drastic in that it causes the pointer and the memory to be completely ignored by the Garbage Collector. So, memory marked as `atomic` is automatically freed when no longer reachable, while memory marked as `skip` is not.

The `atomic` option must be used with great care, because all sorts of problem can occur if used incorrectly, that is, if the memory the pointer points to does actually contain a pointer.

Here is an example of how to use it:

```c
struct GTY(()) my_struct {
  int number_of_elements;
  unsigned int * GTY ((atomic)) elements;
};
```

In this case, `elements` is a pointer under GC, and the memory it points to needs to be allocated using the Garbage Collector, and will be freed automatically by the Garbage Collector when it is no longer referenced. But the memory that the pointer points to is an array of `unsigned int` elements, and the GC must not try to scan it to find pointers to mark or relocate, which is why it is marked with the `atomic` option.

Note that, currently, global variables cannot be marked with `atomic`; only fields of a struct can. This is a known limitation. It would be useful to be able to mark global pointers with `atomic` to make the PCH machinery aware of them so that they are saved and restored correctly to PCH files.

**special ("name")**

The `special` option is used to mark types that have to be dealt with by special case machinery. The parameter is the name of the special case. See ‘`gengtype.c`’ for further details. Avoid adding new special cases unless there is no other alternative.

**user**
The user option indicates that the code to mark structure fields is completely handled by user-provided routines. See section Section 23.3 [User GC], page 700 for details on what functions need to be provided.

23.2 Support for inheritance

gengtype has some support for simple class hierarchies. You can use this to have gengtype autogenerate marking routines, provided:

- There must be a concrete base class, with a discriminator expression that can be used to identify which subclass an instance is.
- Only single inheritance is used.
- None of the classes within the hierarchy are templates.

If your class hierarchy does not fit in this pattern, you must use Section 23.3 [User GC], page 700 instead.

The base class and its discriminator must be identified using the “desc” option. Each concrete subclass must use the “tag” option to identify which value of the discriminator it corresponds to.

Every class in the hierarchy must have a GTY() marker, as gengtype will only attempt to parse classes that have such a marker\(^1\).

```cpp
class GTY((desc("%h.kind"), tag("0"))) example_base {
  public:
    int kind;
    tree a;
};

class GTY((tag("1"))) some_subclass : public example_base {
  public:
    tree b;
};

class GTY((tag("2"))) some_other_subclass : public example_base {
  public:
    tree c;
};
```

The generated marking routines for the above will contain a “switch” on “kind”, visiting all appropriate fields. For example, if kind is 2, it will cast to “some_other_subclass” and visit fields a, b, and c.

23.3 Support for user-provided GC marking routines

The garbage collector supports types for which no automatic marking code is generated. For these types, the user is required to provide three functions: one to act as a marker for

\(^1\) Classes lacking such a marker will not be identified as being part of the hierarchy, and so the marking routines will not handle them, leading to a assertion failure within the marking routines due to an unknown tag value (assuming that assertions are enabled).
garbage collection, and two functions to act as marker and pointer walker for pre-compiled headers.

Given a structure `struct GTY((user)) my_struct`, the following functions should be defined to mark `my_struct`:

```c
void gt_ggc_mx (my_struct *p)
{
    /* This marks field 'fld'. */
    gt_ggc_mx (p->fld);
}

void gt_pch_nx (my_struct *p)
{
    /* This marks field 'fld'. */
    gt_pch_nx (tp->fld);
}

void gt_pch_nx (my_struct *p, gt_pointer_operator op, void *cookie)
{
    /* For every field 'fld', call the given pointer operator. */
    op (&(tp->fld), cookie);
}
```

In general, each marker \( M \) should call \( M \) for every pointer field in the structure. Fields that are not allocated in GC or are not pointers must be ignored.

For embedded lists (e.g., structures with a `next` or `prev` pointer), the marker must follow the chain and mark every element in it.

Note that the rules for the pointer walker `gt_pch_nx (my_struct *, gt_pointer_operator, void *)` are slightly different. In this case, the operation `op` must be applied to the address of every pointer field.

### 23.3.1 User-provided marking routines for template types

When a template type `TP` is marked with `GTY`, all instances of that type are considered user-provided types. This means that the individual instances of `TP` do not need to be marked with `GTY`. The user needs to provide template functions to mark all the fields of the type.

The following code snippets represent all the functions that need to be provided. Note that type `TP` may reference to more than one type. In these snippets, there is only one type `T`, but there could be more.

```c
template<typename T>
void gt_ggc_mx (TP<T> *tp)
{
    extern void gt_ggc_mx (T&);

    /* This marks field 'fld' of type 'T'. */
    gt_ggc_mx (tp->fld);
}

template<typename T>
void gt_pch_nx (TP<T> *tp)
{
    extern void gt_pch_nx (T&);

    /* This marks field 'fld' of type 'T'. */
    gt_pch_nx (tp->fld);
}
Support for user-defined types is currently limited. The following restrictions apply:

1. Type TP and all the argument types T must be marked with GTY.
2. Type TP can only have type names in its argument list.
3. The pointer walker functions are different for TP<T> and TP<T *>. In the case of TP<T>, references to T must be handled by calling gt_pch_nx (which will, in turn, walk all the pointers inside fields of T). In the case of TP<T *>, references to T * must be handled by calling the op function on the address of the pointer (see the code snippets above).

### 23.4 Marking Roots for the Garbage Collector

In addition to keeping track of types, the type machinery also locates the global variables (roots) that the garbage collector starts at. Roots must be declared using one of the following syntaxes:

- `extern GTY([[options]]) type name;`
- `static GTY([[options]]) type name;`

The syntax

- `GTY([[options]]) type name;`

is not accepted. There should be an `extern` declaration of such a variable in a header somewhere—mark that, not the definition. Or, if the variable is only used in one file, make it `static`.

### 23.5 Source Files Containing Type Information

Whenever you add GTY markers to a source file that previously had none, or create a new source file containing GTY markers, there are three things you need to do:

1. You need to add the file to the list of source files the type machinery scans. There are four cases:
   a. For a back-end file, this is usually done automatically; if not, you should add it to `target_gtf files` in the appropriate port’s entries in `config.gcc`. 
b. For files shared by all front ends, add the filename to the \texttt{GTFILES} variable in ‘Makefile.in’.

c. For files that are part of one front end, add the filename to the \texttt{gtfiles} variable defined in the appropriate ‘config-lang.in’. Headers should appear before non-headers in this list.

d. For files that are part of some but not all front ends, add the filename to the \texttt{gtfiles} variable of all the front ends that use it.

2. If the file was a header file, you’ll need to check that it’s included in the right place to be visible to the generated files. For a back-end header file, this should be done automatically. For a front-end header file, it needs to be included by the same file that includes ‘gtype-lang.h’. For other header files, it needs to be included in ‘gtype-desc.c’, which is a generated file, so add it to \texttt{iﬁles} in \texttt{open_base_file} in ‘gengtype.c’.

For source files that aren’t header files, the machinery will generate a header file that should be included in the source file you just changed. The file will be called ‘gt-path.h’ where \texttt{path} is the pathname relative to the ‘gcc’ directory with slashes replaced by -, so for example the header file to be included in ‘cp/parser.c’ is called ‘gt-cp-parser.h’. The generated header file should be included after everything else in the source file.

For language frontends, there is another file that needs to be included somewhere. It will be called ‘gtype-lang.h’, where \texttt{lang} is the name of the subdirectory the language is contained in.

Plugins can add additional root tables. Run the \texttt{gengtype} utility in plugin mode as \texttt{gengtype -P pluginout.h source-dir file-list plugin*.c} with your plugin files \texttt{plugin*.c} using GTY to generate the \texttt{pluginout.h} file. The GCC build tree is needed to be present in that mode.

23.6 How to invoke the garbage collector

The GCC garbage collector GGC is only invoked explicitly. In contrast with many other garbage collectors, it is not implicitly invoked by allocation routines when a lot of memory has been consumed. So the only way to have GGC reclaim storage is to call the \texttt{ggc\_collect} function explicitly. With \texttt{mode GGC\_COLLECT\_FORCE} or otherwise (default \texttt{GGC\_COLLECT\_HEURISTIC}) when the internal heuristic decides to collect, this call is potentially an expensive operation, as it may have to scan the entire heap. Beware that local variables (on the GCC call stack) are not followed by such an invocation (as many other garbage collectors do): you should reference all your data from static or external GTY-ed variables, and it is advised to call \texttt{ggc\_collect} with a shallow call stack. The GGC is an exact mark and sweep garbage collector (so it does not scan the call stack for pointers). In practice GCC passes don’t often call \texttt{ggc\_collect} themselves, because it is called by the pass manager between passes.

At the time of the \texttt{ggc\_collect} call all pointers in the GC-marked structures must be valid or NULL. In practice this means that there should not be uninitialized pointer fields in the structures even if your code never reads or writes those fields at a particular instance. One way to ensure this is to use cleared versions of allocators unless all the fields are initialized manually immediately after allocation.
23.7 Troubleshooting the garbage collector

With the current garbage collector implementation, most issues should show up as GCC compilation errors. Some of the most commonly encountered issues are described below.

- Gengtype does not produce allocators for a GTY-marked type. Gengtype checks if there is at least one possible path from GC roots to at least one instance of each type before outputting allocators. If there is no such path, the GTY markers will be ignored and no allocators will be output. Solve this by making sure that there exists at least one such path. If creating it is unfeasible or raises a “code smell”, consider if you really must use GC for allocating such type.
- Link-time errors about undefined gt_ggc_r_foo_bar and similarly-named symbols. Check if your ‘foo_bar’ source file has #include "gt-foo_bar.h" as its very last line.
24 Plugins

GCC plugins are loadable modules that provide extra features to the compiler. Like GCC itself they can be distributed in source and binary forms.

GCC plugins provide developers with a rich subset of the GCC API to allow them to extend GCC as they see fit. Whether it is writing an additional optimization pass, transforming code, or analyzing information, plugins can be quite useful.

24.1 Loading Plugins

Plugins are supported on platforms that support `-ldl -rdynamic` as well as Windows/MinGW. They are loaded by the compiler using `dlopen` or equivalent and invoked at pre-determined locations in the compilation process.

Plugins are loaded with

`-fplugin=/path/to/name.ext` `-fplugin-arg-name-key1[=value1]`

Where `name` is the plugin name and `ext` is the platform-specific dynamic library extension. It should be `dll` on Windows/MinGW, `dylib` on Darwin/Mac OS X, and so on all other platforms. The plugin arguments are parsed by GCC and passed to respective plugins as key-value pairs. Multiple plugins can be invoked by specifying multiple `-fplugin` arguments.

A plugin can be simply given by its short name (no dots or slashes). When simply passing `-fplugin=name`, the plugin is loaded from the `plugin` directory, so `-fplugin=name` is the same as `-fplugin=’gcc -print-file-name=plugin’/name.ext`, using backquote shell syntax to query the `plugin` directory.

24.2 Plugin API

Plugins are activated by the compiler at specific events as defined in `gcc-plugin.h`. For each event of interest, the plugin should call `register_callback` specifying the name of the event and address of the callback function that will handle that event.

The header `gcc-plugin.h` must be the first gcc header to be included.

24.2.1 Plugin license check

Every plugin should define the global symbol `plugin_is_GPL_compatible` to assert that it has been licensed under a GPL-compatible license. If this symbol does not exist, the compiler will emit a fatal error and exit with the error message:

```
fatal error: plugin name is not licensed under a GPL-compatible license
name: undefined symbol: plugin_is_GPL_compatible
compilation terminated
```

The declared type of the symbol should be `int`, to match a forward declaration in `gcc-plugin.h` that suppresses C++ mangling. It does not need to be in any allocated section, though. The compiler merely asserts that the symbol exists in the global scope. Something like this is enough:

```
text plugin_is_GPL_compatible;
```
24.2.2 Plugin initialization

Every plugin should export a function called `plugin_init` that is called right after the plugin is loaded. This function is responsible for registering all the callbacks required by the plugin and do any other required initialization.

This function is called from `compile_file` right before invoking the parser. The arguments to `plugin_init` are:

- **plugin_info**: Plugin invocation information.
- **version**: GCC version.

The `plugin_info` struct is defined as follows:

```c
struct plugin_name_args
{
    char *base_name;       /* Short name of the plugin
                          (filename without .so suffix). */
    const char *full_name; /* Path to the plugin as specified with
                          -fplugin=. */
    int argc;              /* Number of arguments specified with
                          -fplugin-arg-.... */
    struct plugin_argument *argv; /* Array of ARGC key-value pairs. */
    const char *version;   /* Version string provided by plugin. */
    const char *help;      /* Help string provided by plugin. */
}
```

If initialization fails, `plugin_init` must return a non-zero value. Otherwise, it should return 0.

The version of the GCC compiler loading the plugin is described by the following structure:

```c
struct plugin_gcc_version
{
    const char *basever;
    const char *datestamp;
    const char *devphase;
    const char *revision;
    const char *configuration_arguments;
};
```

The function `plugin_default_version_check` takes two pointers to such structure and compare them field by field. It can be used by the plugin’s `plugin_init` function.

The version of GCC used to compile the plugin can be found in the symbol `gcc_version` defined in the header `plugin-version.h`. The recommended version check to perform looks like

```c
#include "plugin-version.h"
...

int plugin_init (struct plugin_name_args *plugin_info,
                  struct plugin_gcc_version *version)
{
    if (!plugin_default_version_check (version, &gcc_version))
        return 1;
}
```

but you can also check the individual fields if you want a less strict check.
24.2.3 Plugin callbacks

Callback functions have the following prototype:

/* The prototype for a plugin callback function. 
   gcc_data - event-specific data provided by GCC 
   user_data - plugin-specific data provided by the plug-in. */
typedef void (*plugin_callback_func)(void *gcc_data, void *user_data);

Callbacks can be invoked at the following pre-determined events:

enum plugin_event {
    PLUGIN_START_PARSE_FUNCTION, /* Called before parsing the body of a function. */
    PLUGIN_FINISH_PARSE_FUNCTION, /* After finishing parsing a function. */
    PLUGIN_PASS_MANAGER_SETUP, /* To hook into pass manager. */
    PLUGIN_FINISH_TYPE, /* After finishing parsing a type. */
    PLUGIN_FINISH_DECL, /* After finishing parsing a declaration. */
    PLUGIN_FINISH_UNIT, /* Useful for summary processing. */
    PLUGIN_PRE_GENERICIZE, /* Allows to see low level AST in C and C++ frontends. */
    PLUGIN_FINISH, /* Called before GCC exits. */
    PLUGIN_INFO, /* Information about the plugin. */
    PLUGIN_GCC_START, /* Called at start of GCC Garbage Collection. */
    PLUGIN_GCC_MARKING, /* Extend the GCC marking. */
    PLUGIN_GCC_END, /* Called at end of GCC. */
    PLUGIN_REGISTER_GGC_ROOTS, /* Register an extra GGC root table. */
    PLUGIN_ATTRIBUTES, /* Called during attribute registration */
    PLUGIN_START_UNIT, /* Called before processing a translation unit. */
    PLUGIN_PRAGMAS, /* Called during pragma registration. */
    PLUGIN_ALL_PASSES_START, /* Called before first pass from all_passes. */
    PLUGIN_ALL_PASSES_END, /* Called after last pass from all_passes. */
    PLUGIN_ALL_IPA_PASSES_START, /* Called after last ipa pass. */
    PLUGIN_ALL_IPA_PASSES_END, /* Allows to override pass gate decision for current_pass. */
    PLUGIN_OVERRIDE_GATE, /* Called before executing a pass. */
    PLUGIN_PASS_EXECUTION, /* Called before executing subpasses of a GIMPLE_PASS in 
                             execute_ipa_pass_list. */
    PLUGIN_EARLY_GIMPLE_PASSES_START, /* Called after executing subpasses of a GIMPLE_PASS in 
                                       execute_ipa_pass_list. */
    PLUGIN_EARLY_GIMPLE_PASSES_END, /* Called when a pass is first instantiated. */
    PLUGIN_NEW_PASS, /* Called when a file is #include-d or given via the #line directive. 
                      This could happen many times. The event data is the included file path, 
                      as a const char* pointer. */
    PLUGIN_INCLUDE_FILE, /* Called when -fanalyzer starts. The event data is an 
                           ana::plugin_analyzer_init_iface *. */
    PLUGIN_ANALYZER_INIT, PLUGIN_EVENT_FIRST_DYNAMIC /* Dummy event used for indexing callback 
                               array. */
};
In addition, plugins can also look up the enumerator of a named event, and / or generate new events dynamically, by calling the function `get_named_event_id`.

To register a callback, the plugin calls `register_callback` with the arguments:

- `char *name`: Plugin name.
- `int event`: The event code.
- `plugin_callback_func callback`: The function that handles event.
- `void *user_data`: Pointer to plugin-specific data.

For the `PLUGIN_PASS_MANAGER_SETUP`, `PLUGIN_INFO`, and `PLUGIN_REGISTER_GGC_ROOTS` pseudo-events the `callback` should be null, and the `user_data` is specific.

When the `PLUGIN_PRAGMAS` event is triggered (with a null pointer as data from GCC), plugins may register their own pragmas. Notice that pragmas are not available from ‘lto1’, so plugins used with `-flto` option to GCC during link-time optimization cannot use pragmas and do not even see functions like `c_registerPragma` or `pragma_lex`.

The `PLUGIN_INCLUDE_FILE` event, with a `const char*` file path as GCC data, is triggered for processing of `#include` or `#line` directives.

The `PLUGIN_FINISH` event is the last time that plugins can call GCC functions, notably emit diagnostics with `warning`, `error` etc.

### 24.3 Interacting with the pass manager

There needs to be a way to add/reorder/remove passes dynamically. This is useful for both analysis plugins (plugging in after a certain pass such as CFG or an IPA pass) and optimization plugins.

Basic support for inserting new passes or replacing existing passes is provided. A plugin registers a new pass with GCC by calling `register_callback` with the `PLUGIN_PASS_MANAGER_SETUP` event and a pointer to a `struct register_pass_info` object defined as follows:

```c
enum pass_positioning_ops
{
    PASS_POS_INSERT_AFTER, // Insert after the reference pass.
    PASS_POS_INSERT_BEFORE, // Insert before the reference pass.
    PASS_POS_REPLACE        // Replace the reference pass.
};

struct register_pass_info
{
    struct opt_pass *pass;    /* New pass provided by the plugin. */
    const char *reference_pass_name; /* Name of the reference pass for hooking up the new pass. */
    int ref_pass_instance_number; /* Insert the pass at the specified instance number of the reference pass. */
    enum pass_positioning_ops pos_op; /* how to insert the new pass. */
};
```

/* Sample plugin code that registers a new pass. */
int
24.4 Interacting with the GCC Garbage Collector

Some plugins may want to be informed when GGC (the GCC Garbage Collector) is running. They can register callbacks for the PLUGIN_GGC_START and PLUGIN_GGC_END events (for which the callback is called with a null gcc_data) to be notified of the start or end of the GCC garbage collection.

Some plugins may need to have GGC mark additional data. This can be done by registering a callback (called with a null gcc_data) for the PLUGIN_GGC_MARKING event. Such callbacks can call the gg_set_mark routine, preferably through the gg_mark macro (and conversely, these routines should usually not be used in plugins outside of the PLUGIN_GGC_MARKING event). Plugins that wish to hold weak references to gc data may also use this event to drop weak references when the object is about to be collected. The gg_marked_p function can be used to tell if an object is marked, or is about to be collected. The gt_clear_cache overloads which some types define may also be of use in managing weak references.

Some plugins may need to add extra GGC root tables, e.g. to handle their own GTY-ed data. This can be done with the PLUGIN_REGISTER_GGC_ROOTS pseudo-event with a null callback and the extra root table (of type struct ggc_root_tab*) as user_data. Running the gengtype -p source-dir file-list plugin*.c ... utility generates these extra root tables.

You should understand the details of memory management inside GCC before using PLUGIN_GGC_MARKING or PLUGIN_REGISTER_GGC_ROOTS.

24.5 Giving information about a plugin

A plugin should give some information to the user about itself. This uses the following structure:

```c
struct plugin_info
{
  const char *version;
  const char *help;
};
```

Such a structure is passed as the user_data by the plugin’s init routine using register_callback with the PLUGIN_INFO pseudo-event and a null callback.
24.6 Registering custom attributes or pragmas

For analysis (or other) purposes it is useful to be able to add custom attributes or pragmas.

The PLUGIN_ATTRIBUTES callback is called during attribute registration. Use the register_attribute function to register custom attributes.

```c
/* Attribute handler callback */
static tree
handle_user_attribute (tree *node, tree name, tree args,
  int flags, bool *no_add_attrs)
{
  return NULL_TREE;
}

/* Attribute definition */
static struct attribute_spec user_attr =
{ "user", 1, 1, false, false, false, false, handle_user_attribute, NULL };

/* Plugin callback called during attribute registration. 
Registered with register_callback (plugin_name, PLUGIN_ATTRIBUTES, register_attributes, NULL) */
static void
register_attributes (void *event_data, void *data)
{
  warning (0, G_("Callback to register attributes"));
  register_attribute (&user_attr);
}
```

The PLUGIN_PRAGMAS callback is called once during pragmas registration. Use the c_registerPragma, c_registerPragmaWithData, c_registerPragmaWithExpansion, c_registerPragmaWithExpansionAndData functions to register custom pragmas and their handlers (which often want to call pragma_lex) from `c-family/c-pragma.h'.

```c
/* Plugin callback called during pragmas registration. Registered with 
  register_callback (plugin_name, PLUGIN_PRAGMAS, register_myPragma, NULL); */
static void
register_myPragma (void *event_data, void *data)
{
  warning (0, G_("Callback to register pragmas");
  c_registerPragma ("GCCPLUGIN", "sayhello", handlePragma_sayhello);
}
```

It is suggested to pass "GCCPLUGIN" (or a short name identifying your plugin) as the "space" argument of your pragma.

Pragmas registered with c_registerPragmaWithExpansion or c_registerPragmaWithExpansionAndData support preprocessor expansions. For example:

```c
#define NUMBER 10
#pragma GCCPLUGIN foothreshold (NUMBER)
```

24.7 Recording information about pass execution

The event PLUGIN_PASS_EXECUTION passes the pointer to the executed pass (the same as current_pass) as gcc_data to the callback. You can also inspect cfun to find out
about which function this pass is executed for. Note that this event will only be invoked if the gate check (if applicable, modified by PLUGIN OVERRIDE GATE) succeeds. You can use other hooks, like PLUGIN ALL PASSES START, PLUGIN ALL PASSES END, PLUGIN ALL IPA PASSES START, PLUGIN ALL IPA PASSES END, PLUGIN EARLY GIMPLE PASSES START, and/or PLUGIN EARLY GIMPLE PASSES END to manipulate global state in your plugin(s) in order to get context for the pass execution.

24.8 Controlling which passes are being run

After the original gate function for a pass is called, its result - the gate status - is stored as an integer. Then the event PLUGIN OVERRIDE GATE is invoked, with a pointer to the gate status in the gcc_data parameter to the callback function. A nonzero value of the gate status means that the pass is to be executed. You can both read and write the gate status via the passed pointer.

24.9 Keeping track of available passes

When your plugin is loaded, you can inspect the various pass lists to determine what passes are available. However, other plugins might add new passes. Also, future changes to GCC might cause generic passes to be added after plugin loading. When a pass is first added to one of the pass lists, the event PLUGIN NEW PASS is invoked, with the callback parameter gcc_data pointing to the new pass.

24.10 Building GCC plugins

If plugins are enabled, GCC installs the headers needed to build a plugin (somewhere in the installation tree, e.g. under ‘/usr/local’). In particular a ‘plugin/include’ directory is installed, containing all the header files needed to build plugins.

On most systems, you can query this plugin directory by invoking gcc -print-file-name=plugin (replace if needed gcc with the appropriate program path).

Inside plugins, this plugin directory name can be queried by calling default_plugin_dir_name ()

Plugins may know, when they are compiled, the GCC version for which ‘plugin-version.h’ is provided. The constant macros GCCPLUGIN_VERSION_MAJOR, GCCPLUGIN_VERSION_MINOR, GCCPLUGIN_VERSION_PATCHLEVEL, GCCPLUGIN_VERSION are integer numbers, so a plugin could ensure it is built for GCC 4.7 with

#ifndef GCCPLUGIN_VERSION
#error this GCC plugin is for GCC 4.7
#endif

The following GNU Makefile excerpt shows how to build a simple plugin:

```makefile
HOST_GCC=g++
TARGET_GCC=gcc
PLUGIN_SOURCE_FILES= plugin1.c plugin2.cc
GCCPLUGINS_DIR=$(shell $(TARGET_GCC) -print-file-name=plugin)
CXXFLAGS+= -I$(GCCPLUGINS_DIR)/include -fPIC -fno-rtti -O2

plugin.so: $(PLUGIN_SOURCE_FILES)
    $(HOST_GCC) -shared $(CXXFLAGS) $^ -o $@
```
A single source file plugin may be built with `g++ -I'gcc -print-file-name=plugin'/include -fPIC -shared -fno-rtti -O2 plugin.c -o plugin.so`, using backquote shell syntax to query the ‘plugin’ directory.

Plugin support on Windows/MinGW has a number of limitations and additional requirements. When building a plugin on Windows we have to link an import library for the corresponding backend executable, for example, ‘cc1.exe’, ‘cc1plus.exe’, etc., in order to gain access to the symbols provided by GCC. This means that on Windows a plugin is language-specific, for example, for C, C++, etc. If you wish to use your plugin with multiple languages, then you will need to build multiple plugin libraries and either instruct your users on how to load the correct version or provide a compiler wrapper that does this automatically.

Additionally, on Windows the plugin library has to export the `plugin_is_GPL_compatible` and `plugin_init` symbols. If you do not wish to modify the source code of your plugin, then you can use the ‘-Wl,--export-all-symbols’ option or provide a suitable DEF file. Alternatively, you can export just these two symbols by decorating them with `__declspec(dllexport)`, for example:

```c
#ifdef _WIN32
__declspec(dllexport)
#endif
int plugin_is_GPL_compatible;

#ifdef _WIN32
__declspec(dllexport)
#endif
int plugin_init (plugin_name_args *, plugin_gcc_version *)
```

The import libraries are installed into the `plugin` directory and their names are derived by appending the `.a` extension to the backend executable names, for example, ‘cc1.exe.a’, ‘cc1plus.exe.a’, etc. The following command line shows how to build the single source file plugin on Windows to be used with the C++ compiler:

```
g++ -I'gcc -print-file-name=plugin'/include -shared -Wl,--export-all-symbols \ -o plugin.dll plugin.c 'gcc -print-file-name=plugin'/cc1plus.exe.a
```

When a plugin needs to use `gengtype`, be sure that both ‘gengtype’ and ‘gtype.state’ have the same version as the GCC for which the plugin is built.


25 Link Time Optimization

Link Time Optimization (LTO) gives GCC the capability of dumping its internal representation (GIMPLE) to disk, so that all the different compilation units that make up a single executable can be optimized as a single module. This expands the scope of inter-procedural optimizations to encompass the whole program (or, rather, everything that is visible at link time).

25.1 Design Overview

Link time optimization is implemented as a GCC front end for a bytecode representation of GIMPLE that is emitted in special sections of .o files. Currently, LTO support is enabled in most ELF-based systems, as well as darwin, cygwin and mingw systems.

By default, object files generated with LTO support contain only GIMPLE bytecode. Such objects are called “slim”, and they require that tools like `ar` and `nm` understand symbol tables of LTO sections. For most targets these tools have been extended to use the plugin infrastructure, so GCC can support “slim” objects consisting of the intermediate code alone.

GIMPLE bytecode could also be saved alongside final object code if the `-ffat-lto-objects` option is passed, or if no plugin support is detected for `ar` and `nm` when GCC is configured. It makes the object files generated with LTO support larger than regular object files. This “fat” object format allows to ship one set of fat objects which could be used both for development and the production of optimized builds. A, perhaps surprising, side effect of this feature is that any mistake in the toolchain leads to LTO information not being used (e.g. an older `libtool` calling `ld` directly). This is both an advantage, as the system is more robust, and a disadvantage, as the user is not informed that the optimization has been disabled.

At the highest level, LTO splits the compiler in two. The first half (the “writer”) produces a streaming representation of all the internal data structures needed to optimize and generate code. This includes declarations, types, the callgraph and the GIMPLE representation of function bodies.

When `-flto` is given during compilation of a source file, the pass manager executes all the passes in `all_lto_gen_passes`. Currently, this phase is composed of two IPA passes:

- **pass_ipa_lto_gimple_out** This pass executes the function `lto_output` in `lto-streamer-out.c`, which traverses the call graph encoding every reachable declaration, type and function. This generates a memory representation of all the file sections described below.

- **pass_ipa_lto_finish_out** This pass executes the function `produce_asm_for_decls` in `lto-streamer-out.c`, which takes the memory image built in the previous pass and encodes it in the corresponding ELF file sections.

The second half of LTO support is the “reader”. This is implemented as the GCC front end `lto1` in `lto/lto.c`. When `collect2` detects a link set of .o/.a files with LTO information and the `-flto` is enabled, it invokes `lto1` which reads the set of files and aggregates them into a single translation unit for optimization. The main entry point for the reader is `lto/lto.c`:lto_main.
25.1.1 LTO modes of operation

One of the main goals of the GCC link-time infrastructure was to allow effective compilation of large programs. For this reason GCC implements two link-time compilation modes.

1. **LTO mode**, in which the whole program is read into the compiler at link-time and optimized in a similar way as if it were a single source-level compilation unit.

2. **WHOPR or partitioned mode**, designed to utilize multiple CPUs and/or a distributed compilation environment to quickly link large applications. WHOPR stands for WHOle Program optimizeR (not to be confused with the semantics of `-fwhole-program`). It partitions the aggregated callgraph from many different `.o` files and distributes the compilation of the sub-graphs to different CPUs.

Note that distributed compilation is not implemented yet, but since the parallelism is facilitated via generating a `Makefile`, it would be easy to implement.

WHOPR splits LTO into three main stages:

1. **Local generation (LGEN)** This stage executes in parallel. Every file in the program is compiled into the intermediate language and packaged together with the local callgraph and summary information. This stage is the same for both the LTO and WHOPR compilation mode.

2. **Whole Program Analysis (WPA)** WPA is performed sequentially. The global call-graph is generated, and a global analysis procedure makes transformation decisions. The global call-graph is partitioned to facilitate parallel optimization during phase 3. The results of the WPA stage are stored into new object files which contain the partitions of program expressed in the intermediate language and the optimization decisions.

3. **Local transformations (LTRANS)** This stage executes in parallel. All the decisions made during phase 2 are implemented locally in each partitioned object file, and the final object code is generated. Optimizations which cannot be decided efficiently during the phase 2 may be performed on the local call-graph partitions.

WHOPR can be seen as an extension of the usual LTO mode of compilation. In LTO, WPA and LTRANS are executed within a single execution of the compiler, after the whole program has been read into memory.

When compiling in WHOPR mode, the callgraph is partitioned during the WPA stage. The whole program is split into a given number of partitions of roughly the same size. The compiler tries to minimize the number of references which cross partition boundaries. The main advantage of WHOPR is to allow the parallel execution of LTRANS stages, which are the most time-consuming part of the compilation process. Additionally, it avoids the need to load the whole program into memory.

25.2 LTO file sections

LTO information is stored in several ELF sections inside object files. Data structures and enum codes for sections are defined in `lto-streamer.h`.

These sections are emitted from `lto-streamer-out.c` and mapped in all at once from `lto/lto.c`: `lto_file_read`. The individual functions dealing with the reading/writing of each section are described below.
• Command line options (.gnu.lto_.opts)
  This section contains the command line options used to generate the object files. This
  is used at link time to determine the optimization level and other settings when they
  are not explicitly specified at the linker command line.

  Currently, GCC does not support combining LTO object files compiled with different
  set of the command line options into a single binary. At link time, the options given on
  the command line and the options saved on all the files in a link-time set are applied
  globally. No attempt is made at validating the combination of flags (other than the
  usual validation done by option processing). This is implemented in 'lto/lto.c':lto_
  read_all_file_options.

• Symbol table (.gnu.lto_.symtab)
  This table replaces the ELF symbol table for functions and variables represented in the
  LTO IL. Symbols used and exported by the optimized assembly code of “fat” objects
  might not match the ones used and exported by the intermediate code. This table is
  necessary because the intermediate code is less optimized and thus requires a separate
  symbol table.

  Additionally, the binary code in the “fat” object will lack a call to a function, since
  the call was optimized out at compilation time after the intermediate language was
  streamed out. In some special cases, the same optimization may not happen during
  link-time optimization. This would lead to an undefined symbol if only one symbol
  table was used.

  The symbol table is emitted in 'lto-streamer-out.c':produce_symtab.

• Global declarations and types (.gnu.lto_.decls)
  This section contains an intermediate language dump of all declarations and types
  required to represent the callgraph, static variables and top-level debug info.

  The contents of this section are emitted in 'lto-streamer-out.c':produce_asm_for_
  decls. Types and symbols are emitted in a topological order that preserves the sharing
  of pointers when the file is read back in ('lto.c':read_cgraph_and_symbols).

• The callgraph (.gnu.lto_.cgraph)
  This section contains the basic data structure used by the GCC inter-procedural opti-
  mization infrastructure. This section stores an annotated multi-graph which represents
  the functions and call sites as well as the variables, aliases and top-level asm
  statements.

  This section is emitted in 'lto-streamer-out.c':output_cgraph and read in
  'lto-cgraph.c':input_cgraph.

• IPA references (.gnu.lto_.refs)
  This section contains references between function and static variables. It is emitted by
  'lto-cgraph.c':output.refs and read by 'lto-cgraph.c':input.refs.

• Function bodies (.gnu.lto_.function_body.<name>)
  This section contains function bodies in the intermediate language representation. Ev-
  ery function body is in a separate section to allow copying of the section independently
to different object files or reading the function on demand.

  Functions are emitted in 'lto-streamer-out.c':output_function and read in
  'lto-streamer-in.c':input_function.
• Static variable initializers (.gnu.lto_.vars)
  This section contains all the symbols in the global variable pool. It is emitted by
  `lto-cgraph.c`:output_varpool and read in `lto-cgraph.c`:input_cgraph.
• Summaries and optimization summaries used by IPA passes (.gnu.lto_.<xxx>, where
  <xxx> is one of jmpfuncs, pureconst or reference)
  These sections are used by IPA passes that need to emit summary information during
  LTO generation to be read and aggregated at link time. Each pass is responsible for
  implementing two pass manager hooks: one for writing the summary and another for
  reading it in. The format of these sections is entirely up to each individual pass. The
  only requirement is that the writer and reader hooks agree on the format.

25.3 Using summary information in IPA passes

Programs are represented internally as a callgraph (a multi-graph where nodes are functions
and edges are call sites) and a varpool (a list of static and external variables in the program).

The inter-procedural optimization is organized as a sequence of individual passes, which
operate on the callgraph and the varpool. To make the implementation of WHOPR possible,
every inter-procedural optimization pass is split into several stages that are executed at
different times during WHOPR compilation:
• LGEN time
  1. Generate summary (generate_summary in struct ipa_opt_pass_d). This stage
     analyzes every function body and variable initializer is examined and stores rele-
     vant information into a pass-specific data structure.
  2. Write summary (write_summary in struct ipa_opt_pass_d). This stage
     writes all the pass-specific information generated by generate_summary. 
     Summaries go into their own LTO_section_* sections that have to be declared in
     `lto-streamer.h`:enum lto_section_type. A new section is created by calling
     create_output_block and data can be written using the lto_output_* routines.
• WPA time
  1. Read summary (read_summary in struct ipa_opt_pass_d). This stage reads all
     the pass-specific information in exactly the same order that it was written by
     write_summary.
  2. Execute (execute in struct opt_pass). This performs inter-procedural propaga-
     tion. This must be done without actual access to the individual function bodies
     or variable initializers. Typically, this results in a transitive closure operation over
     the summary information of all the nodes in the callgraph.
  3. Write optimization summary (write_optimization_summary in struct
     ipa_opt_pass_d). This writes the result of the inter-procedural propagation into
     the object file. This can use the same data structures and helper routines used in
     write_summary.
• LTRANS time
  1. Read optimization summary (read_optimization_summary in struct ipa_opt_-
     pass_d). The counterpart to write_optimization_summary. This reads the in-
     terprocedural optimization decisions in exactly the same format emitted by write_
     optimization_summary.
2. **Transform** (*function_transform* and *variable_transform* in *struct ipa_opt_pass_d*). The actual function bodies and variable initializers are updated based on the information passed down from the *Execute* stage.

The implementation of the inter-procedural passes are shared between LTO, WHOPR and classic non-LTO compilation.

- During the traditional file-by-file mode every pass executes its own *Generate summary*, *Execute*, and *Transform* stages within the single execution context of the compiler.
- In LTO compilation mode, every pass uses *Generate summary* and *Write summary* stages at compilation time, while the *Read summary*, *Execute*, and *Transform* stages are executed at link time.
- In WHOPR mode all stages are used.

To simplify development, the GCC pass manager differentiates between normal inter-procedural passes (see Section 9.4.2 [Regular IPA passes], page 134), small inter-procedural passes (see Section 9.4.1 [Small IPA passes], page 133) and late inter-procedural passes (see Section 9.4.3 [Late IPA passes], page 136). A small or late IPA pass (*SIMPLE_IPA_PASS*) does everything at once and thus cannot be executed during WPA in WHOPR mode. It defines only the *Execute* stage and during this stage it accesses and modifies the function bodies. Such passes are useful for optimization at LGEN or LTRANS time and are used, for example, to implement early optimization before writing object files. The simple inter-procedural passes can also be used for easier prototyping and development of a new inter-procedural pass.

### 25.3.1 Virtual clones

One of the main challenges of introducing the WHOPR compilation mode was addressing the interactions between optimization passes. In LTO compilation mode, the passes are executed in a sequence, each of which consists of analysis (or *Generate summary*), propagation (or *Execute*) and *Transform* stages. Once the work of one pass is finished, the next pass sees the updated program representation and can execute. This makes the individual passes dependent on each other.

In WHOPR mode all passes first execute their *Generate summary* stage. Then summary writing marks the end of the LGEN stage. At WPA time, the summaries are read back into memory and all passes run the *Execute* stage. Optimization summaries are streamed and sent to LTRANS, where all the passes execute the *Transform* stage.

Most optimization passes split naturally into analysis, propagation and transformation stages. But some do not. The main problem arises when one pass performs changes and the following pass gets confused by seeing different callgraphs between the *Transform* stage and the *Generate summary* or *Execute* stage. This means that the passes are required to communicate their decisions with each other.

To facilitate this communication, the GCC callgraph infrastructure implements *virtual clones*, a method of representing the changes performed by the optimization passes in the callgraph without needing to update function bodies.

A *virtual clone* in the callgraph is a function that has no associated body, just a description of how to create its body based on a different function (which itself may be a virtual clone).

The description of function modifications includes adjustments to the function’s signature (which allows, for example, removing or adding function arguments), substitutions to
perform on the function body, and, for inlined functions, a pointer to the function that it will be inlined into.

It is also possible to redirect any edge of the callgraph from a function to its virtual clone. This implies updating of the call site to adjust for the new function signature.

Most of the transformations performed by inter-procedural optimizations can be represented via virtual clones. For instance, a constant propagation pass can produce a virtual clone of the function which replaces one of its arguments by a constant. The inliner can represent its decisions by producing a clone of a function whose body will be later integrated into a given function.

Using virtual clones, the program can be easily updated during the Execute stage, solving most of pass interactions problems that would otherwise occur during Transform.

Virtual clones are later materialized in the LTRANS stage and turned into real functions. Passes executed after the virtual clone were introduced also perform their Transform stage on new functions, so for a pass there is no significant difference between operating on a real function or a virtual clone introduced before its Execute stage.

Optimization passes then work on virtual clones introduced before their Execute stage as if they were real functions. The only difference is that clones are not visible during the Generate Summary stage.

To keep function summaries updated, the callgraph interface allows an optimizer to register a callback that is called every time a new clone is introduced as well as when the actual function or variable is generated or when a function or variable is removed. These hooks are registered in the Generate summary stage and allow the pass to keep its information intact until the Execute stage. The same hooks can also be registered during the Execute stage to keep the optimization summaries updated for the Transform stage.

25.3.2 IPA references
GCC represents IPA references in the callgraph. For a function or variable A, the IPA reference is a list of all locations where the address of A is taken and, when A is a variable, a list of all direct stores and reads to/from A. References represent an oriented multi-graph on the union of nodes of the callgraph and the varpool. See 'ipa-reference.c':ipa_reference_write_optimization_summary and 'ipa-reference.c':ipa_reference_read_optimization_summary for details.

25.3.3 Jump functions
Suppose that an optimization pass sees a function A and it knows the values of (some of) its arguments. The jump function describes the value of a parameter of a given function call in function A based on this knowledge.

Jump functions are used by several optimizations, such as the inter-procedural constant propagation pass and the devirtualization pass. The inliner also uses jump functions to perform inlining of callbacks.

25.4 Whole program assumptions, linker plugin and symbol visibilities
Link-time optimization gives relatively minor benefits when used alone. The problem is that propagation of inter-procedural information does not work well across functions and
variables that are called or referenced by other compilation units (such as from a dynamically linked library). We say that such functions and variables are \textit{externally visible}.

To make the situation even more difficult, many applications organize themselves as a set of shared libraries, and the default ELF visibility rules allow one to overwrite any externally visible symbol with a different symbol at runtime. This basically disables any optimizations across such functions and variables, because the compiler cannot be sure that the function body it is seeing is the same function body that will be used at runtime. Any function or variable not declared \texttt{static} in the sources degrades the quality of inter-procedural optimization.

To avoid this problem the compiler must assume that it sees the whole program when doing link-time optimization. Strictly speaking, the whole program is rarely visible even at link-time. Standard system libraries are usually linked dynamically or not provided with the link-time information. In GCC, the whole program option (\texttt{-fwhole-program}) asserts that every function and variable defined in the current compilation unit is static, except for function \texttt{main} (note: at link time, the current unit is the union of all objects compiled with LTO). Since some functions and variables need to be referenced externally, for example by another DSO or from an assembler file, GCC also provides the function and variable attribute \texttt{externally_visible} which can be used to disable the effect of \texttt{-fwhole-program} on a specific symbol.

The whole program mode assumptions are slightly more complex in C++, where inline functions in headers are put into \textit{COMDAT} sections. COMDAT function and variables can be defined by multiple object files and their bodies are unified at link-time and dynamic link-time. COMDAT functions are changed to local only when their address is not taken and thus un-sharing them with a library is not harmful. COMDAT variables always remain externally visible, however for readonly variables it is assumed that their initializers cannot be overwritten by a different value.

GCC provides the function and variable attribute \texttt{visibility} that can be used to specify the visibility of externally visible symbols (or alternatively an \texttt{-fdefault-visibility} command line option). ELF defines the \texttt{default, protected, hidden} and \texttt{internal} visibilities.

The most commonly used is visibility is \texttt{hidden}. It specifies that the symbol cannot be referenced from outside of the current shared library. Unfortunately, this information cannot be used directly by the link-time optimization in the compiler since the whole shared library also might contain non-LTO objects and those are not visible to the compiler.

GCC solves this problem using linker plugins. A \textit{linker plugin} is an interface to the linker that allows an external program to claim the ownership of a given object file. The linker then performs the linking procedure by querying the plugin about the symbol table of the claimed objects and once the linking decisions are complete, the plugin is allowed to provide the final object file before the actual linking is made. The linker plugin obtains the symbol resolution information which specifies which symbols provided by the claimed objects are bound from the rest of a binary being linked.

GCC is designed to be independent of the rest of the toolchain and aims to support linkers without plugin support. For this reason it does not use the linker plugin by default. Instead, the object files are examined by \texttt{collect2} before being passed to the linker and objects found to have LTO sections are passed to \texttt{lto1} first. This mode does not work for library archives.
The decision on what object files from the archive are needed depends on the actual linking and thus GCC would have to implement the linker itself. The resolution information is missing too and thus GCC needs to make an educated guess based on ‘-fwhole-program’. Without the linker plugin GCC also assumes that symbols are declared hidden and not referred by non-LTO code by default.

25.5 Internal flags controlling lto1

The following flags are passed into lto1 and are not meant to be used directly from the command line.

- -fwpa This option runs the serial part of the link-time optimizer performing the inter-procedural propagation (WPA mode). The compiler reads in summary information from all inputs and performs an analysis based on summary information only. It generates object files for subsequent runs of the link-time optimizer where individual object files are optimized using both summary information from the WPA mode and the actual function bodies. It then drives the LTRANS phase.

- -fltrans This option runs the link-time optimizer in the local-transformation (LTRANS) mode, which reads in output from a previous run of the LTO in WPA mode. In the LTRANS mode, LTO optimizes an object and produces the final assembly.

- -fltrans-output-list=file This option specifies a file to which the names of LTRANS output files are written. This option is only meaningful in conjunction with ‘-fwpa’.

- -fresolution=file This option specifies the linker resolution file. This option is only meaningful in conjunction with ‘-fwpa’ and as option to pass through to the LTO linker plugin.
26 Match and Simplify

The GIMPLE and GENERIC pattern matching project match-and-simplify tries to address several issues.

1. unify expression simplifications currently spread and duplicated over separate files like fold-const.c, gimple-fold.c and builtins.c
2. allow for a cheap way to implement building and simplifying non-trivial GIMPLE expressions, avoiding the need to go through building and simplifying GENERIC via fold_buildN and then gimplifying via force_gimple_operand

To address these the project introduces a simple domain specific language to write expression simplifications from which code targeting GIMPLE and GENERIC is auto-generated. The GENERIC variant follows the fold_buildN API while for the GIMPLE variant and to address 2) new APIs are introduced.

26.1 GIMPLE API

```
tree gimple_simplify (enum tree_code, tree, tree, gimple_seq *);  // GIMPLE function

// Overloads:
tree gimple_simplify (enum tree_code, tree, tree, gimple_seq *, tree (*)(tree));

// Overloads:
tree gimple_simplify (enum tree_code, tree, tree, gimple_seq *, tree (*)(tree));

// Overloads:
tree gimple_simplify (enum built_in_function, tree, tree, gimple_seq *, tree (*)(tree));

// Overloads:
tree gimple_simplify (enum built_in_function, tree, tree, tree, gimple_seq *, tree (*)(tree));
```

The main GIMPLE API entry to the expression simplifications mimicking that of the GENERIC fold_{unary,binary,ternary} functions.

thus providing n-ary overloads for operation or function. The additional arguments are a gimple_seq where built statements are inserted on (if NULL then simplifications requiring new statements are not performed) and a valueization hook that can be used to tie simplifications to a SSA lattice.

In addition to those APIs fold_stmt is overloaded with a valueization hook:

```
fold_stmt (gimple_stmt_iterator *, tree (*)(tree));  // [bool]
```

On top of these a fold_buildN-like API for GIMPLE is introduced:

```
tree gimple_build (gimple_seq *, location_t, enum tree_code, tree, tree, tree (*valueize) (tree) = NULL);  // GIMPLE function

// Overloads:
tree gimple_build (gimple_seq *, location_t, enum tree_code, tree, tree, tree (*valueize) (tree) = NULL);  // GIMPLE function

// Overloads:
tree gimple_build (gimple_seq *, location_t, enum tree_code, tree, tree, tree (*valueize) (tree) = NULL);  // GIMPLE function
```


tree gimple_build (gimple_seq *, location_t, enum
    built_in_function, tree, tree, tree (*valueize) (tree) = NULL);

which is supposed to replace force_gimple_operand (fold_buildN (...), ...) and
calls to fold_convert. Overloads without the location_t argument exist. Built state-
ments are inserted on the provided sequence and simplification is performed using the
optional valueization hook.

26.2 The Language

The language to write expression simplifications in resembles other domain-specific lan-
guages GCC uses. Thus it is lispy. Lets start with an example from the match.pd file:

(simplify (bit_and @0 integer_all_onesp) @0)

This example contains all required parts of an expression simplification. A simplification
is wrapped inside a (simplify ...) expression. That contains at least two operands - an
expression that is matched with the GIMPLE or GENERIC IL and a replacement expression
that is returned if the match was successful.

Expressions have an operator ID, bit_and in this case. Expressions can be lower-case
tree codes with _expr stripped off or builtin function code names in all-caps, like BUILT_-
IN_SQRT.

@n denotes a so-called capture. It captures the operand and lets you refer to it in other
places of the match-and-simplify. In the above example it is refered to in the replacement
expression. Captures are @ followed by a number or an identifier.

(simplify (bit_xor @0 @0) { build_zero_cst (type); })

In this example @0 is mentioned twice which constrains the matched expression to have
two equal operands. Usually matches are constraint to equal types. If operands may be
constants and conversions are involved matching by value might be preferred in which case
use @@0 to denote a by value match and the specific operand you want to refer to in the
result part. This example also introduces operands written in C code. These can be used
in the expression replacements and are supposed to evaluate to a tree node which has to be
a valid GIMPLE operand (so you cannot generate expressions in C code).

(simplify (trunc_mod integer_zerop@0 @1) (if (!integer_zerop (@1)) @0))

Here @0 captures the first operand of the trunc_mod expression which is also predicated
with integer_zerop. Expression operands may be either expressions, predicates or cap-
tures. Captures can be unconstrained or capture expressions or predicates.

This example introduces an optional operand of simplify, the if-expression. This condition
is evaluated after the expression matched in the IL and is required to evaluate to true to
enable the replacement expression in the second operand position. The expression operand of the `if` is a standard C expression which may contain references to captures. The `if` has an optional third operand which may contain the replacement expression that is enabled when the condition evaluates to false.

A `if` expression can be used to specify a common condition for multiple simplify patterns, avoiding the need to repeat that multiple times:

```c
(if (!TYPE_SATURATING (type)
  && !FLOAT_TYPE_P (type) && !FIXED_POINT_TYPE_P (type))
  (simplify
    (minus (plus @0 @1) @0)
    @1)
  (simplify
    (minus (minus @0 @1) @0)
    (negate @1)))
```

Note that `ifs` in outer position do not have the optional else clause but instead have multiple then clauses.

`Ifs` can be nested.

There exists a `switch` expression which can be used to chain conditions avoiding nesting `ifs` too much:

```c
(simplify
  (simple_comparison @0 REAL_CST@1)
  (switch
   /* a CMP (-0) -> a CMP 0 */
   (if (REAL_VALUE_MINUS_ZERO (TREE_REAL_CST (@1)))
    (cmp @0 { build_real (TREE_TYPE (@1), dconst0); })
   /* x != NaN is always true, other ops are always false. */
   (if (REAL_VALUE_ISNAN (TREE_REAL_CST (@1))
    && ! HONOR_SNANS (@1))
    { constant_boolean_node (cmp == NE_EXPR, type); }))
```

Is equal to

```c
(simplify
  (simple_comparison @0 REAL_CST@1)
  (switch
   /* a CMP (-0) -> a CMP 0 */
   (if (REAL_VALUE_MINUS_ZERO (TREE_REAL_CST (@1)))
    (cmp @0 { build_real (TREE_TYPE (@1), dconst0); })
   /* x != NaN is always true, other ops are always false. */
   (if (REAL_VALUE_ISNAN (TREE_REAL_CST (@1))
    && ! HONOR_SNANS (@1))
    { constant_boolean_node (cmp == NE_EXPR, type); }))
```

which has the second `if` in the else operand of the first. The `switch` expression takes `if` expressions as operands (which may not have else clauses) and as a last operand a replacement expression which should be enabled by default if no other condition evaluated to true.

Captures can also be used for capturing results of sub-expressions.

```c
#if GIMPLE
  (simplify
    (pointer_plus (addr@2 @0) INTEGER_CST_P@1)
    (if (is_gimple_min_invariant (@2)))
    
```

poly_int64 off;
tree base = get_addr_base_and_unit_offset (@0, &off);
off += tree_to_uhwi (@1);
/* Now with that we should be able to simply write */
build1 (ADDR_EXPR, type,
  build2 (MEM_REF, TREE_TYPE (TREE_TYPE (@2)),
    build_fold_addr_expr (base),
    build_int_cst (ptr_type_node, off)));
}
#endif

In the above example, @2 captures the result of the expression (addr @0). For outermost expression only its type can be captured, and the keyword type is reserved for this purpose. The above example also gives a way to conditionalize patterns to only apply to GIMPLE or GENERIC by means of using the pre-defined preprocessor macros GIMPLE and GENERIC and using preprocessor directives.

(simplify
  (bit_and:c integral_op_p@0 (bit_ior:c (bit_not @0) @1))
  (bit_and @1 @0))

Here we introduce flags on match expressions. The flag used above, c, denotes that the expression should be also matched commutated. Thus the above match expression is really the following four match expressions:

(bit_and integral_op_p@0 (bit_ior (bit_not @0) @1))
(bit_and (bit_ior (bit_not @0) @1) integral_op_p@0)
(bit_and integral_op_p@0 (bit_ior @1 (bit_not @0)))
(bit_and (bit_ior @1 (bit_not @0)) integral_op_p@0)

Usual canonicalizations you know from GENERIC expressions are applied before matching, so for example constant operands always come second in commutative expressions.

The second supported flag is s which tells the code generator to fail the pattern if the expression marked with s does have more than one use and the simplification results in an expression with more than one operator. For example in

(simplify
  (pointer_plus (pointer_plus:s @0 @1) @3)
  (pointer_plus @0 (plus @1 @3)))

this avoids the association if (pointer_plus @0 @1) is used outside of the matched expression and thus it would stay live and not trivially removed by dead code elimination. Now consider ((x + 3) + -3) with the temporary holding (x + 3) used elsewhere. This simplifies down to x which is desirable and thus flagging with s does not prevent the transform. Now consider ((x + 3) + 1) which simplifies to (x + 4). Despite being flagged with s the simplification will be performed. The simplification of ((x + a) + 1) to (x + (a + 1)) will not performed in this case though.

More features exist to avoid too much repetition.

(for op (plus pointer_plus minus bit_ior bit_xor)
  simplify
  (op @0 integer_zerop)
  @0))

A for expression can be used to repeat a pattern for each operator specified, substituting op. for can be nested and a for can have multiple operators to iterate.

(for opa (plus minus)
  opb (minus plus)
In this example the pattern will be repeated four times with opa, opb, opc being plus, minus, plus, minus, plus, minus, minus, plus, plus, minus, plus, minus.

To avoid repeating operator lists in for you can name them via

```
(define_operator_list pmm plus minus mult)
```

and use them in for operator lists where they get expanded.

```
(for opa (pmm trunc_div)  
  (simplify...)
```

So this example iterates over plus, minus, mult and trunc_div.

Using operator lists can also remove the need to explicitly write a for. All operator list uses that appear in a simplify or match pattern in operator positions will implicitly be added to a new for. For example

```
(define_operator_list SQRT BUILT_IN_SQRTF BUILT_IN_SQRT BUILT_IN_SQRTL)  
(define_operator_list POW BUILT_IN_POWF BUILT_IN_POW BUILT_IN_POWL)  
(simplify  
  (SQRT (POW @0 @1))  
  (POW (abs @0) (mult @1 { built_real (TREE_TYPE (@1), dconsthalf); })))
```

is the same as

```
(for SQRT (BUILT_IN_SQRTF BUILT_IN_SQRT BUILT_IN_SQRTL)  
  POW (BUILT_IN_POWF BUILT_IN_POW BUILT_IN_POWL)  
  (simplify  
    (SQRT (POW @0 @1))  
    (POW (abs @0) (mult @1 { built_real (TREE_TYPE (@1), dconsthalf); }))))
```

For and operator lists can include the special identifier null that matches nothing and can never be generated. This can be used to pad an operator list so that it has a standard form, even if there isn’t a suitable operator for every form.

Another building block are with expressions in the result expression which nest the generated code in a new C block followed by its argument:

```
(simplify  
  (convert (mult @0 @1))  
  (with { tree utype = unsigned_type_for (type); }  
    (convert (mult:utype @0) (convert:utype @1))))
```

This allows code nested in the with to refer to the declared variables. In the above case we use the feature to specify the type of a generated expression with the :type syntax where type needs to be an identifier that refers to the desired type. Usually the types of the generated result expressions are determined from the context, but sometimes like in the above case it is required that you specify them explicitly.

Another modifier for generated expressions is ! which tells the machinery to only consider the simplification in case the marked expression simplified to a simple operand. Consider for example

```
(simplify  
  (plus (vec_cond:s 00 01 02) 03)  
  (vec_cond 00 (plus! 01 03) (plus! 02 03)))
```

which moves the outer plus operation to the inner arms of the vec_cond expression but only if the actual plus operations both simplify. Note this is currently only supported for code generation targeting GIMPLE.
As intermediate conversions are often optional there is a way to avoid the need to repeat patterns both with and without such conversions. Namely you can mark a conversion as being optional with a `?`:

```
(simplify
 (eq (convert @0 @1) (convert? @2))
 (eq @1 (convert? @2)))
```

which will match both `(eq (convert @0) (convert @2))` and `(eq (convert @0) @2)`. The optional converts are supposed to be all either present or not, thus `(eq (convert? @0) (convert? @2))` will result in two patterns only. If you want to match all four combinations you have access to two additional conditional converts as in `(eq (convert1? @0) (convert2? @2))`.

The support for `?` marking extends to all unary operations including predicates you declare yourself with `match`.

Predicates available from the GCC middle-end need to be made available explicitly via `define_predicates`:

```
(define_predicates
  integer_onep integer_zerop integer_all_onesp)
```

You can also define predicates using the pattern matching language and the `match` form:

```
(match negate_expr_p
  INTEGER_CST
  (if (TYPE_OVERFLOW_WRAPS (type)
      || may_negate_without_overflow_p (t)))
  (match negate_expr_p
    (negate @0))
```

This shows that for `match` expressions there is `t` available which captures the outermost expression (something not possible in the `simplify` context). As you can see `match` has an identifier as first operand which is how you refer to the predicate in patterns. Multiple `match` for the same identifier add additional cases where the predicate matches.

Predicates can also match an expression in which case you need to provide a template specifying the identifier and where to get its operands from:

```
(match (logical_inverted_value @0)
  (eq @0 integer_zerop))
(match (logical_inverted_value @0)
  (bit_not truth_valued_p @0))
```

You can use the above predicate like

```
(simplify
  (bit_and @0 (logical_inverted_value @0))
  { build_zero_cst (type); })
```

Which will match a bitwise and of an operand with its logical inverted value.
Chapter 27: Static Analyzer

27 Static Analyzer

27.1 Analyzer Internals

27.1.1 Overview

The analyzer implementation works on the gimple-SSA representation. (I chose this in the hopes of making it easy to work with LTO to do whole-program analysis).

The implementation is read-only: it doesn’t attempt to change anything, just emit warnings.

The gimple representation can be seen using ‘-fdump-ipa-analyzer’.

Tip: If the analyzer ICEs before this is written out, one workaround is to use ‘--param=analyzer-bb-explosion-factor=0’ to force the analyzer to bail out after analyzing the first basic block.

First, we build a supergraph which combines the callgraph and all of the CFGs into a single directed graph, with both interprocedural and intraprocedural edges. The nodes and edges in the supergraph are called “supernodes” and “superedges”, and often referred to in code as snodes and sedges. Basic blocks in the CFGs are split at interprocedural calls, so there can be more than one supernode per basic block. Most statements will be in just one supernode, but a call statement can appear in two supernodes: at the end of one for the call, and again at the start of another for the return.

The supergraph can be seen using ‘-fdump-analyzer-supergraph’.

We then build an analysis_plan which walks the callgraph to determine which calls might be suitable for being summarized (rather than fully explored) and thus in what order to explore the functions.

Next is the heart of the analyzer: we use a worklist to explore state within the supergraph, building an "exploded graph". Nodes in the exploded graph correspond to <point, state> pairs, as in "Precise Interprocedural Dataflow Analysis via Graph Reachability" (Thomas Reps, Susan Horwitz and Mooly Sagiv).

We reuse nodes for <point, state> pairs we’ve already seen, and avoid tracking state too closely, so that (hopefully) we rapidly converge on a final exploded graph, and terminate the analysis. We also bail out if the number of exploded <end-of-basic-block, state> nodes gets larger than a particular multiple of the total number of basic blocks (to ensure termination in the face of pathological state-explosion cases, or bugs). We also stop exploring a point once we hit a limit of states for that point.

We can identify problems directly when processing a <point, state> instance. For example, if we’re finding the successors of

<point: before-stmt: "free (ptr);"," state: {"ptr": freed}>

then we can detect a double-free of "ptr". We can then emit a path to reach the problem by finding the simplest route through the graph.

Program points in the analysis are much more fine-grained than in the CFG and supergraph, with points (and thus potentially exploded nodes) for various events, including before individual statements. By default the exploded graph merges multiple consecutive statements in a supernode into one exploded edge to minimize the size of the exploded graph.
This can be suppressed via \texttt{--fanalyzer-fine-grained}. The fine-grained approach seems to make things simpler and more debuggable than other approaches I tried, in that each point is responsible for one thing.

Program points in the analysis also have a "call string" identifying the stack of callsites below them, so that paths in the exploded graph correspond to interprocedurally valid paths: we always return to the correct call site, propagating state information accordingly. We avoid infinite recursion by stopping the analysis if a callsite appears more than \texttt{analyzer-max-recursion-depth} in a callstring (defaulting to 2).

\subsection{27.1.2 Graphs}

Nodes and edges in the exploded graph are called “exploded nodes” and “exploded edges” and often referred to in the code as \texttt{enodes} and \texttt{edges} (especially when distinguishing them from the \texttt{snodes} and \texttt{sedges} in the supergraph).

Each graph numbers its nodes, giving unique identifiers - supernodes are referred to throughout dumps in the form \texttt{‘SN’: index} and exploded nodes in the form \texttt{‘EN: index’} (e.g. \texttt{‘SN: 2’} and \texttt{‘EN:29’}).

The supergraph can be seen using \texttt{--fdump-analyzer-supergraph-graph}.

The exploded graph can be seen using \texttt{--fdump-analyzer-exploded-graph} and other dump options. Exploded nodes are color-coded in the .dot output based on state-machine states to make it easier to see state changes at a glance.

\subsection{27.1.3 State Tracking}

There’s a tension between:

\begin{itemize}
\item precision of analysis in the straight-line case, vs
\item exponential blow-up in the face of control flow.
\end{itemize}

For example, in general, given this CFG:

\begin{center}
\begin{verbatim}
A
 / \\ B C
 / \\ D
 / E F
 / \\ G
\end{verbatim}
\end{center}

we want to avoid differences in state-tracking in B and C from leading to blow-up. If we don’t prevent state blowup, we end up with exponential growth of the exploded graph like this:

\begin{center}
\begin{verbatim}
1:A
 / \\ 2:B 3:C
 / \ / 4:D 5:D (2 exploded nodes for D)
 / \ / 6:E 7:F 8:E 9:F
\end{verbatim}
\end{center}
Similar issues arise with loops.

To prevent this, we follow various approaches:

a. state pruning: which tries to discard state that won’t be relevant later on within the function. This can be disabled via ‘-fno-analyzer-state-purge’.

b. state merging. We can try to find the commonality between two program state instances to make a third, simpler program state. We have two strategies here:

1. the worklist keeps new nodes for the same program point together, and tries to merge them before processing, and thus before they have successors. Hence, in the above, the two nodes for D (4 and 5) reach the front of the worklist together, and we create a node for D with the merger of the incoming states.

2. try merging with the state of existing enodes for the program point (which may have already been explored). There will be duplication, but only one set of duplication; subsequent duplicates are more likely to hit the cache. In particular, (hopefully) all merger chains are finite, and so we guarantee termination. This is intended to help with loops: we ought to explore the first iteration, and then have a "subsequent iterations" exploration, which uses a state merged from that of the first, to be more abstract.

We avoid merging pairs of states that have state-machine differences, as these are the kinds of differences that are likely to be most interesting. So, for example, given:

```c
if (condition)
    ptr = malloc (size);
else
    ptr = local_buf;

.... do things with 'ptr'

if (condition)
    free (ptr);

...etc
```

then we end up with an exploded graph that looks like this:

```
if (condition)
/ T \ F
--------- ----------
/ ptr = malloc (size) ptr = local_buf
| copy of copy of
| "do things with 'ptr'" "do things with 'ptr'"
| with ptr: heap_allocated with ptr: stack_allocated
| if (condition) if (condition)
| known to be T known to be F
\ free (ptr);
```

---
where some duplication has occurred, but only for the places where the different paths are worth exploring separately.

Merging can be disabled via ‘-fno-analyzer-state-merge’.

27.1.4 Region Model

Part of the state stored at a exploded_node is a region_model. This is an implementation of the region-based ternary model described in "A Memory Model for Static Analysis of C Programs" (Zhongxing Xu, Ted Kremenek, and Jian Zhang).

A region_model encapsulates a representation of the state of memory, with a store recording a binding between region instances, to svalue instances. The bindings are organized into clusters, where regions accessible via well-defined pointer arithmetic are in the same cluster. The representation is graph-like because values can be pointers to regions. It also stores a constraint_manager, capturing relationships between the values.

Because each node in the exploded_graph has a region_model, and each of the latter is graph-like, the exploded_graph is in some ways a graph of graphs.

Here’s an example of printing a program_state, showing the region_model within it, along with state for the malloc state machine.

    (gdb) call debug (*this)
    rmodel:
    stack depth: 1
    frame (index 0): frame: test@1
    clusters within frame: test@1
    cluster for: ptr_3: &HEAP_ALLOCATED_REGION(12)
    m_called_unknown_fn: FALSE
    constraint_manager:
      equiv classes:
      constraints:
    malloc:
      0x2e89590: &HEAP_ALLOCATED_REGION(12): unchecked ('ptr_3')

This is the state at the point of returning from calls_malloc back to test in the following:

    void *
    calls_malloc (void)
    {
      void *result = malloc (1024);
      return result;
    }

    void test (void)
    {
      void *ptr = calls_malloc ();
      /* etc. */
    }

Within the store, there is the cluster for ptr_3 within the frame for test, where the whole cluster is bound to a pointer value, pointing at HEAP_ALLOCATED_REGION(12). Additionally, this pointer has the unchecked state for the malloc state machine indicating it hasn’t yet been checked against NULL since the allocation call.
27.1.5 Analyzer Paths

We need to explain to the user what the problem is, and to persuade them that there really is a problem. Hence having a diagnostic_path isn’t just an incidental detail of the analyzer; it’s required.

Paths ought to be:

- interprocedurally-valid
- feasible

Without state-merging, all paths in the exploded graph are feasible (in terms of constraints being satisfied). With state-merging, paths in the exploded graph can be infeasible.

We collate warnings and only emit them for the simplest path e.g. for a bug in a utility function, with lots of routes to calling it, we only emit the simplest path (which could be intraprocedural, if it can be reproduced without a caller).

We thus want to find the shortest feasible path through the exploded graph from the origin to the exploded node at which the diagnostic was saved. Unfortunately, if we simply find the shortest such path and check if it’s feasible we might falsely reject the diagnostic, as there might be a longer path that is feasible. Examples include the cases where the diagnostic requires us to go at least once around a loop for a later condition to be satisfied, or where for a later condition to be satisfied we need to enter a suite of code that the simpler path skips.

We attempt to find the shortest feasible path to each diagnostic by first constructing a “trimmed graph” from the exploded graph, containing only those nodes and edges from which there are paths to the target node, and using Dijkstra’s algorithm to order the trimmed nodes by minimal distance to the target.

We then use a worklist to iteratively build a “feasible graph” (actually a tree), capturing the pertinent state along each path, in which every path to a “feasible node” is feasible by construction, restricting ourselves to the trimmed graph to ensure we stay on target, and ordering the worklist so that the first feasible path we find to the target node is the shortest possible path. Hence we start by trying the shortest possible path, but if that fails, we explore progressively longer paths, eventually trying iterations through loops. The exploration is captured in the feasible_graph, which can be dumped as a .dot file via ‘-fdump-analyzer-feasibility’ to visualize the exploration. The indices of the feasible nodes show the order in which they were created. We effectively explore the tree of feasible paths in order of shortest path until we either find a feasible path to the target node, or hit a limit and give up.

This is something of a brute-force approach, but the trimmed graph hopefully keeps the complexity manageable.

This algorithm can be disabled (for debugging purposes) via ‘-fno-analyzer-feasibility’, which simply uses the shortest path, and notes if it is infeasible.

The above gives us a shortest feasible exploded_path through the exploded_graph (a list of exploded_edge *). We use this exploded_path to build a diagnostic_path (a list of events for the diagnostic subsystem) - specifically a checker_path.

Having built the checker_path, we prune it to try to eliminate events that aren’t relevant, to minimize how much the user has to read.
After pruning, we notify each event in the path of its ID and record the IDs of interesting events, allowing for events to refer to other events in their descriptions. The pending_diagnostic class has various vfuncs to support emitting more precise descriptions, so that e.g.

- a deref-of-unchecked-malloc diagnostic might use:
  ```
  return possibly-NUL pointer to 'make_obj' from 'allocator'
  ```
  for a return_event to make it clearer how the unchecked value moves from callee back to caller
- a double-free diagnostic might use:
  ```
  second 'free' here; first 'free' was at (3)
  ```
  and a use-after-free might use
  ```
  use after 'free' here; memory was freed at (2)
  ```

At this point we can emit the diagnostic.

### 27.1.6 Limitations

- Only for C so far
- The implementation of call summaries is currently very simplistic.
- Lack of function pointer analysis
- The constraint-handling code assumes reflexivity in some places (that values are equal to themselves), which is not the case for NaN. As a simple workaround, constraints on floating-point values are currently ignored.
- There are various other limitations in the region model (grep for TODO/xfail in the testsuite).
- The constraint_manager’s implementation of transitivity is currently too expensive to enable by default and so must be manually enabled via ‘-fanalyzer-transitivity’.
- The checkers are currently hardcoded and don’t allow for user extensibility (e.g. adding allocate/release pairs).
- Although the analyzer’s test suite has a proof-of-concept test case for LTO, LTO support hasn’t had extensive testing. There are various lang-specific things in the analyzer that assume C rather than LTO. For example, SSA names are printed to the user in “raw” form, rather than printing the underlying variable name.

Some ideas for other checkers
- File-descriptor-based APIs
- Linux kernel internal APIs
- Signal handling

### 27.2 Debugging the Analyzer

#### 27.2.1 Special Functions for Debugging the Analyzer

The analyzer recognizes various special functions by name, for use in debugging the analyzer. Declarations can be seen in the testsuite in `analyzer-decls.h`. None of these functions are actually implemented.

Add:
__analyzer_break ();

to the source being analyzed to trigger a breakpoint in the analyzer when that source
is reached. By putting a series of these in the source, it’s much easier to effectively step
through the program state as it’s analyzed.

The analyzer handles:

__analyzer_describe (0, expr);

by emitting a warning describing the 2nd argument (which can be of any type), at a
verbosity level given by the 1st argument. This is for use when debugging, and may be of
use in DejaGnu tests.

__analyzer_dump ();

will dump the copious information about the analyzer’s state each time it reaches the call
in its traversal of the source.

extern void __analyzer_dump_capacity (const void *ptr);

will emit a warning describing the capacity of the base region of the region pointed to by
the 1st argument.

__analyzer_dump_path ();

will emit a placeholder “note” diagnostic with a path to that call site, if the analyzer
finds a feasible path to it.

The builtin __analyzer_dump_exploded_nodes will emit a warning after analysis con-
taining information on all of the exploded nodes at that program point:

__analyzer_dump_exploded_nodes (0);

will output the number of “processed” nodes, and the IDs of both “processed” and
“merger” nodes, such as:

warning: 2 processed enodes: [EN: 56, EN: 58] merger(s): [EN: 54-55, EN: 57, EN: 59]

With a non-zero argument

__analyzer_dump_exploded_nodes (1);

it will also dump all of the states within the “processed” nodes.

__analyzer_dump_region_model ();

will dump the region_model’s state to stderr.

__analyzer_dump_state ("malloc", ptr);

will emit a warning describing the state of the 2nd argument (which can be of any type)
with respect to the state machine with a name matching the 1st argument (which must be
a string literal). This is for use when debugging, and may be of use in DejaGnu tests.

__analyzer_eval (expr);

will emit a warning with text "TRUE", FALSE" or "UNKNOWN" based on the truth-
fulness of the argument. This is useful for writing DejaGnu tests.

27.2.2 Other Debugging Techniques

The option ‘-fdump-analyzer-json’ will dump both the supergraph and the exploded
graph in compressed JSON form.

One approach when tracking down where a particular bogus state is introduced into the
exploded_graph is to add custom code to program_state::validate.
28 User Experience Guidelines

To borrow a slogan from Elm,

Compilers should be assistants, not adversaries. A compiler should not just detect bugs, it should then help you understand why there is a bug. It should not berate you in a robot voice, it should give you specific hints that help you write better code. Ultimately, a compiler should make programming faster and more fun!

—Evan Czaplicki

This chapter provides guidelines on how to implement diagnostics and command-line options in ways that we hope achieve the above ideal.

28.1 Guidelines for Diagnostics

28.1.1 Talk in terms of the user’s code

Diagnostics should be worded in terms of the user’s source code, and the source language, rather than GCC’s own implementation details.

28.1.2 Diagnostics are actionable

A good diagnostic is actionable: it should assist the user in taking action.

Consider what an end user will want to do when encountering a diagnostic.

Given an error, an end user will think: “How do I fix this?”

Given a warning, an end user will think:
- “Is this a real problem?”
- “Do I care?”
- if they decide it’s genuine: “How do I fix this?”

A good diagnostic provides pertinent information to allow the user to easily answer the above questions.

28.1.3 The user’s attention is important

A perfect compiler would issue a warning on every aspect of the user’s source code that ought to be fixed, and issue no other warnings. Naturally, this ideal is impossible to achieve.

Warnings should have a good signal-to-noise ratio: we should have few false positives (falsely issuing a warning when no warning is warranted) and few false negatives (failing to issue a warning when one is justified).

Note that a false positive can mean, in practice, a warning that the user doesn’t agree with. Ideally a diagnostic should contain enough information to allow the user to make an informed choice about whether they should care (and how to fix it), but a balance must be drawn against overloading the user with irrelevant data.

28.1.4 Sometimes the user didn’t write the code

GCC is typically used in two different ways:
• Semi-interactive usage: GCC is used as a development tool when the user is writing code, as the “compile” part of the “edit-compile-debug” cycle. The user is actively hacking on the code themself (perhaps a project they wrote, or someone else’s), where they just made a change to the code and want to see what happens, and to be warned about mistakes.

• Batch rebuilds: where the user is recompiling one or more existing packages, and GCC is a detail that’s being invoked by various build scripts. Examples include a user trying to bring up an operating system consisting of hundreds of packages on a new CPU architecture, where the packages were written by many different people, or simply rebuilding packages after a dependency changed, where the user is hoping “nothing breaks”, since they are unfamiliar with the code.

Keep both of these styles of usage in mind when implementing diagnostics.

28.1.5 Precision of Wording

Provide the user with details that allow them to identify what the problem is. For example, the vaguely-worded message:

demo.c:1:1: warning: 'noinline' attribute ignored [-Wattributes]
 1 | int foo __attribute__((noinline));
  | ~~~

doesn’t tell the user why the attribute was ignored, or what kind of entity the compiler thought the attribute was being applied to (the source location for the diagnostic is also poor; see [discussion of input_location], page 738). A better message would be:

demo.c:1:24: warning: attribute 'noinline' on variable 'foo' was ignored [-Wattributes]
 1 | int foo __attribute__((noinline));
  | ~~~ ~~~~~~~~~~~~~~~^~~~~~~~~

demo.c:1:24: note: attribute 'noinline' is only applicable to functions

which spells out the missing information (and fixes the location information, as discussed below).

The above example uses a note to avoid a combinatorial explosion of possible messages.

28.1.6 Try the diagnostic on real-world code

It’s worth testing a new warning on many instances of real-world code, written by different people, and seeing what it complains about, and what it doesn’t complain about.

This may suggest heuristics that silence common false positives.

It may also suggest ways to improve the precision of the message.

28.1.7 Make mismatches clear

Many diagnostics relate to a mismatch between two different places in the user’s source code. Examples include:

• a type mismatch, where the type at a usage site does not match the type at a declaration
• the argument count at a call site does not match the parameter count at the declaration
• something is erroneously duplicated (e.g. an error, due to breaking a uniqueness requirement, or a warning, if it’s suggestive of a bug)
• an “opened” syntactic construct (such as an open-parenthesis) is not closed
In each case, the diagnostic should indicate both pertinent locations (so that the user can easily see the problem and how to fix it).

The standard way to do this is with a note (via `inform`). For example:

```c
auto_diagnostic_group d;
    if (warning_at (loc, OPT_Wduplicated_cond,
                    "duplicated %<if%> condition"))
        inform (EXPR_LOCATION (t), "previously used here");
```

which leads to:

```c
demo.c: In function 'test':
    demo.c:5:17: warning: duplicated 'if' condition [-Wduplicated-cond]
    5 |   else if (flag > 3)
    |    ~~~~~~~
    demo.c:3:12: note: previously used here
    3 | if (flag > 3)
    | ~~~~~~~
```

The `inform` call should be guarded by the return value from the `warning_at` call so that the note isn’t emitted when the warning is suppressed.

For cases involving punctuation where the locations might be near each other, they can be conditionally consolidated via `gcc_rich_location::add_location_if_nearby`:

```c
auto_diagnostic_group d;
    gcc_rich_location richloc (primary_loc);
    bool added secondary = richloc.add_location_if_nearby (secondary_loc);
    error_at (&richloc, "main message");
    if (!added secondary)
        inform (secondary_loc, "message for secondary");
```

This will emit either one diagnostic with two locations:

```c
demo.c:42:10: error: main message
   (foo)
   ~ ~ ~ ~
```

or two diagnostics:

```c
demo.c:42:4: error: main message
   foo)
   ~

demo.c:40:2: note: message for secondary
   ( ~ ~
```

### 28.1.8 Location Information

GCC’s `location_t` type can support both ordinary locations, and locations relating to a macro expansion.

As of GCC 6, ordinary locations changed from supporting just a point in the user’s source code to supporting three points: the caret location, plus a start and a finish:

```c
a = foo \&\& bar;
------------
|   |   |
|   | finish
| caret
start
```

Tokens coming out of libc++ have locations of the form `caret == start`, such as for `foo` here:
a = foo && bar;
    ^~~
   | |
   | finish
caret == start

Compound expressions should be reported using the location of the expression as a whole, rather than just of one token within it.

For example, in `-Wformat`, rather than underlining just the first token of a bad argument:

```c
printf("hello %i %s", (long)0, "world");
    %li
```

the whole of the expression should be underlined, so that the user can easily identify what is being referred to:

```c
printf("hello %i %s", (long)0, "world");
    ^ ~~~~~~~
    %li
```

Avoid using the `input_location` global, and the diagnostic functions that implicitly use it—use `error_at` and `warning_at` rather than `error` and `warning`, and provide the most appropriate `location_t` value available at that phase of the compilation. It’s possible to supply secondary `location_t` values via `rich_location`.

For example, in the example of imprecise wording above, generating the diagnostic using `warning`:

```c
// BAD: implicitly uses input_location
warning (OPT_Wattributes, "%qE attribute ignored", name);
```

leads to:

```c
// BAD: uses input_location
demo.c:1:1: warning: 'noinline' attribute ignored [-Wattributes]
  1 | int foo __attribute__((noinline));
  ^~~
which thus happened to use the location of the `int` token, rather than that of the attribute. Using `warning_at` with the location of the attribute, providing the location of the declaration in question as a secondary location, and adding a note:

```c
auto_diagnostic_group d;
gcc_rich_location richloc (attrib_loc);
richloc.add_range (decl_loc);
if (warning_at (OPT_Wattributes, &richloc,
    "attribute %qE on variable %qE was ignored", name))
    inform (attrib_loc, "attribute %qE is only applicable to functions");
```

would lead to:

```c
// OK: use location of attribute, with a secondary location
demo.c:1:24: warning: attribute 'noinline' on variable 'foo' was ignored [-Wattributes]
  1 | int foo __attribute__((noinline));
  ^ ~~~~~~~~~~~~~~~
demo.c:1:24: note: attribute 'noinline' is only applicable to functions
```

### 28.1.9 Coding Conventions

See the diagnostics section of the GCC coding conventions.
In the C++ front end, when comparing two types in a message, use ‘%H’ and ‘%I’ rather than ‘%T’, as this allows the diagnostics subsystem to highlight differences between template-based types. For example, rather than using ‘%qT’:

```c
// BAD: a pair of %qT used in C++ front end for type comparison
error_at(loc, "could not convert %qE from %qT to %qT", expr,
        TREE_TYPE(expr), type);
```

which could lead to:

```c
error: could not convert 'map<int, double>()' from 'map<int,double>'
to 'map<int,int>'
```

using ‘%H’ and ‘%I’ (via ‘%qH’ and ‘%qI’):

```c
// OK: compare types in C++ front end via %qH and %qI
error_at(loc, "could not convert %qE from %qH to %qI", expr,
        TREE_TYPE(expr), type);
```

allows the above output to be simplified to:

```c
error: could not convert 'map<int, double>()' from 'map<...,double>'
to 'map<...,int>'
```

where the `double` and `int` are colorized to highlight them.

### 28.1.10 Group logically-related diagnostics

Use `auto_diagnostic_group` when issuing multiple related diagnostics (seen in various examples on this page). This informs the diagnostic subsystem that all diagnostics issued within the lifetime of the `auto_diagnostic_group` are related. For example, ‘-fdiagnostics-format=json’ will treat the first diagnostic emitted within the group as a top-level diagnostic, and all subsequent diagnostics within the group as its children.

### 28.1.11 Quoting

Text should be quoted by either using the ‘q’ modifier in a directive such as ‘%qE’, or by enclosing the quoted text in a pair of ‘%<’ and ‘%>’ directives, and never by using explicit quote characters. The directives handle the appropriate quote characters for each language and apply the correct color or highlighting.

The following elements should be quoted in GCC diagnostics:

- Language keywords.
- Tokens.
- Boolean, numerical, character, and string constants that appear in the source code.
- Identifiers, including function, macro, type, and variable names.

Other elements such as numbers that do not refer to numeric constants that appear in the source code should not be quoted. For example, in the message:

```c
argument %d of %qE must be a pointer type
```

since the argument number does not refer to a numerical constant in the source code it should not be quoted.

### 28.1.12 Spelling and Terminology

See the terminology and markup section of the GCC coding conventions.
28.1.13 Fix-it hints

GCC’s diagnostic subsystem can emit fix-it hints: small suggested edits to the user’s source code.

They are printed by default underneath the code in question. They can also be viewed via ‘-fdiagnostics-generate-patch’ and ‘-fdiagnostics-parseable-fixits’. With the latter, an IDE ought to be able to offer to automatically apply the suggested fix.

Fix-it hints contain code fragments, and thus they should not be marked for translation.

Fix-it hints can be added to a diagnostic by using a rich_location rather than a location_t - the fix-it hints are added to the rich_location using one of the various add_fixit member functions of rich_location. They are documented with rich_location in ‘libcpp/line-map.h’. It’s easiest to use the gcc_rich_location subclass of rich_location found in ‘gcc-rich-location.h’, as this implicitly supplies the line_table variable.

For example:

```c
if (const char *suggestion = hint.suggestion ())
{
  gcc_rich_location richloc (location);
  richloc.add_fixit_replace (suggestion);
  error_at (&richloc,
            "%qE does not name a type; did you mean %qs?",
            id, suggestion);
}
```

which can lead to:

```
spellcheck-typenames.C:73:1: error: 'singed' does not name a type; did you mean 'signed'?
73 | singed char ch;
    | ^~~~~~
    | signed
```

Non-trivial edits can be built up by adding multiple fix-it hints to one rich_location. It’s best to express the edits in terms of the locations of individual tokens. Various handy functions for adding fix-it hints for idiomatic C and C++ can be seen in ‘gcc-rich-location.h’.

28.1.13.1 Fix-it hints should work

When implementing a fix-it hint, please verify that the suggested edit leads to fixed, compilable code. (Unfortunately, this currently must be done by hand using ‘-fdiagnostics-generate-patch’. It would be good to have an automated way of verifying that fix-it hints actually fix the code).

For example, a “gotcha” here is to forget to add a space when adding a missing reserved word. Consider a C++ fix-it hint that adds typename in front of a template declaration. A naive way to implement this might be:

```c
gcc_rich_location richloc (loc);
// BAD: insertion is missing a trailing space
richloc.add_fixit_insert_before ("typename");
error_at (&richloc,
          "need %<typename%> before %<%T::%E%> because "
          "%qT is a dependent scope",
          parser->scope, id, parser->scope);
```

When applied to the code, this might lead to:
T::type x;

being “corrected” to:

typename T::type x;

In this case, the correct thing to do is to add a trailing space after `typename`:

gcc_rich_location richloc (loc);
// OK: note that here we have a trailing space
richloc.add_fixit_insert_before ("typename ");
error_at (&richloc, "need %<typename%> before %<%T::%E%> because "
"%qT is a dependent scope",
parser->scope, id, parser->scope);

leading to this corrected code:

typename T::type x;

28.1.13.2 Express deletion in terms of deletion, not replacement

It’s best to express deletion suggestions in terms of deletion fix-it hints, rather than replacement fix-it hints. For example, consider this:

```cpp
auto_diagnostic_group d;
gcc_rich_location richloc (location_of (retval));
tree name = DECL_NAME (arg);
richloc.add_fixit_replace (IDENTIFIER_POINTER (name));
warning_at (&richloc, OPT_Wredundant_move,
"redundant move in return statement");
```

which is intended to e.g. replace a `std::move` with the underlying value:

```cpp
return std::move (retval);
```

leading to this corrected code:

```cpp
return std::move (CONFIGURY_GLOBAL /* some comment */);
```

where the change has been expressed as replacement, replacing with the name of the declaration. This works for simple cases, but consider this case:

```cpp
#ifdef SOME_CONFIG_FLAG
#define CONFIGURY_GLOBAL global_a
#else
#define CONFIGURY_GLOBAL global_b
#endif

int fn ()
{
    return std::move (CONFIGURY_GLOBAL /* some comment */);
}
```

The above implementation erroneously strips out the macro and the comment in the fix-it hint:

```cpp
return std::move (CONFIGURY_GLOBAL /* some comment */);
```

and thus this resulting code:

```cpp
return global_a;
```

It’s better to do deletions in terms of deletions; deleting the `std::move` ( and the trailing close-paren, leading to this:

```cpp
return std::move (CONFIGURY_GLOBAL /* some comment */);
```

```cpp
            CONFIGURY_GLOBAL /* some comment */
```
and thus this result:

```c
    return CONFIGURY_GLOBAL /* some comment */;
```

Unfortunately, the pertinent `location_t` values are not always available.

### 28.1.13.3 Multiple suggestions

In the rare cases where you need to suggest more than one mutually exclusive solution to a problem, this can be done by emitting multiple notes and calling `rich_location::fixits_cannot_be_auto_applied` on each note's `rich_location`. If this is called, then the fix-it hints in the `rich_location` will be printed, but will not be added to generated patches.

### 28.2 Guidelines for Options
Funding Free Software

If you want to have more free software a few years from now, it makes sense for you to help encourage people to contribute funds for its development. The most effective approach known is to encourage commercial redistributors to donate.

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Option Index

GCC’s command line options are indexed here without any initial ‘-’ or ‘--’. Where an option has both positive and negative forms (such as ‘-foption’ and ‘-fno-option’), relevant entries in the manual are indexed under the most appropriate form; it may sometimes be useful to look up both forms.

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